3.4 - 3.5 Monte Carlo approaches to EM

Section 3.5

Motivation

1 In the mean score approach, the MLE can be found by solving

$$E\left\{S_{\text{com}}\left(\frac{\boldsymbol{\eta}}{\boldsymbol{\eta}}\right)\mid\mathbf{y}_{\text{obs}},\boldsymbol{\delta}\right\}=0$$

which requires the knowledge of the conditional distribution of $\mathbf{y}_{\mathrm{mis}}$ given $\mathbf{y}_{\mathrm{obs}}$ and δ .

- 2 In the EM algorithm defined by
 - [E-step] Compute

$$Q\left(\frac{\boldsymbol{\eta}}{\boldsymbol{\eta}}\mid\boldsymbol{\eta}^{(t)}\right) = E\left\{\ln L_{\text{com}}\left(\frac{\boldsymbol{\eta}}{\boldsymbol{\eta}}\right)\mid\mathbf{y}_{\text{obs}},\boldsymbol{\delta},\boldsymbol{\eta}^{(t)}\right\}$$

• [M-step] Find $\eta^{(t+1)}$ that maximizes $Q\left(\frac{\eta}{\eta} \mid \eta^{(t)}\right)$,

E-step is computationally cumbersome because it involves integral.



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Monte Carlo EM (MCEM) method (Wei and Tanner, 1990)

In the E-step, first draw

$$\mathbf{y}_{\mathrm{mis}}^{*(1)}, \cdots, \mathbf{y}_{\mathrm{mis}}^{*(m)} \overset{\mathit{iid}}{\sim} \rho\left(\mathbf{y}_{\mathrm{mis}} \mid \mathbf{y}_{\mathrm{obs}}, \boldsymbol{\delta}, \eta^{(t)}\right) = \frac{f(\mathbf{y}, \boldsymbol{\delta}; \eta^{(t)})}{\int f(\mathbf{y}, \boldsymbol{\delta}; \eta^{(t)}) d\mathbf{y}_{\mathrm{mis}}}$$

and approximate

$$Q\left(\frac{\boldsymbol{\eta}}{\boldsymbol{\eta}}\mid\boldsymbol{\eta}^{(t)}\right)\cong\frac{1}{m}\sum_{i=1}^{m}\ln f\left(\mathbf{y}_{\mathrm{obs}},\mathbf{y}_{\mathrm{mis}}^{*(j)},\boldsymbol{\delta};\boldsymbol{\eta}\right).$$

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Example 3.14 (Nonignorable missing)

$$y_i \sim f(y_i \mid x_i; \theta)$$

Assume that x_i is always observed but we observe y_i only when $\delta_i = 1$ where $\delta_i \sim \textit{Bernoulli}\left[\pi_i\left(\phi\right)\right]$ and

$$\pi_{i}(\phi) = \frac{\exp(\phi_{0} + \phi_{1}x_{i} + \phi_{2}y_{i})}{1 + \exp(\phi_{0} + \phi_{1}x_{i} + \phi_{2}y_{i})}.$$

To implement the MCEM method, we need to generate samples from

$$f\left(y_{i}\mid x_{i}, \delta_{i}=0; \hat{\theta}, \hat{\phi}\right) = \frac{f\left(y_{i}\mid x_{i}; \hat{\theta}\right)\left[1-\pi_{i}\left(\hat{\phi}\right)\right]}{\int f\left(y_{i}\mid x_{i}; \hat{\theta}\right)\left[1-\pi_{i}\left(\hat{\phi}\right)\right] dy_{i}}$$
(1)

How to generate samples from (1)?

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Rejection sampling method

Problem

 Given a density of interest f, suppose that there exist a density g and a constant M such that

$$f\left(x\right)\leq Mg\left(x\right)$$

on the support of f.

• We are interested in generating samples from f, which is difficult. But, generating samples from g is easy.

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Rejection sampling method

The rejection sampling method (or accept-rejection method) is

- **1** Sample $Y \sim g$ and $U \sim Unif(0,1)$.
- Reject Y if

$$U > \frac{f(Y)}{Mg(Y)}.$$

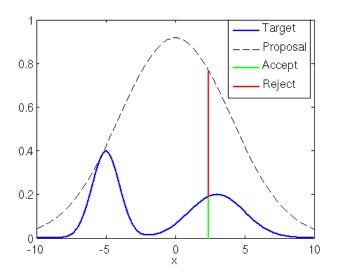
In this case, do not record the value of Y as an element in the target random sample. Instead, return to step 1.

