

IT 3708: Project 4

Solving Job Shop Scheduling Problem (JSSP) Using Bio-Inspired Algorithms

Lab Goals

- Implement three recent bio-inspired algorithms (to solve job shop scheduling problem (JSSP)).
- Compare the performance of your implemented algorithms on several benchmark problems.

Groups Allowed? Yes. For this project you may work alone or in groups of two.

Deadline: May 04, 2017 (Thursday) at 07: 59 AM.

Assignment Details

The objective of scheduling is to efficiently allocate shared resources (machines, people etc) over time to competing activities (jobs, tasks, etc.) such that a certain number of goals can be economically achieved and the given constraints can be satisfied. The solutions that satisfy these constraints are called feasible schedule. In general, the construction of a schedule is an optimization problem of arranging time, space, and (often limited) resources simultaneously. Hence, if scheduling is regarded as a search problem, it is desirable to search for any feasible schedule, and if it is an optimization problem, it is preferred to search for the best feasible schedule. In this paper, we focus on solving the JSSP since it is widely found in the industry and it is considered as a representation of many general scheduling problems in practice.

Among various types of scheduling problems, the shop scheduling is one of the most challenging scheduling problems. It can be classified into four main categories: (i) single-machine scheduling, (ii) flow-shop scheduling, (iii) job-shop scheduling, and (iv) open-shop scheduling. Among these, the Job-Shop Scheduling Problem (JSSP) perhaps receives the most attention from the evolutionary community by a plethora of different approaches. The JSSP is a hard-combinatorial optimization problem, which is not only *NP*-hard but also one of the worst members in that class.

A job-shop scheduling involves processing of the jobs on several machines without any ‘series’ routing structure. The $n \times m$ JSSP can be described by a set of n jobs $\{J_j\}_{1 \leq j \leq n}$ which is to be processed on a set of m machines $\{M_k\}_{1 \leq k \leq m}$. Each job has a technological sequence of machines to be processed. The processing of job J_j on machine M_k is called the operation O_{jk} . Operation O_{jk} requires an exclusive use of machine M_k for an uninterrupted duration t_{jk} , its processing time. A schedule is a set of completion times for each operation $\{C_{jk}\}_{1 \leq j \leq n, 1 \leq k \leq m}$ that satisfies given constraints. The challenge here is to determine the optimum sequence in which the jobs should be processed to optimize one or more performance measure, such as the makespan (the maximum completion time of all jobs), the mean flow time or the total tardiness of jobs, etc. In short, the JSSP can be characterized as follows:

- each job $j \in J$ must be processed by every machine $k \in M$;

- operation O_{jk} requires the exclusive use of machine M_k for an uninterrupted duration t_{jk} ;
- each job consists of an operating sequence of x_j operations (technological sequence of each job);
- O_{jk} can be processed by only one machine k at a time;
- each operation, which has started, runs to completion;
- each machine performs operations one after another;

Table 1 shows an example of 6x6 job-shop scheduling benchmark problem. In this example, the Job-1 is processed by Machine-3 for 1 time unit, and it is also processed by Machine-1 for 3 time units, and so forth.

Table 5.1: A 6x6 job-shop scheduling benchmark problem

Job- n	(k,t)	(k,t)	(k,t)	(k,t)	(k,t)	(k,t)
Job-1	3,1	1,3	2,6	4,7	6,3	5,6
Job-2	2,8	3,5	5,10	6,10	1,10	4,4
Job-3	3,5	4,4	6,8	1,9	2,1	5,7
Job-4	2,5	1,5	3,5	4,3	5,8	6,9
Job-5	3,9	2,3	5,5	6,4	1,3	4,1
Job-6	2,3	4,3	6,9	1,10	5,4	3,1

The typical output of JSSP is a Gantt-Chart presenting the **schedule** (allocation of shared resources over time to competing activities) optimizing one or several objectives. Fig. 1 presents an optimal schedule of the JSSP (Table 1) based on the minimum *makespan* objective.

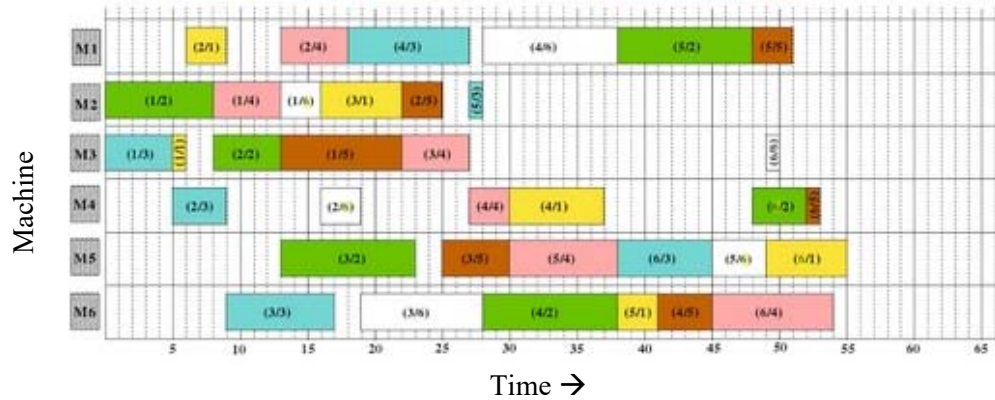


Fig. 1: Gantt-Chart of the optimal schedule with makespan objective.

