
Transductive Learning: Motivation, Model, Algorithms

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- Provide motivation/potential applications
- Sketch algorithmic issues
- Sketch theoretical problems

→ Induction vs Transduction

- Algorithms
- Formalization
- Open issues

The learning problem

Induction

We consider a **phenomenon** f that maps inputs (**instances**) \mathbf{x} to outputs (**labels**) $y = f(\mathbf{x})$ (here $y \in \{-1, 1\}$)

- Given a set of example pairs (**training set**) $\{(\mathbf{x}_i, y_i) : i = 1, \dots, n\}$,
- the goal is to recover f

→ This will allow to **predict** the label y_{n+1} of a previously **unseen** instance \mathbf{x}_{n+1} .

Example: Face recognition
Train on pictures of a person and recognize him/her the next day

But there are situations in which

- Obtaining labels is expensive
- Obtaining instances is cheap
- We know in advance the instances to be classified
- We do not care about the classification function

→ Transduction applies

Information retrieval

Information retrieval with relevance feedback

- User enters a query
- Machine returns sample documents
- User labels the documents (relevant/non-relevant)
- Machine selects most relevant documents from database

Relevance

- Obtaining labels requires work from the user
- Obtaining documents is automatic (from database)
- Instances to be classified: documents of the database
- No need to know the classification function (changes for each query)

Transduction

We consider a **phenomenon** f that maps inputs (**instances**) \mathbf{x} to outputs (**labels**) $y = f(\mathbf{x})$ (here $y \in \{-1, 1\}$)

- Given a set of **labeled examples** $\{(\mathbf{x}_i, y_i) : i = 1, \dots, n\}$,
- and a set of **unlabeled examples** x'_1, \dots, x'_m
- the goal is to find the labels y'_1, \dots, y'_m

→ No need to construct a function f , the output of the transduction algorithm is a vector of labels.

→ **Transfer** the information from labeled examples to unlabeled.

Given training data and data to be classified, one can either

- Use induction: build \hat{f} and classify the data with it
- Use transduction directly for classifying data

Even in an inductive setting, one can use transduction.

Example: News filtering

- First day user classifies news according to interest
 - Subsequent days, machine classifies incoming news based on first day labels
- Train on the fly, when receiving the data to be classified
- Retrain the machine every day
- Maximally use the information and tune the result to the news of the day

- Induction: $\{(\mathbf{x}_i, y_i) : i = 1, \dots, n\} \mapsto f$
- Induction with unlabeled data: $\{(\mathbf{x}_i, y_i) : i = 1, \dots, n\} \cup \{x'_1, \dots, x'_m\} \mapsto f$
- Transduction: $\{(\mathbf{x}_i, y_i) : i = 1, \dots, n\} \cup \{x'_1, \dots, x'_m\} \mapsto (y'_1, \dots, y'_m)$.

The choice will depend on

- Availability of unlabeled data
- Need for interpretability
- Time considerations

