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# AMSC 460 - HW10

```
clear all; format compact; close all; syms f(x) x y z
```

## Problem 1 (finished)(AFFRImative)

Consider the following system of equations.  $f_1(x, y, z) = x^2 + y^2 + z^2 - 1 = 0$ ,  $f_2(x, y, z) = 2x^2 + y^2 - 2z = 0$ ,  $f_3(x, y, z) = 3x^2 - 4y + z^2 = 0$ . This system can be concisely represented as  $F(x) = 0$ , where  $F(x) = (f_1, f_2, f_3)^T$ ,  $x = (x, y, z)^T$  and  $0 = (0, 0, 0)^T$ .

(i) Find the Jacobian matrix  $DF(x)$ .

```
f1(x, y, z) = x^2 + y^2 + z^2 - 1;
f2(x, y, z) = 2*x^2 + y^2 - 2*z;
f3(x, y, z) = 3*x^2 - 4*y + z^2;
F = @(x,y,z) [f1(x,y,z);f2(x,y,z); f3(x,y,z)];
DFx = jacobian([x^2 + y^2 + z^2, 2*x^2 + y^2 - 2*z, 3*x^2 - 4*y + z^2],
    [x, y, z])
```

```
DFx =
[2*x, 2*y, 2*z]
[4*x, 2*y, -2]
[6*x, -4, 2*z]
```

(ii) (MATLAB) Starting with the initial condition  $x_0 = (0.5, 0.5, 0.5)^T$ , implement 5 steps of the multi-variable Newton method to find the approximation  $x_5$ .

```
x0 = [0.5; 0.5 ; 0.5]
i = 0;
while i < 5
    DFx0(1,1) = 2*x0(1); DFx0(1,2) = 2*x0(2); DFx0(1,3) = 2*x0(3);
    DFx0(2,1) = 4*x0(1); DFx0(2,2) = 2*x0(2); DFx0(2,3) = -2;
    DFx0(3,1) = 6*x0(1); DFx0(3,2) = -4; DFx0(3,3) = 2*x0(3);
    Fx0 = [ (x0(1)^2 + x0(2)^2 + x0(3)^2 - 1) ; (2*x0(1)^2 + x0(2)^2 - 2*x0(3)); (3*x0(1)^2 - 4*x0(2) + x0(3)^2)];
    S = DFx0\Fx0;
    x1 = x0 - S;
    x0 = x1
    i = i+1;
    fprintf('\tAfter %g steps\n', i)
end

x0 =
    0.5000
    0.5000
    0.5000
x0 =
    0.7308
    0.4423
    0.5769
    After 1 steps
x0 =
    0.6918
```

