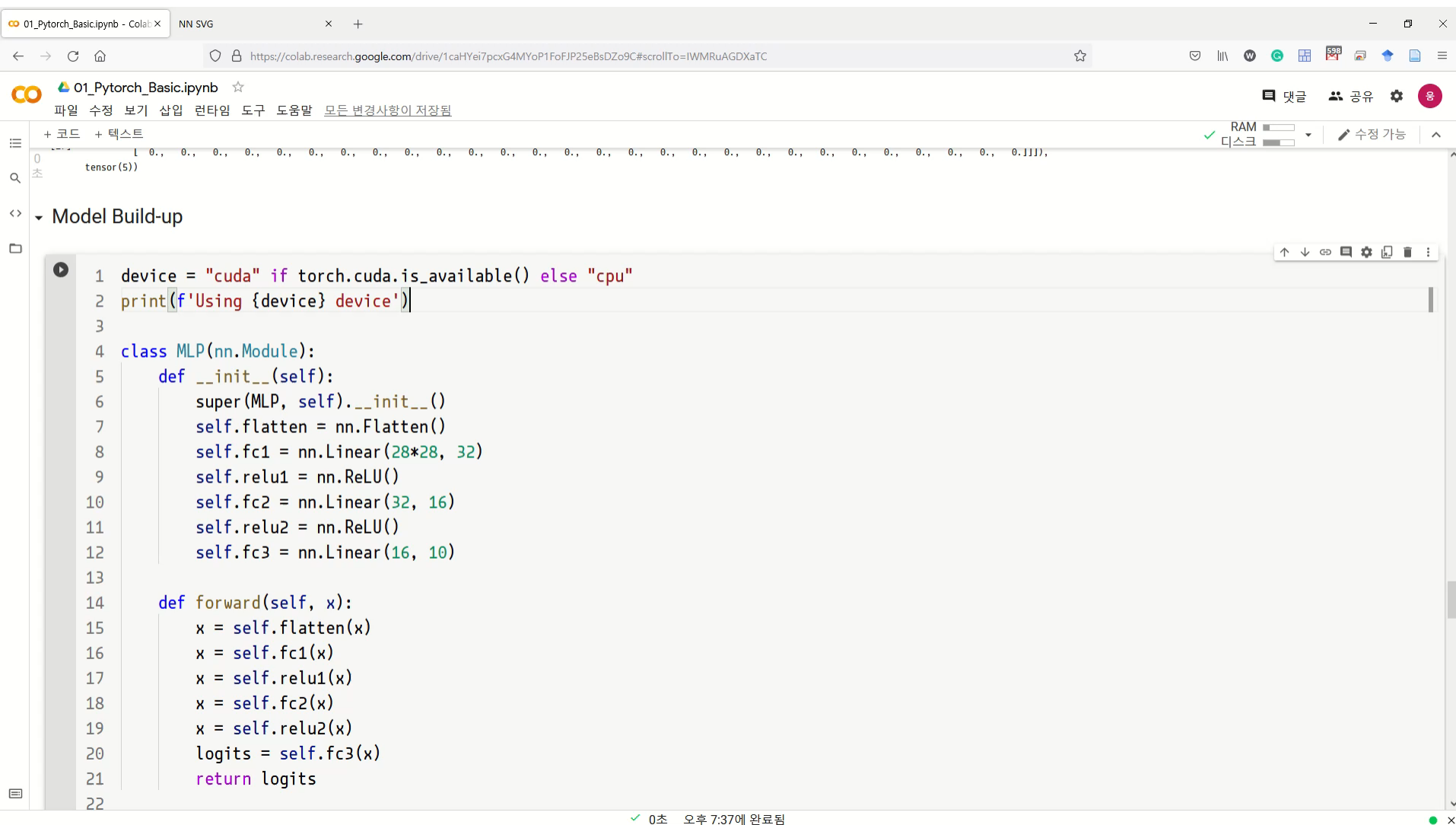


Model Build-up



```
1 device = "cuda" if torch.cuda.is_available() else "cpu"
2 print(f'Using {device} device')
3
4 class MLP(nn.Module):
5     def __init__(self):
6         super(MLP, self).__init__()
7         self.flatten = nn.Flatten()
8         self.fc1 = nn.Linear(28*28, 32)
9         self.relu1 = nn.ReLU()
10        self.fc2 = nn.Linear(32, 16)
11        self.relu2 = nn.ReLU()
12        self.fc3 = nn.Linear(16, 10)
13
14    def forward(self, x):
15        x = self.flatten(x)
16        x = self.fc1(x)
17        x = self.relu1(x)
18        x = self.fc2(x)
19        x = self.relu2(x)
20        logits = self.fc3(x)
21        return logits
22
```

