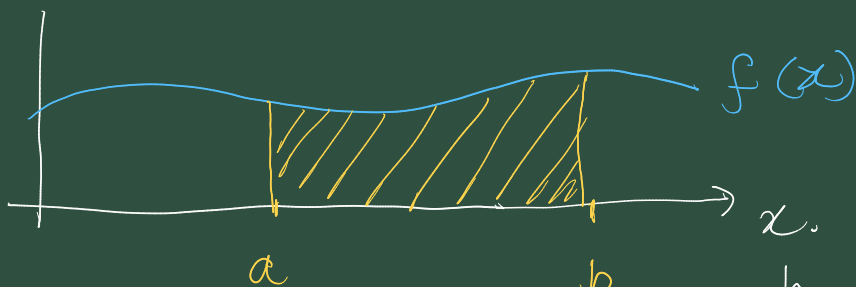


Integration in multi-variable calculus

Two types of integral.

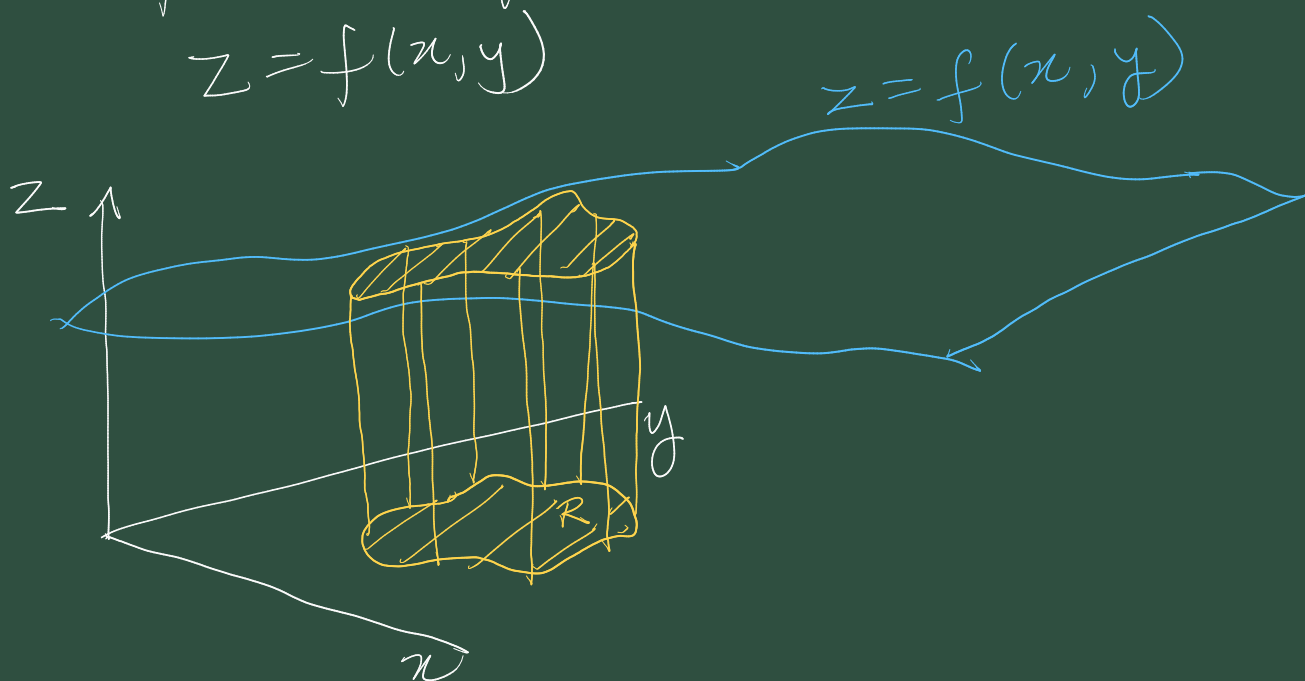
Recall single-variable definite integrals



The definite integral $I = \int_a^b f(x) dx$ gives the area between the graph and x -axis over the interval $a \leq x \leq b$.

For functions of 2-variables

$$z = f(x, y)$$

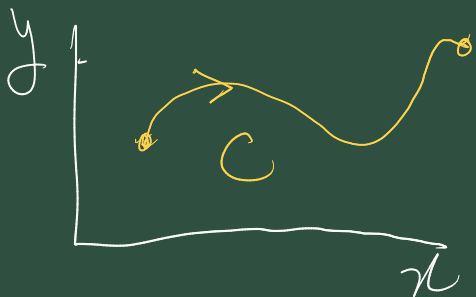


The volume between the surface and the xy -plane over the region R is given by what's called the double integral of f over R , written as:

$$I = \iint_R f(x, y) \, dx \, dy. \quad (\text{next week}).$$

We also have "line integrals" or "path integrals" of linear differential forms L .

