

Maximum Flow

Ch 26 CLRS

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CS566 Project

Flow networks - overview

- Flow networks model the movement of a material from a source **s**, to a sink **t**
- Each edge in the network has a total **capacity** at which material can move
- As well as a current **flow** rate at which the material is moving
- Material is not allowed to accumulate at any of the vertices
 - **Flow conservation** - the rate at which the material enters the vertex should be the rate at which it leaves the vertex
- The goal of maximum flow problems is to determine the largest amount of material we can move through the network while abiding network capacity

Flow networks - requirements

- For a flow network $G = (V, E)$
 - Directed graph
 - With capacity function c
 - Each edge $c(u, v) \in E$ has a nonnegative capacity $c(u, v) \geq 0$
 - No reverse edges
 - If E has an edge (u, v) , there is no edge (v, u)
 - If $(u, v) \notin E$ then $c(u, v) = 0$
 - No self loops

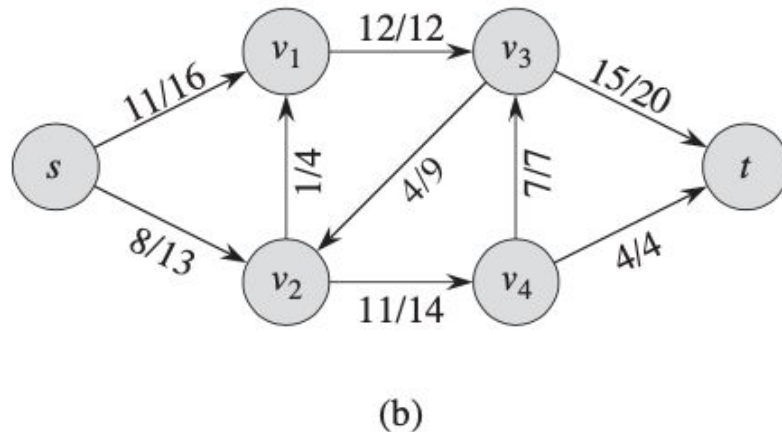
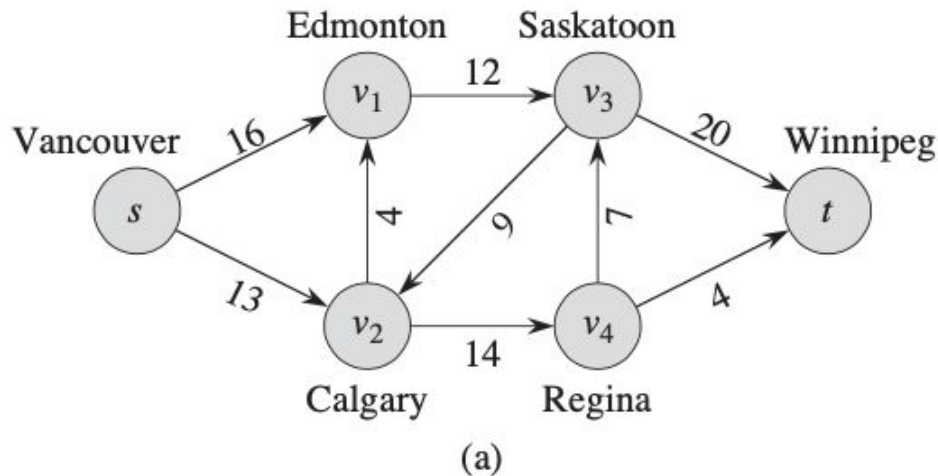
Flow networks - requirements

- For a flow network $G = (V, E)$
 - For each vertex $v \in V$ the flow network should have a path $s \rightsquigarrow v \rightsquigarrow t$
 - Each vertex, other than s has one entering edge
 - Therefore $|E| \geq |V| - 1$
- A flow in G is a real-valued function $f: V \times V \rightarrow \mathbb{R}$
 - **Capacity constraint:** For all $u, v \in V$, we require $0 \leq f(u, v) \leq c(u, v)$
 - **Flow conservation:** For all $u \in V - \{s, t\}$, we require

$$\sum_{v \in V} f(v, u) = \sum_{v \in V} f(u, v).$$

When $(u, v) \notin E$, there can be no flow from u to v , and $f(u, v) = 0$.

