Midterm Homework

1. (a)

(b) PA = LU where

$$P = E(2,3) = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}, \qquad U = \begin{bmatrix} 1 & 1 & 2 & 2 & 3 \\ & 1 & 1 & 1 & 2 \\ & & 0 & 1 & 1 \\ & & & 0 & 0 \\ & & & & 0 \end{bmatrix},$$

 $L = [E(3; -1/2)E(2, 4; -1)E(2; 1/2)E(1, 5; -2)E(1, 4; -1)E(1, 3; -3)E(1; 1/2)]^{-1}$

$$= \begin{bmatrix} 2 & & & & \\ 0 & 2 & & & \\ 3 & 0 & -2 & & \\ 1 & 1 & 0 & 1 & \\ 2 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

(Empty spots are filled with zeroes.)

(c) Note that $B = \mathbf{b}_1 \mathbf{v}_1^T + \mathbf{b}_2 \mathbf{v}_2^T + \mathbf{b}_4 \mathbf{v}_3^T$, where

$$\begin{aligned} \mathbf{b}_1 &= [1,0,0,0]^T, & \mathbf{b}_2 &= [0,1,0,0]^T, & \mathbf{b}_4 &= [0,0,1,0]^T \\ \mathbf{v}_1 &= [1,0,2,0,3]^T, & \mathbf{v}_2 &= [0,1,4,0,5]^T, & \mathbf{v}_3 &= [0,0,0,1,6]^T. \end{aligned}$$

Letting a composition of elementary row operations $E = E_n \cdots E_1$ be operated on M to produce the RREF B = EM, we have $EM = E[\mathbf{c}_1, \dots, \mathbf{c}_5] = B = [\mathbf{b}_1, \dots, \mathbf{b}_5]$. Thus,

$$M = E^{-1}B = E^{-1}\mathbf{b}_{1}\mathbf{v}_{1}^{T} + E^{-1}\mathbf{b}_{2}\mathbf{v}_{2}^{T} + E^{-1}\mathbf{b}_{4}\mathbf{v}_{3}^{T} = \mathbf{c}_{1}\mathbf{v}_{1}^{T} + \mathbf{c}_{2}\mathbf{v}_{2}^{T} + \mathbf{c}_{4}\mathbf{v}_{3}^{T}.$$

Hence, $\mathbf{u}_1 = \mathbf{c}_1$, $\mathbf{u}_2 = \mathbf{c}_2$, $\mathbf{u}_3 = \mathbf{c}_4$, and \mathbf{v}_i 's as above make the given equality true.

2. Since A is of rank k, the RREF R = EA (E: a product of elementary matrices) of A has exactly k nonzero rows. Then, as in the problem 1(c),

$$R =: [\mathbf{v}_1, \cdots, \mathbf{v}_k, \mathbf{0} \cdots, \mathbf{0}]^T, \qquad R = \sum_{i=1}^k \mathbf{e}_i \mathbf{v}_i^T.$$

Here, \mathbf{v}_i 's are linearly independent since they are the rows of the RREF R. Therefore, $A = E^{-1}R = \sum_{i=1}^k (E^{-1}\mathbf{e}_i)\mathbf{v}_i^T$. Note that the one-hot vectors \mathbf{e}_i $(i=1,\ldots,k)$ are linearly independent, and the multiplication of E^{-1} , an invertible matrix, does not affect to the linear independence. Therefore, $\mathbf{u}_i \coloneqq E^{-1}\mathbf{e}_i$ $(i=1,\ldots,k)$ form a linearly independent set. This completes the proof.

3. (a) Suppose they are linearly independent. Then there are $a, b, c, d \in \mathbb{R}$, where not all of them are zero, such that

$$axe^x \cos x + bxe^x \sin x + ce^x \cos x + de^x \sin x = 0$$

for any $x \in \mathbb{R}$. Equivalently,

$$ax\cos x + bx\sin x + c\cos x + d\sin x = 0$$

for any $x \in \mathbb{R}$. Evaluating it at x = 0, we get c = 0. Evaluating it at $x = 2\pi$, we have $a \cdot 2\pi = 0$, that is, a = 0. Then, $bx \sin x + d \sin x = 0$ for any $x \in \mathbb{R}$. Dividing the both side by $\sin x$ assuming $\sin x$ is nonzero, we have bx + d = 0, at least for two values of x. This implies b = d = 0. This contradicts to the initial assumption.

