

Keener, Theoretical Statistics

Chapter 2: Exponential Families

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2.4 Moments, Cumulants, and Generating Functions

Consider a random vector $T = (T_1, T_2, \dots, T_s) \in \mathbb{R}^s$, which we can think of as the outcome of a random experiment. Let $u = (u_1, u_2, \dots, u_s) \in \mathbb{R}^s$ be a constant vector.

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The MGF of the random vector T is defined as:

$$M_T(u) = \mathbb{E}[e^{u_1 T_1 + \dots + u_s T_s}] = \mathbb{E}[e^{u^T T}]$$

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The CGF of the random vector T is the natural logarithm of the MGF:

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Uniqueness of MGFs and Definition of Moments

Lemma (Uniqueness of MGFs)

If the moment generating functions $M_X(u)$ and $M_Y(u)$ for two random vectors X and Y are finite and agree for u in some set with a non-empty interior, then X and Y have the same distribution, i.e., $p_X = p_Y$.

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- ▶ $\alpha_{1,1} = \mathbb{E}[T_1^1 T_2^1] = \mathbb{E}[T_1 T_2]$ (Mixed moment)

Generating Moments and Cumulants

Theorem (Moments from MGF)

If the MGF $M_T(u)$ is finite in some neighborhood of the origin, then $M_T(u)$ has continuous derivatives of all orders at the origin. The moments of T can be found by differentiating $M_T(u)$ and evaluating at $u = 0$:

$$\alpha_{r_1, \dots, r_s} = \left. \frac{\partial^{r_1 + \dots + r_s}}{\partial u_1^{r_1} \dots \partial u_s^{r_s}} M_T(u) \right|_{u=0}$$

Definition: Cumulants

The corresponding derivatives of the Cumulant Generating Function $K_T(u)$ are called the **cumulants**, denoted κ :

$$\kappa_{r_1, \dots, r_s} = \left. \frac{\partial^{r_1 + \dots + r_s}}{\partial u_1^{r_1} \dots \partial u_s^{r_s}} K_T(u) \right|_{u=0}$$

Proof of the Moment Generation Theorem (1/3)

Given Moment Generating Function (MGF), $M_T(u) = \mathbb{E}[e^{u \cdot T}]$,
and the Taylor series expansion for an exponential function,

$$e^z = \sum_{n=0}^{\infty} \frac{z^n}{n!}.$$

Expand the term $e^{u \cdot T}$:

$$\begin{aligned} e^{u \cdot T} &= e^{u_1 T_1 + \dots + u_s T_s} \\ &= e^{u_1 T_1} \times e^{u_2 T_2} \times \dots \times e^{u_s T_s} \\ &= \left(\sum_{r_1=0}^{\infty} \frac{(u_1 T_1)^{r_1}}{r_1!} \right) \times \dots \times \left(\sum_{r_s=0}^{\infty} \frac{(u_s T_s)^{r_s}}{r_s!} \right) \\ &= \sum_{r_1, \dots, r_s=0}^{\infty} \frac{u_1^{r_1} \dots u_s^{r_s}}{r_1! \dots r_s!} T_1^{r_1} \dots T_s^{r_s} \end{aligned}$$

Proof of the Moment Generation Theorem (2/3)

Take the expectation to find the MGF. By the linearity of expectation:

$$\begin{aligned} M_T(u) &= \mathbb{E}[e^{u \cdot T}] = \mathbb{E} \left[\sum_{r_1, \dots, r_s=0}^{\infty} \frac{u_1^{r_1} \dots u_s^{r_s}}{r_1! \dots r_s!} T_1^{r_1} \dots T_s^{r_s} \right] \\ &= \sum_{r_1, \dots, r_s=0}^{\infty} \frac{u_1^{r_1} \dots u_s^{r_s}}{r_1! \dots r_s!} \mathbb{E}[T_1^{r_1} \dots T_s^{r_s}] \end{aligned}$$

Substitute the definition of moments, $\alpha_{r_1, \dots, r_s} = \mathbb{E}[T_1^{r_1} \dots T_s^{r_s}]$:

$$M_T(u) = \sum_{r_1, \dots, r_s=0}^{\infty} \frac{\alpha_{r_1, \dots, r_s}}{r_1! \dots r_s!} u_1^{r_1} \dots u_s^{r_s}$$

Proof of the Moment Generation Theorem (3/3)

