

19. ¹⁰
 $\mathbb{R}_+^2 := \{(x, y) \in \mathbb{R}^2 \mid y > 0\}$ $g_H := \frac{1}{y^2} dx^2 + \frac{1}{y^2} dy^2$

$$g_H = \frac{1}{y^2} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$g_H^{-1} = y^2 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

→ $\overline{P}^1, \overline{P}^2$ を先に計算しておく.

$$\overline{P}_{\bar{x}\bar{y}} = \overline{P}_{\bar{y}\bar{x}}$$

$$\begin{bmatrix} \overline{P}_{11}^1 \\ \overline{P}_{11}^2 \end{bmatrix} = \frac{1}{2} g_H^{-1} \begin{bmatrix} \partial_1 g_{11} + \cancel{\partial_1 g_{11}} - \cancel{\partial_1 g_{11}} \\ \cancel{\partial_1 g_{21}} + \cancel{\partial_1 g_{12}} - \partial_2 g_{11} \end{bmatrix}$$

$$= \frac{1}{2} y^2 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \partial_1 g_{11} \\ -\partial_2 g_{11} \end{bmatrix}$$

$$= \frac{1}{2} y^2 \begin{bmatrix} 0 \\ 2y^{-3} \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ \frac{1}{y} \end{bmatrix}$$

$$\therefore \overline{P}_{11}^1 = 0,$$

$$\overline{P}_{11}^2 = \frac{1}{y} \quad (\text{OK})$$

$$y^{-2}$$

$$-y^{-2}$$

$$2y^{-3}$$

$$\therefore \overline{P}_{22}^1 = 0,$$

$$\overline{P}_{22}^2 = -\frac{1}{y} \quad (\text{OK})$$

$$g_{11} = y^{-2}$$

$$g_{22} = y^{-2}$$

$$\begin{bmatrix} \overline{P}_{12}^1 \\ \overline{P}_{12}^2 \end{bmatrix} = \frac{1}{2} g_H^{-1} \begin{bmatrix} \partial_1 g_{12} + \partial_2 g_{11} - \partial_1 g_{12} \\ \partial_1 g_{22} + \partial_2 g_{12} - \partial_2 g_{12} \end{bmatrix}$$

$$\bar{x}=1, \bar{y}=2,$$

$$= \frac{1}{2} y^2 \begin{bmatrix} \partial_2 g_{11} \\ \partial_1 g_{22} \end{bmatrix}$$

$$= \frac{1}{2} y^2 \begin{bmatrix} -2y^{-3} \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -y^{-1} \\ 0 \end{bmatrix}$$

$$\therefore \overline{P}_{12}^1 = -\frac{1}{y} \quad (\text{OK})$$

$$\overline{P}_{12}^2 = 0$$

$$\begin{bmatrix} \overline{P}_{22}^1 \\ \overline{P}_{22}^2 \end{bmatrix} = \frac{1}{2} g_H^{-1} \begin{bmatrix} \partial_2 g_{12} + \partial_2 g_{21} - \partial_2 g_{22} \\ \partial_2 g_{22} + \partial_2 g_{22} - \partial_2 g_{22} \end{bmatrix}$$

$$\bar{x}=2, \bar{y}=2,$$

$$= \frac{1}{2} y^2 \begin{bmatrix} -\partial_1 g_{22} \\ \partial_2 g_{22} \end{bmatrix}$$

$$= \frac{1}{2} y^2 \begin{bmatrix} 0 \\ -2y^{-3} \end{bmatrix} = \begin{bmatrix} 0 \\ -y^{-1} \end{bmatrix}$$

