Convolutional Neural Networks

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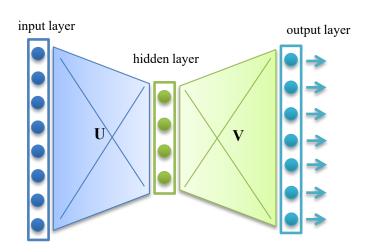
2018/04/26 @ NTUST

Parsimonious Neural Networks

- For image processing, the conventional neural networks have to estimate too many parameters
 - For a 1024*1024 image, the size of the input layer is up to 1,048,576
 - If the size of the first hidden layer is 100, the number of model parameter is over 104,857,600

1,024*1,024





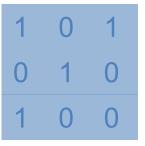
Convolution Neural Networks – 1.

- Inspired from the visual cortex, each neuron can only perceive a sub-region (perceptive field) at a time
 - Convolve the filter with the image
 - Convolution = Element-wise Product then Sum

1	0	1	1
0	1	0	0
1	0	0	1
1	0	1	1
0	0	0	1

Filter or Kernel





Convolution Neural Networks – 1...

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11	00	1	1	2	
00	11	0	0		
1	0	0	1		
1	0	1	1		
0	0	0	1		

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1	01	10	1		2	0	
0	10	01	0	7			
1	0	0	1				
1	0	1	1				
0	0	0	1	'			

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1	0	11	10		2	0	1
0	1	00	01	7			
1	0	0	1				
1	0	1	1				
0	0	0	1				

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1	0	1	1		2	0	1
01	10	0	0	7	0		
10	01	0	1				
1	0	1	1				
0	0	0	1				

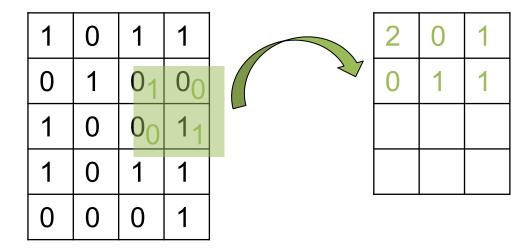
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1	00	01	1				
1	0	1	1				
0	0	0	1				

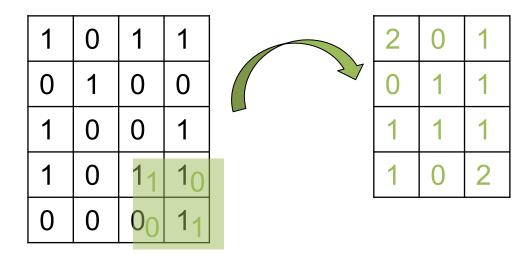
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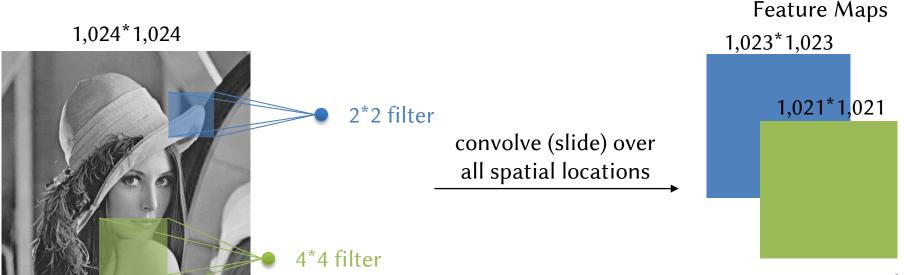
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								 P	
1	0	1	1		2	0	1	4	1
0	1	0	0		0	1	1	1	1
1	01	00	11		1	1	1	1	2
1	00	11	10		1	0	2	4	
0	01	00	10						

Feature Maps

Convolution Neural Networks – 2

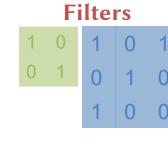
- Inspired from the visual cortex, each neuron can only perceive a sub-region (perceptive field) at a time
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 - If we have two filters (2*2 and 4*4), the total parameters are 4+16=20
 - Parameters Sharing!