Flow networks



- The nonnegative quantity of function $f(u, v)$, is a value $|f|$ of a flow f

$$|f| = \sum_{v \in V} f(s, v) - \sum_{v \in V} f(v, s),$$

- In above e.g. flow f in G with value $|f| = 19$
- Flow out of source should be 0, except when using residuals

Residual networks

- For a flow network G and a flow f , the residual network G_f is a graph where edges are the remaining flow before exceeding capacity
- An edge has a residual capacity if
 - $c_f(u, v) = c(u, v) - f(u, v)$
- Only edges that can admit more flow are in G_f
 - Edges where the flow equals capacity are not in G_f and have $c_f(u, v) = 0$
- Residual G_f network may have edges that are not in G
 - To increase the total flow, may have to decrease flow on an edge
 - $c_f(v, u) = f(u, v)$

Augmenting paths

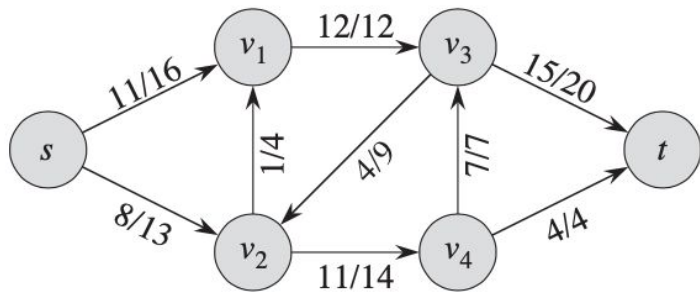
- For a flow network $G = (V, E)$ and a flow f
 - We can **increase** the **flow** on (u, v) by $f'(u, v)$ but **decrease** it by $f'(v, u)$
 - This is equivalent to decreasing flow, also called **cancellation**, by pushing flow in the reverse edge of the residual network

we define $f \uparrow f'$, the **augmentation** of flow f by f' ,

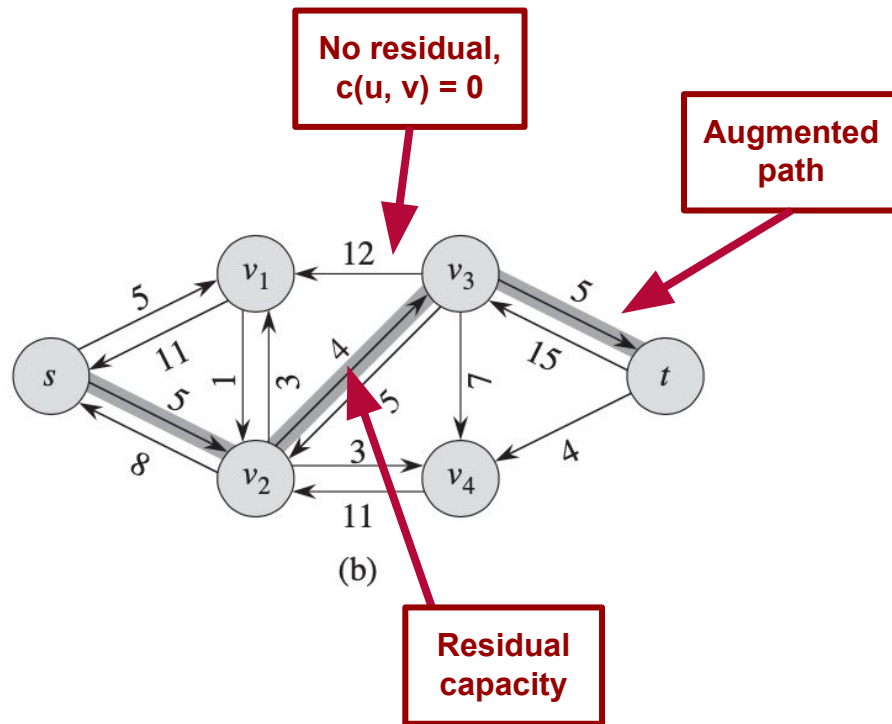
$$(f \uparrow f')(u, v) = \begin{cases} f(u, v) + f'(u, v) - f'(v, u) & \text{if } (u, v) \in E, \\ 0 & \text{otherwise.} \end{cases}$$