We have established the power series representation of the MGF:

$$M_T(u) = \sum_{r_1, \dots, r_s=0}^{\infty} \frac{\alpha_{r_1, \dots, r_s}}{r_1! \dots r_s!} u_1^{r_1} \dots u_s^{r_s}$$

This is a multivariate Taylor series for $M_T(u)$ around the origin. The coefficients of this series are determined by the partial derivatives of the function. By differentiating this series term-by-term with respect to each u_i and then setting all $u_i = 0$, we isolate the coefficient corresponding to the desired moment:

$$\left. \frac{\partial^{r_1 + \dots + r_s}}{\partial u_1^{r_1} \dots \partial u_s^{r_s}} M_T(u) \right|_{u=0} = \alpha_{r_1, \dots, r_s}$$

Example: Cumulants of a Single Variable

Let T be a single random variable ($s = 1$), so u is a scalar. We have $K_T(u) = \log M_T(u)$.

First Cumulant (κ_1):

- ▶ Derivative: $K_T'(u) = \frac{M_T'(u)}{M_T(u)}$.
- ▶ At $u = 0$: $M_T(0) = \mathbb{E}[e^0] = 1$ and $M_T'(0) = \mathbb{E}[Te^0] = \mathbb{E}[T]$.
- ▶ Result: $\kappa_1 = K_T'(0) = \frac{\mathbb{E}[T]}{1} = \mathbb{E}[T]$.
- ▶ *The 1st cumulant is the mean.*

Second Cumulant (κ_2):

- ▶ Derivative: $K_T''(u) = \frac{M_T''(u)M_T(u) - (M_T'(u))^2}{M_T(u)^2}$.
- ▶ At $u = 0$: We also need $M_T''(0) = \mathbb{E}[T^2e^0] = \mathbb{E}[T^2]$.
- ▶ Result: $\kappa_2 = K_T''(0) = \frac{\mathbb{E}[T^2] \cdot 1 - (\mathbb{E}[T])^2}{1^2} = \mathbb{E}[T^2] - (\mathbb{E}[T])^2$.
- ▶ *The 2nd cumulant is the variance, $\text{Var}(T)$.*

A Lemma on Independence

Generating functions are particularly useful in the study of sums of independent random variables. The following property is fundamental.

Lemma

Suppose X and Y are independent random variables. If X and Y are both positive, or if $\mathbb{E}[|X|]$ and $\mathbb{E}[|Y|]$ are both finite, then:

$$\mathbb{E}[XY] = \mathbb{E}[X]\mathbb{E}[Y]$$

Proof

View $|X||Y|$ as a function g of the joint random variable $Z = (X, Y)$, which has the product measure $P_X \times P_Y$ due to independence.

$$\begin{aligned}\mathbb{E}[|X||Y|] &= \int \int |x||y| d(P_X \times P_Y) \\ &= \int \left(\int |x||y| dP_X(x) \right) dP_Y(y) \quad (\text{by Fubini's Thm}) \\ &= \int |y| \left(\int |x| dP_X(x) \right) dP_Y(y) \\ &= \int |y| \mathbb{E}[|X|] dP_Y(y) \\ &= \mathbb{E}[|X|] \int |y| dP_Y(y) = \mathbb{E}[|X|] \mathbb{E}[|Y|]\end{aligned}$$

If $\mathbb{E}[|X|], \mathbb{E}[|Y|]$ are finite, then $\mathbb{E}[|X||Y|] < \infty$, then apply same steps omitting the absolute values.

Generating Functions of Sums

MGF and CGF of a Sum of Independent Vectors

The lemma on expectations extends by iteration to products of several independent variables. Suppose $T = Y_1 + \cdots + Y_n$, where Y_1, \dots, Y_n are independent random vectors.

MGF of a Sum

$$\begin{aligned} M_T(u) &= \mathbb{E}[e^{u^T T}] = \mathbb{E}[e^{u^T (Y_1 + \cdots + Y_n)}] \\ &= \mathbb{E}[e^{u^T Y_1} e^{u^T Y_2} \cdots e^{u^T Y_n}] \end{aligned}$$

Since the Y_i vectors are independent, the random variables $e^{u^T Y_i}$ are also independent. Thus, the expectation of the product is the product of the expectations:

$$M_T(u) = \prod_{i=1}^n \mathbb{E}[e^{u^T Y_i}] = \prod_{i=1}^n M_{Y_i}(u)$$

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CGF of a Sum

Taking the logarithm gives a simpler relationship for the CGF:

$$\begin{aligned} K_T(u) &= \log \left(\prod_{i=1}^n M_{Y_i}(u) \right) = \sum_{i=1}^n \log M_{Y_i}(u) \\ \implies K_T(u) &= \sum_{i=1}^n K_{Y_i}(u) \end{aligned}$$

The Additivity of Cumulants

We get cumulants by differentiating the CGF ($K_T(u)$) and evaluating at $u = 0$. Since $K_T(u)$ is a sum of individual CGFs, its derivatives will be the sum of the individual derivatives.

