## Graph

- Introduction
- Graph API
- **Elementary Graph Operations** 
  - DFS: Depth first search
  - BFS: Breadth first search
  - CC: Connected Components

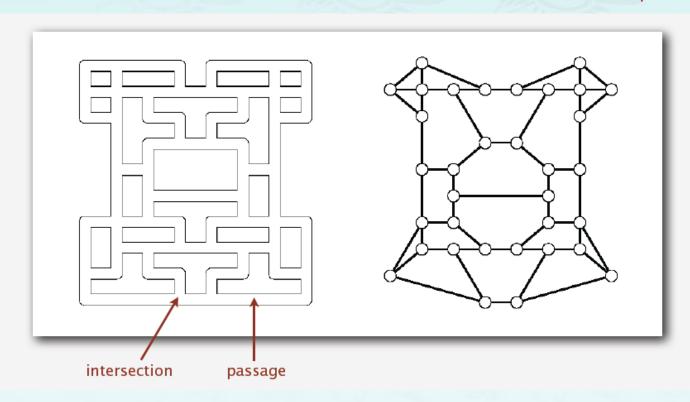
#### Major references:

- Fundamentals of Data Structures by Horowitz, Sahni, Anderson-Freed, Algorithms 4<sup>th</sup> edition Part 1 & Part 2 by Robert Sedgewick and Kevin Wayne
- Wikipedia and many resources available from internet

## Algorithm:

- Vertex = intersection
- Edge = passage

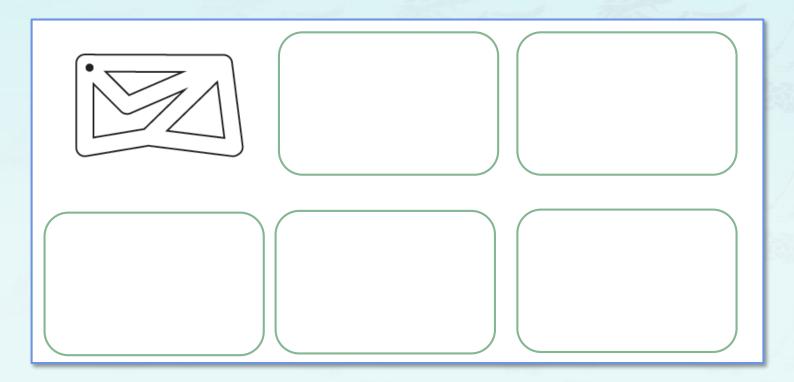
pacman



Maze Goal: Explore every intersection in the maze.

#### Maze graph:

- Unroll a ball of string behind you.
- Mark each visited intersection and each visited passage.
- Retrace steps when no unvisited options



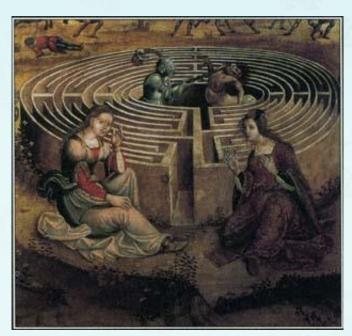
Maze Goal: Explore every intersection in the maze.

Good Visualization: https://www.cs.usfca.edu/~galles/visualization/DFS.html



#### Maze graph:

- Unroll a ball of string behind you.
- Mark each visited intersection and each visited passage.
- Retrace steps when no unvisited options



Theseus, a hero of Greek mythology, is best known for slaying a monster called the Minotaur. When Theseus entered the Labyrinth where the Minotaur lived, he took a ball of <u>yarn</u> to unwind and mark his route. Once he found the Minotaur and killed it, Theseus used the string to find his way out of the maze.

Read more: <a href="http://www.mythencyclopedia.com/Sp-Tl/Theseus.html#ixzz30wFO3ofe">http://www.mythencyclopedia.com/Sp-Tl/Theseus.html#ixzz30wFO3ofe</a>

Maze Goal: Explore every intersection in the maze.



#### Maze graph:

- Unroll a ball of string behind you.
- Mark each visited intersection and each visited passage.
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Shannon and his famous <u>electromechanical</u> mouse Theseus (named after <u>Theseus</u> from Greek mythology) which he tried to have solve the maze in one of the first experiments in <u>artificial intelligence</u>.

**The Las Vegas connection:** Shannon and his wife Betty also used to go on weekends to <u>Las Vegas</u> with <u>MIT</u> mathematician <u>Ed Thorp</u>, and made very successful forays in <u>blackjack</u> using <u>game theory</u>.

Maze Goal: Explore every intersection in the maze.

**Design pattern:** Decouple graph data type

Idea: Mimic maze exploration

#### DFS (to visit a vertex v)

- Mark v as visited.
- Recursively visit all unmarked vertices w adjacent to v.

#### Typical applications:

- Find all vertices connected to a given source vertex.
- Find a path between two vertices.

### Challenge:

How to implement?

Goal: Systematically search through a graph from graph processing

- Create a graph object
- Pass the graph to a graph processing routine
- Query the graph-processing routine

Goal: Systematically search through a graph from graph processing

- Create a graph object
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```
public class Paths

Paths(Graph G, int s) find paths in G from source s

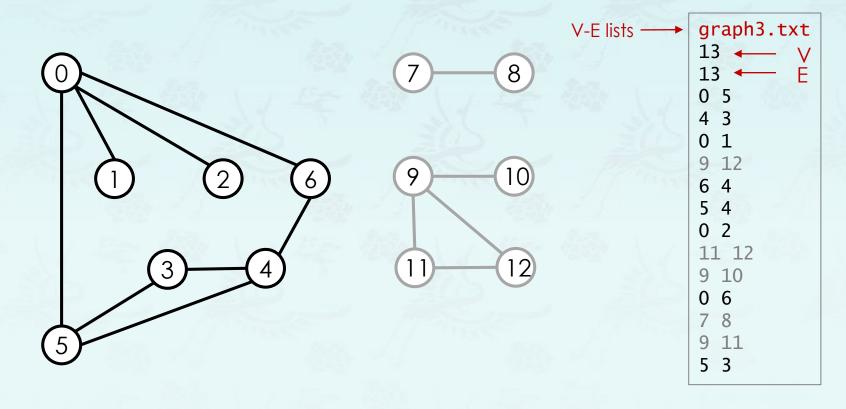
boolean hasPathTo(int v) is there a path from s to v?

Iterable<Integer> pathTo(int v) path from s to v; null if no such path
```

## **Graph - Coding**

For each edge(v, w) in the list

Insert front each vertex both (adj[v], w) and (adj[w], v) addEdgeFromTo(g, v, w); // add an edge from v to w.



Graph g:

Challenge: build adjacency lists?

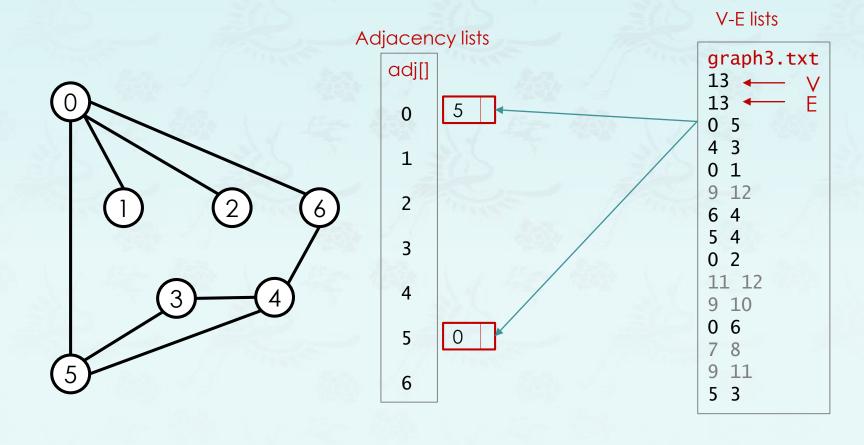
### Graph Coding – graph.cpp

