

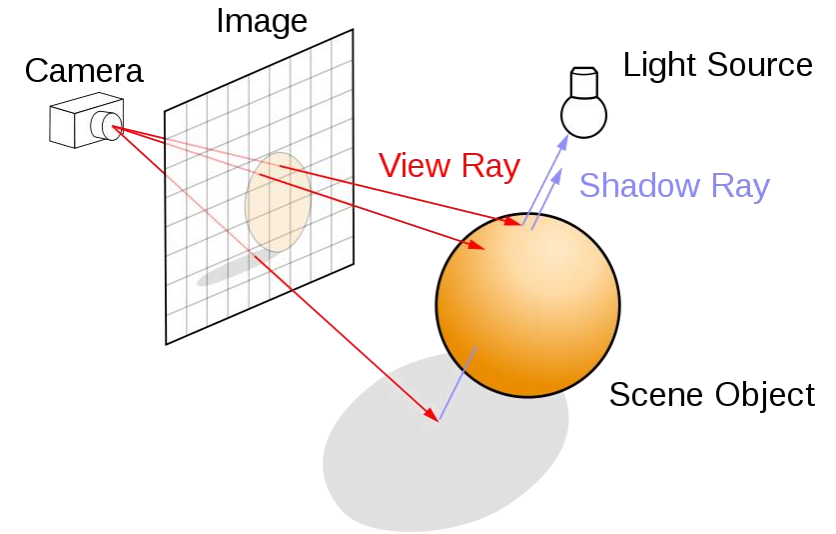
Raytracing Tutorial 1

Agenda

- What is Raytracing?
- XML File Spec and Parsing
- Constructing Camera Rays
- Sphere Intersection Test
- Local Illumination
- Shadows

What is Raytracing?

- A method of computing global illumination
- Simulates how light rays travel through a scene
- **Basic algorithm:**
 - Construct ray from camera to each pixel
 - Find closest object hit by that ray
 - Cast shadow-, reflection- and refraction rays
 - Compute illumination according to some illumination model



Raytracing Algorithm

```
for(y = 0; y < imageHeight; ++y)
  for(x = 0; x < imageWidth; ++x)
    ray = camera.getRayToPixel(x, y)
    color = trace(ray)
    image[x][y] = color
```

```
trace(ray)
  for each object in scene
    intersection = object.intersect(ray)
  determine closest intersection
  if(intersection)
    color = illuminate(ray, intersection)
  else
    color = backgroundColor
  return color
```

How do we get our scene data?

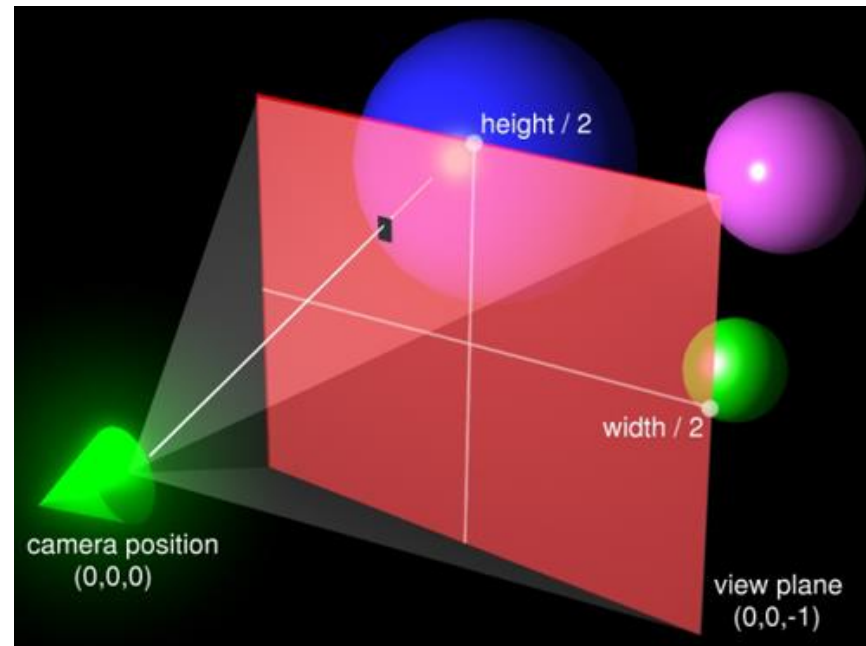
- Read in scene data from xml files provided on the course website
- Specification can be found [here](#)
- You can use any XML library you like for this
- Make sure that the xml file can be chosen at runtime

Hint: Useful data structures

- Make your life easier by structuring your code properly
- Make use of inheritance and other OO concepts
- **Implement a vector class**
 - Make sure to properly differentiate between points and directions
 - Provides all necessary math (dot and cross product, subtraction, addition etc)
- Ray
 - Origin and direction, minimum and maximum distance
- Object/Surface
 - Has material and transformation data
 - Implements an intersection algorithm
- Intersection
 - All data you get from an intersection test: point of intersection, distance, normal, material and texture