The Additivity Property

The cumulants of a sum of independent random vectors are the sums of the corresponding cumulants of the individual vectors.

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Important Consequences

- **Mean (1st Cumulant):** The mean of a sum is the sum of the means.

$$\text{Mean}(T) = \sum_{i=1}^n \text{Mean}(Y_i)$$

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$$\text{Mean}(T) = \sum_{i=1}^n \text{Mean}(Y_i)$$

- **Variance (2nd Cumulant):** The variance of a sum is the sum of the variances.

$$\text{Var}(T) = \sum_{i=1}^n \text{Var}(Y_i)$$

Generating Functions for Exponential Families

If X has a density from a canonical exponential family, we can find the MGF of its sufficient statistic $T = T(X)$ directly.

$$\begin{aligned}M_T(u) &= \mathbb{E}_\eta[e^{u^T T}] = \int e^{u^T T(x)} p_\eta(x) d\mu(x) \\&= \int e^{u^T T(x)} \exp(\eta^T T(x) - A(\eta)) h(x) d\mu(x) \\&= \int \exp((u + \eta)^T T(x) - A(\eta)) h(x) d\mu(x) \\&= e^{-A(\eta)} \int \exp((u + \eta)^T T(x)) h(x) d\mu(x) \\&= e^{-A(\eta)} \cdot e^{A(u+\eta)} \quad (\text{by definition of } A(\cdot))\end{aligned}$$

This holds provided $(u + \eta)$ is in the natural parameter space Ξ .

The CGF for an Exponential Family

The Moment Generating Function is: $M_T(u) = e^{A(u+\eta)-A(\eta)}$.

Therefore, the Cumulant Generating Function is simply:

$$K_T(u) = A(u + \eta) - A(\eta)$$

The Power of the Log-Partition Function

The cumulants of T are the derivatives of $K_T(u)$ with respect to u , evaluated at $u = 0$.

$$\frac{\partial}{\partial u_j} K_T(u) = \frac{\partial}{\partial u_j} (A(u + \eta) - A(\eta)) = \frac{\partial A(v)}{\partial v_j} \Big|_{v=u+\eta}$$

Evaluating at $u = 0$ means we are simply taking the partial derivative of $A(\eta)$ with respect to η_j . This generalizes to all higher-order derivatives.

Main Result

The cumulants of the sufficient statistic T are the partial derivatives of the log-partition function $A(\eta)$ with respect to the natural parameters η .

$$\kappa_{r_1, \dots, r_s}(T) = \frac{\partial^{r_1 + \dots + r_s}}{\partial \eta_1^{r_1} \dots \partial \eta_s^{r_s}} A(\eta)$$

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- ▶ **Variance:** $\text{Var}_{\eta}(T_i) = \frac{\partial^2 A(\eta)}{\partial \eta_i^2}$
- ▶ **Covariance:** $\text{Cov}_{\eta}(T_i, T_j) = \frac{\partial^2 A(\eta)}{\partial \eta_i \partial \eta_j}$

Example: Cumulants of the Poisson Distribution

If X has the Poisson distribution with mean λ , its probability mass function is:

$$P(X = x) = \frac{\lambda^x e^{-\lambda}}{x!} = \frac{1}{x!} \exp(x \log \lambda - \lambda)$$

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This is an exponential family. To find the canonical form, we set the canonical parameter $\eta = \log \lambda$, which means $\lambda = e^\eta$.

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The cumulants of X are the derivatives of $A(\eta)$ with respect to η :

$$\kappa_k = \frac{d^k A(\eta)}{d\eta^k} = \frac{d^k e^\eta}{d\eta^k} = e^\eta = \lambda$$

Example: Normal Distribution with Fixed Variance

Consider the class of normal densities $N(\mu, \sigma^2)$ where μ varies but σ^2 is fixed. We can arrange the PDF as:

$$p_{\mu}(x) = \exp\left(\frac{\mu}{\sigma^2}x - \frac{\mu^2}{2\sigma^2}\right) \cdot \frac{\exp(-x^2/2\sigma^2)}{\sqrt{2\pi\sigma^2}}$$

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Since $A(\eta)$ is quadratic, all higher-order cumulants ($\kappa_3, \kappa_4, \dots$) are zero for the Normal distribution.