```
struct Graph {
         // number of vertices in the graph
  int V;
  int E;
                    // number of edges in the graph
 gnode adj; // an array of adjacency lists (or gnode pointers)
 Graph(int v = 0) { // constructs a graph with v vertices
   V = V:
   \mathsf{E} = 0;
   // initialize each adjacency list as an empty list;
   for (int i = 0; i < V; i++) {
        g->adj[i].next = nullptr; 
                                       ---- set each adj list nullptr
       g->adj[i].item = i;
                                          unused; but may store the size of degree.
 ~Graph() {}
using graph = Graph *;
```

## **Graph Coding**

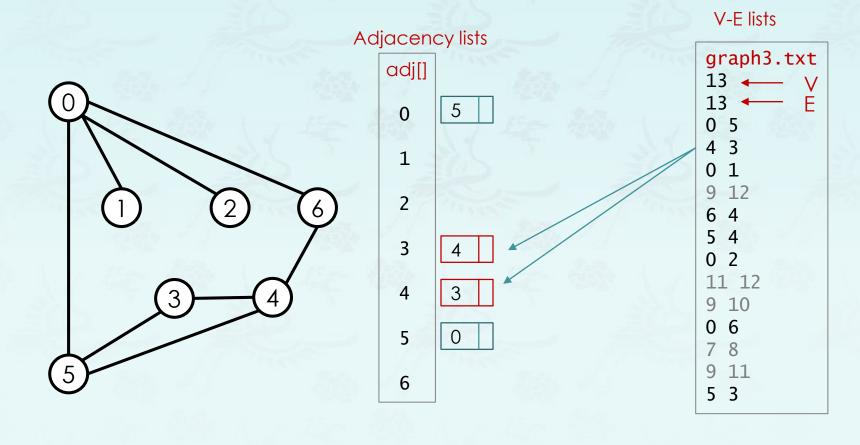
```
// add an edge to an undirected graph
void addEdgeFromTo(graph g, int v, int w) {
  // add an edge from v to w.
  // A new vertex is added to the adjacency list of v.
  // The vertex is added at the beginning
                                                     instantiate a node w insert it
  gnode node = new Gnode(w, g->adj[v].next);
                                                      at the front of adjacency list[v]
