

# Greedy Algorithms: Dijkstra's Algorithm

Textbook: Chapter 9.3

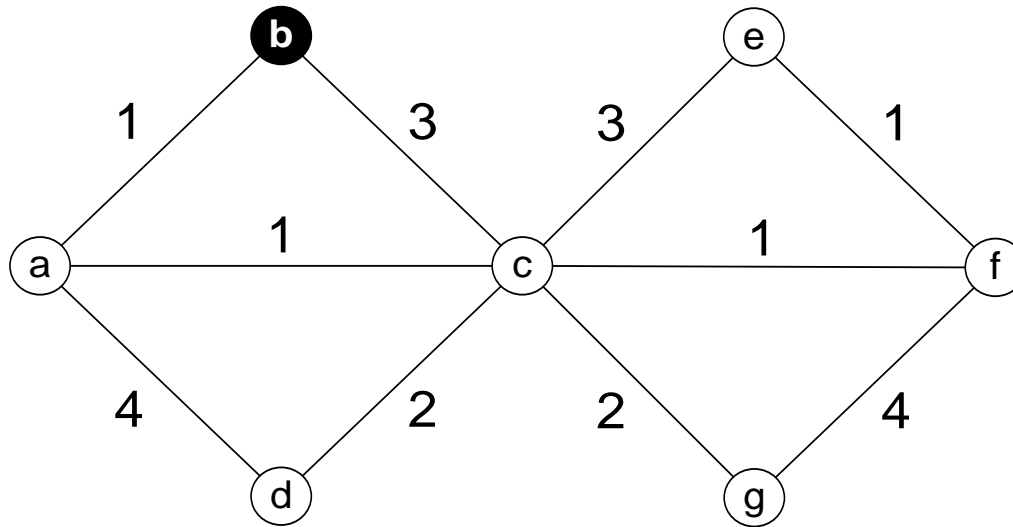
# Context

- This is one of several “greedy algorithms” we will examine:
  - Minimum Spanning Tree of a graph
    - Prim’s algorithm
    - Kruskal’s algorithm
  - Shortest Paths from a Single Source in a graph
    - Dijkstra’s algorithm
  - Graph coloring

# Problem:

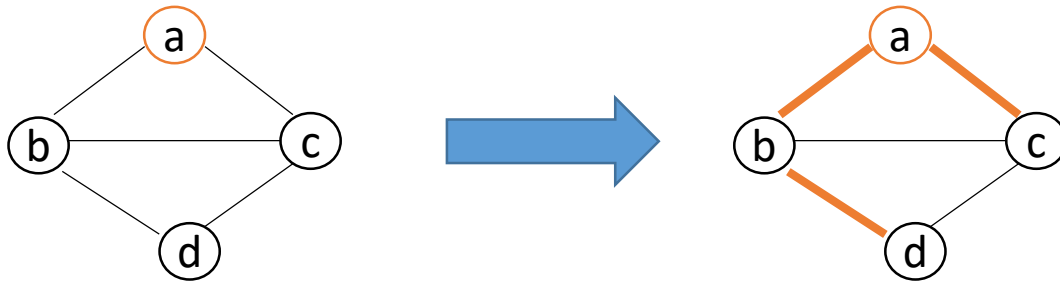
## Single-source Shortest Paths

- Find the shortest path from a chosen vertex (the *source*) to every other vertex

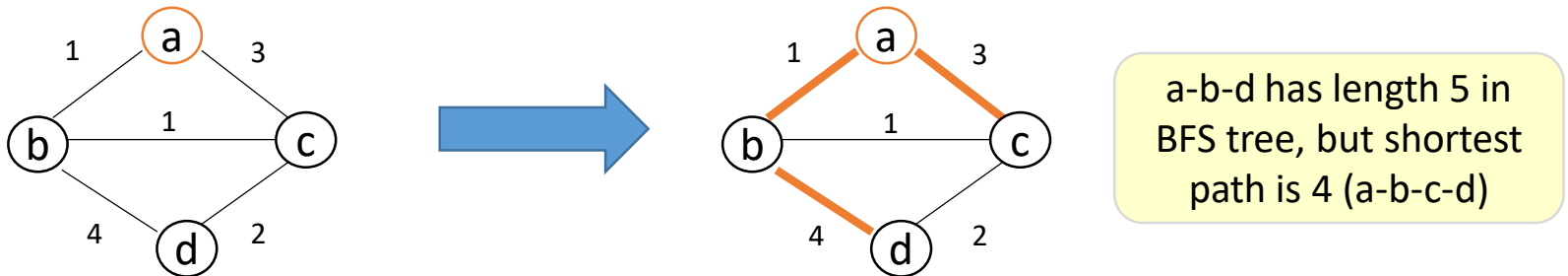


# What about BFS?

- Simple/basic BFS already does this for an unweighted graph:



- ... but not for weighted graphs. Consider the distance between a and d:



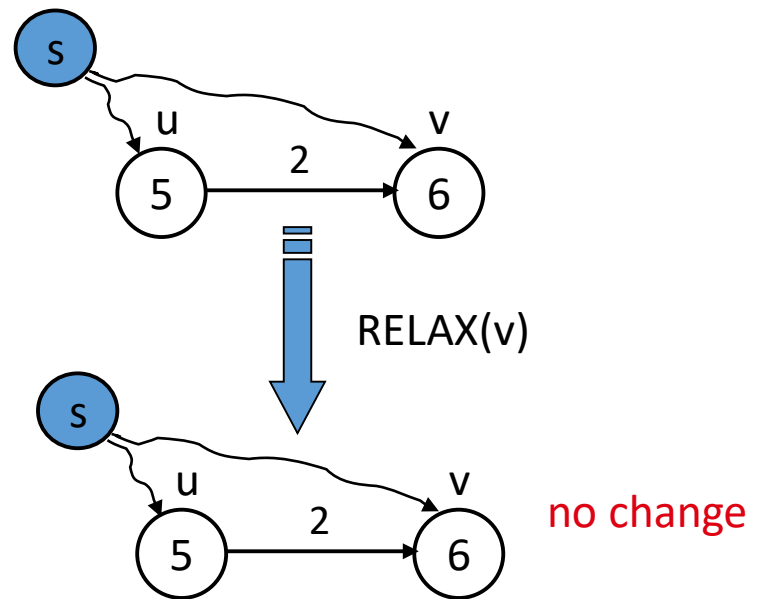
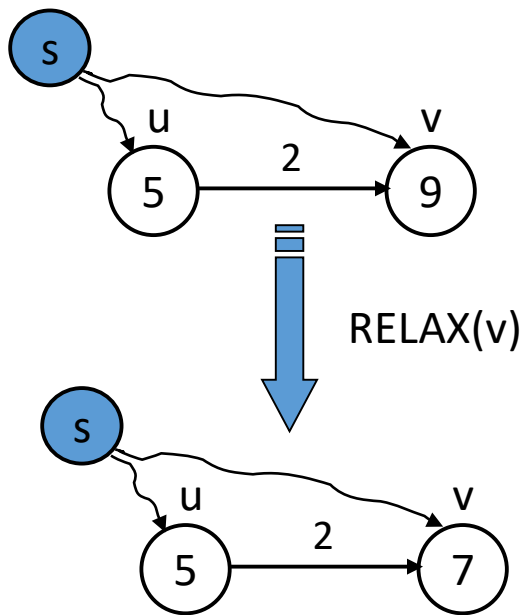
- Algorithm to find shortest paths in weighted graphs needs to consider the weight on the edge before including it in the solution*

