

# Introduction to Assembly Programming

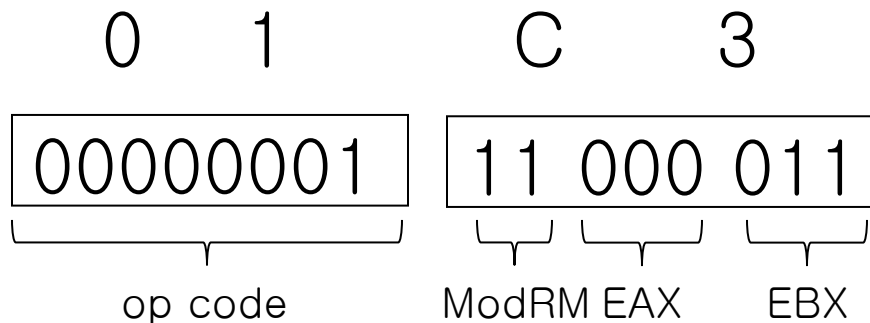


# Assembly language

- Reasons for assembly programming
  - To improve performance
  - There are sections of code which must be written in assembly language
  - To learn how a particular CPU works
- Assembly language is
  - Machine dependent
  - But it follows universal format

# Machine language vs. Assembly language

- Ex) To add *EAX* and *EBX* registers together and store the result back into *EAX*
- Machine language: numerical-coded instruction



- Assembly language  
*add eax, ebx*

# The four field format

- Assembly language program consists of lines
- Every statement in a line consists of four fields
  - label field
  - mnemonic (opcode) field
  - operand field
  - comment field

<b>LABEL</b>	<b>OPCODE</b>	<b>OPERANDS</b>	<b>COMMENT</b>
DATA1	<b>db</b>	00001000b	;Define DATA1 as decimal 8
START:	<b>mov</b>	eax, ebx	;Copy ebx to eax

# The four field format

- Label field
  - specifies the target of a jump instruction
  - jump is the same as *goto*
- Mnemonic (opcode) field
  - an instruction specifier
  - *MOV, ADD, SUB*, etc
  - the word mnemonic suggests that it makes the machine code easy to remember

# The four field format

- Operand field
  - objects on which the instruction is operating
  - Each instruction have a fixed number of operands (0 ~ 3)
    - *ADD* takes two operands, *JMP* takes one operand, ...
  - if there is more than one operand, they are separated by commas
  - Operands can have the following types: register, memory, immediate, implied
- Comment field
  - contains documentation
  - It begins with semicolon
  - documentation is especially important in assembly language, because it is hard to read
  - A line may consist of nothing but a comment

# Example program

```
;
; Greatest common divisor program
;
MOV EDX, 0      ; 0 is the only Edlinas input port
IN EAX,[DX]     ; Get the user's first input
MOV ECX, EAX    ; Get the input out of harm's way
IN EAX,[DX]     ; Get the user's second input
MOV EDX, EAX    ; Use EDX for the larger of the two inputs
ORD: SUB EAX, ECX ; Use EAX as a working copy of EDX
     JZ GCD      ; When equality is obtained we are done.
     JNS NXT     ; We want EDX to be larger. No swap needed
     MOV EAX, ECX ; Swap EDX and ECX (Takes three MOV's)
     MOV ECX, EDX
NXT:  MOV EDX, EAX ; If there was no swap then EDX = EDX-ECX
     JMP ORD     ; End of the loop
GCD:  MOV EAX, EDX ; The GCD is in EDX
     MOV EDX, 1  ; We need EDX for the output port number
     OUT [DX],EAX ; Display the answer to the user
     RET
```

# The *MOV* instruction

- *MOV* reg, imm
  - Reg stands for register
  - Imm stands for immediate value
  - Example
    - *MOV EAX, 54*
    - *MOV AX, 036H*
    - *MOV AL, 'A'*
    - *MOV AL, -129 ; not valid*
    - *MOV AL, 999 ; not valid*



# The *MOV* instruction

- *MOV reg, reg*
  - Copies from the second reg into the first one
  - Example
    - *MOV EAX, EBX*
    - *MOV EBX, DX* ; **not valid**
- Ambiguity problem: *MOV BL, AH*
  - *AH* : register 'AH' or hex number 'A'
  - NASM requires all hex numbers begin with one of the digits 0, 1, ..., 9. -> *AH* is the name of register!

