# **Selected Topics in Visual Recognition in Deep Learning Exercise 3**

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Github link of Homework 3: <a href="https://github.com/kimbold/VRDL">https://github.com/kimbold/VRDL</a> 2019/tree/master/HW3

**References:** The code I used in this work reuses a lot of partly modified code from this repository: <a href="https://github.com/penny4860/Yolo-digit-detector">https://github.com/penny4860/Yolo-digit-detector</a> (<a href="https://github

**Speed benchmark:** Processing one image for digit prediction and localization takes 114 ms as tested on Google Colabs TPU which processed the data in general faster than the GPU in my tests:



# Introduction:

#### Methodology:

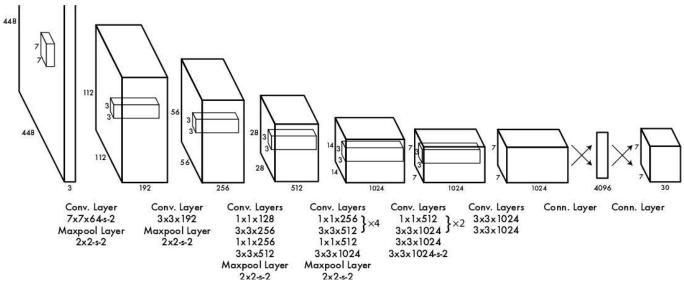
To solve this digit detection exercise, the YOLO v2 network was trained on the provided svhn data and then used to classify the test dataset. For the computation the weights from the training were loaded into google colab and the speed was benchmarked and results stored into the .json file for the submission.

## Data preprocess:

The datasets have been loaded into Google Colab and were extracted. Then the .mat/h5 file was processed to create an xml file for each image for the annotations (label and positions). Based on that it was possible to train the network and store the weights for later usage afterwards.

### Model architecture:

For this task I utilized the darknet yolo v2 architecture. As described in the yolo9000 (yolo v2) paper <a href="https://arxiv.org/pdf/1612.08242v1.pdf">https://arxiv.org/pdf/1612.08242v1.pdf</a>), the YOLO framework uses a custom network based on the Googlenet architecture. It is a fully connected convolutional neural network and can be visually represented:



(This is a figure from the YOLO paper <a href="https://www.semanticscholar.org/paper/You-Only-Look-Once%3A-Unified%2C-Real-Time-Object-Redmon-Divvala/f8e79ac0ea341056ef20f2616628b3e964764cfd">https://www.semanticscholar.org/paper/You-Only-Look-Once%3A-Unified%2C-Real-Time-Object-Redmon-Divvala/f8e79ac0ea341056ef20f2616628b3e964764cfd</a>)

# Hyperparameters:

- "architecture": "ResNet50"
- "input size": 416
- "anchors": [0.57273, 0.677385, 1.87446, 2.06253,3.33843, 5.47434, 7.88282, 3.52778, 9.77052, 9.16828]
- "labels": ["0", "1", "2", "3", "4", "5", "6", "7", "8", "9"]
- "coord\_scale": 1.0
- "class scale": 1.0
- "object scale": 5.0
- "no object scale": 1.0
- weights: "svhn/weights.h5"
- "actual epoch": 25,
- "train times": 5,
- "valid\_times": 1,
- "batch size": 16,
- "learning rate": 1e-4,
- "saved folder": "svhn",
- "jitter": true,
- "first trainable layer": "input 1",
- "is only detect" : false

# **Summary:**

Overall the model performed quite well and managed to detect and a lot of images correctly.

But there are also several instances when the network could not detect any images at all.

# In [ ]:

```
!git clone https://github.com/kimbold/VRDL_2019
```

# In [0]:

# In [3]:

/content/VRDL\_2019/HW3

# In [4]:

```
Requirement already satisfied: gdown in /usr/local/lib/python3.6/dist-pack
ages (3.6.4)
Requirement already satisfied: requests in /usr/local/lib/python3.6/dist-p
ackages (from gdown) (2.21.0)
Requirement already satisfied: tqdm in /usr/local/lib/python3.6/dist-packa
ges (from gdown) (4.28.1)
Requirement already satisfied: six in /usr/local/lib/python3.6/dist-packag
es (from gdown) (1.12.0)
Requirement already satisfied: chardet<3.1.0,>=3.0.2 in /usr/local/lib/pyt
hon3.6/dist-packages (from requests->gdown) (3.0.4)
Requirement already satisfied: urllib3<1.25,>=1.21.1 in /usr/local/lib/pyt
hon3.6/dist-packages (from requests->gdown) (1.24.3)
Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python
3.6/dist-packages (from requests->gdown) (2019.9.11)
Requirement already satisfied: idna<2.9,>=2.5 in /usr/local/lib/python3.6/
dist-packages (from requests->gdown) (2.8)
Downloading...
From: https://drive.google.com/uc?id=1DryVeYEC5mlo0YFHltN6EhO4zFuTIvNn
To: /content/VRDL 2019/HW3/weights.h5
285MB [00:01, 234MB/s]
```

# In [5]:

Downloading...