From Cumulants to Moments

To calculate moments from cumulants for a single random variable ($s = 1$), we can repeatedly differentiate the identity $M_T(u) = e^{K_T(u)}$ and evaluate the results at $u = 0$.

Recalling that at $u = 0$, $\mathbb{E}[T^n] = M_T^{(n)}(0)$ and $\kappa_n = K_T^{(n)}(0)$, this gives the following relationships:

Moments as Functions of Cumulants

$$\mathbb{E}[T] = \kappa_1$$

$$\mathbb{E}[T^2] = \kappa_2 + \kappa_1^2$$

$$\mathbb{E}[T^3] = \kappa_3 + 3\kappa_1\kappa_2 + \kappa_1^3$$

$$\mathbb{E}[T^4] = \kappa_4 + 3\kappa_2^2 + 4\kappa_1\kappa_3 + 6\kappa_1^2\kappa_2 + \kappa_1^4$$

These expressions can also be solved to express cumulants as functions of moments.

Examples: Higher Moments from Cumulants

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Recall that for a Poisson distribution, all cumulants are $\kappa_n = \lambda$.

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Recall that for a Normal distribution, $\kappa_1 = \mu$, $\kappa_2 = \sigma^2$, and $\kappa_{n \geq 3} = 0$.

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 $0 + 3(\sigma^2)^2 + 0 + 6\mu^2\sigma^2 + \mu^4 = 3\sigma^4 + 6\mu^2\sigma^2 + \mu^4$

CGF of a Shifted Random Vector

Consider shifting a random vector T by a constant vector $c \in \mathbb{R}^s$.
The MGF of the new vector $T + c$ is:

$$\begin{aligned}M_{T+c}(u) &= \mathbb{E}[e^{u^T(T+c)}] \\&= \mathbb{E}[e^{u^T T + u^T c}] \\&= e^{u^T c} \cdot \mathbb{E}[e^{u^T T}] \\&= e^{u^T c} M_T(u)\end{aligned}$$

CGF of a Shifted Random Vector

CGF Shift Property

Taking the logarithm reveals a simple additive relationship for the CGF:

$$K_{T+c}(u) = \log(e^{u^T c} M_T(u)) = u^T c + K_T(u)$$

This shows that shifting the random variable only adds a linear term to the CGF, which only affects the first cumulant (the mean) and leaves all higher-order cumulants (variance, skewness, etc.) unchanged.

Cumulants and Central Moments

The shift property $K_{T+c}(u) = u^T c + K_T(u)$ implies that for any derivative of order $j \geq 2$, the linear term $u^T c$ vanishes. This means that cumulants of order 2 and higher are **shift-invariant**. Specifically, they are invariant to centering the random variable:

$$\kappa_j(T) = \kappa_j(T - \mathbb{E}[T]) \quad \text{for } j \geq 2$$

This invariance provides a direct link between cumulants and central moments.

Cumulants and Central Moments

Relationship to Central Moments

For a centered random variable $Y = T - \mathbb{E}[T]$, the first cumulant $\kappa_1(Y)$ is 0. This simplifies the moment-cumulant formulas:

- ▶ **Third Cumulant:** $\kappa_3 = \mathbb{E}[(T - \mathbb{E}[T])^3]$. The 3rd cumulant measures skewness.
- ▶ **Fourth Cumulant:** $\mathbb{E}[(T - \mathbb{E}[T])^4] = \kappa_4 + 3\kappa_2^2$. This is often rearranged to define the 4th cumulant:

$$\kappa_4 = \mathbb{E}[(T - \mathbb{E}[T])^4] - 3(\text{Var}(T))^2$$

This is also known as the *excess kurtosis*.

Higher Dimensions

In the multi-dimensional case, the low-order cumulants correspond to the means and the covariance matrix of the vector T .