In this project, you will implement **three bio-inspired algorithms to solve the JSSP by optimizing makespan**. The algorithms are:

1. Particle Swarm Optimization (PSO),
2. Ant Colony Optimization (ACO), and
3. Bees Algorithm (BA).

Problem Formulation:

Solution (individual/chromosome) representation is a key issue in designing efficient bio-inspired algorithms for JSSPs because different methods for representing parameters (genes) in scheduling solutions create different search spaces and different difficulties for variation/algorithmic operators. For several representation alternatives, you can look at [1]. The individual representation can be classified into two major approaches: (i) direct representation, and (ii) indirect representation. In indirect representation, the individual encodes a sequence of preferences. These decision preferences can be heuristic rules or simple ordering of jobs in a machine. After that a *schedule builder* is required to decode the chromosome into a schedule. In a direct representation, the schedule itself is directly encoded onto the individual/solution/chromosome and thereby eliminating the need for a complex schedule builder. At the same time, applying simple variation/algorithmic operators on direct representation string often results in infeasible schedule solutions. For this reason, domain-specific variation/algorithmic operators are required.

As mentioned earlier, in indirect representation, the individual/solution/chromosome contains an encoded schedule and a scheduler builder is used to transform the individual/solution/chromosome into a feasible schedule. The schedule builder is a module of the evaluation procedure and should be chosen with respect to the performance-measure of optimization. It is well-established that the minimization of *makespan* plays the major role in converting the chromosomes into feasible schedule, and the computational experiments show that genetic minimum-makespan in JSSP improves using a powerful schedule-builder. There are several schedule-builder algorithms exist in literature. For example, one of the efficient approaches to generate an effective schedule builder is the Giffler & Thompson algorithm [1, 2]. You are free to choose your own schedule builder, off-course if you use indirect representation. Even, you can design our own schedule-builder.

In this project, you need to optimize makespan for the JSSP.

- (i) Makespan is the maximum completion time among all jobs. It is subject to minimization and can be defined as:

$$f_1 = \max_{j=1}^n C_j, \text{ where } C_j \text{ is the completion time of job } j.$$

Things To Do

The 30 points total for this project is 30 of the 100 points available for this course. The 30 points will be distributed on two parts: (i) demo and (ii) report. **The demo can give you a maximum of 27 points and the report can give you a maximum of 03 points.**

To test your code, we uploaded 06 benchmark JSSP instances with acceptable values. The description of input files is also included in the test data.

Along with presenting the optimal values for makespan, you need to plot the Gantt-Chart targeting makespan (as in Fig. 1).

(a) Demo (27p):

There will be a demo session where you will show us the running code and we will verify that it works. If you work in a group, **both group members need to attend the demo session together.**

In the demo session, you need to describe how you designed and implemented your algorithms. Also, you need to test your code by solving 02 (two) JSSP instances which will be supplied during the demo.

Note that, **you must run your code and show us all the requirements within 30 (thirty) minutes.** The point distribution for the demo is as follows:

- (1) For each of the three algorithms, you need to run 02 (two) JSSP instances. Each algorithm implementation can give you a maximum of 09 points. (27p = 9 x 3)
 - For each algorithm, each JSSP instance can give you a maximum of 4.5 Points. (9p = 4.5 x 2)
 - If your value is within 10% of acceptable value, you will get full points.
 - If your value is within 20% of acceptable value, you will get 3 points.
 - If your value is within 30% of acceptable value, you will get 2 points.
 - Otherwise, you will get 0.
 - Show the Gantt-Chart targeting the best makespan. (0.5p)

(b) Report (03p):

You should write a report answering the points below. Your report must not exceed 04 (Four) pages in total. **Over length reports will result in points being deducted from your final score.** Print on both sides of the sheet, preferably. **Bring a hard copy of your report to the demo session.** If you work in a group, you only need to submit one single report on behalf of the group.

1. Representation of solutions (individual/chromosome) for each of the three algorithms representation **Using figure(s) for solution is a must.** For each of the three algorithms, how does you build the schedule from respective solution? (1.5p)
2. For the test problem-3, draw the Gantt-Chart targeting the best makespan. You need to draw for all three algorithms. (1.5p)

Delivery

You should deliver your report + a zip file of your code on *itslearning*. The submission system will be closed at 07:59 AM on May 04, 2017.

If you work in a group, you only need to deliver once on *itslearning* (but both group members must be registered as part of the submission on *itslearning*!). **Both group members need to attend the demo session.**

You must attend the demo on the scheduled demo date which has been declared on *itslearning*. Since the demo dates were declared at the beginning of the semester, **no early or late demo will be entertained**

except for extreme emergency like sickness with medical certificate, job interview, attending funeral or the like. Traveling or holidays will not be considered as emergency situation.

References:

- [1] R. Cheng, M. Gen, and Y. Tsujimura, “A tutorial survey of job-shop scheduling problems using genetic algorithms – I: Representation”, *Computers and Industrial Engineering*, 1996, vol. 30, no. 4, pp. 983-997.
- [2] B. Giffler, G. Thompson, “Algorithms for solving production scheduling problems,” *Operations Research*, vol. 8, no 4, 1960, pp. 487-503.
- [2] R. Varela, D. Serrano, and M. Sierra, “New codification schemas for scheduling with genetic algorithms,” in: J. Mira, J. R. Álvarez, Ed., *Lecture Notes in Computer Sciences*, vol. 3562, Springer, 2005, pp. 11–20.