**Class:** Final Year (Computer Science and Engineering)

**Year:** 2022-23 **Semester:** 1

**Course:** High Performance Computing Lab

### **Practical No. 9**

Exam Seat No: 2019BTECS00070

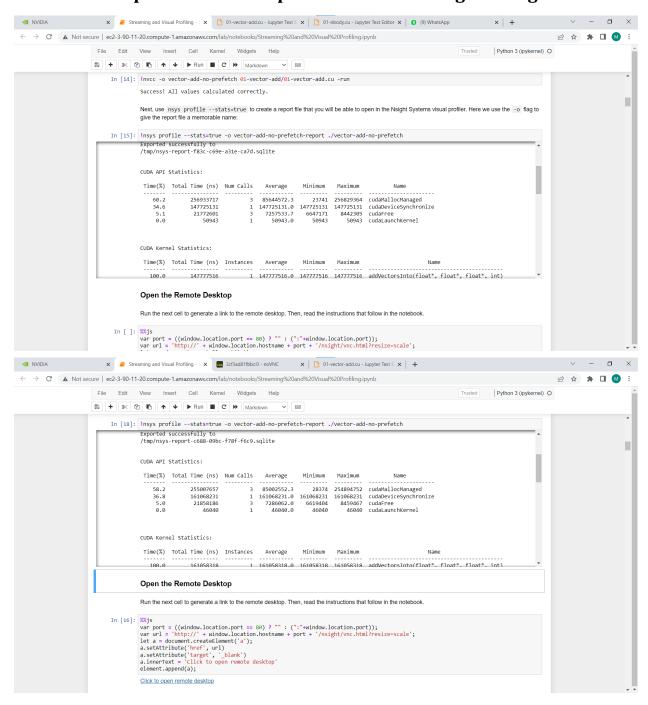
Name - Prathmesh Killedar

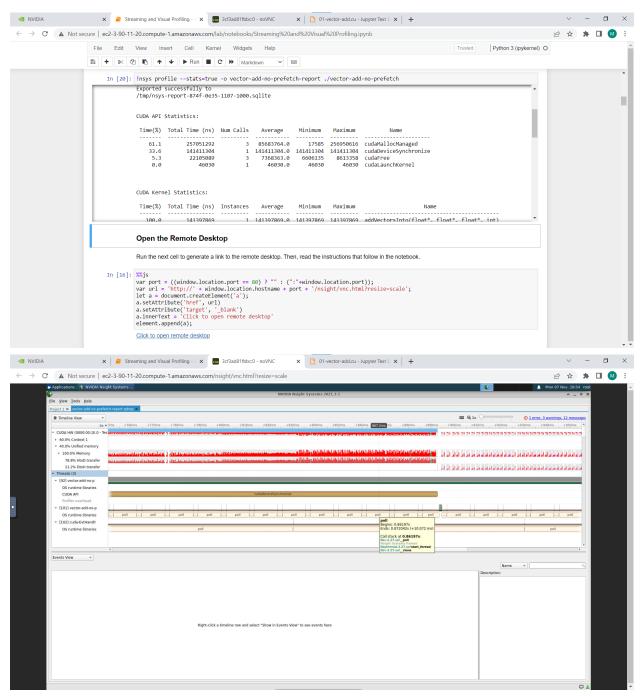
### **Problem Statement 1:**

Implement Vector-Vector addition using CUDA C. State and justify the speedup using different size of threads and blocks.

### Screenshot #:

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#### Information #:

#include <stdio.h>

void initWith(float num, float \*a, int N)

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```
{
       for(int i = 0; i < N; ++i)
       {
              a[i] = num;
       }
}
  _global___ void addVectorsInto(float *result, float *a, float *b, int N)
       int index = threadIdx.x + blockIdx.x * blockDim.x;
       int stride = blockDim.x * gridDim.x;
       for(int i = index; i < N; i += stride)
              result[i] = a[i] + b[i];
       }
}
void checkElementsAre(float target, float *vector, int N)
{
       for(int i = 0; i < N; i++)
              if(vector[i] != target)
                     printf("FAIL: vector[%d] - %0.0f does not equal %0.0f\n",
i, vector[i], target);
                     exit(1);
              }
       printf("Success! All values calculated correctly.\n");
}
int main()
{
```

