

/home/rohit/Opencv  
codes/Lane-Detection  
/include/Lane.hpp

```
graph TD; A["/home/rohit/Opencv  
codes/Lane-Detection  
/include/Lane.hpp"] --> B[iostream]; A --> C[vector]; A --> D[string]; A --> E[numeric]; A --> F[algorithm]; A --> G[opencv2/opencv.hpp];
```

The diagram illustrates a file dependency structure. A central gray box at the top represents the source file `/home/rohit/Opencv/codes/Lane-Detection/include/Lane.hpp`. Six dark blue arrows originate from the bottom of this box and point to six separate white boxes below it. These boxes represent the files that the source file includes: `iostream`, `vector`, `string`, `numeric`, `algorithm`, and `opencv2/opencv.hpp`.

iostream

vector

string

numeric

algorithm

opencv2/opencv.hpp