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MATH1080
Coding Assignment #3

The below tables display Gaussian elimination with and without pivoting, as indicated. A matrix $A_{n \times n}$ is fed into the program. When pivoting *is not* used, only an upper triangular matrix $U_{n \times n}$ and lower triangular matrix $L_{n \times n}$ are output. When pivoting *is* used, an upper triangular matrix $U_{n \times n}$, lower triangular matrix $L_{n \times n}$, and projection (or row swap) matrix $P_{n \times n}$ are output.

In the example provided in the homework, the non-pivoting Gaussian elimination relative accuracy is 3.5604×10^{-12} . The pivoting Gaussian elimination relative accuracy is 8.9907×10^{-17} .

Gauss (non-pivot)	Gauss (pivot)
L1: 1.0000 0 0 0 0 -1.1250 1.0000 0 0 0 -0.8750 47.0000 1.0000 0 0 -2.3750 107.0000 2.2730 1.0000 0 -1.8750 55.0000 1.1308 -692.7727 1.0000 U1: 1.0e+03 * -0.0080 -0.0090 0.0070 0.0190 0.0030 0 -0.0001 0.0169 0.0224 -0.0126 0 0 -0.7950 -1.0370 0.5990 0 0 0.0000 0.0001 -0.0065 0 0 0 0 -4.4988 Gauss (non-pivot) relative accuracy: 3.5604e-12	L2: 1.0000 0 0 0 0 0.4737 1.0000 0 0 0 0.7895 0.5932 1.0000 0 0 -0.4211 -0.9068 0.7729 1.0000 0 0.3684 -0.1525 0.0659 0.0844 1.0000 U2: 19.0000 8.0000 -18.0000 -8.0000 -3.0000 0 6.2105 17.5263 4.7895 -14.5789 0 0 19.8136 -12.5254 -6.9831 0 0 0 29.6553 -6.0860 0 -0.0000 -0.0000 0 2.8550 P2: 0 0 0 1 0 0 1 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 1 0 0 Gauss (partial pivot) relative accuracy: 8.9907e-17

Clearly, pivoting provides more stability for the Gaussian elimination, which is used to solve linear systems, very common, practical problems. With the above relative accuracies, we can see pivoting is about 39601 times more accurate than non-pivoting.