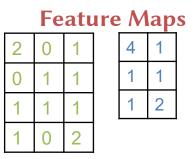


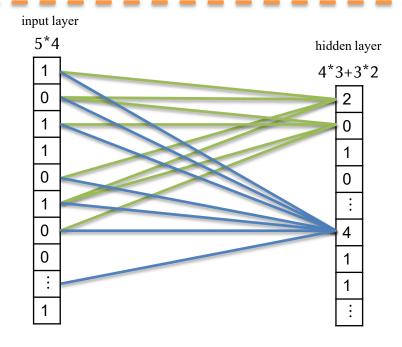
Convolution Neural Networks – 3

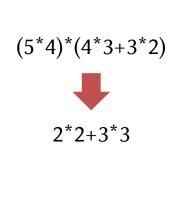
• CNN is a special case of DNN

1 0 1 1 0 1 0 0 1 0 0 1 1 0 1 1 0 0 0 1

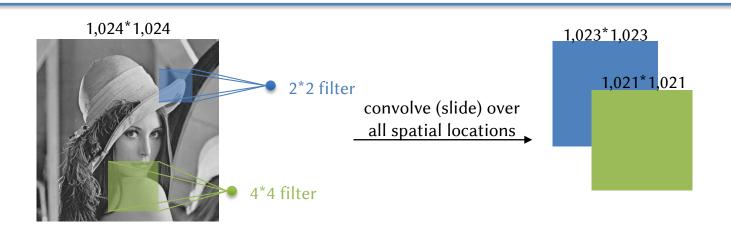


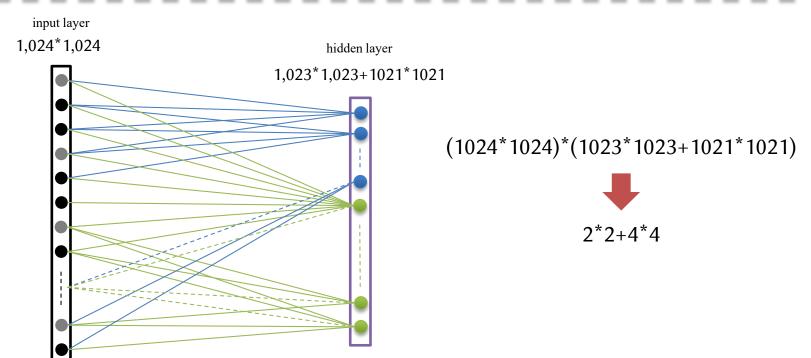






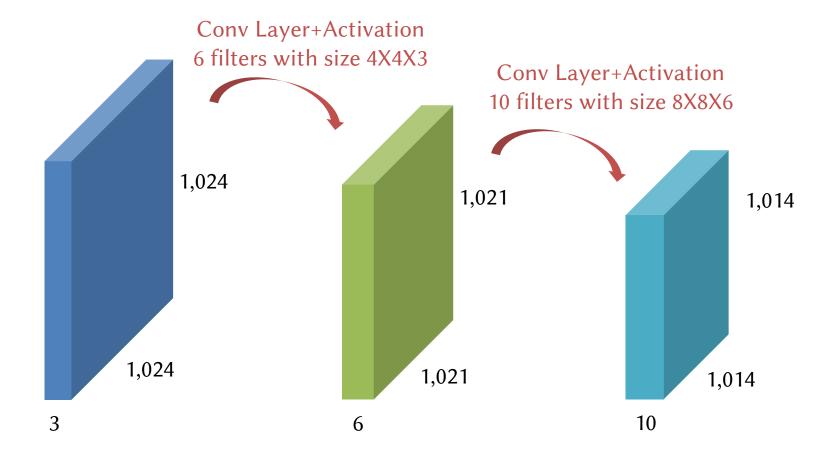
Convolution Neural Networks – 4





ConvNet

- Convolutional neural networks also call ConvNets or CNNs
 - It is a sequence of convolutional layers, interspersed with activation functions



Pooling & Stride

- Although the model parameters can be reduced, the feature dimension is still very large
 - Pooling
 - Stride

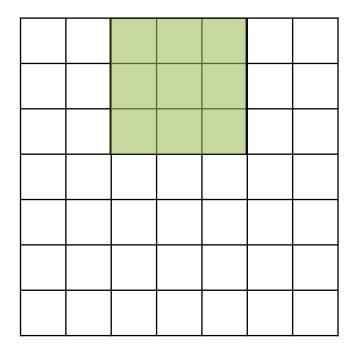
• Output
$$Size = \frac{(Input\ Size\ -Filter\ Size)}{Stride\ Size} + 1$$

7x7 input
3x3 filter
stride 2
=> 3x3 output!