From: https://drive.google.com/uc?id=1GV4TLocxFcsR8QPdM-rP8RoOB2vjs\_E\_

To: /content/VRDL\_2019/HW3/test.zip

272MB [00:01, 224MB/s]

# In [ ]:

### Load svhn dataset

```
In [0]:
```

#### **Extract dataset files**

```
In [3]:
```

```
!unzip test.zip
```

# Import required modules

# In [ ]:

```
import numpy as np
import argparse
import os
import json
from yolo.frontend import create_yolo, get_object_labels
import xml.etree.cElementTree as ET
import h5pv
from lxml import etree
import tables
import argparse
import json
import cv2
import numpy as np
from yolo.frontend import create yolo
from yolo.backend.utils.box import draw scaled boxes
from yolo.backend.utils.annotation import parse annotation
from yolo.backend.utils.eval._box_match import BoxMatcher
import os
import volo
import os
os.environ["CUDA DEVICE ORDER"]="PCI BUS ID"
os.environ["CUDA_VISIBLE_DEVICES"]="0"
```

# **Define methods to load annotations**

```
def get name(index, hdf5 data):
    name = hdf5_data['/digitStruct/name']
    return ''.join([chr(v[0]) for v in hdf5_data[name[index][0]].value])
def keys(f):
    return [key for key in f.keys()]
def get_bbox(index, hdf5_data):
  The box data contains width and height of the box as well as the upper left corner.
  By supplying the distance from the left border and top border, the upper left point c
an be identified.
  .....
  attrs = {}
  item = hdf5_data['digitStruct']['bbox'][index].item()
  for key in ['label', 'left', 'top', 'width', 'height']:
      attr = hdf5 data[item][key]
      values = [hdf5 data[attr.value[i].item()].value[0][0]
                for i in range(len(attr))] if len(attr) > 1 else [attr.value[0][0]]
      attrs[key] = values
  return attrs
def prettyPrintXml(xmlFilePathToPrettyPrint):
    parser = etree.XMLParser(resolve entities=False, strip cdata=False)
    document = etree.parse(xmlFilePathToPrettyPrint, parser)
    document.write(xmlFilePathToPrettyPrint, pretty_print=True, encoding='utf-8')
# Define replacement strings for different operating systems
WINDOWS LINE ENDING = b'\r\n'
UNIX_LINE_ENDING = b'\n'
def replace_Unix_with_Windows_in_XLM(xmlFilePath):
    with open(xmlFilePath, 'rb') as open file:
      content = open file.read()
    content = content.replace(UNIX_LINE_ENDING,WINDOWS_LINE_ENDING)
    with open(xmlFilePath, 'wb') as open_file:
        open file.write(content)
```

# In [0]:

# Load annotations for training

The annotations are read from the h5 file and then written to xml files for each picture.

```
if(training==1):
  # Need to define method to read .mat data and then write annotation files for each pi
  filename = "train/digitStruct.mat"
  f = h5py.File(filename, 'r')
  # Iterate through all images to create the annotation file
  for image in range(f['digitStruct']['bbox'].shape[0]):
    #annotation
    root = ET.Element("annotation")
    #Get image annotation data
    size_data = get_bbox(image, f)
    #filename
    filename = get name(image,f)
    doc = ET.SubElement(root, "filename").text = filename
    # For each detected digit, add the data for the box for it
    object_list = [[] for _ in range(len(size_data['label']))]
    bndbox = [[] for _ in range(len(size_data['label']))]
    for number in range(len(size data['label'])):
      object list[number] = ET.SubElement(root, "object")
      ET.SubElement(object_list[number], "name").text = str(int(size_data['label'][numb
er]))
      bndbox[number] = ET.SubElement(object_list[number], "bndbox")
      ET.SubElement(bndbox[number], "xmin").text = str(int(size_data['left'][number]))
ET.SubElement(bndbox[number], "ymin").text = str(int(size_data['top'][number]))
      ET.SubElement(bndbox[number], "xmax").text = str(int(size_data['width'][number]+s
ize_data['left'][number]))
      ET.SubElement(bndbox[number], "ymax").text = str(int(size_data['height'][number]+
size_data['top'][number]))
    tree = ET.ElementTree(root)
    #Write xml
    tree.write("tests/dataset/svhn/anns/"+str(image+1)+".xml")
    prettyPrintXml("tests/dataset/svhn/anns/"+str(image+1)+".xml")
    replace_Unix_with_Windows_in_XLM("tests/dataset/svhn/anns/"+str(image+1)+".xml")
 # For some reason google colab always showed an error with this checkpoint directory
 after this operation
  # So I had to delete it
  if os.path.exists('tests/dataset/svhn/anns/.ipynb_checkpoints'):
    os.rmdir('tests/dataset/svhn/anns/.ipynb_checkpoints')
```