 g->E++;
// add an edge to an undirected graph
                                                      add an edge for undirected graph
void addEdge(graph g, int v, int w) {
  addEdgeFromTo(g, v, w); // add an edge from v to w.
  addEdgeFromTo(g, w, v); // if graph is undirected, add both
```

For each edge(v, w) in the list



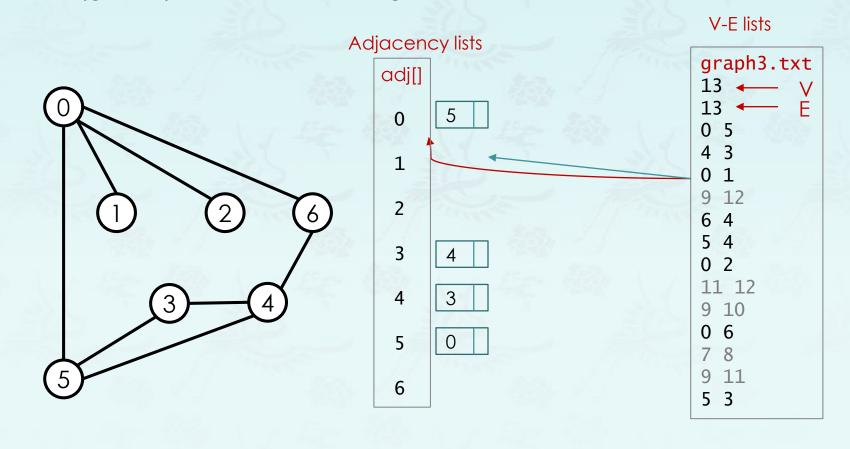
Graph g

For each edge(v, w) in the list



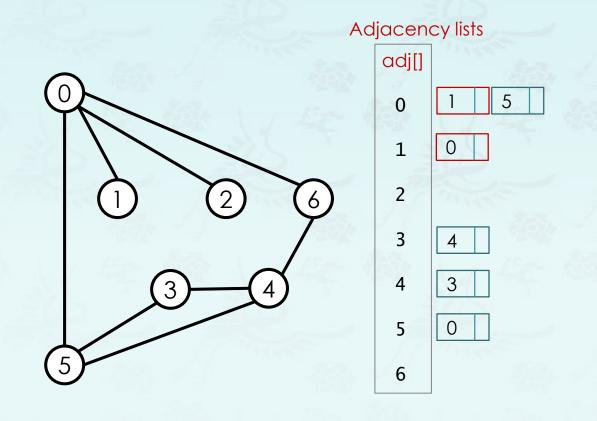
Graph g

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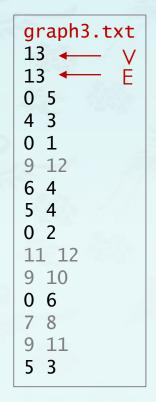


Graph g

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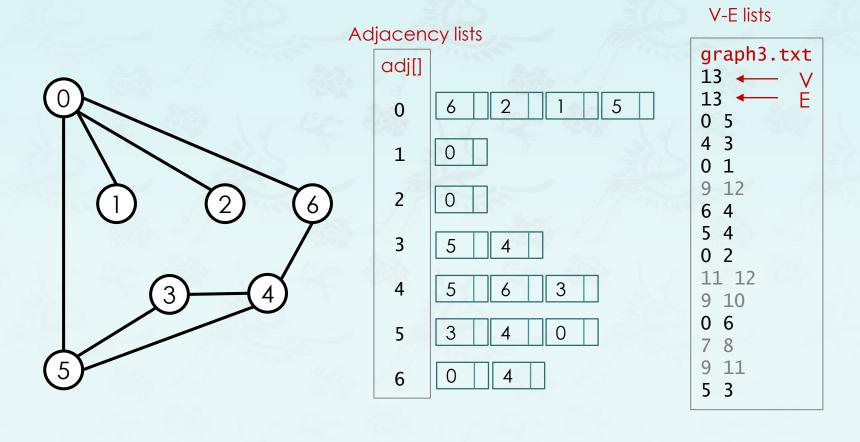






Graph g

For each edge(v, w) in the list



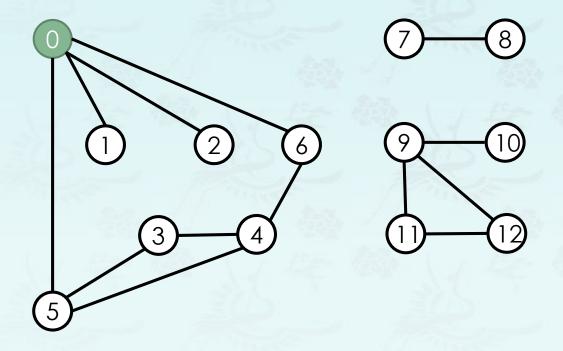
Graph g

#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

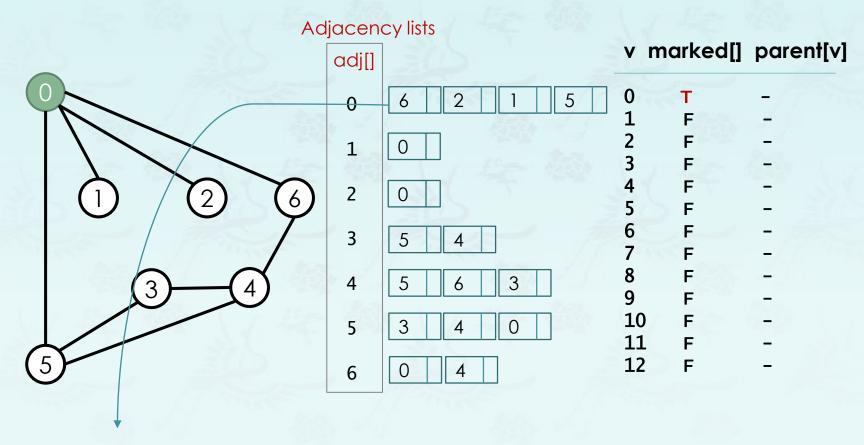
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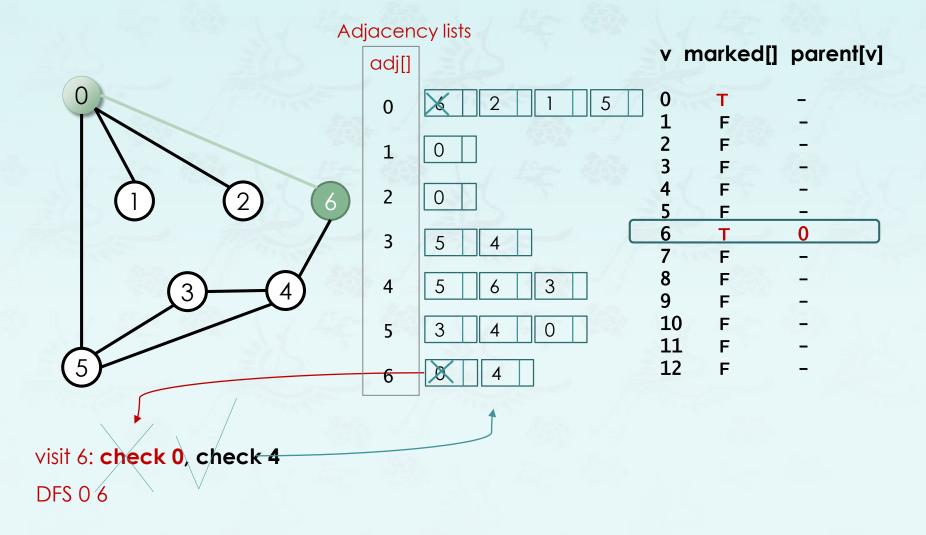


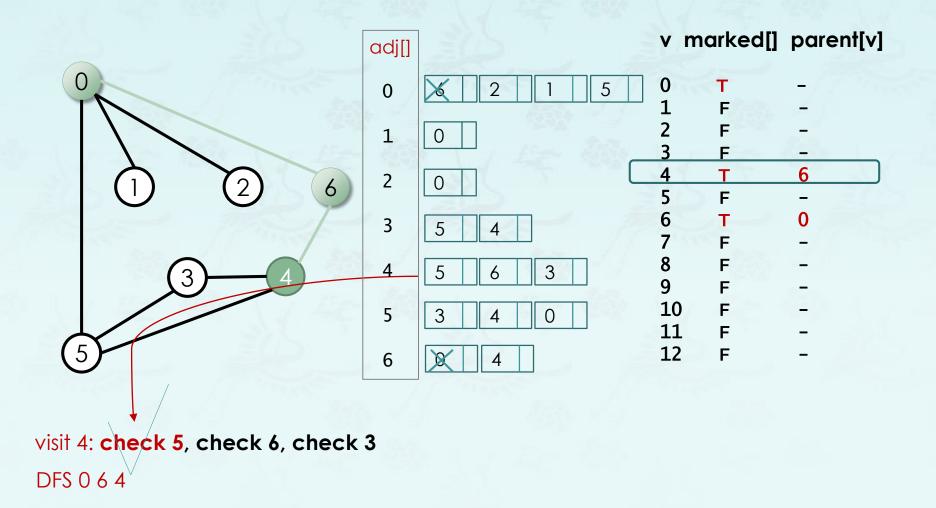
٧	marked[]	parent[v]
0	T	-//
1	F	<u>,</u> 2
2	F	
1 2 3 4 5	F	
4	F	
5	F	- 500
6	F	-
7	F	-///
7 8	F	- <u>-</u>