```
int deviceId;
      int numberOfSMs;
      cudaGetDevice(&deviceId);
      cudaDeviceGetAttribute(&numberOfSMs,
cudaDevAttrMultiProcessorCount, deviceId);
      const int N = 2 << 24;
      size_t size = N * sizeof(float);
      float *a;
      float *b;
      float *c;
      cudaMallocManaged(&a, size);
      cudaMallocManaged(&b, size);
      cudaMallocManaged(&c, size);
      initWith(3, a, N);
      initWith(4, b, N);
      initWith(0, c, N);
      size t threadsPerBlock;
      size t numberOfBlocks;
      threadsPerBlock = 256;
      numberOfBlocks = 32 * numberOfSMs;
      cudaError t addVectorsErr;
      cudaError t asyncErr;
      addVectorsInto<<<numberOfBlocks, threadsPerBlock>>>(c, a, b, N);
      addVectorsErr = cudaGetLastError();
```

```
if(addVectorsErr != cudaSuccess) printf("Error: %s\n",
cudaGetErrorString(addVectorsErr));

asyncErr = cudaDeviceSynchronize();
if(asyncErr != cudaSuccess) printf("Error: %s\n",
cudaGetErrorString(asyncErr));

checkElementsAre(7, c, N);

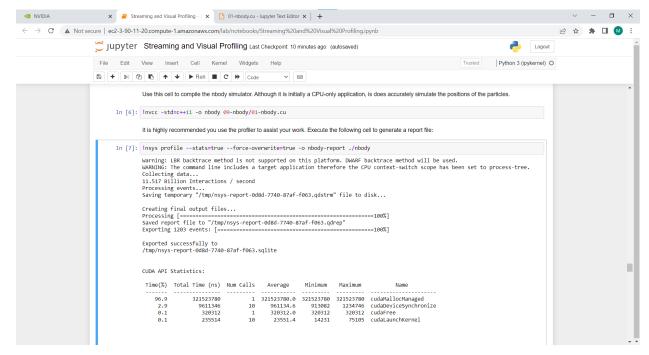
cudaFree(a);
cudaFree(b);
cudaFree(c);
}
```

### **Problem Statement 2:**

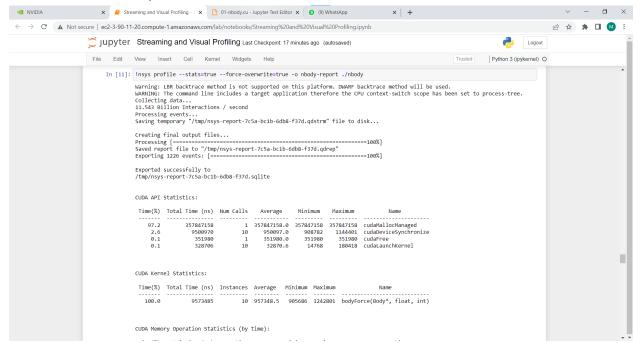
Implement N-Body Simulator using CUDA C. State and justify the speedup using different size of threads and blocks.

### Screenshot #:

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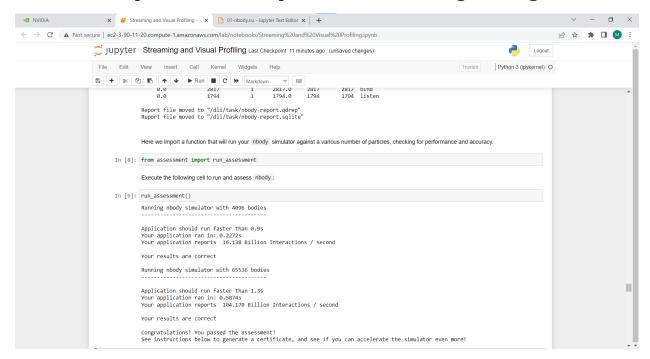


### Number of thread per block – 32 with block size 1024

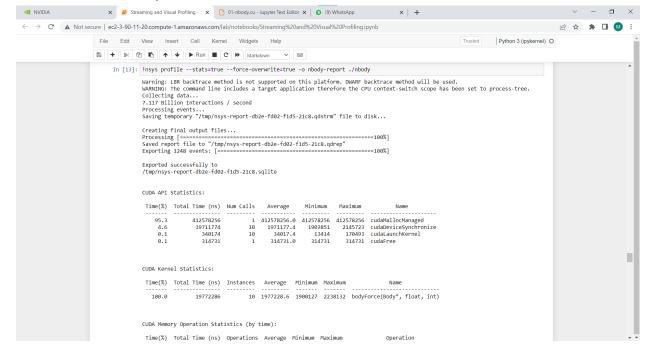


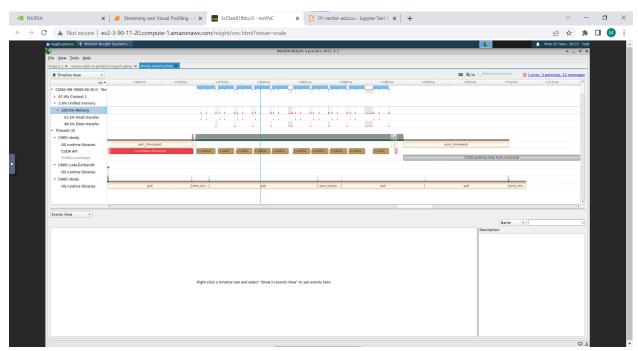
Number of thread per block – 32 with block size 512

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### Number of thread per block – 4 with block size 1024





### Information #:

