



uOttawa

L'Université canadienne
Canada's university

CEG3136

Computer Architecture II

Software Development using C

Notes for
Dr. Voicu Groza

Université d'Ottawa | University of Ottawa



Topics of discussion

- Programming in C
 - Basics: Variables, Operators, Statements
 - Functions
 - Pointers and Structures
 - Standard Functions
- Creating Program Modules
- Extensions for Embedded Systems Software
- Reading: Chapter 10

A Simple C Program

- A C program contains
 - Comments enclosed in `/* */` characters
 - Preprocessor directives executed before compilation
 - A set of functions - processing starts with the *main()* function
 - C statements are executed within the functions and consist of:
 - Assignment statements
 - Arithmetic and logical expressions
 - Control statements
 - Calls to other functions

`/* Comments are enclosed as shown */`

`/*-----*/`

`FILE: simple.c`

`Description: simple program. Note
how comments can be
visual.`

`-----*/`

`#include <stdio.h> /* Preproc.directive */`

`void main(void)`

`{`

`/* Stmt is call to standard function */`

`printf("Hello world\n");`

`}`

Things you should know already

- Basic variable types: char, int, float, double
 - Variables must be declared
 - Variable name is associated to an address in memory
- Arrays – collection of variables
 - Indexing
 - In C array names represent the address
- C Operators: arithmetic, comparison, logic, assignment
- C Control Statements: decision, loop

C Functions

- A C program is a collection of functions
 - The function **main** is the first function executed
 - *type name(paramlist) { stmts }*
 - *type* defines type of value returned by function
 - *name* is the function name
 - *paramlist* provides a list of arguments to the function
 - *stmts* is a set of statements executed when the function is called
- On variables:
 - What is a local variable?
 - What is a global variable?

```
#include <stdio.h>
int sum(int, int); /* Prototype */
int gz;

void main(void)
{
    printf("sum of 2+3 = %d\n",
           sum(2,3));
}

int sum(int x, int y)
{
    int z;
    z=x+y;
    gz = z;
    return(z);
}
```

C Function Prototype

- The prototype provides specifications of functions
 - Used by compiler to check functions calls, including use of return value and argument types
 - Defined at start of program file or within headers
 - Example
 - `int sum(int, int);`
 - Note that parameter names are not required.
 - The following is also valid:
 - `int sum(int a, int b);`

```
#include <stdio.h>
int sum(int, int); /* Prototype */
int gz;

void main(void)
{
    printf("sum of 2+3 = %d\n",
           sum(2,3));
}

int sum(int x, int y)
{
    int z;
    z=x+y;
    gz = z;
    return(z);
}
```

C Pointer Variables

- A C pointer variable (a.k.a. pointer) contains an address
int c;
 - &c gives the address of variable c
 - “string” actually returns an address to the character array
- A pointer points to a type of value
 - Use * after *type* to declare pointer
char *strPtr;
 - **strPtr** is a variable that can contain an address to a *char* or *char* array
 - Array name gives address of first element
float realnums[10], *realPtr;
 - **realnums** can be used to reference address of first element
realPtr = realnums; //points to array
is equivalent to
realPtr = &realnums[0];

```
#include <stdio.h>
char str[20];

void main(void)
{
    char *pt;
    strcpy(str,"Hello world\n");
    pt = str;
    pt = &str[0];
    printf("%s",pt);
}
```

C Function Arguments – pass by reference

- For arrays, an address to the array is passed as function argument

```
int arr[10];
```

```
...
```

```
sumArray(arr);
```

- Consider a function to exchange the values of two integer variables

```
/* what is wrong with this function ? */
```

```
exchange(int x, int y)
```

```
{ ... }
```


C Variables – Structures (records)

- The C structure is a data type used to define complex data structures (e.g. linked list).

