```python
#********************* Set vehicle's start position for parking maneuver ***************

def parking_preparation():
 vehicle.apply_control(carla.VehicleControl(throttle=0.4));
 sensor_obstacle_rightSide.listen(lambda data: detect_non_players(data));

def detect_non_players(data):
    current_vhcl = data.other_actor.id;
    if config.nonplayer != current_vhcl and current_vhcl != 0:
      config.count += 1;
      config.nonplayer = current_vhcl;

    if config.count == 3:
      print('time of parking');
      frontDistance=data.distance;
      sensor_obstacle_rearRight.listen(lambda data: stablePosition(frontDistance, data));

    def stablePosition(frontDistance, event):
      if event.distance == frontDistance:
        vehicle.applyControl(carla.VehicleControl(throttle=0.0,steer=0.0));
        parking_maneuver();
```