$\frac{1}{10-1}$

y^{-1}

$$R_{221}^1 = ? \quad (\bar{i}=1, \bar{j}=2, k=2, l=1)$$

$$\begin{aligned} R_{221}^1 &= \frac{\partial}{\partial x^1} \Gamma_{22}^1 - \frac{\partial}{\partial x^2} \Gamma_{12}^1 + \sum_{a=1}^2 (\Gamma_{1a}^1 \Gamma_{22}^a - \Gamma_{2a}^1 \Gamma_{12}^a) \\ &= \frac{\partial}{\partial x^1} (0) - \frac{\partial}{\partial x^2} (-y^{-1}) + (\underbrace{\Gamma_{11}^1 \Gamma_{22}^1}_0 - \underbrace{\Gamma_{21}^1 \Gamma_{12}^1}_{\frac{1}{y^2}} + \underbrace{\Gamma_{12}^1 \Gamma_{22}^2}_{\frac{1}{y^2}} - \underbrace{\Gamma_{22}^1 \Gamma_{12}^2}_0) \\ &= 0 - y^{-2} + (-\frac{1}{y^2} + \frac{1}{y^2}) \\ &= -\frac{1}{y^2} \quad (\text{ok}) \end{aligned}$$

$$(2), R_{222}^1 = ? \quad (\bar{i}=1, \bar{j}=2, k=2, l=2)$$

$$\begin{aligned} R_{222}^1 &= \frac{\partial}{\partial x^2} \Gamma_{22}^1 - \frac{\partial}{\partial x^2} \Gamma_{22}^1 + \sum_{a=1}^2 (\Gamma_{2a}^1 \Gamma_{22}^a - \Gamma_{2a}^1 \Gamma_{22}^a) \\ &= \frac{\partial}{\partial x^2} (0) - \frac{\partial}{\partial x^2} (0) + (\underbrace{\Gamma_{21}^1 \Gamma_{22}^1}_0 - \underbrace{\Gamma_{21}^1 \Gamma_{22}^1}_0 + \underbrace{\Gamma_{22}^1 \Gamma_{22}^2}_0 - \underbrace{\Gamma_{22}^1 \Gamma_{22}^2}_0) \\ &= 0 - 0 + 0 \\ &= 0 \end{aligned}$$

$$(3) \nabla_{\frac{\partial}{\partial x^i}} \left(\frac{\partial}{\partial x^j} \right) \stackrel{?}{=} \nabla_{\frac{\partial}{\partial x^j}} \left(\frac{\partial}{\partial x^i} \right)$$

(∇ : 平行移動接続)

$$\left(\begin{array}{c} \text{1. 補} \\ \left[\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right] = 0 \end{array} \right)$$

$R \neq 0$

(M, g): 平坦でない リーマンメトリック

∂x | R : リーマン曲率テンソル

$$(4) \nabla_{\partial^{\bar{i}}} \partial^{\bar{j}} - \nabla_{\partial^{\bar{j}}} \partial^{\bar{i}} = [\partial^{\bar{i}}, \partial^{\bar{j}}] = 0$$

$$R_{\partial^{\bar{i}} \partial^{\bar{j}}} \partial^{\bar{k}} \stackrel{?}{=} R_{\partial^{\bar{j}} \partial^{\bar{i}}} \partial^{\bar{k}}$$

曲率作用素の反対称性: $R_{XY} = -R_{YX}$

$$\nabla_{\partial^{\bar{i}}} \partial^{\bar{j}} = \nabla_{\partial^{\bar{j}}} \partial^{\bar{i}}$$

局所座標系で成り立つ

一般のベクトル場
 $X, Y, Z \in \mathfrak{X}(M)$
成り立つ

$$R_{\partial^{\bar{i}} \partial^{\bar{j}}} \partial^{\bar{k}} = \nabla_{[\partial^{\bar{i}}, \partial^{\bar{j}}]} \partial^{\bar{k}}$$

$$= (\nabla_{\partial^{\bar{i}}} \nabla_{\partial^{\bar{j}}} \partial^{\bar{k}} - \nabla_{\partial^{\bar{j}}} \nabla_{\partial^{\bar{i}}} \partial^{\bar{k}})$$