

Image fundamentals, Neural Network

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- Neural Network

Pixels

- Pixels are the raw building blocks of an image. Every image consists of a set of pixels.



This image is 1,000 pixels wide and 750 pixels tall, for a total of $1,000 \times 750 = 750,000$ total pixels.



151	121	1	93	165	204	14	214	28	235	29	142	142	75	22	109	111	28	6	5
62	67	17	234	27	1	221	37	189	141	137	168	41	206	100	70	219	127	114	191
20	168	155	113	178	228	25	130	139	221	205	154	226	14	89	86	242	67	203	15
236	136	158	230	10	5	165	17	30	155	247	47	128	123	253	229	181	251	232	28
174	148	93	70	95	106	151	10	160	214	68	75	24	99	93	63	215	222	182	180
103	126	58	16	138	136	98	202	42	233	206	246	85	103	215	3	62	64	77	215
235	103	52	37	94	104	173	86	223	113	126	80	165	149	196	75	186	60	179	193
212	15	179	139	48	232	194	46	174	37	44	253	164	253	14	216	175	30	46	254
119	81	241	172	95	170	29	210	22	194	137	23	33	203	241	21	144	63	244	188
129	19	33	253	229	5	152	233	52	44	32	214	142	121	249	109	99	232	183	71
88	200	194	185	140	200	223	190	164	102	45	36	152	27	190	137	61	1	237	247
113	16	220	215	143	104	247	29	97	203	1	14	241	70	2	30	151	67	169	205
9	210	102	246	75	9	158	104	184	129	32	80	102	32	99	169	91	166	73	214
124	52	76	148	249	107	65	216	187	181	186	219	9	203	209	240	40	249	119	122
6	251	52	208	46	65	185	38	77	240	177	252	38	203	119	0	217	139	139	157
150	194	28	206	148	197	208	28	74	93	154	145	49	251	150	185	235	23	230	156
33	183	248	153	168	205	146	100	254	218	157	168	223	60	247	118	5	180	16	206
130	53	128	212	61	226	201	110	140	183	102	208	195	246	140	138	54	191	139	79
165	246	22	102	151	213	40	138	8	93	17	233	85	169	166	24	49	40	160	97
152	251	101	230	23	162	70	238	75	24	84	242	247	144	203	3	19	24	198	88
187	105	152	83	167	98	125	180	136	121	67	67	185	98	123	106	168	105	127	153
139	197	55	209	28	124	208	208	104	40	37	113	214	252	203	80	146	211	7	16
123	19	144	223	62	253	202	108	47	242	142	241	66	86	214	133	146	253	189	200
220	144	31	16	136	123	227	62	183	163	67	215	174	111	189	54	144	56	59	163

Gray and Color image

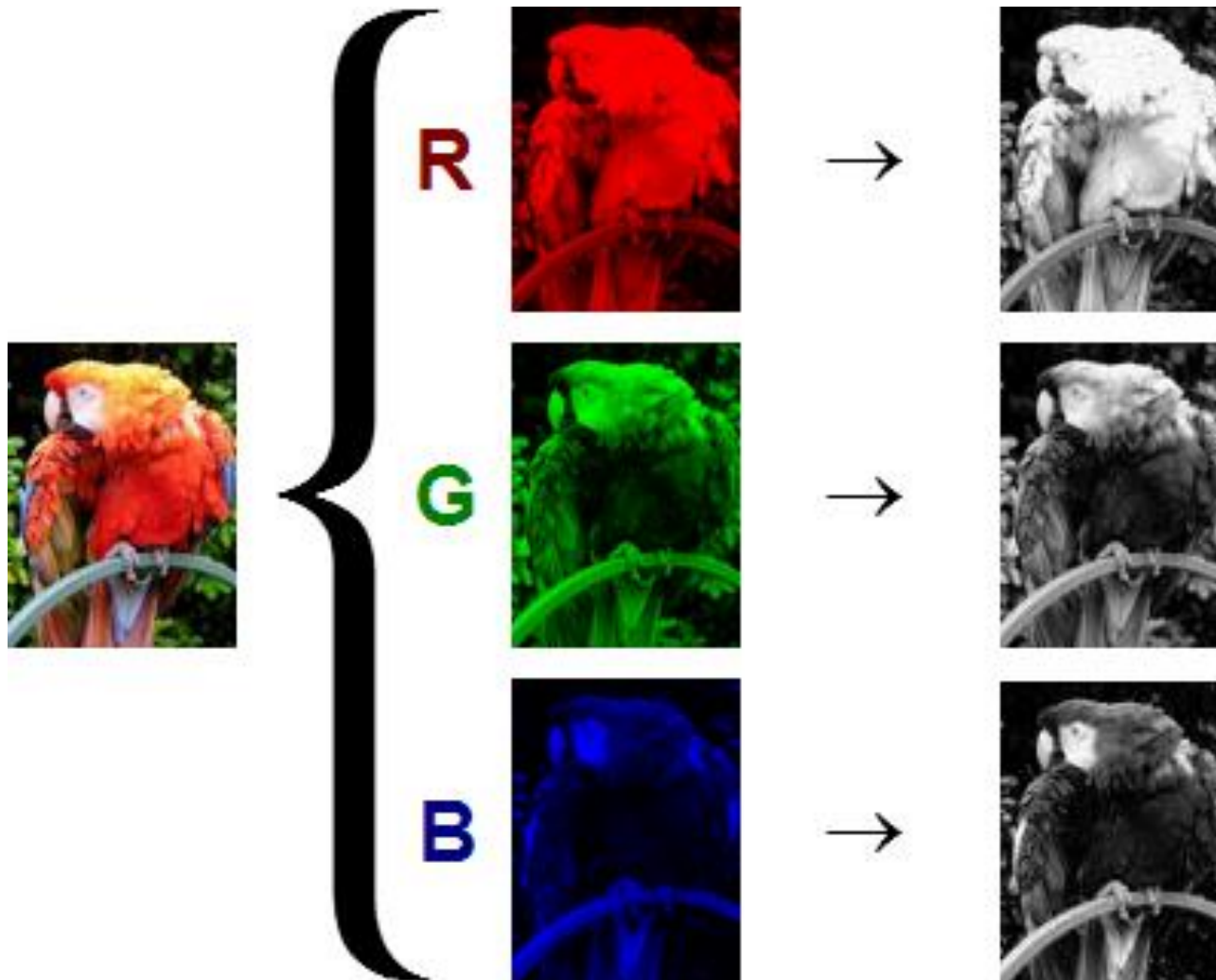


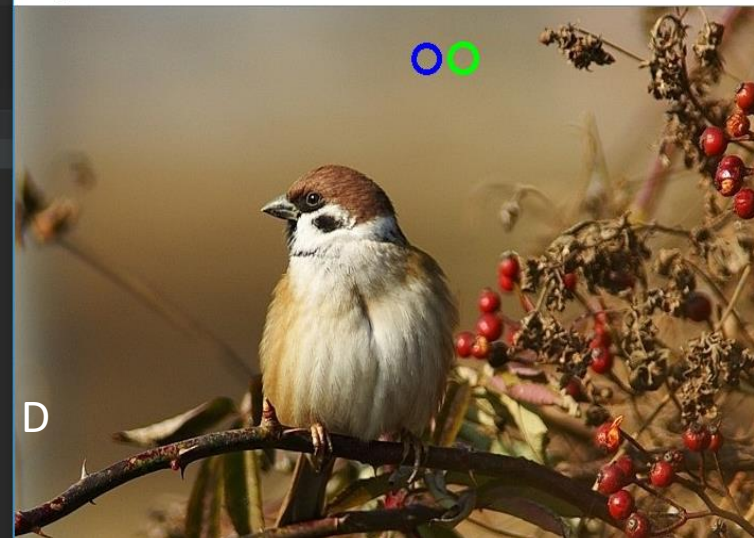
Gray image: 256x256x**1**



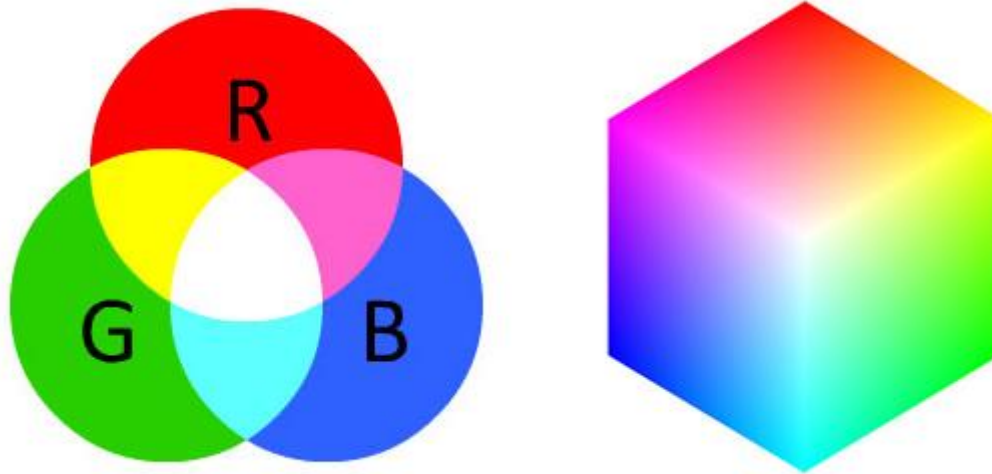
Color image: 256x256x**3**

Color image





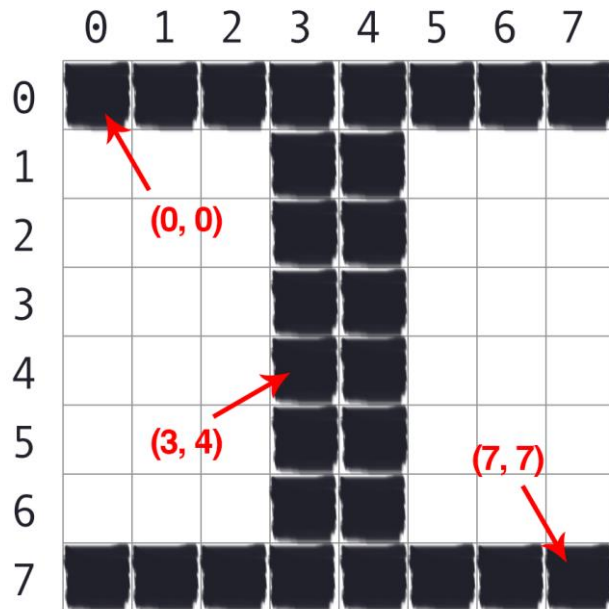
Color image



Left: The RGB color space is additive. The more red, green and blue you mix together, the closer you get to white. Right: The RGB cube.

$$\begin{array}{ccccccc} \text{Red } 252 & + & \text{Green } 198 & + & \text{Blue } 188 & = & \text{Light Pink} \\ \text{Black } 22 & + & \text{Green } 159 & + & \text{Blue } 230 & = & \text{Cyan} \end{array}$$

Image coordinate system



```
1 import cv2
2 image = cv2.imread("example.png")
3 print(image.shape)
4 cv2.imshow("Image", image)
5 cv2.waitKey(0)
```

```
1 (b, g, r) = image[20, 100] # accesses pixel at x=100, y=20
2 (b, g, r) = image[75, 25] # accesses pixel at x=25, y=75
3 (b, g, r) = image[90, 85] # accesses pixel at x=85, y=90
```

The letter “I” placed on a piece of graph paper. Pixels are accessed by their (x,y)-coordinates, where we go x columns to the right and y rows down, keeping in mind that Python is zero-indexed.

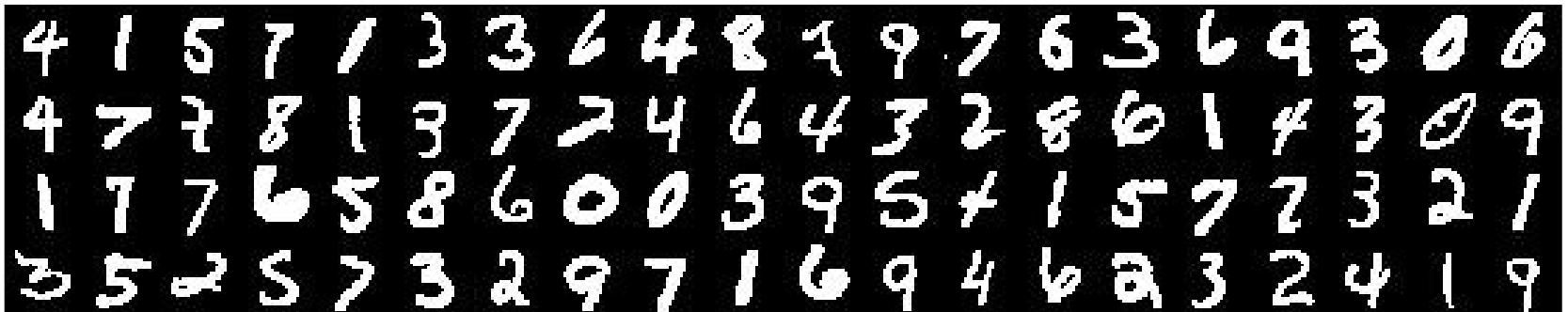
RGB and BGR ordering

- OpenCV stores RGB channels in reverse order.
 - While we normally think in terms of Red, Green, and Blue, OpenCV actually stores the pixel values in Blue, Green, Red order.
- Why does OpenCV do this?
 - The answer is simply historical reasons. Early developers of the OpenCV library chose the BGR color format **because the BGR ordering was popular among camera manufacturers** and other software developers at the time .

Datasets - MNIST

- MNIST

- A sample of the MNIST dataset. The goal of this dataset is to correctly classify the handwritten digits, 0-9.
- Consists of **60,000 training images and 10,000 testing images**.
- Each feature vector is **784-dim**, corresponding to the **28x28** grayscale pixel intensities of the image.
- These grayscale pixel intensities are **unsigned integers**, falling into the range [0~255].



Datasets - Animals

- A sample of the 3-class animals dataset consisting of 1,000 images per **dog, cat, and panda** class respectively for a total of **3,000 images**.



Datasets – CIFAR-10

- CIFAR-10 consists of **60,000**, 32x32x3 (RGB) images resulting in a feature vector dimensionality of 3072.

airplane



automobile



bird



cat



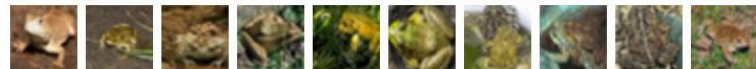
deer



dog



frog



horse



ship



truck



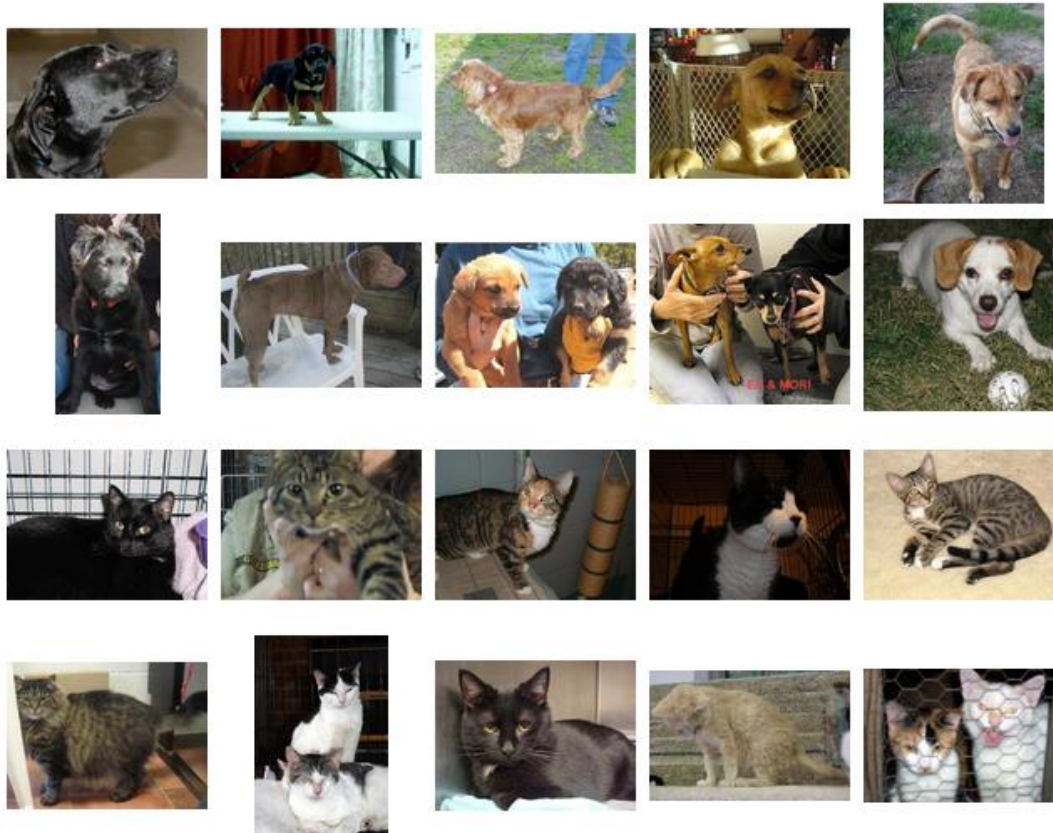
Datasets – SMILES

- SMILES dataset consists of images of faces that are either smiling or not smiling.
- In total, there are **13,165 grayscale** images in the dataset, with each image having a size of 64x64.



Datasets – Kaggle :dogs vs cats

- A total of **25,000 images** are provided to train your algorithm with **varying image resolutions**.



Datasets – flowers-17

- The Flowers-17 dataset is a 17 category dataset with **80 images per class**.



- Introduced by Fei-Fei et al. [53] in 2004, the CALTECH-101 dataset is a popular benchmark dataset for object detection.
- The dataset of **8,677 images** includes **101 categories** spanning a diverse range of objects, including elephants, bicycles, soccer balls, and even human brains, just to name a few. The CALTECH-101 dataset exhibits heavy class imbalances

Datasets – Tiny ImageNet 200



- There are a total of **200 image classes** in this dataset with **500 images for training, 50 images for validation, and 50 images for testing per class**. Each image has been preprocessed and cropped to **64x64x3** pixels making it easier for students to focus on deep learning techniques rather than computer vision preprocessing functions.

Datasets –ImageNet

- ImageNet is actually a project aimed at labeling and categorizing images into almost **22,000 categories** based on a defined set of words and phrases.
- At the time of this writing, there are over **14 million images** in the ImageNet project.

Datasets –ImageNet

- ImageNet Large Scale Visual Recognition Challenge (ILSVRC)
 - A collage of ImageNet examples put together by Stanford University.
 - This dataset is massive with over **1.2 million images and 1,000 possible object categories**.
 - ImageNet is considered the de facto standard for benchmarking image classification algorithms.



Datasets – Adience

- total of **26,580 images** are included in the dataset with ages ranging from 0-60.



Datasets - Kaggle: Facial Expression Recognition Challenge(FER)

- A total of 35,888 images are provided in the FER challenge with the goal to label a given
- facial expression into seven different categories:
 1. Angry
 2. Disgust (sometimes grouped in with “Fear” due to class imbalance)
 3. Fear
 4. Happy
 5. Sad
 6. Surprise
 7. Neutral



Datasets - Stanford Cars

- The Stanford Cars Dataset consists of **16,185 images** with **196 vehicle** make and model classes.



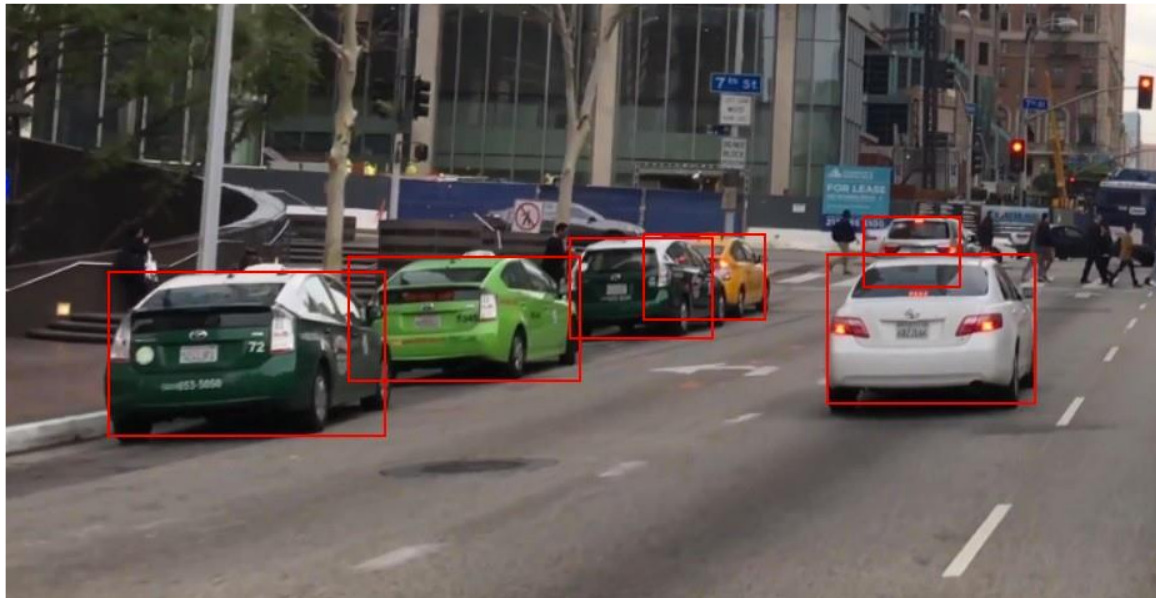
Datasets - LISA Traffic Signs

- The LISA Traffic Signs datasets consists of **47 different United States traffic signs** with **7,855 annotations over 6,610 frames**.

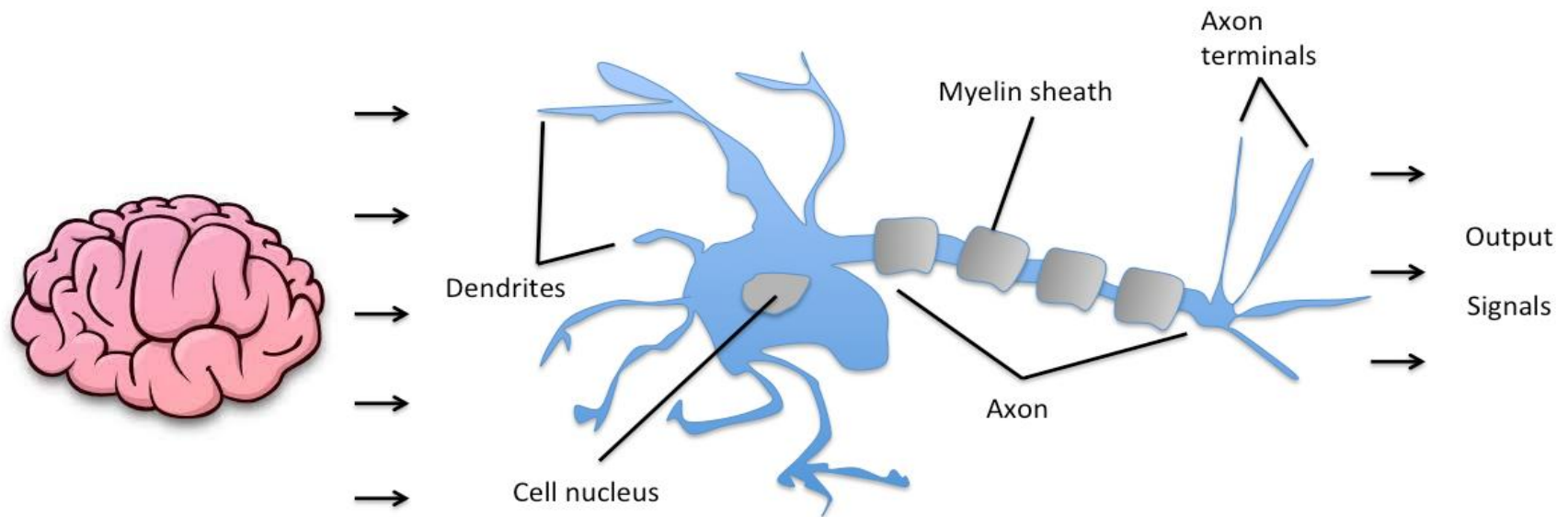


Datasets -Front/Rear View Vehicles

- The Front/Rear View Vehicles dataset comes from **Davis King's dlib library** and was hand annotated by King for usage in a demonstration of his max-margin object detection algorithm.

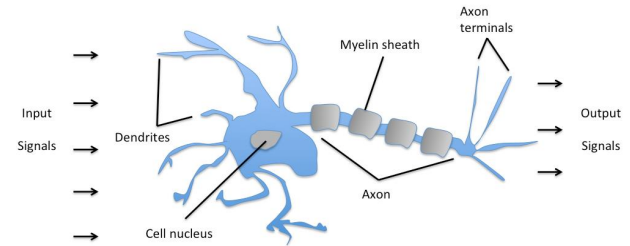


Relation to Biology

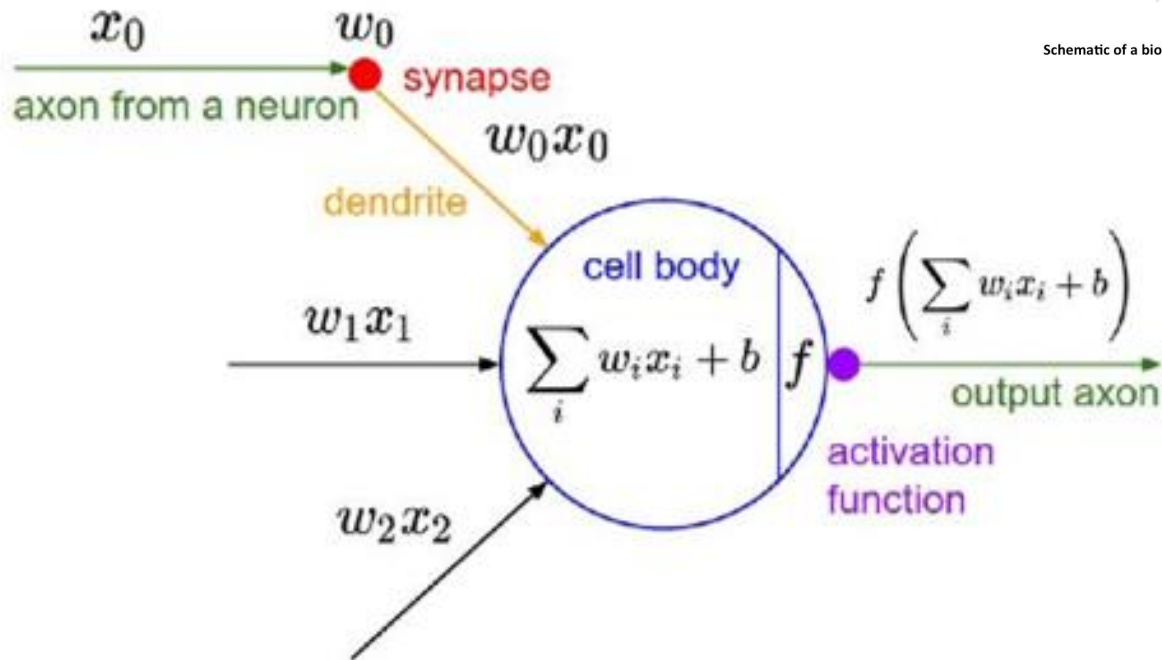


Schematic of a biological neuron.

