Revision of Probability and Statistics

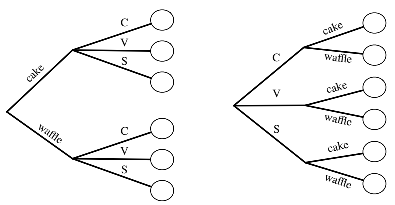
These notes are adapted from the Probability Cheatsheet by William Chen (`http://wzchen.com`) and Joe Blitzstein, with contributions from Sebastian Chiu, Yuan Jiang, Yuqi Hou, and Jessy Hwang. Material based on Joe Blitzstein's (`@stat110`) lectures (`http://stat110.net`) and Blitzstein/Hwang's Introduction to Probability textbook (`http://bit.ly/introprobability`).

The original document is available from http://wzchen.com/probability-cheatsheet.

Please note that the notations used here may not the same as those used in MATHS 2103/7103 and this course (STATS 2107).

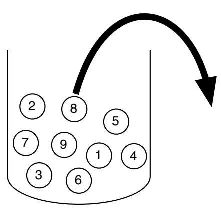
Counting

Multiplication Rule



Let's say we have a compound experiment (an experiment with multiple components). If the 1st component has n_1 possible outcomes, the 2nd component has n_2 possible outcomes, ..., and the rth component has n_r possible outcomes, then overall there are $n_1 n_2 \dots n_r$ possibilities for the whole experiment.

Sampling Table



The sampling table gives the number of possible samples of size k out of a population of size n, under various assumptions about how the sample is collected.

	Order Matters	**Not Matter**
With Replacement	n^k	$\binom{n+k-1}{k}$
Without Replacement	$\frac{n!}{(n-k)!}$	$\binom{n}{k}$

Naive Definition of Probability

If all outcomes are equally likely, the probability of an event A happening is:

$$P_{\text{naive}}(A) = \frac{\text{number of outcomes favorable to } A}{\text{number of outcomes}}$$

Thinking Conditionally

Independence

Independent Events A and B are independent if knowing whether A occurred gives no information about whether B occurred. More formally, A and B (which have nonzero probability) are independent if and only if one of the following equivalent statements holds:

$$P(A \cap B) = P(A)P(B)$$
$$P(A|B) = P(A)$$
$$P(B|A) = P(B)$$

Conditional Independence A and B are conditionally independent given C if $P(A \cap B|C) = P(A|C)P(B|C)$. Conditional independence does not imply independence, and independence does not imply conditional independence.

Unions, Intersections, and Complements

De Morgan's Laws A useful identity that can make calculating probabilities of unions easier by relating them to intersections, and vice versa. Analogous results hold with more than two sets.

$$(A \cup B)^c = A^c \cap B^c$$
$$(A \cap B)^c = A^c \cup B^c$$

Joint, Marginal, and Conditional

Joint Probability $P(A \cap B)$ or $P(A, B)$ – Probability of A and B.

Marginal (Unconditional) Probability $P(A)$ – Probability of A.

Conditional Probability $P(A|B) = P(A, B)/P(B)$ – Probability of A, given that B occurred.

Conditional Probability *is* Probability $P(A|B)$ is a probability function for any fixed B. Any theorem that holds for probability also holds for conditional probability.

Probability of an Intersection or Union

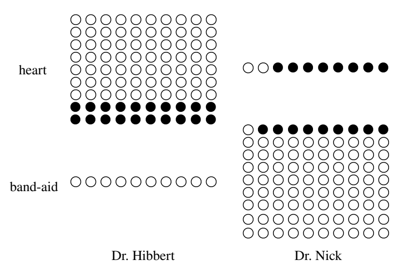
Intersections via Conditioning

$$P(A, B) = P(A)P(B|A)$$
$$P(A, B, C) = P(A)P(B|A)P(C|A, B)$$

Unions via Inclusion-Exclusion

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$
$$\begin{aligned} P(A \cup B \cup C) = {} & P(A) + P(B) + P(C) \\ & - P(A \cap B) - P(A \cap C) - P(B \cap C) \\ & + P(A \cap B \cap C). \end{aligned}$$

Simpson's Paradox



It is possible to have

$$P(A \mid B, C) < P(A \mid B^c, C) \text{ and } P(A \mid B, C^c) < P(A \mid B^c, C^c)$$
$$\text{yet also } P(A \mid B) > P(A \mid B^c).$$

Law of Total Probability (LOTP)

Let $B_1, B_2, B_3, \dots B_n$ be a *partition* of the sample space (i.e., they are disjoint and their union is the entire sample space).

$$P(A) = P(A|B_1)P(B_1) + P(A|B_2)P(B_2) + \cdots + P(A|B_n)P(B_n)$$
$$P(A) = P(A \cap B_1) + P(A \cap B_2) + \cdots + P(A \cap B_n)$$

For **LOTP with extra conditioning**, just add in another event C!

$$P(A|C) = P(A|B_1, C)P(B_1|C) + \cdots + P(A|B_n, C)P(B_n|C)$$
$$P(A|C) = P(A \cap B_1|C) + P(A \cap B_2|C) + \cdots + P(A \cap B_n|C)$$

Special case of LOTP with B and B^c as partition:

$$P(A) = P(A|B)P(B) + P(A|B^c)P(B^c)$$
$$P(A) = P(A \cap B) + P(A \cap B^c)$$

Bayes' Rule

Bayes' Rule, and with extra conditioning (just add in C!)