9	F	
10	) F	9 <u>-</u> 30
11	L F	
12	? F	_

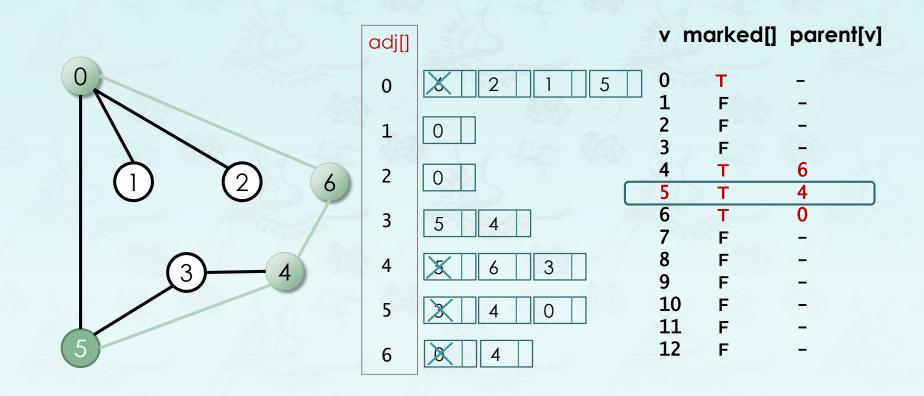
visit 0: Which one first?



visit 0: check 6, check 2, check 1, and check 5 DFS 0

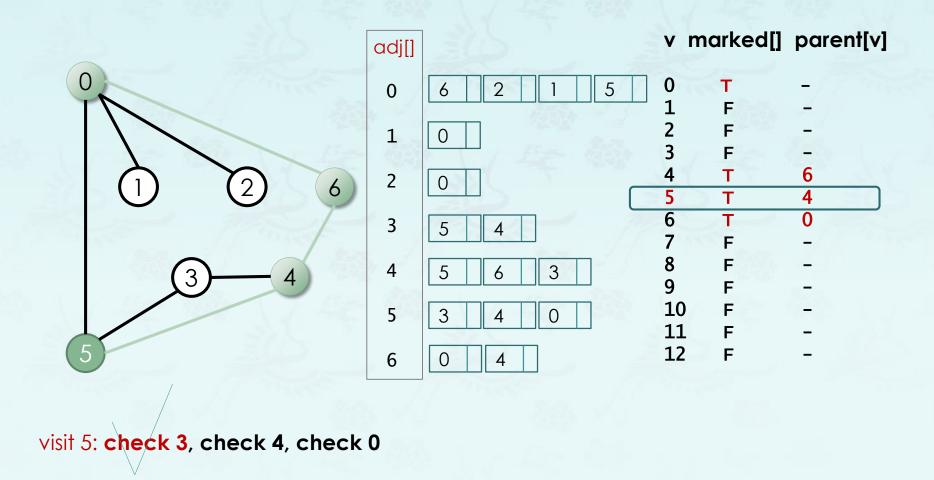


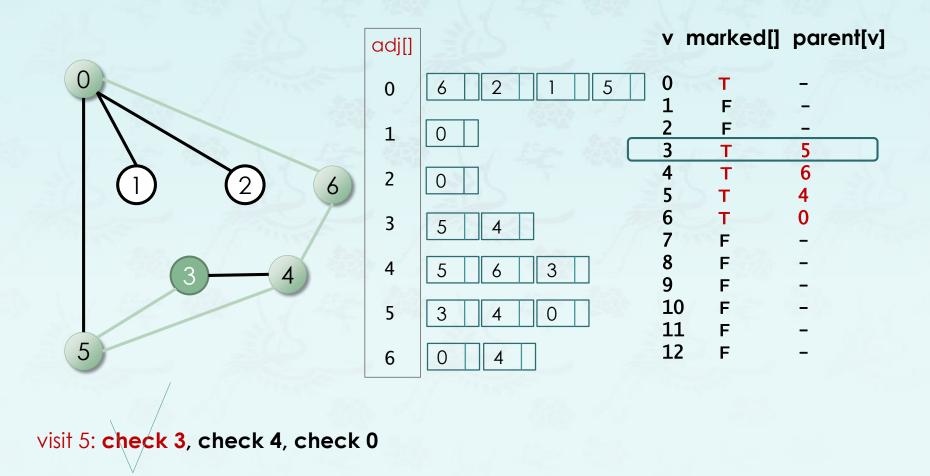


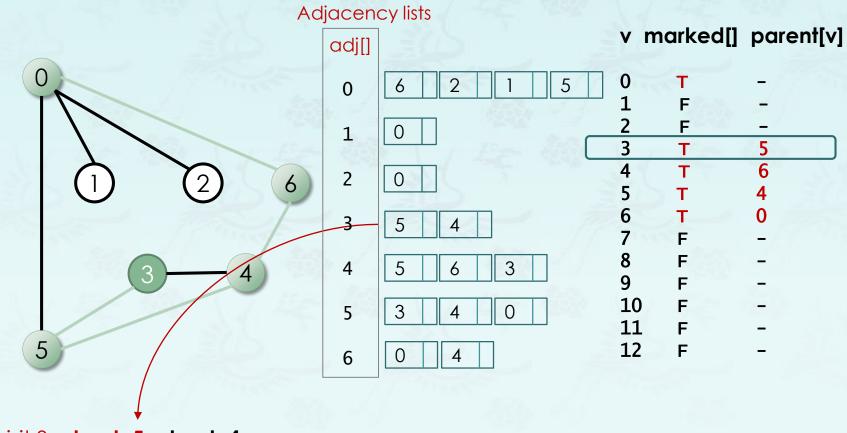


visit 5: check 3, check 4, check 0

DFS 0 6 4 5

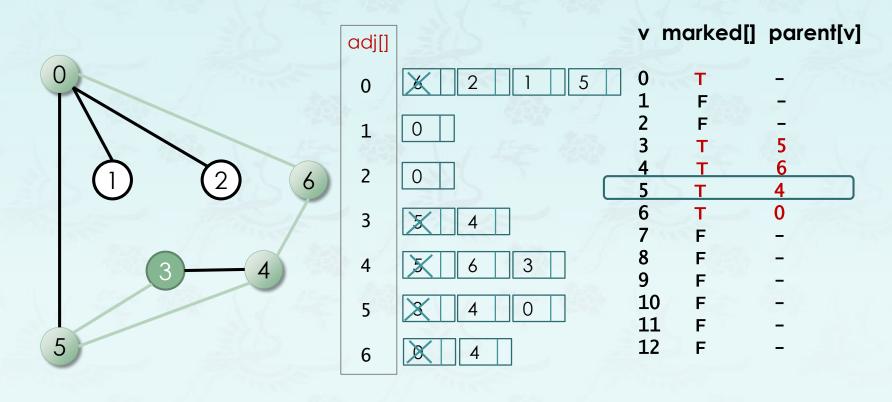




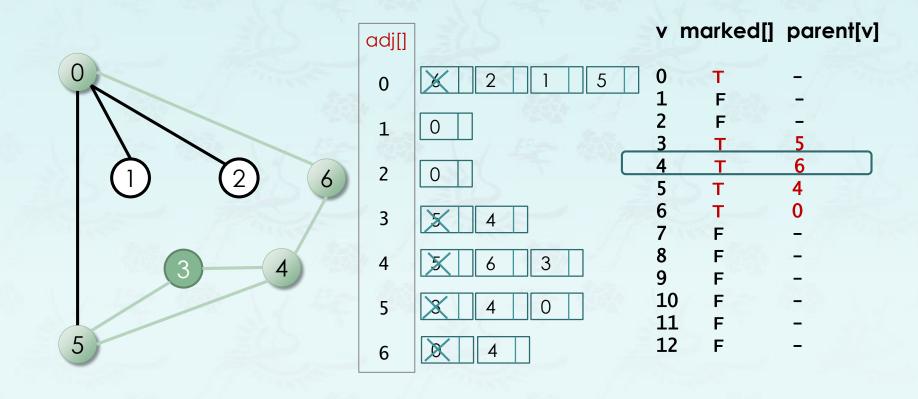


visit 3: check 5, check 4

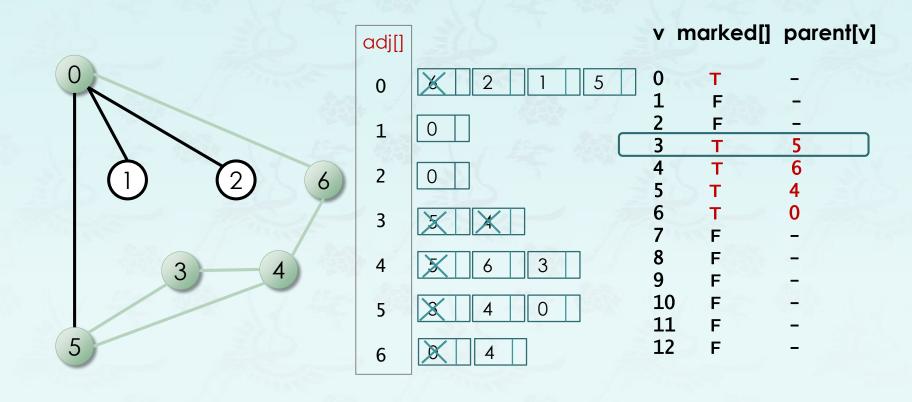
DFS 0 6 4 5 3



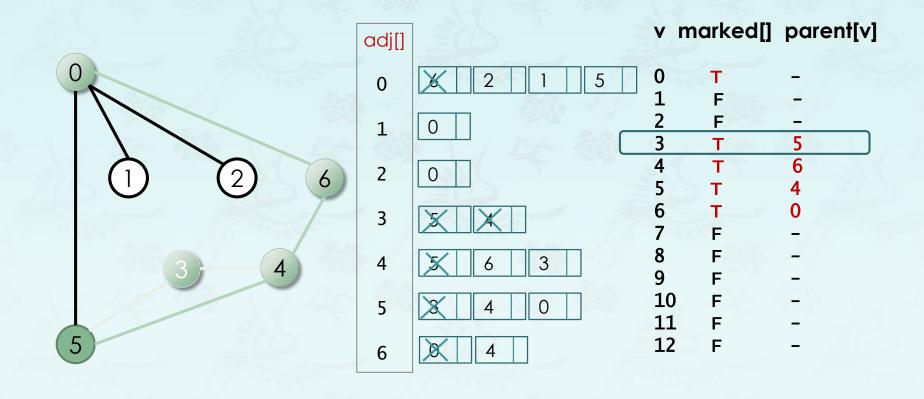
visit 3: check 5, check 4



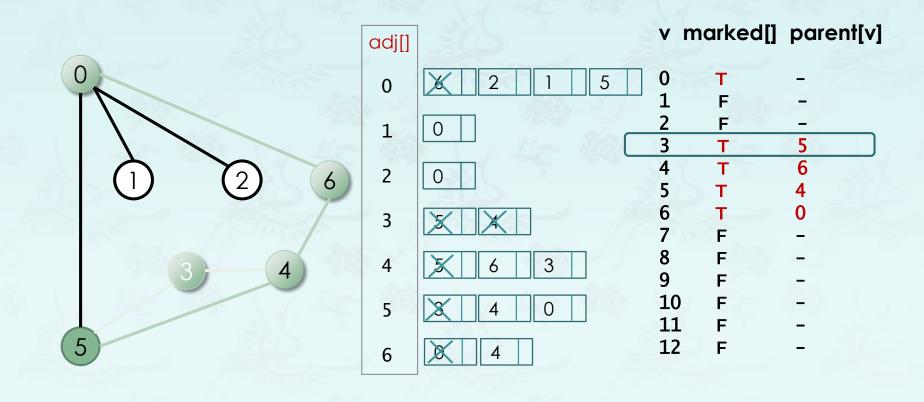
visit 3: check 5, check 4



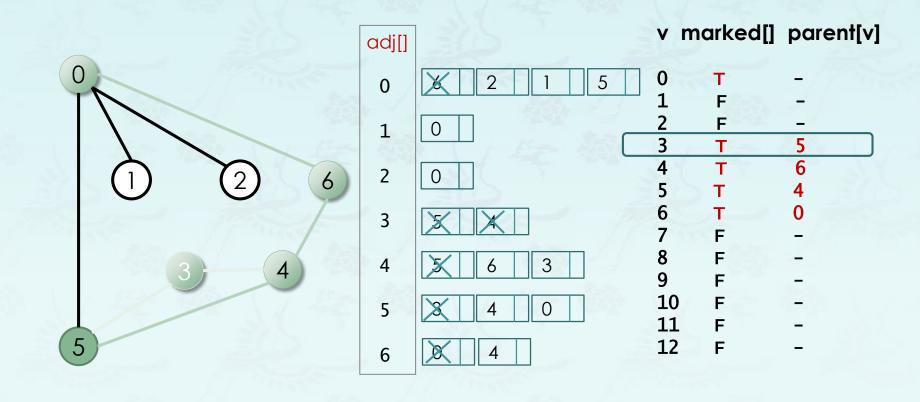
visit 3: check 5, check 4



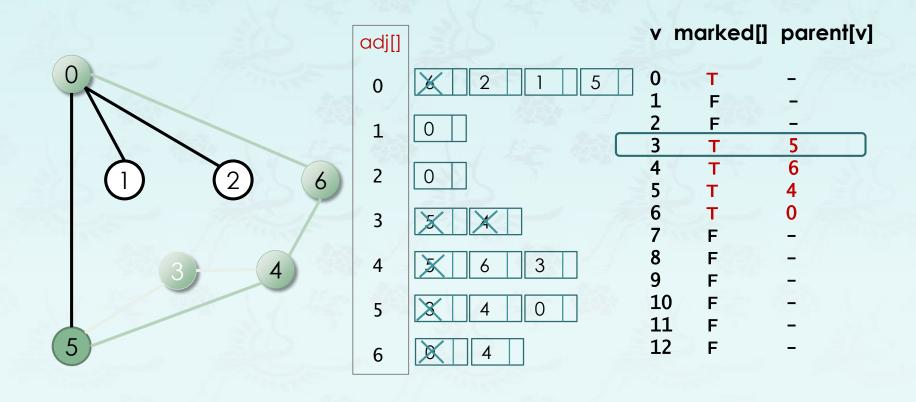
3 done: What's the next?



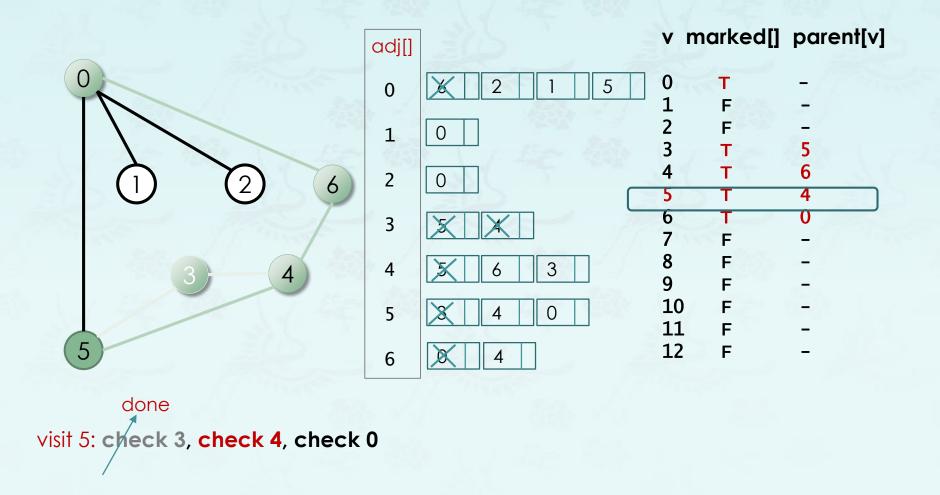
3 done: What's the next? Backtrack!

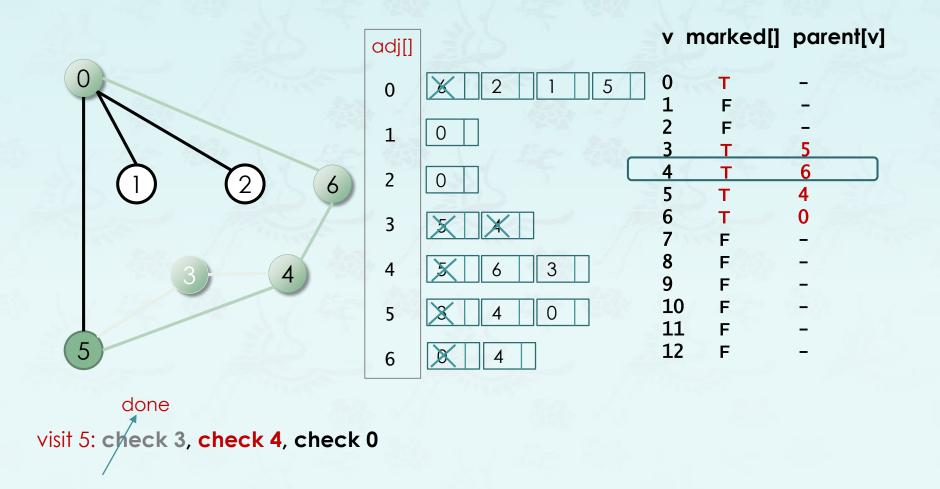


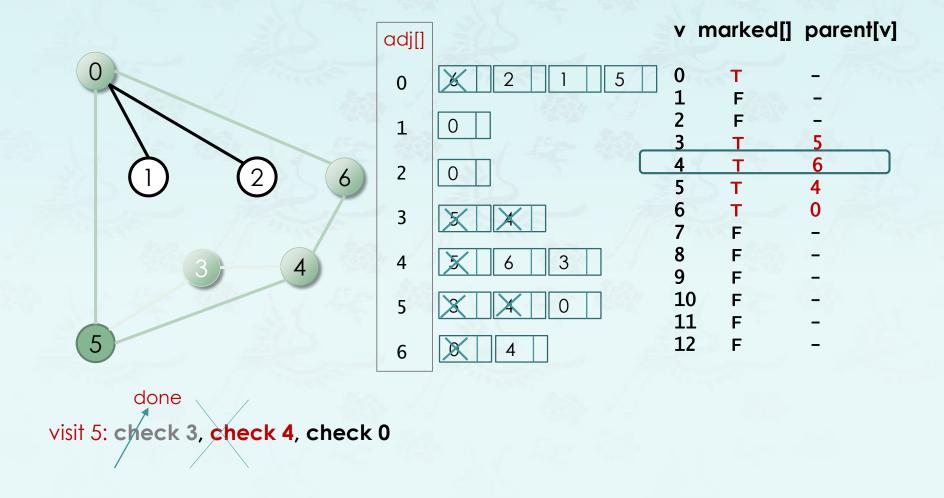
3 done: What's the next? **Backtrack!** How to?

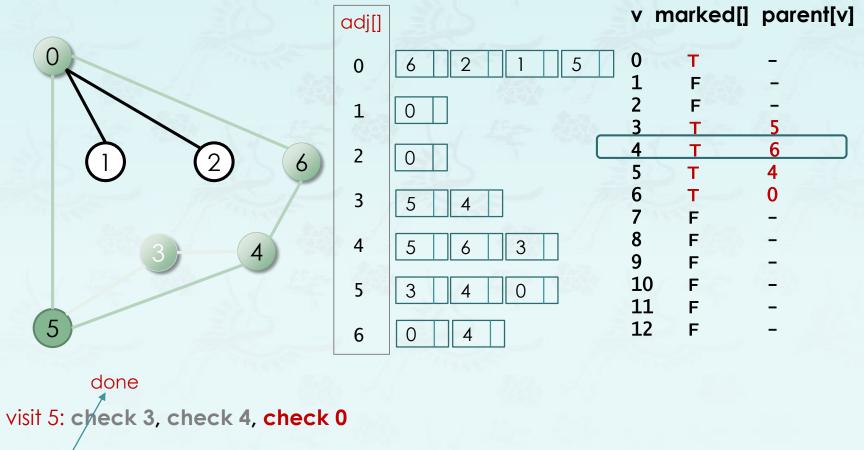


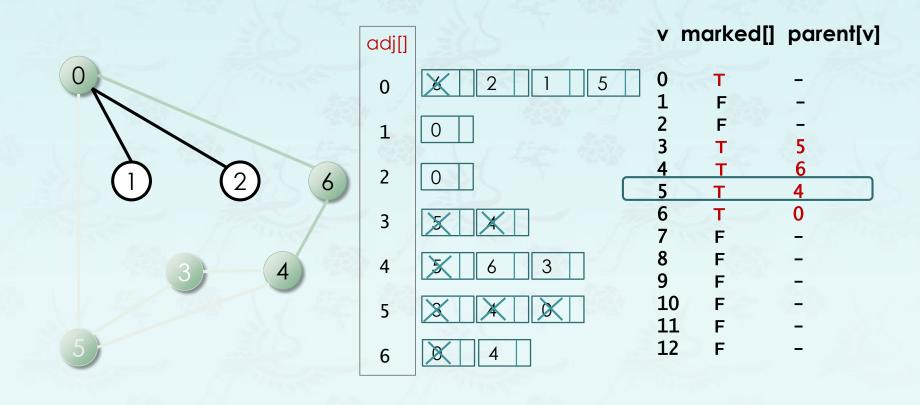
3 done: What's the next? Backtrack!
