

Advanced Structures

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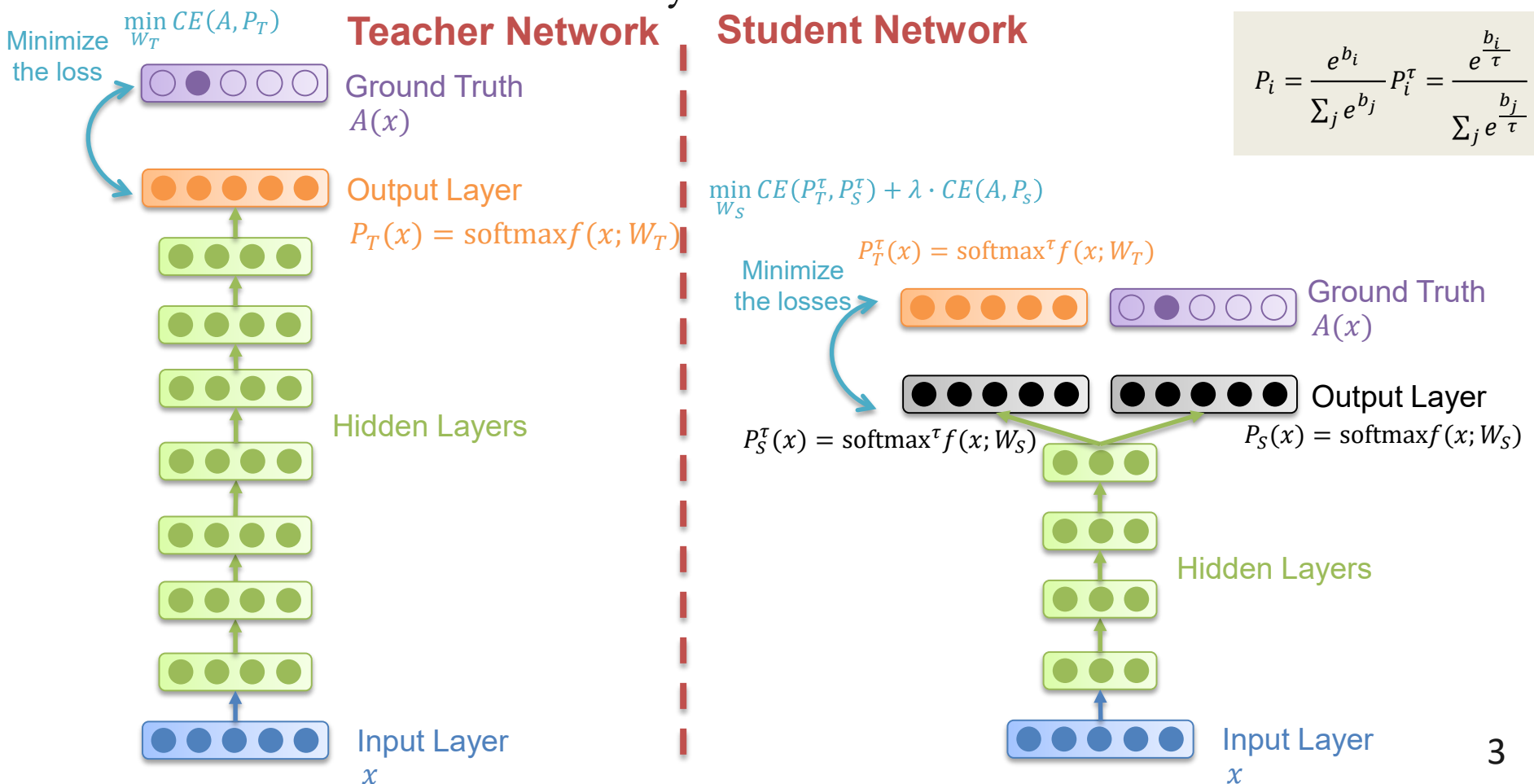
2018/05/10 @ NTUST

Model Compression

- Deep networks have recently exhibited state-of-the-art performance in computer vision tasks such as image classification and object detection
 - Top-performing systems usually involve very wide and deep networks, with numerous parameters
 - time consuming
 - high memory demanding
 - Knowledge Distillation (Teacher-student network) and FitNet are representatives

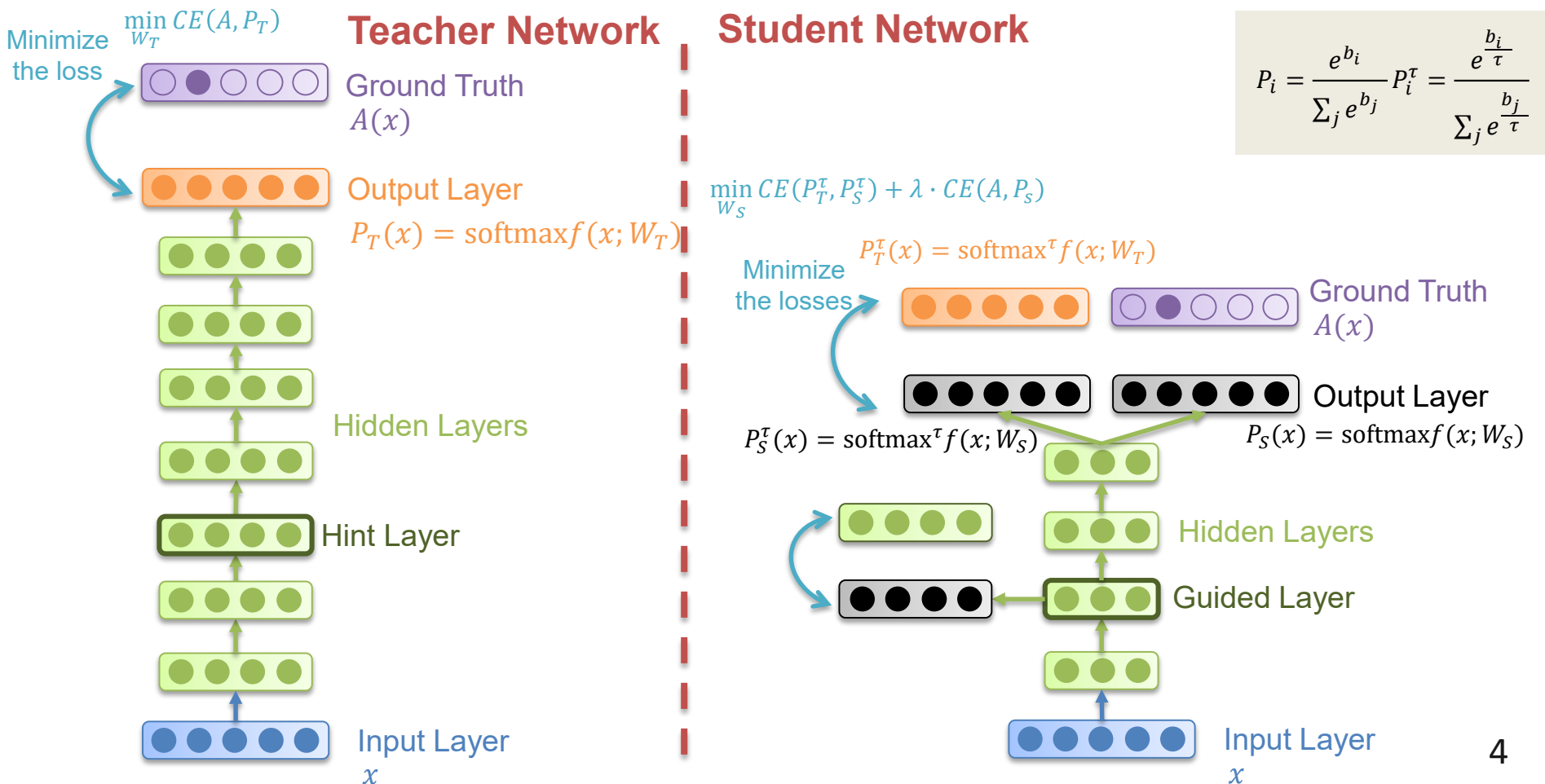
Knowledge Distilling

- The idea is to allow the student network to capture not only the information provided by the **true labels**, but also the finer structure learned by the **teacher network**



FitNets.