0초 오후 7:37에 완료됨

Model Build-up

□ Class 기반 Model 생성

```
device = "cuda" if torch.cuda.is_available() else "cpu"  
print(f'Using {device} device')
```

```
class MLP(nn.Module):  
    def __init__(self):  
        super(MLP, self).__init__()  
        self.flatten = nn.Flatten()  
        self.fc1 = nn.Linear(28*28, 32)  
        self.relu1 = nn.ReLU()  
        self.fc2 = nn.Linear(32, 16)  
        self.relu2 = nn.ReLU()  
        self.fc3 = nn.Linear(16, 10)
```

```
    def forward(self, x):  
        x = self.flatten(x)  
        x = self.fc1(x)  
        x = self.relu1(x)  
        x = self.fc2(x)  
        x = self.relu2(x)  
        logits = self.fc3(x)  
        return logits
```

```
model = MLP().to(device)
```

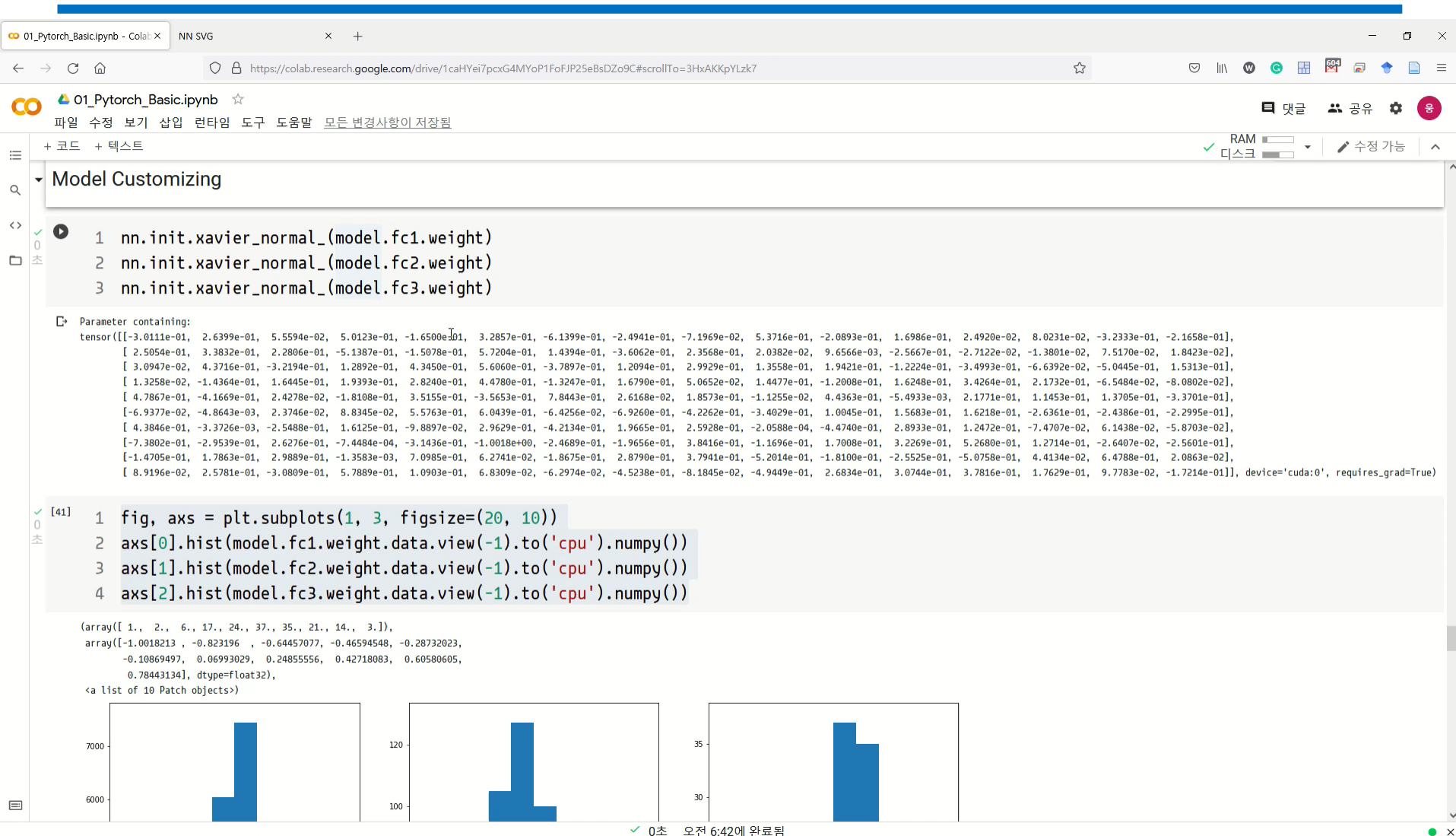
- 모델 파라미터 Handling

model_name.state_dict()

model_name.layer_name.weight.data



Model Customizing



Model Customizing

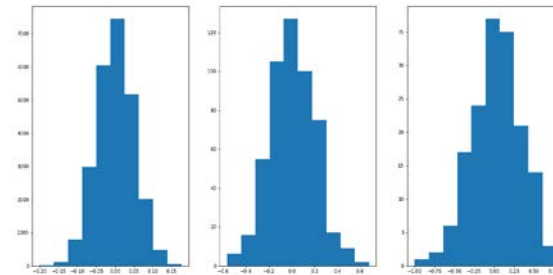
□ 모델 가중치 초기화

```
1 torch.nn.init.xavier_normal_(model.fc1.weight)
2 torch.nn.init.xavier_normal_(model.fc2.weight)
3 torch.nn.init.xavier_normal_(model.fc3.weight)
```

dir(내부를 확인하고자 하는 변수)

ex) dir(torch.nn.init)

```