# Idea of Dijkstra's algorithm

- Remember the best-known shortest distances for all vertices
  - Initially “infinity” for all
- Choose the nearest unprocessed vertex
  - Definition of “nearest” tbd
- Look at all of its neighbors
- Update their known shortest distances (“Relax”)
- Repeat

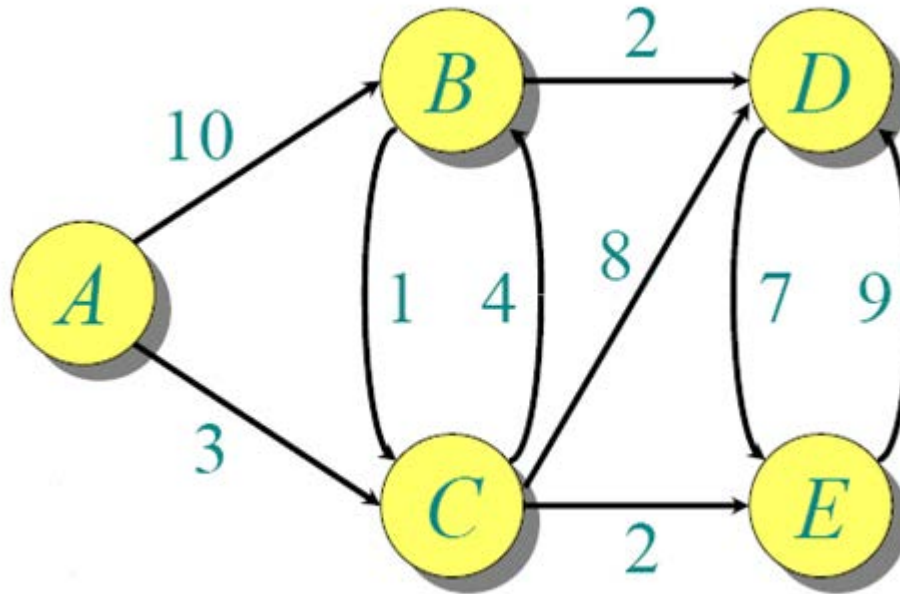
# Relaxation

- Dijkstra refers to “relaxing” a vertex
- Meaning: update the best known shortest path to  $v$