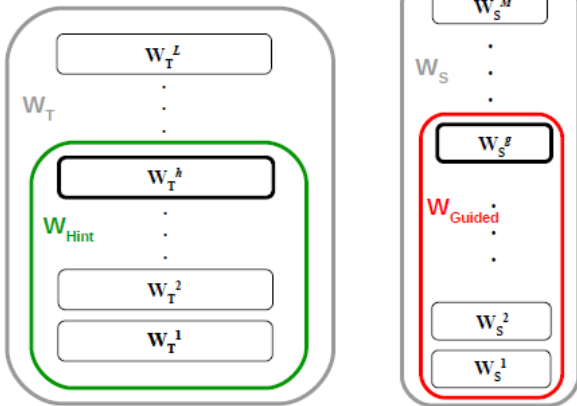
- The FitNet is trained in a stage-wise fashion
 - The core idea is that layer-wise information should also be obtained



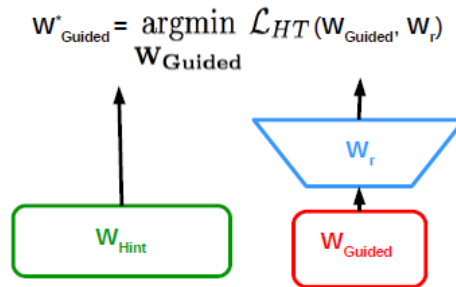
FitNets..

Teacher Network

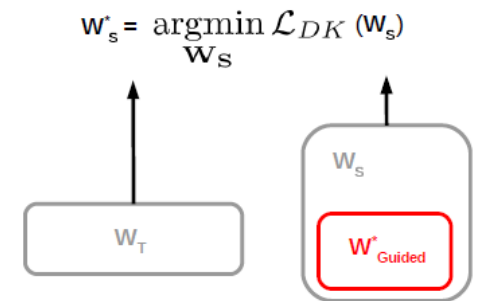
FitNet



(a) Teacher and Student Networks



(b) Hints Training

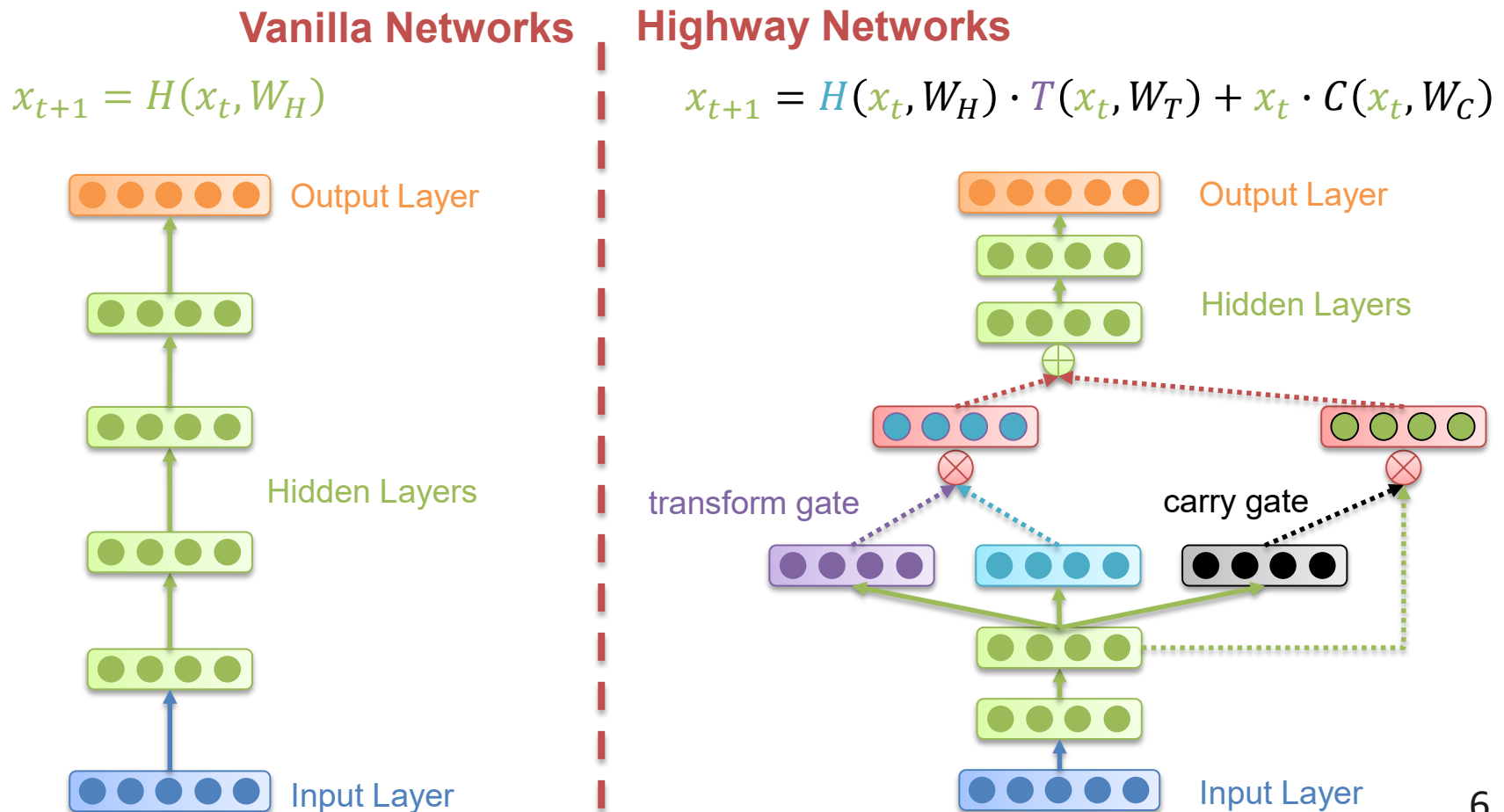


(c) Knowledge Distillation

1. Starting from a trained teacher network and a randomly initialized FitNet
2. Adding a regressor W_r on top of the FitNet guided layer and train the FitNet parameters W_{Guided}
3. Based on the pre-trained parameters W_{Guided} , we train the parameters of whole FitNet, W_S

Highway Networks.

