#### Fisher Information

- Fisher information is the variance of the score function
- It tells us how much information Y carries about the parameters of the distribution that models Y
- The asymptotic variance of the MLE is the inverse of the Fisher information
- The Cramér-Rao lower bound, an important result about related to minimum variance unbiased estimators, is given in terms of the Fisher information

### Cramér-Rao inequality

Suppose that  $Y_1, Y_2, ..., Y_n$  are i.i.d. with pdf  $f(y; \theta)$ . Subject to regularity conditions on  $f(y; \theta)$ , we have that for any unbiased estimator  $\tilde{\theta}$  for  $\theta$ ,

$$var(\tilde{\theta}) \ge I_{\theta}^{-1}$$

where

$$I_{\theta} = E\left[\left(\frac{\partial \ell}{\partial \theta}\right)^{2}\right].$$

Fisher information about 0

This inequality gives the lower bound for the variance of unbiased estimators, under regularity conditions (see next slide).

Essentially, this says that, under these conditions, all unbiased estimator for  $\theta$  have variance at least as big as the inverse of the Fisher information about  $\theta$ .

Precise statement of the regularity conditions is somewhat technical. But, in broad terms, we require that:

- The probability density f is sufficiently many times continuously differentiable
- The support of Y does not depend on  $\theta$

These are needed so that we can exchange the order of integration (with respect to y) and differentiation (with respect to  $\theta$ ). That is, we can perform operations like the following:

$$\frac{\partial^2}{\partial \theta^2} \int f(\theta; \mathbf{y}) d\mathbf{y} = \int \frac{\partial^2}{\partial \theta^2} f(\theta; \mathbf{y}) d\mathbf{y}$$

#### Fisher information

 $I_{\theta}$  is known as the Fisher information about  $\theta$  in the observations.

$$I_0 = var [S(0;y)]$$
 i.e. variance of the score
$$= E \left[ \left( \frac{\partial L}{\partial \theta} \right)^2 \right] \quad \text{under regularity conditions}$$

If  $\theta = (\theta_1, \theta_2, ..., \theta_{1k})^T$ , then Io is the Fisher information matrix, with dimensions kxk. The ijth element of Io is given by

$$[l_0]_{ij} = E \left[ \frac{\partial l}{\partial 0_i} \frac{\partial l}{\partial 0_j} \right].$$

#### Alternative form

Under the same regularity conditions as for the Cramér-Rao inequality:

$$I_{\theta} = -E \left[ \frac{\partial^2 \ell}{\partial \theta^2} \right].$$

In the case of 
$$\theta = (\theta_1, \theta_2, ..., \theta_K)^T$$
,
$$\left[ [\theta]_{ij} = - E \left[ \frac{\partial^2 L}{\partial \theta_i \partial \theta_j} \right].$$

## Proof of alternative form

$$\frac{\partial^{2}L}{\partial \theta^{2}} = \frac{\partial}{\partial \theta} \left( \frac{\partial L}{\partial \theta} \right)$$

$$= \frac{\partial}{\partial \theta} \left( \frac{1}{2} \frac{\partial L}{\partial \theta} \right)$$

$$= \frac{\partial^{2}L}{\partial \theta^{2}} \frac{1}{2} \frac{1}$$

quotient rule:

$$\left(\frac{f}{g}\right)' = \frac{f'g - fg'}{g^2}$$
In our case, let  $f = \frac{\partial l}{\partial \theta}$  and  $g = L$ .

Then  $f' = \frac{\partial^2 l}{\partial \theta^2}$  and  $g' = \frac{\partial L}{\partial \theta}$ .

$$\frac{\partial \log L}{\partial \theta} = \boxed{\frac{L}{L} \left( \frac{\partial \theta}{\partial L} \right)}$$

### Proof of alternative form

$$E\left[-\frac{\partial^{2}l}{\partial\theta^{3}}\right] = E\left[-\frac{1}{L}\frac{\partial^{2}l}{\partial\theta^{2}} + \left(\frac{\partial \log L}{\partial\theta}\right)^{2}\right]$$

$$= -E\left[\frac{1}{L}\frac{\partial^{2}l}{\partial\theta^{3}}\right] + E\left[\left(\frac{\partial \log L}{\partial\theta}\right)^{2}\right]$$

$$= \int_{-\infty}^{\infty} \frac{1}{L}\frac{\partial^{2}l}{\partial\theta^{2}} + \int_{-\infty}^{\infty} L dy$$

$$= \int_{-\infty}^{\infty} \frac{\partial^{2}l}{\partial\theta^{2}} dy$$

$$= \frac{\partial^{2}}{\partial\theta^{2}}\int_{-\infty}^{\infty} L dy \quad \text{under regularity conditions}$$

$$= \frac{\partial^{2}}{\partial\theta^{2}} = \frac{\partial^{2}l}{\partial\theta^{2}} = \frac{\partial^{2}l}{\partial\theta^{2$$

$$: \quad E\left[-\frac{\partial^2 L}{\partial \theta^2}\right] = E\left[\left(\frac{\partial L}{\partial \theta}\right)^2\right] = E\left[S(\theta;y)^2\right]$$

#### Example 5.7

Suppose  $y_1, y_2, ..., y_n$  are  $i.i.d.Po(\lambda)$  observations. Find the Fisher information about  $\lambda$ .