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

$$P(A|B, C) = \frac{P(B|A, C)P(A|C)}{P(B|C)}$$

We can also write

$$P(A|B, C) = \frac{P(A, B, C)}{P(B, C)} = \frac{P(B, C|A)P(A)}{P(B, C)}$$

Odds Form of Bayes' Rule

$$\frac{P(A|B)}{P(A^c|B)} = \frac{P(B|A)}{P(B|A^c)} \frac{P(A)}{P(A^c)}$$

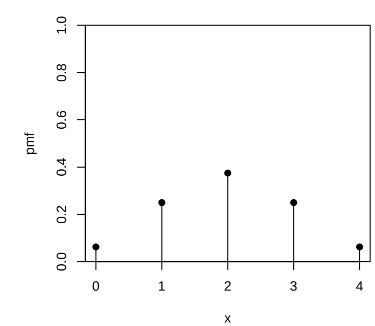
The *posterior odds* of A are the *likelihood ratio* times the *prior odds*.

Random Variables and their Distributions

PMF, CDF, and Independence

Probability Mass Function (PMF) Gives the probability that a *discrete* random variable takes on the value x.

$$p_X(x) = P(X = x)$$

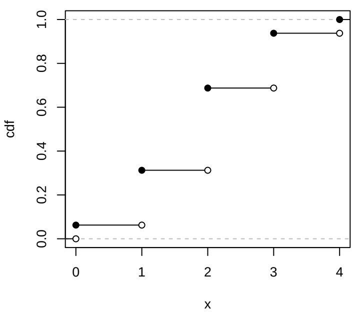


The PMF satisfies

$$p_X(x) \geq 0 \text{ and } \sum_x p_X(x) = 1$$

Cumulative Distribution Function (CDF) Gives the probability that a random variable is less than or equal to x.

$$F_X(x) = P(X \le x)$$



The CDF is an increasing, right-continuous function with

$$F_X(x) \to 0 \text{ as } x \to -\infty \text{ and } F_X(x) \to 1 \text{ as } x \to \infty$$

Independence Intuitively, two random variables are independent if knowing the value of one gives no information about the other. Discrete r.v.s X and Y are independent if for *all* values of x and y

$$P(X = x, Y = y) = P(X = x)P(Y = y)$$

Expected Value and Indicators

Expected Value and Linearity

Expected Value (a.k.a. *mean*, *expectation*, or *average*) is a weighted average of the possible outcomes of our random variable. Mathematically, if $x_1, x_2, x_3, \ldots$ are all of the distinct possible values that X can take, the expected value of X is

$$E(X) = \sum_i x_i P(X = x_i)$$

X	Y	$X + Y$
3	4	7
2	2	4
6	8	14
10	23	33
1	–3	–2
1	0	1
5	9	14
4	1	5
...	...	...

$$\frac{1}{n}\sum_{i=1}^{n} x_i \quad + \quad \frac{1}{n}\sum_{i=1}^{n} y_i \quad = \quad \frac{1}{n}\sum_{i=1}^{n} (x_i + y_i)$$

$$E(X) \quad + \quad E(Y) \quad = \quad E(X + Y)$$

Linearity For any r.v.s X and Y, and constants a, b, c,

$$E(aX + bY + c) = aE(X) + bE(Y) + c$$

Same distribution implies same mean If X and Y have the same distribution, then $E(X) = E(Y)$ and, more generally,

$$E(g(X)) = E(g(Y))$$

Conditional Expected Value is defined like expectation, only conditioned on any event A.

$$E(X|A) = \sum_x xP(X = x|A)$$

Indicator Random Variables

Indicator Random Variable is a random variable that takes on the value 1 or 0. It is always an indicator of some event: if the event occurs, the indicator is 1; otherwise it is 0. They are useful for many problems about counting how many events of some kind occur. Write

$$I_A = \begin{cases} 1 & \text{if } A \text{ occurs,} \\ 0 & \text{if } A \text{ does not occur.} \end{cases}$$

Note that $I_A^2 = I_A, I_A I_B = I_{A\cap B}$, and $I_{A\cup B} = I_A + I_B - I_A I_B$.

Distribution $I_A \sim \text{Bern}(p)$ where $p = P(A)$.

Fundamental Bridge The expectation of the indicator for event A is the probability of event A: $E(I_A) = P(A)$.