- The **residual capacity** of augmenting path p is the maximum amount by which we can increase the flow on **each edge**

Residual networks with augmented paths



(a)



(b)

Cuts

- As a part of the max-flow min-cut theorem, a flow is only at maximum when its residual network no longer has augmenting paths
 - s must be a part of set S , $s \in S$
 - t must be a part of set T , $t \in T$
- For flow f , the **net flow** $f(S, T)$ across cut (S, T)
 - We consider the flow going from S to T minus the flow from T to S

$$f(S, T) = \sum_{u \in S} \sum_{v \in T} f(u, v) - \sum_{u \in S} \sum_{v \in T} f(v, u) .$$

Cuts

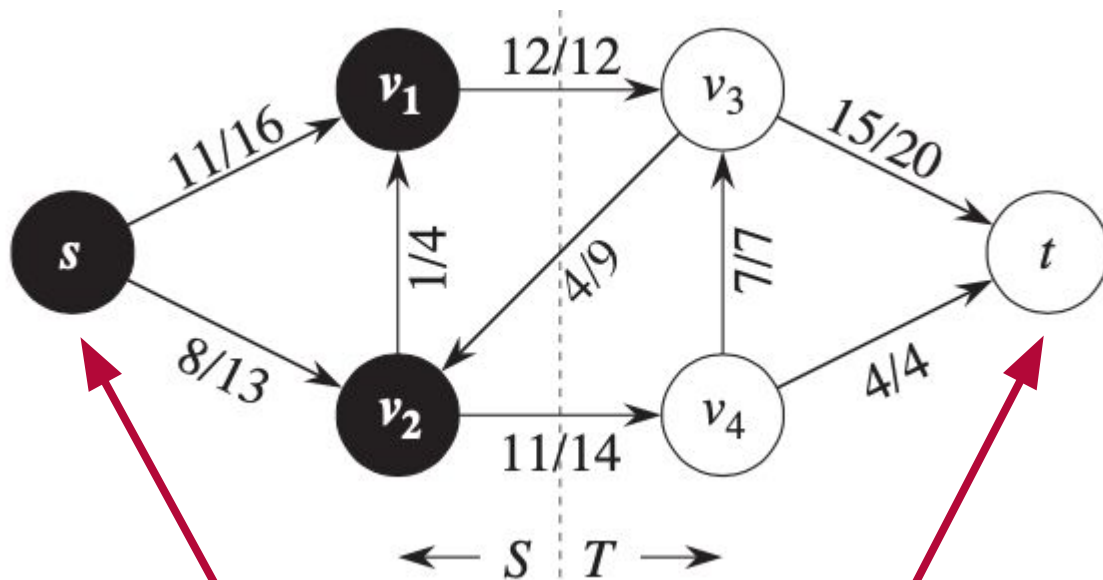
- The **capacity** of the cut (S, T)
 - We consider only flow going from S to T , not from T to S

$$c(S, T) = \sum_{u \in S} \sum_{v \in T} c(u, v) .$$

- A **minimum cut** of a network is a cut where the capacity is minimum over all the cut options in the network

Minimum cut

Net flow $f(S, T) = 19$
Capacity $c(S, T) = 26$



s and t in separate partitions

Min-cut max-flow theorem

If f is a flow in a flow network $G = (V, E)$ with source s and sink t , then the following conditions are equivalent:

1. f is a maximum flow in G .
2. The residual network G_f contains no augmenting paths.
3. $|f| = c(S, T)$ for some cut (S, T) of G .