Recall 
$$l(\lambda;y) = -n\lambda + (\frac{2}{\xi},y;) \log \lambda + \log \frac{1}{|x|}(\frac{1}{y;x})$$

$$\frac{\partial l}{\partial \lambda} = -n + \frac{1}{\lambda}(\frac{2}{\xi},y;)$$

$$\frac{\partial^2 l}{\partial \lambda^2} = -\frac{1}{\lambda^2}(\frac{2}{\xi},y;)$$

$$I_{\lambda} = E\left[-\frac{\delta^{2} \mathcal{L}}{\delta \lambda^{2}}\right]$$

$$= E\left[\frac{1}{\lambda^{2}}\left(\frac{z}{z}, Y_{i}\right)\right]$$

$$= \frac{1}{\lambda^{2}} \underbrace{\hat{z}}_{i} E(Y_{i})$$

$$= \frac{1}{\lambda^{2}} (n\lambda)$$

$$= \frac{1}{\lambda^{2}} (n\lambda)$$

### Example 5.8

Suppose  $y_1, y_2, ..., y_n$  are  $i.i.d.N(\mu, \sigma^2)$  observations with  $\sigma^2$  known. Find the Fisher information about  $\mu$ .

Recall 
$$l(\mu; y) = -\frac{1}{2} \log(2\pi\sigma^2) - \frac{1}{2\sigma^2} \frac{2}{2} (y; -\mu)^2$$

$$\frac{\partial l}{\partial \mu} = \frac{1}{\sigma^2} \frac{2}{i} (y; -\mu)$$

$$\frac{\partial^2 l}{\partial \mu^2} = \frac{1}{\sigma^2} \frac{2}{i} (-1) = -\frac{\Omega}{\sigma^2}$$

$$T = \left[-\frac{\delta^2 l}{\delta^2}\right]$$

$$I_{\mu} = \bar{E} \left[ -\frac{\delta^{2} \ell}{\delta \mu^{2}} \right]$$

$$= \bar{E} \left[ \frac{n}{\sigma^{2}} \right]$$

$$= \frac{n}{\ell^{2}}$$

#### Example 5.9

Suppose  $y_1, y_2, ..., y_n$  are  $i.i.d.N(\mu, \sigma^2)$  observations where both  $\mu$  and  $\sigma^2$  are unknown. Find the Fisher information matrix.

Recall 
$$l(\mu, \sigma^2; y) = -\frac{2}{2} \log(2\pi) - \frac{2}{2} \log(\sigma^2) - \frac{1}{2\sigma^2} \sum_{i=1}^{n} (y_i - \mu)^2$$
  
 $S(\mu, \sigma^2; y) = \begin{bmatrix} \frac{\partial l}{\partial \mu} \\ \frac{\partial l}{\partial \sigma^2} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sigma^2} \sum_{i=1}^{n} (y_i - \mu) \\ -\frac{n}{2\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^{n} (y_i - \mu)^2 \end{bmatrix}$   
Observe that:

$$\frac{\partial^2 l}{\partial \mu^2} = -\frac{n}{\sigma^2}$$

$$\frac{\partial^2 \mathcal{L}}{\partial \mu \partial \sigma^2} = \frac{\partial^2 \mathcal{L}}{\partial \sigma^2 \partial \mu} = \frac{\partial}{\partial \sigma} \left[ \frac{\partial \mathcal{L}}{\partial \mu} \right] = -\frac{1}{\sigma^4} \stackrel{\mathcal{L}}{\stackrel{:}{=}} (y; -\mu)$$

$$\frac{\delta^{2} l}{3 \sigma^{4}} = \frac{\Omega}{2 \sigma^{4}} - \frac{1}{\sigma^{6}} \sum_{i=1}^{2} (y_{i} - \mu)^{2}$$

# Example 5.9 Solution

$$\begin{bmatrix}
\begin{bmatrix} \frac{3^{2}1}{3\mu^{2}} \end{bmatrix} = \frac{\Lambda}{\sigma^{2}}
\end{bmatrix} = \begin{bmatrix}
\begin{bmatrix} \frac{1}{64} \sum_{i=1}^{2} (Y_{i} - \mu) \end{bmatrix} = \frac{1}{64} \sum_{i=1}^{2} \left[ E(Y_{i}) - \mu \right] = \frac{1}{64} \sum_{i=1}^{2} (\mu - \mu) = 0
\end{bmatrix}$$

$$\begin{bmatrix} \frac{3^{2}1}{3\mu^{3}} \end{bmatrix} = \begin{bmatrix} \frac{1}{64} \sum_{i=1}^{2} (Y_{i} - \mu)^{2} - \frac{N}{2\sigma^{4}} \\ \frac{1}{66} E \begin{bmatrix} \sigma^{2} \sum_{i=1}^{2} (Y_{i} - \mu)^{2} \end{bmatrix} - \frac{N}{2\sigma^{4}}
\end{bmatrix}$$

$$= \frac{1}{66} E \begin{bmatrix} \sigma^{2} \sum_{i=1}^{2} (Y_{i} - \mu)^{2} \end{bmatrix} - \frac{N}{2\sigma^{4}}$$

$$= \frac{1}{64} E \begin{bmatrix} \sum_{i=1}^{2} Z_{i}^{2} \end{bmatrix} - \frac{N}{2\sigma^{4}}$$

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$$= \frac{1}{64} E \begin{bmatrix} \sum_{i=1}^{2} Z_{i}^{2} \end{bmatrix} - \frac{N}{2\sigma^{4}}$$

$$= \frac{N}{2\sigma^{4}}$$

$$= \frac{N}{2\sigma^{4}}$$

$$= \begin{bmatrix} \frac{1}{6} \frac{3^{2}1}{3\mu^{3}} \end{bmatrix} E \begin{bmatrix} -\frac{3^{2}1}{3\mu^{3}} \end{bmatrix}$$

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$$= \begin{bmatrix} \frac{N}{6} \end{bmatrix}$$

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