

1.

(a) Observation equation

$$: y_t = y_t^* + \varepsilon_t, \quad \varepsilon_t \sim N(0, \sigma_\varepsilon^2)$$

Transition equation

$$: \begin{bmatrix} y_{t+1}^* \\ \Phi_t y_t^* + \theta z_{t+1} \end{bmatrix} = \begin{bmatrix} \Phi_t & 1 \\ \Phi_t & 0 \end{bmatrix} \begin{bmatrix} y_t^* \\ \Phi_t y_{t-1}^* + \theta z_t \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} z_{t+1} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u$$

where $z_t \sim N(0, \sigma_z^2)$

$$y_1^* \sim N(\alpha_1, P_1)$$

(b) We can write the model as $y_t = I y_t^* + \varepsilon_t$,where I is a identity matrix.Assume that α_1, P_1 are known, from $y_1^* \sim N(\alpha_1, P_1)$ and, let $Y_t = (y_1, \dots, y_{t-1})'$ We need to obtain $\alpha_{t+1} = E(y_{t+1}^* | Y_t)$, $P_{t+1} = \text{Var}(y_{t+1}^* | Y_t)$

$$\alpha_{t+1} = E(y_{t+1}^* | Y_t), \quad P_{t+1} = \text{Var}(y_{t+1}^* | Y_t)$$

Assume that $y_t^* | Y_t \sim N(\alpha_{t+1}, P_{t+1})$

$$y_{t+1}^* | Y_t \sim N(\alpha_{t+1}, P_{t+1})$$

$$\text{Let } v_t = y_t - E(y_t | Y_{t-1}) = y_t - I \alpha_t = y_t - \alpha_t$$

When Y_{t-1} and v_t are fixed, Y_t is also fixed.

$$\text{Thus, } \alpha_{t+1} = E(y_{t+1}^* | Y_t) = E(y_{t+1}^* | Y_{t-1}, v_t)$$

$$\alpha_{t+1} = E(y_{t+1}^* | Y_t) = E(y_{t+1}^* | Y_{t-1}, v_t)$$

Lemma

Suppose that $\begin{pmatrix} x \\ y \end{pmatrix} \sim N\left(\begin{pmatrix} \mu_x \\ \mu_y \end{pmatrix}, \begin{pmatrix} \Sigma_{xx} & \Sigma_{xy} \\ \Sigma_{yx} & \Sigma_{yy} \end{pmatrix}\right)$

Then, $x|y \sim N(\mu_x + \Sigma_{xy}\Sigma_{yy}^{-1}(y - \mu_y), \Sigma_{xx} - \Sigma_{xy}\Sigma_{yy}^{-1}\Sigma_{yx})$

Taking x and y as y_t^* and v_t , we can obtain

$$a_{t+1} = E(y_t^* | \mathcal{F}_t) = E(y_t^* | \mathcal{F}_{t-1}, v_t)$$

$$= E(y_t^* | \mathcal{F}_{t-1}) + \text{Cov}(y_t^*, v_t | \mathcal{F}_{t-1}) \text{Var}(v_t | \mathcal{F}_{t-1})^{-1} v_t$$

$$\text{and, } \text{Cov}(y_t^*, v_t | \mathcal{F}_{t-1}) = E(y_t^* (I y_t^* + \varepsilon_t - I a_t)' | \mathcal{F}_{t-1})$$

$$= E(y_t^* (y_t^* - a_t)' I | \mathcal{F}_{t-1}) = P_t I' = P_t$$

$$\text{Var}(v_t | \mathcal{F}_{t-1}) = \text{Var}(I y_t^* + \varepsilon_t - I a_t | \mathcal{F}_{t-1})$$

$$= I P_t I' + \sigma_\varepsilon^2 = P_t + \sigma_\varepsilon^2 = F_t, \text{ say.}$$

$$\text{Thus, } a_{t+1} = a_t + P_t F_t^{-1} v_t$$

Using Lemma, we can obtain

$$P_{t+1} = \text{Var}(y_t^* | \mathcal{F}_t) = \text{Var}(y_t^* | \mathcal{F}_{t-1}, v_t)$$

$$= \text{Var}(y_t^* | \mathcal{F}_{t-1}) - \text{Cov}(y_t^*, v_t | \mathcal{F}_{t-1}) \text{Var}(v_t | \mathcal{F}_{t-1})^{-1} \text{Cov}(y_t^*, v_t | \mathcal{F}_{t-1})'$$

$$= P_t - P_t F_t^{-1} P_t'$$

Now, we can develop recursion for a_{t+1} and P_{t+1} .