- Highway networks allow unimpeded information flow across several layers on information highways

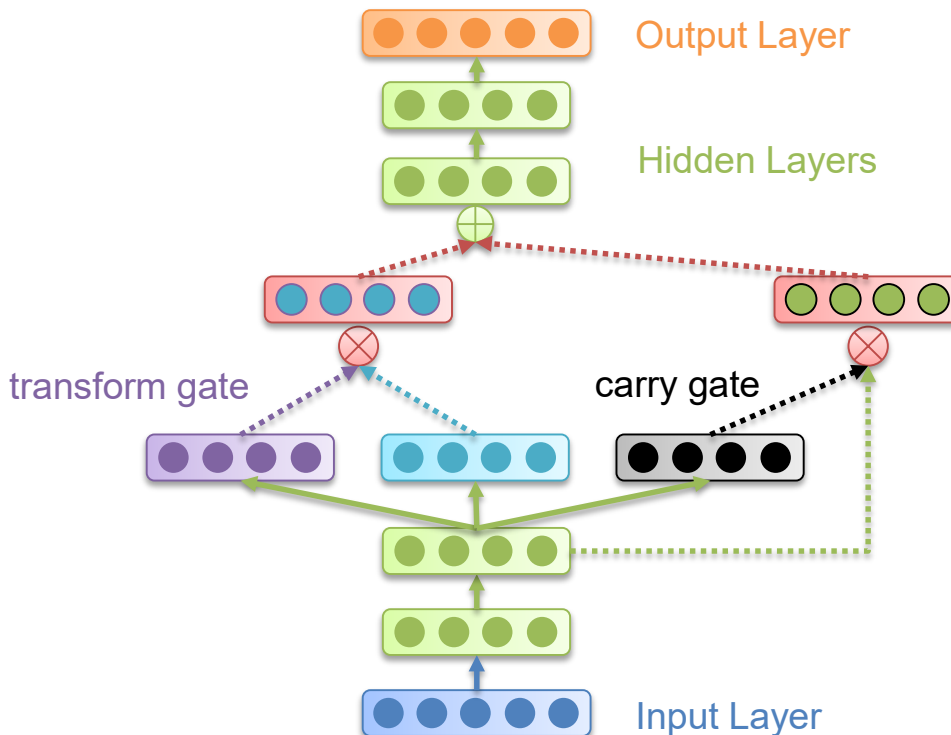


Highway Networks..

- A simplified variant is to set carry gate equal to one minus transform gate

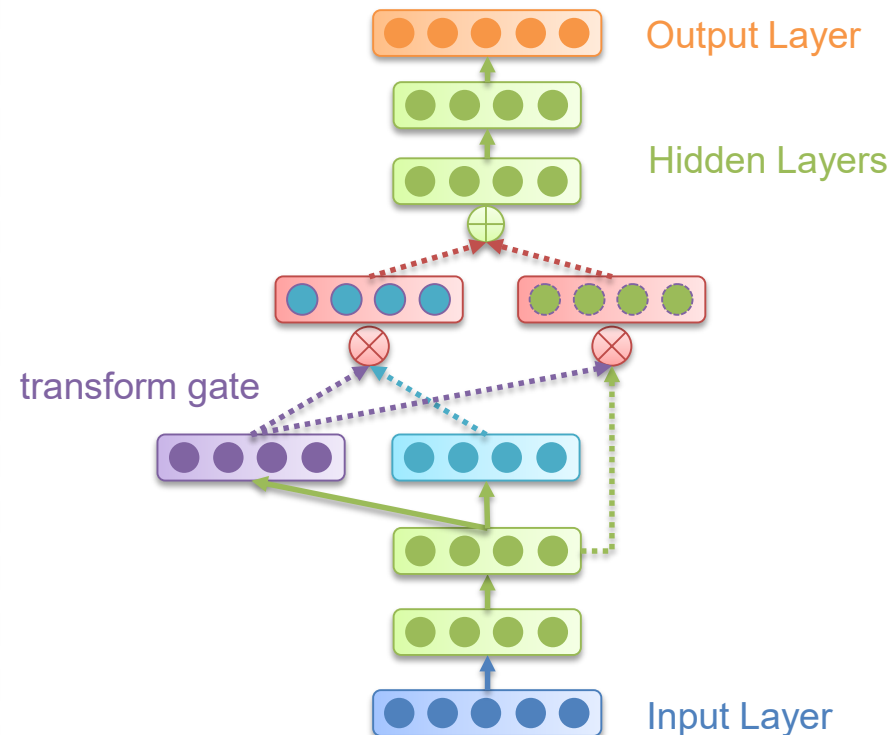
Highway Networks

$$x_{t+1} = H(x_t, W_H) \cdot T(x_t, W_T) + x_t \cdot C(x_t, W_C)$$



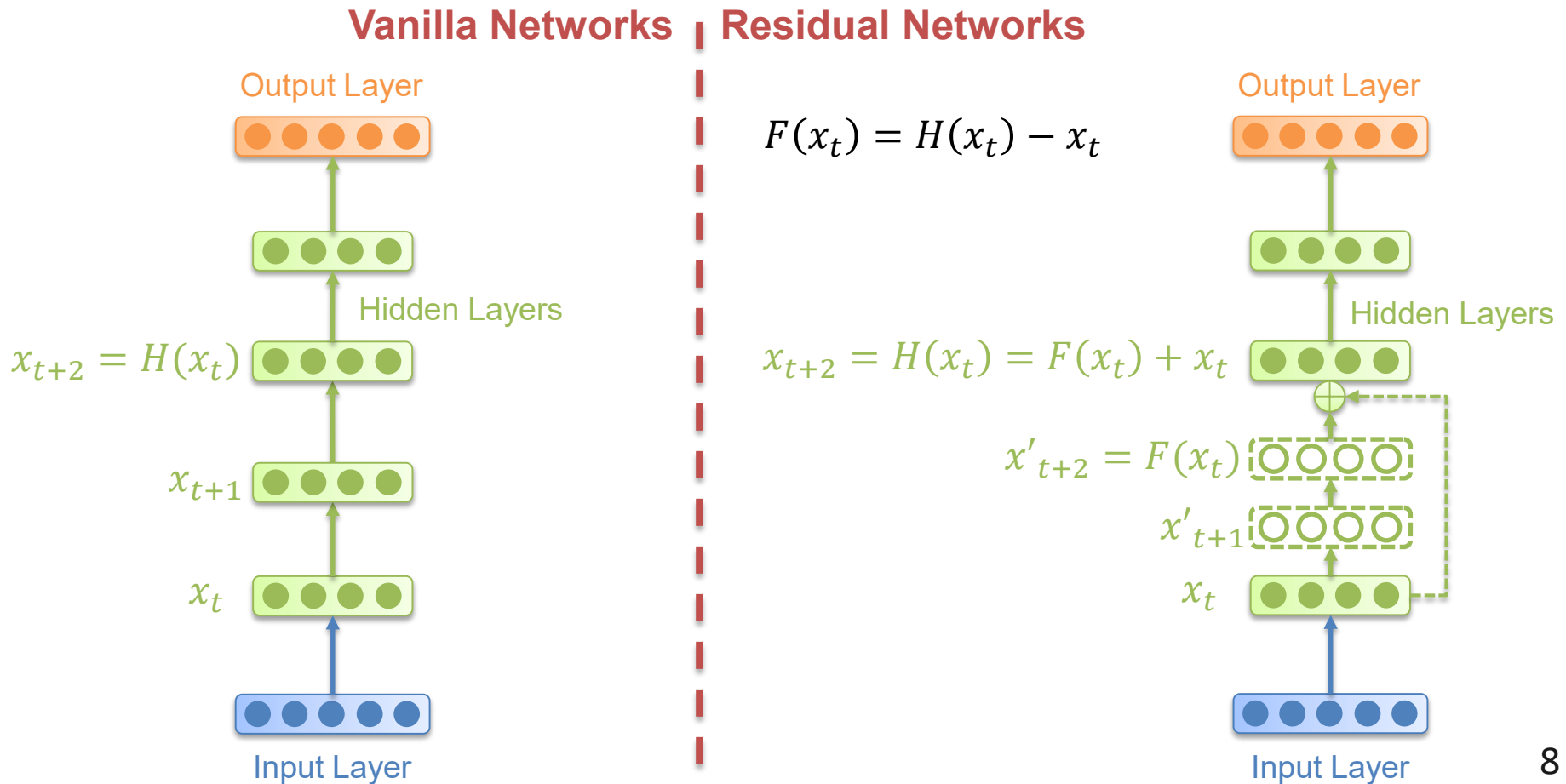
Simplified Highway Networks

$$x_{t+1} = H(x_t, W_H) \cdot T(x_t, W_T) + x_t \cdot [1 - T(x_t, W_T)]$$



Residual Networks

- ResNet hypothesizes that it is easier to optimize the **residual mapping** than to optimize the original, unreferenced mapping

