### Homework 2

#### COSC 3337 Dr.Rizk

```
In [1]: %reload_ext watermark
%watermark -d -u -a '<Kim Nguyen>' -v -p numpy,scipy,matplotlib,sklearn

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    last updated: 2020-06-18

CPython 3.7.6
    IPython 7.12.0

    numpy 1.18.1
    scipy 1.4.1
    matplotlib 3.1.3
    sklearn 0.22.1
In [2]: import numpy as np
```

## 1) Implementing an ID3 Decision Tree

### 1.1 Splitting a node

```
In [3]: def split(array):
    # your code to generate dictionary
    res = {classi: np.where(array == classi)[0] for classi in np.unique(
    array)}
    return res # return the dictionary variable

In [4]: # Double check solution
    print(split(np.array([0, 1, 2])))
    print(split(np.array([1, 0, 1, 0, 0, 1, 0])))
    print(split(np.array([1, 0, 3, 2, 0, 1, 1])))

{0: array([0]), 1: array([1]), 2: array([2])}
    {0: array([1, 3, 4, 6]), 1: array([0, 2, 5])}
    {0: array([1, 4]), 1: array([0, 5, 6]), 2: array([3]), 3: array([2])}
```

### 1.2 Implement Entropy

```
In [5]: def entropy(array):
            # your code
            N = len(array)
            counts = np.bincount(array)
            P = counts[np.nonzero(counts)]/N # avoid log(0)
            H = -np.dot(P, np.log2(P))
            return H # return a scalar
In [6]: # Double check solution
        print(round(entropy(np.array([0, 1, 0, 1, 1, 0])), 4))
        print(round(entropy(np.array([1, 2])), 4))
        print(round(entropy(np.array([1, 1])), 4))
        print(round(entropy(np.array([1, 0, 0, 0, 0, 0, 0, 0, 0, 0])), 4))
        print(round(entropy(np.array([0, 0, 0])), 4))
        print(round(entropy(np.array([1, 1, 1, 0, 1, 4, 4, 2, 1])), 4))
        1.0
        1.0
        -0.0
        0.4395
        -0.0
        1.6577
```

### 1.3 Implement Information Gain

```
In [7]: def information_gain(x_array, y_array):
    parent_entropy = entropy(x_array)

split_dict = split(y_array)

for val in split_dict.values():
    freq = val.size/x_array.size
    child_entropy = entropy([x_array[i] for i in val])
    parent_entropy -= child_entropy*freq

return parent_entropy
```

```
In [8]: # Double check solution

x = np.array([0, 1, 0, 1, 0, 1])
y = np.array([0, 1, 0, 1, 1, 1])
print(round(information_gain(x, y), 4))

x = np.array([0, 0, 1, 1, 2, 2])
y = np.array([0, 1, 0, 1, 1, 1])
print(round(information_gain(x, y), 4))
```

0.4591 0.2516

### 1.4 Decision Tree Splitting

```
In [9]: def make_tree(X, y):
        # Return array if node is empty or pure (1 example in leaf node)
            if y.shape[0] == 1 or y.shape[0] == 0:
                return y
            # Compute information gain for each feature
            gains = [information gain(x attribute,y) for x attribute in X.T] # Y
        OUR CODE
            # Early stopping if there is no information gain
            if all(eachGain <= 1e-05 for eachGain in gains):</pre>
                return y # YOUR CODE
            # Else, get best feature
            best_feature = np.argmax(gains)
            results = {}
            # Use the `split` function to split on the best feature
            subset_dict = split(X[:, best_feature])
            # Note that each entry in the dictionary returned by
            # split is an attribute value: array indices pair.
            # here, we are going to iterate over these key-value
            # pairs and select the respective examples for the
            # new child nodes
            for feature value, train example indices in subset dict.items():
                child y subset = y.take(train example indices, axis = 0) # YOUR
         CODE
                child x subset = X.take(train_example_indices, axis = 0) # YOUR
         CODE
                # Next, we are using "recursion," that is, calling the same
                # tree split function on the child subset(s)
                results["X %d = %d" % (best_feature, feature_value)] = \
                    make_tree(child_x_subset, child_y_subset)
            return results
```

```
In [10]: # Double check solution
                                                   x1 = np.array([0, 0, 1, 1, 2, 2])
                                                   x2 = np.array([0, 1, 0, 1, 0, 1])
                                                   X = np.array([x1, x2]).T
                                                   y = np.array([0, 1, 0, 1, 1, 1])
                                                    print('Inputs:\n', X)
                                                   print('\nLabels:\n', y)
                                                   print('\nDecision tree:\n', make_tree(X, y))
                                                   Inputs:
                                                        [[0 0]]
                                                        [0 1]
                                                        [1 0]
                                                        [1 1]
                                                        [2 0]
                                                        [2 1]]
                                                  Labels:
                                                        [0 1 0 1 1 1]
                                                  Decision tree:
                                                        \{'X_1 = 0': \{'X_0 = 0': array([0]), 'X_0 = 1': array([0]), 'X_0 = 2': array([0]), 'X_0 = 
                                                   array([1]), 'X_1 = 1': array([1, 1, 1])}
```

