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import heapq
class PuzzleState:
   def init (self, state, parent=None, move=None, cost=0):
        self.state = state
        self.parent = parent
        self.move = move
        self.cost = cost
        self.heuristic = self.calculate heuristic()
   def lt (self, other):
        return (self.cost + self.heuristic) < (other.cost + other.heuristic)</pre>
    def __eq__(self, other):
        return self.state == other.state
   def hash (self):
        return hash(tuple(self.state))
   def find blank(self):
        return self.state.index(0)
    def calculate_heuristic(self):
        # Manhattan distance heuristic
       distance = 0
       goal_state = [1, 2, 3, 4, 5, 6, 7, 8, 0]
       for i, value in enumerate(self.state):
            if value != 0:
                goal_pos = goal_state.index(value)
                distance += abs(i % 3 - goal_pos % 3) + abs(i // 3 - goal_pos // 3)
        return distance
    def generate neighbors(self):
       blank pos = self.find blank()
       neighbors = []
       moves = [(-1, 0), (1, 0), (0, -1), (0, 1)] # Up, down, left, right
        for move in moves:
            new_row, new_col = blank_pos // 3 + move[0], blank_pos % 3 + move[1]
            if 0 <= new_row < 3 and 0 <= new_col < 3:
                new blank pos = new row * 3 + new col
               new_state = self.state[:]
                new_state[blank_pos], new_state[new_blank_pos] = new_state[new_blank_pos],
                neighbors.append(PuzzleState(new state, self, move, self.cost + 1))
        return neighbors
def solve_8_puzzle(initial_state):
   initial_puzzle = PuzzleState(initial_state)
    goal state = [1, 2, 3, 4, 5, 6, 7, 8, 0]
   goal_puzzle = PuzzleState(goal_state)
   if initial_puzzle == goal_puzzle:
        return [initial puzzle]
   open_list = []
   heapq.heappush(open_list, initial_puzzle)
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closed set = set()
   while open list:
       current puzzle = heapq.heappop(open list)
        if current puzzle.state == goal state:
            path = []
            while current puzzle:
                path.append(current puzzle)
                current puzzle = current puzzle.parent
            return path[::-1]
       closed set.add(current puzzle)
        for neighbor in current puzzle.generate neighbors():
            if neighbor not in closed set:
                heapq.heappush(open_list, neighbor)
   return None # No solution found
def get user input():
   print("Enter the initial state of the 8-puzzle (use 0 for the blank space):")
   print("Example input format: 2 8 3 1 6 4 7 0 5")
   while True:
       user input = input("Enter 9 numbers separated by spaces: ")
       numbers = user input.split()
        if len(numbers) != 9:
            print("Please enter exactly 9 numbers.")
            continue
        try:
            numbers = [int(num) for num in numbers]
        except ValueError:
            print("Please enter numbers only.")
            continue
        if sorted(numbers) != list(range(9)):
            print("Please use each digit from 0 to 8 exactly once.")
            continue
        return numbers
def main():
   initial state = get user input()
   solution = solve_8_puzzle(initial_state)
   if solution:
        print("\nSolution found! Here are the steps:")
       for step, puzzle in enumerate(solution):
            print(f"\nStep {step}:")
            if step > 0:
               move = puzzle.move
                if move == (-1, 0):
                    print("Move: UP")
                elif move == (1, 0):
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print("Move: DOWN")
               elif move == (0, -1):
                    print("Move: LEFT")
                elif move == (0, 1):
                    print("Move: RIGHT")
           for i in range(0, 9, 3):
                print(puzzle.state[i:i + 3])
   else:
       print("\nNo solution exists for this puzzle configuration.")
if __name__ == "__main__":
   main()
→ Enter the initial state of the 8-puzzle (use 0 for the blank space):
    Example input format: 2 8 3 1 6 4 7 0 5
    Enter 9 numbers separated by spaces: 1 2 3 4 5 6 7 0 8
    Solution found! Here are the steps:
    Step 0:
    [1, 2, 3]
    [4, 5, 6]
    [7, 0, 8]
    Step 1:
    Move: RIGHT
     [1, 2, 3]
     [4, 5, 6]
    [7, 8, 0]
```