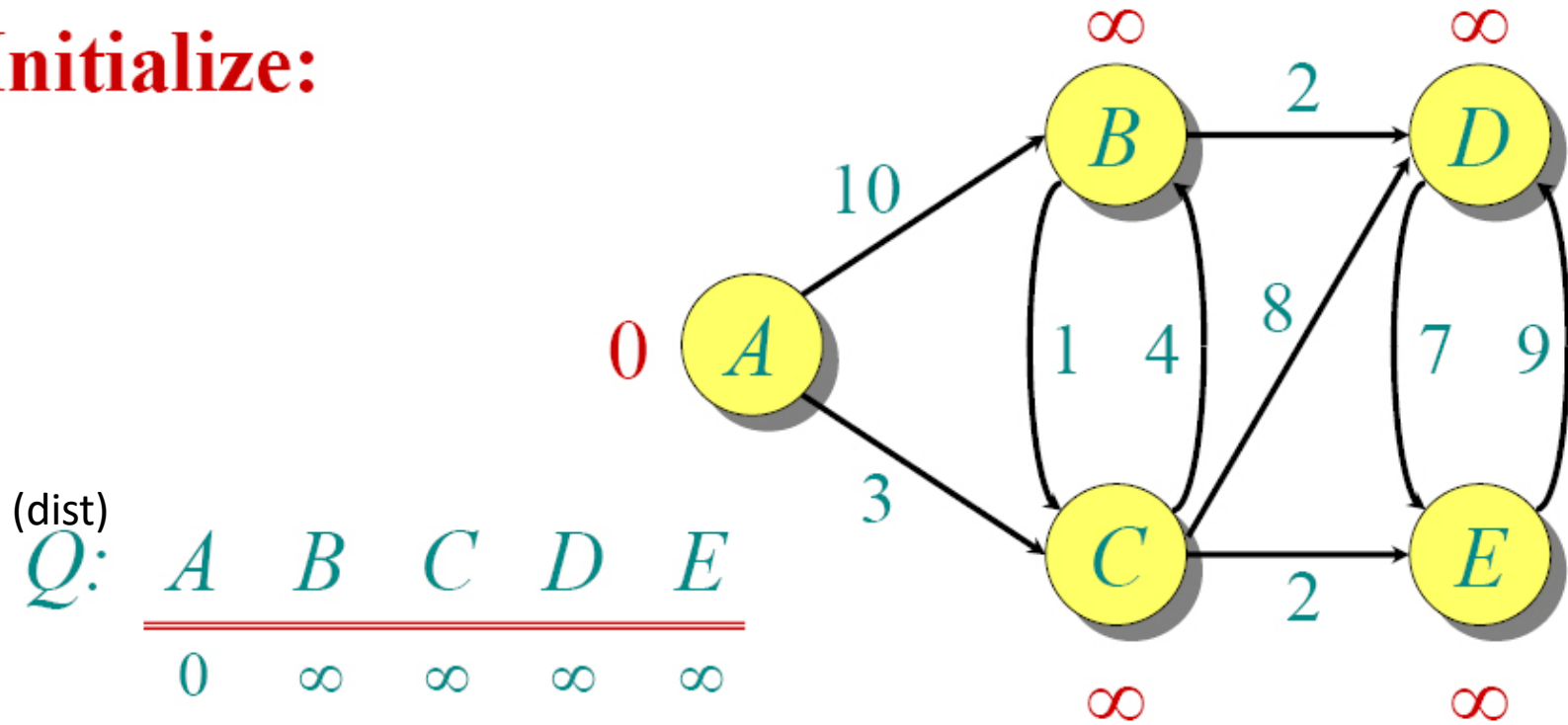
# Dijkstra Example

Find the shortest paths from A to all other vertices



# Dijkstra Example

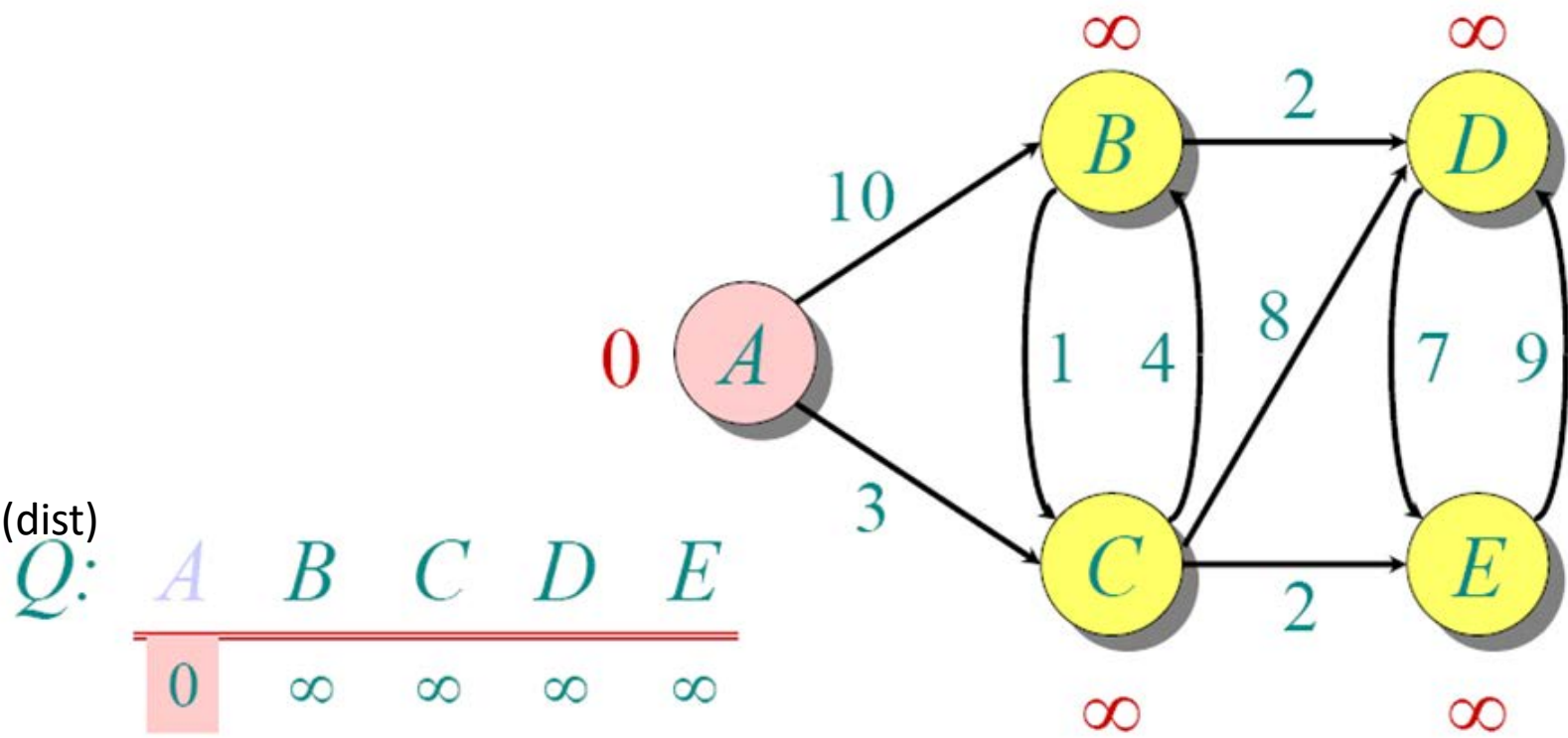