Proof (1) \Rightarrow (2)

Proof (2) \Rightarrow (3)

Proof (3) \Rightarrow (1)

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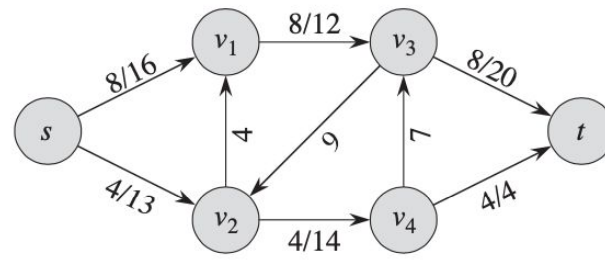
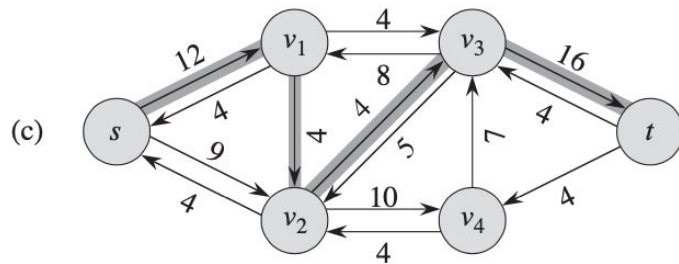
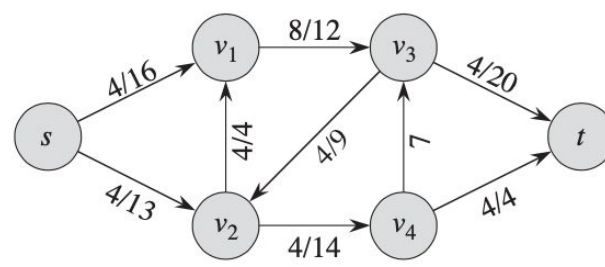
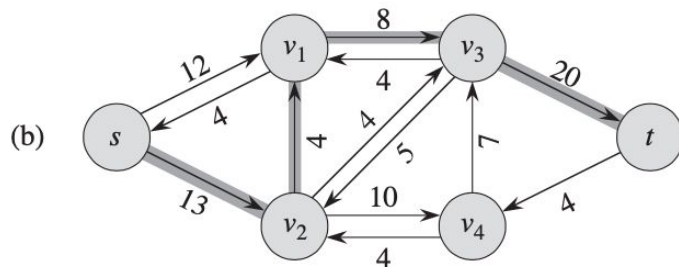
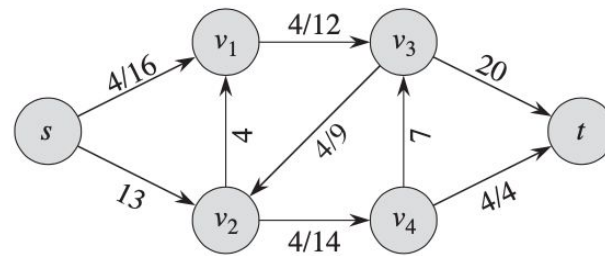
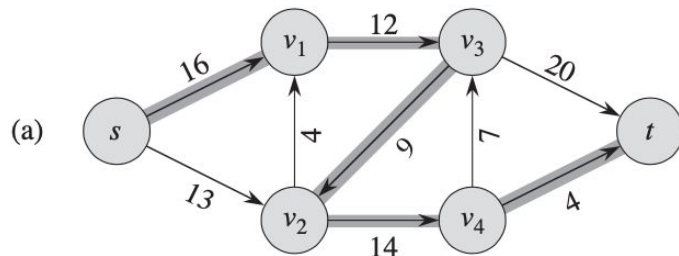
Ford-Fulkerson algorithm

- We find some augmenting path p
 - Use p to modify the flow f
 - By replacing f by $f \uparrow f_p$, we get a new flow of $|f| + |f_p|$
- Running time is $O(E)$