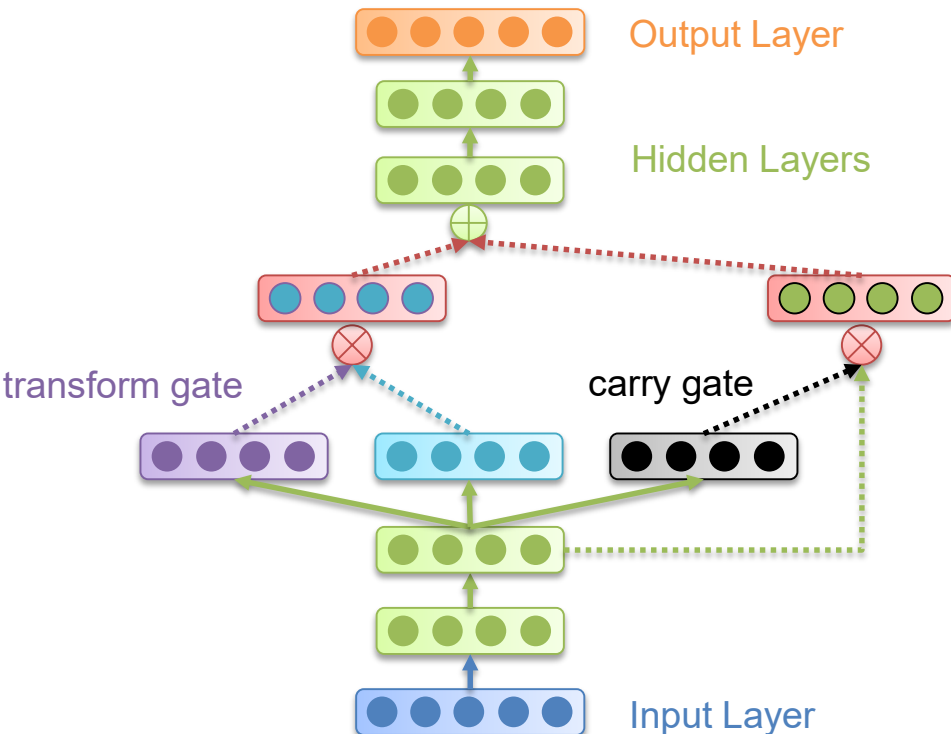


Highway vs. ResNet

- ResNet is a short name for Residual Network
 - ResNet usually refers to the classic CNN-based residual learning
- When $T(\cdot) = C(\cdot) = 1$, ResNet \sim Highway

