15.9

# Change of Variables in Multiple Integrals

In one-dimensional calculus we often use a change of variable (a substitution) to simplify an integral. By reversing the roles of *x* and *u*, we can write

$$\int_a^b f(x) \ dx = \int_c^d f(g(u)) g'(u) \ du$$

where x = g(u) and a = g(c), b = g(d). Another way of writing Formula 1 is as follows:

$$\int_{a}^{b} f(x) dx = \int_{c}^{d} f(x(u)) \frac{dx}{du} du$$

We consider a change of variables that is given by a **transformation** *T* from the *uv*-plane to the *xy*-plane:

$$T(u, v) = (x, y)$$

where x and y are related to u and v by the equations

or, as we sometimes write,

$$X = X(U, V)$$
  $Y = Y(U, V)$ 

We usually assume that T is a  $C^1$  transformation, which means that g and h have continuous first-order partial derivatives.

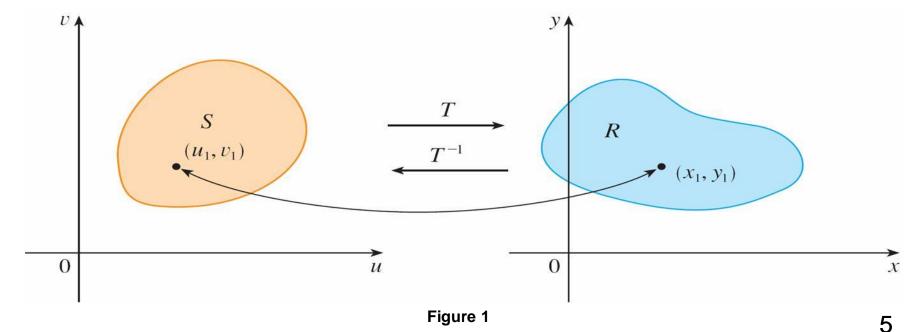
A transformation T is really just a function whose domain and range are both subsets of  $\mathbb{R}^2$ .

If  $T(u_1, v_1) = (x_1, y_1)$ , then the point  $(x_1, y_1)$  is called the **image** of the point  $(u_1, v_1)$ .

If no two points have the same image, *T* is called **one-to-one**.

Figure 1 shows the effect of a transformation *T* on a region *S* in the *uv*-plane.

T transforms S into a region R in the xy-plane called the **image of S**, consisting of the images of all points in S.



If T is a one-to-one transformation, then it has an **inverse** transformation  $T^{-1}$  from the xy-plane to the uv-plane and it may be possible to solve Equations 3 for u and v in terms of x and y:

$$u = G(x, y)$$
  $v = H(x, y)$ 

## Example 1

A transformation is defined by the equations

$$X = U^2 - V^2$$

$$y = 2uv$$

Find the image of the square

$$S = \{(u, v) \mid 0 \le u \le 1, 0 \le v \le 1\}.$$

# Example 1

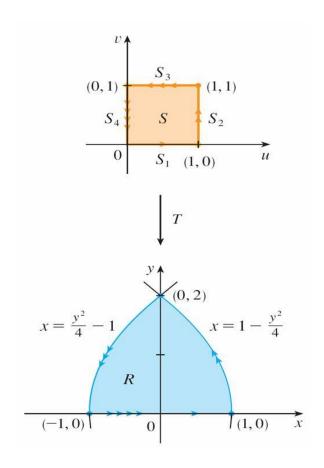


Figure 2

Now let's see how a change of variables affects a double integral. We start with a small rectangle S in the uv-plane whose lower left corner is the point  $(u_0, v_0)$  and whose dimensions are  $\Delta u$  and  $\Delta v$ . (See Figure 3.)