3 Otherwise, keep the value of Y. Set X = Y, and consider X to be an element of the target random sample.



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Rejection sampling method



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Remark

1 In the rejection sampling method,

$$P(Y \le y) = P\left[X \le y \mid U \le \frac{f(X)}{Mg(X)}\right]$$
$$= \frac{\int_{-\infty}^{y} \int_{0}^{f(x)/Mg(x)} dug(x) dx}{\int_{-\infty}^{\infty} \int_{0}^{f(x)/Mg(x)} dug(x) dx}$$
$$= \frac{\int_{-\infty}^{y} f(x) dx}{\int_{-\infty}^{\infty} f(x) dx}$$

2 The rejection sampling method can be applicable when the density f is known up to a multiplicative factor.



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Example 3.14 (Cont'd)

We can use the following rejection method to generate m Monte Carlo samples from $f(y_i \mid x_i, \delta_i = 0; \hat{\theta}, \hat{\phi})$:

- **1** Generate y_i^* from $f(y_i \mid x_i; \hat{\theta})$.
- 2 Using y_i^* , compute

$$\pi_i^* \left(\hat{\phi} \right) = \frac{\exp \left(\hat{\phi}_0 + \hat{\phi}_1 x_i + \hat{\phi}_2 y_i^* \right)}{1 + \exp \left(\hat{\phi}_0 + \hat{\phi}_1 x_i + \hat{\phi}_2 y_i^* \right)}.$$

3 Accept y_i^* with probability $1 - \pi_i^*(\hat{\phi})$. Otherwise, goto Step 1.



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Example 3.14 (Cont'd)

M-step: Update the parameters by solving

$$\sum_{i=1}^{n} \sum_{j=1}^{m} S\left(\theta; x_i, y_i^{*(j)}\right) = 0$$

and

$$\sum_{i=1}^{n} \sum_{j=1}^{m} \left\{ \delta_{i} - \pi(\phi; x_{i}, y_{i}^{*(j)}) \right\} \left(1, x_{i}, y_{i}^{*(j)} \right) = 0,$$

where $S(\theta; x_i, y_i) = \partial \log f(y_i \mid x_i; \theta) / \partial \theta$.

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Importance sampling

Write $\theta \equiv \int h(x) f(x) dx = \int h(x) \frac{f(x)}{g(x)} g(x) dx$ for some density g(x) and approximate θ by

$$\hat{\theta} = \sum_{i=1}^{n} w_i h(X_i)$$

where

$$w_i = \frac{f(X_i)/g(X_i)}{\sum_{j=1}^n f(X_j)/g(X_j)}$$

and X_1, \dots, X_n are IID with pdf g(x). The weight w_i is called important weight.

(Details are skipped. Will be covered again in Chapter 6)



Section 3.5

Markov Chain Monte Carlo (MCMC) method

What is MCMC?

- Markov Chain Monte Carlo: A body of methods for generating pseudorandom draws from probability distributions via Markov chains
- Markov chain: A sequence of random variables in which the distribution of each element depends only the previous one:

$${X_t; t = 1, 2, \cdots}$$

where

$$P(X_t | X_0, X_1, \dots, X_{t-1}) = P(X_t | X_{t-1}).$$

"Today is the tomorrow of yesterday".

History of MCMC

- Metropolis et al (1953): algorithm for indirect simulation of energy distributions
- Hastings (1970): extension of Metropolis to a non-symmetric jumping distributions
- Seman and Geman (1984): the "Gibbs sampler" for Bayesian image reconstruction
- Tanner and Wong (1987): data augmentation for Bayesian inference in generic missing-data problems
- **6** Gelfand and Smith (1990): simulation of marginal distributions by repeated draws from conditionals

Basic setup for MCMC

- X: generic random vector with density f(X)
- f(X): difficult to simulate directly
- Goal: construct a Markov chain $\{X^{(t)}; t = 1, 2 \cdots\}$ with f as its stationary distribution,

$$P\left(X^{(t)}\right) o f$$
 as $t o \infty$

or

$$\frac{1}{N}\sum_{t=1}^{N}h\left(X^{(t)}\right)\to E_{f}\left[h\left(X\right)\right]=\int h\left(x\right)f\left(x\right)dx\tag{2}$$

as $N \to \infty$.

A Markov chain that satisfies (2) is called ergodic.

Metropolis-Hastings algorithm: Algorithm

Starting with $X^{(0)}$ iterate for $t = 1, 2, \cdots$

- **1** Draw $X^* \sim q(\cdot \mid X^{(t-1)})$.
- 2 Compute

$$R\left(X^{*}, X^{(t-1)}\right) = \frac{q\left(X^{(t-1)} \mid X^{*}\right)}{q\left(X^{*} \mid X^{(t-1)}\right)} \frac{f\left(X^{*}\right)}{f\left(X^{(t-1)}\right)}$$

and

$$\rho\left(X^*,X^{(t-1)}\right)=\min\{R\left(X^*,X^{(t-1)}\right),1\}.$$

3 With probability $\rho\left(X^*, X^{(t-1)}\right)$ set $X^{(t)} = X^*$. Otherwise set $X^{(t)} = X^{(t-1)}$.

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Remark

• The probability of acceptance does not depend on the normalization constant: If $f(x) = C \cdot \pi(x)$, then

$$R\left(X^{*}\mid X^{(t-1)}\right) = \frac{q\left(X^{(t-1)}\mid X^{*}\right)}{q\left(X^{*}\mid X^{(t-1)}\right)} \frac{\pi\left(X^{*}\right)}{\pi\left(X^{(t-1)}\right)}.$$

