

Title

code - courseName

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```
source("chrisFunctions.r")
library(ggplot2)
```

GARCH

GARCH(p, q) is given by

$$r_t = \sigma_t \epsilon_t, \quad (1)$$

$$\sigma_t^2 = \alpha_0 + \sum_{j=1}^p \alpha_j r_{t-j}^2 + \sum_{j=1}^q \beta_j \sigma_{t-j}^2. \quad (2)$$

It can be shown that a GARCH(p, q) admits a non-Gaussian ARMA(p, q) for the squared process

$$r_t^2 \quad (3)$$

acf and pacf

For fun we consider the simple acf and pacf of the difference

$$\nabla x_t = x_t - x_{t-1}$$

```
d = diff(df$Inflation)
par(mfrow = c(2, 2))
dacf = sampleAcf(d, 22)
dacf2 = acf(d)

dpacf = samplePacf(d, 22)
dpacf2 = pacf(d)
```

Now let's look at the return

$$\nabla r_t = \frac{x_t - x_{t-1}}{x_{t-1}}. \quad (4)$$

Problem: Some values are zero. Let's make sure that they are not. (Should not matter since we are looking at variance, right?)

```
n = dim(df)[1]
shift = min(df$Inflation - 0.1)
inflationShifted = df$Inflation - shift
r = diff(inflationShifted)/inflationShifted[1:(n - 1)]
par(mfrow = c(1, 2))
dacf = sampleAcf(r, 22)

dpacf = samplePacf(r, 22)
```

Finally, let's consider the squared return, which is supposed to be ARMA(p, q)

```
par(mfrow = c(1, 2))
dacf = sampleAcf(r^2, 22)