1 fig, axs = plt.subplots(1, 3, figsize=(20, 10))
2 axs[0].hist(model.fc1.weight.data.view(-1).to('cpu').numpy())
3 axs[1].hist(model.fc2.weight.data.view(-1).to('cpu').numpy())
4 axs[2].hist(model.fc3.weight.data.view(-1).to('cpu').numpy())
```



□ torch.nn.Module 기반 모델 생성

```
1 fc1 = torch.nn.Linear(28*28, 32)
2 fc2 = torch.nn.Linear(32, 16)
3 fc3 = torch.nn.Linear(16, 10)
4 relu = torch.nn.ReLU()
5 model_with_seq = torch.nn.Sequential(fc1, relu, fc2, relu, fc3).to(device)
```

Model I/O

Model I/O

❑ Model Input

```
1 train_iter = iter(train_dataloader)
2 images, labels = next(train_iter)
3 images = images.to(device)
4 labels = labels.to(device)
```

```
1 print(model.flatten(images[0]).size())
2 print(images[0].view(1, -1).size())
```

```
1 fc1_out_a = model.fc1(model.flatten(images[0]))
2 fc1_out_a
```

```
tensor([[ 0.4556, -0.3542, -0.4255, -0.2685,  0.0113, -0.1706,  0.2055,  0.3898,  0.8445,
          < 
```

```
1 fc1_out_b = model.fc1(images[0].view(1, -1))
2 fc1_out_b
```

```
tensor([[ 0.4556, -0.3542, -0.4255, -0.2685,  0.0113, -0.1706,  0.2055,  0.3898,  0.8445,
          < 
```

```
1 torch.equal(fc1_out_a, fc1_out_b)
```