$L = P(x, y) \, dx + Q(x, y) \, dy$
taken over paths in the xy -plane expressed as



$$J = \int_C L$$

$$= \int_C P dx + Q dy.$$

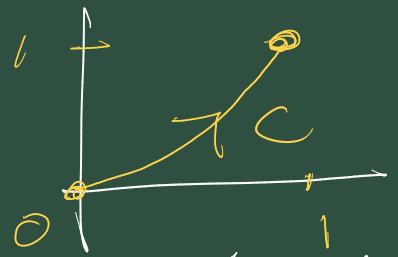
(geometric interpretation not so immediately available). But such integrals arise in maths and physics.

Example 0.1

Consider $I = \int_C 10x^2y dx + (3x+2y) dy$
integrate this along the curve

$C: y = x^2$ from $(0,0)$ to $(1,1)$.

Idea: Convert the path integral into a standard 1-variable integral using the specification of C .



$C: y = x^2, dy = 2x dx$

Use these substitutions to transform the path integral.

$$I = \int_C 10x^2y dx + (3x+2y) dy.$$

$$= \int_0^1 10x^4 dx + (3x + 2x^2)2x dx$$

$$= \int_0^1 (10x^4 + 4x^3 + 6x^2) dx.$$

$$= \left[2x^5 + x^4 + 2x^3 \right]_0^1 = 5.$$

Theorem Basic properties of path integrals.

(generalisations of properties we're familiar with for single variable integrals)

1. Linearity. For $\alpha, \beta \in \mathbb{R}$, L_1, L_2 linear differentials forms

$$\int_C \alpha L_1 + \beta L_2$$

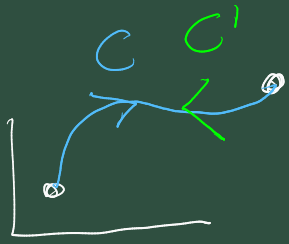
$$= \alpha \int_C L_1 + \beta \int_C L_2.$$

OR $\int_C P(x, y) dx + Q(x, y) dy$

$$= \int_C P(x, y) dx + \int_C Q(x, y) dy.$$

(cf. $\int_a^b (\alpha f_1(x) + \beta f_2(x)) dx$
 $= \alpha \int_a^b f_1(x) dx + \beta \int_a^b f_2(x) dx$).

2. Direction of integration.

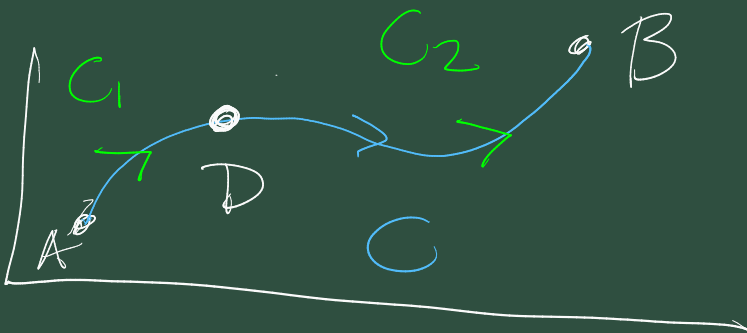


For a 1-form \$L\$.

$$\int_C L = - \int_{C'} L$$

(cf. $\int_a^b f(x) dx = - \int_b^a f(x) dx$)

3. Subdividing the path / curve.



$$C_1: A \rightarrow D$$

$$C_2: D \rightarrow B$$

$$C: A \rightarrow B$$

$$\int_C L = \int_{C_1} L + \int_{C_2} L$$

cf.

$$\int_a^b f(x) dx = \int_a^d f(x) dx + \int_d^b f(x) dx$$



Example 02 Same L as before.

$$L = 10x^2y dx + (3x + 2y) dy$$

Integrate this from $A = (0,0)$ to $B = (1,1)$ along the two straight line segments.

AD, DB where $D = (1,0)$.