- Definition of a structure has the following format:

```
struct name
{
    Type memberName1;
    Type memberName2;
    Type memberName3;
    .
    .
} <list of variables>;
```

- The type definition of the structure (without list of variables) can be used as a type in variable declarations:

```
struct name variableName;
```

- Arrays of structure: ***struct name variableName[dimension];***

C Structure - Example

- Defining structure type

```
struct pers
{
    char name[30];
    char street[40];
    char city[20];
    char prov[4];
    long employee_num;
};
```

- Declaring variable

```
struct pers person1; /* memory allocated */
```

- Finding size of memory allocated to structure

```
sizeof(person1); /* gives amount of memory allocated
                  to person1 */
```

- Array of 10 structures: `struct pers persons[10];`

Using Structure Members

- The dot (.) operator is used to access structure members

- Referencing a structure member has the format

structureName.memberName

- Examples

```
person1.employee_num = 654321;
```

```
printf("%ld\n", person1.employee_num);
```

```
gets(person1.name);
```

```
for(i=0 ; person1.street[i]; i++)
```

```
    putchar(person1.street[i]);
```

```
persons[4].employee_num = 123456;
```

Pointers to structures

- When passing a structure to a function, the complete structure is placed on the stack

```
printRecord(person1);
```

- This can be time-consuming if the structure is large
- Does not allow the function to access (i.e. update) the original structure

- Using a pointer to a structure is normally used to have a function manipulate its contents

```
fillRecord(&person1); // call
```

- One single address is passed to the function, much more efficient
- Allows the function to update the addressed structure
- Replace the dot “.” operator with “->” operator when using a pointer to access structure members

```
fillRecord(struct pers *persPtr)
{ ...
    persPtr->employee_num = 123456;
```

Defining data types - typedef

- Can define new data types using “typedef”
 - `typedef “type expression” newTypeName`
- Examples:

```
typedef int size_t;  
typedef struct adr  
{  
    char name[30];  
    char street[40];  
    char city[20];  
    char prov[4];  
    long employee_num;  
} EmployeeRecord;  
EmployeeRecord employees[10];
```

C Standard Functions

- A C development system comes with standard libraries
 - System library provides functions for making UNIX system calls
 - Standard C library provides functions for manipulating strings, I/O (such as printf), math, time, etc.
 - Other libraries come with some applications, such as X Window.
- CodeWarrior does not support all standard C functions.
- For this course, standard functions are not required.

```
#include <stdio.h>
/*-----
time.h contains prototypes for
time() and ctime(), as well as the type
time_t
-----*/
#include <time.h>

void main(void)
{
    time_t tm;

    time(&tm); /* get system time */
    printf("Current time is %s\n",
           ctime(tm));
}
```

Compiling a C Program - Single Module

- For small programs, all functions are stored in the same file
- A C file represents a C module

```
#include <stdio.h>
void reverse(char *, char *); /* prototype*/
void main(void)
{
    char str[100];
    reverse("cat",str);
    printf("Reverse of cat is %s\n",str);
}
void reverse(char *bef, char *aft)
{
    int x,y,len;
    len = strlen(bef);
    for(x=0; y=len-1; y>x ; x++, y- -)
        aft[x] = bef[y];
    aft[len] = '\0';
}
```

C Preprocessor

- Before compilation, the C preprocessor translates its directives

- ☐ #include <file> -
 - inserts file contents
- ☐ #define NAME value
 - defines constant NAME
 - all occurrences of NAME are replaced with value.
- ☐ Other directives are also available

```
#include <stdio.h>
#define NUM1 10
#define STRING1 "Hello world"

void main(void)
{
    int x;
    float y;
    for(x=1 ; x<NUM1 ; x++)
    {
        y = y*x;
        printf("x: %d x!: %f\n",x,y);
    }
    printf("%s\n",STRING1);
}
```


Compiling a C Program - Multiple Modules

- For larger or modular programs, separate code among many files
 - Certain functions can be made available to many programs
 - Files are compiled separately (e.g. “cc -c prog.c”) - creates object file “prog.o”
 - Object files can then be linked to create final executable (e.g. “cc -o *execFile* *objectFiles*”)
- Use of *static*
 - Local variable becomes permanent
 - Global variable is local to the file module
- For example, create the following files:
 - reverse.h - with prototype of reverse function
 - main.c - main function (contains #include “reverse.h”)
 - reverse.c - reverse function
- To create application, use
 - cc -c main.c
 - cc -c reverse.c
 - cc -o rev main.o reverse.o

