

hw07_report_106062202

1. How I developed my finite state machine: (X stands for impossible situation)

a. Move: Forward, next move:

Previous / Now	Wall at left	Wall at right	Wall ahead	No walls
Wall at left	Forward	X	Turn right	Turn left
Wall at right	X	Forward	X	Turn right
Wall ahead	X	X	X	X
No walls	Forward	Turn right	Turn right	Turn right

b. Move: Left, next move:

Previous / Now	Wall at left	Wall at right	Wall ahead	No walls
Wall at left	X	X	Turn right	X
Wall at right	Forward	X	X	Turn left
Wall ahead	Turn right	Turn right	Turn right	X
No walls	Forward	X	X	forward

c. Move: Right, next move:

Previous / Now	Wall at left	Wall at right	Wall ahead	No walls
Wall at left	X	Turn left	X	Turn left
Wall at right	X	X	Turn right	X
Wall ahead	Forward	X	Turn right	X
No walls	X	Turn left	X	forward

d. Move: Halt, next move:

Now	Wall at left	Wall at right	Wall ahead	No walls
Next move	Forward	Turn right	Turn right	Forward

2. Results:

a. my maze:

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Initial position: ( 1, 1)
Initial direction: West
Maze Exit: ( 7, 9)

Maze Universe:
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88888888888888888888
8W          8
8           8
88888888888888888888
8           8 8
8           8 8
8 8888888 8 8
8 8      8 8 8
8 8      8 8 8
8 8 8* 8 8 8
8 8 8888 8 8
8 8      8 8
8 8      8 8
8 8      8 8
8 888888888888888888
8           8
8           8
88888888888888888888
Current (x, y) = ( 1, 1)

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[Step 1] Turn Right Position ( 1, 1) North LR=11 [Step 30] Move Forward Position (14, 15) South LR=11 [Step 59] Move Forward Position ( 3, 4) East LR=10
[Step 2] Turn Right Position ( 1, 1) East LR=10 [Step 31] Turn Right Position (14, 15) West LR=10 [Step 60] Move Forward Position ( 4, 4) East LR=10
[Step 3] Move Forward Position ( 2, 1) East LR=10 [Step 32] Move Forward Position (13, 15) West LR=10 [Step 61] Move Forward Position ( 5, 4) East LR=10
[Step 4] Move Forward Position ( 3, 1) East LR=10 [Step 33] Move Forward Position (12, 15) West LR=10 [Step 62] Move Forward Position ( 6, 4) East LR=10
[Step 5] Move Forward Position ( 4, 1) East LR=10 [Step 34] Move Forward Position (11, 15) West LR=10 [Step 63] Move Forward Position ( 7, 4) East LR=10
[Step 6] Move Forward Position ( 5, 1) East LR=10 [Step 35] Move Forward Position (10, 15) West LR=10 [Step 64] Move Forward Position ( 8, 4) East LR=10
[Step 7] Move Forward Position ( 6, 1) East LR=10 [Step 36] Move Forward Position ( 9, 15) West LR=10 [Step 65] Move Forward Position ( 9, 4) East LR=10
[Step 8] Move Forward Position ( 7, 1) East LR=10 [Step 37] Move Forward Position ( 8, 15) West LR=10 [Step 66] Move Forward Position (10, 4) East LR=10
[Step 9] Move Forward Position ( 8, 1) East LR=10 [Step 38] Move Forward Position ( 7, 15) West LR=10 [Step 67] Move Forward Position (11, 4) East LR=11
[Step 10] Move Forward Position ( 9, 1) East LR=10 [Step 39] Move Forward Position ( 6, 15) West LR=10 [Step 68] Turn Right Position (11, 4) South LR=10
[Step 11] Move Forward Position (10, 1) East LR=10 [Step 40] Move Forward Position ( 5, 15) West LR=10 [Step 69] Move Forward Position (11, 5) South LR=10
[Step 12] Move Forward Position (11, 1) East LR=10 [Step 41] Move Forward Position ( 4, 15) West LR=10 [Step 70] Move Forward Position (11, 6) South LR=10
[Step 13] Move Forward Position (12, 1) East LR=10 [Step 42] Move Forward Position ( 3, 15) West LR=10 [Step 71] Move Forward Position (11, 7) South LR=10
[Step 14] Move Forward Position (13, 1) East LR=10 [Step 43] Move Forward Position ( 2, 15) West LR=10 [Step 72] Move Forward Position (11, 8) South LR=10
[Step 15] Move Forward Position (14, 1) East LR=11 [Step 44] Move Forward Position ( 1, 15) West LR=11 [Step 73] Move Forward Position (11, 9) South LR=10
[Step 16] Turn Right Position (14, 1) South LR=10 [Step 45] Turn Right Position ( 1, 15) North LR=10 [Step 74] Move Forward Position (11, 10) South LR=10
[Step 17] Move Forward Position (14, 2) South LR=10 [Step 46] Move Forward Position ( 1, 14) North LR=10 [Step 75] Move Forward Position (11, 11) South LR=10
[Step 18] Move Forward Position (14, 3) South LR=10 [Step 47] Move Forward Position ( 1, 13) North LR=10 [Step 76] Move Forward Position (11, 12) South LR=11
[Step 19] Move Forward Position (14, 4) South LR=10 [Step 48] Move Forward Position ( 1, 12) North LR=10 [Step 77] Turn Right Position (11, 12) West LR=10
[Step 20] Move Forward Position (14, 5) South LR=10 [Step 49] Move Forward Position ( 1, 11) North LR=10 [Step 78] Move Forward Position (10, 12) West LR=10
[Step 21] Move Forward Position (14, 6) South LR=10 [Step 50] Move Forward Position ( 1, 10) North LR=10 [Step 79] Move Forward Position ( 9, 12) West LR=10
[Step 22] Move Forward Position (14, 7) South LR=10 [Step 51] Move Forward Position ( 1, 9) North LR=10 [Step 80] Move Forward Position ( 8, 12) West LR=10
[Step 23] Move Forward Position (14, 8) South LR=10 [Step 52] Move Forward Position ( 1, 8) North LR=10 [Step 81] Move Forward Position ( 7, 12) West LR=10
[Step 24] Move Forward Position (14, 9) South LR=10 [Step 53] Move Forward Position ( 1, 7) North LR=10 [Step 82] Move Forward Position ( 6, 12) West LR=10
[Step 25] Move Forward Position (14, 10) South LR=10 [Step 54] Move Forward Position ( 1, 6) North LR=10 [Step 83] Move Forward Position ( 5, 12) West LR=10
[Step 26] Move Forward Position (14, 11) South LR=10 [Step 55] Move Forward Position ( 1, 5) North LR=10 [Step 84] Move Forward Position ( 4, 12) West LR=11
[Step 27] Move Forward Position (14, 12) South LR=10 [Step 56] Move Forward Position ( 1, 4) North LR=11 [Step 85] Turn Right Position ( 4, 12) North LR=10
[Step 28] Move Forward Position (14, 13) South LR=10 [Step 57] Turn Right Position ( 1, 4) East LR=10 [Step 86] Move Forward Position ( 4, 11) North LR=10
[Step 29] Move Forward Position (14, 14) South LR=10 [Step 58] Move Forward Position ( 2, 4) East LR=10 [Step 87] Move Forward Position ( 4, 10) North LR=10