Exercise 2.1

Consider independent Bernoulli trials with a success probability of p . Let X be the number of failures before the first success. The probability mass function (PMF), using θ for the success probability, is:

$$P(X = x|\theta) = \theta(1 - \theta)^x, \quad x = 0, 1, 2, \dots$$

Goals:

- a) Show the geometric distribution is an exponential family.
- b) Write its density in canonical form and identify its components.
- c) Find the mean of the distribution using differentiation.
- d) Analyze the joint distribution of i.i.d. samples.

a) An Exponential Family Member

A distribution belongs to the exponential family if its PMF can be written as:

$$p(x|\theta) = h(x) \exp(\eta(\theta) T(x) - B(\theta))$$

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For the geometric PMF, $p(x|\theta) = \theta(1 - \theta)^x$:

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This form matches, with the sufficient statistic being $T(x) = x$ and $h(x) = 1$.

b) The Canonical Form

The canonical form is $p(x|\eta) = h(x) \exp(\eta T(x) - A(\eta))$. We need to express our PMF using the natural parameter η .

Canonical Parameter η

We have $\eta = \log(1 - \theta)$.

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Canonical Parameter η

We have $\eta = \log(1 - \theta)$. Solving for θ gives:

$$e^\eta = 1 - \theta \implies \theta = 1 - e^\eta$$

Log-Partition Function $A(\eta)$

Substituting θ back into the log-PMF from the previous slide:

$$\log(1 - e^\eta) + x\eta = \eta x - (-\log(1 - e^\eta))$$

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Thus, the log-partition function is:

$$A(\eta) = -\log(1 - e^\eta)$$

c) Finding the Mean via Differentiation

For an exponential family, the mean of the sufficient statistic is the first derivative of the log-partition function, $A(\eta)$.

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$$\begin{aligned} A'(\eta) &= \frac{d}{d\eta} (-\log(1 - e^\eta)) \\ &= -\frac{1}{1 - e^\eta} \cdot (-e^\eta) = \frac{e^\eta}{1 - e^\eta} \end{aligned}$$

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Converting back to θ (since $e^\eta = 1 - \theta$):

$$E[X] = \frac{1 - \theta}{\theta}$$

c) Finding the Variance via Differentiation

Similarly, the variance is the second derivative of $A(\eta)$.

$$\text{Var}(X) = A''(\eta)$$

$$\begin{aligned} A''(\eta) &= \frac{d}{d\eta} \left(\frac{e^\eta}{1 - e^\eta} \right) \\ &= \frac{e^\eta(1 - e^\eta) - e^\eta(-e^\eta)}{(1 - e^\eta)^2} \\ &= \frac{e^\eta}{(1 - e^\eta)^2} \end{aligned}$$

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Converting back to θ :

$$\text{Var}(X) = \frac{1 - \theta}{\theta^2}$$

d) Joint Distribution of i.i.d. Samples

For X_1, \dots, X_n i.i.d. from $\text{Geometric}(\theta)$, the joint PMF is:

$$\begin{aligned} p(\mathbf{x}|\theta) &= \prod_{i=1}^n \theta(1-\theta)^{x_i} \\ &= \theta^n (1-\theta)^{\sum x_i} \\ &= \exp \left(n \log(\theta) + \left(\sum x_i \right) \log(1-\theta) \right) \end{aligned}$$

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In terms of $\eta = \log(1-\theta)$, this becomes:

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In terms of $\eta = \log(1-\theta)$, this becomes:

$$p(\mathbf{x}|\eta) = \exp \left(\eta \left(\sum x_i \right) + n \log(1 - e^\eta) \right)$$

This is an exponential family with sufficient statistic

$T(\mathbf{x}) = \sum_{i=1}^n X_i$ and log-partition function

$A_n(\eta) = -n \log(1 - e^\eta) = nA(\eta)$.

d) Mean and Variance of the Sum

Using the new log-partition function $A_n(\eta) = nA(\eta)$, we can find the moments of the sufficient statistic $T = \sum X_i$.

Mean of T

$$\begin{aligned} E[T] &= \frac{dA_n(\eta)}{d\eta} = nA'(\eta) \\ &= n \frac{1 - \theta}{\theta} \end{aligned}$$

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Variance of T

$$\begin{aligned} \text{Var}(T) &= \frac{d^2 A_n(\eta)}{d\eta^2} = nA''(\eta) \\ &= n \frac{1 - \theta}{\theta^2} \end{aligned}$$

Exercise 2.23

Suppose $Z \sim N(0, 1)$. Find the first four cumulants of the random variable $X = Z^2$.

Hint

Consider the exponential family form of the more general distribution $N(0, \sigma^2)$.

