

Quiz #1

1. (Exercise 1.5)

Since the i -th coordinate of $\gamma'(t)$ is $x'_i(t) = \lim_{h \rightarrow 0} \frac{x_i(t+h) - x_i(t)}{h}$, for any $\varepsilon > 0$, there is a positive real number $\delta_i(\varepsilon) > 0$ such that

$$\left| \frac{x_i(t+h) - x_i(t)}{h} - x'_i(t) \right| < \varepsilon$$

whenever $|h| < \delta_i(\varepsilon)$. Hence, for any $\varepsilon > 0$,

$$\begin{aligned} \left| \frac{\gamma(t+h) - \gamma(t)}{h} - \gamma'(t) \right| &= \sqrt{\sum_{i=1}^n \left| \frac{x_i(t+h) - x_i(t)}{h} - x'_i(t) \right|^2} \\ &< \sqrt{\sum_{i=1}^n \left(\frac{\varepsilon}{\sqrt{n}} \right)^2} = \varepsilon \end{aligned}$$

whenever $|h| < \min_{i=1, \dots, n} \delta_i(\varepsilon/\sqrt{n})$. Therefore, we have

$$\gamma'(t) = \lim_{h \rightarrow 0} \frac{\gamma(t+h) - \gamma(t)}{h}.$$

2. (Exercise 1.22)

When $\gamma'(t)$ is orthogonal to $\gamma(t)$ for any $t \in I$, we have $\langle \gamma'(t), \gamma(t) \rangle = 0$ for any $t \in I$. Note that

$$\frac{d}{dt} \langle \gamma(t), \gamma(t) \rangle = 2 \langle \gamma'(t), \gamma(t) \rangle = 0,$$

hence $\langle \gamma(t), \gamma(t) \rangle$ is a constant on I . Since $\langle \gamma(t), \gamma(t) \rangle \geq 0$, there is a real number $C \geq 0$ such that $|\gamma(t)|^2 = \langle \gamma(t), \gamma(t) \rangle = C^2$, which means $|\gamma(t)| = C$ for any $t \in I$. Thus, the converse of the part (1) in Proposition 1.17 holds.

3. (Exercise 1.36)

Answer: f is not independent of parametrization.

Without loss of generality, consider the case that γ is a unit speed parametrized curve. Let $\tilde{\gamma}$ be a (regular) reparametrization of γ , that is, $\tilde{\gamma} = \gamma \circ \phi$ for some smooth bijection ϕ with nonvanishing derivative. Then,

$$\tilde{\gamma}'(t) = \gamma'(\phi(t))\phi'(t),$$

and

$$\tilde{\gamma}''(t) = \gamma''(\phi(t))(\phi'(t))^2 + \gamma'(\phi(t))\phi''(t).$$

Since γ is a unit speed curve, $\langle \gamma'(t), \gamma'(t) \rangle = 1$ so that $\langle \gamma'(t), \gamma''(t) \rangle = 0$ by differentiating both sides. Now we have

$$\begin{aligned} |\tilde{\gamma}''(t)|^2 &= \langle \tilde{\gamma}''(t), \tilde{\gamma}''(t) \rangle \\ &= \langle \gamma''(\phi(t))(\phi'(t))^2 + \gamma'(\phi(t))\phi''(t), \gamma''(\phi(t))(\phi'(t))^2 + \gamma'(\phi(t))\phi''(t) \rangle \\ &= (\phi'(t))^4 \langle \gamma''(\phi(t)), \gamma''(\phi(t)) \rangle + (\phi''(t))^2 \langle \gamma'(\phi(t)), \gamma'(\phi(t)) \rangle \\ &= (\phi'(t))^4 |\gamma''(\phi(t))|^2 + (\phi''(t))^2. \end{aligned}$$

Since $|\tilde{\gamma}'(t)| = |\phi'(t)|$, we have

$$\frac{|\tilde{\gamma}''(t)|^2}{|\tilde{\gamma}'(t)|^4} = |\gamma''(\phi(t))|^2 + \frac{(\phi''(t))^2}{|\phi'(t)|^4} = f(\phi(t))^2 + \frac{(\phi''(t))^2}{|\phi'(t)|^4}.$$

Therefore, for a reparametrization such that $\phi''(t) \neq 0$, $f(t)$ is **not** independent of parametrization.