Variance and Standard Deviation

$$\text{Var}(X) = E\left(X - E(X)\right)^2 = E(X^2) - (E(X))^2$$

$$\text{SD}(X) = \sqrt{\text{Var}(X)}$$

Continuous RVs, LOTUS, UoU

Continuous Random Variables (CRVs)

What's the probability that a CRV is in an interval? Take the difference in CDF values (or use the PDF as described later).

$$P(a \le X \le b) = P(X \le b) - P(X \le a) = F_X(b) - F_X(a)$$

For $X \sim \mathcal{N}(\mu, \sigma^2)$, this becomes

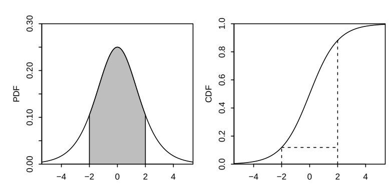
$$P(a \le X \le b) = \Phi\left(\frac{b-\mu}{\sigma}\right) - \Phi\left(\frac{a-\mu}{\sigma}\right)$$

What is the Probability Density Function (PDF)? The PDF f is the derivative of the CDF F.

$$F'(x) = f(x)$$

A PDF is nonnegative and integrates to 1. By the fundamental theorem of calculus, to get from PDF back to CDF we can integrate:

$$F(x) = \int_{-\infty}^{x} f(t)dt$$



To find the probability that a CRV takes on a value in an interval, integrate the PDF over that interval.

$$F(b) - F(a) = \int_a^b f(x)dx$$

How do I find the expected value of a CRV? Analogous to the discrete case, where you sum x times the PMF, for CRVs you integrate x times the PDF.

$$E(X) = \int_{-\infty}^{\infty} xf(x)dx$$

LOTUS

Expected value of a function of an r.v. The expected value of X is defined this way:

$$E(X) = \sum_x xP(X = x) \text{ (for discrete } X\text{)}$$

$$E(X) = \int_{-\infty}^{\infty} xf(x)dx \text{ (for continuous } X\text{)}$$

The **Law of the Unconscious Statistician (LOTUS)** states that you can find the expected value of a *function of a random variable*, $g(X)$, in a similar way, by replacing the x in front of the PMF/PDF by $g(x)$ but still working with the PMF/PDF of X:

$$E(g(X)) = \sum_x g(x)P(X = x) \text{ (for discrete } X\text{)}$$

$$E(g(X)) = \int_{-\infty}^{\infty} g(x)f(x)dx \text{ (for continuous } X\text{)}$$

What's a function of a random variable? A function of a random variable is also a random variable. For example, if X is the number of bikes you see in an hour, then $g(X) = 2X$ is the number of bike wheels you see in that hour and $h(X) = \binom{X}{2} = \frac{X(X-1)}{2}$ is the number of *pairs* of bikes such that you see both of those bikes in that hour.

What's the point? You don't need to know the PMF/PDF of $g(X)$ to find its expected value. All you need is the PMF/PDF of X.

Universality of Uniform (UoU)

When you plug any CRV into its own CDF, you get a Uniform(0,1) random variable. When you plug a Uniform(0,1) r.v. into an inverse CDF, you get an r.v. with that CDF. For example, let's say that a random variable X has CDF

$$F(x) = 1 - e^{-x}, \text{ for } x > 0$$

By UoU, if we plug X into this function then we get a uniformly distributed random variable.

$$F(X) = 1 - e^{-X} \sim \text{Unif}(0, 1)$$

Similarly, if $U \sim \text{Unif}(0, 1)$ then $F^{-1}(U)$ has CDF F. The key point is that for any continuous random variable X, we can transform it into a Uniform random variable and back by using its CDF.

Moments and MGFs

Moments

Moments describe the shape of a distribution. Let X have mean μ and standard deviation σ, and $Z = (X - \mu)/\sigma$ be the *standardized* version of X. The kth moment of X is $\mu_k = E(X^k)$ and the kth standardized moment of X is $m_k = E(Z^k)$. The mean, variance, skewness, and kurtosis are important summaries of the shape of a distribution.

Mean $E(X) = \mu_1$

Variance $\text{Var}(X) = \mu_2 - \mu_1^2$

Skewness $\text{Skew}(X) = m_3$

Kurtosis $\text{Kurt}(X) = m_4 - 3$

Moment Generating Functions

MGF For any random variable X, the function

$$M_X(t) = E(e^{tX})$$

is the **moment generating function (MGF)** of X, if it exists for all t in some open interval containing 0. The variable t could just as well have been called u or v. It's a bookkeeping device that lets us work with the *function* M_X rather than the *sequence* of moments.

Why is it called the Moment Generating Function? Because the kth derivative of the moment generating function, evaluated at 0, is the kth moment of X.

$$\mu_k = E(X^k) = M_X^{(k)}(0)$$

This is true by Taylor expansion of e^{tX} since

$$M_X(t) = E(e^{tX}) = \sum_{k=0}^{\infty} \frac{E(X^k)t^k}{k!} = \sum_{k=0}^{\infty} \frac{\mu_k t^k}{k!}$$

MGF of linear functions If we have $Y = aX + b$, then

$$M_Y(t) = E(e^{t(aX+b)}) = e^{bt}E(e^{(at)X}) = e^{bt}M_X(at)$$

Uniqueness *If it exists, the MGF uniquely determines the distribution.* This means that for any two random variables X and Y, they are distributed the same (their PMFs/PDFs are equal) if and only if their MGFs are equal.

