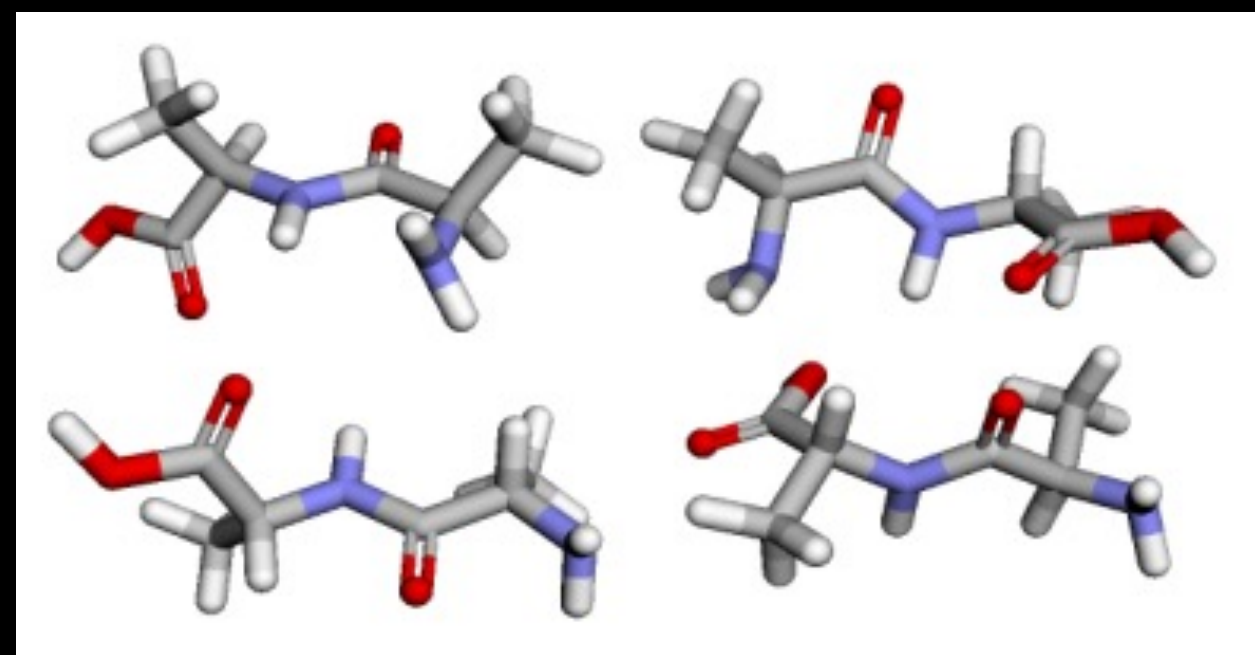


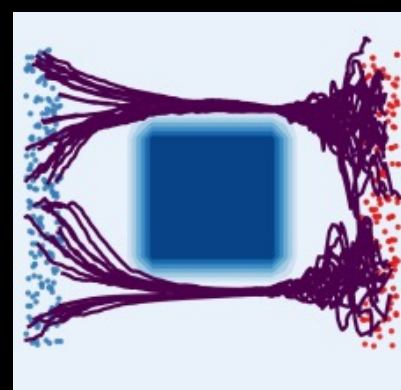
Generative Modelling



Bayesian Inference / Protein Folding



Filtering / Data Assimilation



Diffusion Models and SDEs

Lecture 1:

A very fast paced introduction to the foundations.

Quick Probability Recap

Probability Space

- Sample Space

e.g $\Omega = \{0, 1\}$ or $\Omega = \mathbb{R}$

$$\mathbb{P}(\Omega) = 1, \quad P(A) \geq 0$$

$$\mathbb{P}(\cup_{i \in \mathcal{I}} A_i) = \sum_{i \in \mathcal{I}} \mathbb{P}(A_i)$$

$$A_i \cap A_j = \emptyset, i \neq j, \quad \exists f : \mathcal{I} \longleftrightarrow \mathbb{N}$$

