

# - Module 9 -

## $k$ -Nearest Neighbors

### Outline

- $k$ -Nearest Neighbors
  - Distance Metrics
  - Effects of  $k$
- Classifier Performance Metrics

# $k$ -Nearest Neighbors (1)

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- $k$ -Nearest Neighbors ( $k$ -NN) is a **non-parametric, instance-based** learning algorithm
  - non-parametric: it does not make explicit assumptions about the form of the mapping function,  $h(X): X \rightarrow Y$   
(as opposed to parametric techniques, e.g., linear regression,  $h(X): Y = X\beta$ )
  - instance-based: it does not explicitly learn a model, i.e., there is no training stage  
(instead, the training samples are only used during the prediction stage)
- $k$ -NN can be used for classification and regression
  - ➔ for this course, focus on multiclass classification where the input features can have continuous or discrete values

## $k$ -Nearest Neighbors (2)

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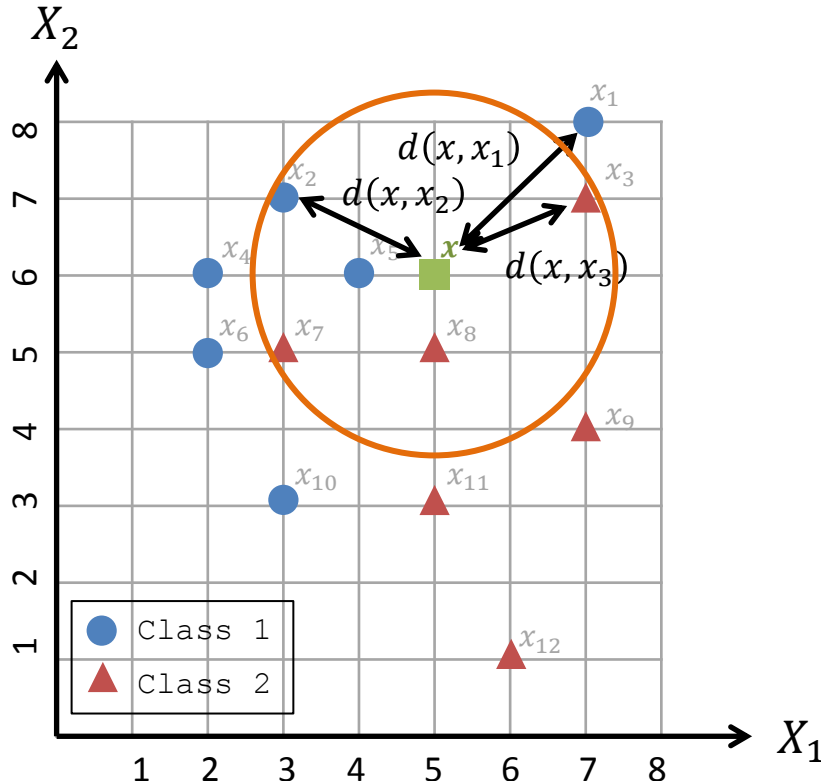
- Steps to use  $k$ -NN for classification,  $kNN(x, \mathcal{T}, k)$ , given
  - a test sample,  $x$
  - a training set,  $\mathcal{T}$       consists of the training samples,  $(x_i, y_i)$  for  $i = 1, \dots, N$
  - a positive integer,  $k$
  - a **distance metric**,  $d(x, x_i)$       measures the distance between  $x$  and  $x_i \forall i = 1, \dots, N$
- Step 1:** For each training sample  $x_i \forall i = 1, \dots, N$ , compute the distance,  $d(x, x_i)$ , between  $x$  and  $x_i$
- Step 2:** Order the training samples by increasing distance
- Step 3:** Select the first  $k$  training samples that have the smallest  $d(x, x_i)$ , i.e.,  $k$  nearest neighbors of  $x$
- Step 4:** Determine the predicted value  $\hat{y}$  of  $x$  by majority vote, i.e., most commonly occurring class of the  $k$  nearest neighbors  
(Note:  $k$  is usually an odd number to avoid ties)

# $k$ -Nearest Neighbors: Example (3)

## Example:

Consider the following training samples.

Classify test sample  $x$  using 5-NN.



5 nearest  
neighbors

$d(x, x_1) = 2.83$	$d(x, x_5) = 1.00$
$d(x, x_2) = 2.24$	$d(x, x_8) = 1.00$
$d(x, x_3) = 2.24$	$d(x, x_2) = 2.24$
$d(x, x_4) = 3.00$	$d(x, x_3) = 2.24$
$d(x, x_5) = 1.00$	$d(x, x_7) = 2.24$
$d(x, x_6) = 3.16$	$d(x, x_1) = 2.83$
$d(x, x_7) = 2.24$	$d(x, x_9) = 2.83$
$d(x, x_8) = 1.00$	$d(x, x_4) = 3.00$
$d(x, x_9) = 2.83$	$d(x, x_{11}) = 3.00$
$d(x, x_{10}) = 3.61$	$d(x, x_6) = 3.16$
$d(x, x_{11}) = 3.00$	$d(x, x_{10}) = 3.61$
$d(x, x_{12}) = 5.10$	$d(x, x_{12}) = 5.10$

sort

Majority  
vote

$x \rightarrow$  Class 2

# $k$ -Nearest Neighbors: Distance Metrics (4)

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- The distance metrics,  $d(x, x')$ , where  $x$  and  $x'$  are vectors of  $p$  features indexed by  $j$ , for  $j = 1, \dots, p$ , are computed as follows:

- for continuous features

- $L^2$  norm (Euclidean distance):

$$d(x, x') = \sqrt{\sum_{j=1}^p (x_j - x'_j)^2}$$

- $L^1$  norm (Manhattan distance):


$$d(x, x') = \sum_{j=1}^p |x_j - x'_j|$$

- for categorical features

- Hamming distance:

$$d(x, x') = \sum_{j=1}^p I(x_j \neq x'_j)$$

Indicator function:  
 $I(\text{condition})$   
 $= \begin{cases} 1, & \text{if condition} = \text{true} \\ 0, & \text{otherwise} \end{cases}$



# $k$ -Nearest Neighbors: Distance Metrics (5)

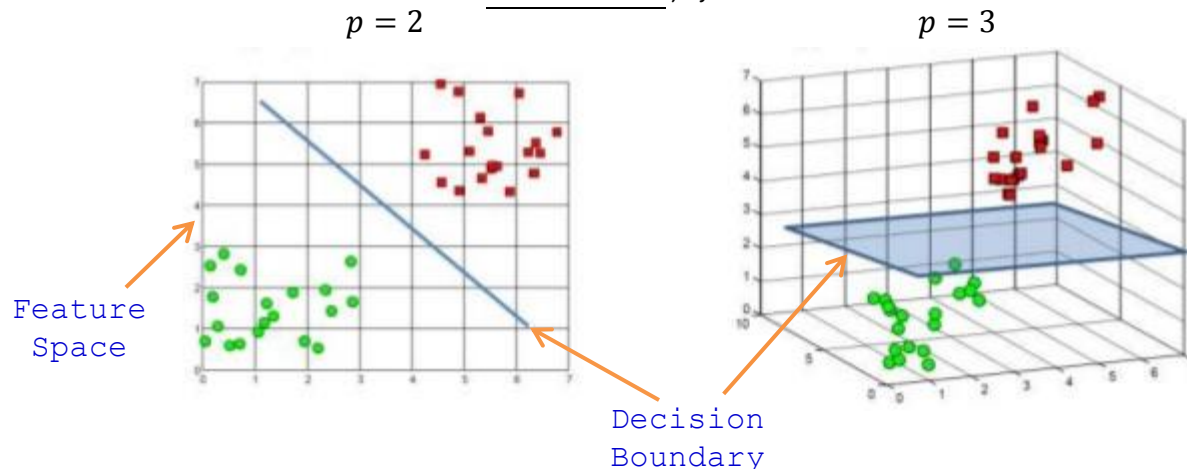
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- Note that the distance metric is dependent on the scales of the features  
(e.g., if a feature changes measurements from centimeters to miles while keeping other features the same, a different set of nearest neighbors will be selected)
- ➔ to avoid this, it is common to standardize each feature  $j$ , i.e.,  $x_{i,j}$  is replaced with  $(x_{i,j} - \mu_j)/\sigma_j$ , before performing  $k$ -NN

# $k$ -Nearest Neighbors: Effects of $k$ (6)

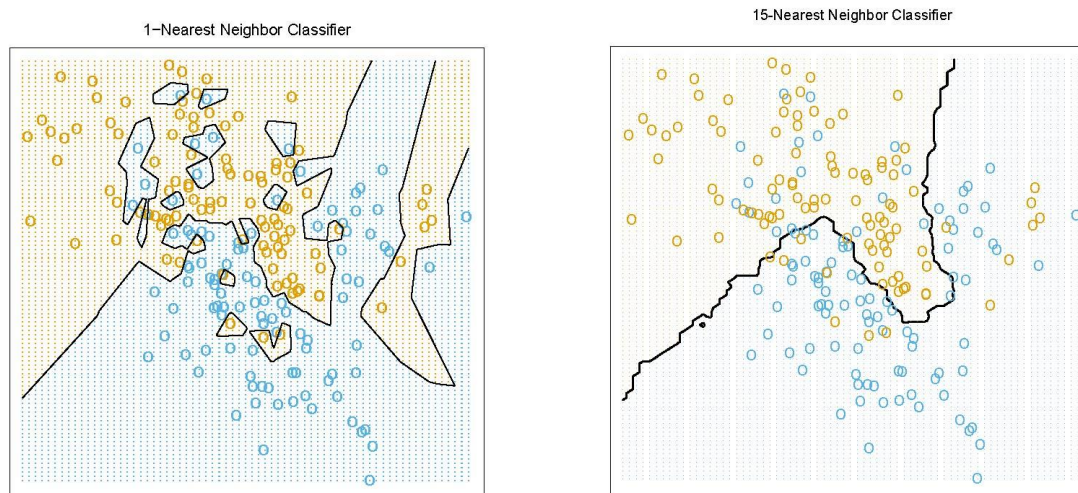
- In  $k$ -NN, the parameter,  $k$ , is a tuning parameter that controls the smoothness of the **decision boundary** of a  $k$ -NN classifier and its fit for the given dataset

{decision boundary: partition the **feature space** (space spanned by possible values of  $X_1, X_2, \dots, X_p$ ) into  $C$  non-overlapping regions, one for each class (e.g., lines for two-dimensional ( $p = 2$ ) input vectors or hyper-surfaces for higher-dimensional ( $p > 2$ ) input vectors) }



# $k$ -Nearest Neighbors: Effects of $k$ (7)

- When  $k$  is small,  $k$ -NN has high flexibility but highly sensitive to outliers
  - exhibit overfitting (i.e., low bias and high variance) and the decision boundary is more jagged
- When  $k$  is large,  $k$ -NN is more resilient to outliers but has lower flexibility
  - exhibit underfitting (i.e., high bias and low variance) and the decision boundary is more smooth



➔ the best value of  $k$  is chosen using cross-validation, i.e., select  $k$  that gives the lowest average cross-validation estimate of prediction error



# $k$ -Nearest Neighbors: Cross-Validation (8)

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- $K$ -fold cross-validation for  $k$ -NN:
  - Step 1:** Sub-divide the training set into  $K$  non-overlapping subsets of equal size
  - Step 2:** For each trial  $q = 1, \dots, K$ 
    - all subsets except the  $q$ -th subset is used as the training set,  $\mathcal{T}_q$ , and the  $q$ -th subset is used as the validation set,  $\mathcal{V}_q$
    - for each sample  $x_i$  in  $\mathcal{V}_q$ 
      - perform  $kNN(x_i, \mathcal{T}_q, k)$  to obtain the predicted value,  $\hat{y}_i$
    - compute the cross-validation estimate of prediction error (or **misclassification rate**) for trial  $q$ :

