Assignment 3 Report

Course Code: CS 512

Course Name: Computer Vision Course Instructor: Dr. Gady Agam

AS3

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1. Problem Statement

The objective is to write 4 programs that performs the following 4 tasks:

- A basic line fitting algorithm
- Estimate line parameters from points by line fitting that is robust to outliers
- Image classification on Kaggle's Cats and Dogs dataset. Perform data augmentation and also use VGG16 pre trained convolution base
- Image classification on CIFAR10 dataset using convolution blocks, inception blocks and residual blocks

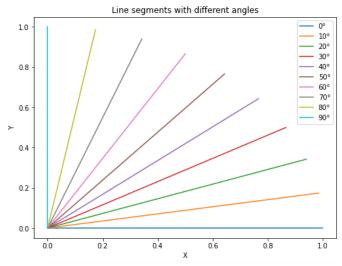
2. Proposed Solution

Keras and tensorflow packages were used along with python in google colab to preprocess the data, train the model and test it on the test dataset.

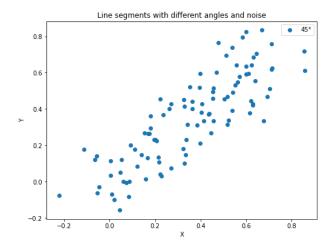
3. Implementation Details

Programming Problem 1 & 2:

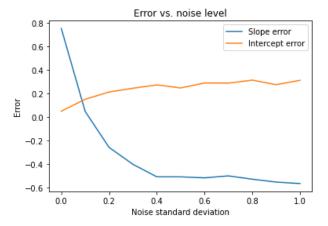
At first, some points were generated belonging to a line segment with given parameters of angle and distance from the origin.



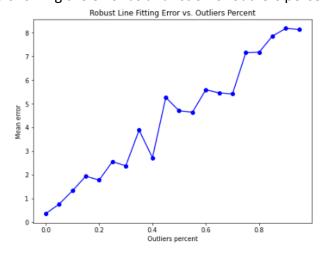
Then gaussian noise with specified mean and standard deviation to the points was generated for a 45-degree angled line segment.



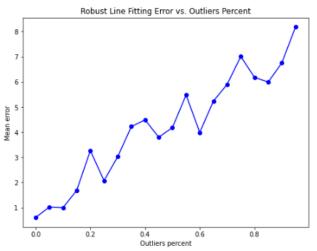
The line parameters were estimated for the points above and the errors were computed for the known line parameters, which was -0.1924. Next, a graph is plotted showing error as a function of noise level.



Then, a graph is plotted showing the error as a function of outliers percent.

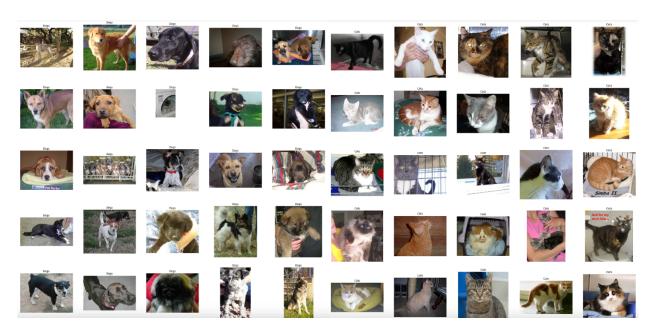


Next, the cv2.fitLine line fitting function is used to perform robust estimation using CV_DIST_HUBER distance and a graph is plotted showing the error as a function of outliers percent.



Programming Problem 3:

At first, the cats and dogs datasets were downloaded from the <u>link</u>. It had 12510 cat images and 12500 dog images. From there, a subset of 1000 cat images and 1000 dog images were put aside for training purpose, 500 cat images and 500 dog images were kept for validation and another 500 cat images and 500 dog images were kept for testing.

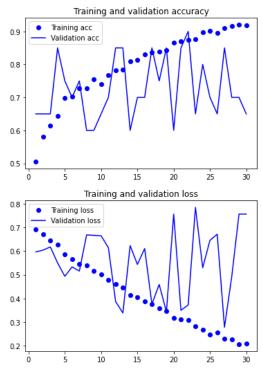


The final model architecture is defined as the following.

