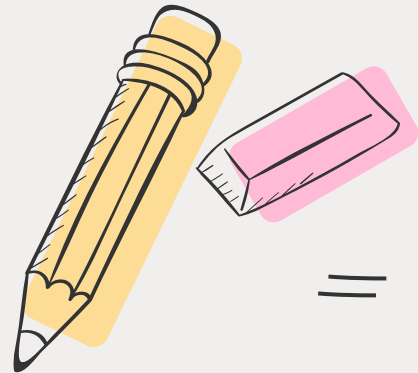


# Divide and Conquer Algorithm


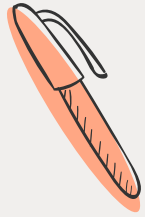



Group 8





# Idea

- 
- 
- The basic idea is to decompose a given problem into independent and simpler sub-problems, to solve them in turn, and to compose their solutions to solve the given problem.
  - Sub-problems must be **independent**. (Ex: Fibonacci)
- 



# Framework

3



## Divide

The problem is divided into smaller sub-problems that are similar to the original problem but of smaller size.



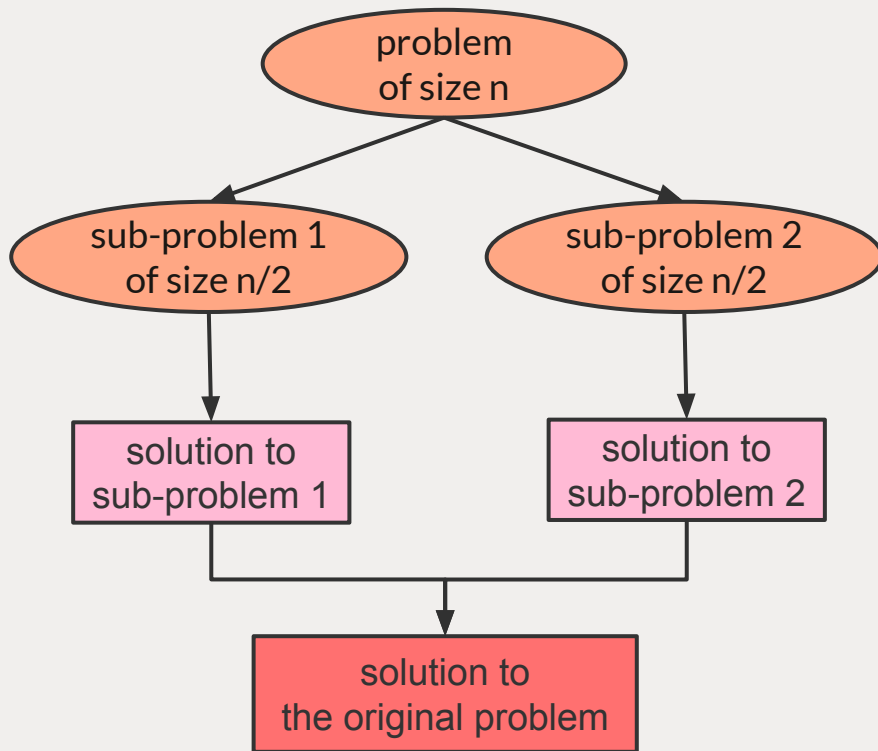
## Conquer

The sub-problems are solved recursively using the same algorithm until they become simple enough to be solved directly.




## Combine

The solutions to the sub-problems are combined to solve the original problem.






# Specification



The problem must be able to divide into sub-problems similar to the big problem but with a smaller size.



