Jinzhou Li

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304 Research Drive, Durham, NC 27710

Research interests

My research focuses on enabling robots to achieve **human-level dexterity** in complex environments by integrating multisensory intelligence with advanced control strategies and machine learning.

Education

2025 –	**Duke University** – Durham, NC Ph.D. Student in Robotics Advisor: Prof. Xianyi, Cheng.
2022 – 2023	**Cornell University** – Ithaca, NY M.Eng in Systems Engineering Advisor: Prof. Maha, Haji.
2017 – 2021	**University of Vermont** – Burlington, VT BS in Computer Science

Research experience

2024 – 2025	**Peking University, PKU-Agibot Joint Lab** Advisor: Prof. Hao, Dong. Tactile Dexterous Manipulation, Sim2Real, Real2Sim2Real
2022 – 2023	**Cornell University, SEA Lab & MIT, Engineering System Lab** Advisors: Prof. Maha, Haji. & Prof. Daniel, Hasting. 1) System of Systems Concept for Effective Oceans to Near Space Observation 2) Hybrid Agent-Based Model and Discrete Event Simulation to Optimize AUV Fleet Operations

Honors and scholarships

2017 – 2021   Merit Scholars Award
Awarded for academic excellence; $5,000 per semester.

Publications

Paper (* denotes equal contribution):

c6.   **TwinAligner: Visual and Physical Real2Sim2Real All-in-one for Robotic Manipulation**
Hongwei Fan*, Hang Dai*, Jiyao Zhang*, **Jinzhou Li**, Qiyang Yan, Yujie Zhao, Xuanyu Lai, Hao Tang, Hao Dong
Preprint, 2025.

c5.   **ClutterDexGrasp: A System for General Closed-Loop Dexterous Grasping in Cluttered Scenes**
Zeyuan Chen*, Qiyang Yan*, Yuanpei Chen*, Jiyao Zhang, Tianhao Wu, Zihan Ding, **Jinzhou Li**, Yaodong Yang, Hao Dong.
The Conference on Robot Learning (CoRL), 2025. **Oral ~5%**

c4.   **Adaptive Visual-Tactile Fusion with Predictive Force Attention for Dexterous Manipulation**
Jinzhou Li*, Tianhao Wu*, Jiyao Zhang, Zeyuan Chen, Haotian Jin, Mingdong Wu, Yujun Shen, Yaodong Yang, Hao Dong
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) **(Oral)**, *2025.*

c3.   **SimLauncher: Launching Sample-Efficient Robotic Reinforcement Learning via Simulation Pre-training**
Mingdong Wu*, Lehong Wu*, Yizhuo Wu*, Weiyao Huang, Hongwei Fan, Zheyuan Hu, Haoran Geng, **Jinzhou Li**, Jiahe Ying, Long Yang, Yuanpei Chen, Hao Dong.
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) **(Oral)**, *2025.*

c2.   **Canonical Representation and Force-Based Pretraining of 3D Dexterous Visuo-Tactile Policy Learning**
Tianhao Wu, **Jinzhou Li***, Jiyao Zhang*, Mingdong Wu, Hao Dong.
IEEE International Conference on Robotics and Automation (ICRA), 2025.

c1. **HGIC: A Hand Gesture Based Interactive Control System for Efficient and Scalable Multi-UAV Operations**
Mengsha Hu, **Jinzhou Li**, Runxiang Jin, Chao Shi, Lei Xu, Rui Liu.
IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN), 2024.

Presentations:

p1. **HGIC: A Hand Gesture Based Interactive Control System for Efficient and Scalable Multi-UAV Operations**
Jinzhou Li, Mengsha Hu, Lei Xu, Yibei Guo, Rui Liu
IEEE International Symposium on Multi-Robot & Multi-Agent Systems (MRS), 2023.

Teaching experience

Fall 2023 **Cornell University**
Teaching Assistant, Meta CS 4782: Intro to Deep Learning

Industry experience

2024 – 2025 **Agibot Inc.** – Research Intern

Service

Reviewer
ICRA (2024, 2025)

Technical skills

Programming languages
Python, C++, Rust

Software
LaTeX, Git, ROS, PyTorch, Unreal Engine, IssacGym

Robot Experience
Leap Hand, Hello Robot, Franka, Aloha, Flexiv