$$Err_{CV}^q = \frac{\sum_{i=1}^{|\mathcal{V}_q|} I(y_i \neq \hat{y}_i)}{|\mathcal{V}_q|},$$

where  $|\mathcal{V}_q|$  denotes the number of samples in  $\mathcal{V}_q$

# $k$ -Nearest Neighbors: Cross-Validation (9)

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**Step 3:** Compute the average cross-validation estimate of prediction error,  $Err_{CV}$ , across  $K$  trials

$$Err_{CV} = \frac{1}{K} \sum_{q=1}^K Err_{CV}^q$$

- To determine the best value of  $k$  (in  $k$ -NN), repeat steps 1 to 3 for all considered  $k$  values and select  $k$  that gives the lowest average cross-validation estimate of prediction error,  $Err_{CV}$

# $k$ -Nearest Neighbors:

## Advantages and Limitations (10)

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- **Advantages** of  $k$ -NN:

- easy to implement
- ability to achieve good classification performance when the training set is large
- works with multiclass datasets

- **Limitations** of  $k$ -NN:

- prediction stage is computationally intensive as the algorithm has to iterate through all samples in the training set
  - ➔ often an issue where the training set is very large
- high memory requirement as it has to store all of the training samples all the time
- unable to provide information as to whether a feature is more informative than another

# Classifier Performance Metrics (1)

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- How to assess the performance of a classifier?
  - **Accuracy:** percentage of correct classifications
  - **Error Rate:** percentage of misclassifications ( $1 - \text{Accuracy}$ )
- However, accuracy or error rate assume equal costs for misclassification, but this assumption is often not valid for real applications
  - **Example:** Spam filter
    - cost of misclassifying a spam e-mail as a legitimate e-mail  
→ **LOW**
    - cost of misclassifying a legitimate e-mail as a spam e-mail  
→ **HIGH**
  - **Example:** Medical screening
    - cost of misclassifying a healthy person as a potential cancer patient → **LOW**
    - cost of misclassifying a potential cancer patient as a healthy person → **HIGH**
- Need to differentiate different kinds of misclassifications → **Confusion Matrix**

# Classifier Performance Metrics (2)

- Confusion matrix

- **True Positives (TP)**: actual class of a sample is positive and the predicted class is also positive

(e.g., the person has cancer and the classifier also indicates that the person has cancer)

- **True Negatives (TN)**: actual class of a sample is negative and the predicted class is also negative

(e.g., the person does not have cancer and the classifier also indicates that the person does not have cancer)

- **False Positives (FP)**: actual class of a sample is negative but the predicted class is positive

(e.g., the person does not have cancer but the classifier indicates that the person has cancer)

- **False Negatives (FN)**: actual class of a sample is positive but the predicted class is negative

(e.g., the person has cancer but the classifier indicates that the person does not have cancer)

		Predicted	
		Positive	Negative
Actual	Positive	# of <b>True Positives</b> (TP)	# of <b>False Negatives</b> (FN)
	Negative	# of <b>False Positives</b> (FP)	# of <b>True Negatives</b> (TN)

(false positive)



(false negative)



# Classifier Performance Metrics (3)

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- Different performance metrics can be calculated from the confusion matrix:

- $Accuracy = \frac{TP+TN}{TP+TN+FP+FN} = \frac{TP+TN}{total}$

- $Precision = \frac{TP}{TP+FP} = \frac{TP}{predicted\ positive}$

- $Sensitivity/Recall = \frac{TP}{TP+FN} = \frac{TP}{actual\ positive}$

- $Specificity = \frac{TN}{TN+FP} = \frac{TN}{actual\ negative}$

- $False\ Positive\ Rate = \frac{FP}{TN+FP} = \frac{FP}{actual\ negative}$   
 $= 1 - specificity$

- $False\ Negative\ Rate/MissRate = \frac{FN}{FN+TP}$   
 $= \frac{FN}{actual\ positive}$