- Induction vs Transduction

→ Algorithms

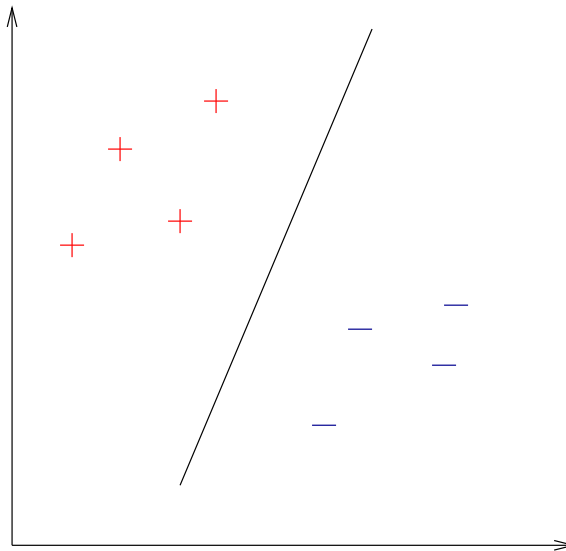
- Formalization

- Open issues

Linear classification

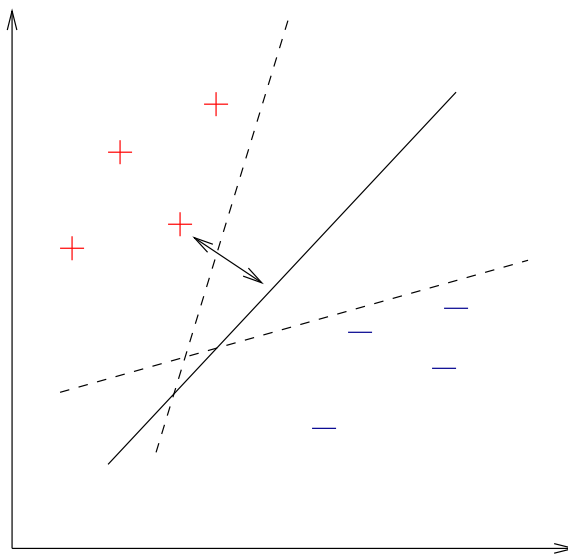
Instances represented in \mathbb{R}^d .

Find a **linear** separation.



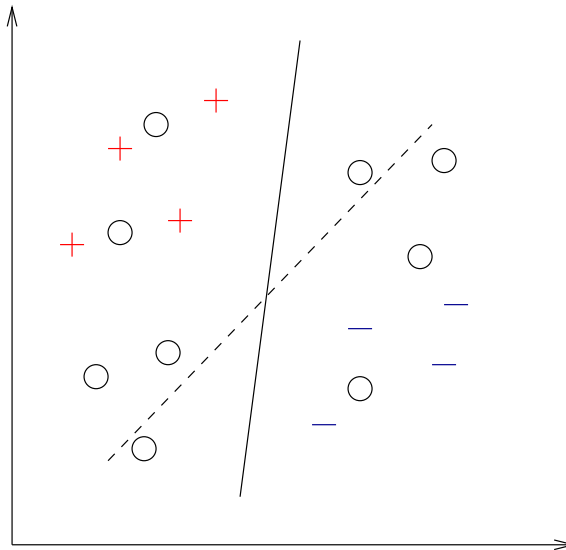
Large margin classification

Margin = distance from the hyperplane to the closest point



Maximize the margin \rightarrow leads to 'robust' solution
 \rightarrow Support Vector Machines

- Assumption: separated classes
- Maximize the margin on unlabeled instances.



Implementation

Goal: Maximize the margin on all examples

Algorithmic issues

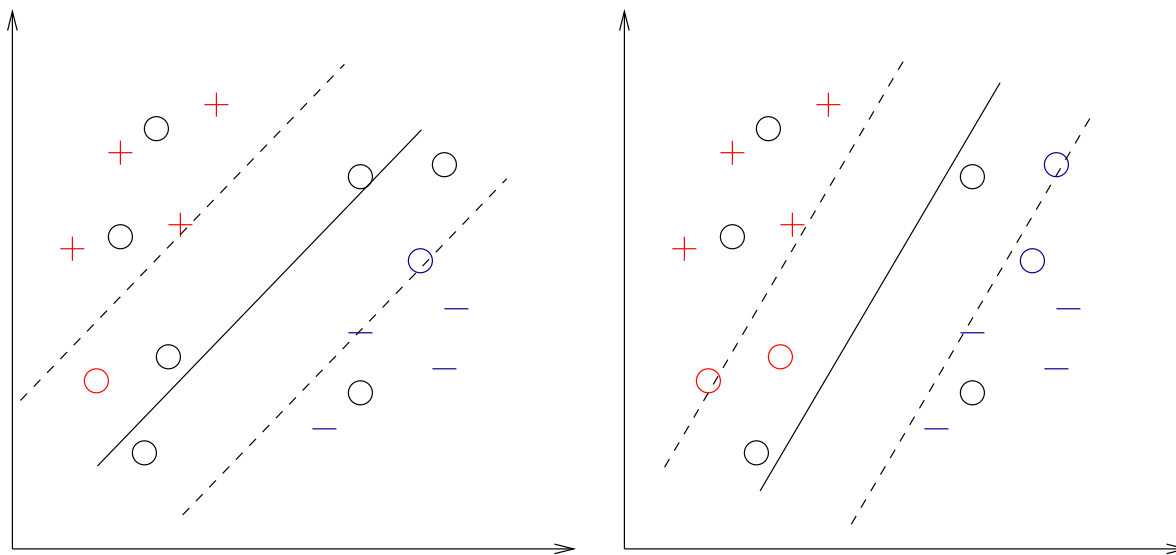
- no unlabeled data \rightarrow quadratic optimization (n^3)
- unlabeled data \rightarrow combinatorial problem (NP)