How to? Use parent[v] parent[3] = 5



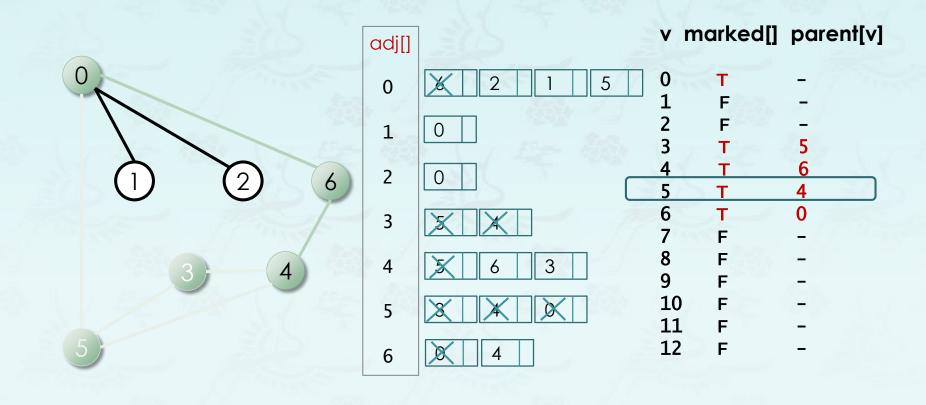








5 done What's the next? **Backtrack!** How to?

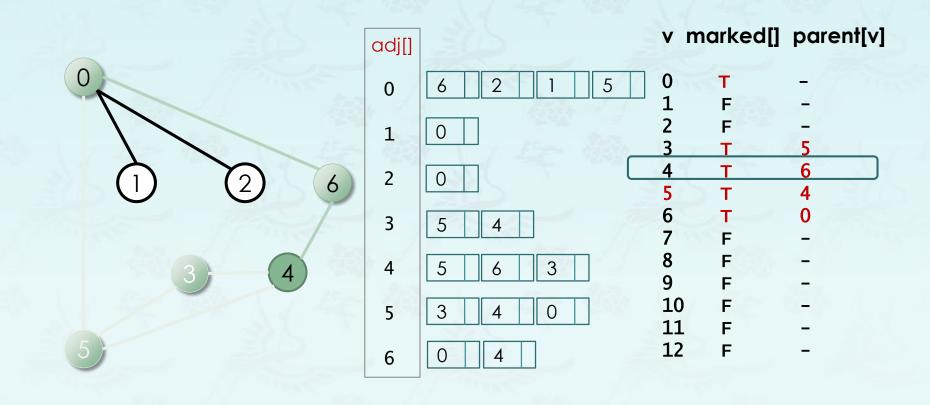


5 done

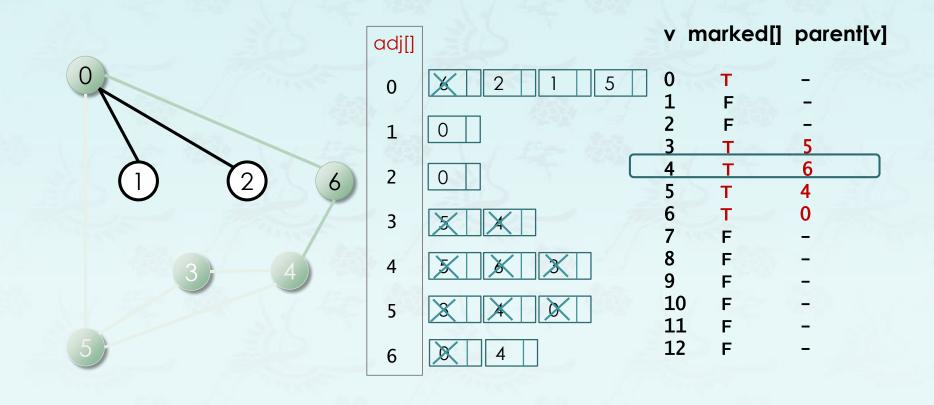
What's the next? How to?

Backtrack!
Use parent[v]

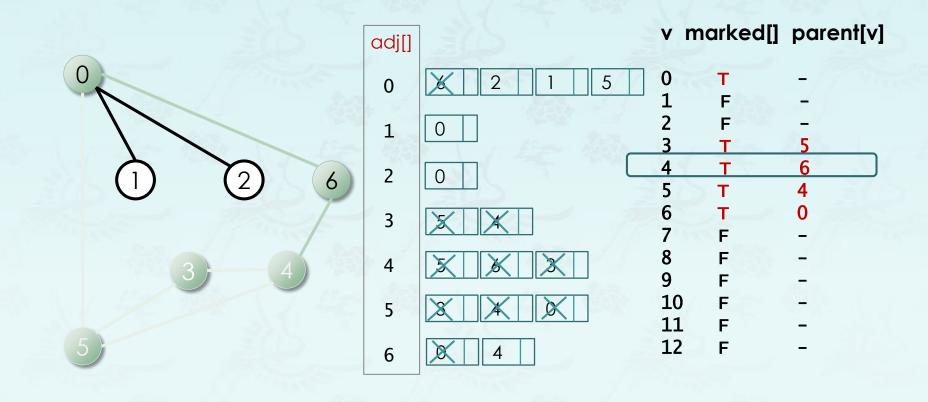
parent[5] = 4



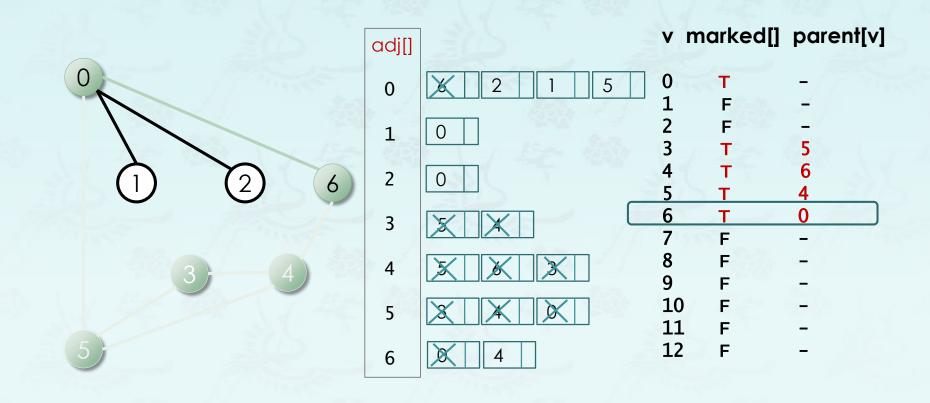
visit 4: check 5, check 6, check 3



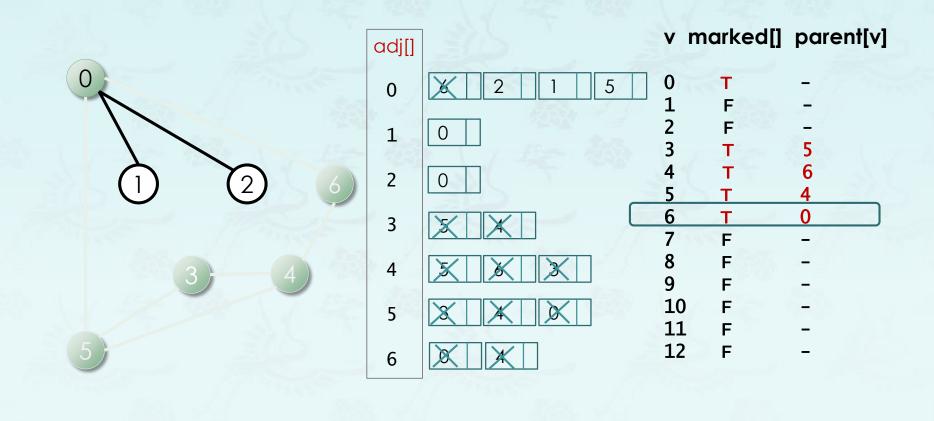
visit 4: check 5, check 6, check 3 4 done



visit 4: check 5, check 6, check 3 4 done Backtrack! parent[4] = 6



visit 6: check 0, check 4



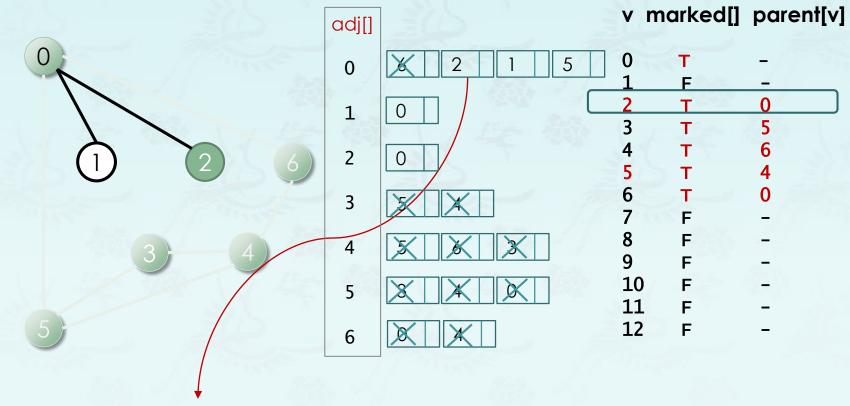
Backtrack!

43

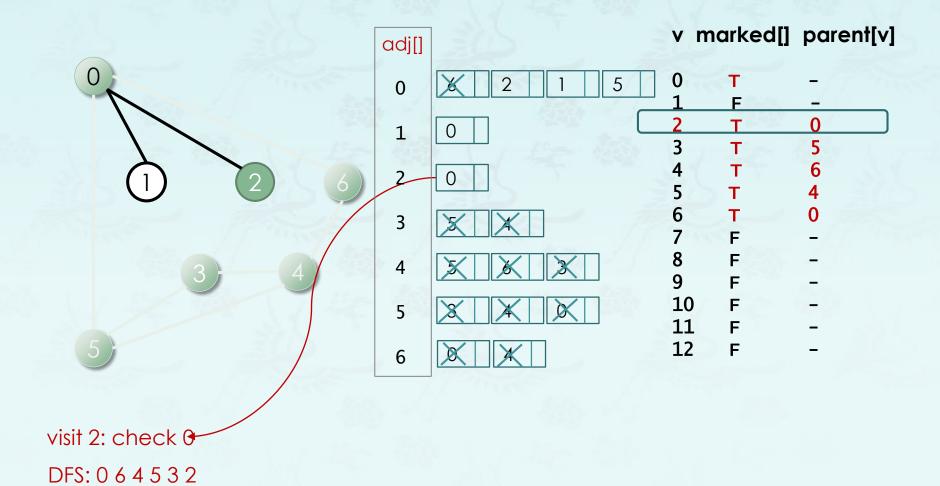
parent[6] = 0

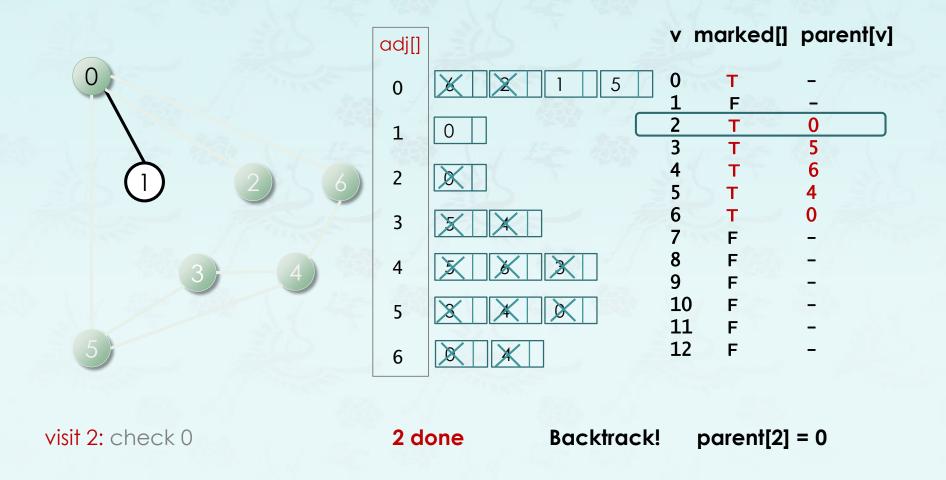
done 6

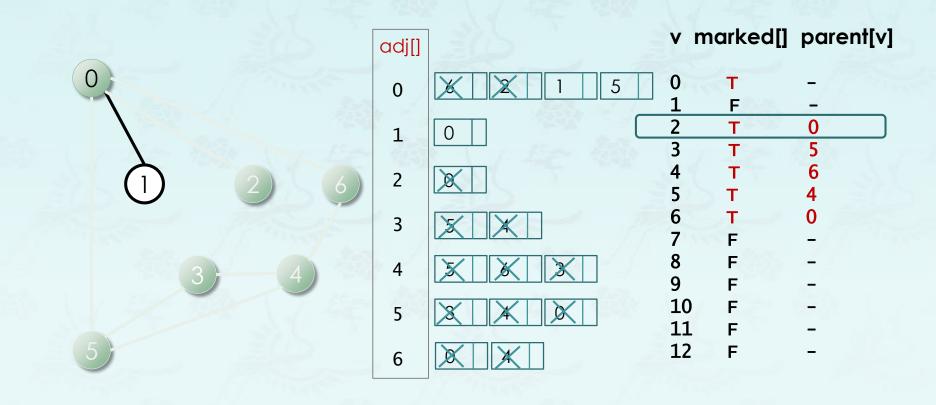
visit 6: check 0, check 4



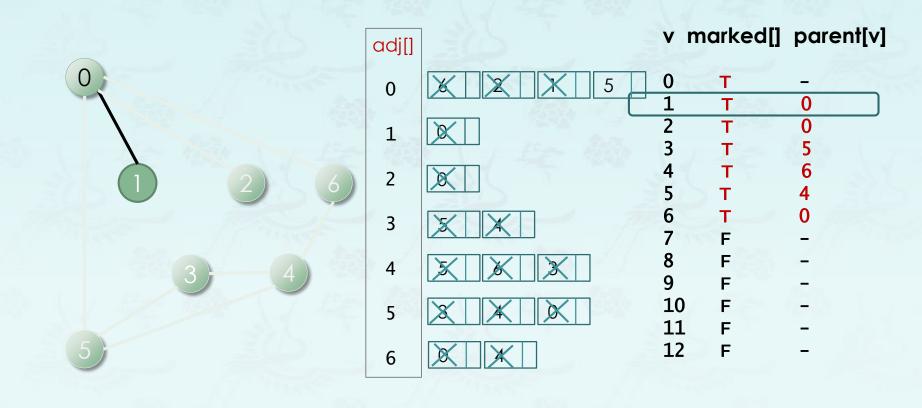
visit 0: check 6, check 2, check 1, and check 5







visit 0: check 6, check 2, check 1, and check 5



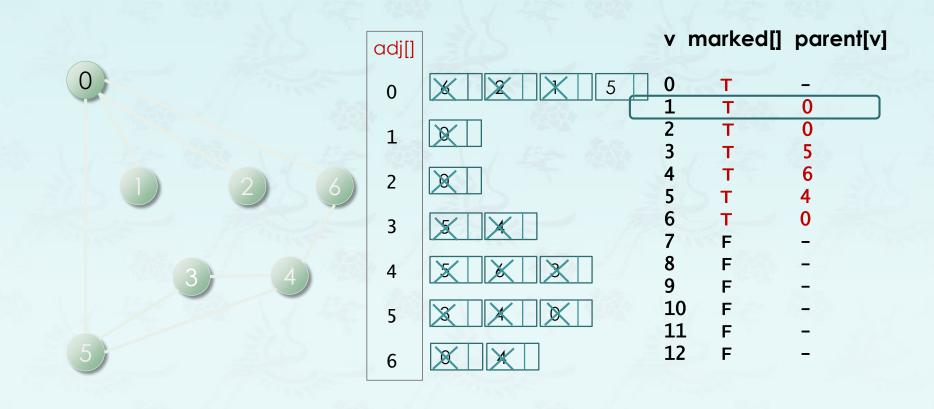
visit 1: check 0

DFS: 0 6 4 5 3 2 1

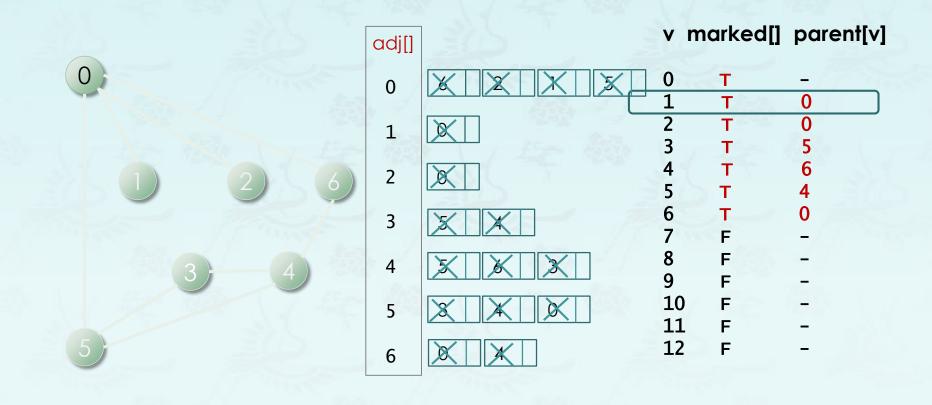