# Algorithm

```
DAC(a, i, j)
{
    if(small(a, i, j)
        return(Solution(a, i, j))
    else
        mid = divide(a, i, j)
        b = DAC(a, i, mid)
        c = DAC(a, mid+1, j)
        d = combine(b, c)
    return(d)
}
```

# Time Complexity

size of input

**n**

size of each sub-problem; all sub-problems  
are assumed to have the same size

**n/b**

$$T(n) = aT(n/b) + f(n)$$

**a**

number of sub-problems  
in the recursion

**f(n)**

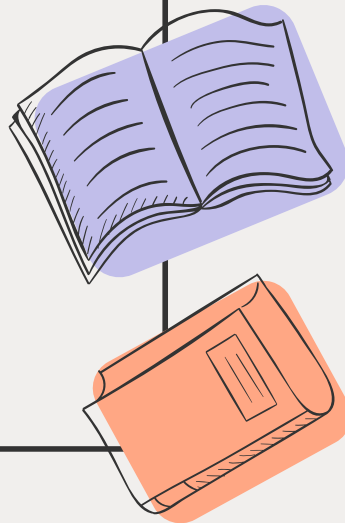
cost of the work done outside the  
recursive call, which includes the  
cost of dividing the problem and  
cost of merging the solutions



# Master Theorem

If  $f(n) \in \theta(n^d)$  where  $d \geq 0$  in recurrence  $T(n) = aT(n/b) + f(n)$ , then

$$T(n) \in \begin{cases} \theta(n^d) & \text{if } a < b^d \\ \theta(n^d \log n) & \text{if } a = b^d \\ \theta(n^{\log_b a}) & \text{if } a > b^d \end{cases}$$





# Binary Search



2

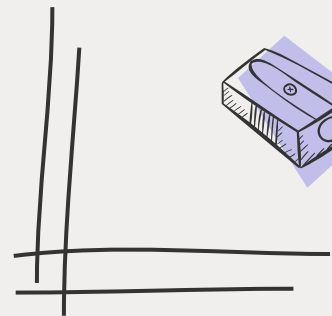
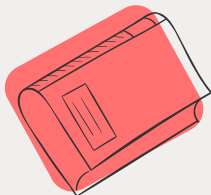
## Idea

A searching algorithm used in a sorted array by repeatedly dividing the search interval in half

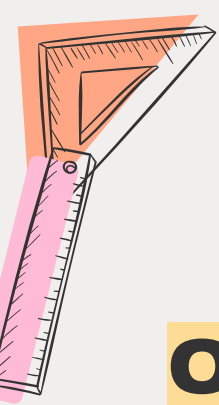


## Conditions

- The data structure must be sorted
- Access to any element of the data structure takes constant time







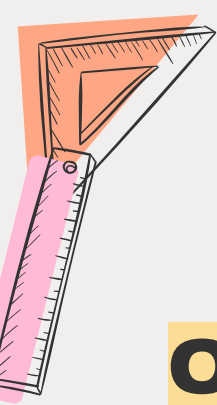
# Binary Search

**01**

Set the low index to the first element of the array and the high index to the last element.

	0	1	2	3	4	5	6	7	8	9
Search 23	2	5	8	12	16	23	38	56	72	91



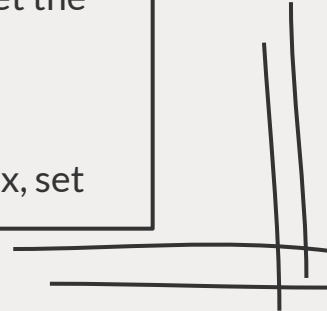


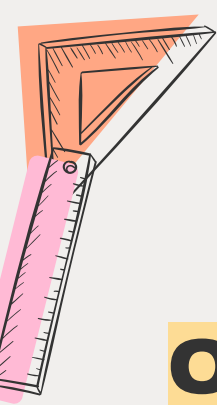
# Binary Search

Set the middle index to the average of the low and high indices.

02

- If the element at the middle index is the target element, return the middle index.
- Otherwise, based on the value of the key to be found and the value of the middle element, decide the next search space.
  - If the target is less than the element at the middle index, set the high index to **middle index - 1**.
  - If the target is greater than the element at the middle index, set the low index to **middle index + 1**.





# Binary Search

**02**

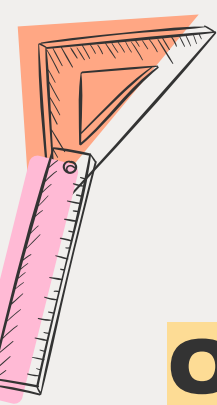
$23 > 16$   
take 2<sup>nd</sup> half

L=0	1	2	3	M=4	5	6	7	8	H=9
2	5	8	12	16	23	38	56	72	91

$23 < 16$   
take 1<sup>st</sup> half

0	1	2	3	4	L=5	6	M=7	8	H=9
2	5	8	12	16	23	38	56	72	91





# Binary Search

**03**

Perform step 2 repeatedly until the target element is found or the search space is exhausted.