$$a_{t+1} = E(\phi_t y_t^* + \theta z_t | \mathcal{F}_t) = \phi_t a_{t+1}$$

$$P_{t+1} = \text{Var}(\phi_t y_t^* + \theta z_t | \mathcal{F}_t) = \phi_t \text{Var}(y_t^* | \mathcal{F}_t) \phi_t' + \theta \sigma_\varepsilon^2 \theta'$$

$$= \phi_t P_{t+1} \phi_t' + \theta \sigma_\varepsilon^2 \theta'$$

And,

$$a_{t+1} = \phi_t (a_t + P_t F_t^{-1} v_t) = \phi_t a_t + K_t v_t$$

$$\text{where } K_t = \phi_t P_t I' F_t^{-1} = \phi_t P_t F_t^{-1}$$

$$P_{t+1} = \Phi_1 (P_t - P_t F_t^{-1} P_t') \Phi_1' + \theta \sigma_\epsilon^2 \theta'$$

$$= \Phi_1 P_t (\Phi_1 - K_t)' + \theta \sigma_\epsilon^2 \theta'$$

State estimation x_t can be defined as

$$x_t = y_t^* - a_t \quad \text{with} \quad \text{Var}(x_t) = P_t.$$

Then,

$$v_t = y_t - a_t = I y_t^* + \epsilon_t - a_t = y_t^* + \epsilon_t - a_t$$

$$= x_t + \epsilon_t$$

$$\text{Thus, } x_{t+1} = y_{t+1}^* - a_{t+1} = \Phi_1 y_t^* + \theta z_t - \Phi_1 a_t - K_t v_t$$

$$= \Phi_1 y_t^* + \theta z_t - K_t x_t - K_t \epsilon_t$$

$$= L_t x_t + \theta z_t - K_t \epsilon_t$$

$$\text{where } L_t = \Phi_1 - K_t.$$

In Summary,

$$v_t = y_t - a_t$$

$$F_t = P_{t+1} \sigma_\epsilon^{-2}$$

$$a_{t|t} = a_t + P_t F_t^{-1} v_t$$

$$P_{t|t} = P_t - P_t F_t^{-1} P_t'$$

$$a_{t+1} = \Phi_1 a_t + K_t v_t$$

$$P_{t+1} = \Phi_1 P_t (\Phi_1 - K_t)' + \theta \sigma_\epsilon^2 \theta'$$

$$\hat{x}_{t+1} = L_t x_t + \theta z_t - K_t \epsilon_t.$$

(c)

We need to obtain $\hat{y}_t^* = E(y_t^* | Y_n)$

Let $v_{t:n} = (v_t', \dots, v_n')'$, Y_n is fixed when Y_{t-1} and $v_{t:n}$ are fixed.

$$\text{Using Lemma from (b), } \hat{y}_t^* = E(y_t^* | Y_n) = E(y_t^* | Y_{t-1}, v_{t:n}) \\ = a_t = \sum_{j=t}^n \text{Cov}(y_t^*, v_j) F_j^{-1} v_j$$

where $F_j = \text{Var}(v_j, Y_{t-1})$

$$\text{Then, } \text{Cov}(y_t^*, v_j | Y_{t-1}) = E(y_t^* v_j' | Y_{t-1}) = E[y_t^* (x_j + \varepsilon_j)' | Y_{t-1}] \\ = E(y_t^* x_j' | Y_{t-1})$$

And,

$$E(y_t^* x_t' | Y_{t-1}) = E(y_t^* (y_t^* a_t)' | Y_{t-1}) = P_t$$

$$E(y_t^* x_{t+1}' | Y_{t-1}) = E[y_t^* (L_t x_t + \theta z_t - k_t \varepsilon_t)' | Y_{t-1}] = P_t L_t'$$

$$E(y_t^* x_{t+2}' | Y_{t-1}) = P_t L_t' L_{t+1}'$$

\vdots

$$E(y_t^* x_n' | Y_{t-1}) = P_t L_t' \dots L_{n-1}' = \text{Cov}(y_t^*, v_n | Y_{t-1})$$

Then, we can write $y_t^* = a_t + P_t r_{t-1}$

where $r_{n-1} = F_n^{-1} v_n$,

$$r_{t-1} = F_t^{-1} v_t + L_t F_{t+1}^{-1} v_{t+1} + \dots + L_t' L_{t+1}' \dots L_{n-1}' F_n^{-1} v_n$$

$\{r_t\}$ satisfies the backward recursion

$$r_{t-1} = F_t^{-1} v_t + L_t' r_t \quad \text{with } r_n = 0$$

Applying Lemma to the conditional joint distribution of y_t^* , $v_{t:n}$ given Y_{t-1} ,

$$V_t = \text{Var}(y_t^* | Y_{t-1}, v_{t:n}) = P_t - \sum_{j=2}^n \text{cov}(y_t^*, v_j | Y_{t-1}) F_j^{-1} \text{cov}(y_t^*, v_j | Y_{t-1})'$$

$$= P_t - P_t N_{t-1} P_t$$

$$\text{where } N_{t-1} = F_t^{-1} + L_t' F_{t+1}^{-1} L_t + \dots + L_t' L_{t+1}' \dots L_{n-1}' F_n^{-1} L_{n-1} \dots L_t$$

$\{N_t\}$ satisfies the recursion

$$N_{t-1} = F_t^{-1} + L_t' N_t L_t \quad \text{with } N_n = 0$$

In Summary,

$$r_{t-1} = F_t^{-1} v_t + L_t' r_t$$

$$N_{t-1} = F_t^{-1} + L_t' N_t L_t$$

$$\hat{y}_t^* = a_t + P_t r_{t-1}$$

$$V_t = P_t - P_t N_{t-1} P_t$$

$$\text{with } r_n = N_n = 0$$