- Usually, q is chosen so that $q(y \mid x)$ is easy to sample from.
- The Markov chain is irreducible if $q(X \mid X^{(t-1)}) > 0$ for all $X, X^{(t-1)} \in \text{supp}(f)$: every state can be reached in a single step.

Remark (Cont'd)

• In the independent chain where $q(X^* \mid X^{(t)}) = q(X^*)$, the Metropolis-Hastings ratio is

$$R\left(X^{*},X^{(t)}\right) = \frac{f\left(X^{*}\right)/q\left(X^{*}\right)}{f\left(X^{(t)}\right)/q\left(X^{(t)}\right)},$$

which is the ratio of the importance weight for X^* over the importance weight for $X^{(t)}$. Thus, the Metropolis-Hastings ratio $R\left(X^*,X^{(t)}\right)$ is also called the importance ratio.

- The basic idea of the MH algorithm is
 - from the current position x, move to y according to $q(y \mid x)$ and
 - we decide to stay at y, roughly speaking, with probability f(y)/f(x).
- Hence, $q(y \mid x)$ having more mass when f(y) is larger is a good candidate.

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Example 3.14 (Normal-Cauchy model)

- Let $Y_1, \dots, Y_n \stackrel{iid}{\sim} N(\theta, 1)$
- Prior: Cauchy distribution

$$\pi\left(\frac{\theta}{\theta}\right) = \frac{1}{\pi\left(1 + \frac{\theta^2}{\theta^2}\right)}\tag{3}$$

Posterior

$$\pi\left(\frac{\theta}{y}\right) \propto \exp\left\{-\frac{\sum_{i=1}^{n}(y_{i}-\theta)^{2}}{2}\right\} \times \frac{1}{1+\theta^{2}}$$

$$\propto \exp\left\{-\frac{n(\theta-\bar{y})^{2}}{2}\right\} \times \frac{1}{1+\theta^{2}}$$

• We want to generate $\theta \sim \pi \left(\theta \mid y \right)$.

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Example 3.13 (Normal-Cauchy model)

- MH algorithm
 - **1** Generate θ^* from Cauchy (0,1).
 - 2 Given y_1, \dots, y_n , compute the importance ratio

$$R\left(\theta^*, \theta^{(t)}\right) = \frac{\pi(\theta^* \mid y) / \pi(\theta^*)}{\pi(\theta^{(t)} \mid y) / \pi(\theta^{(t)})} = \frac{f\left(y \mid \theta^*\right)}{f\left(y \mid \theta^{(t)}\right)}$$

where $f(y \mid \theta) = C \exp \{-n(\theta - \bar{y})^2/2\}$ and $\pi(\theta)$ is defined in (3).

 $\textbf{3} \text{ Accept } \theta^* \text{ as } \theta^{(t+1)} \text{ with probability } \rho(\theta^{(t)}, \theta^*) = \min \Big\{ R\left(\theta^{(t)}, \theta^*\right), 1 \Big\}.$

Random-walk Metropolis: Idea

- ullet In the Metropolis-Hastings algorithm the proposal is from $X \sim q\left(\cdot \mid X^{(t-1)}
 ight)$.
- A popular choice for the proposal is $q(X \mid X^{(t-1)}) = g(X X^{(t-1)})$ with g being a symmetric distribution. That is,

$$X = X^{(t-1)} + \epsilon, \quad \epsilon \sim g.$$

The Metropolis-Hastings ratio becomes

$$R\left(X^{*},X^{(t)}\right) = \frac{g\left(X^{(t-1)} - X^{*}\right)}{g\left(X^{*} - X^{(t-1)}\right)} \frac{f\left(X^{*}\right)}{f\left(X^{(t-1)}\right)} = \frac{f\left(X^{*}\right)}{f\left(X^{(t-1)}\right)}.$$

- We accept
 - every move to a more probable state with probability 1.
 - Moves to less probable states with a probability $f(X^*)/f(X^{(t-1)}) < 1$.