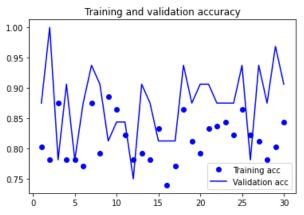
Model: "sequential_1"

ne, 148, 148, 32) 896 ne, 74, 74, 32) 0 ne, 72, 72, 64) 18496 ne, 36, 36, 64) 0 ne, 34, 34, 128) 73856 ne, 17, 17, 128) 0 ne, 15, 15, 128) 147584 ne, 7, 7, 128) 0
ne, 72, 72, 64) 18496 ne, 36, 36, 64) 0 ne, 34, 34, 128) 73856 ne, 17, 17, 128) 0 ne, 15, 15, 128) 147584
ne, 36, 36, 64) 0 ne, 34, 34, 128) 73856 ne, 17, 17, 128) 0 ne, 15, 15, 128) 147584
ne, 34, 34, 128) 73856 ne, 17, 17, 128) 0 ne, 15, 15, 128) 147584
ne, 17, 17, 128) 0 ne, 15, 15, 128) 147584
ne, 15, 15, 128) 147584
ne 7 7 128) 0
, , , , , , , , , , , , , , , , , ,
ne, 6272) 0
ne, 6272) 0
ne, 512) 3211776
ne, 1) 513
1

There are 2 classes in our case. Binary cross entropy was used as the loss function, RMSprop was used as the optimizer and the metric was selected to be 'accuracy'. The learning rate was set at 1e-4. The training and validation datasets were standardized. The model was then fitted using 100 steps per epoch and a total of 30 epochs. The performance on training and validation set is given below.

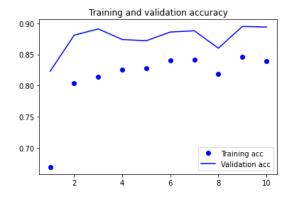


Next, the data generator was used to perform data augmentation. The performance reported is given below.



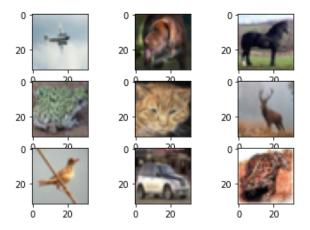
Finally, the convolution layers were replaced with pre-trained convolution base of VGG16. The VGG16 architecture consists of 16 layers, including 13 convolutional layers and 3 fully connected layers. The convolutional layers use 3x3 filters and have a stride of 1, and are followed by rectified linear unit (ReLU) activations and 2x2 max pooling layers with a stride of 2. The fully connected layers have 4096 neurons each, followed by a final softmax layer for classification. In our case, we use the weights of imagenet problem i.e. we do not update the weights of the model with training. The number of epochs was set at 10 as it was computationally expensive to set it any higher. The performance reported is given below.

```
63/63
                                          870s 14s/step - loss: 0.7882 - accuracy: 0.6690 - val_loss: 0.3698 - val_accuracy: 0.8230
                                           41s 13s/step - loss: 0.4282 - accuracy: 0.8035 - val_loss: 0.2904 - val_accuracy: 0.8810
     [===
3/10
                                               14s/step - loss: 0.3975 - accuracy: 0.8140 - val_loss: 0.2642 - val_accuracy: 0.8910
Epoch 4/
63/63 [=
      4/10
                                              14s/step - loss: 0.3773 - accuracy: 0.8255 - val_loss: 0.2872 - val_accuracy: 0.8740
      5/10
                                              14s/step - loss: 0.3767 - accuracy: 0.8275 - val_loss: 0.2983 - val_accuracy: 0.8720
                                              14s/step - loss: 0.3637 - accuracy: 0.8400 - val_loss: 0.2590 - val_accuracy: 0.8860
                                              14s/step - loss: 0.3508 - accuracy: 0.8420 - val loss: 0.2528 - val accuracy: 0.8880
      8/10
                                               14s/step - loss: 0.3723 - accuracy: 0.8190 - val loss: 0.3078 - val accuracy: 0.8600
                                          883s 14s/step - loss: 0.3384 - accuracy: 0.8465 - val_loss: 0.2409 - val_accuracy: 0.8950
      10/10
                                                          loss: 0.3456 - accuracy: 0.8395 - val_loss: 0.2474 - val_accuracy: 0.8940
```



Programming Problem 4:

The CIFAR10 dataset is first downloaded from the <u>link</u> and loaded into the program. The CIFAR-10 dataset consists of 60000 32x32 colour images in 10 classes, with 6000 images per class. There are 50000 training images and 10000 test images. The 10 classes are: airplane, automobile, bird, cat, deer, dog, frog, horse, ship and truck. Some sample images are:



We built a basic convolutional neural networks with several convolution blocks, where each convolution block contains convolution, pooling, and normalization layers. Then the output of the convolution layers was flattened and passed to a single dense layer that produced the output using softmax activation. The model architecture is given below.