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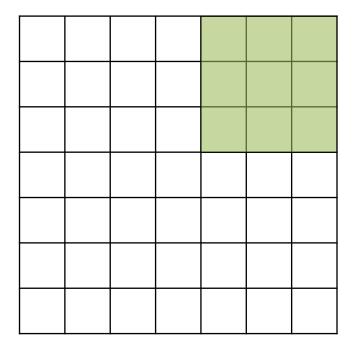


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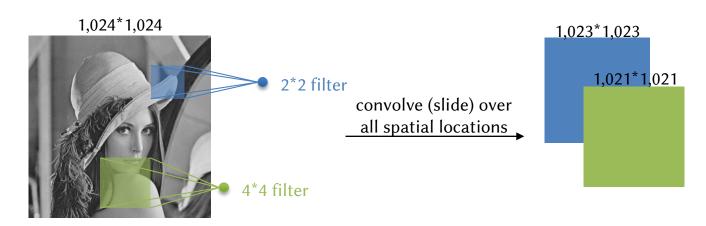
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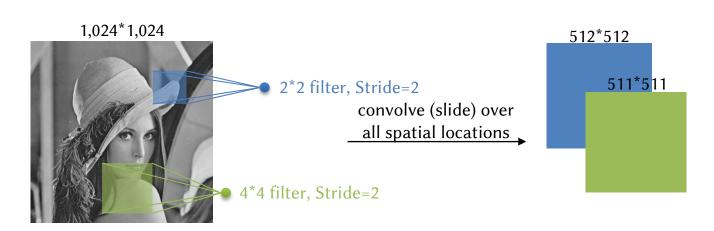


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Stride

$$Output Size = \frac{(Input Size - Filter Size)}{Stride Size} + 1$$

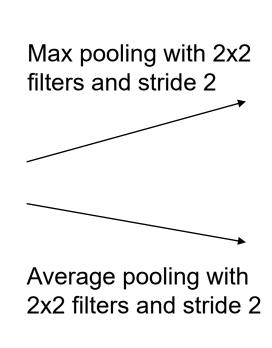




Pooling

- Pooling can make the representations smaller and more manageable
 - It operates over each feature map independently
 - Max Pooling
 - Average Pooling