# Train yolo

```
#Train and validate YOLO v2 model on any dataset
def setup_training(config_file):
    """make directory to save weights & its configuration """
    import shutil
    with open(config_file) as config_buffer:
        config = json.loads(config_buffer.read())
    dirname = config['train']['saved_folder']
    if os.path.isdir(dirname):
        print("{} is already exists. Weight file in directory will be overwritten".form
at(dirname))
   else:
        print("{} is created.".format(dirname, dirname))
        os.makedirs(dirname)
    print("Weight file and Config file will be saved in \"{}\"".format(dirname))
    shutil.copyfile(config_file, os.path.join(dirname, "config.json"))
    return config, os.path.join(dirname, "weights.h5")
def train(conf="configs/from scratch.json"):
 #path to configuration file
    config, weight file = setup training(conf)
    if config['train']['is only detect']:
        labels = ["object"]
    else:
        if config['model']['labels']:
            labels = config['model']['labels']
            labels = get_object_labels(config['train']['train_annot_folder'])
    print(labels)
    # 1. Construct the model
    yolo = create yolo(config['model']['architecture'],
                       labels,
                       config['model']['input_size'],
                       config['model']['anchors'],
                       config['model']['coord_scale'],
                       config['model']['class_scale'],
                       config['model']['object_scale'],
                       config['model']['no_object_scale'])
    # 2. Load the pretrained weights (if any)
    yolo.load_weights(config['pretrained']['full'], by_name=True)
    # 3. actual training
    yolo.train(config['train']['train_image_folder'],
               config['train']['train_annot_folder'],
               config['train']['actual_epoch'],
               weight_file,
               config["train"]["batch_size"],
               config["train"]["jitter"],
               config['train']['learning_rate'],
               config['train']['train_times'],
               config['train']['valid times'],
               config['train']['valid_image_folder'],
               config['train']['valid_annot_folder'],
               config['train']['first_trainable_layer'],
```

```
config['train']['is_only_detect'])
# loss: 2.1691, train batch jitter=False
```

# In [0]:

# After training the weights are stored in .h5 file

So now it is necessary to ensure that it is closed properly to avoid corruption. Not sure why exactly but it caused errors.

# In [0]:

```
# Closing all .hd5 files: https://stackoverflow.com/questions/29863342/close-an-open-h5
py-data-file against corruption
tables.file._open_files.close_all()
```

# Evaluate trained yolo digit detector

#### In [5]:

# Predict test data

```
import json
# Define method to just build the network and load the weights
# so that the speed can be benchmarked with just the prediction
# and not the model loading as well
def create_yolo_instance(conf=DEFAULT_CONFIG_FILE, weights=DEFAULT_WEIGHT_FILE):
 with open(conf) as config buffer:
   config = json.loads(config_buffer.read())
 # 2. create yolo instance & predict
 yolo = create_yolo(config['model']['architecture'],
                  config['model']['labels'],
                  config['model']['input_size'],
                  config['model']['anchors'])
 yolo.load weights(weights)
 return yolo
# Define method to predict the 13068 test images
def predict_testdata(image_folder="test/",conf=DEFAULT_CONFIG_FILE, weights=DEFAULT_WEI
GHT_FILE, threshold=DEFAULT_THRESHOLD):
     # Create list of dictionaries for submission
     prediction_dictionaries = [{} for _ in range(1,13069)]
     with open(conf) as config_buffer:
         config = json.loads(config buffer.read())
     # 2. create yolo instance & predict
     yolo = create_yolo(config['model']['architecture'],
                     config['model']['labels'],
                     config['model']['input_size'],
                     config['model']['anchors'])
     yolo.load weights(weights)
     # 3. read image
     write dname = "detected"
     if not os.path.exists(write_dname): os.makedirs(write_dname)
     for i in range(1,13069):
        # For each image, get the predicted labels, probabilities and boxes
        img_path=image_folder+str(i)+".png"
        print(img_path)
         img fname = os.path.basename(img path)
        image = cv2.imread(img_path)
        boxes = [[]]
        probs = []
        labels = []
        boxes, probs = yolo.predict(image, float(threshold))
        labels = np.argmax(probs, axis=1) if len(probs) > 0 else []
```

```
try:
            prediction_dictionaries[i-1]['bbox']=boxes.tolist()
            prediction dictionaries[i-1]['bbox']=boxes
          prediction_dictionaries[i-1]['score']=[np.max(probs[i]) for i in range(len(pr
obs))]
          try:
            prediction_dictionaries[i-1]['label']=labels.tolist()
          except:
            prediction_dictionaries[i-1]['label']=labels
          #print(prediction_dictionaries)
          # 4. save detection result
          image = draw scaled boxes(image, boxes, probs, config['model']['labels'])
          output_path = os.path.join(write_dname, os.path.split(img_fname)[-1])
          cv2.imwrite(output path, image)
          #print("{}-boxes are detected. {} saved.".format(len(boxes), output_path))
      #5. Write the list of dictionaries to a .json file for the submission
      with open("0845058.json", 'w') as f:
        f.write(str(prediction_dictionaries))
      #6. Upload the .json file to google drive
      file1 = drive.CreateFile()
      file1.SetContentFile('0845058.json')
      file1.Upload()
```

#### Timing for one picture

### In [2]:

# In [22]:

The slowest run took 7.99 times longer than the fastest. This could mean that an intermediate result is being cached.

1 loop, best of 3: 114 ms per loop

# In [1]: