- Module 8 - Decision Trees

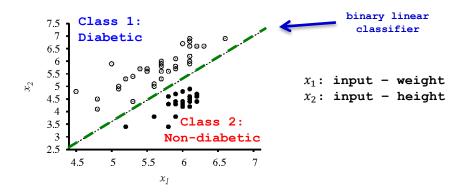
Outline

- Classification
- Decision Trees



Supervised Learning: Classification

• Classification is another subcategory of supervised learning where the goal is the prediction of categorical labels. In classification, given a number of features, p, and a categorical outcome, the objective is to find a relationship (a function $f: \mathbb{R}^p \to \{1, ..., C\}$) to predict which of C classes (or categories) a sample belongs to





Supervised Learning: Classification Applications

- Classification Applications:
 - Spam filtering
 - a binary classification problem
 - Input: email subject and message content
 (extracting keywords to form "bag of words",
 i.e., number of occurrences of 'buy', 'viagra', etc.)
 - Output: spam or non-spam
 - Movie genre classification
 - a multiclass classification problem (E.g., a genre is a class)
 - Input: plot summary
 (extracting keywords from the summary to form "bag of
 words",
 i.e., number of occurrences of 'love', 'laugh', etc.)
 - Output: movie genre (romance, comedy, thriller, etc.)
 - Object recognition
 - a multiclass classification problem (can be lots of classes)
 - Input: image (pixel RGB values)
 - Output: <u>object class</u> (car, traffic light, motorcycle, pedestrian, bicycle, etc.)

Decision Trees (1)

- **Decision tree** induction is one of the <u>simplest</u> and yet most <u>successful</u> forms of machine learning
- A <u>decision tree</u> represents a **function** that takes as <u>input</u> a <u>vector of features</u> and <u>returns</u> a <u>decision</u> (<u>single</u> <u>output value</u>)
 - the <u>input</u> and <u>output</u> values can be <u>continuous</u> or discrete

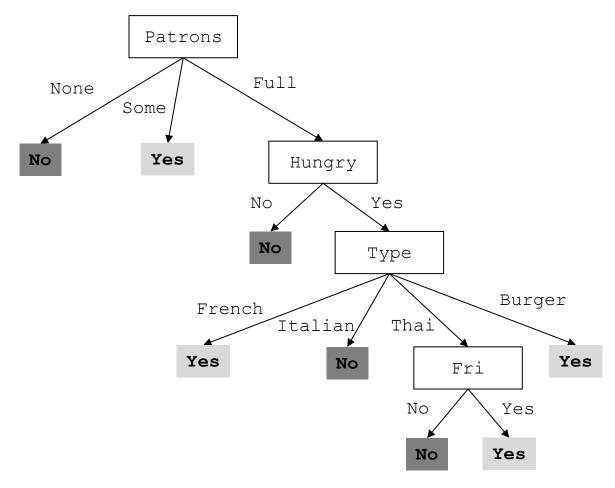
• continuous output: regression trees

• <u>discrete</u> output: **classification trees**

→ For this course, focus on classification trees where input features have discrete values and the output has exactly two (2) possible values, i.e., a positive example or a false example (binary classification)

Decision Trees: Example (2)

• Example: Decision Tree



Decision Trees (3)

- A decision tree reaches its decision by performing a sequence of tests where
 - each internal node (white box in the example) corresponds to one of the <u>input features</u>, X_i for j=1,...,p
 - the branches (arrow) from the node are labeled with the possible values of the feature, v_k for k=1,...,K
 - each leaf node (shaded box: light grey shading y_i = Yes, dark grey shading $y_i = No$) specifies a value to be returned by the function, i.e., classification output
- After a decision tree has been induced, a new sample is classified by
 - starting at the root node of the tree
 - testing the feature specified by this node
 - moving down the branch corresponding to the value of the feature
 - → process is then repeated for the subtree rooted at the new node until a leaf node is reached

Decision Trees (4)

- Advantages of decision trees:
 - easy to explain (compared to linear regression)
 - can be displayed graphically and easier to interpret
 - closely <u>mirror</u> <u>human decision-making process</u> (i.e., more intuitive)
- Limitations of decision trees:
 - can be <u>non-robust</u>: a <u>small change</u> in the <u>training data</u> can lead to a <u>significant change</u> in the <u>tree</u> and consequently the <u>prediction outcomes</u>, i.e., high variance
 - handling of <u>continuous input features</u> require finding the <u>split points</u> that give <u>accurate</u> <u>classification</u>

Decision Trees: Example (5)