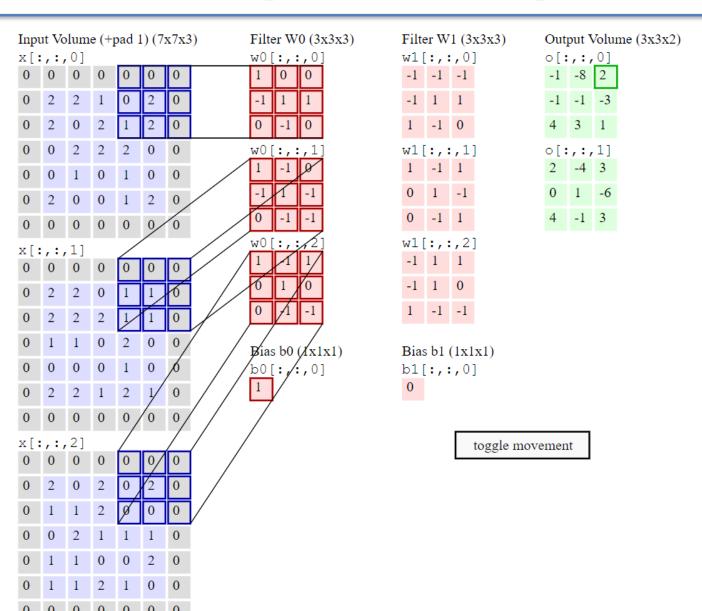
0	1	3	4
5	6	5	8
3	2	1	0
1	2	3	4



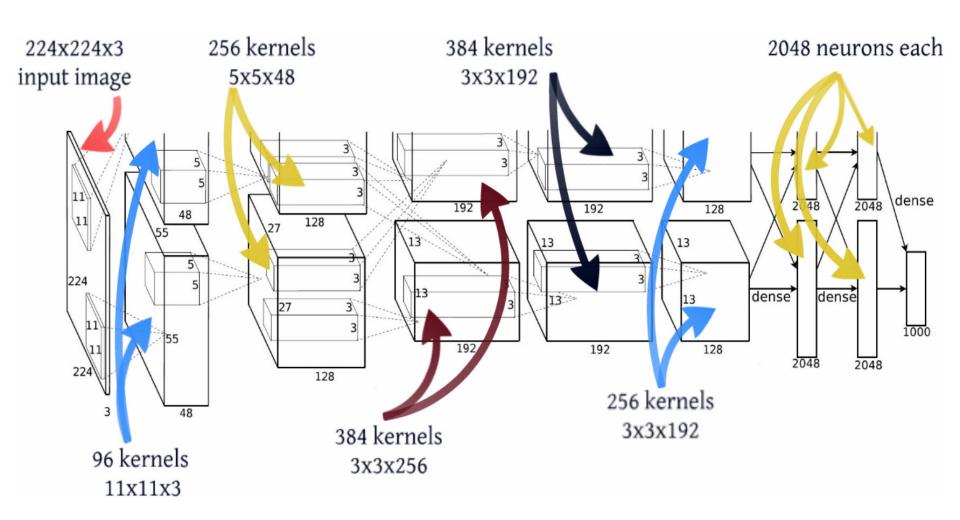
6	8
3	4

3	5
2	2

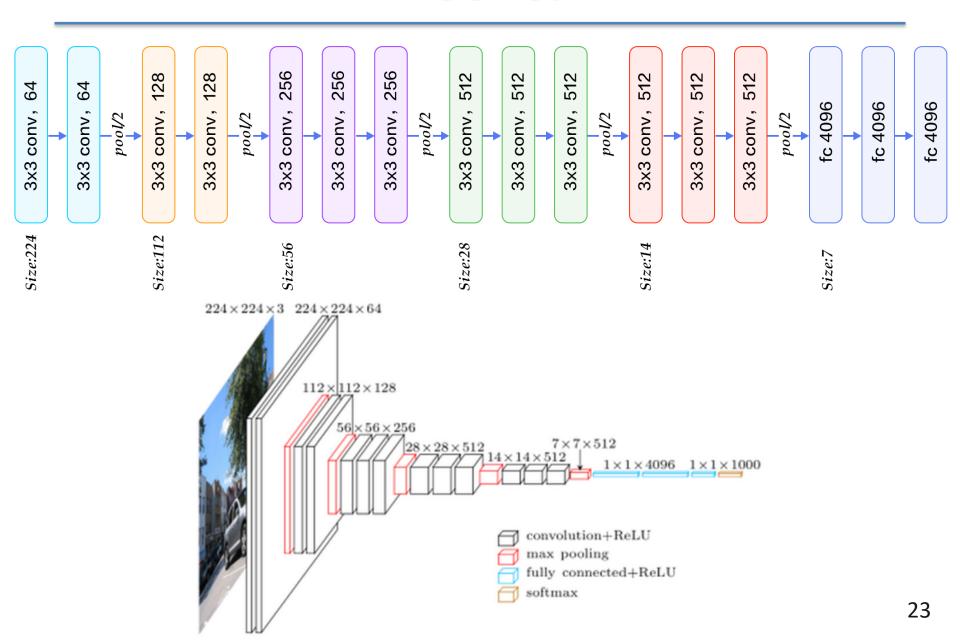
Padding & Color Image



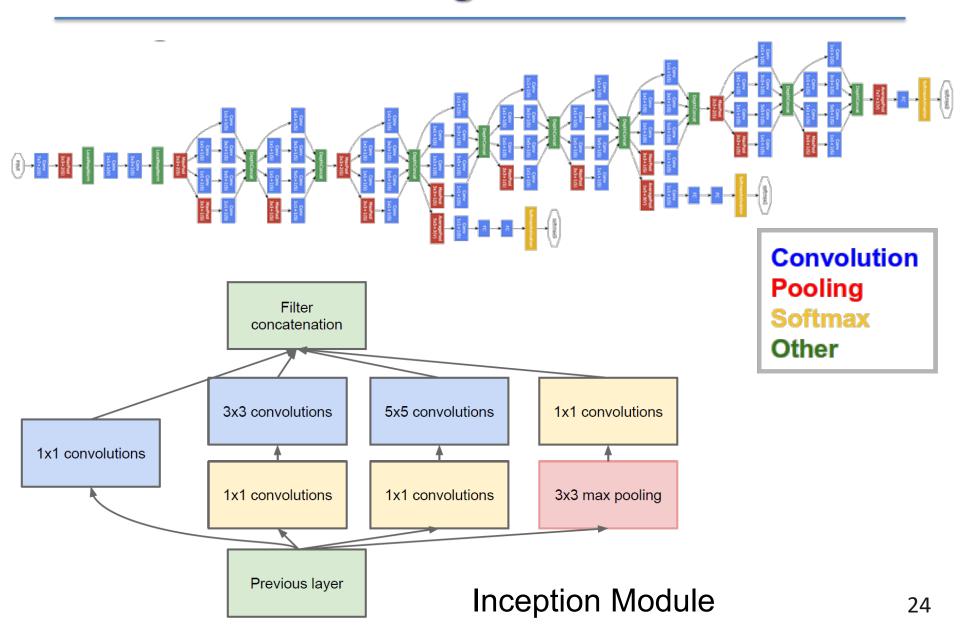
AlexNet



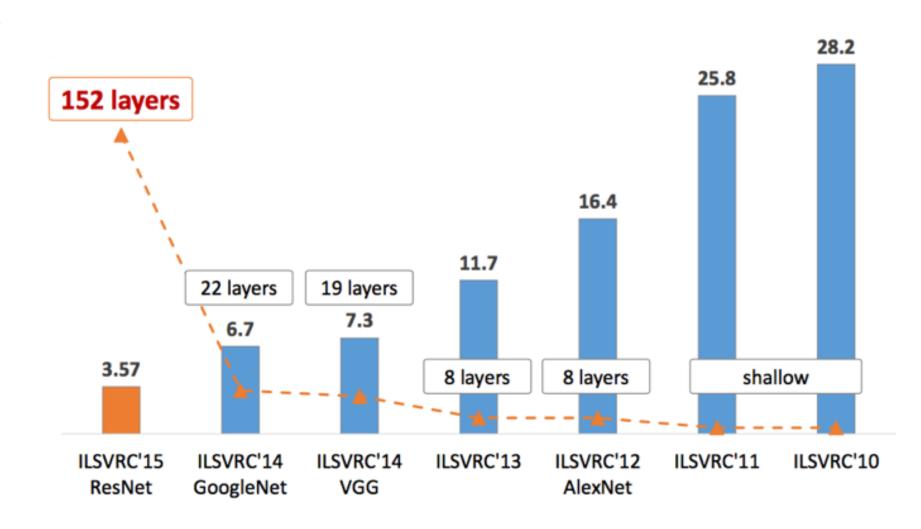
VGGNet