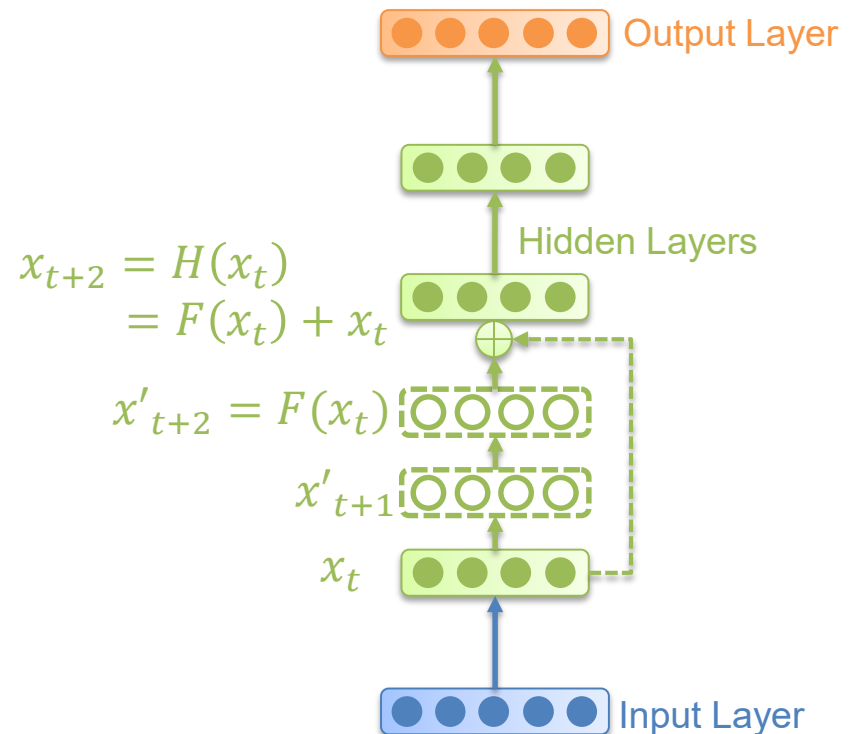
Highway Networks

$$x_{t+1} = H(x_t, W_H) \cdot T(x_t, W_T) + x_t \cdot C(x_t, W_C)$$

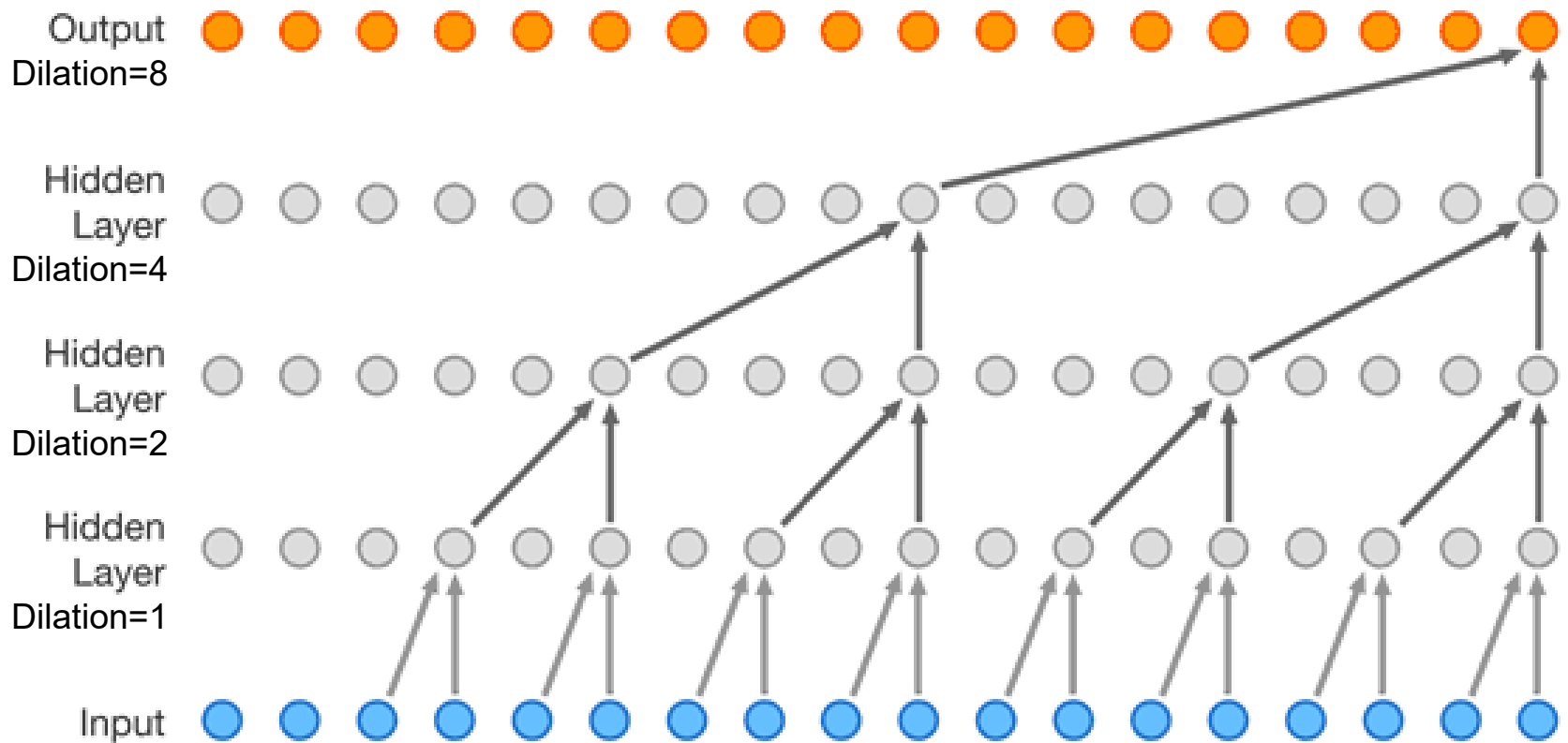


Residual Networks

$$x_{t+2} = F(x_t) + x_t \quad F(x_t) = H(x_t) - x_t$$

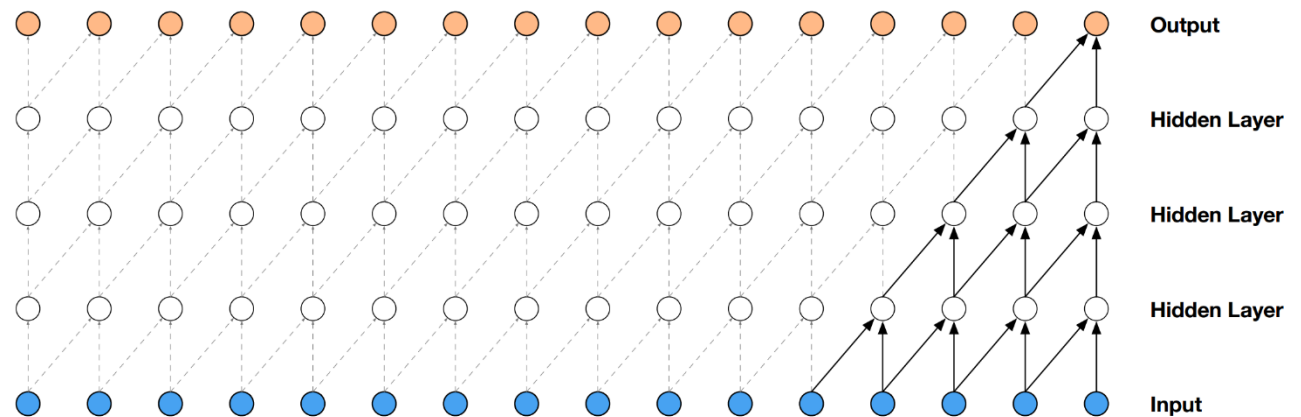


Dilated Convolutions.

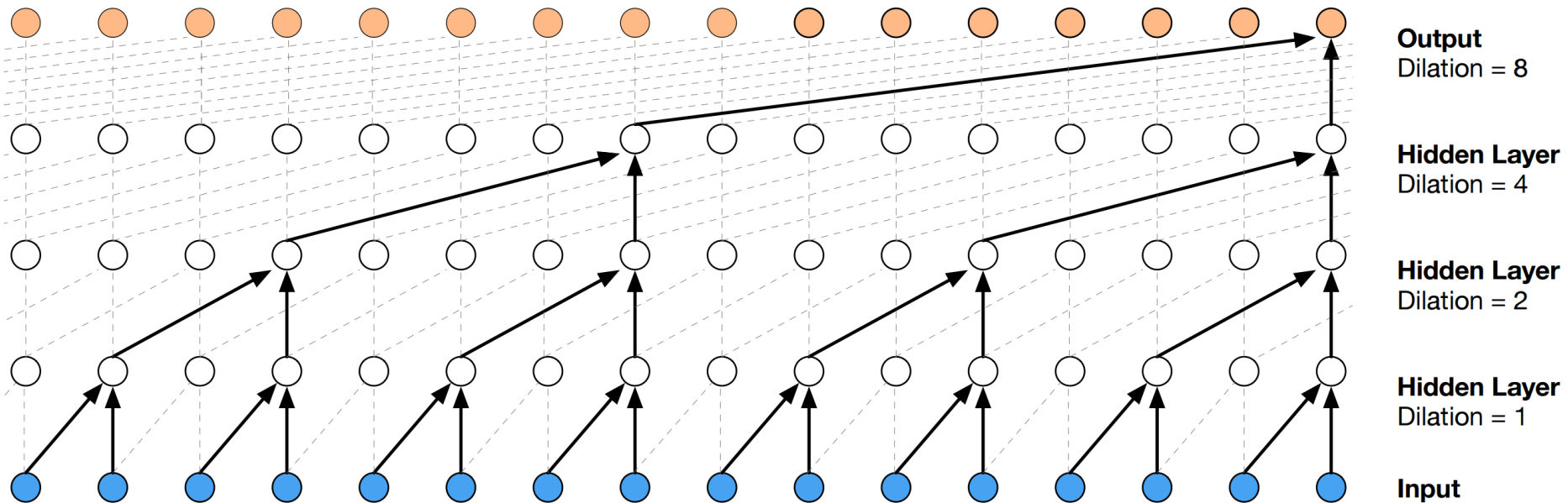


Dilated Convolutions..