• Example: Classification Problem

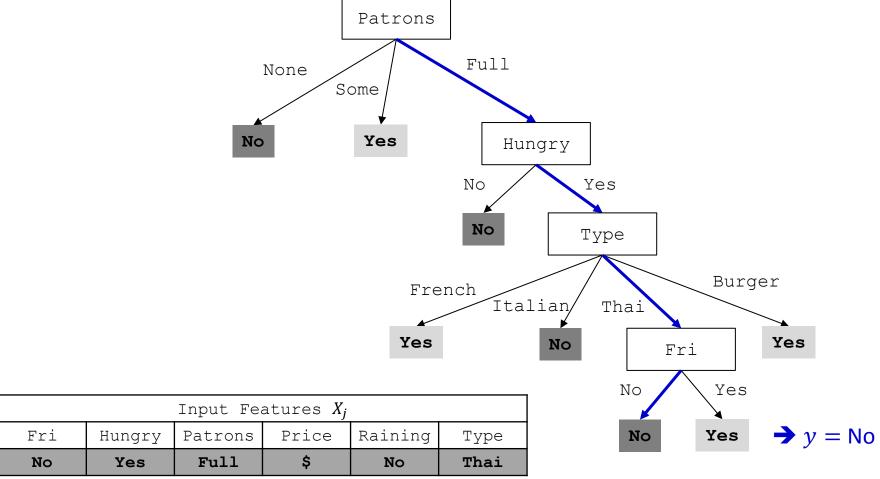
for a table at a given restaurant

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Given the following input features and possible values
of each feature:
-X_1: Friday = {Yes, No}
-X_2: Hungry = {Yes, No}
- X_3: Patrons = {None, Some, Full}
       (indicates how many people are in the restaurant)
- X_4: Price = {$, $$, $$$}
       (indicates the restaurant's price range)
-X_5: Raining = {Yes, No}
       (indicates whether it is raining outside)
-X_6: Type = {French, Italian, Thai, Burger}
        (the kind of restaurant)
Question: Determine if the person,
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{No, Yes, Full, \$, No, Thai}, will wait, $y = \{Yes, No\}$,

Decision Trees: Example (6)

• Solution: Prediction using a decision tree



Decision Trees (7)

- Steps to use a decision tree for prediction:
 - Step 1: **Induce**: <u>construct</u> a <u>decision tree</u> using training samples
 - Step 2: **Prediction:** for a <u>new sample</u> x, its <u>predicted classification output</u> \hat{y} , is given by the value corresponding to the leaf node

Decision Trees: Induction (8)

- The <u>goal</u> of <u>decision tree induction</u> is to construct a decision tree that is <u>consistent</u> with <u>training samples</u> and is as <u>small</u> as possible
 - however, finding the <u>smallest</u> <u>consistent tree</u> is generally <u>computationally infeasible</u> (i.e., intractable)
- A greedy divide-and-conquer approach is used
 - greedy:

always test the

most important feature first

→ one that makes the

most difference to the

classification of a sample

then be solved recursively

- <u>divide-and-conquer</u>: <u>divide</u> the <u>problem</u> into <u>smaller subproblems</u> that can

Decision Trees: Example - Induction (9)

Example: A training set of 12 samples is shown below

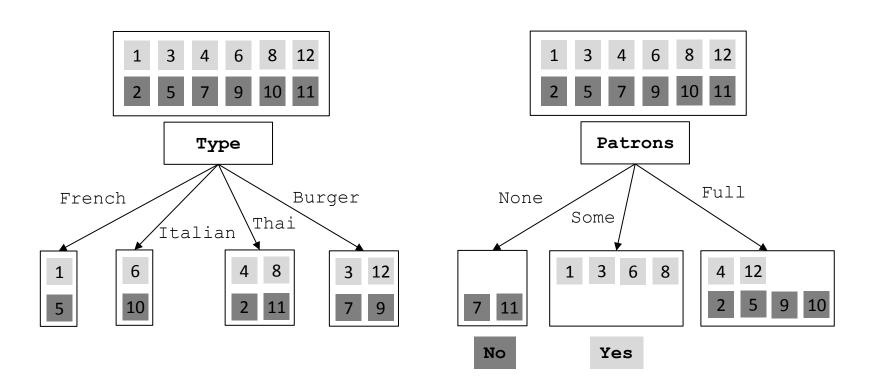
Sample		WillWait					
	Fri	Hungry	Patrons	Price	Raining	Туре	y_i
x_1	No	Yes	Some	\$\$\$	No	French	$y_1 = $ Yes
x_2	No	Yes	Full	\$	No	Thai	$y_2 = No$
x_3	No	No	Some	\$	No	Burger	$y_3 = $ Yes
x_4	Yes	Yes	Full	\$	Yes	Thai	$y_4 = $ Yes
x_5	Yes	No	Full	\$\$\$	No	French	$y_5 = No$
x_6	No	Yes	Some	\$\$	Yes	Italian	$y_6 = $ Yes
x_7	No	No	None	\$	Yes	Burger	$y_7 = No$
x_8	No	Yes	Some	\$\$	Yes	Thai	$y_8 = $ Yes
<i>x</i> ₉	Yes	No	Full	\$	Yes	Burger	$y_9 = No$
<i>x</i> ₁₀	Yes	Yes	Full	\$\$\$	No	Italian	$y_{10} = No$
<i>x</i> ₁₁	No	No	None	\$	No	Thai	$y_{11} = No$
<i>x</i> ₁₂	Yes	Yes	Full	\$	No	Burger	$y_{12} = $ Yes