dpacf = samplePacf(r^2, 22) # Verified with pacf fnc.
```

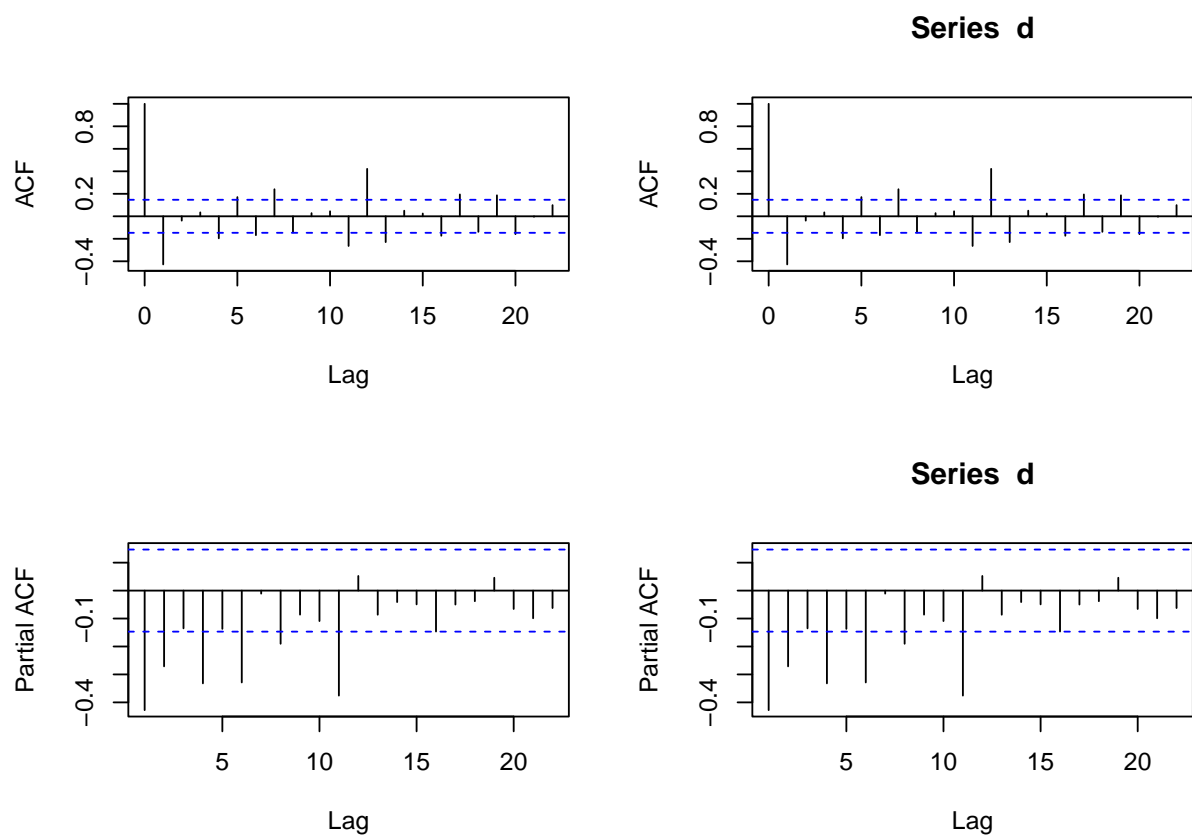


Figure 1: Manual to the left and built-in to the right

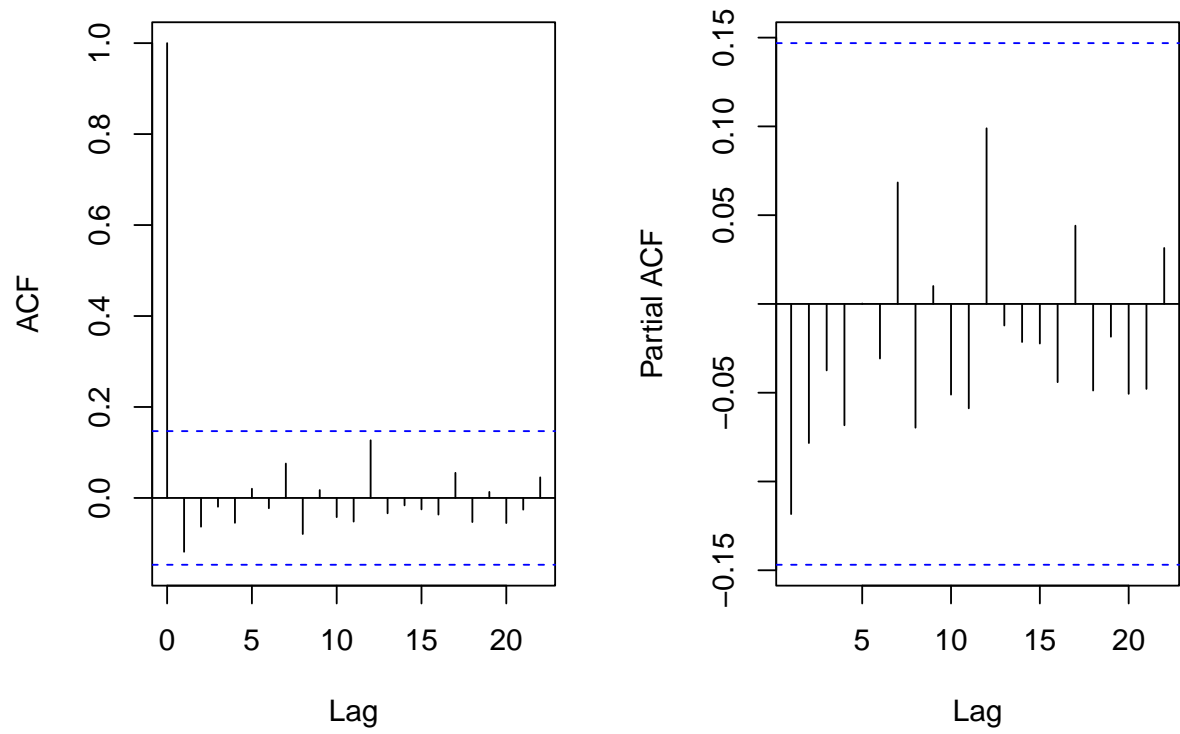


Figure 2: Return

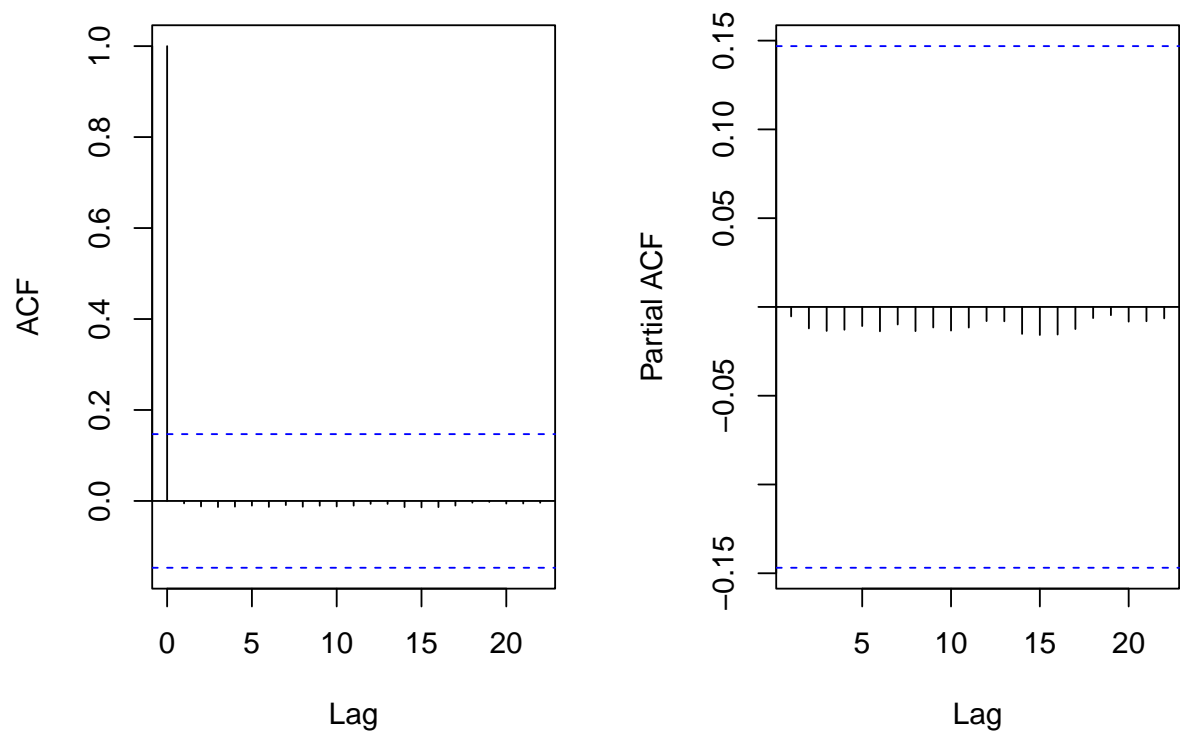


Figure 3: Squared return

Table 3.1. Behavior of the ACF and PACF for ARMA models

	AR(p)	MA(q)	ARMA(p, q)
ACF	Tails off	Cuts off after lag q	Tails off
PACF	Cuts off after lag p	Tails off	Tails off

(5)

GARCH(p,q) Implementation

Definitions for notational purposes:

- $\mathcal{R}_1 = (r_1, \dots, r_{\max(p,q)})$
- $\mathcal{R}_2 = (r_t, \dots, r_{t+\max(p,q)})$
- $\boldsymbol{\alpha} = (\alpha_0, \dots, \alpha_p)$
- $\boldsymbol{\beta} = (\beta_1, \dots, \beta_q)$
- $\mathbf{r}_{tp} = (1, r_{t-1}, \dots, r_{t-p})^\top$
- $\boldsymbol{\sigma}_{tq}^2 = (\sigma_{t-1}^2, \dots, \sigma_{t-q}^2)^\top$

It can be shown that $r_t | \mathcal{R}_2 \sim \mathcal{N}(0, \sigma_t^2)$, $\mathcal{R}_2 = (r_t, \dots, r_{t+\max(p,q)})$. Because of the normality of the conditional return we can find MLE of $\boldsymbol{\alpha}$ and $\boldsymbol{\beta}$ parameters. That is, the likelihood to be maximized is given by

$$\begin{aligned}