(b)

$$\frac{d}{dx} x e^x \cos x = x e^x \cos x - x e^x \sin x + e^x \cos x,$$

$$\frac{d}{dx} x e^x \sin x = x e^x \sin x + x e^x \cos x + e^x \sin x,$$

$$\frac{d}{dx} e^x \cos x = e^x \cos x - e^x \sin x,$$

$$\frac{d}{dx} e^x \sin x = e^x \sin x + e^x \cos x.$$

Therefore,

$$[D]_{\mathcal{B}} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & 1 \end{bmatrix}.$$

(c) The characteristic polynomial of D is

$$p_{[D]_{\mathcal{B}}}(t) = t^4 - 4t^3 + 8t^2 - 8t + 4 = (t^2 - 2t + 2)^2$$

So the eigenvalues are $1 \pm i$. By a simple calculation,

$$[D]_{\mathcal{B}}[\mathbf{v}]_{\mathcal{B}} = (1+i)[\mathbf{v}]_{\mathcal{B}} \implies [\mathbf{v}]_{\mathcal{B}} = c(0,0,1,i)^T, \text{ and}$$

 $[D]_{\mathcal{B}}[\mathbf{v}]_{\mathcal{B}} = (1-i)[\mathbf{v}]_{\mathcal{B}} \implies [\mathbf{v}]_{\mathcal{B}} = c(0,0,i,1)^T$

for an arbitrary $c \in \mathbb{C}$. Therefore, the eigenvectors corresponding to $\lambda = 1 + i$ is $ce^x(\cos x + i \sin x) = ce^{(1+i)x}$; and the eigenvectors corresponding to $\lambda = 1 - i$ is $ce^x(\cos x - i \sin x) = ce^{(1-i)x}$, for $c \in \mathbb{C}$.

4. Let us solve (b) first and then (a).

(b) Take
$$\mathbf{v}_1 = \frac{1}{\sqrt{3}}(1,1,1)^T$$
, and a (unit) vector $\mathbf{v}_2 = \frac{1}{\sqrt{2}}(1,0,-1)^T$ in the

orthogonal complement of \mathbf{v}_1 . Finally, let $\mathbf{v}_3 = \mathbf{v}_1 \times \mathbf{v}_2 = \frac{1}{\sqrt{6}}(-1, 2, -1)^T$. Then, T becomes a rotation following the right-hand direction with respect to the basis $\mathcal{B} = {\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}}$, that is, the direction of other fingers when the thumb is pointing the vector $(1, 1, 1)^T$. Thus, T is a CCW rotation on a plane orthogonal to \mathbf{v}_1 , so that

$$[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos(30^{\circ}) & -\sin(30^{\circ}) \\ 0 & \sin(30^{\circ}) & \cos(30^{\circ}) \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \sqrt{3}/2 & -1/2 \\ 0 & 1/2 & \sqrt{3}/2 \end{bmatrix}.$$

(a) Letting

$$P = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & \frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} \end{bmatrix},$$

we have $[T]_{\mathcal{E}} = P[T]_{\mathcal{B}}P^{-1}$ where \mathcal{E} is the standard basis of \mathbb{R}^3 . By a simple calculation, using $P^{-1} = P^T$, we get

$$[T]_{\mathcal{E}} = \frac{1}{3} \begin{bmatrix} 1 + \sqrt{3} & 1 - \sqrt{3} & 1 \\ 1 & 1 + \sqrt{3} & 1 - \sqrt{3} \\ 1 - \sqrt{3} & 1 & 1 + \sqrt{3} \end{bmatrix}.$$

5. (a) Note $W = \operatorname{col}(A)$ where $A = [\mathbf{u}_1, \mathbf{u}_2]$, and

$$[T]_{\mathcal{E}} = A(A^T A)^{-1} A^T.$$

(b) Taking an orthogonal basis \mathcal{B} extending $\{\mathbf{u}_1, \mathbf{u}_2\}$ which exists due to, say, Gram-Schmidt orthogonalization, we have

$$[T]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 0 \end{bmatrix} = \begin{bmatrix} I_2 & O_{2\times(n-2)} \\ O_{(n-2)\times 2} & O_{(n-2)\times(n-2)} \end{bmatrix}.$$