Found 23,  
Return 5

0	1	2	3	4	L=5 M=5	H=6	7	8	9
2	5	8	12	16	23	38	56	72	91







# Binary Search



```
binarySearch(arr, x, low, high)
  if low > high
    return False
  else
    mid = (low + high) / 2
    if x == arr[mid]
      return mid
    else if x > arr[mid]
      return binarySearch(arr, x, mid + 1, high)
    else
      return binarySearch(arr, x, low, mid - 1)
```





# Binary Search



2

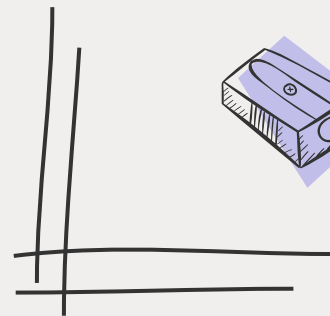
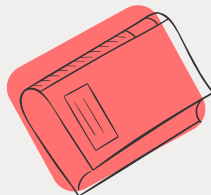
## Time Complexity

$O(\log n)$

!!

## Auxiliary Space

$O(1)$ , if the recursive call stack is considered then the auxiliary space will be  $O(\log n)$





# Merge Sort

2

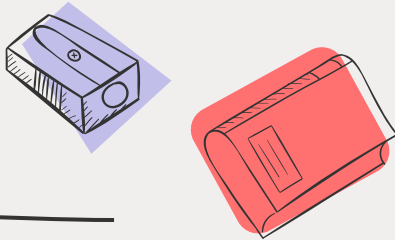
## Sorting algorithm

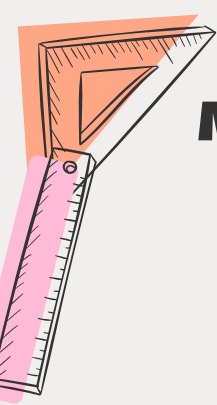
Dividing the array into 2 halves, recursively sorting them, and finally merging the 2 sorted halves to get the original array sorted.

!!