**Initialize:**



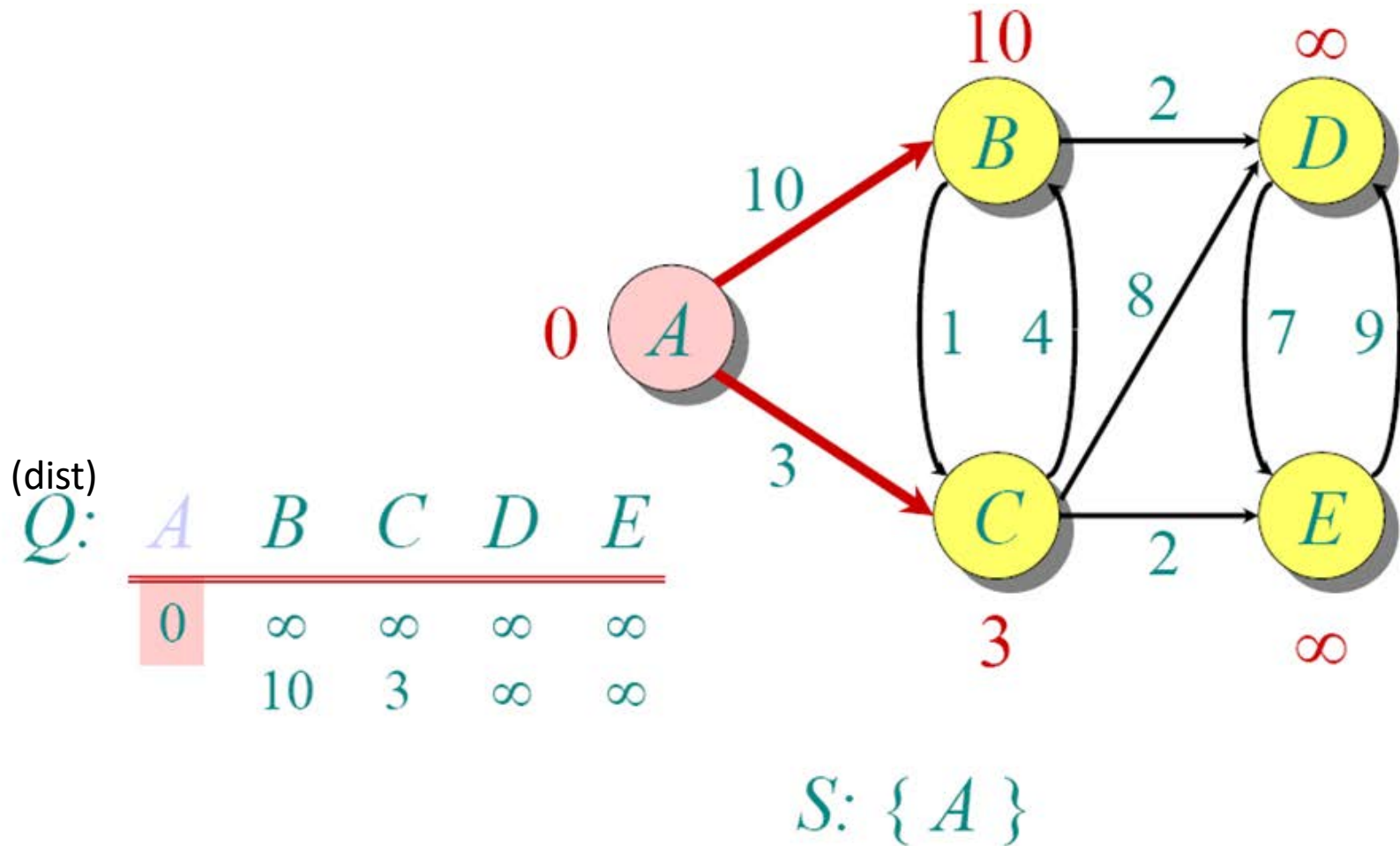
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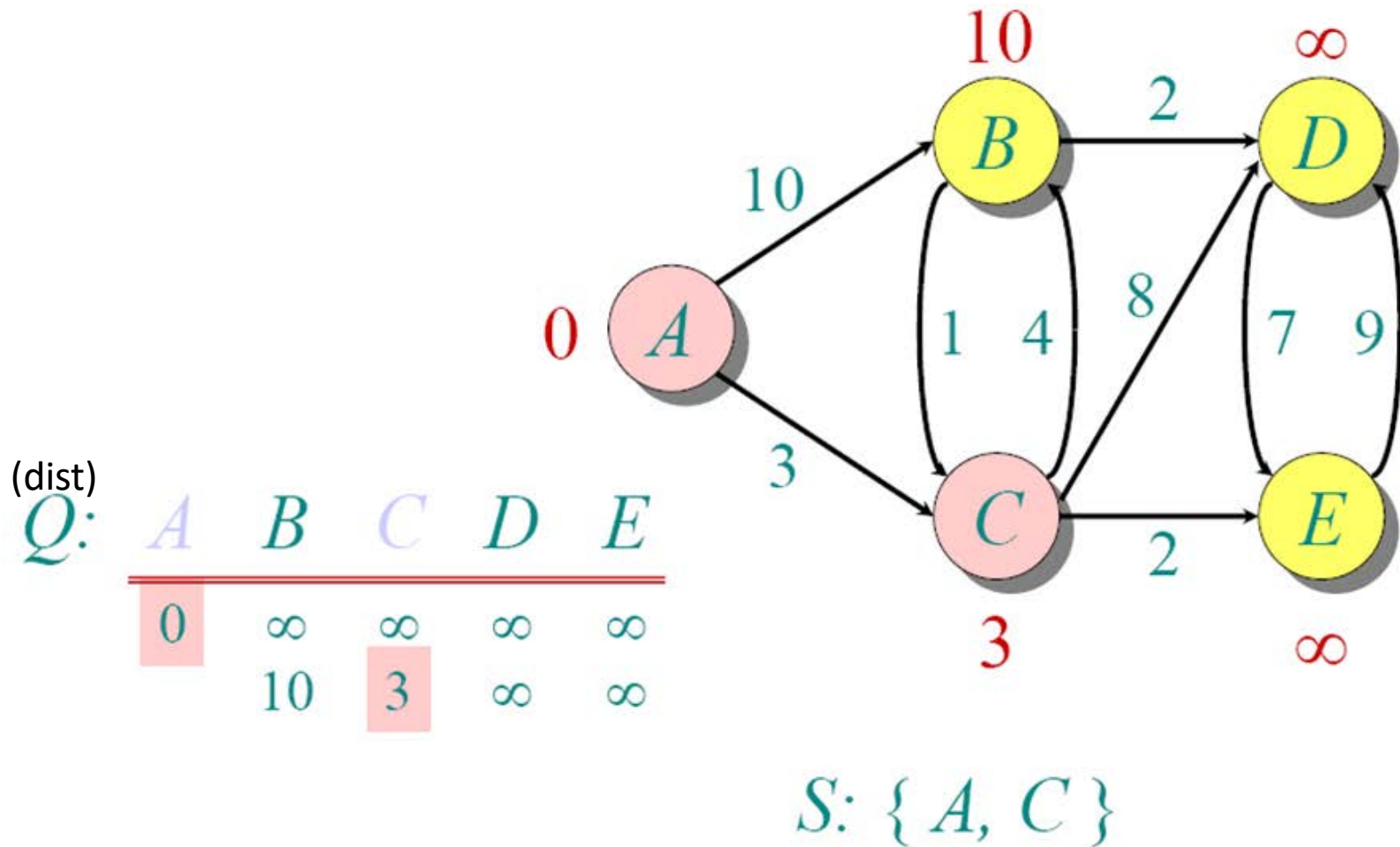
# Dijkstra Example