 $\boldsymbol{6}$. (a) The characteristic polynomial of A is

$$\det(tI - A) = t^4 - 16t^3 - 20t^2 = t^2(t^2 - 16t - 20).$$

Thus, the eigenvalues are $\lambda_1 = 8 + 2\sqrt{21}$, $\lambda_2 = 8 - 2\sqrt{21}$, and $\lambda_3 = \lambda_4 = 0$. Corresponding eigenvectors are:

•
$$\mathbf{v}_1 = (13 + 3\sqrt{21}, 18 + 4\sqrt{21}, 23 + 5\sqrt{21}, 28 + 6\sqrt{21})^T$$

•
$$\mathbf{v}_2 = (-13 + 3\sqrt{21}, -18 + 4\sqrt{21}, -23 + 5\sqrt{21}, -28 + 6\sqrt{21})^T$$

•
$$\mathbf{v}_3 = (2, -3, 0, 1)^T$$
,

•
$$\mathbf{v}_4 = (1, 2, -7, 4)^T$$
.

Normalizing them, we obtain

•
$$\mathbf{u}_1 = \frac{1}{2\sqrt{903+197\sqrt{21}}}\mathbf{v}_1,$$

•
$$\mathbf{u}_2 = \frac{1}{2\sqrt{903-197\sqrt{21}}}\mathbf{v}_2,$$

•
$$\mathbf{u}_3 = \frac{1}{\sqrt{14}} \mathbf{v}_3$$
,

•
$$\mathbf{u}_4 = \frac{1}{\sqrt{70}} \mathbf{v}_4$$
.

Let $P = [\mathbf{u}_1, \cdots, \mathbf{u}_4]$. Then the orthogonal diagonalization of A is

$$P^{T}AP = \operatorname{diag}(\lambda_{1}, \lambda_{2}, \lambda_{3}, \lambda_{4}) = \operatorname{diag}(8 + 2\sqrt{21}, 8 - 2\sqrt{21}, 0, 0).$$

(b) The spectral decomposition of A is

$$A = (8 + 2\sqrt{21})\mathbf{u}_1\mathbf{u}_1^T + (8 - 2\sqrt{21})\mathbf{u}_2\mathbf{u}_2^T$$

$$\left(= \frac{8 + 2\sqrt{21}}{4(903 + 197\sqrt{21})}\mathbf{v}_1\mathbf{v}_1^T + \frac{8 - 2\sqrt{21}}{4(903 - 197\sqrt{21})}\mathbf{v}_2\mathbf{v}_2^T \right)$$

where $\mathbf{u}_1, \mathbf{u}_2, \mathbf{v}_1, \mathbf{v}_2$ are as in (a).

(c) Singular values of $A^TA=A^2$ are λ_i^2 (i=1,2), which are $(8\pm 2\sqrt{21})^2.$

(d)

$$e^{A} = \sum_{k\geq 0} \frac{1}{k!} A^{k}$$

$$= \sum_{k\geq 0} \frac{1}{k!} (\lambda_{1}^{k} \mathbf{u}_{1} \mathbf{u}_{1}^{T} + \lambda_{2}^{k} \mathbf{u}_{2} \mathbf{u}_{2}^{T})$$

$$= \sum_{k\geq 0} \frac{1}{k!} ((8 + 2\sqrt{21})^{k} \mathbf{u}_{1} \mathbf{u}_{1}^{T} + (8 - 2\sqrt{21})^{k} \mathbf{u}_{2} \mathbf{u}_{2}^{T})$$

where $\mathbf{u}_1, \mathbf{u}_2$ are as in (a).

(e) Let $\mathbf{w}_1 = (1, 2, 3, 4)^T$ and $\mathbf{w}_2 = (2, 3, 4, 5)^T$, then an orthogonal basis $\{\mathbf{q}_1, \mathbf{q}_2\}$ for span $(\mathbf{w}_1, \mathbf{w}_2)$ is given by

$$\mathbf{v}_1 = \mathbf{w}_1, \qquad \mathbf{q}_1 = \frac{1}{\sqrt{30}} (1, 2, 3, 4)^T,$$

and

$$\mathbf{v}_2 = \mathbf{w}_2 - \operatorname{proj}_{\mathbf{w}_1} \mathbf{w}_2 = (2, 3, 4, 5) - \frac{4}{3} (1, 2, 3, 4)^T = \frac{1}{3} (2, 1, 0, -1)^T$$
$$\mathbf{q}_2 = \frac{1}{\sqrt{6}} (2, 1, 0, -1)^T.$$

Let us extend $\{\mathbf{q}_1, \mathbf{q}_2\}$ into an orthonormal basis of \mathbb{R}^4 . Letting $\mathbf{w}_3 = (1, 0, 0, 0)^T$, we have

$$\mathbf{v}_3 = \mathbf{w}_3 - (\mathbf{w}_3 \cdot \mathbf{q}_1)\mathbf{q}_1 - (\mathbf{w}_3 \cdot \mathbf{q}_2)\mathbf{q}_2 = \frac{1}{10}(3, -4, -1, 2)^T,$$

$$\mathbf{q}_3 = \frac{1}{\sqrt{30}}(3, -4, -1, 2)^T.$$

Letting $\mathbf{w}_4 = (0, 1, 0, 0)^T$, we have

$$\mathbf{v}_4 = \mathbf{w}_4 - (\mathbf{w}_4 \cdot \mathbf{q}_1)\mathbf{q}_1 - (\mathbf{w}_4 \cdot \mathbf{q}_2)\mathbf{q}_2 - (\mathbf{w}_4 \cdot \mathbf{q}_3)\mathbf{q}_3 = \frac{1}{6}(0, 1, -2, 1)^T,$$
$$\mathbf{q}_4 = \frac{1}{\sqrt{6}}(0, 1, -2, 1)^T.$$

Thus, $Q = [\mathbf{q}_1, \dots, \mathbf{q}_4]$ is an orthogonal matrix. With $A = [\mathbf{a}_1, \dots, \mathbf{a}_4]$,

$$R = \begin{bmatrix} \mathbf{a}_1 \cdot \mathbf{q}_1 & \mathbf{a}_2 \cdot \mathbf{q}_1 & \mathbf{a}_3 \cdot \mathbf{q}_1 & \mathbf{a}_4 \cdot \mathbf{q}_1 \\ 0 & \mathbf{a}_2 \cdot \mathbf{q}_2 & \mathbf{a}_3 \cdot \mathbf{q}_2 & \mathbf{a}_4 \cdot \mathbf{q}_2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} \sqrt{30} & \frac{4}{3}\sqrt{3} & \frac{5}{3}\sqrt{3} & 2\sqrt{3} \\ 0 & \frac{1}{3}\sqrt{6} & \frac{2}{3}\sqrt{6} & \sqrt{6} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

where A = QR.

(f) The SVD of A is given by $A = U\Sigma V^T$, where A^TA has eigenvalues $\sigma_1^2 = (8 + 2\sqrt{21})^2$, $\sigma_2^2 = (8 - 2\sqrt{21})^2$ and $\lambda_3 = \lambda_4 = 0$ (with multiplicity 2),

and the (unit) eigenvectors

$$V = [\mathbf{v}_1, \cdots, \mathbf{v}_4] = \begin{bmatrix} -0.3147 & 0.7752 & 0.3041 & -0.4556 \\ -0.4275 & 0.3424 & -0.0659 & 0.8341 \\ -0.5402 & -0.0903 & -0.7805 & -0.3015 \\ -0.6530 & -0.5231 & 0.5423 & -0.0770 \end{bmatrix}$$

(where \mathbf{v}_i corresponds to σ_i^2 .) And $\mathbf{u}_i = A\mathbf{v}_i/\sigma_i$ for i = 1, 2, yielding

$$\mathbf{u}_1 = (-0.3147, -0.4275, -0.5402, -0.6530)^T,
\mathbf{u}_2 = (-0.7752, -0.3424, 0.0903, 0.5231)^T.$$

Extending $\{\mathbf{u}_1, \mathbf{u}_2\}$ to an orthogonal basis of \mathbb{R}^4 , we have

$$U = [\mathbf{u}_1, \dots, \mathbf{u}_4] = \begin{bmatrix} -0.3147 & -0.7752 & 0.5442 & 0.0619 \\ -0.4275 & -0.3424 & -0.7718 & 0.3231 \\ -0.5402 & 0.0903 & -0.0891 & -0.8319 \\ -0.6530 & 0.5231 & 0.3167 & 0.4469 \end{bmatrix}.$$