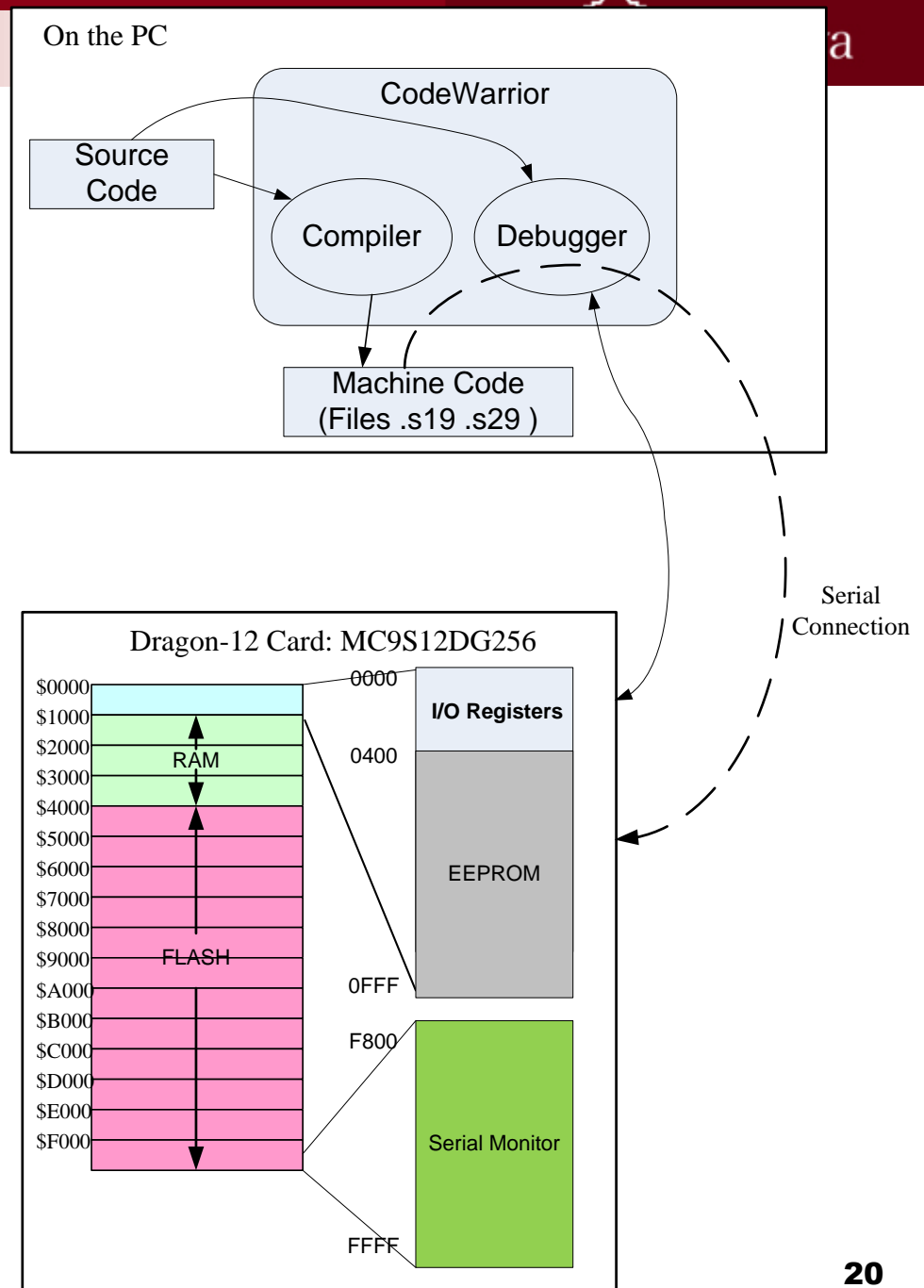
Using C for Developing Embedded Software