- Classic CNNs

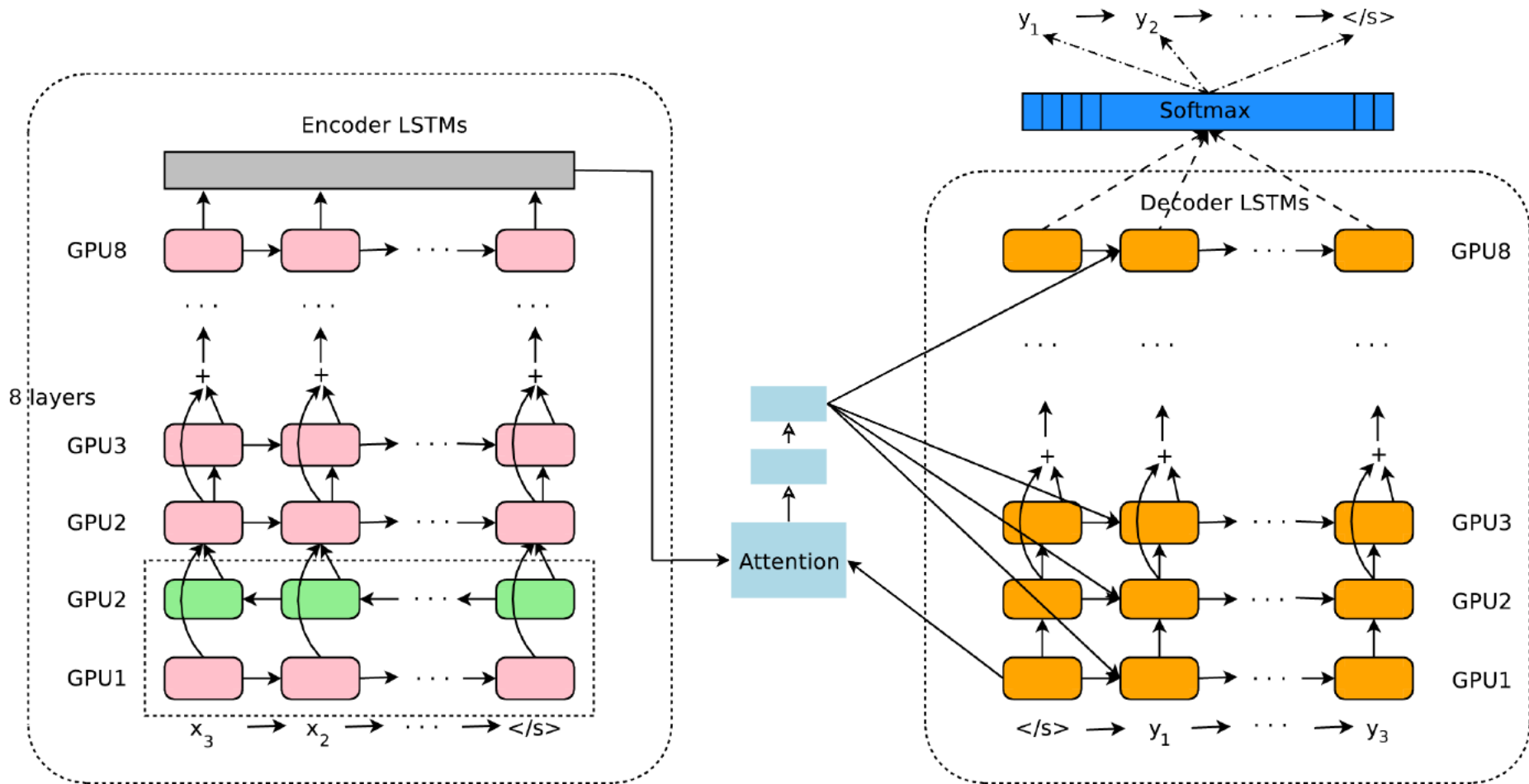


- Dilated Convolutions



Google's Neural Machine Translation.

- A conventional encoder-decoder architecture with attention



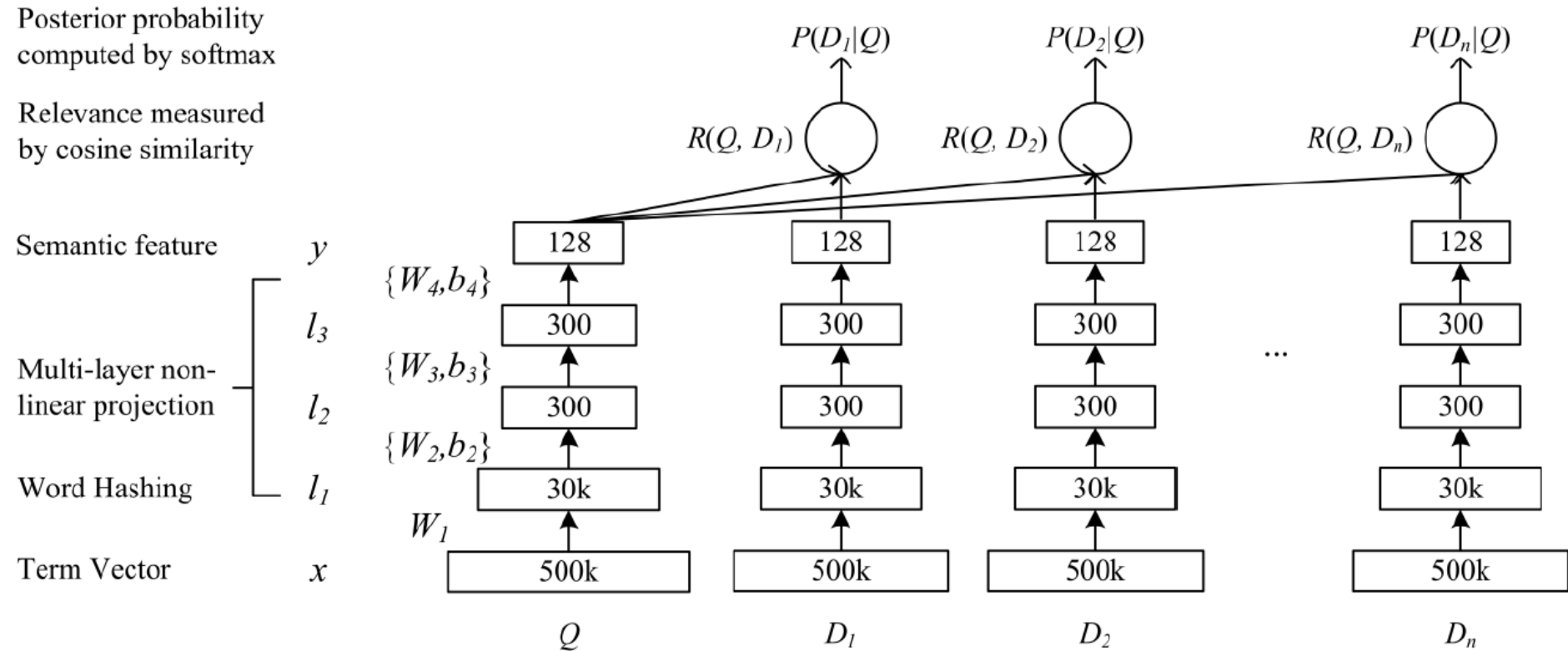
Google's Neural Machine Translation..

- To be able to make use of multilingual data within a single system, GNMT proposes one simple modification to the input data
 - An artificial token is introduced at the beginning of the input sentence to indicate the target language the model should translate to

How are you? -> ¿Cómo estás?

<2es> How are you? -> ¿Cómo estás?

Deep Structured Semantic Model (DSSM).



	Letter-Bigram		Letter-Trigram	
Word Size	Token Size	Collision	Token Size	Collision
40k	1107	18	10306	2
500k	1607	1192	30621	22

#good# => [#go, goo, ood, od#]

DSSM..