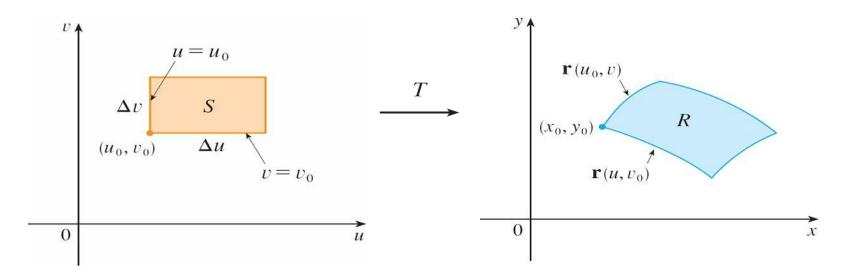


Figure 3

The image of S is a region R in the xy-plane, one of whose boundary points is  $(x_0, y_0) = T(u_0, v_0)$ .

The vector

$$\mathbf{r}(u, v) = g(u, v) \mathbf{i} + h(u, v) \mathbf{j}$$

is the position vector of the image of the point (u, v).

The equation of the lower side of S is  $v = v_0$ , whose image curve is given by the vector function  $\mathbf{r}(u, v_0)$ .

The tangent vector at  $(x_0, y_0)$  to this image curve is

$$\mathbf{r}_{u} = g_{u}(u_{0}, v_{0}) \mathbf{i} + h_{u}(u_{0}, v_{0}) \mathbf{j}$$
$$= \frac{\partial x}{\partial u} \mathbf{i} + \frac{\partial y}{\partial u} \mathbf{j}$$

Similarly, the tangent vector at  $(x_0, y_0)$  to the image curve of the left side of S (namely,  $u = u_0$ ) is

$$\mathbf{r}_{v} = g_{v}(u_{0}, v_{0}) \mathbf{i} + h_{v}(u_{0}, v_{0}) \mathbf{j}$$
$$= \frac{\partial x}{\partial v} \mathbf{i} + \frac{\partial y}{\partial v} \mathbf{j}$$

We can approximate the image region R = T(S) by a parallelogram determined by the secant vectors

$$\mathbf{a} = \mathbf{r}(u_0 + \Delta u, v_0) - \mathbf{r}(u_0, v_0)$$
  $\mathbf{b} = \mathbf{r}(u_0, v_0 + \Delta v) - \mathbf{r}(u_0, v_0)$ 

shown in Figure 4.

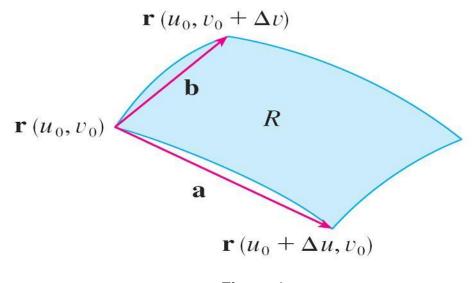


Figure 4

But

$$\mathbf{r}_{u} = \lim_{\Delta u \to 0} \frac{\mathbf{r}(u_0 + \Delta u, v_0) - \mathbf{r}(u_0, v_0)}{\Delta u}$$

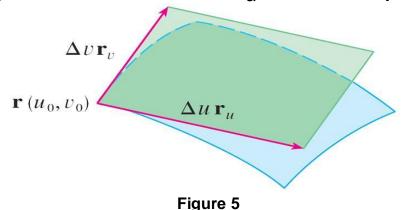
and so

$$\mathbf{r}(u_0 + \Delta u, v_0) - \mathbf{r}(u_0, v_0) \approx \Delta u \mathbf{r}_u$$

Similarly

$$\mathbf{r}(u_0, v_0 + \Delta v) - \mathbf{r}(u_0, v_0) \approx \Delta v \mathbf{r}_v$$

This means that we can approximate R by a parallelogram determined by the vectors  $\Delta u \mathbf{r}_{u}$  and  $\Delta v \mathbf{r}_{v}$ . (See Figure 5.)