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[Step 82] Move Forward Position ( 6, 12) West LR=10
[Step 83] Move Forward Position ( 5, 12) West LR=10
[Step 84] Move Forward Position ( 4, 12) West LR=11
[Step 85] Turn Right Position ( 4, 12) North LR=10
[Step 86] Move Forward Position ( 4, 11) North LR=10
[Step 87] Move Forward Position ( 4, 10) North LR=10
[Step 88] Move Forward Position ( 4, 9) North LR=10
[Step 89] Move Forward Position ( 4, 8) North LR=10
[Step 90] Move Forward Position ( 4, 7) North LR=11
[Step 91] Turn Right Position ( 4, 7) East LR=10
[Step 92] Move Forward Position ( 5, 7) East LR=10
[Step 93] Move Forward Position ( 6, 7) East LR=10
[Step 94] Move Forward Position ( 7, 7) East LR=10
[Step 95] Move Forward Position ( 8, 7) East LR=11
[Step 96] Turn Right Position ( 8, 7) South LR=10
[Step 97] Move Forward Position ( 8, 8) South LR=10
[Step 98] Move Forward Position ( 8, 9) South LR=11
[Step 99] Turn Right Position ( 8, 9) West LR=10
[Step 100] Move Forward Position ( 7, 9) West LR=00 <You Made It!!>

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<<< Total steps used: 100 >>>
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>>> MAZE ESCAPED!!!
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>>> Congratulations! Escape at time [ 10400]
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```
Simulation complete via $finish(1) at time 1090 NS + 0
```

```
./AntVengers.v:66 $finish;
```

```
ncsim> exit
```

```
[dld063@ic21 ~/hw07]$
```

b. maze07x06:

```
Initial position: ( 1, 1)
Initial direction: West
Maze Exit: ( 6, 2)

Maze Universe:
-----
88888888
8W 8 8
8 8 *
8 8
8 8
88888888
Current (x, y) = ( 1, 1)
[Step 1] Turn Right Position ( 1, 1) North LR=11
[Step 2] Turn Right Position ( 1, 1) East LR=10
[Step 3] Move Forward Position ( 2, 1) East LR=11
[Step 4] Turn Right Position ( 2, 1) South LR=10
[Step 5] Move Forward Position ( 2, 2) South LR=10
[Step 6] Move Forward Position ( 2, 3) South LR=00
[Step 7] Turn Left Position ( 2, 3) East LR=00
[Step 8] Move Forward Position ( 3, 3) East LR=10
[Step 9] Move Forward Position ( 4, 3) East LR=00
[Step 10] Turn Left Position ( 4, 3) North LR=00
[Step 11] Move Forward Position ( 4, 2) North LR=10
[Step 12] Move Forward Position ( 4, 1) North LR=11
[Step 13] Turn Right Position ( 4, 1) East LR=10
[Step 14] Move Forward Position ( 5, 1) East LR=11
[Step 15] Turn Right Position ( 5, 1) South LR=10

8W 8 8
8 8 *
8 8
8 8
88888888
Current (x, y) = ( 1, 1)
[Step 1] Turn Right Position ( 1, 1) North LR=11
[Step 2] Turn Right Position ( 1, 1) East LR=10
[Step 3] Move Forward Position ( 2, 1) East LR=11
[Step 4] Turn Right Position ( 2, 1) South LR=10
[Step 5] Move Forward Position ( 2, 2) South LR=10
[Step 6] Move Forward Position ( 2, 3) South LR=00
[Step 7] Turn Left Position ( 2, 3) East LR=00
[Step 8] Move Forward Position ( 3, 3) East LR=10
[Step 9] Move Forward Position ( 4, 3) East LR=00
[Step 10] Turn Left Position ( 4, 3) North LR=00
[Step 11] Move Forward Position ( 4, 2) North LR=10
[Step 12] Move Forward Position ( 4, 1) North LR=11
[Step 13] Turn Right Position ( 4, 1) East LR=10
[Step 14] Move Forward Position ( 5, 1) East LR=11
[Step 15] Turn Right Position ( 5, 1) South LR=10
[Step 16] Move Forward Position ( 5, 2) South LR=00
[Step 17] Turn Left Position ( 5, 2) East LR=00
[Step 18] Move Forward Position ( 6, 2) East LR=00 <You Made It!!>

<<< Total steps used: 18 >>>
>>> MAZE ESCAPED!!!

>>> Congratulations! Escape at time [ 2200]
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c. maze_15x15

Initial direction: South
Maze Exit: (6, 0)

Maze Universe:

888888*88888888

8 8 8

8 8 8

8 8 88 8

8 8888 88

8 8 8

8 8 8

8888888 S 888

8 88

8 8

8 88888 8

8 8 8

8 8 8 8

8 8 8 8

888888888888888

Current (x, y) = (10, 7)

[Step 1] Move Forward Position (10, 8) South LR=00
[Step 2] Move Forward Position (10, 9) South LR=11
[Step 3] Turn Right Position (10, 9) West LR=10
[Step 4] Move Forward Position (9, 9) West LR=10
[Step 5] Move Forward Position (8, 9) West LR=10
[Step 6] Move Forward Position (7, 9) West LR=10
[Step 7] Move Forward Position (6, 9) West LR=10

[Step 8] Move Forward Position (5, 9) West LR=00
[Step 9] Turn Left Position (5, 9) South LR=00
[Step 10] Move Forward Position (5, 10) South LR=10
[Step 11] Move Forward Position (5, 11) South LR=00
[Step 12] Turn Left Position (5, 11) East LR=00
[Step 13] Move Forward Position (6, 11) East LR=10
[Step 14] Move Forward Position (7, 11) East LR=10
[Step 15] Move Forward Position (8, 11) East LR=11
[Step 16] Turn Right Position (8, 11) South LR=10
[Step 17] Move Forward Position (8, 12) South LR=10
[Step 18] Move Forward Position (8, 13) South LR=11
[Step 19] Turn Right Position (8, 13) West LR=10
[Step 20] Move Forward Position (7, 13) West LR=10
[Step 21] Move Forward Position (6, 13) West LR=10
[Step 22] Move Forward Position (5, 13) West LR=10
[Step 23] Move Forward Position (4, 13) West LR=11
[Step 24] Turn Right Position (4, 13) North LR=10
[Step 25] Move Forward Position (4, 12) North LR=10
[Step 26] Move Forward Position (4, 11) North LR=00
[Step 27] Turn Left Position (4, 11) West LR=00
[Step 28] Move Forward Position (3, 11) West LR=10
[Step 29] Move Forward Position (2, 11) West LR=00
[Step 30] Turn Left Position (2, 11) South LR=00
[Step 31] Move Forward Position (2, 12) South LR=10
[Step 32] Move Forward Position (2, 13) South LR=11
[Step 33] Turn Right Position (2, 13) West LR=10
[Step 34] Move Forward Position (1, 13) West LR=11
[Step 35] Turn Right Position (1, 13) North LR=10
[Step 36] Move Forward Position (1, 12) North LR=10