With $\Sigma = \text{diag}(8 + 2\sqrt{21}, 8 - 2\sqrt{21}, 0, 0)$, we have $A = U\Sigma V^T$. Then, the following is the polar decomposition of A: A = QS where

$$Q = UV^T = \begin{bmatrix} -0.3646 & -0.1152 & -0.2034 & 0.9014 \\ -0.5128 & 0.3858 & 0.7668 & 0.0149 \\ 0.5919 & -0.4261 & 0.6040 & 0.3213 \\ 0.5037 & 0.8101 & -0.0764 & 0.2900 \end{bmatrix},$$

$$S = V\Sigma V^T = \begin{bmatrix} 2.4004 & 2.6186 & 2.8368 & 3.0551 \\ 2.6186 & 3.2733 & 3.9279 & 4.5826 \\ 2.8368 & 3.9279 & 5.0190 & 6.1101 \\ 3.0551 & 4.5826 & 6.1101 & 7.6376 \end{bmatrix}.$$

7. (a) The characteristic polynomial of A is

$$\det(tI - A) = \det\begin{bmatrix} t - 1 & -1 \\ -1 & t - 1 \end{bmatrix} \cdot \det\begin{bmatrix} t - 2 & -2 & 0 \\ 0 & t - 2 & -1 \\ 0 & 0 & t - 2 \end{bmatrix} \cdot \det\begin{bmatrix} t & 0 \\ -1 & t \end{bmatrix}$$
$$= [(t - 1)^2 - 1](t - 2)^3 t^2 = t^3 (t - 2)^4.$$

(b) Eigenvalues are 0 and 2. Eigenvectors corresponding to 0 are

$$(-1, 1, 0, 0, 0, 0, 0)^T$$
, $(0, 0, 0, 0, 0, 0, 1)^T$,

and eigenvectors corresponding to 2 are

$$(1, 1, 0, 0, 0, 0, 0)^T$$
, $(0, 0, 1, 0, 0, 0, 0)^T$.

- (c) Algebraic multiplicities of eigenvalues 0 and 2 are $\underline{3}$ and $\underline{4}$, respectively. Geometric multiplicities of both eigenvalues are 2.
- (d) The minimal polynomial of A has the factor t and t-2. Since A(A-2I), $A(A-2I)^2$, $A(A-2I)^3$, $A^2(A-2I)$, $A^2(A-2I)^2$ are nonzero and $A^2(A-2I)^3 = O_{7\times 7}$, the minimal polynomial of A is $m_A(t) = t^2(t-2)^3$.
- 8. Let $X = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$. Then

$$T(X) = \begin{bmatrix} -3b + 2c & -2a - 3b + 2d \\ 3a + 3c - 3d & 3b - 2c \end{bmatrix}.$$

(a) The kernel of T is

$$\ker T = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : 3b = 2c, d = a + c \right\} = \left\{ \begin{bmatrix} a & 2c/3 \\ c & a + c \end{bmatrix} : a, c \in \mathbb{R}^4 \right\}.$$

(b) With the standard basis $\mathcal{E} = \{\mathbf{e}_1, \dots, \mathbf{e}_4\}$ where

$$\mathbf{e}_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \ \mathbf{e}_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \ \mathbf{e}_3 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \ \mathbf{e}_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix},$$

we have

$$T\mathbf{e}_1 = -2\mathbf{e}_2 + 3\mathbf{e}_3,$$

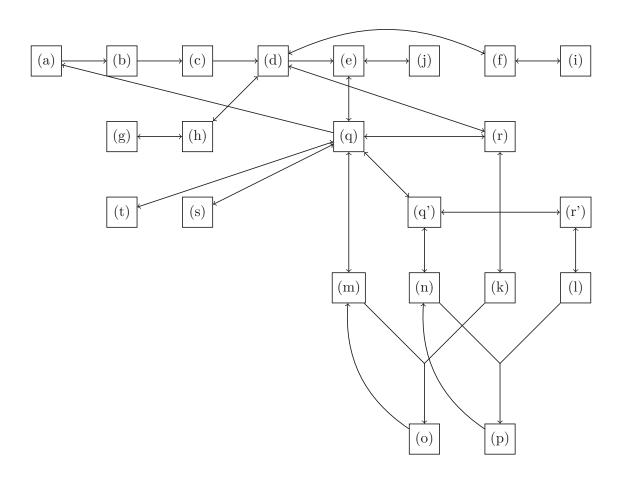
 $T\mathbf{e}_2 = -3\mathbf{e}_1 - 3\mathbf{e}_2 + 3\mathbf{e}_4,$
 $T\mathbf{e}_3 = 2\mathbf{e}_1 + 3\mathbf{e}_3 - 2\mathbf{e}_4,$
 $T\mathbf{e}_4 = 2\mathbf{e}_2 - 3\mathbf{e}_3,$