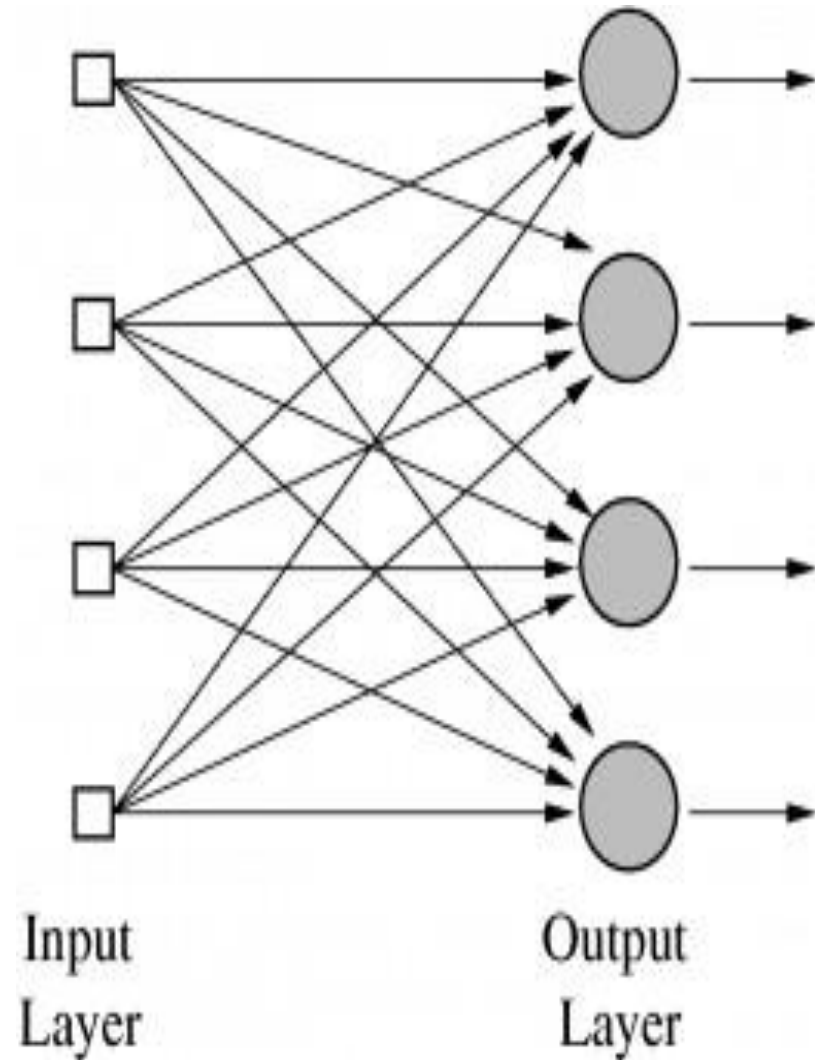
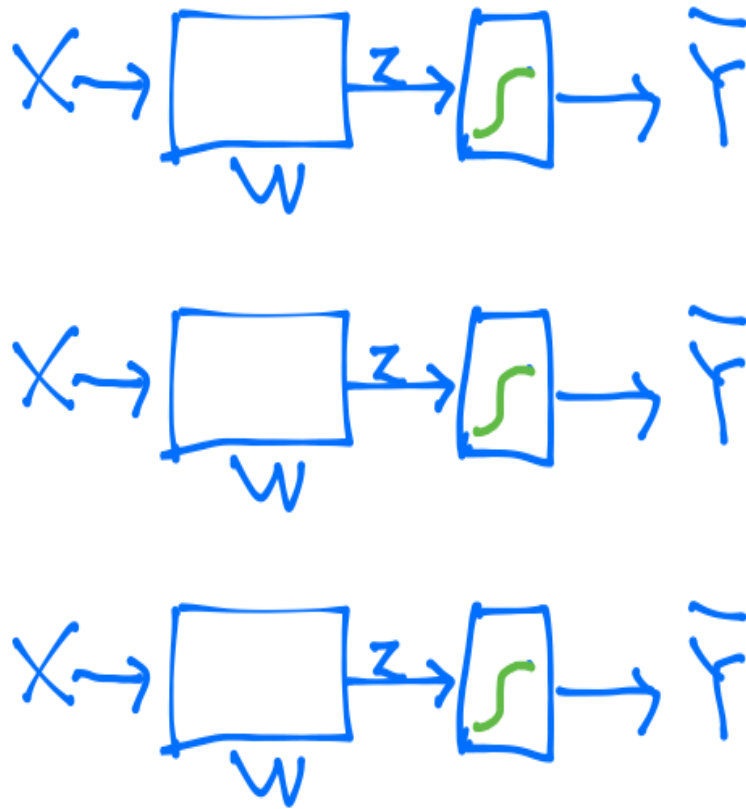
Activation functions



Schematic of a biological neuron.

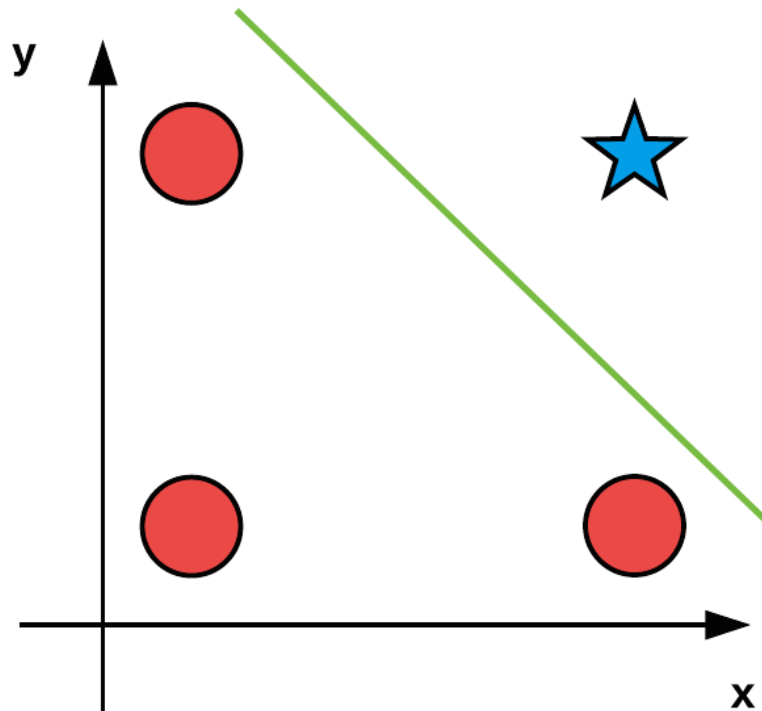


Logistic regression units

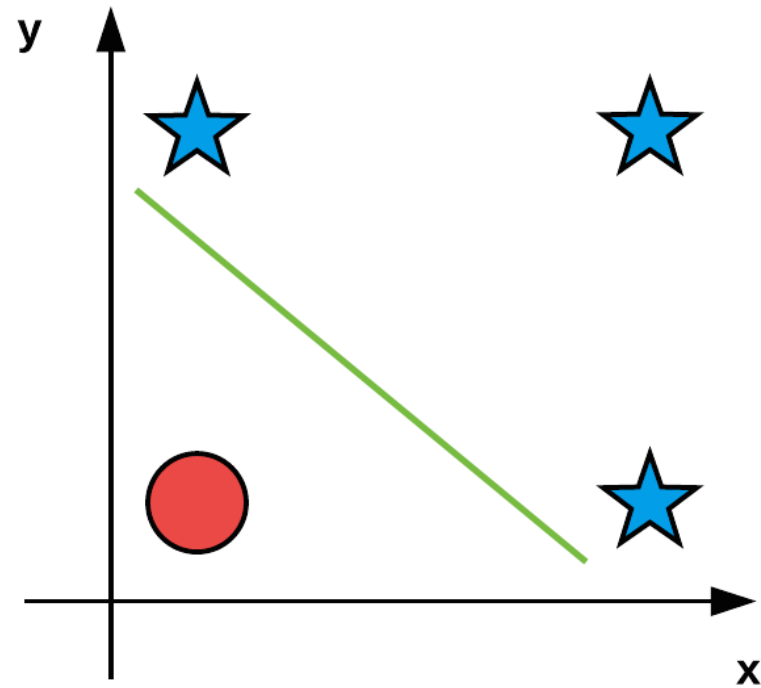


AND/OR problem: linearly separable?

