: reduce tensor product Algorithm formula "ijk = -jik = ikj"
and ineps of each index  $\begin{cases} i = 1e \\ k = 1e \end{cases}$ input: change of basis Q output: Q shape is (\*\*actual deg-of freedom, d, ..., dn) Crank

Current implementation:

@ germinate formula: create a group from the input

2 create basis P from perm. symmetry

3) create basis Q from Clebsch-Gordan coeff.

(4) find projectors into the intersection of Pand Q (see next page)

(5) choose a basis using orthonormatize (6) create the change of basis

- 1) is fast and memory cheap
- 2) is same size as the output
- 3) is memory expensive
- (4) is memory expensive and slow
- 5 is ok
- 6 is ok
- 2 and 6 create large objects but 3 is even larger

@ defails

$$P \in \mathbb{R}^{P \times d}$$

$$Q \in \mathbb{R}^{q \times d}$$

look for 
$$(x,y) \in \mathbb{R}^P \times \mathbb{R}^q$$
 such that  $x^T P = y^T Q$ 

which can be rewritten in the form:

solutions of (x) are also solutions of:

$$(x^{T} y^{T}) \begin{pmatrix} P \\ -Q \end{pmatrix} (P^{T} - Q^{T}) = 0$$

$$\begin{pmatrix} PP^{T} & -PQ^{T} \\ -(PQ^{T})^{T} & QQ^{T} \end{pmatrix}$$