- Probability Measure

$$(\Omega, \Sigma, \mathbb{P})$$

- Event Space e.g $2^{\{0,1\}}$

/ Sigma Algebra: is a algebra/system of sets that are “closed” under countable # of operations $\cup, \cap, \setminus \Omega$ and $\Omega, \emptyset \in \Sigma \subseteq 2^\Omega$

Quick Probability Recap

Probability Space

- Sample Space

e.g $\Omega = \{0, 1\}$ or $\Omega = \mathbb{R}$

$$\mathbb{P}(\Omega) = 1, \quad P(A) \geq 0$$

$$\mathbb{P}(\cup_{i \in \mathcal{I}} A_i) = \sum_{i \in \mathcal{I}} \mathbb{P}(A_i)$$

$$A_i \cap A_j = \emptyset, i \neq j, \quad \exists f : \mathcal{I} \longleftrightarrow \mathbb{N}$$

- Probability Measure

$$(\Omega, \mathcal{B}(\Omega), \mathbb{P})$$

- Event Space e.g $2^{\{0,1\}}$

The Borel-sigma algebra is the smallest sigma algebra containing the event space (i.e. intersect all possible sigma algebra containing Omega).

Quick Probability Recap

Filtered Probability Space

- Think of a filtration as the sample space of a time series, that is a series of sample spaces:

$$\mathcal{F} = \{\mathcal{F}_t\}_{t \in [0, T]}$$

$$s \leq t \implies \mathcal{F}_s \subseteq \mathcal{F}_t$$

$$(\Omega, \mathcal{F}, \mathbb{P})$$

Quick Probability Recap

Stochastic Process

$$A \in \mathcal{F}_s \implies X^{-1}(A) \in \mathcal{B}(\mathbb{R}^d)$$

- Collection of Random Variables (Measurable Maps) !

$$\{X_t\}_{t \in [0, T]} \quad X_t(\omega) : [0, T] \times \Omega \rightarrow \mathbb{R}^d$$

$$(C([0, T]; \mathbb{R}^d), \mathcal{F}, \mathbb{P})$$

Quick Probability Recap

Brownian Motion

- Brownian motion is a Gaussian Process, and one of the simplest Stochastic Processes:
 - Pinned Origin: $W_0 = 0$
 - Independent increments $s, t > 0, W_{t+s} - W_t \perp\!\!\!\perp W_t$
 - $W_{t+s} - W_t \sim \mathcal{N}(0, s)$
 - W_t is continuous in t (almost surely)

$$W \sim \mathcal{GP}(0, \min(s, t))$$

Quick Probability Recap

Lebesgue Measure

$$\lambda([a, b]) = |a - b|$$

$$\lambda\left(\bigcup_{i \in \mathcal{I}} [a_i, b_i]\right) = \sum_{i \in \mathcal{I}} \lambda([a_i, b_i])$$

$$\lambda(A) = \inf \{ \lambda(I) : A \subseteq I, I = \bigcup_{i \in \mathcal{I}} [a_i, b_i] \}$$

Volume/Size

- Caratheodory Extension Theorem and Criterion
assert uniqueness/existence of the space $(\mathbb{R}, \mathcal{B}(\mathbb{R}), \lambda)$

Quick Probability Recap

Lebesgue Integral

$$\int_A d\lambda = \lambda(A)$$

$$\int_{\Omega} \mathbb{I}_A(x) d\lambda = \lambda(A)$$

$$\int_{\Omega} \sum_{i=1}^n a_i \mathbb{I}_{A_i}(x) d\lambda = \sum_{i=1}^n a_i \lambda(A_i)$$

$$\int_A f d\lambda = \sup \left\{ \int s d\lambda : 0 \leq s \leq f, s = \sum_{i=1}^n \mathbb{I}_{A_i}(x) \right\}$$

Quick Probability Recap

Lebesgue Integral Matches Traditional Riemann Integral

$$\int_A f d\lambda = \sup \left\{ \int s d\lambda : 0 \leq s \leq f, s = \sum_{i=1}^n \mathbb{I}_{A_i}(x) \right\}$$

$$\int_A f(x) d\lambda(x) = \int_A f(x) dx = \int_A f(x) \lambda(dx)$$

Also note we can replace lambda with a probability distribution:

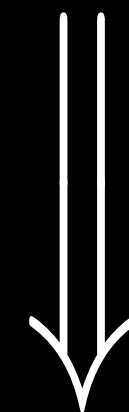
$$\int_A f(x) dP(x) = \mathbb{E}_P[f(X)]$$

Quick Probability Recap

Lebesgue Integral Matches Traditional Riemann Integral

Why bother with this integral formalism, isn't Riemann enough ? Many useful theorems come for free, in particular Dominated Convergence (for integrable g):

$$f_n \xrightarrow{\text{pointwise}} f \quad \text{and} \quad |f_n| \leq g(x)$$



$$\lim_{n \rightarrow \infty} \mathbb{E}_P[f_n(X)] = \mathbb{E}_P[f(X)]$$

Quick Probability Recap

Lebesgue Integral – Exercise (Uniform Distribution)

$$P([a, b]) = |a - b|$$

$$P(\Omega) = P([0, 1]) = 1$$

$$\int_{[1/4, 1/2]} dP = ?$$

$$\int_{[0, 1]} \mathbb{I}_{[1/e, 1/(e+1)]}(x) dP = ?$$

$$\int_{\Omega} x dP = ?$$

Quick Probability Recap

Lebesgue Integral – Exercise (Uniform Distribution)

$$P([a, b]) = |a - b|$$

$$P(\Omega) = P([0, 1]) = 1$$

$$\int_{[1/4, 1/2]} dP = 1/2$$

$$\int_{[0, 1]} \mathbb{I}_{[1/e, 1/(e+1)]}(x) dP = 1/(e(e+1))$$

$$\int_{\Omega} x dP = 1/2$$

Quick Probability Recap

Radon Nikodym Theorem – Change of Measure

$$\mu \ll \lambda := \lambda(A) = 0 \implies \mu(A) = 0$$

$$\mu(A) = \int_A \frac{d\mu}{d\lambda}(x) d\lambda(x)$$

$$\int_A f(x) d\mu(x) = \int_A f(x) \frac{d\mu}{d\lambda}(x) d\lambda(x)$$

Quick Probability Recap

Radon Nikodym Theorem (Exercise)

$$\mathbb{P} \ll \lambda \qquad \mathbb{P}(A) = \int_A \frac{d\mathbb{P}}{d\lambda}(x) d\lambda(x)$$

Now For sake of simplicity assume Reimann Integrability

$$\mathbb{P}(A) = \int_A \frac{d\mathbb{P}}{d\lambda}(x) d\lambda(x) = \int_A \frac{d\mathbb{P}}{d\lambda}(x) dx$$

$$\frac{d\mathbb{P}}{d\lambda}(x) = ???$$

Quick Probability Recap

Radon Nikodym Theorem (Exercise: Probability Density)

$$\mathbb{P} \ll \lambda \qquad \mathbb{P}(A) = \int_A \frac{d\mathbb{P}}{d\lambda}(x) d\lambda(x)$$

Now For sake of simplicity assume Reimann Integrability

$$\mathbb{P}(A) = \int_A \frac{d\mathbb{P}}{d\lambda}(x) d\lambda(x) = \int_A \frac{d\mathbb{P}}{d\lambda}(x) dx$$

$$\frac{d\mathbb{P}}{d\lambda}(x) = \text{Probability Density Function !}$$

Quick Probability Recap

Radon Nikodym Theorem (e.g. Importance Sampling)

$$\mathbb{P} \ll \mathbb{Q}$$

$$\int_{\Omega} f(x) d\mathbb{P}(x) = \int_{\Omega} f(x) \frac{d\mathbb{P}}{d\mathbb{Q}}(x) d\mathbb{Q}(x)$$

$$\mathbb{E}_{\mathbb{P}}[f(X)] = \mathbb{E}_{\mathbb{Q}} \left[f(X) \frac{d\mathbb{P}}{d\mathbb{Q}}(X) \right]$$

$$\mathbb{E}_{\mathbb{P}}[f(X)] = \mathbb{E}_{\mathbb{Q}} \left[f(X) \frac{p(X)}{q(X)} \right]$$

Quick Probability Recap

Modes of Convergence - Exercise

- What does It mean for two random variables to be equal ? Is it as simple as saying they have the same distribution ?