### 1.5 Building a Decision Tree API

```
In [11]: class ID3DecisionTreeClassifer(object):
             def __init__(self):
                 pass
             def fit(self, X, y):
                 self.splits_ = make_tree(X,y) #YOUR CODE
             def _majority_vote(self, label_array):
                 return np.argmax(np.bincount(label_array)) #YOUR CODE
             def _traverse(self, x, d):
                 if isinstance(d, np.ndarray):
                     return d
                 for key in d:
                     name, value = key.split(' = ')
                     feature_idx = int(name.split('_')[-1])
                     value = int(value)
                     if x[feature_idx] == value:
                         return self. traverse(x, d[key])
             def predict(self, x):
                 label_array = self._traverse(x,self.splits_) #YOUR CODE to get c
         lass labels from the target node
                 return self. majority vote(label array) #YOUR CODE to predict th
         e class label via majority voting from label array
```

```
In [12]: # Double check solution

tree = ID3DecisionTreeClassifer()
tree.fit(X, y)

print(tree.predict(np.array([0, 0])))
print(tree.predict(np.array([0, 1])))
print(tree.predict(np.array([1, 0])))
print(tree.predict(np.array([1, 0])))
print(tree.predict(np.array([1, 1])))
print(tree.predict(np.array([2, 0])))
print(tree.predict(np.array([2, 0])))
print(tree.predict(np.array([2, 1])))
```

### 2) Bagging

### 2.1 Bootrapping

```
In [13]: # DO NOT EDIT OR DELETE THIS CELL
         from mlxtend.data import iris data
         X, y = iris_data()
         print('Number of examples:', X.shape[0])
         print('Number of features:', X.shape[1])
         print('Unique class labels:', np.unique(y))
         Number of examples: 150
         Number of features: 4
         Unique class labels: [0 1 2]
In [14]: from sklearn.model_selection import train_test_split #YOUR CODE
         X_train, X_test, y_train, y_test = train_test_split(X, y, test_size = 45
         , random_state=123, stratify=y) # YOUR CODE
         print('Number of training examples:', X train.shape[0])
         print('Number of test examples:', X_test.shape[0])
         Number of training examples: 105
         Number of test examples: 45
In [15]: # Double check solution
         print('Number of training examples:', X_train.shape[0])
         print('Number of test examples:', X_test.shape[0])
         Number of training examples: 105
         Number of test examples: 45
In [16]: def draw bootstrap sample(rng, X, y):
             sample_indices = np.arange(X_train.shape[0]) # YOUR CODE
             bootstrap_indices = rng.choice(sample_indices,size=sample_indices.sh
         ape[0]) # YOUR CODE
             return X[bootstrap_indices], y[bootstrap_indices] # YOUR CODE
```

### 2.2 Bagging classifier from decision trees

```
In [18]: from sklearn.tree import DecisionTreeClassifier
         class BaggingClassifier(object):
             def __init__(self, num_trees=10, random_state=123):
                 self.num_trees = num_trees
                 self.rng = np.random.RandomState(random state)
             def fit(self, X, y):
                 self.trees_ = [DecisionTreeClassifier(random_state=self.rng) for
         i in range(self.num trees)]
                 for i in range(self.num_trees):
                     X boot, y boot = draw bootstrap sample(self.rng, X, y) #YOUR
         CODE
                     # YOUR CODE to
                     # fit the trees in self.trees on the bootstrap samples
                     self.trees [i].fit(X boot, y boot) #YOUR CODE
             def predict(self, X):
                 ary = np.zeros((X.shape[0], len(self.trees )), dtype=np.int)
                 for i in range(len(self.trees_)):
                     ary[:, i] = self.trees_[i].predict(X)
                 maj = np.apply along axis(lambda x:
                                                np.argmax(np.bincount(x)),
                                                axis=1,
                                                arr=ary)
                 return maj
```

```
In [19]: # Double check solution
         model = BaggingClassifier()
         model.fit(X_train, y_train)
         predictions = model.predict(X_test)
         print('Individual Tree Accuracies:')
         for tree in model.trees_:
             predictions = tree.predict(X_test)
             print('%.1f%%' % ((predictions == y_test).sum() / X_test.shape[0] *
         100))
         print('\nBagging Test Accuracy: %.1f%%' % ((predictions == y_test).sum()
         / X_test.shape[0] * 100))
         Individual Tree Accuracies:
         88.9%
         93.3%
         97.8%
         93.3%
         93.3%
         93.3%
         91.1%
         97.8%
         97.8%
         97.8%
```