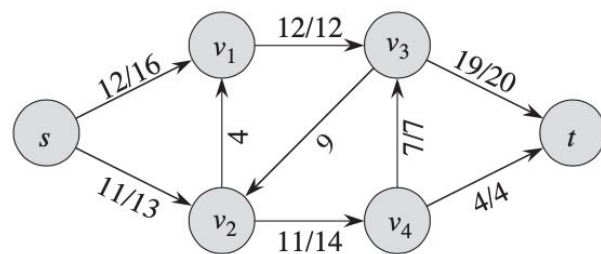
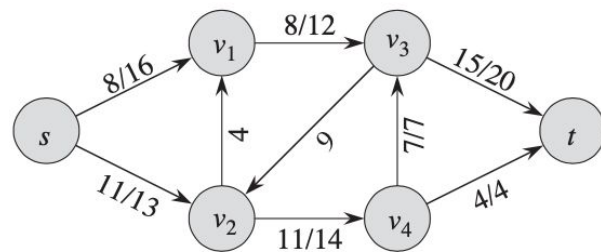
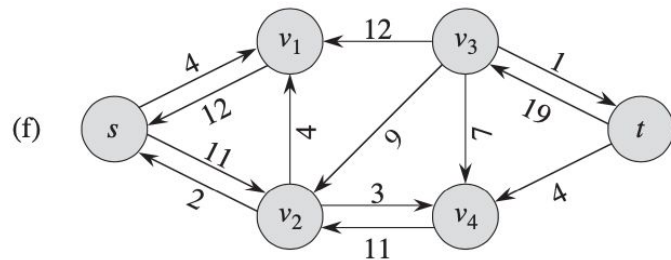
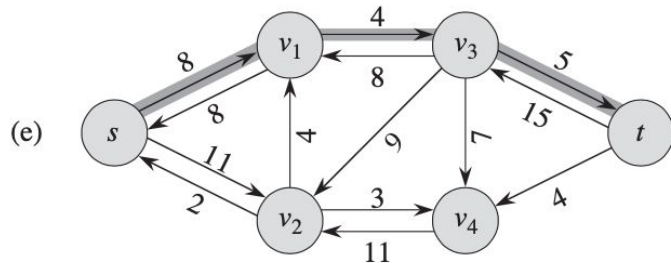
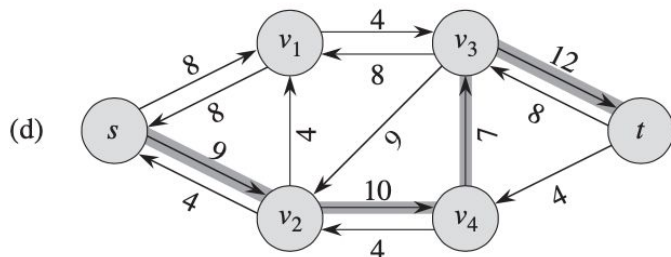
FORD-FULKERSON(G, s, t)

```
1  for each edge  $(u, v) \in G.E$ 
2       $(u, v).f = 0$ 
3  while there exists a path  $p$  from  $s$  to  $t$  in the residual network  $G_f$ 
4       $c_f(p) = \min \{c_f(u, v) : (u, v) \text{ is in } p\}$ 
5      for each edge  $(u, v)$  in  $p$ 
6          if  $(u, v) \in E$ 
7               $(u, v).f = (u, v).f + c_f(p)$ 
8          else  $(v, u).f = (v, u).f - c_f(p)$ 
```

Ford-Fulkerson algorithm



Ford-Fulkerson algorithm



Edmonds-Karp algorithm

- Developed due to high running time on Ford-Fulkerson with large edge weights
- Improves bound by finding augmenting paths using breadth-first search
 - Augmenting path is shortest path from s to t in residual network
- Running time is $O(VE^2)$

References

Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, and Clifford Stein. 2009. Introduction to Algorithms, Third Edition (3rd. ed.). The MIT Press.

Chapter 26. Maximum Flow pgs 708 - 730

Erik Demaine, Srinivas Devadas, and Nancy Lynch. 6.046J Design and Analysis of Algorithms. Spring 2015. Massachusetts Institute of Technology: MIT OpenCourseWare, <https://ocw.mit.edu>. License: Creative Commons BY-NC-SA.

[Lecture 13. Incremental Improvement: Max Flow, Min Cut](#)

[Lecture 14. Incremental Improvement: Matching](#)

Back To Back SWE. [Network Flows: Max-Flow Min-Cut Theorem \(& Ford-Fulkerson Algorithm\)](#). Oct 2019. Youtube.