True

❑ Model Output

```
1 y_direct = model(images[0])
2 y_direct
```

```
tensor([[ 0.0093,  0.1454,  0.1872,  0.0068, -0.1608,  0.1232,  0.0666,  0.1991, -0.0420,  0.1664]],
```

```
1 x = images[0].view(1, -1) # model.flatten(images[0])
2 y1 = model.relu1(model.fc1(x))
3 y2 = model.relu2(model.fc2(y1))
4 y = model.fc3(y2)
5 y
```

```
tensor([[ 0.0093,  0.1454,  0.1872,  0.0068, -0.1608,  0.1232,  0.0666,  0.1991, -0.0420,  0.1664]],
```

```
1 torch.equal(y_direct, y)
```

True

```
1 x = images[0].view(1, -1)
2 act1_direct = model.fc1(x)
3 act1_direct
```

```
tensor([[ 0.4556, -0.3542, -0.4255, -0.2685,  0.0113, -0.1706,  0.2055,  0.3898,  0.8445, -0.2810, -0.4039, -0.2997,
          < 
```

```
1 x = images[0].view(1, -1)
2 act1 = torch.matmul(x, model.fc1.weight.t()) + model.fc1.bias
3 act1
```

```
tensor([[ 0.4556, -0.3542, -0.4255, -0.2685,  0.0113, -0.1706,  0.2055,  0.3898,  0.8445, -0.2810, -0.4039, -0.2997,
          < 
```

```
1 torch.equal(act1_direct, act1)
```

True

Loss Function

01_Pytorch_Basic.ipynb - Colab

https://colab.research.google.com/drive/1caHYei7pcxG4MYoP1FoFJP25eBsDZo9C#scrollTo=n8mkEWJFuny6

01_Pytorch_Basic.ipynb

파일 수정 보기 삽입 런타임 도구 도움말 오전 7:46 이후 저장되지 않음

+ 코드 + 텍스트

RAM 디스크 수정 가능

Define Loss Function

$$H(p, q) = - \sum_{x \in \mathcal{X}} p(x) \log q(x)$$

```
1 # y = [1      0      0  0 ... 0]
2 # y_ = [0.9    0.05  0  0 ... 0]
3 loss_func = nn.CrossEntropyLoss()
```

```
[199] 1 print(model(images[0]))
      2 print(model(images[0]).size())
      3 print(labels[0])
      4 print(labels[0].view(1))
```

tensor([[0.0505, 0.1701, 0.1653, -0.0931, -0.2277, 0.2645, 0.1575, 0.1905, 0.0016, 0.0455]], device='cuda:0', grad_fn=<AddmmBackward>)

torch.Size([1, 10])

tensor(5, device='cuda:0')

tensor([5], device='cuda:0')

```
[206] 1 def myCrossEntropyLoss(logits, labels):
      2     cee = 0
      3     for idx, logit in enumerate(logits):
      4         #print(f'IDX:{idx}, Logit:{logit}')
      5         y = labels[idx]
      6         y_ = nn.functional.softmax(logit)[y]
      7         cee = cee - torch.log(y_)/len(logits)
      8     return cee
```

0초 오전 8:52에 완료됨

Loss Function

□ Classification → CrossEntropyLoss

- Equation $H(p, q) = - \sum_{x \in \mathcal{X}} p(x) \log q(x)$

- 'Built-in' vs 'Custom'

```
1 # y = [0      1      0  0 ... 0]
2 # y_ = [0.9    0.05   0  0 ... 0] # model output > softmax
3 loss_func = nn.CrossEntropyLoss()
```

```
1 def myCrossEntropyLoss(logits, labels):
2     cee = 0
3     for idx, logit in enumerate(logits): # logits = [[~~~~~],..., [~~~~~]] logit = [~~~~~: 10 elements]
4         #print(f'IDX:{idx}, Logit:{logit}')
5         y = labels[idx]
6         y_ = nn.functional.softmax(logit)[y]
7         cee = cee - torch.log(y_)/len(logits)
8     return cee
```

```
1 loss_builtin = loss_func(model(images), labels)
2 loss_builtin
tensor(2.3562, device='cuda:0', grad_fn=<NLLLossBackward0>)
```

```
1 loss_custom = myCrossEntropyLoss(model(images), labels)
2 loss_custom
tensor(2.3562, device='cuda:0', grad_fn=<SubBackward0>)
```