Model: "sequential_18"

Output Shape	Param #
(None, 16, 16, 32)	1024
(None, 8, 8, 64)	18752
(None, 4, 4, 128)	74368
(None, 2, 2, 256)	296192
(None, 1024)	0
(None, 10)	10250
	(None, 16, 16, 32) (None, 8, 8, 64) (None, 4, 4, 128) (None, 2, 2, 256) (None, 1024)

Total params: 400,586 Trainable params: 399,626 Non-trainable params: 960 The performance evaluation on the validation set is also given below. The accuracy is around 71% for the basic convolutional neural network.

```
model.fit(X_train, Y_train, batch_size=128, epochs=10, validation_data=(X_val, Y_val)) #epochs=10 original
Epoch 1/10
313/313 [===
                                     ======] - 142s 451ms/step - loss: 1.3013 - accuracy: 0.5469 - val_loss: 2.5546 - val_accuracy: 0.2128
     Epoch 2/10
313/313 [==
                                           == ] - 136s 433ms/step - loss: 0.8316 - accuracy: 0.7107 - val_loss: 1.1211 - val_accuracy: 0.6065
    313/313 [===
Epoch 3/10
313/313 [===
Epoch 4/10
313/313 [===
Epoch 5/10
313/313 [===
Epoch 6/10
                                           =] - 135s 430ms/step - loss: 0.6161 - accuracy: 0.7871 - val_loss: 0.9011 - val_accuracy: 0.6991
                                           = | - 136s 435ms/step - loss: 0.4556 - accuracy: 0.8449 - val loss: 0.9441 - val accuracy: 0.7034
                                         ===] - 135s 432ms/step - loss: 0.3271 - accuracy: 0.8898 - val_loss: 0.9871 - val_accuracy: 0.7011
     313/313 [==:
Epoch 7/10
                                           = ] - 139s 444ms/step - loss: 0.2112 - accuracy: 0.9320 - val_loss: 0.9485 - val_accuracy: 0.7166
     313/313 [==:
Epoch 8/10
                                           =] - 137s 437ms/step - loss: 0.1302 - accuracy: 0.9607 - val_loss: 0.9605 - val_accuracy: 0.7228
     313/313 [==
                                          ==] - 136s 435ms/step - loss: 0.0877 - accuracy: 0.9758 - val_loss: 0.9501 - val_accuracy: 0.7501
     Epoch 9/10
313/313 [==
                                          ==] - 136s 433ms/step - loss: 0.0699 - accuracy: 0.9799 - val_loss: 1.2128 - val_accuracy: 0.7225
    [24] model.evaluate(X_test,Y_test)
                                          ==] - 9s 29ms/step - loss: 1.3585 - accuracy: 0.7129
     [1.358510971069336, 0.7128999829292297]
```