\rightarrow Need heuristics

\rightarrow Greedy optimization

Greedy

- Only the examples in the margin have an influence
- Label the ones with largest confidence (largest margin)



→ May add backtracking

- Influenced by starting point (induction)
- Not fully transductive because builds an \hat{f}
- Assumption that data is separated

→ Can we make the data separated ?

Support Vector Machines

- Map data into a **feature space**

$$\mathbf{x} \in \mathcal{X} \rightarrow \Phi(\mathbf{x}) \in \mathcal{F}$$

- Perform maximal margin classification in feature space

Kernel trick

- Algorithm can be implemented by computing inner products

$$\Phi(\mathbf{x}) \cdot \Phi(\mathbf{x}') = k(\mathbf{x}, \mathbf{x}')$$

- Simply choose a **kernel** and run the linear algorithm on the matrix

$$K = (k(\mathbf{x}_i, \mathbf{x}_j))_{i,j \in \{1, \dots, n\}}$$

→ k is a measure of similarity. Algorithm works on similarity matrix.

- Choice of Kernel = choice of feature space
- Ideal kernel = feature space contains label
- Ideal kernel matrix

$$k_I(\mathbf{x}_i, \mathbf{x}_j) = y_i y_j$$

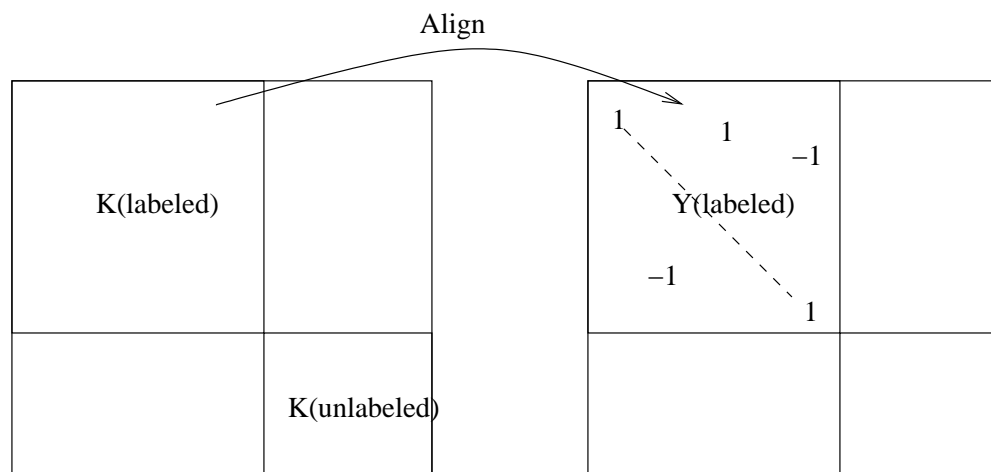
Measure distance from ideal kernel: Alignment

$$A(K) = \sum_{i,j} K_{ij} y_i y_j$$

Measures the data separation:

$$A(K) = \sum_{y_i=y_j} k(\mathbf{x}_i, \mathbf{x}_j) - \sum_{y_i \neq y_j} k(\mathbf{x}_i, \mathbf{x}_j)$$