- Offers a high level language to develop software for embedded systems
- Must keep in mind a number of additional issues
 - Program is to be loaded into regions of memory: code in ROM, variables in RAM
 - Need to use assembly language subroutines to effectively manipulate hardware.
 - Also use inline assembly instructions
 - Require extensions to C for implementing Interrupt Service Routines (to service hardware interrupts)
- Shall use FreeScale CodeWarrior C Compiler

Architecture of a C Program

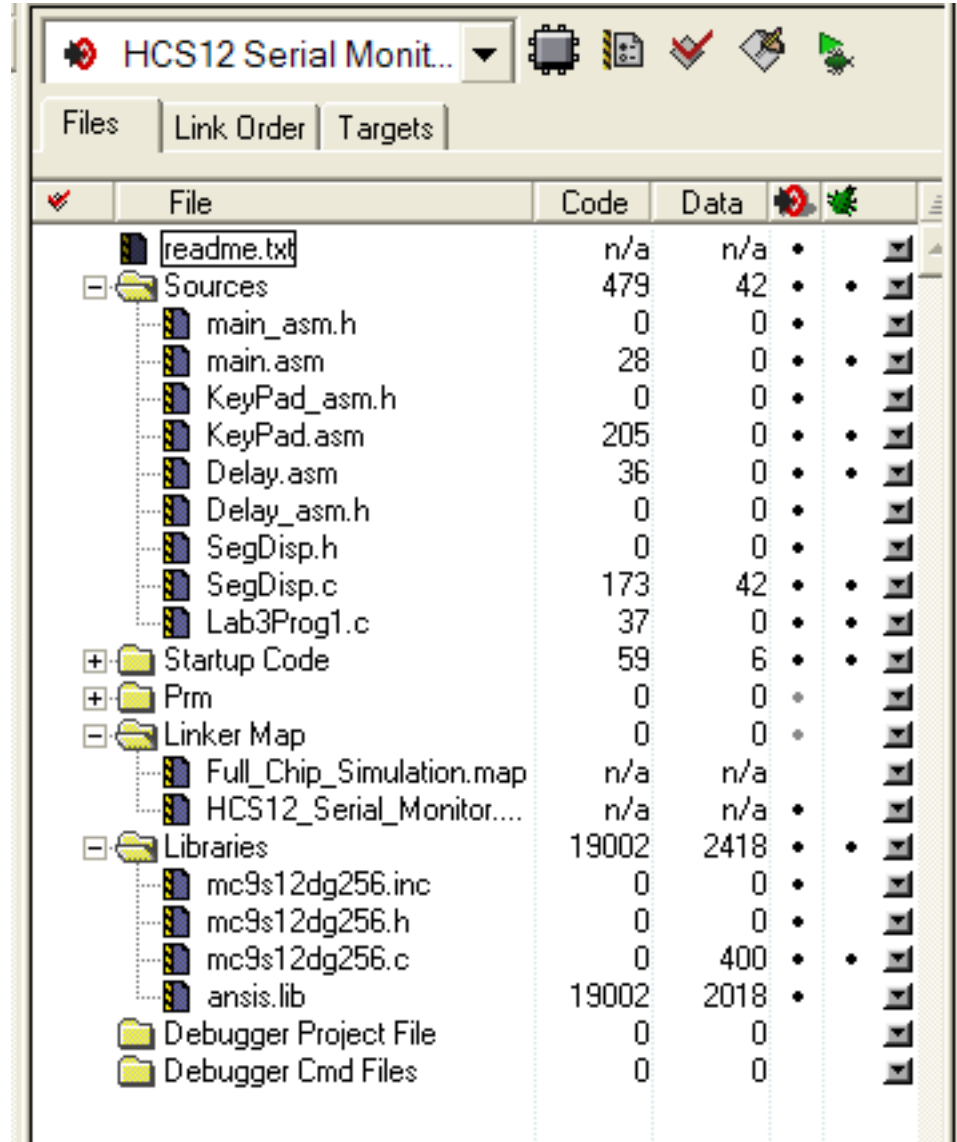
- Startup Code
 - ☐ Hardware initialization
 - ☐ Data initialization
 - ☐ Stack pointer
 - ☐ Call main
- `void main(void)`
 - ☐ The start of developed software
- Automatic variables
 - ☐ Local variables on the **stack**
- Static variables
 - ☐ Global variables
 - ☐ Static local variables
- Volatile variables
 - ☐ Variables that are updated from hardware registers
 - ☐ Prevent compiler optimization from removing duplicate instructions