GoogLeNet



Comparisons

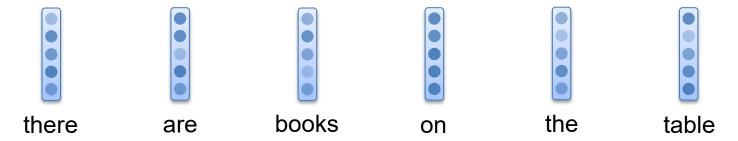


CNN in NLP

A document is a sequence of words

there are books on the table

Each word can be represented by a word embedding

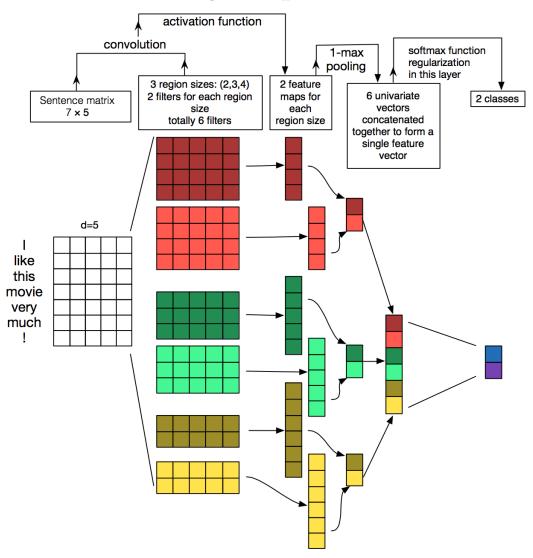


- The document can be viewed as a image/matrix
 - Apply CNN!