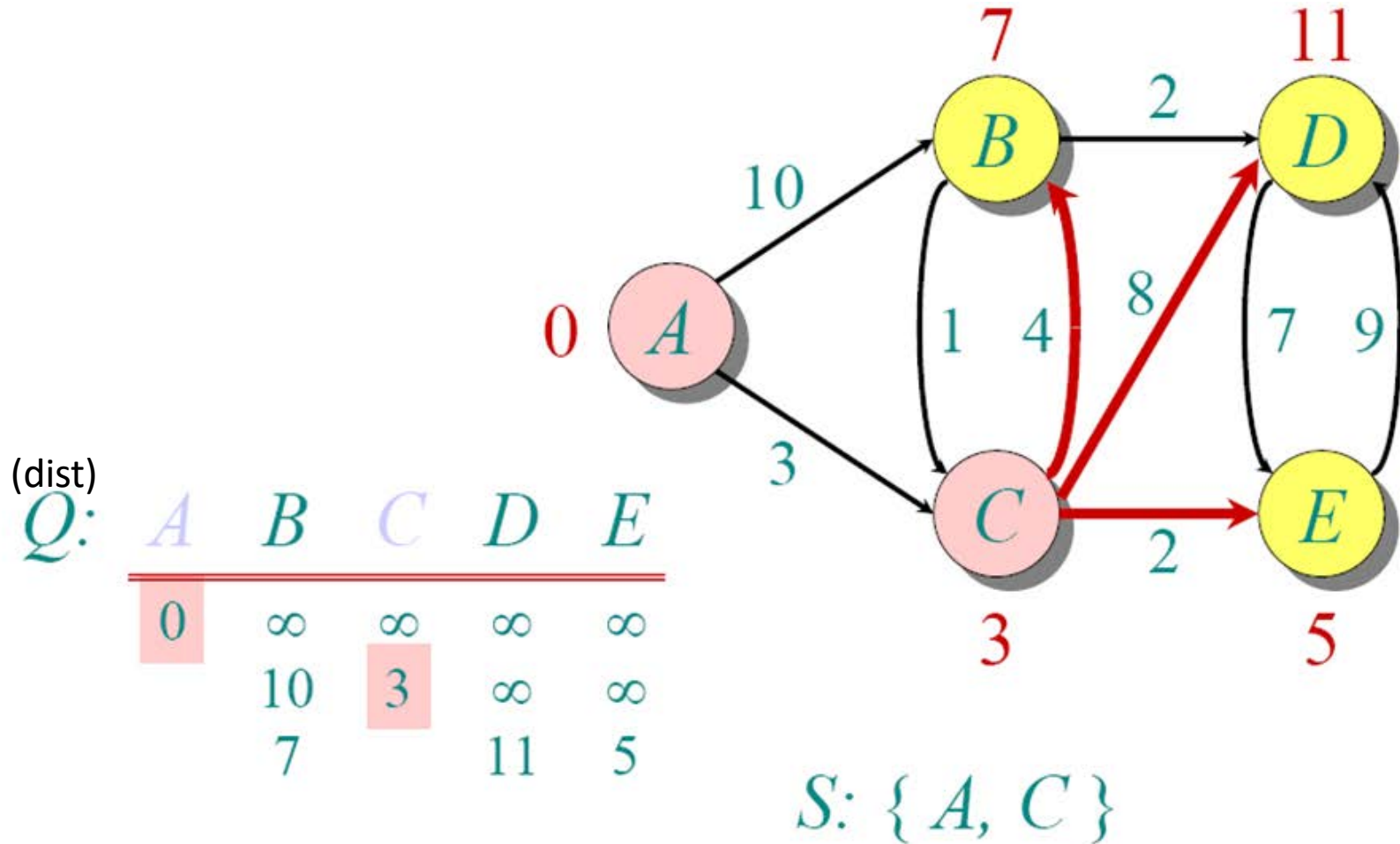
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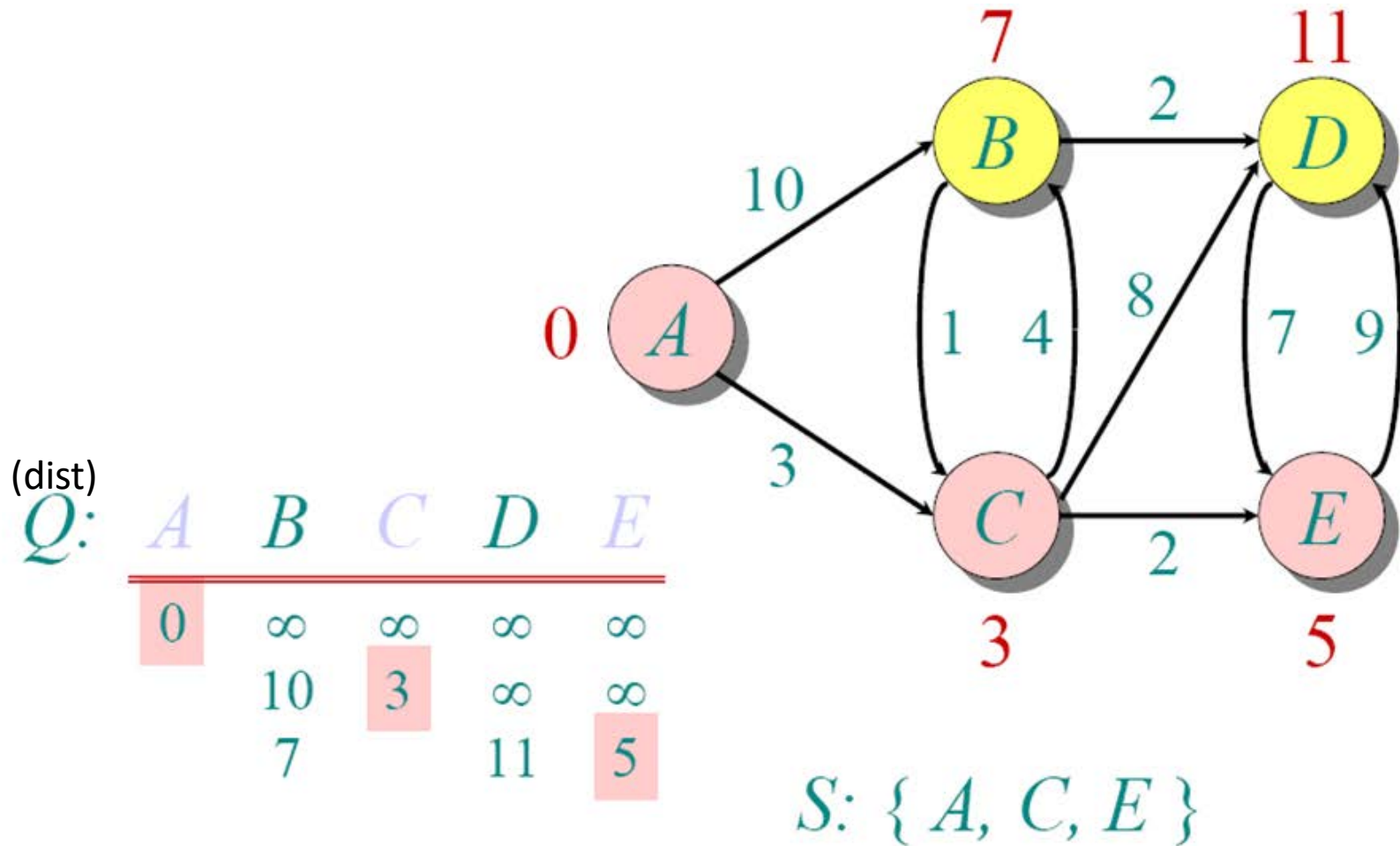
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