so that

$$[T]_{\mathcal{E}} = \begin{bmatrix} 0 & -3 & 2 & 0 \\ -2 & -3 & 0 & 2 \\ 3 & 0 & 3 & -3 \\ 0 & 3 & -2 & 0 \end{bmatrix}.$$

Thus, the characteristic polynomial of T is the same with $\det(tI - [T]_{\mathcal{E}}) = t^4 - 33t^2$.

9. I will show the following: (the arrows mean the implications)



where (q') rank $(A^T) = n$ and (r') nullity $(A^T) = 0$.

(a) \Longrightarrow (b): Since A is row-equivalent to I_n , there is matrix $E = E_n \cdots E_1$ which is a product of elementary matrices such that $EA = I_n$. Then $A = E_1^{-1} \cdots E_n^{-1}$, where each E_i^{-1} is again an elementary matrix. Thus, A is expressible as a product of elementary matrices.

- (b) \Longrightarrow (c): If $A = E_n \cdots E_1$, $A^{-1} = E_1^{-1} \cdots E_n^{-1}$.
- (c) \Longrightarrow (d): $A\mathbf{x} = \mathbf{0}$ implies $\mathbf{x} = A^{-1}A\mathbf{x} = A\mathbf{0} = \mathbf{0}$.
- (d) \Longrightarrow (e): There is a solution $\mathbf{b} = A^{-1}\mathbf{x}$ to the equation $A\mathbf{x} = \mathbf{b}$.
- (e) \iff (j): By definition.
- (d) \iff (h): $\lambda = 0$ is an eigenvalue of A iff there is a nonzero vector \mathbf{x} such that $A\mathbf{x} = 0\mathbf{x} = \mathbf{0}$. The contrapositive of this statement is exactly (d) \iff (h).
- (h) \iff (g): $\lambda = 0$ is an eigenvalue of A iff $\det(tI A)|_{t=0} = (-1)^n \det(A) = 0$ iff $\det(A) = 0$. The contrapositive of this statement is exactly (h) \iff (g).
- (e) \iff (q): (e) iff $T_A(\mathbb{R}^n) = \mathbb{R}^n$ iff $T_A(\mathbb{R}^n)$, which is a subspace of \mathbb{R}^n , has the dimension n iff rank(A) = n.
- (d) \iff (f): (\iff) is clear. (\implies) If $A\mathbf{x}_1 = \mathbf{b} = A\mathbf{x}_2$, then $A(\mathbf{x}_1 \mathbf{x}_2) = \mathbf{0}$ so that $\mathbf{x}_1 \mathbf{x}_2$, a solution of $A\mathbf{x} = \mathbf{0}$, should be $\mathbf{0}$.
- $(d) \iff (r)$: By definition.
- (f) \iff (i): By definition.
- $(q) \Longrightarrow (a)$: Since the rank of A and the rref of A are the same, the rref of A has rank n. Since I_n is the only possible candidate of rref having the rank n, the rref of A should be I_n .
- $(q) \iff (r)$: The rank-nullity theorem implies this.
- $(q) \iff (q'): \operatorname{rank}(A) = \operatorname{rank}(A^T).$
- $(q') \iff (r')$: The rank-nullity theorem implies this.
- $(q) \iff (r)$: The rank-nullity theorem implies this.
- (q) \Longrightarrow (m): The columns of A span the subspace of the dimension n in \mathbb{R}^n , which is \mathbb{R}^n .
- (q') \Longrightarrow (n): The columns of A^T , i.e. the (transposes of) rows of A, span the subspace of the dimension n in \mathbb{R}^n , which is \mathbb{R}^n .
- (q) \Longrightarrow (k): Suppose the contrary. Then the columns, Ae_i , of A has a linear dependency for some $a_i \in \mathbb{R}$ which are not simultaneously zero:

$$\sum_{i=1}^{n} a_i A \mathbf{e}_i = A \sum_{i=1}^{n} a_i \mathbf{e}_i = \mathbf{0}.$$

This implies $\mathbf{0} \neq \sum_{i=1}^{n} a_i \mathbf{e}_i \in \text{null}(T_A)$, which leads to a contradiction that nullity(A) > 0.