Quick Probability Recap

Modes of Convergence

- What does it mean for two random variables to be equal ? Is it as simple as saying they have the same distribution ? (Law X = Distribution of X)

$$\mathbb{P}(|X - Y| > \epsilon) = 0$$

$$\mathbb{P}(|X - Y| = 0) = 1$$

$$\mathbb{E}[|X - Y|^p] = 0$$

$$\text{Law } X = \text{Law } Y$$

Quick Probability Recap

Modes of Convergence

- In particular we speak about modes of convergence when we consider limits

$$\lim_{n \rightarrow \infty} \mathbb{P}(|X - X_n| > \epsilon) = 0$$

$$\lim_{n \rightarrow \infty} \mathbb{P}(|X - X_n| = 0) = 1$$

$$\lim_{n \rightarrow \infty} \mathbb{E}[|X - X_n|^p] = 0$$

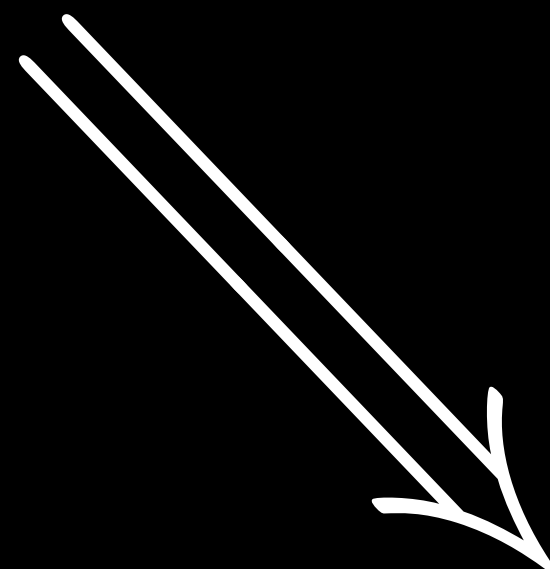
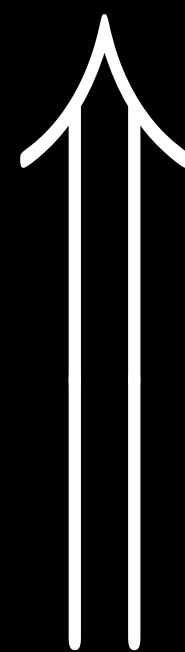
$$\text{Law } X = \lim_{n \rightarrow \infty} \text{Law } X_n$$

Quick Probability Recap

Modes of Convergence

$$\lim_{n \rightarrow \infty} \mathbb{P}(|X - X_n| > \epsilon) = 0 \quad \Longleftarrow$$

$$\lim_{n \rightarrow \infty} \mathbb{P}(|X - X_n| = 0) = 1$$



$$\lim_{n \rightarrow \infty} \mathbb{E}[|X - X_n|^p] = 0 \quad \Longrightarrow$$

$$\text{Law } X = \lim_{n \rightarrow \infty} \text{Law } X_n$$



SDEs

Heuristic 1 - Discrete Time Markov Chain

$$X_0 \sim \pi,$$

$$\epsilon_n \sim \mathcal{N}(0, \gamma I)$$

$$X_{n+1} = X_n + f(X_n, n)\delta t + \sqrt{\delta t}\epsilon_n,$$

SDEs

Heuristic 2 - Langevin Dynamics and White Noise

- Consider the ODE + Noise

$$X_0 \sim \pi,$$

$$\frac{dX_t}{dt} = f(X_t, t) + \gamma w(t),$$

$$w(\cdot) \sim \mathcal{GP}(0, \mathbb{I}_{s=t})$$

SDEs

Stochastic Integrals - Types

$$Y_t = \int_0^t X_s \mathrm{d}s$$

- Can think of this as a Reimann integral with convergence asserted in the $\mathcal{L}^p(\mathbb{P})$ sense

$$Z_t = \int_0^t Y_s \mathrm{d}X_s$$

- Now integrating against/wrt to random variable. Not so simple to define. Reimann conditions fail