# Addition Instruction

- *ADD reg, imm*
  - Add the immediate value *imm* to the register *reg*
  - Example
    - *ADD BL, 10 ; let  $BL = BL + 10$*
- *ADD reg, reg*
  - Add the contents of the second register to the first one
  - Example
    - *ADD BL, AL ; let  $BL = BL + AL$  - **AL is not changed !!***

# Subtraction Instruction

- *SUB reg, imm*
  - Subtract the immediate value from the register
  - Example
    - *SUB BL, 10 ; let  $BL = BL - 10$*
- *SUB reg, reg*
  - Subtract the contents of the second register from the first
  - Example
    - *SUB BL, AL ; let  $BL = BL - AL$  ,  $AL$  is not changed*

# Multiplication Instruction

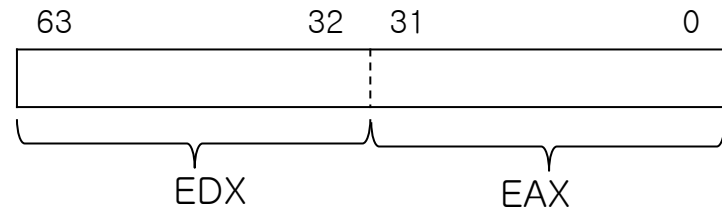
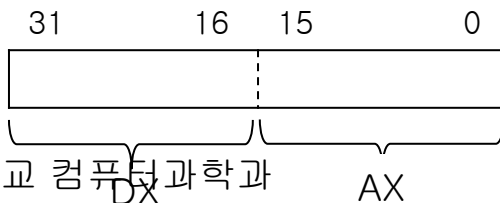
- *MUL reg*
  - Multiplier is in *reg*
  - Multiplicand is always in *A* register and result are always in *A* and *D* register
  - *MUL* command has **no immediate form**
  - Example

- *MUL BH* ; let  $AX = AL \times BH$
- *MUL BX* ; let  $DX:AX = AX \times BX$
- *MUL EBX* ; let  $EDX:EAX = EAX \times EBX$

$P \times Q$

← multiplicand  
곱해지는 수/피승수  
A 레지스터

← Multiplier  
곱하는 수/승수  
오퍼랜드에 표기



# Division Instruction

- *DIV reg*
  - *DIV* resemble *MUL* syntax; and is essentially its inverse

	dividend	remainder	quotient
32-bit form	<i>EDX:EAX</i>	<i>EDX</i>	<i>EAX</i>
16-bit form	<i>DX:AX</i>	<i>DX</i>	<i>AX</i>
8-bit form	<i>AX</i>	<i>AH</i>	<i>AL</i>

- Example

- When  $AX = 17, BH = 3$

*DIV BH* ;  $AH = 2$  and  $AL = 5$

$P \div Q$

dividend  
나눠는수/피젯수  
A와 D 레지스터

divisor  
나누는수/젯수  
오퍼랜드에 표기

# Constants

- Numeric constants

```
mov     ax, 100           ; decimal
mov     ax, 0a2h          ; hex
mov     ax, $0a2          ; hex again: the 0 is required
mov     ax, 0xa2          ; hex yet again
mov     ax, 777q           ; octal
mov     ax, 777o           ; octal again
mov     ax, 10010011b      ; binary
```

- Character constants

- A character constant consists of up to four characters enclosed in either single or double quotes.
- A character constant with more than one character will be arranged with little-endian order in mind

```
mov     eax, 'abcd'
```

# Constants

- String constants
  - only acceptable to some pseudo-instructions

```
db      'hello'                ; string constant
db      'h','e','l','l','o'    ; equivalent character constants
dd      'ninechars'            ; doubleword string constant
dd      'nine','char','s'      ; becomes three doublewords
db      'ninechars',0,0,0      ; and really looks like this
```

- Floating-point constants

```
dd      1.2                    ; an easy one
dq      1.e10                  ; 10,000,000,000
dq      1.e+10                 ; synonymous with 1.e10
dq      1.e-10                 ; 0.000 000 000 1
dt      3.141592653589793238462 ; pi
```

# Pseudo-Instructions and Directives

- To instruct the assembler to do something or inform the assembler of something
  - Define constants
  - Define memory to store data into
  - Group memory into segments
  - Conditionally include source code
  - Include other files



# Pseudo-Instructions

- DB and friends: declaring initialized data

L1 *db* 0x55 ; byte labeled L1 with initial value 0x55

L2 *db* 0x55, 0x56, 0x57 ; three bytes in succession

L3 *db* 'a', 0x55 ; character constants are OK

L4 *db* 'hello', 13, 10, '\$' ; so are string constants

L5 *dw* 0x1234 ; 0x34 0x12

L6 *dw* 'a' ; 0x61 0x00 (it's just a number)