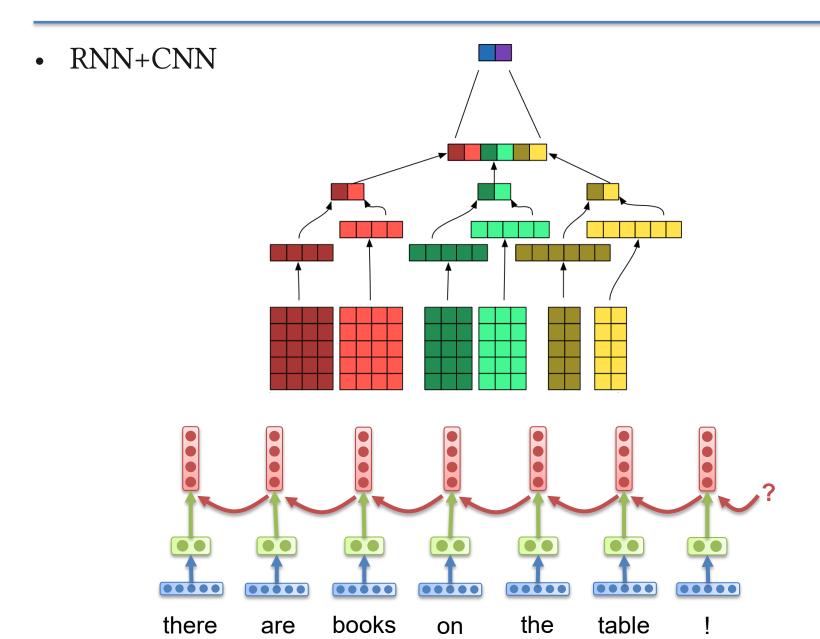


CNN for NLP - 1

• Using CNN to extract *N*-gram pattern

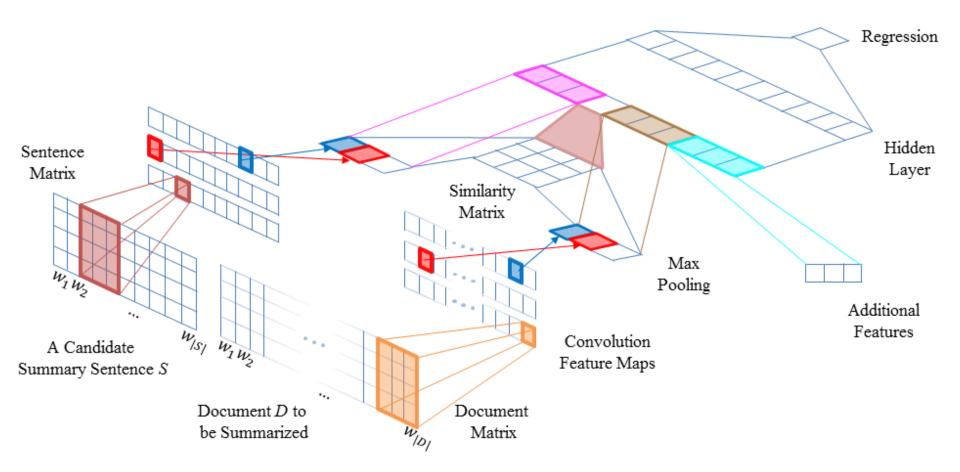


CNN for NLP – 2

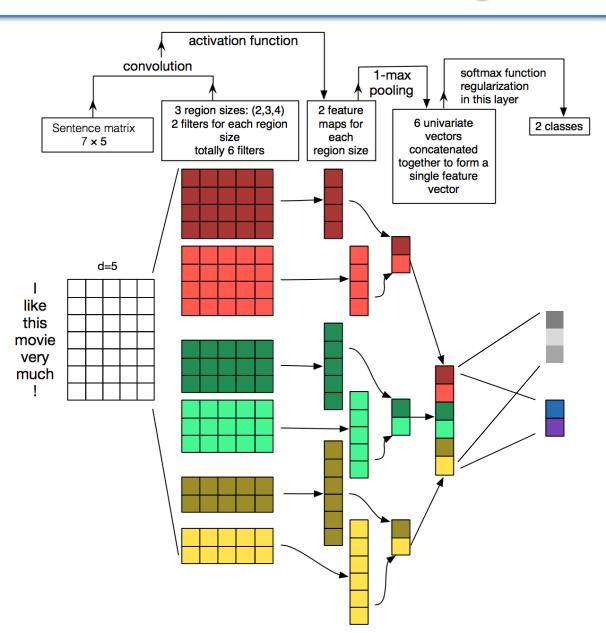


CNN for NLP – 3

For Summarization



Multi-task Learning



Questions?



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