SDEs

Stochastic Integrals - Definition

- First partition the grid $[0,t]$ $t_{k+1} - t_k = \frac{t}{N}$

- Now we make the following assumption

$$\lim_{n \rightarrow \infty} \mathbb{E} \left[\int_0^t |Y_t - Y_t^{(n)}|^2 ds \right] = 0 \quad \text{s.t.} \quad Y^{(n)}(t) = \sum_{k=1}^n Y_{t_k} \mathbb{I}_{t \in [t_k, t_{k+1})}(t)$$

- Then the Ito Integral is defined as:

$$\int_0^t Y_s dW_s \stackrel{\mathcal{L}^2(\mathbb{P})}{=} \lim_{n \rightarrow \infty} \sum_{k=1}^n Y_{t_k} (W_{t_{k+1}} - W_{t_k})$$

SDEs

Stochastic Integrals - Counter Example

$$\mathbb{E} \left[\sum_{k=1}^n W_{t_k} (W_{t_{k+1}} - W_{t_k}) \right] = 0$$

$$\mathbb{E} \left[\sum_{k=1}^n W_{t_{k+1}} (W_{t_{k+1}} - W_{t_k}) \right] = t$$

SDEs

Stochastic Integrals - Counter Example

$$\mathbb{E} \left[\sum_{k=1}^n W_{t_k} (W_{t_{k+1}} - W_{t_k}) \right] = 0$$

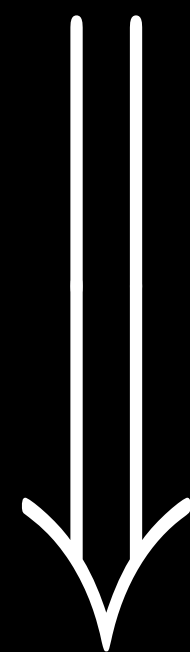
$$\mathbb{E} \left[\sum_{k=1}^n W_{t_{k+1}} (W_{t_{k+1}} - W_{t_k}) \right] = t$$

- Where you evaluate the integrand (within the grid) changes the result, thus violating the conditions required to be Riemann integrable (remember upper and lower Darboux sums must much)

SDEs

Stochastic Integrals - Martingales

$$\mathbb{E}[X_t | \mathcal{F}_s] = X_s$$



$$\mathbb{E}[X_t | X_s] = \mathbb{E}[X_t | \sigma(X_s)] = X_s$$

SDEs

Stochastic Integrals - Martingales

$$\mathbb{E} \left[\int_0^t X_\tau \mathrm{d}W_\tau \middle| \mathcal{F}_s \right] = \int_0^s X_\tau \mathrm{d}W_\tau$$

SDEs

Stochastic Integrals - Martingales

$$\begin{aligned}\mathbb{E} \left[\int_0^t X_\tau \mathrm{d}W_\tau \right] &= \mathbb{E} \left[\mathbb{E} \left[\int_0^t X_\tau \mathrm{d}W_\tau \middle| \mathcal{F}_0 \right] \right] \\ &= \mathbb{E} \left[\int_0^0 X_\tau \mathrm{d}W_\tau \right] = 0\end{aligned}$$

SDEs

Formal Definition - Stochastic Piccard Lindeloff Theorem

- Assumptions (Lipchitz + Linear Growth):

$$|\mu(x, t) - \mu(y, s)| + |\sigma(x, t) - \sigma(y, s)| \leq L(|x - y| + |t - s|)$$

$$|\mu(x, t)| + |\sigma(x, t)| \leq C(1 + |x|)$$

- Then we have existence and uniqueness of (in $\mathcal{L}^p(\mathbb{P})$):

$$X_0 \sim \pi$$

$$X_t = X_0 + \int_0^t \mu(X_s, s)ds + \int_0^t \sigma(X_s, s)dW_s$$

$$dX_t = \mu(X_t, t)dt + \sigma(X_t, t)dW_t$$