The Exponential Family Formulation

The PDF of $Y \sim N(0, \sigma^2)$ is:

$$p(y; \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{y^2}{2\sigma^2}\right)$$

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We can rewrite this to identify its exponential family components:

$$p(y; \sigma^2) = \frac{1}{\sqrt{2\pi}} \exp\left(\left(\frac{-1}{2\sigma^2}\right) y^2 - \frac{1}{2} \log(\sigma^2)\right)$$

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- ▶ Sufficient Statistic: $T(y) = y^2$
- ▶ Natural Parameter: $\eta = -\frac{1}{2\sigma^2}$

The cumulant-generating function (CGF) of the sufficient statistic $T(y) = y^2$ can be derived from this form.

Deriving the CGF for $T = Y^2$

The exponential family form is:

$$p(y) = h(y) \exp(\eta y^2 - A(\eta)), \quad h(y) = \frac{1}{\sqrt{2\pi}}, \quad A(\eta) = \frac{1}{2} \log\left(-\frac{1}{\eta}\right)$$

Define the moment-generating function (MGF) of $T = Y^2$:

$$M_T(u) = \mathbb{E}[e^{uY^2}] = \exp(-A(\eta)) \int h(y) \exp((\eta + u)y^2) dy$$

We know that

$$M_T(u) = \exp(A(\eta + u) - A(\eta))$$

Compute the CGF as the log of the MGF:

$$K_T(u) = A(\eta + u) - A(\eta) = \frac{1}{2} \log\left(\frac{-1/\eta}{-1/(\eta + u)}\right) = -\frac{1}{2} \log\left(1 + \frac{u}{\eta}\right)$$

The Cumulant-Generating Function (CGF)

The CGF of the sufficient statistic $T = Y^2$ for $Y \sim N(0, \sigma^2)$ is found to be:

$$K_T(u) = -\frac{1}{2} \log \left(1 + \frac{u}{\eta} \right)$$

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We are interested in the case where $Z \sim N(0, 1)$, so we set $\sigma^2 = 1$. This gives a natural parameter of:

$$\eta = -\frac{1}{2(1)^2} = -\frac{1}{2}$$

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We are interested in the case where $Z \sim N(0, 1)$, so we set $\sigma^2 = 1$. This gives a natural parameter of:

$$\eta = -\frac{1}{2(1)^2} = -\frac{1}{2}$$

Substituting $\eta = -1/2$ into the CGF gives the CGF for Z^2 :

$$\begin{aligned} K_{Z^2}(u) &= -\frac{1}{2} \log \left(1 + \frac{u}{-1/2} \right) \\ &= -\frac{1}{2} \log(1 - 2u) \end{aligned}$$

Calculating the Cumulants

The k -th cumulant, κ_k , is the k -th derivative of the CGF, evaluated at $u = 0$.

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$$K'(u) = -\frac{1}{2} \cdot \frac{-2}{1-2u} = (1 - 2u)^{-1}$$

$$\kappa_1 = K'(0) = 1$$

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Second Derivative (κ_2)

$$K''(u) = (-1)(1 - 2u)^{-2}(-2) = 2(1 - 2u)^{-2}$$

$$\kappa_2 = K''(0) = 2$$

Calculating the Cumulants (cont.)

Continuing with the derivatives of $K(u) = -\frac{1}{2} \log(1 - 2u)$.

Third Derivative (κ_3)

$$K'''(u) = 2(-2)(1 - 2u)^{-3}(-2) = 8(1 - 2u)^{-3}$$

$$\kappa_3 = K'''(0) = 8$$

Calculating the Cumulants (cont.)

Continuing with the derivatives of $K(u) = -\frac{1}{2} \log(1 - 2u)$.

Third Derivative (κ_3)

$$K'''(u) = 2(-2)(1 - 2u)^{-3}(-2) = 8(1 - 2u)^{-3}$$

$$\kappa_3 = K'''(0) = 8$$

Fourth Derivative (κ_4)

$$K^{(4)}(u) = 8(-3)(1 - 2u)^{-4}(-2) = 48(1 - 2u)^{-4}$$

$$\kappa_4 = K^{(4)}(0) = 48$$

Summary of Results

For the random variable $X = Z^2$ where $Z \sim N(0, 1)$, the first four cumulants are:

► $\kappa_1 = E[X] = 1$

► $\kappa_3 = 8$

► $\kappa_2 = \text{Var}(X) = 2$

► $\kappa_4 = 48$

3.1 Models, Estimators, and Risk Functions

In inferential statistics, we aim to learn about an unknown parameter θ from observed data X .