Legend: No Dark-colored Yes Light-colored

Decision Trees: Example - Induction (10)

Greedy Approach:

Determine the <u>most important feature</u> from Fri, Hungry, Patrons, Price, Raining, Type



Decision Trees: Most Important Feature (11)

- The <u>greedy approach</u> is designed to approximately <u>minimize</u> the <u>depth</u> of the <u>final tree</u>
- The idea is to <u>pick</u> the <u>feature</u> that goes as far as possible towards providing an <u>exact</u> classification of the samples
- A <u>perfect feature</u> <u>divides</u> the <u>samples</u> into <u>sets</u>, each of which are <u>all positive</u> or <u>all negative</u> and thus will be leaves of the tree
 - → However, <u>features</u> may <u>not</u> be <u>perfect</u> use information gain, which is defined in terms of entropy

Decision Trees: Most Important Feature (12)

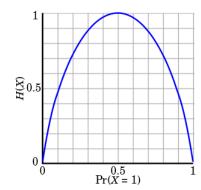
• The entropy of a random variable X with values v_k , each with probability $\Pr(X=v_k)$, is defined as

$$H(X) = -\sum_{k=1}^{K} \Pr(X = v_k) \log_2 \Pr(X = v_k)$$

is a <u>measure</u> of the <u>uncertainty</u> of a <u>random variable</u> (where <u>acquisition of information</u> corresponds to a reduction in entropy)

Examples:

- A coin that always comes up heads - $\Pr(X=1)=1$, $\Pr(X=0)=0$ - (where X=1 represents a result of heads), has no uncertainty and thus its entropy is defined as $H(X)=-(1\log_2 1+0\log_2 0)=0$



- A <u>fair coin</u> is <u>equally likely</u> to come up <u>heads</u> or <u>tails</u> - Pr(X = 1) = 0.5, Pr(X = 0) = 0.5 - has <u>maximum uncertainty</u> and thus its <u>entropy</u> is defined as $H(X) = -(0.5 \log_2 0.5 + 0.5 \log_2 0.5) = 1$

Decision Trees: Most Important Feature (13)

- Using entropy, the steps to induce the decision tree:
 - 1. Compute the entropy H_m for the current node, m
 - 2. For every feature X_j (X_j has K distinct values, $v_1, v_2, ..., v_K$)
 - a) Compute the <code>entropy</code>, H_k , for <code>each value</code> v_k of <code>feature</code> X_j

Indicator function:
$$H_k = -\sum_{\substack{l \text{ (condition)} \\ = \begin{cases} 1, & \text{if condition} = true \\ 0, & \text{otherwise} \end{cases}} p_{k,c} \log_2 p_{k,c}$$

where

- $p_{k,c} = \frac{1}{N_k} \sum_{x_i} I(x_{i,j} = v_k \text{ and } y_i = c)$ is the <u>proportion</u> of <u>training samples</u> whose <u>feature</u> $X_j = v_k$ and <u>output</u> $y_i = c$ (N_k is the <u>number of samples</u> at node m with feature $X_i = v_k$)

Insight: H_k will take on a <u>small value</u> if the <u>node</u> contains predominantly samples from a single class

Decision Trees: Most Important Feature (14)

b) Compute the <u>information gain</u>, $G(m,X_j)$, for <u>node</u> m, <u>feature</u> X_j :

$$G(m, X_j) = H_m - \sum_{k=1}^K \frac{N_k}{N_m} H_k$$

where

- N_m is the <u>number of samples</u> at <u>current node</u> m
- 3. Select the feature with the highest information gain
- 4. Add a branch for each value v_k of X_j to the current node
- 5. Repeat steps 1 to 4 for the subtrees until stopping criterion is met

Example - Most Important Feature (15)

Example - Most Important Feature (16)