- Maximize alignment on the labeled data
- Corresponds to maximizing data separation
- Diagonalize, fix eigenvectors, optimize eigenvalues



- Induction vs Transduction

- Algorithms

→ Formalization

- Open issues

- Data is **fixed**

$$x_1, \dots, x_{n+m} \in \mathcal{X}$$
$$y_1, \dots, y_{n+m} \in \{-1, 1\}$$

- Oracle (teacher) chooses **randomly** a subset

$$I \subset \{1, \dots, n + m\}$$

- Input to algorithm

$$x_1, \dots, x_{n+m}$$
$$I$$
$$(y_i)_{i \in I}$$

- Output of algorithm

$$(\hat{y}_i)_{i \in \{1, \dots, n+m\}}$$

Random choice of I

Randomness models

- Fixed size

Choose n examples among $n + m$ with uniform probability for every choice, $\binom{n+m}{n}^{-1}$. $|I| = n$.

- Variable size

For each $i \in \{1, \dots, n + m\}$ choose independently with probability $\frac{n}{n+m}$ to include it.

$\rightarrow \mathbb{E}[|I|] = n$.

\rightarrow We want to make statements that hold with high probability over the random choice of I .

Risk

Recall output $\hat{\mathbf{y}} = \hat{y}_1, \dots, \hat{y}_{n+m}$.

$\hat{\mathbf{y}}$ is an $n + m$ dimensional vector in $\{-1, 1\}^{n+m}$.

- Test error

$$R(\bar{I}, \mathbf{y}) = \frac{1}{|\bar{I}|} \sum_{i \in \bar{I}} \mathbb{I}\{\hat{y}_i \neq y_i\}$$

- Cannot be computed: need to estimate it from the data

Error bounds

We estimate the test error by the empirical error

$$R(I, \hat{\mathbf{y}})$$

We want to prove

$$\mathbb{P}_I [R(\bar{I}, \hat{\mathbf{y}}) - R(I, \hat{\mathbf{y}}) > \epsilon] \leq \delta$$

Choose a set of vectors $\mathcal{Y} \subset \{-1, 1\}^{n+m}$. We want to bound

$$\mathbb{P}_I \left[\sup_{\mathbf{y} \in \mathcal{Y}} R(\bar{I}, \mathbf{y}) - R(I, \mathbf{y}) > \epsilon \right]$$

When $n = m$,

$$R(\bar{I}, \mathbf{y}) \leq R(I, \mathbf{y}) + KC(\mathcal{Y}) + O\left(\frac{1}{\sqrt{n}}\right)$$

Where C Rademacher complexity of \mathcal{Y} .

When $m > n$,

$$R(\bar{I}, \mathbf{y}) \leq R(I, \mathbf{y}) + K\bar{C}(\mathcal{Y}_{2n}) + O\left(\frac{1}{\sqrt{n}}\right)$$

where $\bar{C}(\mathcal{Y}_{2n})$ is the average Rademacher complexity computed on subsets of size $2n$ of the data.

→ Complexity can be computed from x_i only. Labels don't play any role !

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Model Selection

Induction

- Define a structure without any data
- Compute empirical complexity

Transduction

- Define a structure with all the x_i
 - Know exact complexity of this structure
- Data-dependent classes.
- Justifies the margin approach.

- Analyze alignment algorithm in that framework
- Provide model selection methods
- Provide Rademacher estimates
- Prove that unlabeled data **really help**

- Different framework with potentially interesting applications
- Very few people studied it: a lot remains to be done
- Challenges
 - Good empirical evidence \rightarrow justification ?
 - Algorithmic \rightarrow make transduction efficient
 - Theoretical \rightarrow provide guarantees