L(\boldsymbol{\alpha}, \boldsymbol{\beta} | \mathcal{R}_1) &= \prod_{t=\max(p,q)+1}^n f_{\boldsymbol{\alpha}, \boldsymbol{\beta}}(r_t | \mathcal{R}_2) \\
&= \prod_{t=\max(p,q)+1}^n (2\pi\sigma_t^2)^{-1/2} \exp\left(-\frac{1}{2} \frac{r_t^2}{\sigma_t^2}\right),
\end{aligned} \tag{6}$$

where $\mathcal{R}_1 = (r_1, \dots, r_{\max(p,q)})$ and σ_t^2 is given by equation (2). We define the criterion function l to be minimized as proportional to $-\ln L$, such that

$$\begin{aligned}
l(\boldsymbol{\alpha}, \boldsymbol{\beta} | \mathcal{R}_1) &= \sum_{t=\max(p,q)+1}^n \ln(\sigma_t^2) + \frac{r_t^2}{\sigma_t^2} \\
&= \sum_{t=\max(p,q)+1}^n \ln\left(\alpha_0 + \sum_{j=1}^p \alpha_j r_{t-j}^2 + \sum_{j=1}^q \beta_j \sigma_{t-j}^2\right) + \frac{r_t^2}{\alpha_0 + \sum_{j=1}^p \alpha_j r_{t-j}^2 + \sum_{j=1}^q \beta_j \sigma_{t-j}^2} \\
&= \sum_{t=\max(p,q)+1}^n \ln(\boldsymbol{\alpha} \mathbf{r}_{tp} + \boldsymbol{\beta} \boldsymbol{\sigma}_{tq}^2) + \frac{r_t^2}{\boldsymbol{\alpha} \mathbf{r}_{tp} + \boldsymbol{\beta} \boldsymbol{\sigma}_{tq}^2},
\end{aligned} \tag{7}$$

where $\mathbf{r}_{tp} = (1, r_{t-1}, \dots, r_{t-p})^\top$ and $\boldsymbol{\sigma}_{tq}^2 = (\sigma_{t-1}^2, \dots, \sigma_{t-q}^2)^\top$