AND



OR



Exercise:

- Design the model to solve the AND problem

x_0	x_1	$x_0 \& x_1$
0	0	0
0	1	0
1	0	0
1	1	1

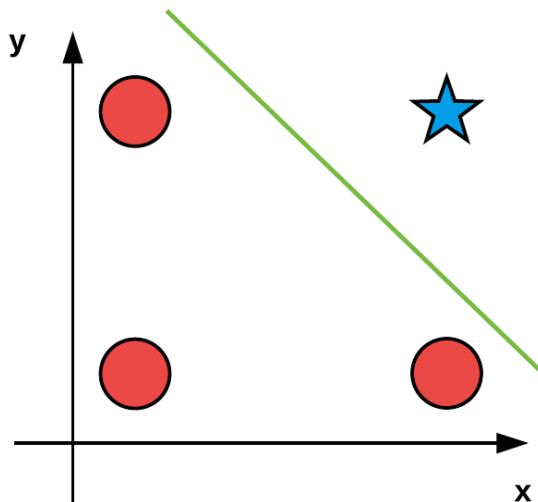
- Design the model to solve the OR problem

x_0	x_1	$x_0 x_1$
0	0	0
0	1	1
1	0	1
1	1	1

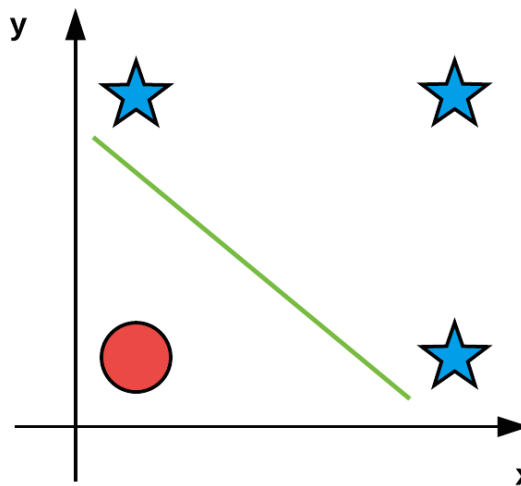
XOR problem: linearly separable?