```
#include <math.h>
#include <stdio.h>
#include <stdlib.h>
#include "timer.h"
#include "files.h"

#define SOFTENING 1e-9f

typedef struct { float x, y, z, vx, vy, vz; } Body;

__global___ void bodyForce(Body *p, float dt, int n) {
    int index = threadIdx.x + blockIdx.x * blockDim.x; int stride = blockDim.x * gridDim.x;
    for(int i = index; i < N; i += stride)
    {
}</pre>
```

```
float Fx = 0.0f; float Fy = 0.0f; float Fz = 0.0f;
             for (int j = 0; j < n; j++)
             {
                    float dx = p[i].x - p[i].x;
                    float dy = p[j].y - p[i].y;
                    float dz = p[i].z - p[i].z;
                    float distSqr = dx*dx + dy*dy + dz*dz + SOFTENING;
                    float invDist = rsqrtf(distSqr);
                    float invDist3 = invDist * invDist * invDist;
                    Fx += dx * invDist3; Fy += dy * invDist3; Fz += dz *
invDist3;
             }
             p[i].vx += dt*Fx; p[i].vy += dt*Fy; p[i].vz += dt*Fz;
      }
}
int main(const int argc, const char** argv)
{
      // The assessment will test against both 2<11 and 2<15.
      // Feel free to pass the command line argument 15 when you
generate ./nbody report files
      y report files
      int nBodies = 2 << 11;
      if (argc > 1) nBodies = 2<<atoi(argv[1]);
      // The assessment will pass hidden initialized values to check for
correctness.
      // You should not make changes to these files, or else the assessment
will not work.
      const char * initialized_values;
```

```
const char * solution values;
if (nBodies == 2<<11)
{
      initialized values = "09-nbody/files/initialized 4096";
      solution values = "09-nbody/files/solution 4096";
}
else
{ // nBodies == 2<<15
      initialized values = "09-nbody/files/initialized 65536";
      solution values = "09-nbody/files/solution 65536";
}
if (argc > 2)
      initialized values = argv[2];
if (argc > 3)
      solution_values = argv[3];
const float dt = 0.01f; // Time step
const int nIters = 10; // Simulation iterations
int bytes = nBodies * sizeof(Body);
float *buf;
buf = (float *)malloc(bytes);
cudaMallocManaged(&buf, bytes)
Body *p = (Body*)buf;
read values from file(initialized values, buf, bytes);
double totalTime = 0.0;
for (int iter = 0; iter < nlters; iter++) {
```

```
StartTimer();
            bodyForce<<<1024,32>>>(p, dt, nBodies); // compute
interbody forces
             cudaDeviceSynchronize();
             for (int i = 0; i < nBodies; i++)
             { // integrate position
                   p[i].x += p[i].vx*dt;
                   p[i].y += p[i].vy*dt;
                   p[i].z += p[i].vz*dt;
             }
            const double tElapsed = GetTimer() / 1000.0;
             totalTime += tElapsed;
      }
      double avgTime = totalTime / (double)(nIters);
      float billionsOfOpsPerSecond = 1e-9 * nBodies * nBodies / avgTime;
      write values to file(solution values, buf, bytes);
      printf("%0.3f Billion Interactions / second\n",
billionsOfOpsPerSecond);
      cudaFree(buf);
}
```

### **Github Link:**

 $\frac{https://github.com/killedar27/HPC-assignments/blob/main/assignment9/code/Vector-vectorAddition.cp}{\underline{p}}$ 

https://github.com/killedar27/HPC-assignments/blob/main/assignment9/code/n-body.cpp