Development Environment



Development Environment

- Use the course sample project
 - Available on Virtual Campus (Labs/lab3 module)
 - Install in C:\Program Files\Freescale\CodeWarrior for S12(X) V5.0\CodeWarrior_Examples



File	Code	Data		
readme.txt	n/a	n/a	•	
Sources	479	42	•	•
main_asm.h	0	0	•	
main.asm	28	0	•	•
KeyPad_asm.h	0	0	•	
KeyPad.asm	205	0	•	•
Delay.asm	36	0	•	•
Delay_asm.h	0	0	•	
SegDisp.h	0	0	•	
SegDisp.c	173	42	•	•
Lab3Prog1.c	37	0	•	•
Startup Code	59	6	•	•
Prm	0	0	•	
Linker Map	0	0	•	
Full_Chip_Simulation.map	n/a	n/a		
HCS12_Serial_Monitor...	n/a	n/a	•	
Libraries	19002	2418	•	•
mc9s12dg256.inc	0	0	•	
mc9s12dg256.h	0	0	•	
mc9s12dg256.c	0	400	•	•
ansis.lib	19002	2018	•	
Debugger Project File	0	0		
Debugger Cmd Files	0	0		

Volatile Variables

Source code

```
typedef unsigned char BYTE;
BYTE PORTA;
void main(void)
{
    volatile static BYTE a_val;
        static BYTE b_val;
    /* Read from port A */
    a_Val = PORTA;

    a_Val = PORTA;

    /* */
    b_val = PORTA;
    b_val = PORTA;

}
```

listing showing compiled code

```
.
.
.
.
11: a_val = PORTA;
0000 f60000    LDAB PORTA
0003 7b0000    STAB a_Val

12: a_val = PORTA;
0006 f60000    LDAB PORTA
0009 7b0000    STAB a_Val

14: b_val = PORTA;
15: b_val = PORTA;
000c f60000    LDAB PORTA
000f 7b0000    STAB b_Val

rts
```

Assembly Language Interface

- Should understand how the compiler works
 - E.g. see previous slides
 - E.g. see next slide on initialization of automatic and static variables
- Often parts of a C program are replaced with assembler instructions/subroutines
 - To reduce size of program
 - Use profiling to identify bottlenecks and replace with faster assembly code
 - Need to understand calling conventions

Overhead for Initializing Variables

```
/******  
void main(void) {  
    static char a_Val[] =  
        {2,90,53, 8 };  
    char b_Val[] =  
        {0,7,255, 34};
```

```
    char c_Val[4], i;  
    i=2;  
    c_Val[i] = a_Val[i]+  
                b_Val[i];
```

```
}
```

```
.  
.  
.  
9: char b_Val[] = {0,7,255,34}  
0000 69a8 CLR 8,-SP  
0002 c607 LDAB #7  
0004 6b81 STAB 1,SP  
0006 86ff LDAA #255  
0008 6a82 STAA 2,SP  
000a c622 LDAB #34  
00Cc 6b83. STAB 3,SP  
  
.  
  
12: i = 2;  
13: c_Val[i] = a_Val[i]+b_Val[i]  
000e f60000 LDAB a_Val:2  
0011 eb82 ADDB 2,SP  
0013 6b86 STAB 6,SP  
  
.  
0015 1b88 LEAS 8,SP  
0017 3d RTS
```