Step 1)
$$p_{yes} = 6/12 \quad \boxed{1 \quad 3 \quad 4 \quad 6 \quad 8 \quad 12} \\ p_{no} = 6/12 \quad \boxed{2 \quad 5 \quad 7 \quad 9 \quad 10 \quad 11} \\ p_{atrons} \quad \boxed{1 \quad 3 \quad 6 \quad 8} \\ p_{atrons} \quad \boxed{1 \quad 3 \quad 6 \quad$$

Step 2b)
$$Gain(root, Patrons) = H_{root} - \sum_{k} \frac{N_k}{N_{root}} H_k = 1 - \left(\frac{2}{12}(0) + \frac{4}{12}(0) + \frac{6}{12}(0.918)\right) = 1 - 0.459 = 0.541$$

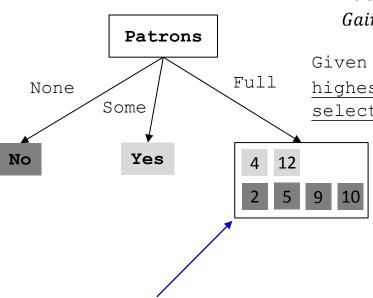
• Compute $Gain(root, X_j)$ for the remaining features (Fri, Hungry, Price and Raining) ...

Example - Most Important Feature (17)

Step 3)

Step 4)

Step 5)



• Select the <u>feature</u> that has the <u>highest</u> $Gain(root, X_i)$

Given that **Patrons** has the $\underline{\text{highest}}$ $Gain(root, X_j)$, it is selected as the root node

Divide-and-conquer Approach:

For <u>subtree</u> at <u>node</u> m, <u>compute</u> $Gain(m, X_j)$ for <u>every remaining feature</u> X_j (Fri, Hungry, Price, Raining and Type), i.e., <u>excluding features</u> of <u>parent node(s)</u>, using the <u>remaining</u> six (6) <u>training</u> <u>samples</u> $(x_2, x_4, x_5, x_9, x_{10} \text{ and } x_{12})$ and <u>select</u> one that has the <u>highest</u> $Gain(m, X_j)$

Example - Most Important Feature (18)

Cample		WillWait					
Sample	Fri	Hungry	Patrons	Price	Raining	Type	y_i
x_2	No	Yes	Full	\$	No	Thai	$y_2 = No$
x_4	Yes	Yes	Full	\$	Yes	Thai	$y_4 = Yes$
x_5	Yes	No	Full	\$\$\$	No	French	$y_5 = No$
<i>x</i> ₉	Yes	No	Full	\$	Yes	Burger	$y_9 = No$
x_{10}	Yes	Yes	Full	\$\$\$	No	Italian	$y_{10} = N \circ$
<i>x</i> ₁₂	Yes	Yes	Full	\$	No	Burger	$y_{12} = $ Yes

Step 2a)

$$p_{yes} = 0/2$$
 $p_{no} = 2/2$
 $H_{No} = 0$

 $p_{yes} = 2/6$

 $p_{no}=4/6$

$$H_m = -(p_{yes}\log_2 p_{yes} + p_{no}\log_2 p_{no})$$

$$= -\left(\frac{2}{6}\log_2 \frac{2}{6} + \frac{4}{6}\log_2 \frac{4}{6}\right)$$

$$= 0.918$$

4 12
$$p_{yes} = 2/4$$

 $p_{no} = 2/4$

Yes

$$H_{Yes}=1$$

Step 2b)
$$Gain(m, Hungry) = H_m - \sum_k \frac{N_k}{N_m} H_k = 0.918 - \left(\frac{2}{6}(0) + \frac{4}{6}(1)\right) = 0.918 - 0.667 = 0.251$$

- Compute $Gain(m,X_j)$ for the <u>remaining features</u> (Fri, Price, Raining and Type) ...
- Continue with Steps 3 through 5 (until stopping criterion is met)

Decision Trees: Stopping Criteria (19)

- Examples of stopping criteria:
 - <u>all training samples</u> in a <u>node</u> belong to the <u>same class</u> (e.g., for Patrons = None, all training samples belong to No class)
 - maximum tree depth has been reached (a root node will have a depth of 0)
 - <u>number of training samples</u> in a <u>node</u> is <u>less than</u> some pre-defined <u>threshold</u> (e.g., number of training samples is less than 5 in a node)
- In the case of where a <u>leaf node</u> contains <u>training samples</u> of <u>different classes</u>, its <u>value</u> is <u>determined</u> by **majority vote**, i.e., the <u>most commonly occurring class</u> of the <u>training samples</u>

