view\_frames Result Recorded at time: 1687274054.976 map Broadcaster: /slam\_gmapping Average rate: 38.587 Hz Most recent transform: 1687274056.882 ( -1.906 sec old) Buffer length: 6.764 sec odom Broadcaster: /robot\_pose\_ekf Average rate: 26.096 Hz Most recent transform: 1687274056.821 ( -1.845 sec old) Buffer length: 4.867 sec base\_footprint Broadcaster: /base\_footprint\_to\_baselink Average rate: 33.404 Hz Most recent transform: 1687274056.873 ( -1.897 sec old) Buffer length: 4.850 sec base\_link Broadcaster: /base\_link\_to\_laser Broadcaster: /rpy\_tf Average rate: 33.399 Hz Average rate: 50.206 Hz

imu\_link

Most recent transform: 1687274056.852 (-1.876 sec old)

Buffer length: 4.860 sec

Most recent transform: 1687274056.873 (-1.897 sec old)
Buffer length: 4.850 sec

i