Summing Independent RVs by Multiplying MGFs. If X and Y are independent, then

$$M_{X+Y}(t) = E(e^{t(X+Y)}) = E(e^{tX})E(e^{tY}) = M_X(t) \cdot M_Y(t)$$

The MGF of the sum of two random variables is the product of the MGFs of those two random variables.

Joint PDFs and CDFs

Joint Distributions

The **joint CDF** of X and Y is

$$F(x, y) = P(X \leq x, Y \leq y)$$

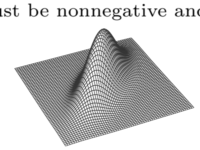
In the discrete case, X and Y have a **joint PMF**

$$p_{X,Y}(x, y) = P(X = x, Y = y).$$

In the continuous case, they have a **joint PDF**

$$f_{X,Y}(x, y) = \frac{\partial^2}{\partial x \partial y} F_{X,Y}(x, y).$$

The joint PMF/PDF must be nonnegative and sum/integrate to 1.



Conditional Distributions

Conditioning and Bayes' rule for discrete r.v.s

$$P(Y = y|X = x) = \frac{P(X = x, Y = y)}{P(X = x)} = \frac{P(X = x|Y = y)P(Y = y)}{P(X = x)}$$

Conditioning and Bayes' rule for continuous r.v.s

$$f_{Y|X}(y|x) = \frac{f_{X,Y}(x, y)}{f_X(x)} = \frac{f_{X|Y}(x|y)f_Y(y)}{f_X(x)}$$

Hybrid Bayes' rule

$$f_X(x|A) = \frac{P(A|X = x)f_X(x)}{P(A)}$$

Marginal Distributions

To find the distribution of one (or more) random variables from a joint PMF/PDF, sum/integrate over the unwanted random variables.

Marginal PMF from joint PMF

$$P(X = x) = \sum_y P(X = x, Y = y)$$

Marginal PDF from joint PDF

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, y)dy$$

Independence of Random Variables

Random variables X and Y are independent if and only if any of the following conditions holds:

- Joint CDF is the product of the marginal CDFs
- Joint PMF/PDF is the product of the marginal PMFs/PDFs
- Conditional distribution of Y given X is the marginal distribution of Y

Write $X \perp\!\!\!\perp Y$ to denote that X and Y are independent.

Multivariate LOTUS

LOTUS in more than one dimension is analogous to the 1D LOTUS. For discrete random variables:

$$E(g(X, Y)) = \sum_x \sum_y g(x, y)P(X = x, Y = y)$$

For continuous random variables:

$$E(g(X, Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y)f_{X,Y}(x, y)dxdy$$

Covariance and Transformations

Covariance and Correlation

Covariance is the analog of variance for two random variables.

$$\mathrm{Cov}(X, Y) = E\left((X - E(X))(Y - E(Y))\right) = E(XY) - E(X)E(Y)$$

Note that

$$\mathrm{Cov}(X, X) = E(X^2) - (E(X))^2 = \mathrm{Var}(X)$$

Correlation is a standardized version of covariance that is always between -1 and 1.

$$\mathrm{Corr}(X, Y) = \frac{\mathrm{Cov}(X, Y)}{\sqrt{\mathrm{Var}(X)\mathrm{Var}(Y)}}$$

Covariance and Independence If two random variables are independent, then they are uncorrelated. The converse is not necessarily true (e.g., consider $X \sim \mathcal{N}(0, 1)$ and $Y = X^2$).

$$X \perp\!\!\!\perp Y \longrightarrow \mathrm{Cov}(X, Y) = 0 \longrightarrow E(XY) = E(X)E(Y)$$

Covariance and Variance The variance of a sum can be found by

$$\mathrm{Var}(X + Y) = \mathrm{Var}(X) + \mathrm{Var}(Y) + 2\mathrm{Cov}(X, Y)$$

$$\mathrm{Var}(X_1 + X_2 + \cdots + X_n) = \sum_{i=1}^{n} \mathrm{Var}(X_i) + 2\sum_{i<j} \mathrm{Cov}(X_i, X_j)$$

If X and Y are independent then they have covariance 0, so

$$X \perp\!\!\!\perp Y \Longrightarrow \mathrm{Var}(X + Y) = \mathrm{Var}(X) + \mathrm{Var}(Y)$$

If $X_1, X_2, \dots, X_n$ are identically distributed and have the same covariance relationships (often by **symmetry**), then

$$\mathrm{Var}(X_1 + X_2 + \cdots + X_n) = n\mathrm{Var}(X_1) + 2\binom{n}{2}\mathrm{Cov}(X_1, X_2)$$

Covariance Properties For random variables W, X, Y, Z and constants a, b:

$$\begin{aligned}
\mathrm{Cov}(X, Y) &= \mathrm{Cov}(Y, X)\\
\mathrm{Cov}(X + a, Y + b) &= \mathrm{Cov}(X, Y)\\
\mathrm{Cov}(aX, bY) &= ab\mathrm{Cov}(X, Y)\\
\mathrm{Cov}(W + X, Y + Z) &= \mathrm{Cov}(W, Y) + \mathrm{Cov}(W, Z) + \mathrm{Cov}(X, Y)\\
&\quad + \mathrm{Cov}(X, Z)
\end{aligned}$$

Correlation is location-invariant and scale-invariant For any constants a, b, c, d with a and c nonzero,

$$\mathrm{Corr}(aX + b, cY + d) = \mathrm{Corr}(X, Y)$$

Transformations

One Variable Transformations Let's say that we have a random variable X with PDF $f_X(x)$, but we are also interested in some function of X. We call this function $Y = g(X)$. Also let $y = g(x)$. If g is differentiable and strictly increasing (or strictly decreasing), then the PDF of Y is

$$f_Y(y) = f_X(x)\left|\frac{dx}{dy}\right| = f_X(g^{-1}(y))\left|\frac{d}{dy}g^{-1}(y)\right|$$

The derivative of the inverse transformation is called the **Jacobian**.