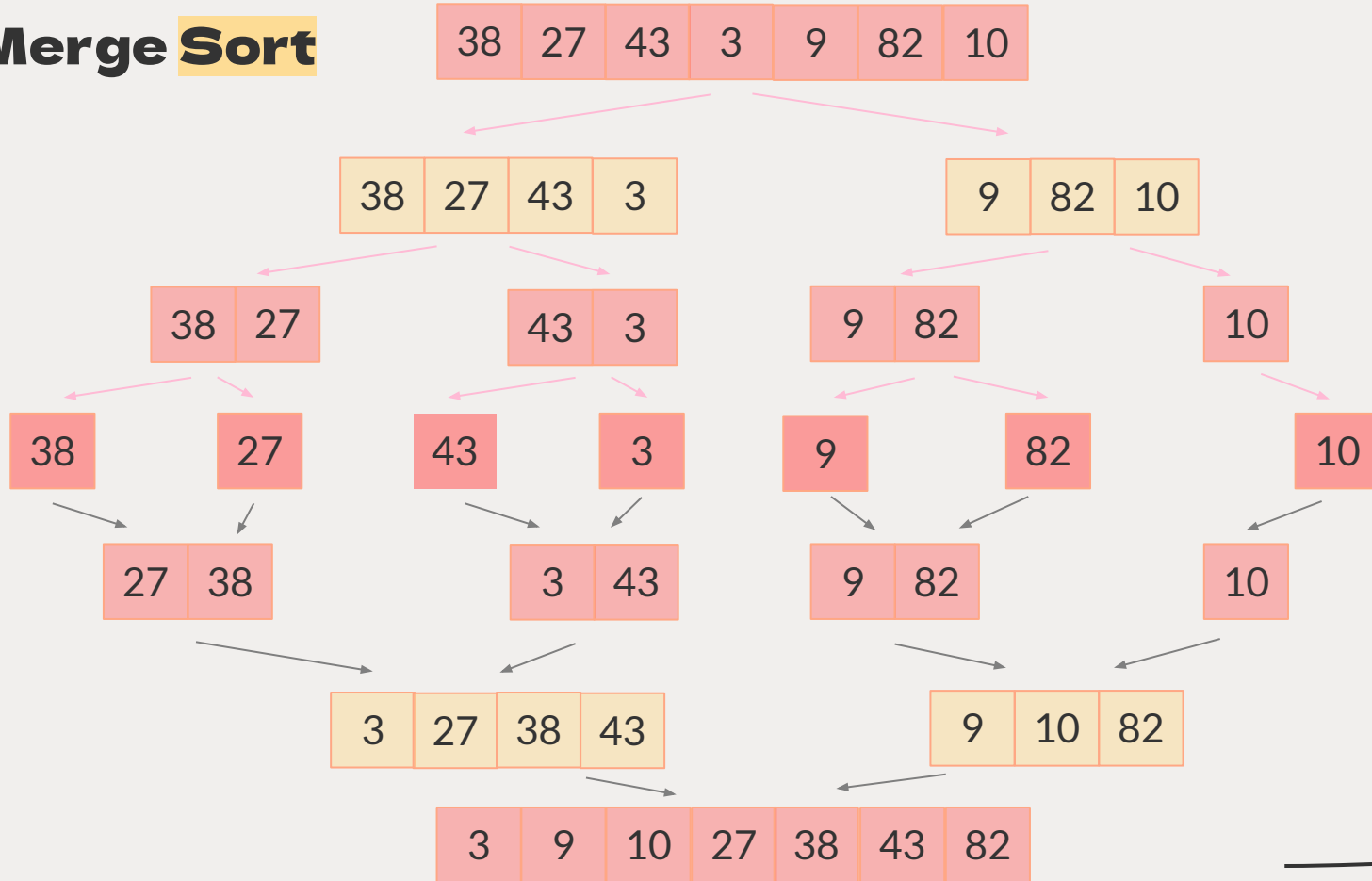
## Time complexity

$O(n \log n)$





# Merge Sort





# Merge Sort

```
mergeSort(arr, left, right)
  if left > right
    return
  mid = (left + right) / 2
  mergeSort(arr, left, mid)
  mergeSort(arr, mid + 1, right)
  merge(arr, left, mid, right)
```



# Quick Sort

2

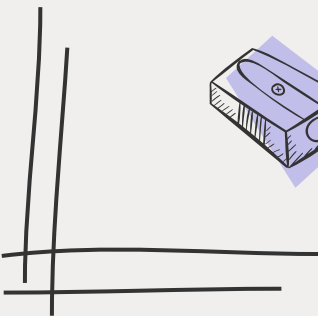
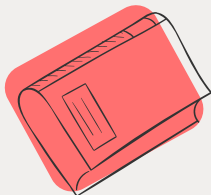
## Sorting algorithm

Picking an element as a pivot and partitioning the given array around the picked pivot