 $(r') \Longrightarrow (l)$: The analogous argument of the above works.

 $(m) \land (k) \Longrightarrow (o)$: By definition.

 $(n) \land (l) \Longrightarrow (p)$: By definition.

(o) \Longrightarrow (m): By definition.

(p) \Longrightarrow (n): By definition. (The columns of A^T is the transposes of the rows of A.)

 $(q) \iff (s)$: A has n singular values iff $A^T A$ does not have $\sigma^2 = 0$ as an eigenvalue, which is equivalent, by $(h) \iff (d) \iff (r) \iff (q)$, to that $\operatorname{rank}(A^T A) = n$. Therefore, $(s) \iff \operatorname{rank}(A^T A) = n$. Since $\operatorname{rank}(A^T A) = \operatorname{rank}(A)$, we have $(q) \iff (s)$.

(q) \iff (t): A is of rank < n iff there are vectors $\mathbf{v}_1, \ldots, \mathbf{v}_{n-1} \in \mathbb{R}^n$ such that for the i-th column A_i of A,

$$A_i = \sum_{j=1}^{n-1} c_{ij} \mathbf{v}_j$$

for some c_{ij} 's. That is,

$$A = \sum_{j=1}^{n-1} [c_{1j}, \cdots, c_{nj}] \mathbf{v}_j.$$

for some c_{ij} 's. This is equivalent to that A is a sum of < n rank-one matrices $[c_{1j}, \dots, c_{nj}]\mathbf{v}_j \ (j = 1, \dots, n-1)$.

10. (a) When n = 2,

$$A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}, \quad A^T A = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}, \quad p_{A^T A}(t) = \det(tI - A^T A) = t^2 - 3t + 1,$$
 singular values:
$$\sqrt{\frac{3 \pm \sqrt{5}}{2}} = \frac{\sqrt{5} \pm 1}{2} \approx 0.6180, \ 1.6180.$$

When n=3,

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}, \quad A^T A = \begin{bmatrix} 3 & 2 & 1 \\ 2 & 2 & 1 \\ 1 & 1 & 1 \end{bmatrix}, \quad p_{A^T A}(t) = t^3 - 6t^2 + 5t - 1,$$

singular values: 0.554958, 0.801938, 2.246980.

When n = 4,

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix}, \quad A^T A = \begin{bmatrix} 4 & 3 & 2 & 1 \\ 3 & 3 & 2 & 1 \\ 2 & 2 & 2 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix},$$

 $p_{A^TA}(t) = t^4 - 10t^3 + 15t^2 - 7t + 1 = (t-1)(t^3 - 9t^2 + 6t - 1),$

singular values: 0.532089, 0.652704, 1, 2.879385.

(b)

- n = 10: (6.6907, 2.2470, 1.3686, 1.0000, 0.8019, 0.6821, 0.6052, 0.5550, 0.5232, 0.5056)
- n = 20: (13.0539, 4.3598, 2.6262, 1.8869, 1.4792, 1.2223, 1.0466, 0.9198, 0.8248, 0.7515, ...)
- n = 30: (19.4190, 6.4787, 3.8941, 2.7889, 2.1769, 1.7890, 1.5219, 1.3272, 1.1795, 1.0639, ...)
- n = 40: (25.7847, 8.5992, 5.1647, 3.6946, 2.8794, 2.3618, 2.0045, 1.7434, 1.5445, 1.3882, ...)
- n = 50: (32.1506, 10.7203, 6.4363, 4.6018, 3.5838, 2.9370, 2.4900, 2.1629, 1.9133, 1.7169, ...)
- n = 60: (38.5166, 12.8417, 7.7085, 5.5098, 4.2893, 3.5133, 2.9768, 2.5840, 2.2841, 2.0478,...)
- n = 70: (44.8826, 14.9634, 8.9810, 6.4182, 4.9952, 4.0904, 3.4645, 3.0061, 2.6559, 2.3799, ...)
- n = 80: (51.2487, 17.0851, 10.2536, 7.3268, 5.7015, 4.6679, 3.9527, 3.4288, 3.0284, 2.7128, ...)
- n = 90: (57.6148, 19.2069, 11.5264, 8.2356, 6.4081, 5.2456, 4.4413, 3.8518, 3.4014, 3.0461, ...)
- n = 100: (63.9809, 21.3287, 12.7993, 9.1446, 7.1148, 5.8236, 4.9300, 4.2751, 3.7746, 3.3798, ...)