Constructing Camera Rays

- Given a ray with origin $(0, 0, 0)^T$, we need to calculate the ray direction for a specific pixel
- Need to map original pixel coordinates u and v to coordinates x and y on image plane at $z = -1$
- Ideally, we want to shoot the ray through the center of pixel



Constructing Camera Rays

- First, normalize coordinates (range [0 to 1]):

- $x_n = \frac{u+0.5}{width}$
- $y_n = \frac{v+0.5}{height}$

- Then, map to image plane (range [-1 to 1]):

- $x_i = 2 * x_n - 1$
- $y_i = 2 * y_n - 1$

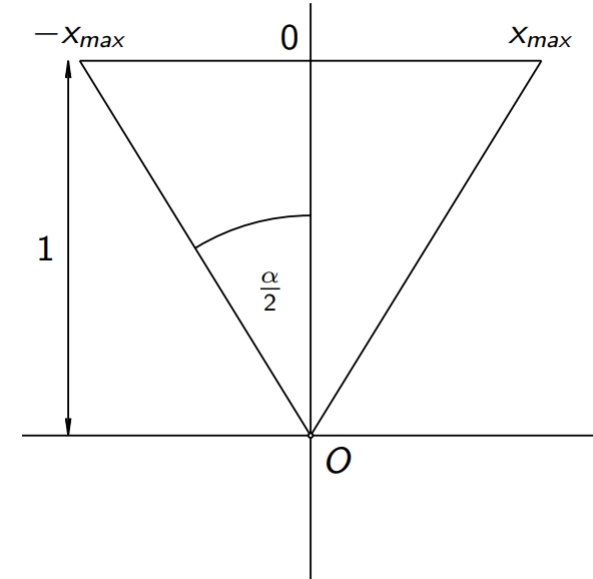
- Include FOV and image dimensions

- fov_x : specified in XML file
- $fov_y = fov_x * \frac{height}{width}$
- $x_i = (2 * x_n - 1) * \tan(fov_x)$
- $y_i = (2 * y_n - 1) * \tan(fov_y)$

- The ray is now given by the origin $(0, 0, 0)^T$ and the direction $(x_i, y_i, -1)^T$ (don't forget to normalize)

- Notes

- This will make your image upside down, keep that in mind when writing to the image file.
- This assumes that $width \geq height$. If $height > width$, you need to invert aspect ratio and multiply fov_x by it instead



Surface Intersections

- Ray can be described as $r(t) = o + t * d$, with
 - o being the ray's origin
 - d being the ray's direction
 - t being a real number.
 - We are only interested in $t > 0$
- How to determine if a ray intersects an object?

Ray-Sphere Intersections

- Given a radius R and a center point C , a sphere can be defined as:

$$(P - C)^2 - R^2 = 0$$

- Any point P that satisfies this equation lies on the sphere
- To see if a ray intersects the sphere, we just plug in our ray:

$$(o + t * d - C)^2 - R^2 = 0$$

- Rearranging the terms gives us:

$$(dt)^2 + 2d * (o - C)t + (o - C)^2 - R^2 = 0$$

- Now solve for t

Ray-Sphere Intersections

- We want to solve $(dt)^2 + 2d * (o - C)t + (o - C)^2 - R^2 = 0$ for t
- This is a quadratic equation with the form:

$$a * t^2 + b * t + c = 0$$

$$a = d^2$$

$$b = 2d * (o - C)$$

$$c = (o - C)^2 - R^2$$

- Applying the general solution formula gives us:

$$t_{1,2} = \frac{-d*(o-C) \pm \sqrt{(d*(o-C))^2 - d^2*((o-C)^2 - R^2)}}{d^2}$$

- Instead of instantly solving this, look at discriminant first:
 - $disc > 0$ means we have two intersections \rightarrow use closer t
 - $disc = 0$ means we have one intersection
 - $disc < 0$ means we have no intersections

Ray-Sphere Intersections

- How to get normal at the intersection point?
- We have t from the intersection test
- Pass t to the ray to get the intersection Point P
- Compute vector from center of sphere to P
- Normalize vector

Local Illumination

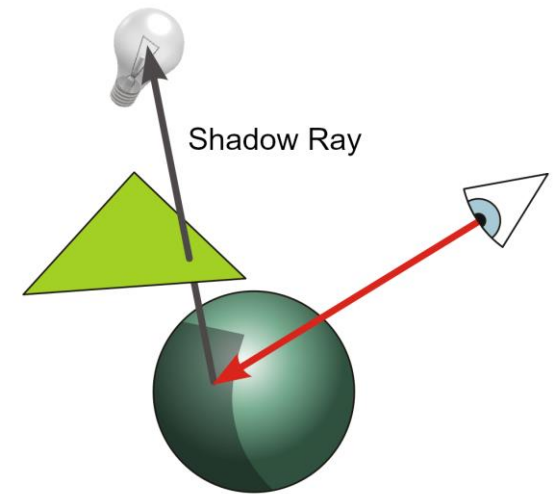
- Once you found the closest intersection point, compute color using the intersection and material data you got
- Phong shading: like Lab 1b
 - Ambient light: Only one global ambient light
 - Each object can have different coefficients for ambient, diffuse and specular light
- How to handle multiple lightsources?
 - Compute light for each source separately and sum them up
- Hints:
 - Don't multiply the specular light with the object's color
 - For specular light, the vector to the viewer is simply the flipped ray direction