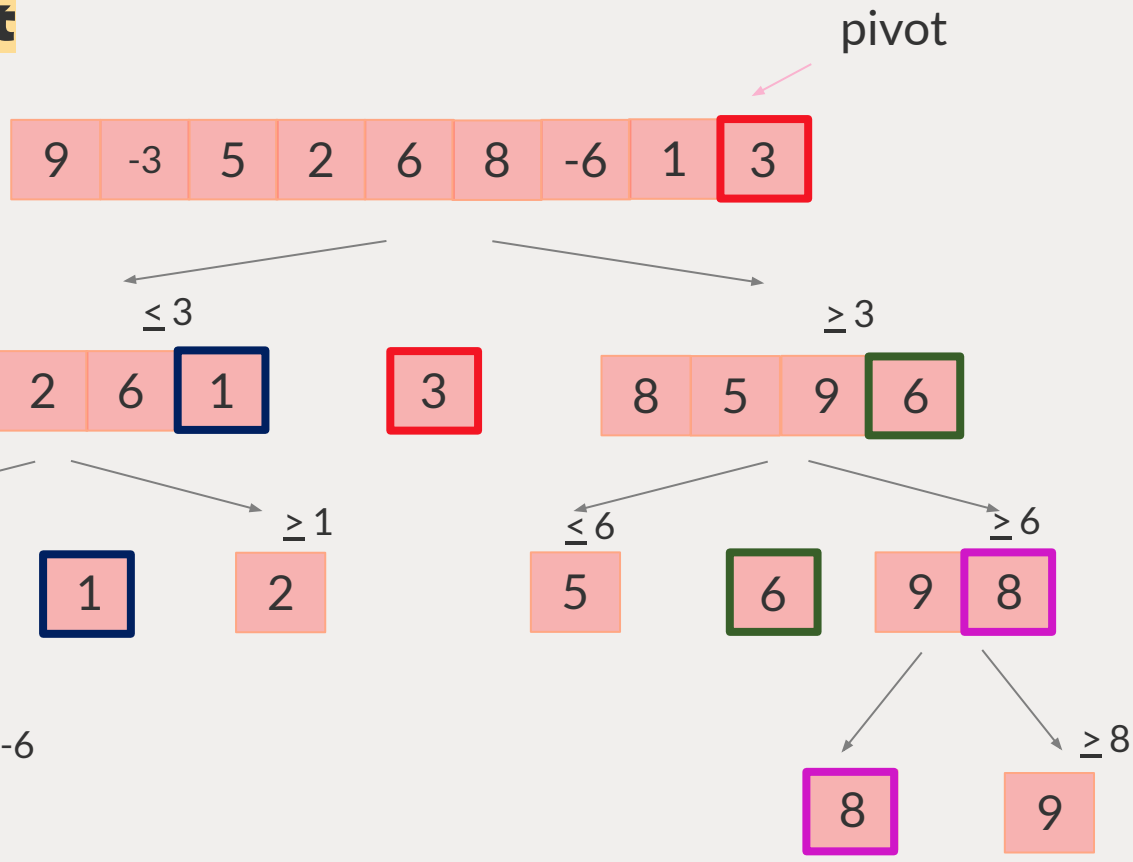
!!

## Time complexity

$O(n \log n)$



# Quick Sort



# Quick Sort

```
quickSort(arr, low, high)
  if low < high
    pi = partition(arr, low, high)
    quickSort(arr, low, pi - 1)
    quickSort(arr, pi + 1, high)
```



# Applications



**Binary  
Search**



**Merge Sort  
Quick Sort**



**Median  
Finding**



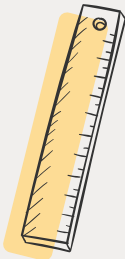
**Fast  
Power**



**Matrix  
Multiplication**



**Closest Pair  
Problem**





# Basic Matrix Multiplication

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}, \quad \mathbf{B} = \begin{pmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{pmatrix}$$

$$\mathbf{C} = \begin{pmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mp} \end{pmatrix}$$

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \cdots + a_{in}b_{nj} = \sum_{k=1}^n a_{ik}b_{kj},$$

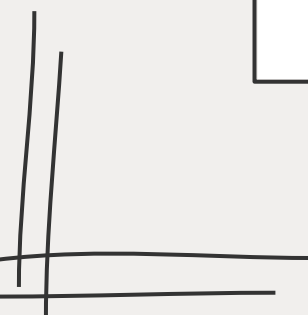




# Basic Matrix Multiplication

```
for i ← 1 to n do
  for j ← 1 to n do
     $c_{ij} \leftarrow 0$ 
    for k ← 1 to n do
       $c_{ij} = c_{ij} + a_{ik} \times b_{kj}$ 
```

**Time complexity**

$$O(n^3)$$




# DAC Matrix Multiplication

$n \times n$  matrix =  $2 \times 2$  matrix of  $(n/2) \times (n/2)$  submatrices:

$$\begin{bmatrix} r & s \\ t & u \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \cdot \begin{bmatrix} e & f \\ g & h \end{bmatrix}$$
$$C = A \cdot B$$

$$\begin{aligned} r &= ae + bg \\ s &= af + bh \\ t &= ce + dh \\ u &= cf + dh \end{aligned}$$