Posterior probability
computed by softmax

Relevance measured
by cosine similarity

Semantic feature

y

$\{W_4, b_4\}$

l_3

Multi-layer non-
linear projection

$\{W_3, b_3\}$

l_2

Word Hashing

$\{W_2, b_2\}$

l_1

Term Vector

x

W_1

500k

Q

500k

D_1

500k

D_2

500k

D_n

128

128

128

128

300

300

300

300

300

300

30k

30k

30k

$P(D_1|Q)$

$P(D_2|Q)$

$P(D_n|Q)$

$R(Q, D_1)$

$R(Q, D_2)$

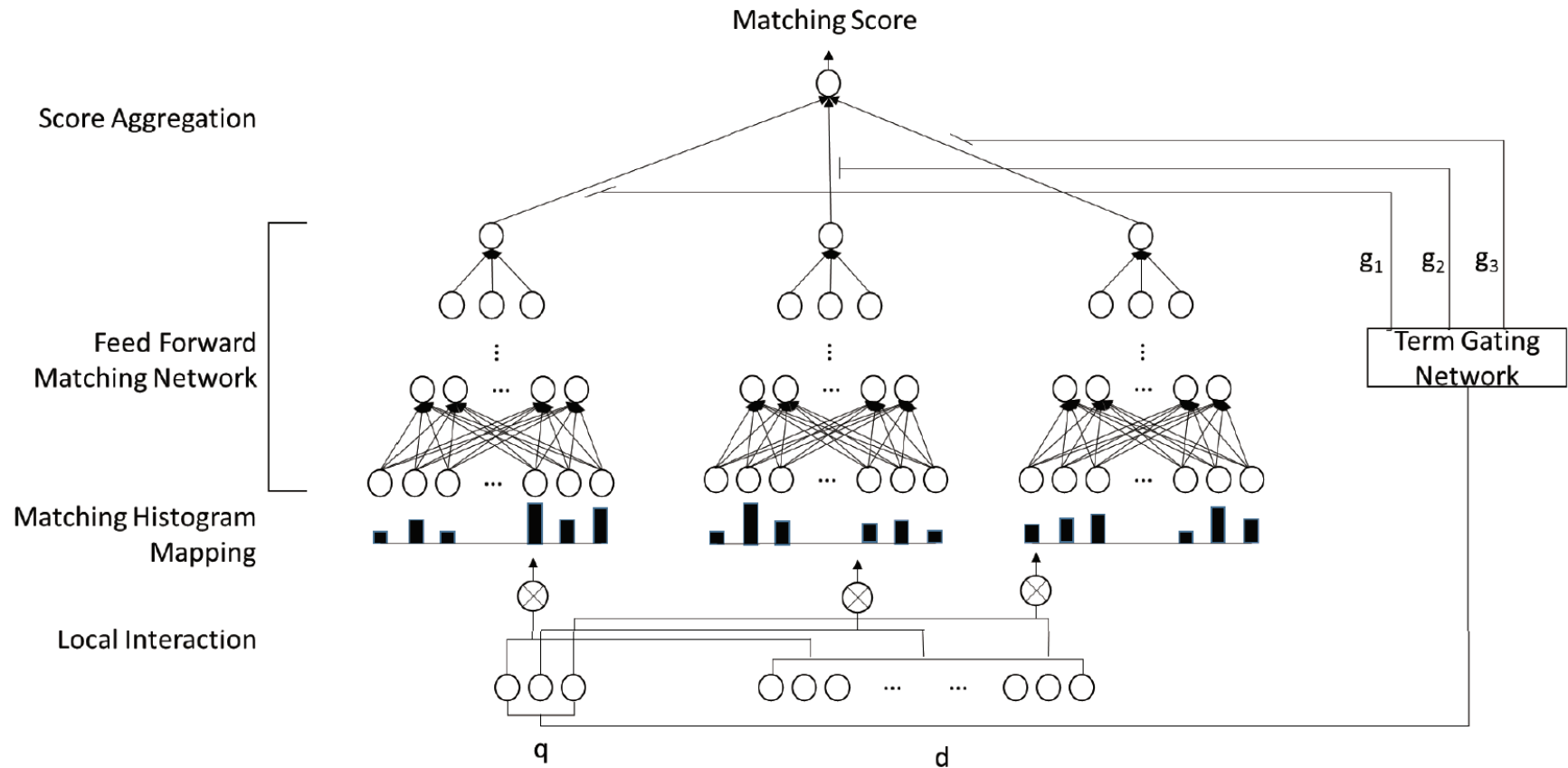
$R(Q, D_n)$

$$R(q, d) = \cos(\vec{q}, \vec{d})$$

$$P(d|q) = \frac{\exp(R(q, d))}{\sum_{d'} \exp(R(q, d'))}$$

$$L = \prod_{d \in R_q} P(d|q)$$

Deep Relevance Matching Model



Query: "car to go"

Document: "car, rent, truck, bump, injuncion, runway"

Five Bins: $\{[-1,-0.5), [-0.5,0), [0,0.5), [0.5,1), [1,1]\}$

Local Interaction for "car": (1, 0.2, 0.7, 0.3, -0.1, 0.1)

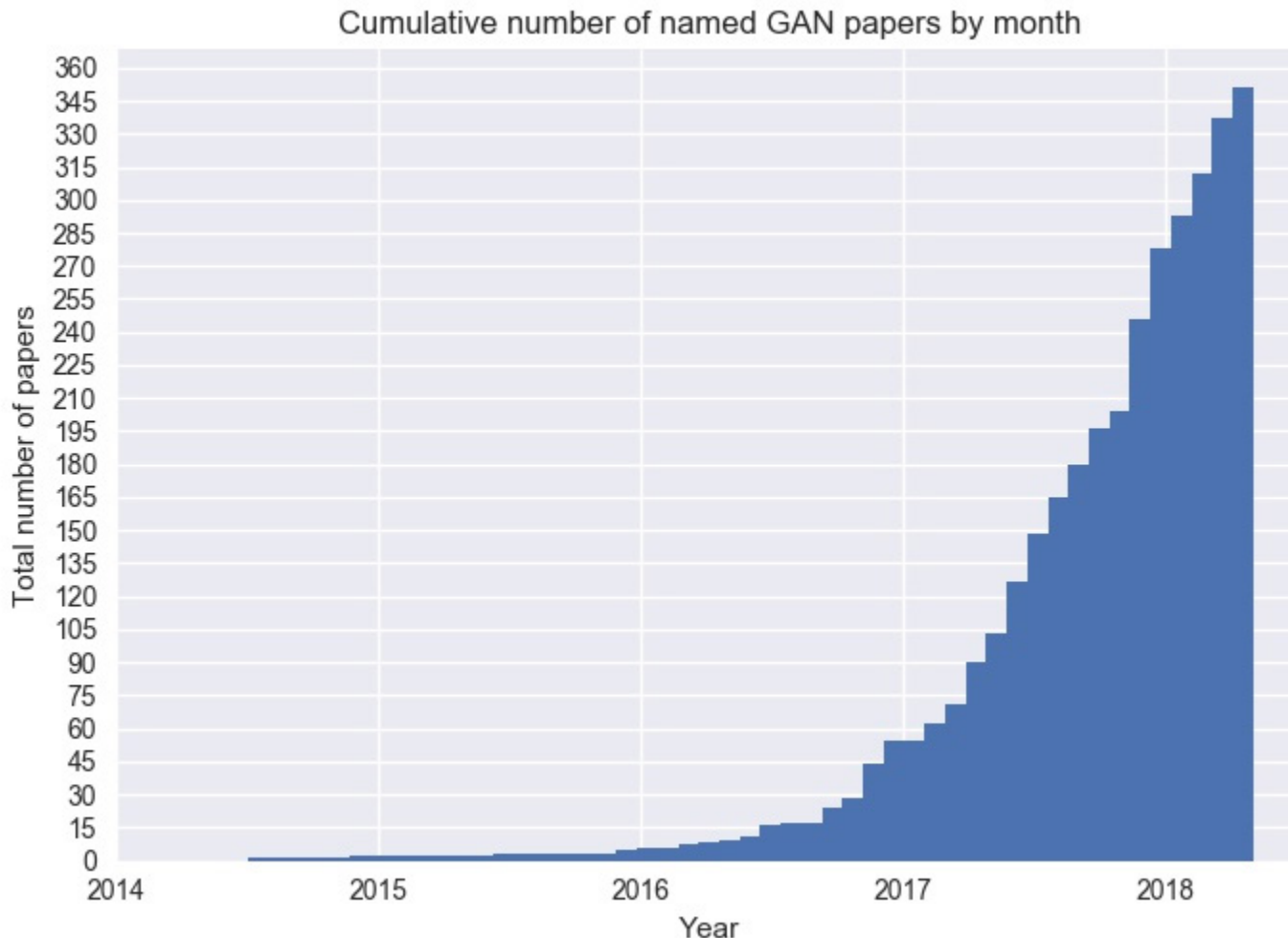
Matching Histogram for "car": [0, 1, 3, 1, 1]