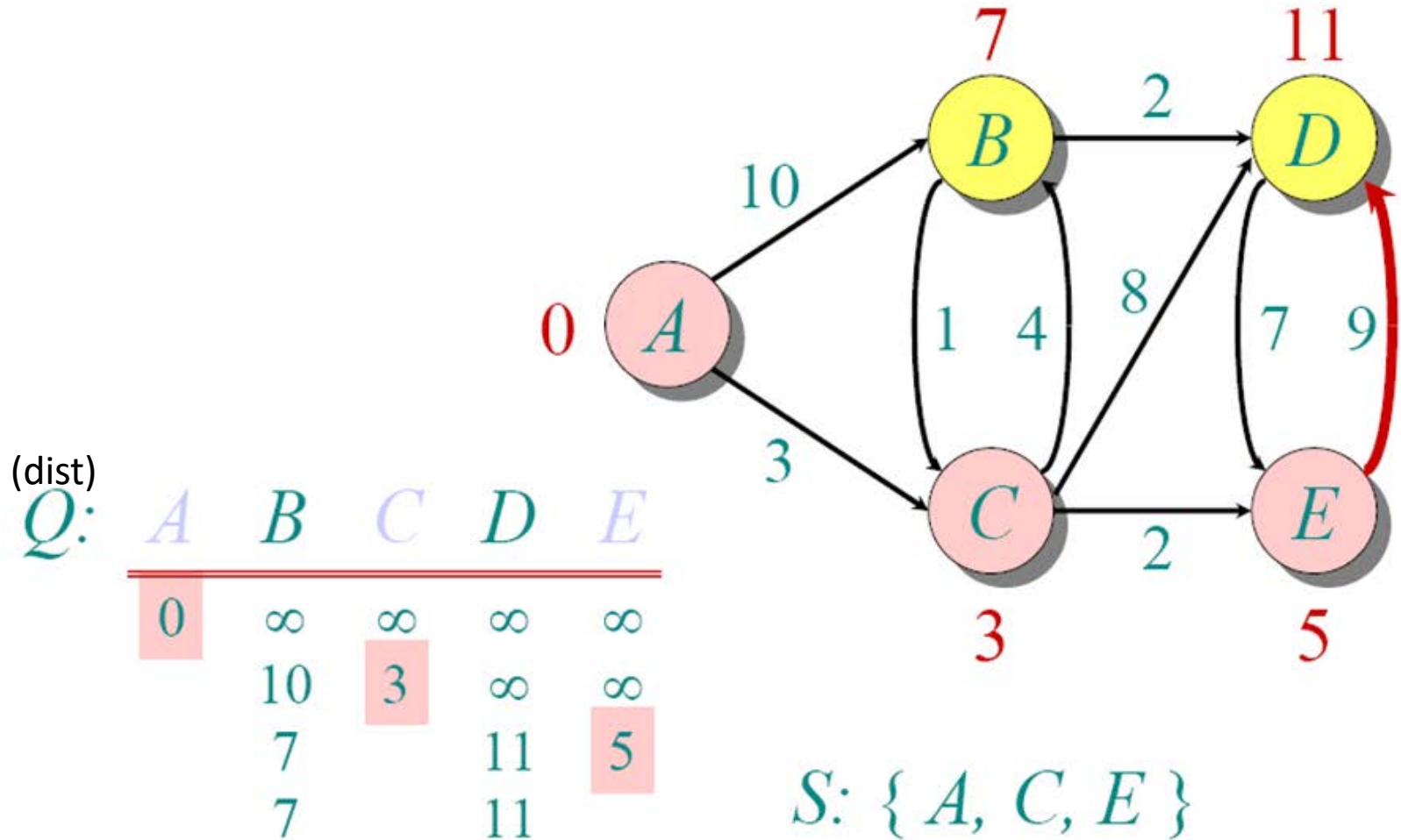
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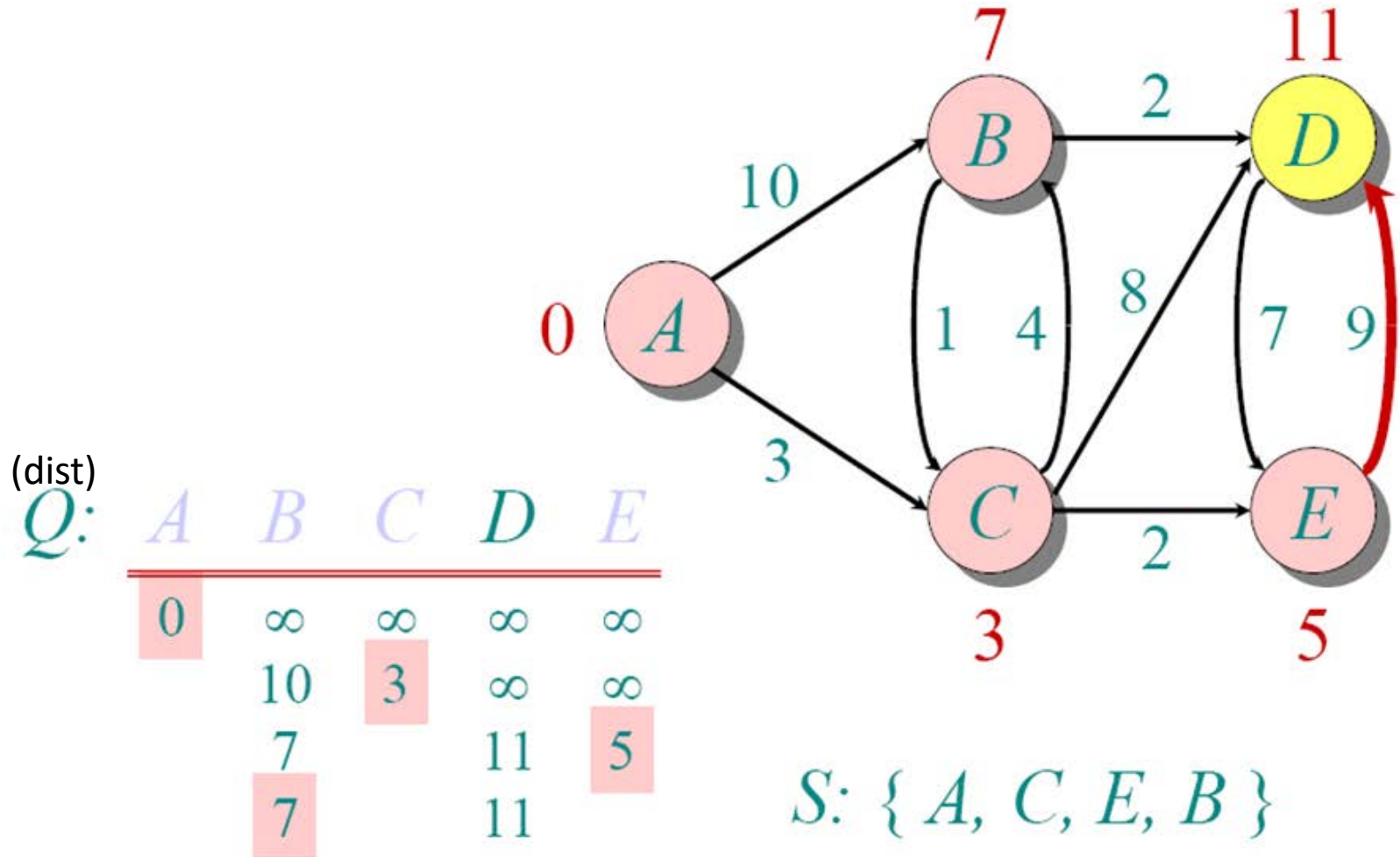