Handling multiple light sources

```
trace(ray)
  for each object in scene
    intersection = object.intersect(ray)
  determine closest intersection
  if(intersection)
    for each light source
      color += illuminate(ray, intersection, light source)
  else
    color = backgroundColor
  return color
```

Shadows

- Before computing local illumination for a light source, cast shadow ray towards it
- If the shadow ray hits something, the light doesn't reach the surface
 - Ignore this light source

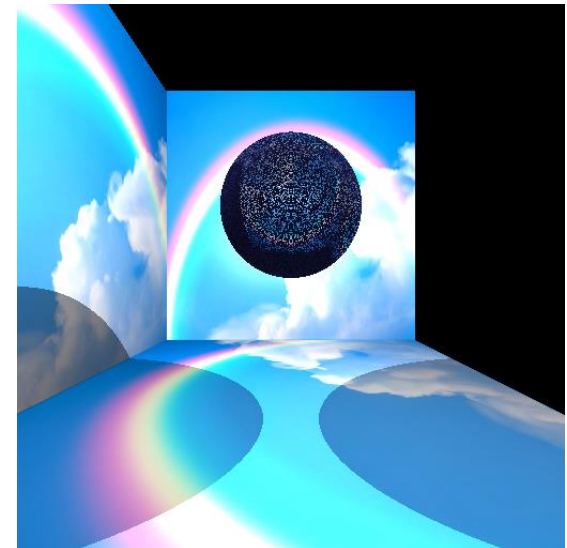
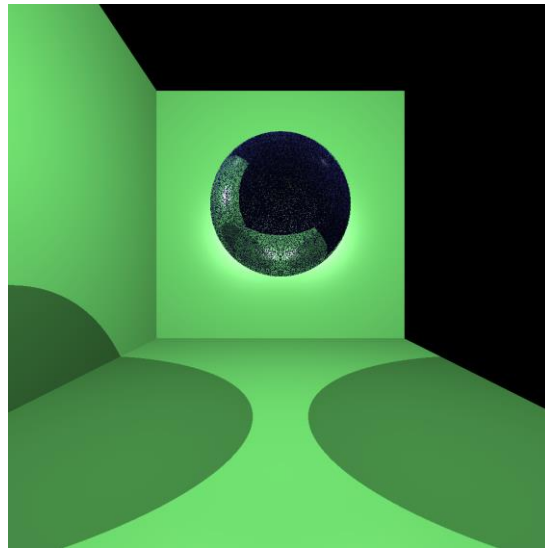
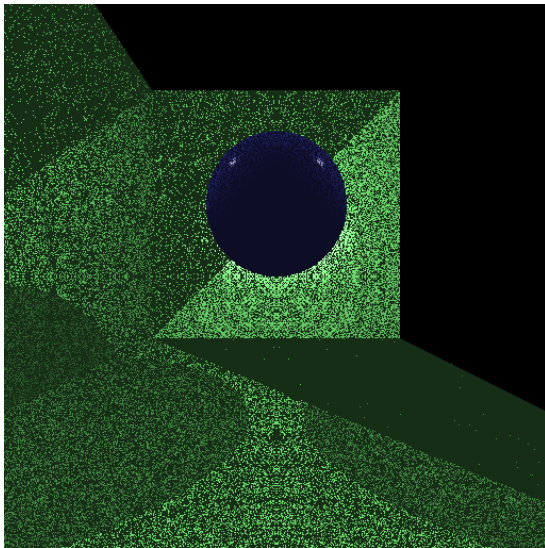


Casting Shadow Rays

```
trace(ray)
  for each object in scene
    intersection = object.intersect(ray)
  determine closest intersection
  if(intersection)
    for each light_source
      shadow_intersection = cast_shadowray(intersection, light_source)
      if(no shadow_intersection)
        color += illuminate(ray, intersection, light_source)
  else
    color = backgroundColor
  return color
```


Shadows Acne/Bias

- Due to imprecisions of floating point numbers, a ray can sometimes intersect at a point inside an object.
- Shadow (and also reflection and refraction) rays cast from these points will immediately intersect the object again



Shadows Acne/Bias

- How to solve this?
- Either:
 - Offset ray origin by small ε along the ray's/normal's direction
 - Reject intersections that have t too close to 0, i.e. $t < \varepsilon$
 - Might need to adjust ε depending on your exact circumstances

Hints & Common Mistakes

- **Normalize your vectors**
- Make sure that your vectors point in the right direction
- For debugging, consider encoding your normal/ray directions to colors
- Whenever you map values from one range to another (e.g. colors from $[0; 1]$ to $[0; 255]$ or vice versa), make sure to watch out for integer truncation
- Make sure to limit the travel distance of shadow rays. You don't want them to hit things behind the light source.

Questions?