## 3) Bias-Variance Decomposition

Bagging Test Accuracy: 97.8%

3.1 Bias\_Variance decomposition of the 0-1 Loss for Decision Trees

```
In [20]: # DO NOT EDIT OR DELETE THIS CELL
         rng = np.random.RandomState(123)
         num_bootstrap = 200
         all_pred = np.zeros((num_bootstrap, y_test.shape[0]), dtype=np.int)
         for i in range(num_bootstrap):
             X_boot, y_boot = draw_bootstrap_sample(rng, X_train, y_train)
             pred = DecisionTreeClassifier(random_state=66).fit(X_boot, y_boot).p
         redict(X_test)
             all_pred[i] = pred
         main predictions = np.apply along axis(lambda x:
                                                 np.argmax(np.bincount(x)),
                                                 axis=0,
                                                 arr=all_pred)
In [21]: # YOUR CODE
         avg_bias = round(np.sum(main_predictions != y_test) / y_test.size,4)
         print("Average Bias: ", avg_bias)
         Average Bias: 0.0222
In [22]: # YOUR CODE
         # you probably need multiple
         # lines of code and a for-loop
         var = np.zeros(pred.shape)
         for pred in all pred:
             var += (pred != main_predictions).astype(np.int)
         var /= num_bootstrap
         avg_var = round(var.sum()/y_test.shape[0],4)
         print("Average variance: ", avg_var)
```

Average variance: 0.0346

#### 3.2 Bias\_Variance decomposition of the 0-1 Loss for Bagging

```
In [23]: # YOUR SOLUTION
         # Many lines of code (which you may copy and modify from 3.1)
         rng = np.random.RandomState(123)
         num_bootstrap = 200
         all_pred = np.zeros((num_bootstrap, y_test.shape[0]), dtype=np.int)
         for i in range(num bootstrap):
             X boot, y boot = draw bootstrap sample(rng, X train, y train)
             model = BaggingClassifier()
             model.fit(X_boot, y_boot)
             pred= model.predict(X_test)
             all_pred[i] = pred
         main predictions = np.apply along axis(lambda x:
                                                 np.argmax(np.bincount(x)),
                                                 axis=0,
                                                 arr=all pred)
In [24]: # YOUR CODE
         avg bias = round(np.sum(main predictions != y_test) / y_test.size,4)
         print("Average Bias: ", avg_bias)
         Average Bias: 0.0222
In [25]: # YOUR CODE
         # you probably need multiple
         # lines of code and a for-loop
         var = np.zeros(pred.shape)
         for pred in all pred:
             var += (pred != main_predictions).astype(np.int)
         var /= num_bootstrap
         avg_var = round(var.sum()/y_test.shape[0],4)
         print("Average variance: ", avg_var)
```

# Compare to the Bias\_Variance decomposition of the 0-1 Loss for Decision Trees in 3.1

```
\#\#\# \Rightarrow Average Bias is the same (0.0222) \#\#\# \Rightarrow Average variance is lower than in 3.1 (0.0281 < 0.0346)
```

### 3.3 Bias-Variance decomposition of the 0-1 Loss for AdaBoost

Average variance: 0.0281

```
In [26]: # YOUR SOLUTION
         # Many lines of code (which you may copy and modify from 3.1)
         from sklearn.ensemble import AdaBoostClassifier
         rng = np.random.RandomState(123)
         num bootstrap = 200
         all pred = np.zeros((num bootstrap, y test.shape[0]), dtype=np.int)
         for i in range(num_bootstrap):
             X boot, y boot = draw bootstrap_sample(rng, X train, y train)
             pred = AdaBoostClassifier(random state=66).fit(X boot, y boot).predi
         ct(X_test)
             all pred[i] = pred
         main_predictions = np.apply_along_axis(lambda x:
                                                 np.argmax(np.bincount(x)),
                                                 axis=0,
                                                 arr=all pred)
In [27]: # YOUR CODE
         avg bias = round(np.sum(main predictions != y test) / y test.size,4)
         print("Average Bias: ", avg_bias)
         Average Bias: 0.0444
In [28]: var = np.zeros(pred.shape)
         for pred in all_pred:
             # (np.array(something) == np.array(something)).astype(np.int), the c
         ondition is only for numpy array
             var += (pred != main predictions).astype(np.int)
         var /= num bootstrap
         avg_var = round(var.sum()/y_test.shape[0],4)
         print("Average variance: ", avg_var)
         Average variance: 0.0328
```

# Compare to the Bias\_Variance decomposition of the 0-1 Loss for Decision Trees in 3.1

```
### => Average Bias is higher than in 3.1 (0.0444 > 0.0222)
### => Average variance is a little lower than in 3.1 (0.0328 > 0.0346)
In [ ]:
```