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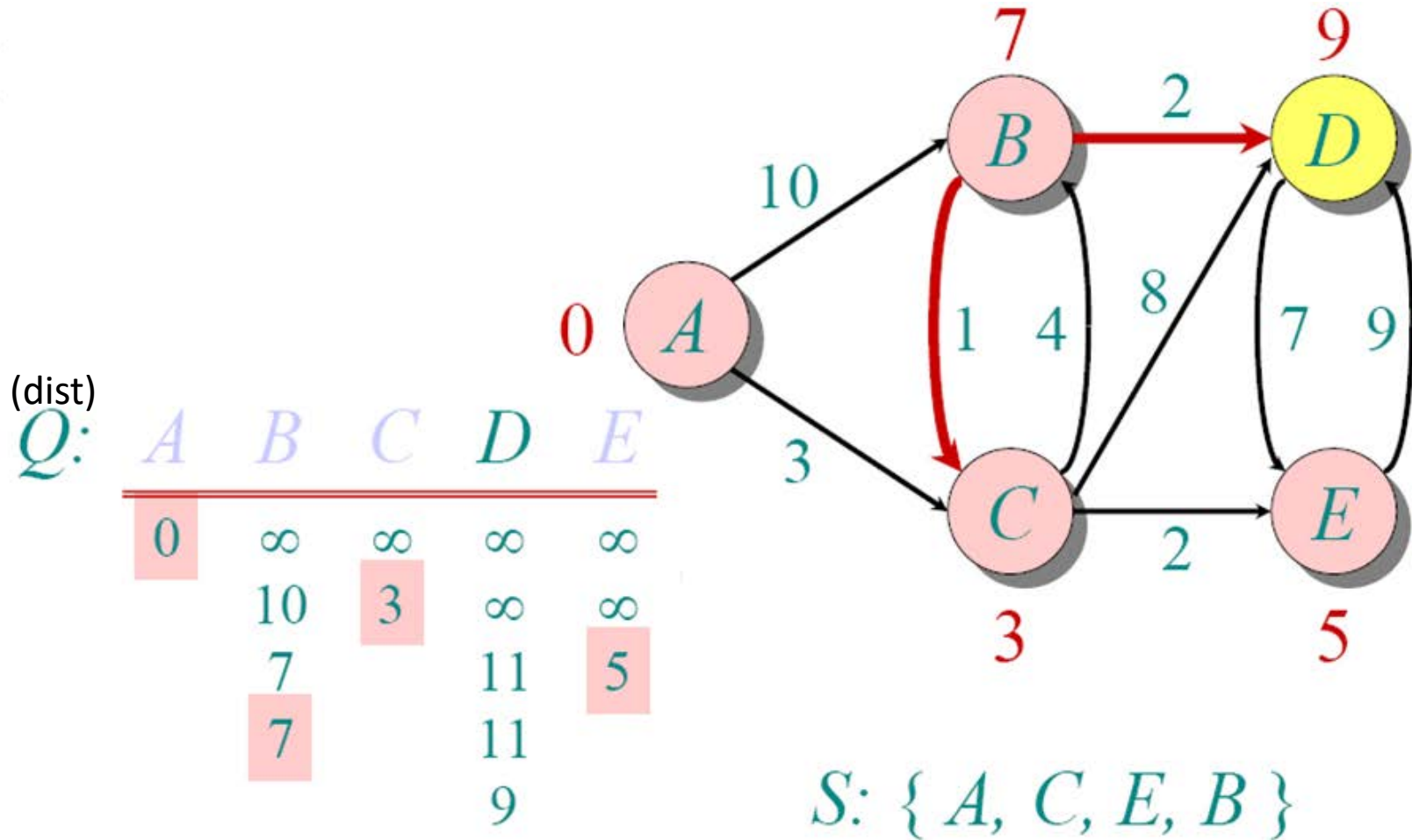
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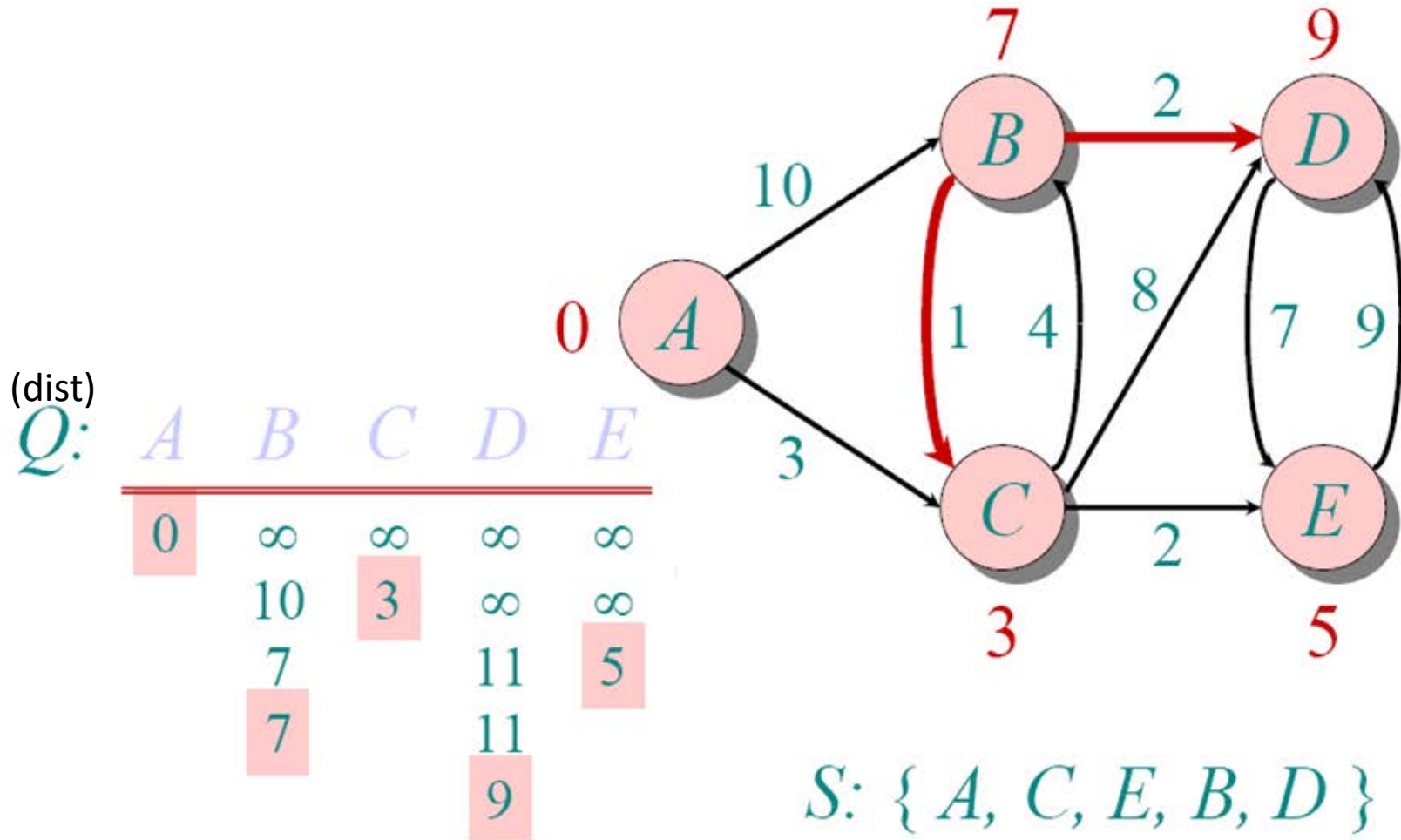