1 done

Backtrack! parent[1] = 0

48



visit 0: check 6, check 2, check 1, and check 5

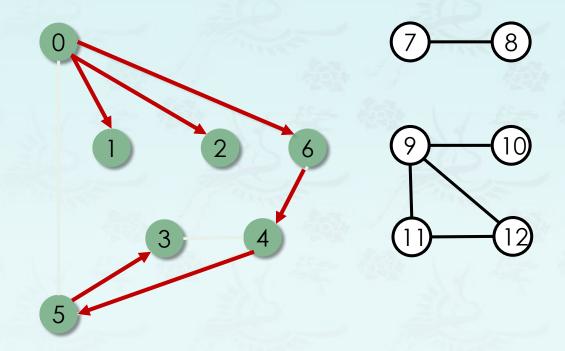


visit 0: check 6, check 2, check 1, and check 5 0 done

## **DFS: Depth-First Search Demo**

#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



#### v marked[] parent[v]

7	0	Т	-///
	1	T	0
	1 2 3 4	Т	0 5 6 4
	3	T	5
	4	Т	6
	5	Т	4
	5 6 7	T	0
	7	F	-///
	8 9	F	-
	9	F	<del>-</del>
	10	F	• (4 <u>-</u> 3)
	11	F	-
	12	F	_ = 10

**DFS Output:** DFS: 0 6 4 5 3 2 1

- found vertices reachable from 0
- build a data structure parent[v]

### **DFS: Depth-First Search Demo**

Goal: Find all vertices connected to s (and a corresponding path).

**Idea:** Mimic maze exploration

### **Algorithm:**

- Use recursion (ball of string).
- Mark each visited vertex (and keep track of edge taken to visit it).
- Return (retrace steps) when no unvisited options.

#### **Data Structures:**

- Boolean[] marked to mark visited vetices.
- int[] parent to keep tree of paths.
   (parent[w] == v) means that edge v-w taken to visit w for first time

## **DFS: Depth-First Search Coding**