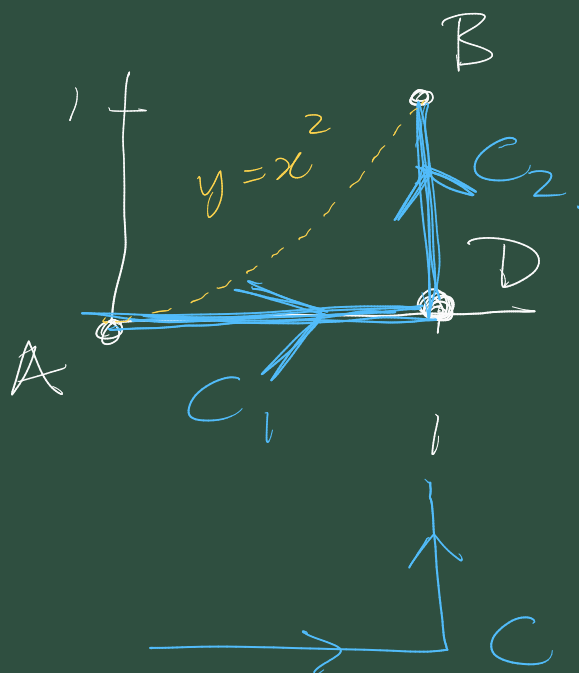
$$C = C_1 + C_2$$

$$\int_C L$$

C

$$= \int_{C_1} L + \int_{C_2} L$$

On C_1 : $y=0, dy=0$
 $x: 0 \rightarrow 1$



On C_2 : $x=1, dx=0$

$$y: 0 \rightarrow 1.$$

$$\oint_{C_1} L = \int_0^1 0 \, dx = 0$$

$$\begin{aligned} \int_{C_2} L &= \int_0^1 (3 + 2y) \, dy \\ &= [3y + y^2]_0^1 = 4. \end{aligned}$$

$$\text{And so } \int_C L = 0 + 4 = 4.$$

which is different to previous result integrating along $y=x^2$ from A to B.

This is known as path dependence and is the

typical expected behaviour
of such integrals.

But there are special
"path independent" linear
differential forms which
we'll meet later.

Parametrized paths

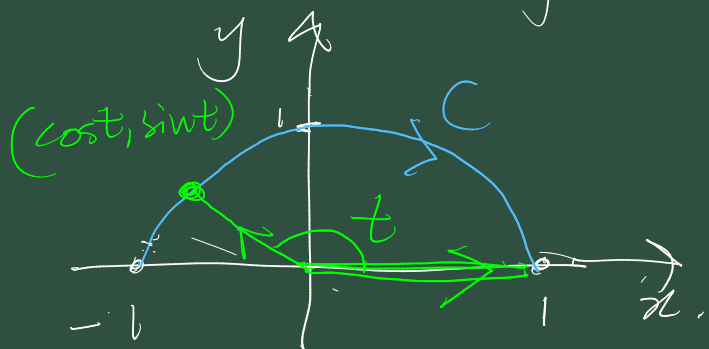
Example 0.3 Evaluate I .

$$I = \int_C x^2 dy - yx dx.$$

where C is the semi-circular path
of radius 1 traversed clockwise from
 $(-1, 0)$ to $(1, 0)$

The curve C is
parametrized as

$$(x, y) = (\cos(t), \sin(t))$$



for $t: \pi \rightarrow 0$

Use this to translate I into a single-variable t -integral

$$\begin{cases} x = \cos(t) & , \quad dx = -\sin(t) dt \\ y = \sin(t) & , \quad dy = \cos(t) dt. \end{cases}$$

So

$$I = \int_{\pi}^0 \cos^3(t) dt + \sin^2(t) \cos(t) dt.$$

$$= \int_{\pi}^0 \cos(t) \underbrace{(\cos^2(t) + \sin^2(t))}_{=1} dt.$$

$$= \int_{\pi}^0 \cos(t) dt$$

$$= \left[\sin(t) \right]_{\pi}^0 = \sin(0) - \sin(\pi) \\ = 0 - 0 = 0$$

Question

Compute the integral J .

$$J = \int_C x e^y dx + x^2 y dy$$

But if $x^2 = e^y$ then $\textcircled{2}$ ensures $\frac{\partial g}{\partial x} = 0$

$$\frac{\partial g}{\partial y} = 0$$

$$\Leftrightarrow e^{2y} - 4e^{4y} = 0.$$

$$\Leftrightarrow e^{2y}(1 - 4e^{2y}) = 0$$

Now $e^{2y} \neq 0$

$$\Leftrightarrow 1 - 4e^{2y} = 0$$

$$\Leftrightarrow e^{2y} = \frac{1}{4}$$

$$\Leftrightarrow e^y = \frac{1}{2}$$

$$\Leftrightarrow y = \ln(1/2) \quad \textcircled{1}$$

ensures $\frac{\partial g}{\partial y} = 0$

So critical points (a, b) are found by combining $\textcircled{1}$ and $\textcircled{2}$.

$$\text{So } x^2 = 1/2$$

$$\text{so } x = \pm \sqrt{1/2} = \pm \frac{1}{\sqrt{2}}$$