Therefore, we can approximate the area of R by the area of this parallelogram, which is

$$|(\Delta u \mathbf{r}_u) \times (\Delta v \mathbf{r}_v)| = |\mathbf{r}_u \times \mathbf{r}_v| \Delta u \Delta v$$

Computing the cross product, we obtain

$$\mathbf{r}_{u} \times \mathbf{r}_{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & 0 \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & 0 \end{vmatrix} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} \mathbf{k} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} \mathbf{k}$$

The determinant that arises in this calculation is called the *Jacobian* of the transformation and is given a special notation.

**Definition** The **Jacobian** of the transformation 
$$T$$
 given by  $x = g(u, v)$  and  $y = h(u, v)$  is 
$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$

With this notation we can use Equation 6 to give an approximation to the area  $\Delta A$  of R:

8 
$$\Delta A \approx \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \, \Delta v$$

where the Jacobian is evaluated at  $(u_0, v_0)$ .

Next we divide a region S in the uv-plane into rectangles  $S_{ij}$  and call their images in the xy-plane  $R_{ij}$ . (See Figure 6.)

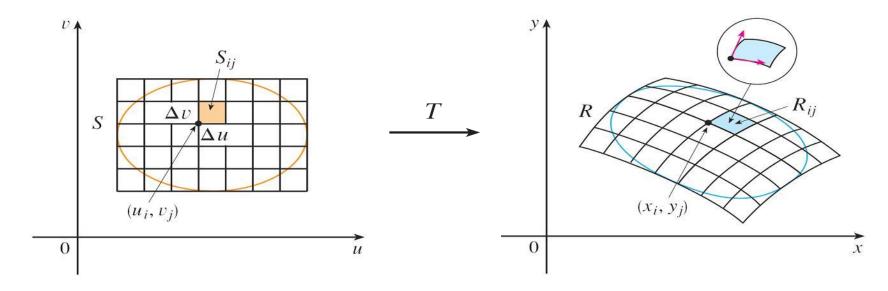


Figure 6

Applying the approximation (8) to each  $R_{ij}$ , we approximate the double integral of f over R as follows:

$$\iint\limits_R f(x, y) \ dA \approx \sum_{i=1}^m \sum_{j=1}^n f(x_i, y_j) \ \Delta A$$

$$pprox \sum_{i=1}^m \sum_{j=1}^n f(g(u_i, v_j), h(u_i, v_j)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| \Delta u \Delta v$$

where the Jacobian is evaluated at  $(u_i, v_j)$ . Notice that this double sum is a Riemann sum for the integral

$$\iint_{S} f(g(u, v), h(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

The foregoing argument suggests that the following theorem is true.

**9** Change of Variables in a Double Integral Suppose that T is a  $C^1$  transformation whose Jacobian is nonzero and that maps a region S in the uv-plane onto a region R in the xy-plane. Suppose that f is continuous on R and that R and S are type I or type II plane regions. Suppose also that T is one-to-one, except perhaps on the boundary of S. Then

$$\iint\limits_R f(x, y) dA = \iint\limits_S f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

Theorem 9 says that we change from an integral in x and y to an integral in u and v by expressing x and y in terms of u and v and writing

 $dA = \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$ 

The requirements about the type of R and S are not essential.

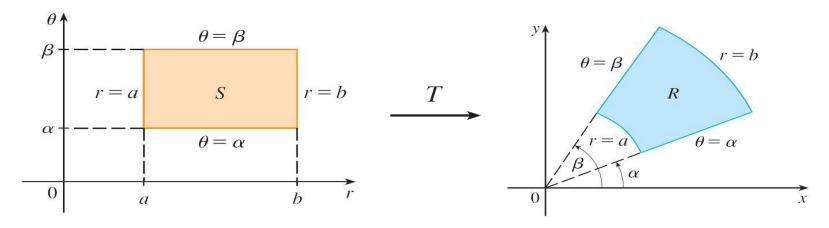
Notice the similarity between Theorem 9 and the one-dimensional formula in Equation 2.