```
// DFS - find vertices connected to v
void DFS(graph g, int v, queue<int>& que) {
  if (empty(g)) return;
  for (int i = 0; i < V(g); i++)
    g->marked[i] = false;
  _DFS(g, v, que); // recursive _DFS at v
  g->DFSv = que; // save result at DFSv at v
}
```

## **DFS: Depth-First Search Coding**

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void DFS(graph g, int v, queue<int>& que) {
  if (empty(g)) return;
  for (int i = 0; i < V(g); i++)
    g->marked[i] = false;
  _DFS(g, v, que); // recursive _DFS at g->DFSv = que; // save result at DF
}
```

```
// Recursive _DFS does the work
void _DFS(graph g, int v, queue<int>& que) {
 g->marked[v] = true; 'v' current visiting vertex
 que.push(v);
                    // save the path
 for (gnode w = g->adj[v].next; w; w = w->next) {
   if (!g->marked[w->item]) {
       _DFS(g, w->item, que);
       g->parentDFS[w->item] = v;
                            keep where it reached from
```

### **DFS: Depth-First Search Properties**

**Proposition:** After DFS, can find vertices connected to s in constant time and can find a path to s (if one exists) in time proportional to its length.

**Proof:** parent[] is parent-link representation of a tree rooted at s.

```
// returns a path from v to w using the result of DFS's parent[].
// It has to use a stack to retrace the path back to the source.
// Once the client(caller) gets a stack returned,
void DFSpath(graph g, int v, int w, stack<int>& path) {
  if (empty(q)) return;
 // DFS at v, starting vertex
 queue<int> q;
 DFS(q, v, q);
 path = {};
 for (int x = w; x != v; x = q -> parentDFS[x])
   path.push(x);
 path.push(v);
```

#### v marked[] parent[v]

```
0 T - 1 T 0 2 T 0 3 T 5 4 T 6 5 T 4 6 T 0 7 F - 8 F - 9 F - 10 F - 11 F - 12 F - 12 F - 10
```

### **DFS: Depth-First Search Coding**

**Proposition:** After DFS, can find vertices connected to s in constant time and can find a path to s (if one exists) in time proportional to its length.

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What is the path from vertex 0 to vertex 3? In this case, what is in the stack when parnet() returns?

```
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 // DFS at v, starting vertex
 queue<int> q;
 DFS(q, v, q);
 path = {};
 for (int x = w; x != v; x = g->parentDFS[x])
   path.push(x);
 path.push(v);
```