Two Variable Transformations Similarly, let's say we know the joint PDF of U and V but are also interested in the random vector (X, Y) defined by $(X, Y) = g(U, V)$. Let

$$\frac{\partial(u, v)}{\partial(x, y)} = \begin{pmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{pmatrix}$$

be the **Jacobian matrix.** If the entries in this matrix exist and are continuous, and the determinant of the matrix is never 0, then

$$f_{X,Y}(x, y) = f_{U,V}(u, v)\left|\left|\frac{\partial(u, v)}{\partial(x, y)}\right|\right|$$

The inner bars tells us to take the matrix's determinant, and the outer bars tell us to take the absolute value. In a 2×2 matrix,

$$\left|\left|\begin{matrix} a & b \\ c & d \end{matrix}\right|\right| = |ad - bc|$$

Convolutions

Convolution Integral If you want to find the PDF of the sum of two independent CRVs X and Y, you can do the following integral:

$$f_{X+Y}(t) = \int_{-\infty}^{\infty} f_X(x)f_Y(t - x)dx$$

Example Let $X, Y \sim \mathcal{N}(0, 1)$ be i.i.d. Then for each fixed t,

$$f_{X+Y}(t) = \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}}e^{-x^2/2}\frac{1}{\sqrt{2\pi}}e^{-(t-x)^2/2}dx$$

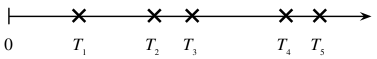
By completing the square and using the fact that a Normal PDF integrates to 1, this works out to $f_{X+Y}(t)$ being the $\mathcal{N}(0, 2)$ PDF.

Poisson Process

Definition We have a **Poisson process** of rate λ arrivals per unit time if the following conditions hold:

1. The number of arrivals in a time interval of length t is $\text{Po}(\lambda t)$.
2. Numbers of arrivals in disjoint time intervals are independent.

For example, the numbers of arrivals in the time intervals $[0, 5]$, $(5, 12)$, and $[13, 23)$ are independent with $\text{Po}(5\lambda)$, $\text{Po}(7\lambda)$, $\text{Po}(10\lambda)$ distributions, respectively.



Count-Time Duality Consider a Poisson process of emails arriving in an inbox at rate λ emails per hour. Let T_n be the time of arrival of the nth email (relative to some starting time 0) and N_t be the number of emails that arrive in $[0, t]$. Let's find the distribution of T_1. The event $T_1 > t$, the event that you have to wait more than t hours to get the first email, is the same as the event $N_t = 0$, which is the event that there are no emails in the first t hours. So

$$P(T_1 > t) = P(N_t = 0) = e^{-\lambda t} \longrightarrow P(T_1 \leq t) = 1 - e^{-\lambda t}$$

Thus we have $T_1 \sim \text{Exp}(\lambda)$. By the memoryless property and similar reasoning, the interarrival times between emails are i.i.d. $\text{Exp}(\lambda)$, i.e., the differences $T_n - T_{n-1}$ are i.i.d. $\text{Exp}(\lambda)$.

Order Statistics

Definition Let's say you have n i.i.d. r.v.s $X_1, X_2, \dots, X_n$. If you arrange them from smallest to largest, the ith element in that list is the ith order statistic, denoted $X_{(i)}$. So $X_{(1)}$ is the smallest in the list and $X_{(n)}$ is the largest in the list.

Note that the order statistics are *dependent*, e.g., learning $X_{(4)} = 42$ gives us the information that $X_{(1)}, X_{(2)}, X_{(3)}$ are ≤ 42 and $X_{(5)}, X_{(6)}, \dots, X_{(n)}$ are ≥ 42.

Distribution Taking n i.i.d. random variables $X_1, X_2, \dots, X_n$ with CDF $F(x)$ and PDF $f(x)$, the CDF and PDF of $X_{(i)}$ are:

$$F_{X_{(i)}}(x) = P(X_{(i)} \leq x) = \sum_{k=i}^{n} \binom{n}{k} F(x)^k (1 - F(x))^{n-k}$$

$$f_{X_{(i)}}(x) = n\binom{n-1}{i-1} F(x)^{i-1} (1 - F(x))^{n-i} f(x)$$

Uniform Order Statistics The jth order statistic of i.i.d. $U_1, \dots, U_n \sim \text{Unif}(0, 1)$ is $U_{(j)} \sim \text{Beta}(j, n - j + 1)$.