4. (Exercise 1.54)

By the definition of the signed curvature, we have

$$\kappa_s(t) = \frac{\langle \mathbf{a}(t), R_{90}(\mathbf{v}(t)) \rangle}{|\mathbf{v}(t)|^3}.$$

Within the polar coordinate system $(r, \theta)_\angle = (r \cos \theta, r \sin \theta)$, we have

$$R_{90}((r, \theta)_\angle) = (r, \theta + \pi/2)_\angle.$$

Also, $\frac{d}{d\theta}(\cos \theta, \sin \theta) = (-\sin \theta, \cos \theta) = R_{90}(\cos \theta, \sin \theta)$. Hence, we have

$$\begin{aligned}\mathbf{v}(\theta) &= \frac{d}{d\theta}[r(\theta)(\cos \theta, \sin \theta)] \\ &= r'(\theta)(\cos \theta, \sin \theta) + r(\theta)(-\sin \theta, \cos \theta) \\ &= (r'(\theta) \cos \theta - r(\theta) \sin \theta, r'(\theta) \sin \theta + r(\theta) \cos \theta)\end{aligned}$$

and

$$\begin{aligned}\mathbf{a}(\theta) &= \frac{d}{d\theta}\mathbf{v}(\theta) \\ &= r''(\theta)(\cos \theta, \sin \theta) + 2r'(\theta)(-\sin \theta, \cos \theta) - r(\theta)(\cos \theta, \sin \theta). \\ &= (r''(\theta) \cos \theta - 2r'(\theta) \sin \theta - r(\theta) \cos \theta, r''(\theta) \sin \theta + 2r'(\theta) \cos \theta - r(\theta) \sin \theta).\end{aligned}$$

Furthermore,

$$\begin{aligned}R_{90}(\mathbf{v}(t)) &= R_{90}(r'(\theta)(\cos \theta, \sin \theta)) + R_{90}(r(\theta)(-\sin \theta, \cos \theta)) \\ &= R_{90}((r'(\theta), \theta)_{\angle}) + R_{90}((r(\theta), \theta + \pi/2)_{\angle}) \\ &= (r'(\theta), \theta + \pi/2)_{\angle} + (r(\theta), \theta + \pi)_{\angle} \\ &= r'(\theta)(-\sin \theta, \cos \theta) - r(\theta)(\cos \theta, \sin \theta) \\ &= (-r'(\theta) \sin \theta - r(\theta) \cos \theta, r'(\theta) \cos \theta - r(\theta) \sin \theta).\end{aligned}$$

since R_{90} is linear. Therefore,

$$\begin{aligned}\langle \mathbf{a}(t), R_{90}(\mathbf{v}(t)) \rangle &= (r''(\theta) \cos \theta - 2r'(\theta) \sin \theta - r(\theta) \cos \theta)(-r'(\theta) \sin \theta - r(\theta) \cos \theta) \\ &\quad + (r''(\theta) \sin \theta + 2r'(\theta) \cos \theta - r(\theta) \sin \theta)(r'(\theta) \cos \theta - r(\theta) \sin \theta) \\ &= \cancel{-r''r'cs} + 2(r')^2s^2 + \cancel{r'r'cs} - r''rc^2 + \cancel{2r'r'cs} + r^2c^2 \\ &\quad + \cancel{r''r'cs} + 2(r')^2c^2 - \cancel{r'r'cs} - r''rs^2 - \cancel{2r'r'cs} + r^2s^2 \\ &= 2(r'(\theta))^2 - r''(\theta)r(\theta) + r(\theta)^2\end{aligned}$$

where $r = r(\theta)$, $r' = r'(\theta)$, $r'' = r''(\theta)$, $c = \cos \theta$, and $s = \sin \theta$. Since

$$\begin{aligned}|\mathbf{v}(\theta)|^2 &= (r'c - rs)^2 + (r's + rc)^2 \\ &= (r')^2c^2 - \cancel{2r'r'cs} + r^2s^2 + (r')^2s^2 + \cancel{2r'r'cs} + r^2c^2 \\ &= (r'(\theta))^2 + (r(\theta))^2,\end{aligned}$$

we have

$$\kappa_s(\theta) = \frac{2(r'(\theta))^2 - r''(\theta)r(\theta) + r(\theta)^2}{((r'(\theta))^2 + (r(\theta))^2)^{3/2}}.$$