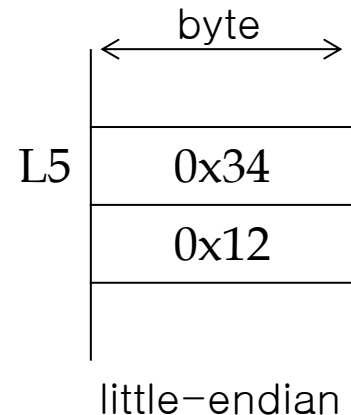
L7 *dw* 'ab' ; 0x61 0x62 (character constant)

L8 *dw* 'abc' ; 0x61 0x62 0x63 0x00 (string)

L9 *dd* 0x12345678 ; 0x78 0x56 0x34 0x12

L10 *dd* 1.234567e20 ; floating point constant

L11 *dq* 1.234567e20 ; double-precision float



# Pseudo-Instructions

- RESB and friends: declaring uninitialized data

buffer     *resb*    64                 ; *reserve 64 bytes*

wordvar   *resw*    1                 ; *reserve a word*

doublevar  *resd*    2                 ; *reserve two doubles*

realarray  *resq*   10                 ; *array of 10 reals*

- TIMES: prefix to repeat instructions or data

zerobuf    *times* 64  *db* 0             ; *reserve 64 bytes*

buf        *times* 100 *resb* 1           ; *same as resb 100*

buffer  *db* 'hello, world'             ; *to make the total length of*  
          *times* 64-(\$-buffer) *db* ' '   ; *buffer up to 64*

- EQU: defining constants

ten  *equ* 10

# Directives

- SECTION or SEGMENT
  - Defines and changes segments
  - Segment names: *.text .data .bss*
- GLOBAL
  - Exports symbols to other modules  
*global \_main*  
*\_main:*  
*; som code*
- EXTERN
  - Imports symbols from other modules  
*extern \_printf, \_scanf*

# Hello, World

- *Hello World (using ld):*

```
msg      section .data
len      db    'Hello, world!',0x0A
          equ $ - msg          ;length of hello string.

          section .text
_start:  global _start          ;must be declared for linker (ld)
          ;we tell linker where is entry point
          mov eax, 4             ;system call number (sys_write)
          mov ebx, 1             ;file descriptor (stdout)
          mov ecx, msg           ;message to write
          mov edx, len           ;message length
          int 0x80               ;call kernel

          mov eax, 1             ;system call number (sys_exit)
          xor ebx, ebx           ;exit status of this program
          int 0x80
```

# Hello, World

- To produce *hello.o* **object file**:

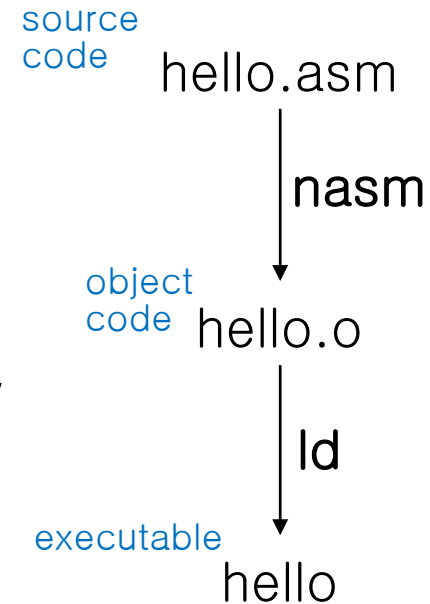
*\$ nasm -f elf hello.asm*

- To produce *hello.lst* **list file** too:

*\$ nasm -f elf hello.asm -l hello.lst*

- To produce *hello* **ELF executable**:

*\$ ld -s -o hello hello.o*



# hello.lst

```
1                                     section .data
2
3 00000000 48656C6C6F2C20776F-   msg    db    "Hello, world!",0xA
4 00000009 726C64210A
5                                     len    equ    $ - msg
6
7                                     section .text
8                                     global _start
9                                     _start:
10 00000000 B804000000               mov     eax,4
11 00000005 BB01000000               mov     ebx,1
12 0000000A B9[00000000]             mov     ecx,msg
13 0000000F BA0E000000               mov     edx,len
14 00000014 CD80                     int     0x80
15
16 00000016 B801000000               mov     eax,1
17 0000001B 31DB                     xor     ebx,ebx
18 0000001D CD80                     int     0x80
```