The **parameter** θ and **data** X are related through a statistical **model**. When the parameter's value is θ , the data's distribution is denoted by P_θ .

Formal Definition

A model \mathcal{P} is a set of distributions for the data X , indexed by the parameter θ :

$$\mathcal{P} = \{P_\theta : \theta \in \Omega\}$$

where Ω is the **parameter space**, representing all possible values for θ .

Example: A Coin Toss Experiment

Suppose we model a coin toss that is performed 100 times, with independent trials and a common probability θ of landing heads.

- ▶ **Data:** The total number of heads, X .
- ▶ **Distribution:** X follows a Binomial distribution, $X \sim \text{Binom}(100, \theta)$.
- ▶ **Parameter Space:** $\theta \in [0, 1]$.

The statistical model \mathcal{P} is the set of all binomial distributions with 100 trials:

$$\mathcal{P} = \{P_\theta = \text{Binom}(100, \theta) \mid \theta \in [0, 1]\}$$

Estimation: Guessing the Parameter

A primary goal of statistical inference is **estimation**. We want to find a function of the data, called a **statistic**, that gives a good guess for the true value of θ .

Estimator

An **estimator** $\delta(X)$ is a function of the data used to estimate a parameter θ (or a function of it, $g(\theta)$). The resulting value, $\delta(X)$, is the **estimate**.

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Example continued: For the coin toss experiment, a natural estimator for the probability of heads θ is the sample proportion:

$$\delta(X) = \frac{X}{100}$$

How Good Is an Estimate?

To judge the quality of an estimator, we need to quantify the "cost" or "error" of a bad estimate. This is done using a **loss function**.

Loss Function $L(\theta, d)$

A loss function $L(\theta, d)$ measures the penalty associated with estimating the true parameter value θ with an estimate d .

- ▶ $L(\theta, \theta) = 0$ (no loss for a perfect estimate)
- ▶ $L(\theta, d) \geq 0$ for all $d \neq \theta$

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- ▶ $L(\theta, d) \geq 0$ for all $d \neq \theta$

A very common choice is the **squared error loss**:

$$L(\theta, d) = (\theta - d)^2$$

Average Loss: The Risk Function

The loss $L(\theta, \delta(X))$ is random because the data X is random. We can be unlucky and get a large loss even with a good estimator.

To evaluate an estimator's overall performance, we look at its **average loss**, known as the **risk function**.

Risk Function $R(\theta, \delta)$

The risk of an estimator δ is its expected loss, where the expectation is taken over the distribution of the data X given θ .

$$R(\theta, \delta) = \mathbb{E}_{\theta}[L(\theta, \delta(X))]$$

Example: Risk of the Sample Mean

Let's find the risk for our coin toss example.

- ▶ Data: $X \sim \text{Binom}(100, \theta)$
- ▶ Estimator: $\delta(X) = \frac{X}{100}$
- ▶ Loss Function: Squared error loss $L(\theta, d) = (\theta - d)^2$

Example: Risk of the Sample Mean

Let's find the risk for our coin toss example.

- ▶ Data: $X \sim \text{Binom}(100, \theta)$
- ▶ Estimator: $\delta(X) = \frac{X}{100}$
- ▶ Loss Function: Squared error loss $L(\theta, d) = (\theta - d)^2$

The risk function $R(\theta, \delta)$ is:

$$\begin{aligned} R(\theta, \delta) &= \mathbb{E}_{\theta} \left[\left(\theta - \frac{X}{100} \right)^2 \right] \\ &= \frac{1}{100^2} \mathbb{E}_{\theta} [(X - 100\theta)^2] \\ &= \frac{1}{100^2} \text{Var}_{\theta}(X) \\ &= \frac{100\theta(1 - \theta)}{100^2} = \frac{\theta(1 - \theta)}{100} \end{aligned}$$

A Fundamental Problem in Estimation

How do we choose the "best" estimator?

A fundamental problem arises when comparing two different estimators, say δ_1 and δ_2 , using their risk functions.

The Challenge

If the risk functions $R(\theta, \delta_1)$ and $R(\theta, \delta_2)$ cross, there is no clear answer as to which estimator is universally better. One may have lower risk for some values of θ , while the other is better for other values of θ .