x_0	x_1	$x_0 \wedge x_1$
0	0	0
0	1	1
1	0	1
1	1	0

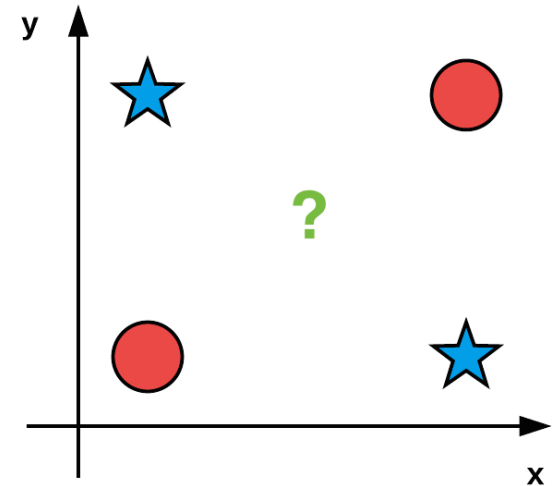
AND



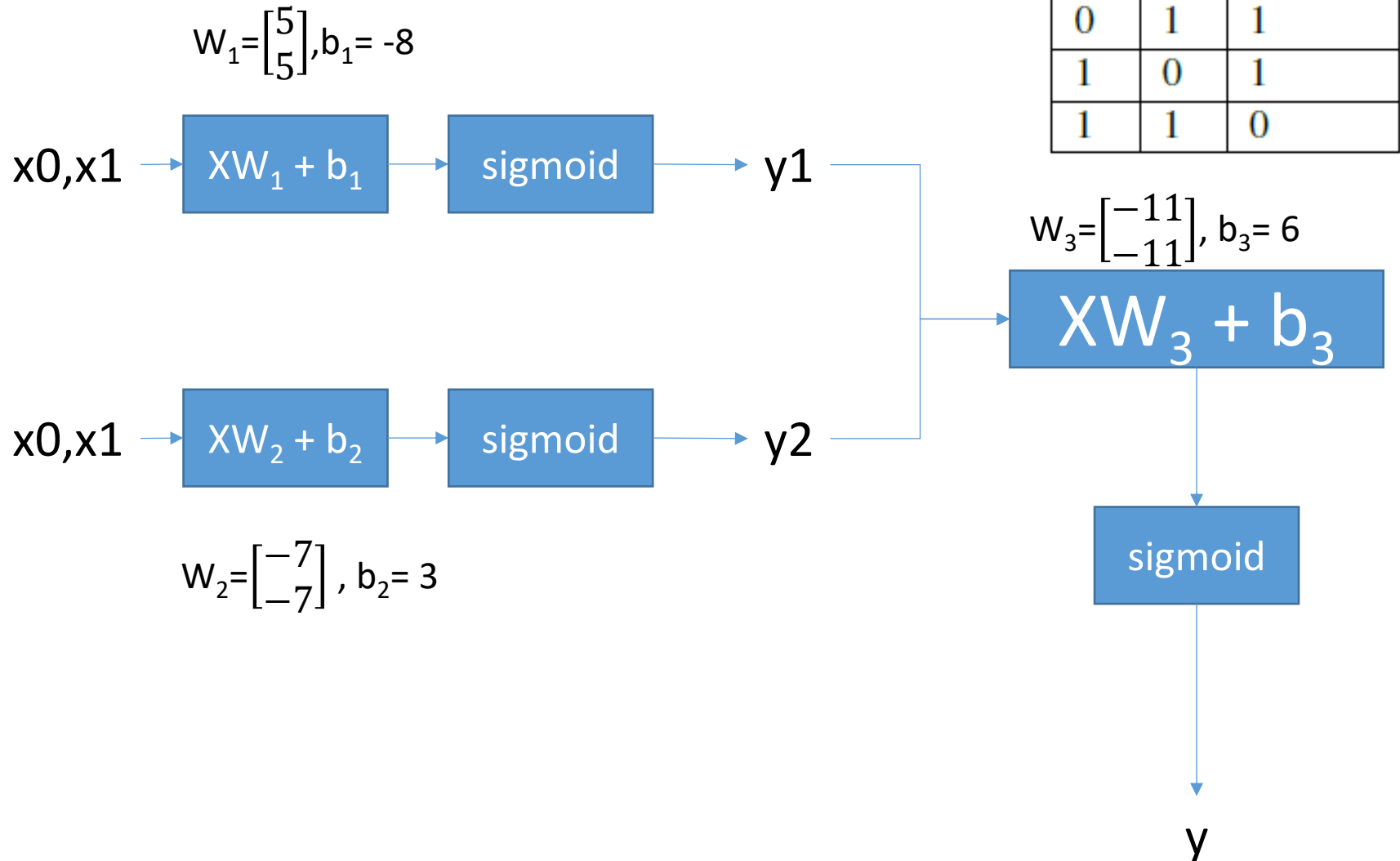
OR



XOR



Neural net to solve XOR problem

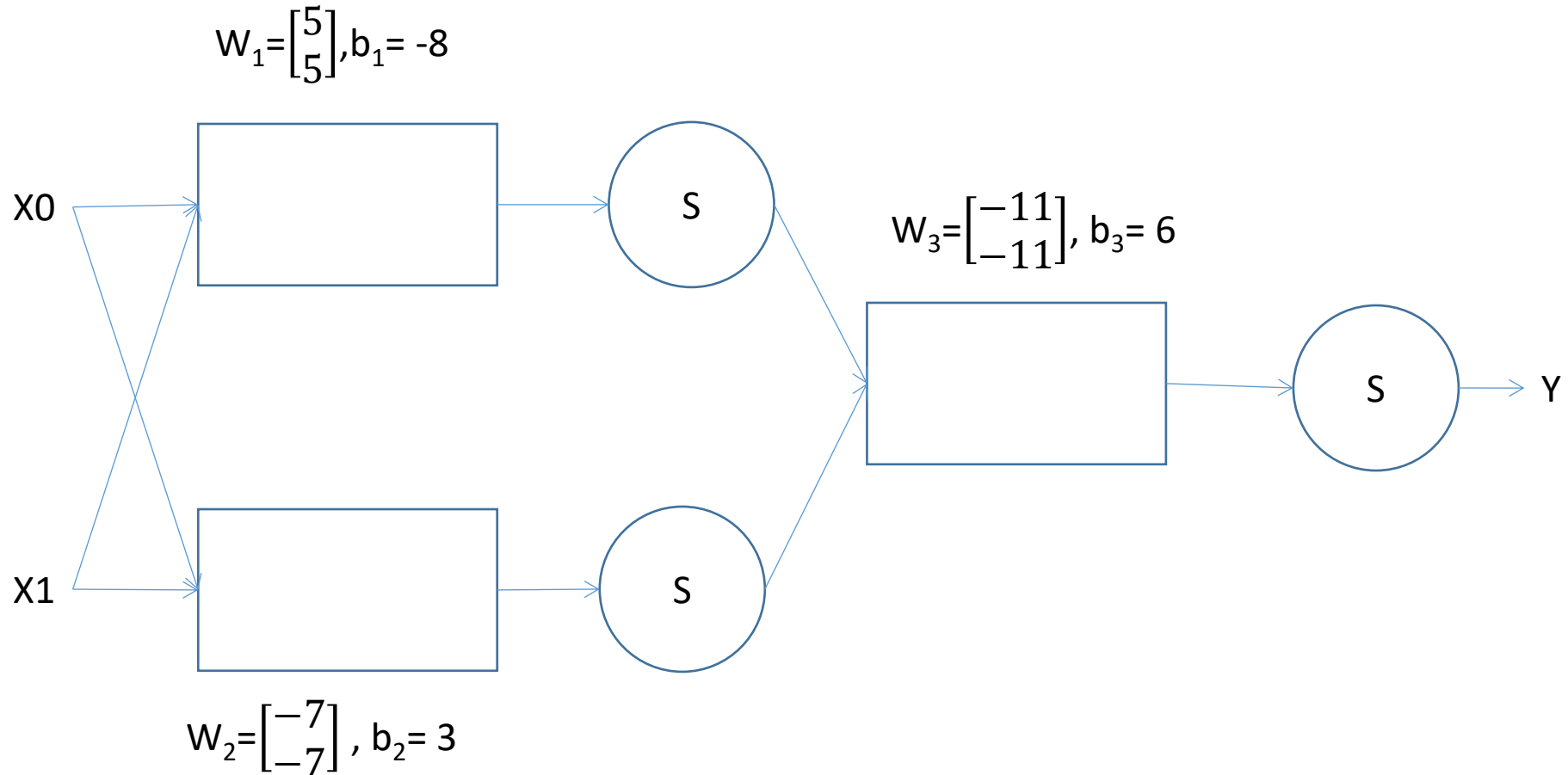


Neural net to solve XOR problem

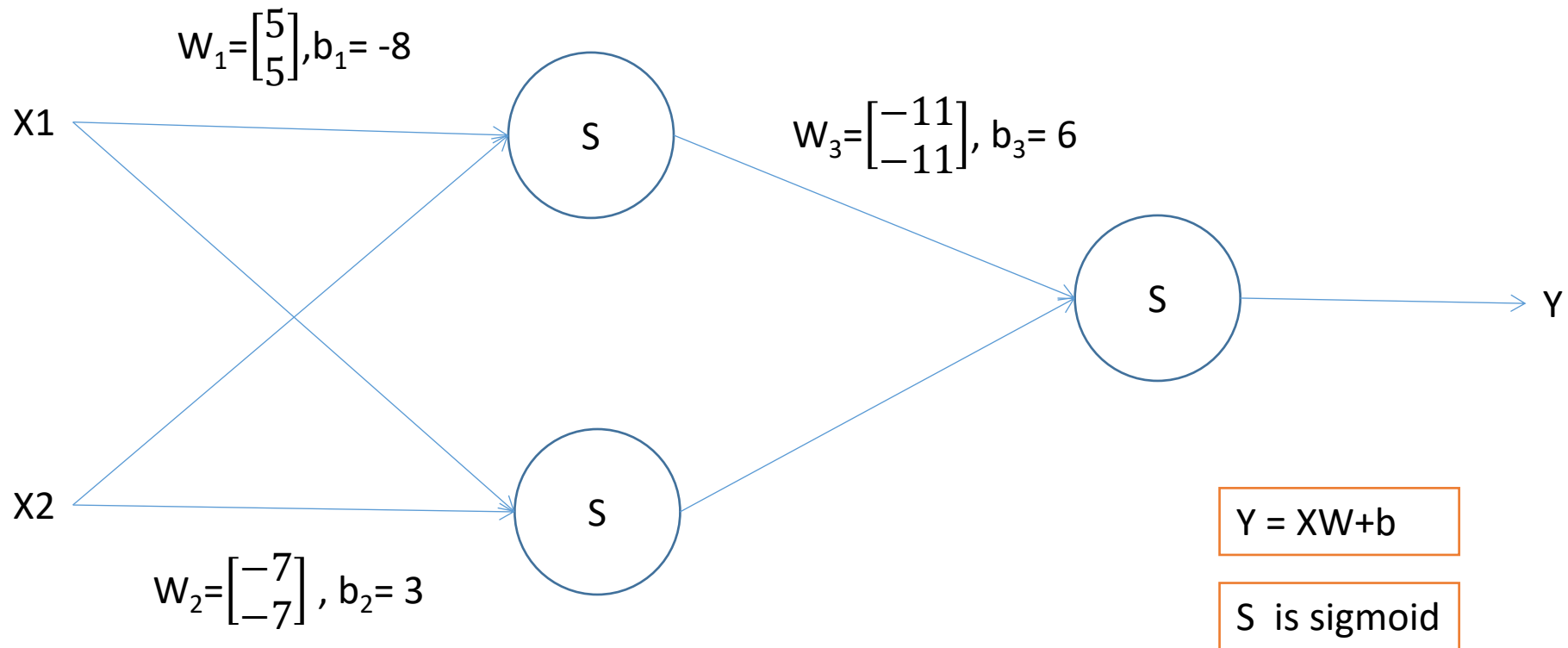


- $[x_0, x_1] = [0, 0]$
- $[x_0, x_1] = [0, 1]$
- $[x_0, x_1] = [1, 0]$
- $[x_0, x_1] = [1, 1]$