Instead of the derivative dx/du, we have the absolute value of the Jacobian, that is,  $|\partial(x, y)/\partial(u, v)|$ .

As a first illustration of Theorem 9, we show that the formula for integration in polar coordinates.

#### Example: Polar coordinates

Derive the formula for double integration in polar coordinates



The polar coordinate transformation

## **Triple Integrals**

## Triple Integrals

There is a similar change of variables formula for triple integrals.

Let *T* be a transformation that maps a region *S* in *uvw*-space onto a region *R* in *xyz*-space by means of the equations

$$x = g(u, v, w)$$
  $y = h(u, v, w)$   $z = k(u, v, w)$ 

## Triple Integrals

The **Jacobian** of T is the following  $3 \times 3$  determinant:

$$\frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{vmatrix}
\frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\
\frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\
\frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w}
\end{vmatrix}$$

Under hypotheses similar to those in Theorem 9, we have the following formula for triple integrals:

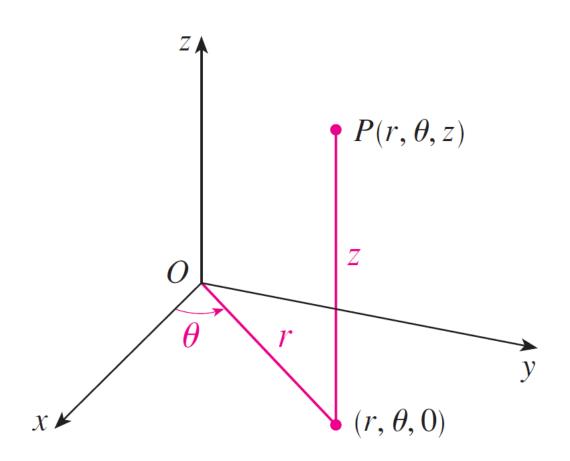
$$\iiint\limits_R f(x, y, z) \ dV = \iiint\limits_S f(x(u, v, w), y(u, v, w), z(u, v, w)) \left| \frac{\partial(x, y, z)}{\partial(u, v, w)} \right| \ du \ dv \ dw$$

## Example

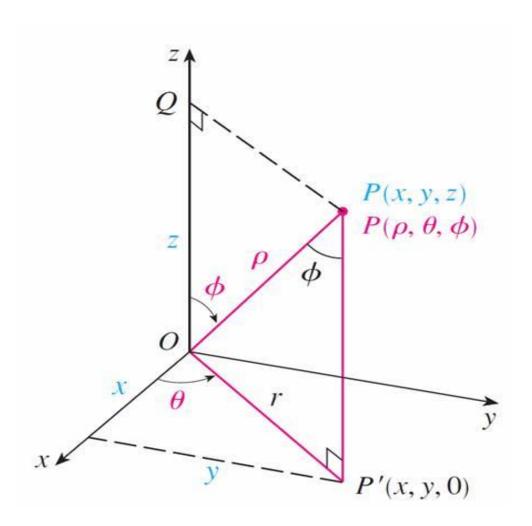
Use Formula 13 to derive the formula for triple integration in

- (a) cylindrical coordinates about the z-axis;
- (b) spherical coordinates.

# Cylindrical coordinates



# Spherical coordinates



## Example (15.8/Example 4)

Use spherical coordinates to find the volume of the solid that lies above the cone  $z = \sqrt{x^2 + y^2}$  and below the sphere  $x^2 + y^2 + z^2 = z$ . (See Figure 9.)

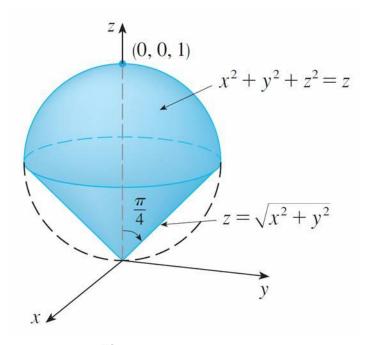


Figure 9