Conditional Expectation

Conditioning on an Event We can find $E(Y|A)$, the expected value of Y given that event A occurred. A very important case is when A is the event $X = x$. Note that $E(Y|A)$ is a *number*. For example:

- The expected value of a fair die roll, given that it is prime, is $\frac{1}{3} \cdot 2 + \frac{1}{3} \cdot 3 + \frac{1}{3} \cdot 5 = \frac{10}{3}$.
- Let Y be the number of successes in 10 independent Bernoulli trials with probability p of success. Let A be the event that the first 3 trials are all successes. Then

  $$E(Y|A) = 3 + 7p$$

  since the number of successes among the last 7 trials is $\text{Bin}(7, p)$.
- Let $T \sim \text{Exp}(1/10)$ be how long you have to wait until the shuttle comes. Given that you have already waited t minutes, the expected additional waiting time is 10 more minutes, by the memoryless property. That is, $E(T|T > t) = t + 10$.

Discrete Y	**Continuous** Y
$E(Y) = \sum_y yP(Y = y)$	$E(Y) = \int_{-\infty}^{\infty} yf_Y(y)dy$
$E(Y\|A) = \sum_y yP(Y = y\|A)$	$E(Y\|A) = \int_{-\infty}^{\infty} yf(y\|A)dy$

Conditioning on a Random Variable We can also find $E(Y|X)$, the expected value of Y given the random variable X. This is *a function of the random variable* X. It is *not* a number except in certain special cases such as if $X \perp\!\!\!\perp Y$. To find $E(Y|X)$, find $E(Y|X = x)$ and then plug in X for x. For example:

- If $E(Y|X = x) = x^3 + 5x$, then $E(Y|X) = X^3 + 5X$.
- Let Y be the number of successes in 10 independent Bernoulli trials with probability p of success and X be the number of successes among the first 3 trials. Then $E(Y|X) = X + 7p$.
- Let $X \sim \mathcal{N}(0, 1)$ and $Y = X^2$. Then $E(Y|X = x) = x^2$ since if we know $X = x$ then we know $Y = x^2$. And $E(X|Y = y) = 0$ since if we know $Y = y$ then we know $X = \pm\sqrt{y}$, with equal probabilities (by symmetry). So $E(Y|X) = X^2$, $E(X|Y) = 0$.

Properties of Conditional Expectation

1. $E(Y|X) = E(Y)$ if $X \perp\!\!\!\perp Y$
2. $E(h(X)W|X) = h(X)E(W|X)$ (**taking out what's known**) In particular, $E(h(X)|X) = h(X)$.
3. $E(E(Y|X)) = E(Y)$ (**Adam's Law**, a.k.a. Law of Total Expectation)

Adam's Law (a.k.a. Law of Total Expectation) can also be written in a way that looks analogous to LOTP. For any events $A_1, A_2, \dots, A_n$ that partition the sample space,

$$E(Y) = E(Y|A_1)P(A_1) + \dots + E(Y|A_n)P(A_n)$$

For the special case where the partition is A, A^c, this says

$$E(Y) = E(Y|A)P(A) + E(Y|A^c)P(A^c)$$

Eve's Law (a.k.a. Law of Total Variance)

$$\text{Var}(Y) = E(\text{Var}(Y|X)) + \text{Var}(E(Y|X))$$

MVN, LLN, CLT

Law of Large Numbers (LLN)

Let $X_1, X_2, X_3 \dots$ be i.i.d. with mean μ. The **sample mean** is

$$\bar{X}_n = \frac{X_1 + X_2 + X_3 + \dots + X_n}{n}$$

The **Law of Large Numbers** states that as $n \to \infty$, $\bar{X}_n \to \mu$ with probability 1. For example, in flips of a coin with probability p of Heads, let X_j be the indicator of the jth flip being Heads. Then LLN says the proportion of Heads converges to p (with probability 1).

Central Limit Theorem (CLT)

Approximation using CLT

We use $\dot{\sim}$ to denote *is approximately distributed*. We can use the **Central Limit Theorem** to approximate the distribution of a random variable $Y = X_1 + X_2 + \dots + X_n$ that is a sum of n i.i.d. random variables X_i. Let $E(Y) = \mu_Y$ and $\text{Var}(Y) = \sigma_Y^2$. The CLT says

$$Y \dot{\sim} \mathcal{N}(\mu_Y, \sigma_Y^2)$$

If the X_i are i.i.d. with mean μ_X and variance σ_X^2, then $\mu_Y = n\mu_X$ and $\sigma_Y^2 = n\sigma_X^2$. For the sample mean $\bar{X}_n$, the CLT says

$$\bar{X}_n = \frac{1}{n}(X_1 + X_2 + \dots + X_n) \dot{\sim} \mathcal{N}(\mu_X, \sigma_X^2/n)$$

Asymptotic Distributions using CLT

We use $\xrightarrow{D}$ to denote *converges in distribution to* as $n \to \infty$. The CLT says that if we standardize the sum $X_1 + \dots + X_n$ then the distribution of the sum converges to $\mathcal{N}(0, 1)$ as $n \to \infty$:

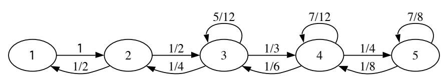
$$\frac{1}{\sigma\sqrt{n}}(X_1 + \dots + X_n - n\mu_X) \xrightarrow{D} \mathcal{N}(0, 1)$$

In other words, the CDF of the left-hand side goes to the standard Normal CDF, Φ. In terms of the sample mean, the CLT says

$$\frac{\sqrt{n}(\bar{X}_n - \mu_X)}{\sigma_X} \xrightarrow{D} \mathcal{N}(0, 1)$$

Markov Chains

Definition



A Markov chain is a random walk in a **state space**, which we will assume is finite, say $\{1, 2, \dots, M\}$. We let X_t denote which element of the state space the walk is visiting at time t. The Markov chain is the sequence of random variables tracking where the walk is at all points in time, $X_0, X_1, X_2, \dots$. By definition, a Markov chain must satisfy the **Markov property**, which says that if you want to predict where the chain will be at a future time, if we know the present state then the entire past history is irrelevant. *Given the present, the past and future are conditionally independent.* In symbols,

$$P(X_{n+1} = j|X_0 = i_0, X_1 = i_1, \dots, X_n = i) = P(X_{n+1} = j|X_n = i)$$

State Properties

A state is either recurrent or transient.

- If you start at a **recurrent state**, then you will always return back to that state at some point in the future. ♪*You can check-out any time you like, but you can never leave.* ♪
- Otherwise you are at a **transient state**. There is some positive probability that once you leave you will never return. ♪*You don't have to go home, but you can't stay here.* ♪

A state is either periodic or aperiodic.

- If you start at a **periodic state** of period k, then the GCD of the possible numbers of steps it would take to return back is $k > 1$.
- Otherwise you are at an **aperiodic state**. The GCD of the possible numbers of steps it would take to return back is 1.

Transition Matrix

Let the state space be $\{1, 2, \dots, M\}$. The transition matrix Q is the $M \times M$ matrix where element q_{ij} is the probability that the chain goes from state i to state j in one step:

$$q_{ij} = P(X_{n+1} = j | X_n = i)$$

To find the probability that the chain goes from state i to state j in exactly m steps, take the (i, j) element of Q^m.

$$q_{ij}^{(m)} = P(X_{n+m} = j | X_n = i)$$

If X_0 is distributed according to the row vector PMF $\vec{p}$, i.e., $p_j = P(X_0 = j)$, then the PMF of X_n is $\vec{p}Q^n$.

Chain Properties

A chain is **irreducible** if you can get from anywhere to anywhere. If a chain (on a finite state space) is irreducible, then all of its states are recurrent. A chain is **periodic** if any of its states are periodic, and is **aperiodic** if none of its states are periodic. In an irreducible chain, all states have the same period.

A chain is **reversible** with respect to $\vec{s}$ if $s_i q_{ij} = s_j q_{ji}$ for all i, j. Examples of reversible chains include any chain with $q_{ij} = q_{ji}$, with $\vec{s} = (\frac{1}{M}, \frac{1}{M}, \dots, \frac{1}{M})$, and random walk on an undirected network.

Stationary Distribution

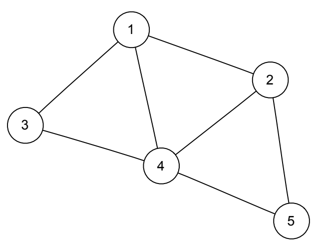
Let us say that the vector $\vec{s} = (s_1, s_2, \dots, s_M)$ be a PMF (written as a row vector). We will call $\vec{s}$ the **stationary distribution** for the chain if $\vec{s}Q = \vec{s}$. As a consequence, if X_t has the stationary distribution, then all future $X_{t+1}, X_{t+2}, \dots$ also have the stationary distribution.

For irreducible, aperiodic chains, the stationary distribution exists, is unique, and s_i is the long-run probability of a chain being at state i. The expected number of steps to return to i starting from i is $1/s_i$.

To find the stationary distribution, you can solve the matrix equation $(Q' - I)\vec{s}\,' = 0$. The stationary distribution is uniform if the columns of Q sum to 1.

Reversibility Condition Implies Stationarity If you have a PMF $\vec{s}$ and a Markov chain with transition matrix Q, then $s_i q_{ij} = s_j q_{ji}$ for all states i, j implies that $\vec{s}$ is stationary.

Random Walk on an Undirected Network



If you have a collection of **nodes**, pairs of which can be connected by undirected **edges**, and a Markov chain is run by going from the current node to a uniformly random node that is connected to it by an edge, then this is a random walk on an undirected network. The stationary distribution of this chain is proportional to the **degree sequence** (this is the sequence of degrees, where the degree of a node is how many edges are attached to it). For example, the stationary distribution of random walk on the network shown above is proportional to $(3, 3, 2, 4, 2)$, so it's $(\frac{3}{14}, \frac{3}{14}, \frac{3}{14}, \frac{4}{14}, \frac{2}{14})$.