(c)

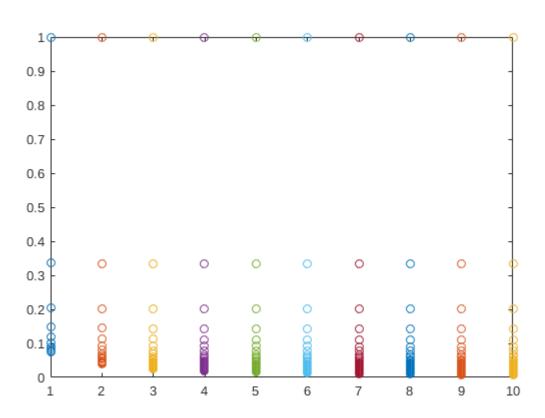


Figure 1: Figure for #10 (c)

(d) Using the SVD $A = \sigma_1 \mathbf{u}_1^T \mathbf{v}_1^T + \cdots$ of A, the closest rank-one matrix to A is

$$\sigma_1 \mathbf{u}_1^T \mathbf{v}_1^T =$$

8.4793	8.2898	7.9152	7.3638	6.6479	5.7835	4.7899	3.6893	2.5063	1.2673	
8.2898	8.1047	7.7384	7.1993	6.4994	5.6543	4.6829	3.6069	2.4503	1.2390	
7.9152	7.7384	7.3888	6.8740	6.2057	5.3988	4.4713	3.4439	2.3396	1.1830	
7.3638	7.1993	6.8740	6.3952	5.7734	5.0227	4.1598	3.2040	2.1766	1.1006	
6.6479	6.4994	6.2057	5.7734	5.2121	4.5344	3.7554	2.8925	1.9650	0.9936	
5.7835	5.6543	5.3988	5.0227	4.5344	3.9448	3.2671	2.5164	1.7095	0.8644	
4.7899	4.6829	4.4713	4.1598	3.7554	3.2671	2.7058	2.0841	1.4158	0.7159	
3.6893	3.6069	3.4439	3.2040	2.8925	2.5164	2.0841	1.6052	1.0905	0.5514	
2.5063	2.4503	2.3396	2.1766	1.9650	1.7095	1.4158	1.0905	0.7408	0.3746	
1.2673	1.2390	1.1830	1.1006	0.9936	0.8644	0.7159	0.5514	0.3746	0.1894	

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(d) Using the SVD $A = \sigma_1 \mathbf{u}_1^T \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2^T \mathbf{v}_2^T + \cdots$ of A, the closest rank-two matrix to A is

$$\sigma_1 \mathbf{u}_1^T \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2^T \mathbf{v}_2^T =$$

		-								
9.3933	9.0229	8.3220	7.3638	6.2411	5.0505	3.8758	2.7752	1.7733	0.8605	
9.0229	8.6925	8.0647	7.1993	6.1732	5.0665	3.9499	2.8739	1.8625	0.9128	
8.3220	8.0647	7.5698	6.8740	6.0247	5.0726	4.0645	3.0371	2.0134	1.0020	
7.3638	7.1993	6.8740	6.3952	5.7734	5.0227	4.1598	3.2040	2.1766	1.1006	
6.2411	6.1732	6.0247	5.7734	5.3932	4.8607	4.1622	3.2993	2.2912	1.1746	
5.0505	5.0665	5.0726	5.0227	4.8607	4.5327	4.0001	3.2494	2.2974	1.1906	
3.8758	3.9499	4.0645	4.1598	4.1622	4.0001	3.6199	2.9982	2.1488	1.1227	
2.7752	2.8739	3.0371	3.2040	3.2993	3.2494	2.9982	2.5193	1.8235	0.9582	
1.7733	1.8625	2.0134	2.1766	2.2912	2.2974	2.1488	1.8235	1.3287	0.7008	
0.8605	0.9128	1.0020	1.1006	1.1746	1.1906	1.1227	0.9582	0.7008	0.3705	