# Dijkstra Example





# Dijkstra Example



# Dijkstra's Algorithm

- Builds a tree of shortest paths rooted at the starting vertex
- This is a greedy algorithm: it adds the closest vertex, then the next closest, and so on (until all vertices have been added)

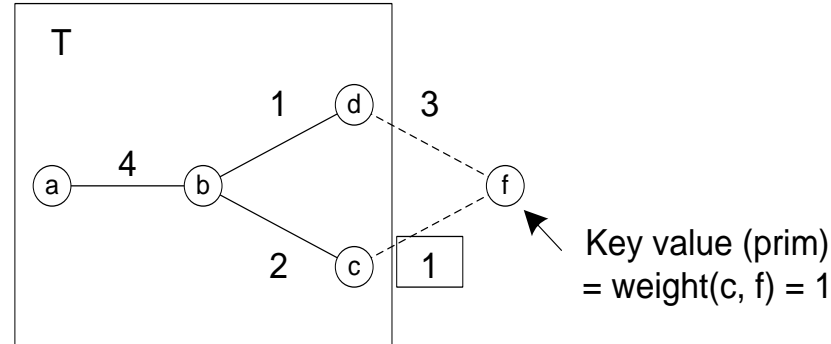
High-level pseudocode:

1. Initialise  $d$  and  $prev$
2. Add all vertices to a PQ with distance from source as the key
3. While there are still vertices in PQ
4.     Get next vertex  $u$  from the PQ
5.     For each vertex  $v$  adjacent to  $u$
6.         If  $v$  is still in PQ, relax  $v$

1. Relax( $v$ ):
2.     if  $d[u] + w(u,v) < d[v]$
3.          $d[v] \leftarrow d[u] + w(u,v)$
4.          $prev[v] \leftarrow u$
5.         PQ.updateKey( $d[v]$ ,  $v$ )

# Similarity of Dijkstra to Prim

- Both accumulate a tree  $T$  of edges from  $G$
- Each iteration: select the minimum priority edge adjacent to the tree that has been built so far
- In Prim's the priority of an edge is simply the weight of the edge



- In Dijkstra's the "priority" is the weight of the edge  $(u, v)$  plus the distance from the start to the parent of  $v$

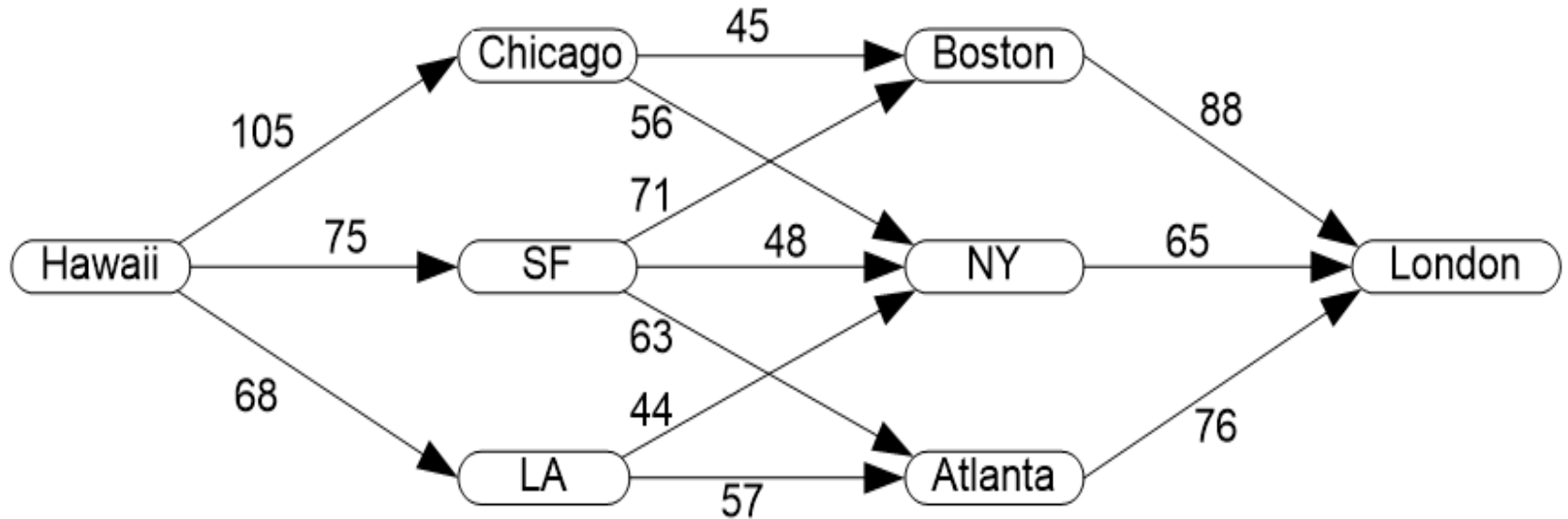
# Sample application of Dijkstra's

- Suppose London wants fresh pineapples from Hawaii.
- There are no direct flights, but many possible connections.
- What is the best possible route to minimize overall shipping cost?

# Input: Shipping costs, city to city

- Honolulu to Chicago 105
- Honolulu to San Francisco 75
- Honolulu to Los Angeles 68
- Chicago to Boston 45
- Chicago to New York 56
- San Francisco to Boston 71
- San Francisco to New York 48
- San Francisco to Atlanta 63
- Los Angeles to New York 44
- Los Angeles to Atlanta 57
- Boston to London 88
- New York to London 65
- Atlanta to London 76

# Graph model of the problem



Apply Dijkstra's algorithm to find the cheapest cost from Hawaii to London  
(bonus: cheapest cost to all the other cities, too)

# Dijkstra limitation: negative weight edges

- Dijkstra's algorithm doesn't work with negative weight edges
- If we added a new edge to T, and it had a negative weight, then there could exist a shorter path (through this new vertex) to vertices already in T
- For example, consider graph A below.
  - Graph B is the result of running Dijkstra's algorithm on A.
  - But clearly there exists a path such as a-c-e in graph C that is shorter than the path found in B. Therefore Dijkstra's algorithm did not work on this graph that has a negative edge weight.