Generative Adversarial Networks.



Generative Adversarial Networks..

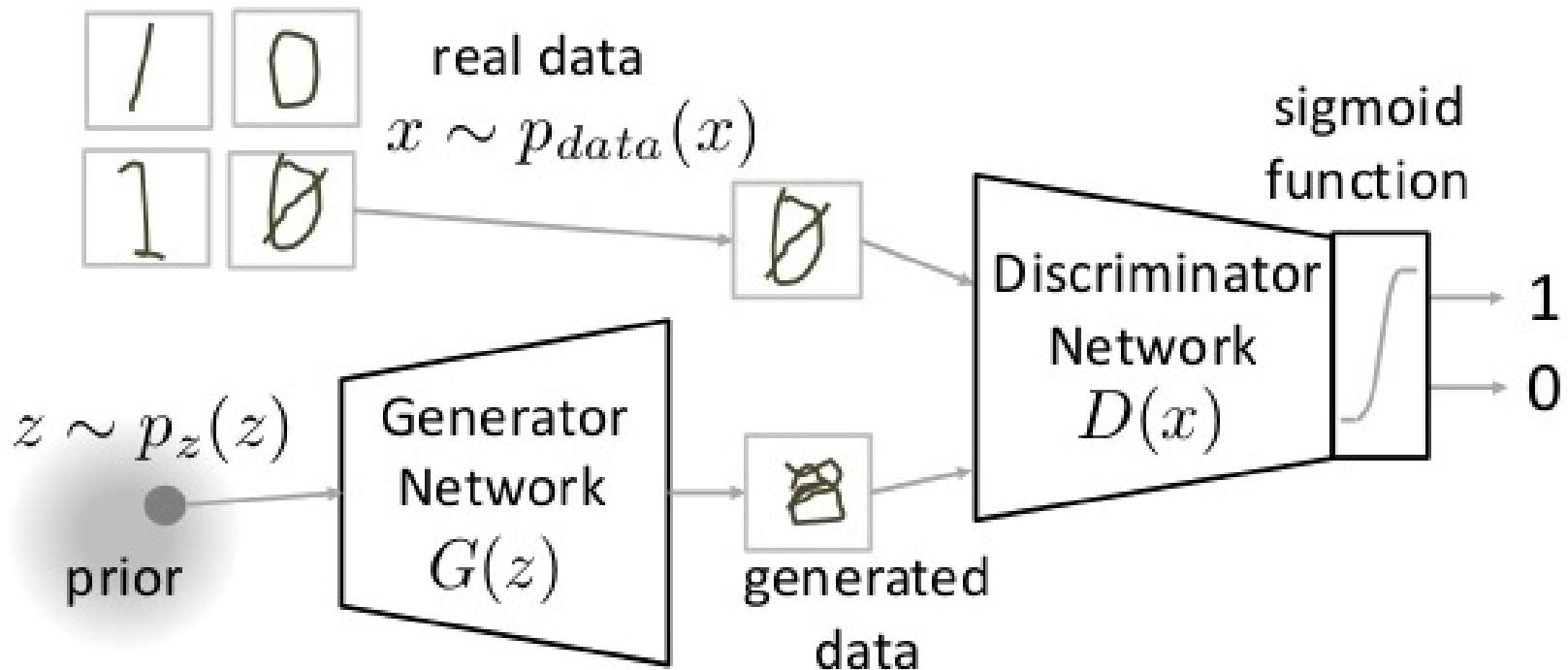
- <https://github.com/hindupuravinash/the-gan-zoo>



Generative Adversarial Networks...

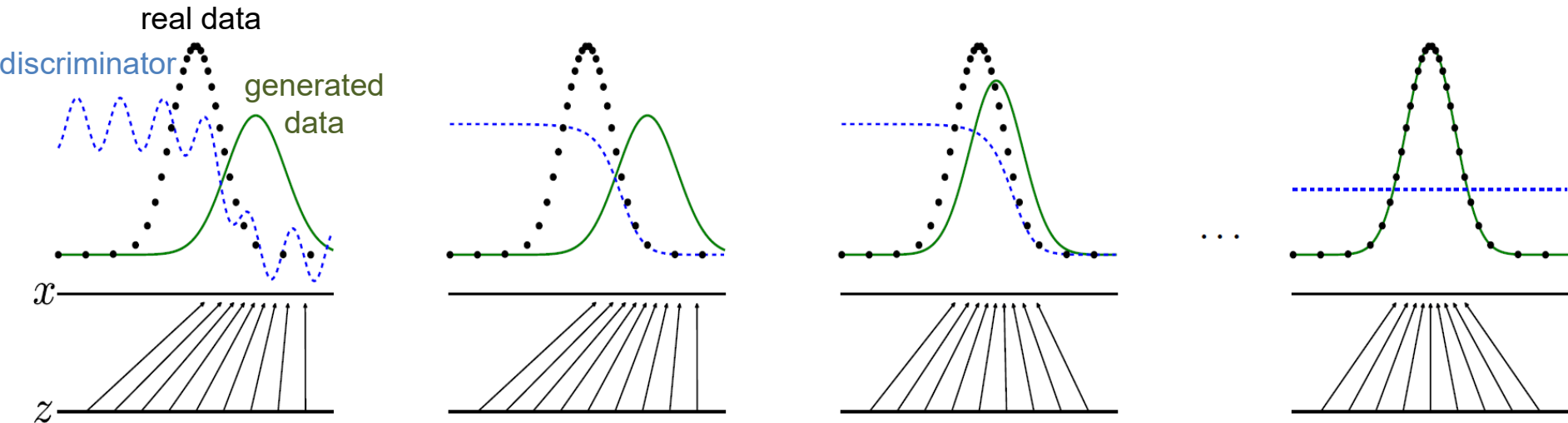
- Discriminator is used to criticize the results produced by generator
- The ultimate goal of generator is to cheat the discriminator, thus the generator can create potential objects

$$\min_G \max_D V(D, G) = \mathbf{E}_{x \sim p_{data}(x)} [\log D(x)] + \mathbf{E}_{z \sim p_z(z)} [\log(1 - D(G(z)))]$$



Generative Adversarial Networks....

$$\min_G \max_D V(D, G) = \mathbf{E}_{x \sim p_{data}(x)} [\log D(x)] + \mathbf{E}_{z \sim p_z(z)} [\log(1 - D(G(z)))]$$



Questions?



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