Calling Convention

- Fixed number of arguments (Pascal convention)
 - Arguments (values) are pushed onto the stack in order (from left to right). The last argument is passed in a register if possible (see below).
- Variable number of arguments (C convention)
 - Arguments (values) are pushed onto the stack in reverse order (from right to left). The last argument is passed in a register if possible (see below).
- When the argument value to be passed via a register is ≤ 4 bytes, it is passed as follows:
 - 1 byte, in B 2 bytes, in D
 - 3 bytes, in X (LW) B(HB) 4 bytes, in D(LW), X(HW)
- When the argument value to be passed in a register is larger than 4 bytes, it is pushed onto the stack
- All values pushed onto the stack are pulled from the stack after the function/subprogram returns

Calling Convention (cont'd)

- The return value are passed back using registers when they are ≤ 4 bytes
 - 1 byte, in B 2 bytes, in D
 - 3 bytes, in X (LW) B(HB) 4 bytes, in D(LW), X(HW)
- When return values are larger than 4 bytes, an address is added to the argument list, and the return value copied to that address

Calling Convention - Example

```
/******  
* Test showing the Pascal  
* calling convention used by  
* CodeWarrior.  
*****/
```

```
int function1(char arg1,  
              int arg2,  
              float arg3);  
int function2(char arg1);  
void main (void) {  
    static char stacy;  
    static int sam, mike;  
    static float susan;  
    mike = function1(stacy, sam,  
                    susan);
```

```
    sam = function2(stacy);
```

```
}
```

```
13: mike = function1(stacy..  
    0000 f60000 LDAB stacy  
    0003 37      PSHB  
    0004 fc0000 LDD sam  
    0007 3d      PSHD  
    0008 fc0000 LDD susan:2  
    000b fe0000 LDX susan  
    000e 160000 JSR function1  
    0011 1b83 LEAS 3,SP  
    0013 7c0000 STD mike  
14: sam = function2(stacy);  
    00:6 160000 LDAB stacy  
    0019 160000 JSR function2  
    0010 7c0000 STD sam  
.  
    0011 3d RTS
```

C Prototypes for Assembler Routines

```
/*-----  
File: KeyPad_asm.h  
Description:  Header file to use the KeyPad Module  
-----*/  
#ifndef _KEYPAD_ASM_H  
#define _KEYPAD_ASM_H  
  
//C Prototypes to assembler subroutines  
void initKeyPad(void);  
byte pollReadKey(void);  
byte readKey(void);  
  
// Some Definitions  
#define NOKEY 0 // See KeyPad.asm  
  
#endif /* _KEYPAD_ASM_H */
```

External Symbols in Assembler Source

```
; File: Keypad.asm
```

```
; External Symbols Referenced
```

```
XREF delays
```

```
; Define External Symbols
```

```
XDEF initKey, pollReadKey, readKey
```

Inline Assembler Instructions

- It is possible to add assembler instructions within C code.
- Careful (see example),
 - C instructions in between assembler instructions can change register contents
 - Assembler instructions can inconvenience C instructions
- With CodeWarrior, assembler instructions can be inserted in place of C instructions
 - Many forms of inline assembly instructions are available – see example

Careful – Register Changes with Inline Assembler Instructions

```
int a_val;
void main(void){
    int fred;
    fred = 1;

    asm {
        ldd #5555
        std a_Val
    }
    fred = 2;

    for(;;) {


```

```
.
.
.
10: fred = 1;
    0000 c601    LDAB #1
    0002 87     CLRA
    0003 3b     PSHD
.
12:  asm {
    0004 cc15b3 LDD #5555
    0007 7c0000 STD a_Val
15: }
16:  fred = 2;
    000a 58     ASLB
    000b 6c80    STD 0,SP

    000d
```

Examples of Inline Assembler Instructions

```
void main(void) {
    static char static_var;
    char auto_var;
    /*In-line Asm. Inst.*/
    asm nop;
    asm ldaa #55;
    /*Block of Asm. Inst.*/
    asm {
        nop    /*Comment*/
        staa static_var;
        staa auto_var;
    }
```

```
/* Mult. Inst. On a line*/
asm nop; asm nop;
asm (nop; /*comment*/);

/*Block of Asm Inst*/
#asm
    nop
    bset static_var, 0x01
    bclr auto_var, 0x02
#endasm
```