[Step 37] Move Forward Position (1, 11) North LR=10
[Step 38] Move Forward Position (1, 10) North LR=10
[Step 39] Move Forward Position (1, 9) North LR=10
[Step 40] Move Forward Position (1, 8) North LR=11
[Step 41] Turn Right Position (1, 8) East LR=10
[Step 42] Move Forward Position (2, 8) East LR=10
[Step 43] Move Forward Position (3, 8) East LR=10
[Step 44] Move Forward Position (4, 8) East LR=10
[Step 45] Move Forward Position (5, 8) East LR=10
[Step 46] Move Forward Position (6, 8) East LR=10
[Step 47] Move Forward Position (7, 8) East LR=00
[Step 48] Turn Left Position (7, 8) North LR=00
[Step 49] Move Forward Position (7, 7) North LR=10
[Step 50] Move Forward Position (7, 6) North LR=10
[Step 51] Move Forward Position (7, 5) North LR=10
[Step 52] Move Forward Position (7, 4) North LR=10
[Step 53] Move Forward Position (7, 3) North LR=00
[Step 54] Turn Left Position (7, 3) West LR=00
[Step 55] Move Forward Position (6, 3) West LR=10
[Step 56] Move Forward Position (5, 3) West LR=10
[Step 57] Move Forward Position (4, 3) West LR=11
[Step 58] Turn Right Position (4, 3) North LR=10
[Step 59] Move Forward Position (4, 2) North LR=00
[Step 60] Turn Left Position (4, 2) West LR=00
[Step 61] Move Forward Position (3, 2) West LR=10
[Step 62] Move Forward Position (2, 2) West LR=00
[Step 63] Turn Left Position (2, 2) South LR=00
[Step 64] Move Forward Position (2, 3) South LR=10
[Step 65] Move Forward Position (2, 4) South LR=10

[Step 68] Move Forward Position (3, 5) East LR=10
[Step 69] Move Forward Position (4, 5) East LR=10
[Step 70] Move Forward Position (5, 5) East LR=11
[Step 71] Turn Right Position (5, 5) South LR=10
[Step 72] Move Forward Position (5, 6) South LR=11
[Step 73] Turn Right Position (5, 6) West LR=10
[Step 74] Move Forward Position (4, 6) West LR=10
[Step 75] Move Forward Position (3, 6) West LR=10
[Step 76] Move Forward Position (2, 6) West LR=10
[Step 77] Move Forward Position (1, 6) West LR=11
[Step 78] Turn Right Position (1, 6) North LR=10
[Step 79] Move Forward Position (1, 5) North LR=10
[Step 80] Move Forward Position (1, 4) North LR=10
[Step 81] Move Forward Position (1, 3) North LR=10
[Step 82] Move Forward Position (1, 2) North LR=10
[Step 83] Move Forward Position (1, 1) North LR=11
[Step 84] Turn Right Position (1, 1) East LR=10
[Step 85] Move Forward Position (2, 1) East LR=10
[Step 86] Move Forward Position (3, 1) East LR=10
[Step 87] Move Forward Position (4, 1) East LR=10
[Step 88] Move Forward Position (5, 1) East LR=10
[Step 89] Move Forward Position (6, 1) East LR=00
[Step 90] Turn Left Position (6, 1) North LR=00
[Step 91] Move Forward Position (6, 0) North LR=00 <You Made It!!>

<<< Total steps used: 91 >>>
>>> MAZE ESCAPED!!!
>>> Congratulations! Escape at time [9500]

3. Challenge: narrow corridors or corners

Originally, if the antenna signals are 11, it is seen as the “wall ahead” condition. However, with narrow corridors or corners, we should always assume that there is no wall ahead. Thus, the next move should be “Forward”. If there is a wall ahead, the “hit” signal would tell us that it is impossible to walk forward. Only when the “hit” signal is invoked can we be sure that the condition is “wall ahead”.

When the antenna signals are 11, store the original move into a register and assign “Forward” to next move. At the move “Forward”, if hit signal is not invoked, then continue with forward; if hit signal is invoked, assign the register to the next move.