8 mults of  $(n/2) \times (n/2)$  submatrices  
4 adds of  $(n/2) \times (n/2)$  submatrices





# DAC Matrix Multiplication

SQUARE-MATRIX-MULTIPLY-RECURSIVE( $A, B$ )

```
1   $n = A.rows$ 
2  let  $C$  be a new  $n \times n$  matrix
3  if  $n == 1$ 
4       $c_{11} = a_{11} \cdot b_{11}$ 
5  else partition  $A, B$ , and  $C$  as in equations (4.9)
6       $C_{11} = \text{SQUARE-MATRIX-MULTIPLY-RECURSIVE}(A_{11}, B_{11})$ 
           +  $\text{SQUARE-MATRIX-MULTIPLY-RECURSIVE}(A_{12}, B_{21})$ 
7       $C_{12} = \text{SQUARE-MATRIX-MULTIPLY-RECURSIVE}(A_{11}, B_{12})$ 
           +  $\text{SQUARE-MATRIX-MULTIPLY-RECURSIVE}(A_{12}, B_{22})$ 
8       $C_{21} = \text{SQUARE-MATRIX-MULTIPLY-RECURSIVE}(A_{21}, B_{11})$ 
           +  $\text{SQUARE-MATRIX-MULTIPLY-RECURSIVE}(A_{22}, B_{21})$ 
9       $C_{22} = \text{SQUARE-MATRIX-MULTIPLY-RECURSIVE}(A_{21}, B_{12})$ 
           +  $\text{SQUARE-MATRIX-MULTIPLY-RECURSIVE}(A_{22}, B_{22})$ 
10 return  $C$ 
```

**Time complexity**

$$T(n) = \Theta(n^{\log_2 8}) = \Theta(n^3)$$



# Strassen's Matrix

Multiply  $2 \times 2$  matrices with only 7 recursive mults.

$$\begin{aligned}P_1 &= a \cdot (f - h) \\P_2 &= (a + b) \cdot h \\P_3 &= (c + d) \cdot e \\P_4 &= d \cdot (g - e) \\P_5 &= (a + d) \cdot (e + h) \\P_6 &= (b - d) \cdot (g + h) \\P_7 &= (a - c) \cdot (e + f)\end{aligned}$$

$$\begin{aligned}r &= P_5 + P_4 - P_2 + P_6 \\s &= P_1 + P_2 \\t &= P_3 + P_4 \\u &= P_5 + P_1 - P_3 - P_7\end{aligned}$$

**Time complexity**

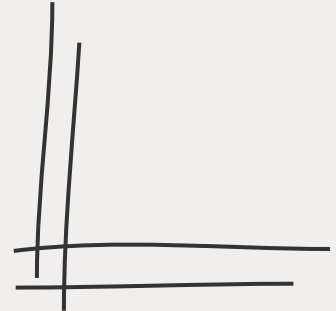
$$T(n) = \Theta(n^{\log_2 7})$$





# Strassen's Matrix

**Note:** If  $n$  is small enough, 7 mults and 18 adds or subs the matrix may run slower than basic multiplication, so the algorithm is usually only run until it reaches the predetermined threshold and then fallbacks to multiply by definition.





# Advantages



**solving  
difficult  
problems**



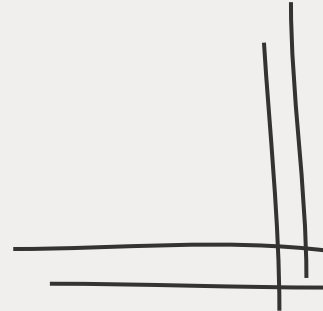
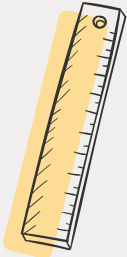
**algorithm  
efficiency**



**parallelism**



**memory  
access**



# Disadvantages



**overhead**



**memory  
limitations**



**difficulty of  
implementation**