The convolutional blocks are then replaced with the inception blocks.

```
Epoch 1/10
313/313 [==
Epoch 2/10
                                           =] - 312s 992ms/step - loss: 1.5489 - accuracy: 0.4512 - val_loss: 1.2756 - val_accuracy: 0.5405
                                               306s 977ms/step - loss: 1.1470 - accuracy: 0.5967 - val_loss: 1.1130 - val_accuracy: 0.6036
Epoch 3/10
313/313 [==
                                             - 308s 984ms/step - loss: 0.9797 - accuracy: 0.6532 - val_loss: 1.1073 - val_accuracy: 0.6142
Epoch 4/10
313/313 [==
Epoch 5/10
313/313 [==
                                          =] - 311s 995ms/step - loss: 0.8646 - accuracy: 0.6990 - val_loss: 0.9815 - val_accuracy: 0.6616
                                             - 307s 980ms/step - loss: 0.7748 - accuracy: 0.7290 - val_loss: 1.0233 - val_accuracy: 0.6449
Epoch 6/10
313/313 [===
Epoch 7/10
313/313 [===
                                         ==] - 307s 981ms/step - loss: 0.6866 - accuracy: 0.7588 - val_loss: 0.9670 - val_accuracy: 0.6709
                                         ==] - 308s 984ms/step - loss: 0.6060 - accuracy: 0.7874 - val_loss: 1.0310 - val_accuracy: 0.6569
Epoch 8/10 313/313 [==
                                          =] - 304s 973ms/step - loss: 0.5239 - accuracy: 0.8169 - val_loss: 1.0047 - val_accuracy: 0.6757
Epoch 9/10
313/313 [===
Epoch 10/10
313/313 [===
                             ========] - 309s 987ms/step - loss: 0.4438 - accuracy: 0.8468 - val_loss: 1.1049 - val_accuracy: 0.6620
                                      =====] - 307s 980ms/step - loss: 0.3662 - accuracy: 0.8755 - val_loss: 1.1115 - val_accuracy: 0.6713
313/313 [=====
                        ======== ] - 14s 45ms/step - loss: 1.1115 - accuracy: 0.6713
Test loss: 1.1114801168441772
Test accuracy: 0.6712999939918518
```

The inception blocks are then replaced with the residual blocks.

```
=] - 627s 2s/step - loss: 5.1503 - accuracy: 0.3871 - val_loss: 2.9296 - val_accuracy: 0.1716
Epoch 2/10
313/313 [==
                                            - 642s 2s/step - loss: 1.2543 - accuracy: 0.5528 - val_loss: 1.6202 - val_accuracy: 0.4571
Epoch 3/10
313/313 [=
                                            - 635s 2s/step - loss: 1.0518 - accuracy: 0.6266 - val_loss: 1.2074 - val_accuracy: 0.5784
Epoch 4/10
                                        == ] - 631s 2s/step - loss: 0.9041 - accuracy: 0.6819 - val loss: 2.1502 - val accuracy: 0.4685
313/313 [===
Epoch 5/10
313/313 [==
                                         =] - 625s 2s/step - loss: 0.7859 - accuracy: 0.7236 - val_loss: 1.4872 - val_accuracy: 0.5391
Epoch 6/10
313/313 [==
                                         = ] - 641s 2s/step - loss: 0.6822 - accuracy: 0.7593 - val_loss: 1.3554 - val_accuracy: 0.5675
Epoch 7/10
313/313 [==
Epoch 8/10
                                            - 627s 2s/step - loss: 0.5999 - accuracy: 0.7886 - val_loss: 1.1356 - val_accuracy: 0.6356
313/313 [===
Epoch 9/10
                                        ==] - 662s 2s/step - loss: 0.4971 - accuracy: 0.8272 - val_loss: 1.6183 - val_accuracy: 0.5575
                                         == ] - 680s 2s/step - loss: 0.4344 - accuracy: 0.8472 - val_loss: 1.3075 - val_accuracy: 0.6195
313/313 [==
Epoch 10/10
313/313 [====
313/313 [====
                                   ======] - 662s 2s/step - loss: 0.3724 - accuracy: 0.8687 - val_loss: 1.4879 - val_accuracy: 0.6128
                                    ----- ] - 34s 107ms/step - loss: 1.4879 - accuracy: 0.6128
 est loss: 1.487900972366333
 est accuracy: 0.6128000020980835
```

4. Results and Discussion

It should be mentioned that a few issues were encountered while solving the programming questions. Firstly, within the Kaggle's cats and dogs dataset, there were 1 cat image and 1 dog image which couldn't be opened or were empty. Because of these images, the training and testing dataset were showing errors. They were eventually filtered out. Another issue faced was that tensorflow was showing an error which says that the input ran out of data. This was solved by setting the following 2 lines of code:

steps_per_epoch = len(X_train)//batch_size
validation_steps = len(X_test)//batch_size # if you have validation data

5. References

- 1. https://www.cs.toronto.edu/~kriz/learning-features-2009-TR.pdf
- 2. https://arxiv.org/abs/1409.1556
- 3. https://arxiv.org/abs/1409.4842
- 4. https://arxiv.org/abs/1512.03385
- 5. https://arxiv.org/abs/1603.05027
- 6. https://towardsdatascience.com/a-comprehensive-guide-to-convolutional-neural-networks-the-eli5-way-3bd2b1164a53