Accessing I/O Registers

- As we shall see, manipulating hardware registers requires accessing them at specific locations and requires bit manipulation
- Addressing Registers
 - CodeWarrior provides the **global address modifier @**, to tie variable names to specific addresses
 - Otherwise pointer manipulation is required
- Manipulating Bits
 - C Structures can be defined to assign member names to specific bits
 - CodeWarrior documentation does NOT recommend this approach, but use bitwise operators **&** and **|**
 - CodeWarrior recognizes binary values, e.g. 0b01001000

Options for Associating Variables to Hardware Registers

```

/*****
/*  Define a PORT type = unsigned char  */
typedef unsigned char PORT;
/*****
/*Declare PORTA to be volatile unsigned char at addr 0x0000 */
volatile PORT PORTA @0x0000;
/*****
/*Declare PORTB to be the contents of a memory location
    pointed to by a volatile unsigned char pointer 0x0001 */
#define PORTB (*(volatile PORT *) 0x0001)
/*****
void main(void) {
    unsigned char p_a_val;
    PORTA = 6;          /* Write to PORT A */
    p_a_val = PORTA;    /* Read from PORT A */
    PORTB = 26;         /* Write to PORT B */
}

```

Structures with Bitfields

```
/* Define a bitfield type as unsigned int */
typedef unsigned int BITFIELD;
/*****/
/* Declare an eight-bit field for the PORTB which is
   volatile at address 0x0001 */
struct {
    BITFIELD BIT0 : 1;
    BITFIELD BIT1 : 1;
    .
    .
    BITFIELD BIT7 : 1;
} volatile PORTB @0x0001;
/*****/
void main(void) {
    /* translates to bit-set and bit-clr asm instr */
    PORTB.BIT0 = 1;
    PORTB.BIT0 = 0;
    PORTB.BIT1 = 1;
    PORTB.BIT1 = 0;
}
```

Not Recommended

Combining Register and Bit Addressing

```
/****** Types *****/
typedef unsigned char PORT;
typedef unsigned int BITFIELD;
/***** Union that gives two perspectives ****/
typedef union {
    PORT PortByte;
    struct {
        BITFIELD BIT0 : 1;
        BITFIELD BIT1 : 1;
        .
        .
        BITFIELD BIT7 : 1;
    } PortBits;
} IOPort;
/* Data and Data direction registers for Port T */
volatile IOPort PORTT @0x0240
volatile IOPort DDRT @0x0242
/******/
void main(void) {
    DDRT.PortByte = 0x0F; /* Bits 3 - 0 , output */
    PORTT.PortBits.Bit3 = 1; /* make Bit 3 = 1 */
}
```

Interrupts – an Introduction

- An interrupt is a hardware generated signal that request some service
 - Efficient way of dealing with hardware
 - Basis for operating systems
- The interrupt service routine (ISR)
 - A routine (i.e. function/sub-routine) executed to service an interrupt
 - Terminated with RTI, and not RTS
 - The CPU maintains a vector of addresses to these routines to associate them to the specific interrupts

Servicing an Interrupt

- CodeWarrior provides the « interrupt » qualifier to declare functions that service interrupts
 - Include the « interrupt » keyword in the function definition.
 - Can also add the interrupt vector number to associate the function to a specific interrupt
 - More on this in module 8

Example of an ISR C Function in CodeWarrior

```
/* LED connected to bit 0 of Port A */
/* Interrupts received on IRQ pin */
#define BIT0 0b00000001
void main(void) {
    DDRA = DDRA | BIT0; /*Output*/
    PORTA = PORTA & ~BIT0; /*Turn off LED*/
    INCR = INCR | BIT0; /*Activate IRQ */
    asm cli; /* allow interrupts*/
    for(;;) ; /* infinite loop */
}
/*****ISR*****/
/* Vector # 6 can be replaced with VectorNumber_Virq
   see mc9s12dg256.h */
void interrupt 6 irq_handler(void) {
    if(PORTA & 1) /* is lit? */
        PORTA |= BIT0; /* turn off */
    else
        PORTA &= ~BIT0; /* turn on */
}
```