#### v marked[] parent[v]

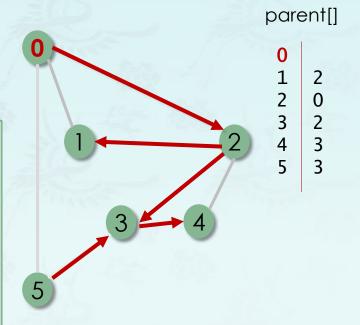
```
10
11
12
```

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 path.push(v);
```



a wrong edge between?

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- 2. Algorithms 4<sup>th</sup> edition Part 1 & Part 2 by Robert Sedgewick and Kevin Wayne
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Prof. Youngsup Kim, idebtor@handong.edu, 2014 Data Structures, CSEE Dept., Handong Global University

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# **Connectivity Queries**

**Def.:** Vertices v and w are connected if there is a path between them.

**Goal:** Preprocess graph to answer queries of the form "is v connected to w?" in constant time.

public class CC				
	CC(Graph G)	find connected components in G		
boolean	<pre>connected(int v, int w)</pre>	are v and w connected?		
int	count()	number of connected components		
int	id(int v)	component identifier for v		

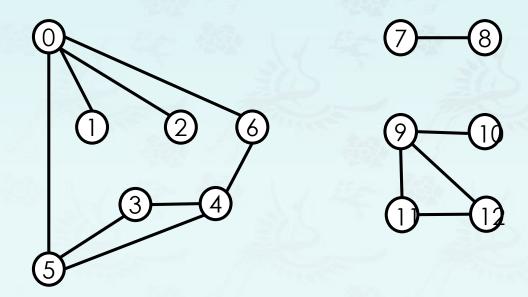
Depth-first search? Yes ...

The relation "is connected to" is equivalence relation:

**Reflexive:** v is connected to v.

**Symmetric:** if v is connected to w, then w is connected v.

**Transitive:** if v connected to w and w connected to x, then v connected to x



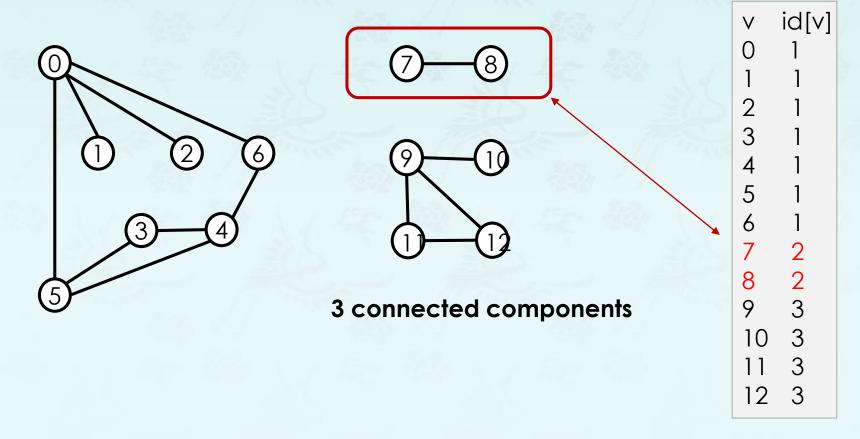
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**Def.:** A connected component is a maximal set of connected vertices.



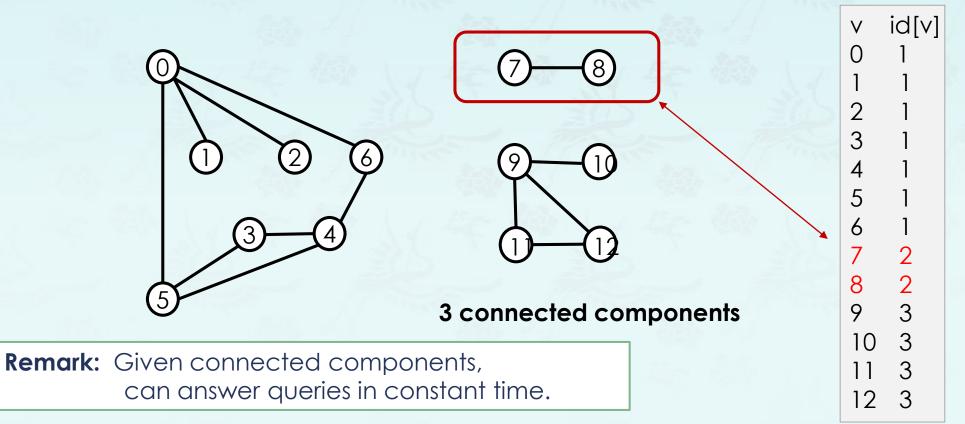
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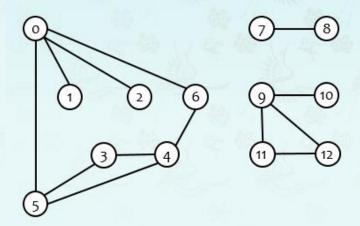


Goal: Partition vertices into connected components.

#### **Connected components**

Initialize all vertices v as unmarked.

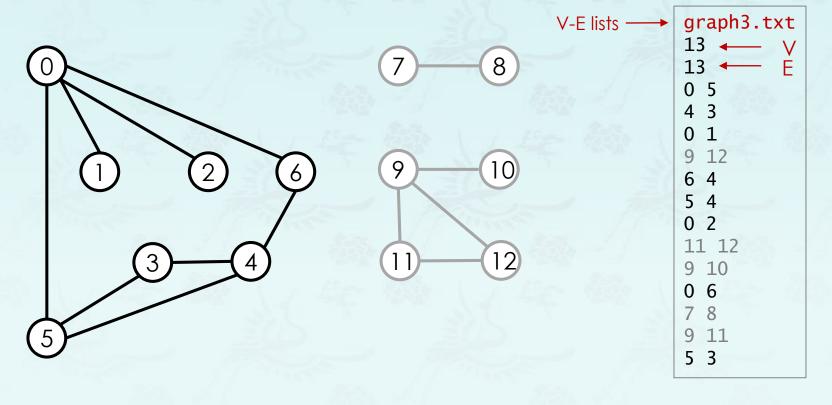
For each unmarked vertex v, run DFS to identify all vertices discovered as part of the same component.



# graph3.txt 13 13 11 12 9 10 0 6 7 8 9 11 5 3

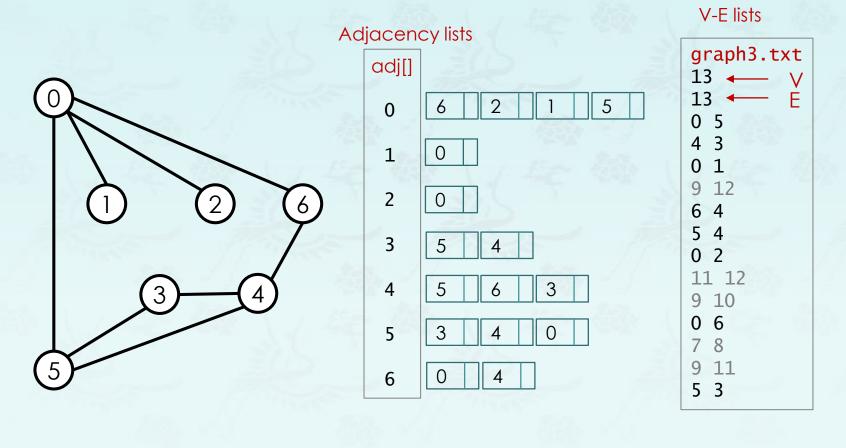
#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.

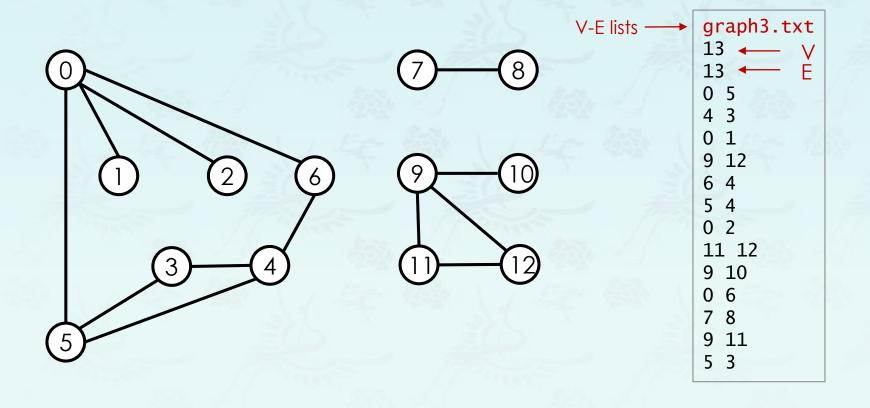


Graph g:

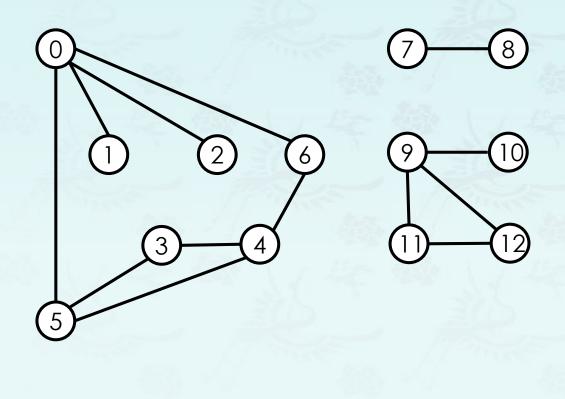
Challenge: build adjacency lists?



Graph g

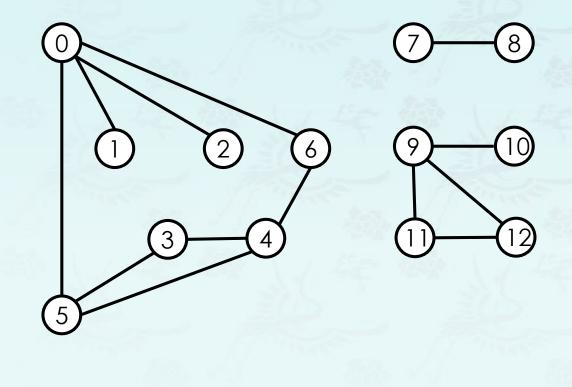


Graph g:



v	marked[]	id[]
0	F	_
1	F	-
2	F	-
3	F	-
4	F	-
5	F	-
6	F	-
7	F	-
8	F	-
9	F	-
10	F	-
11	F	-
12	F	-

Graph g:



v	marked[]	id[]
0	Т	0
1	Т	0
2	Т	0
3	Т	0
4	Т	0
5	Т	0
6	Т	0
7	Т	1
8	Т	1
9	Т	2
10	Т	2
11	Т	2
12	Т	2

Done:

### **Connected Components – Coding**

```
// returns true if v and w are connected.
bool connected(graph g, int v, int w) {
  if (empty(g)) return true;

  queue<int> q;
  DFS(g, v, q);

  return g->CCID[v] == g->CCID[w];
}
```

```
// returns number of connected components.
int nCCs(graph g) {
  int id = g->CCID[0];
  int count = 1;
  for (int i = 0; i < V(g); i++)
    if (id != g->CCID[i]) {
    id = g->CCID[i];
    count++;
    }
  return id == 0 ? 0 : count;
}
```

# Graph

- Introduction
- Graph API
- Elementary Graph Operations
  - DFS: Depth first search
  - BFS: Breadth first search
  - CC: Connected Components
- pset graph.cpp
  - implement DFS, BFS, CC and others

#### Major references:

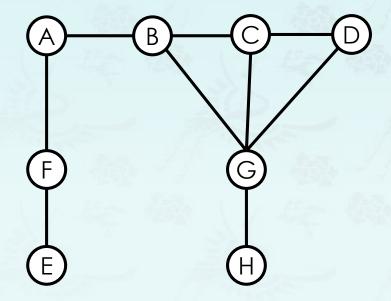
- 1. Fundamentals of Data Structures by Horowitz, Sahni, Anderson-Freed,
- 2. Algorithms 4<sup>th</sup> edition Part 1 & Part 2 by Robert Sedgewick and Kevin Wayne
- 3. Wikipedia and many resources available from internet

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### **DFS - Exercise**

#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



### adjacent list

A: BF

B: G C A

C: DGB

D: CG

E: F

F: E A

G: HBCD

H: G

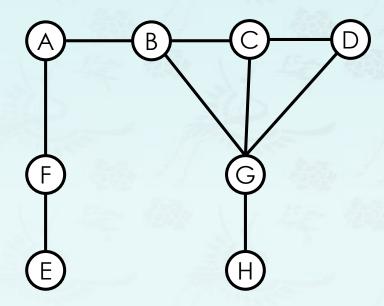
Graph g:

Hint: A B...?...F E

#### **DFS - Exercise**

#### To visit a vertex v:

- Mark vertex v as visited.
- Recursively visit all unmarked vertices adjacent to v.



#### adjacent list

A: B F
B: G C A
C: D G B
D: C G
E: F
F: E A
G: H B C D
H: G

dfs(A) dfs(B) dfs(G) dfs(H) check G H done check B dfs(C) dfs(D) check C check G D done check G check B C done check D G done check C check A B done dfs(F) dfs(E) check F E done check A F done A done check B check C check D check E check F check G

check H

Graph g:

Hint: A B G H C D F E