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Kim Section 3.4

Example 3.18 (GLMM)

• Basic Setup: Let y_{ij} be a binary random variable (that takes 0 or 1) with probability $p_{ij} = Pr\left(y_{ij} = 1 \mid \mathbf{x}_{ij}, \mathbf{a}_i\right)$ and we assume that

$$logit(p_{ij}) = \mathbf{x}'_{ij}\mathbf{\beta} + \mathbf{a}_i$$

where \mathbf{x}_{ij} is a p-dimensional covariate associate with j-th repetition of unit i, $\boldsymbol{\beta}$ is the parameter of interest that can represent the treatment effect due to \mathbf{x} , and \mathbf{a}_i represents the random effect associate with unit i. We assume that \mathbf{a}_i are iid with $N\left(0, \sigma^2\right)$.

- Missing data: a_i
- Observed likelihood:

$$L_{\text{obs}}\left(\boldsymbol{\beta}, \sigma^{2}\right) = \prod_{i} \int \left\{ \prod_{j} p(\mathbf{x}_{ij}, \mathbf{a}_{i}; \boldsymbol{\beta})^{y_{ij}} \left[1 - p(\mathbf{x}_{ij}, \mathbf{a}_{i}; \boldsymbol{\beta})\right]^{1 - y_{ij}} \right\} \frac{1}{\sigma} \phi\left(\frac{\mathbf{a}_{i}}{\sigma}\right) d\mathbf{a}_{i}$$

where $\phi(\cdot)$ is the pdf of the standard normal distribution.

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 To apply EM algorithm, note that a_i are observed in the complete sample log-likelihood

$$\ell_{\text{com}}(\beta, \sigma^2) = \ell_{\text{com}, 1}(\beta) + \ell_{\text{com}, 2}(\sigma^2)$$

where

$$\ell_{\text{com},1}(\beta) = \sum_{i} \sum_{j} [y_{ij} \log p_{ij}(\beta) + (1-y_{ij}) \log\{1-p_{ij}(\beta)\}]$$

and

$$\ell_{\text{com},2}(\sigma^2) = -\frac{1}{2}\log(2\pi\sigma^2) - \frac{1}{2\sigma^2}a_i^2$$

Thus, in the E-step, we need to compute

$$Q(\theta \mid \theta^{(t)}) = E\left\{\ell_{\mathrm{com}}(oldsymbol{eta}, \sigma^2) \mid \mathsf{data}, \theta^{(t)}
ight\}$$

where the conditional expectation is with respect to $f(a_i | \mathbf{x}_i, \mathbf{y}_i; \theta^{(t)})$.

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MCEM approach: Target distribution is

$$f(a_i \mid \mathbf{x}_i, \mathbf{y}_i; \hat{\boldsymbol{\beta}}, \hat{\sigma}) \propto f_1(\mathbf{y}_i \mid \mathbf{x}_i, a_i; \hat{\boldsymbol{\beta}}) f_2(a_i; \hat{\sigma}).$$

• M-H algorithm 1: Generate a_i^* from $f_2(a_i; \hat{\sigma})$. Then, we accept a_i^* with probability

$$\rho\left(a_{i}^{*}, a_{i}^{(t-1)}\right) = \min\left\{\frac{f_{1}\left(\mathbf{y}_{i} \mid \mathbf{x}_{i}, a_{i}^{*}; \hat{\boldsymbol{\beta}}\right)}{f_{1}\left(\mathbf{y}_{i} \mid \mathbf{x}_{i}, a_{i}^{(t-1)}; \hat{\boldsymbol{\beta}}\right)}, 1\right\}.$$

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M-H algorithm 2: Random Walk Metropolis algorithm

- **1** Starting with any $a_i^{(0)}$, iterate for $t = 1, 2 \cdots$
- 2 Draw $\epsilon_i \sim N(0, 0.1)$ and set

$$a_i^* = a_i^{(t-1)} + \epsilon_i$$

3 Compute

$$R(a_i^*, a_i^{(t-1)}) = \frac{f(a_i^* \mid \mathbf{x}_i, \mathbf{y}_i; \hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\sigma}})}{f(a_i^{(t-1)} \mid \mathbf{x}_i, \mathbf{y}_i; \hat{\boldsymbol{\beta}}, \hat{\boldsymbol{\sigma}})}$$

and

$$\rho(a_i^*, a_i^{(t-1)}) = \min\{R(a_i^*, a_i^{(t+1)}), 1\}.$$

4 Set $a_i^{(t)} = a_i^*$ with probability $\rho(a_i^*, a_i^{(t+1)})$. Otherwise, set $a_i^{(t)} = a_i^{(t-1)}$.

Summary

- Monte Carlo methods can be used to compute the E-step of the EM algorithm.
- Sometimes, MCMC algorithm is used for the E-step and so it is an MCMC-EM algorithm.
- Because of the nature of MC algorithm, the convergence is not guaranteed for a fixed MC sample size. Booth and Hobert (1999) discussed some convergence criteria for MCEM.

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