Forward propagation

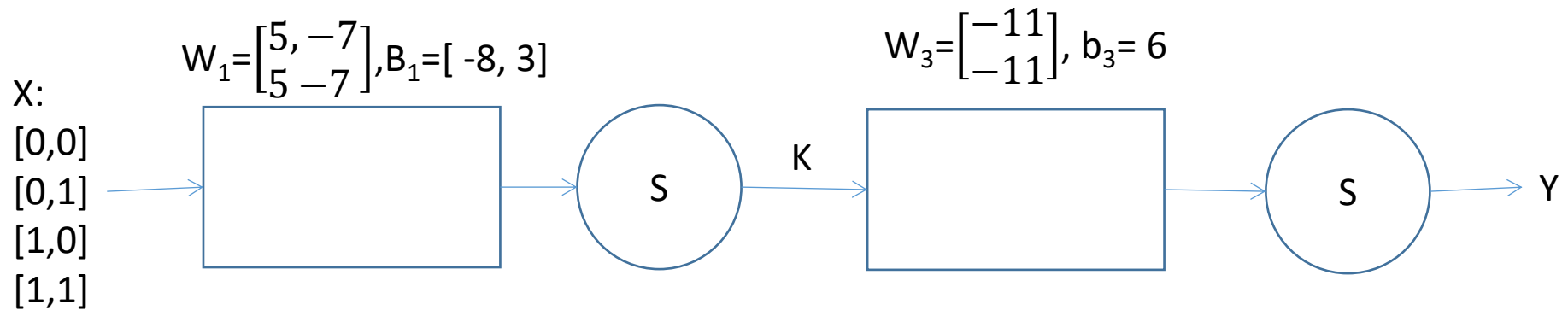


Forward propagation

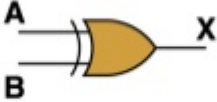


Neural network

- Matrix form



XOR data set

Boolean Expression	Logic Diagram Symbol	Truth Table															
$X = A \oplus B$		<table><tr><th>A</th><th>B</th><th>X</th></tr><tr><td>0</td><td>0</td><td>0</td></tr><tr><td>0</td><td>1</td><td>1</td></tr><tr><td>1</td><td>0</td><td>1</td></tr><tr><td>1</td><td>1</td><td>0</td></tr></table>	A	B	X	0	0	0	0	1	1	1	0	1	1	1	0
A	B	X															
0	0	0															
0	1	1															
1	0	1															
1	1	0															

```
x_data = np.array([[0, 0], [0, 1], [1, 0], [1, 1]], dtype=np.float32)
y_data = np.array([[0], [1], [1], [0]], dtype=np.float32)
```

Pytorch practice 1: XOR with logistic regression



```
x_data = np.array([[0, 0], [0, 1], [1, 0], [1, 1]], dtype=np.float32)
y_data = np.array([[0], [1], [1], [0]], dtype=np.float32)
```

```
X = Variable(torch.from_numpy(x_data))
Y = Variable(torch.from_numpy(y_data))
```

```
# Hypothesis using sigmoid
linear = torch.nn.Linear(2, 1, bias=True)
sigmoid = torch.nn.Sigmoid()
model = torch.nn.Sequential(linear, sigmoid)
```

```
optimizer = torch.optim.SGD(model.parameters(), lr=0.1)
```

```
for step in range(10001):
    optimizer.zero_grad()
    hypothesis = model(X)
    # cost/loss function
    cost = -(Y * torch.log(hypothesis) + (1 - Y)
            * torch.log(1 - hypothesis)).mean()
    cost.backward()
    optimizer.step()
```

```
if step % 100 == 0:
    print(step, cost.data.numpy())
```

```
# Accuracy computation
# True if hypothesis>0.5 else False
predicted = (model(X).data > 0.5).float()
accuracy = (predicted == Y.data).float().mean()
print("\nHypothesis: ", hypothesis.data.numpy(), "\nCorrect: ", predicted.numpy(), "\nAccuracy: ", accuracy)
```

```
Hypothesis: [[ 0.49999997]
[ 0.5      ]
[ 0.5      ]
[ 0.5      ]]
Correct: [[ 0.]
[ 0.]
[ 0.]
[ 0.]]
Accuracy: 0.5
```

Pytorch practice2: XOR with Neural Network



```
x_data = np.array([[0, 0], [0, 1], [1, 0], [1, 1]], dtype=np.float32)
y_data = np.array([[0], [1], [1], [0]], dtype=np.float32)
```

```
X = Variable(torch.from_numpy(x_data))
Y = Variable(torch.from_numpy(y_data))
```

```
linear1 = torch.nn.Linear(2, 2, bias=True)
linear2 = torch.nn.Linear(2, 1, bias=True)
sigmoid = torch.nn.Sigmoid()
model = torch.nn.Sequential(linear1, sigmoid, linear2, sigmoid)
```

```
optimizer = torch.optim.SGD(model.parameters(), lr=0.1)
```

```
for step in range(10001):
    optimizer.zero_grad()
    hypothesis = model(X)
    # cost/loss function
    cost = -(Y * torch.log(hypothesis) + (1 - Y)
            * torch.log(1 - hypothesis)).mean()
    cost.backward()
    optimizer.step()
```

```
if step % 100 == 0:
    print(step, cost.data.numpy())
```

```
# Accuracy computation
# True if hypothesis>0.5 else False
predicted = (model(X).data > 0.5).float()
accuracy = (predicted == Y.data).float().mean()
print("\nHypothesis: ", hypothesis.data.numpy(), "\nCorrect: ", predicted.numpy(), "\nAccuracy: ", accuracy)
```

```
Hypothesis: [[ 0.0216833 ]
[ 0.97211885]
[ 0.97253156]
[ 0.04630803]]
Correct: [[ 0.]
[ 1.]
[ 1.]
[ 0.]]
Accuracy: 1.0
```


Pytorch practice2: XOR with Neural Network

```
x_data = np.array([[0, 0], [0, 1], [1, 0], [1, 1]], dtype=np.float32)
y_data = np.array([[0], [1], [1], [0]], dtype=np.float32)
```

```
X = Variable(torch.from_numpy(x_data))
Y = Variable(torch.from_numpy(y_data))
```

```
linear1 = torch.nn.Linear(2, 2, bias=True)
linear2 = torch.nn.Linear(2, 1, bias=True)
sigmoid = torch.nn.Sigmoid()
model = torch.nn.Sequential(linear1, sigmoid, linear2, sigmoid)
```

```
optimizer = torch.optim.SGD(model.parameters(), lr=0.1)
```