Continuous Distributions

Uniform Distribution

Let us say that U is distributed $\text{Unif}(a, b)$. We know the following:

Properties of the Uniform For a Uniform distribution, the probability of a draw from any interval within the support is proportional to the length of the interval. See *Universality of Uniform* and *Order Statistics* for other properties.

Example William throws darts really badly, so his darts are uniform over the whole room because they're equally likely to appear anywhere. William's darts have a Uniform distribution on the surface of the room. The Uniform is the only distribution where the probability of hitting in any specific region is proportional to the length/area/volume of that region, and where the density of occurrence in any one specific spot is constant throughout the whole support.

Normal Distribution

Let us say that X is distributed $\mathcal{N}(\mu, \sigma^2)$. We know the following:

Central Limit Theorem The Normal distribution is ubiquitous because of the Central Limit Theorem, which states that the sample mean of i.i.d. r.v.s will approach a Normal distribution as the sample size grows, regardless of the initial distribution.

Location-Scale Transformation Every time we shift a Normal r.v. (by adding a constant) or rescale a Normal (by multiplying by a constant), we change it to another Normal r.v. For any Normal $X \sim \mathcal{N}(\mu, \sigma^2)$, we can transform it to the standard $\mathcal{N}(0, 1)$ by the following transformation:

$$Z = \frac{X - \mu}{\sigma} \sim \mathcal{N}(0, 1)$$

Standard Normal The Standard Normal, $Z \sim \mathcal{N}(0, 1)$, has mean 0 and variance 1. Its CDF is denoted by Φ.

Exponential Distribution

Let us say that X is distributed $\text{Exp}(\lambda)$. We know the following:

Story You're sitting on an open meadow right before the break of dawn, wishing that airplanes in the night sky were shooting stars, because you could really use a wish right now. You know that shooting stars come on average every 15 minutes, but a shooting star is not "due" to come just because you've waited so long. Your waiting time is memoryless; the additional time until the next shooting star comes does not depend on how long you've waited already.

Example The waiting time until the next shooting star is distributed $\text{Exp}(4)$ hours. Here $\lambda = 4$ is the **rate parameter**, since shooting stars arrive at a rate of 1 per 1/4 hour on average. The expected time until the next shooting star is $1/\lambda = 1/4$ hour.

Exp as a rescaled Exp(1)

$$Y \sim \text{Exp}(\lambda) \rightarrow X = \lambda Y \sim \text{Exp}(1)$$

Memorylessness The Exponential Distribution is the only continuous memoryless distribution. The memoryless property says that for $X \sim \text{Exp}(\lambda)$ and any positive numbers s and t,

$$P(X > s + t | X > s) = P(X > t)$$

Equivalently,

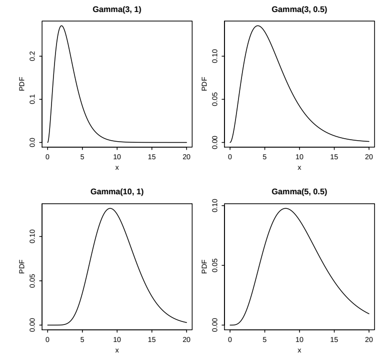
$$X - a | (X > a) \sim \text{Exp}(\lambda)$$

For example, a product with an $\text{Exp}(\lambda)$ lifetime is always "as good as new" (it doesn't experience wear and tear). Given that the product has survived a years, the additional time that it will last is still $\text{Exp}(\lambda)$.

Min of Exp If we have independent $X_i \sim \text{Exp}(\lambda_i)$, then $\min(X_1, \dots, X_k) \sim \text{Exp}(\lambda_1 + \lambda_2 + \dots + \lambda_k)$.

Max of Exp If we have i.i.d. $X_i \sim \text{Exp}(\lambda)$, then $\max(X_1, \dots, X_k)$ has the same distribution as $Y_1 + Y_2 + \dots + Y_k$, where $Y_j \sim \text{Exp}(j\lambda)$ and the Y_j are independent.

Gamma Distribution

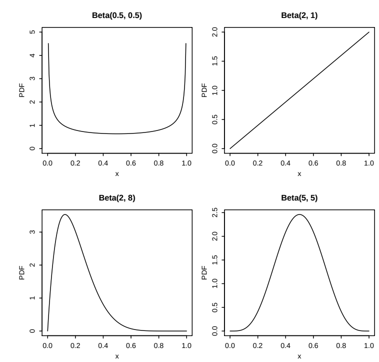


Let us say that X is distributed $\text{Gamma}(a, \lambda)$. We know the following:

Story You sit waiting for shooting stars, where the waiting time for a star is distributed $\text{Exp}(\lambda)$. You want to see n shooting stars before you go home. The total waiting time for the nth shooting star is $\text{Gamma}(n, \lambda)$.

Example You are at a bank, and there are 3 people ahead of you. The serving time for each person is Exponential with mean 2 minutes. Only one person at a time can be served. The distribution of your waiting time until it's your turn to be served is $\text{Gamma}(3, \frac{1}{2})$.

Beta Distribution



Conjugate Prior of the Binomial In the Bayesian approach to statistics, parameters are viewed as random variables, to reflect our uncertainty. The *prior* for a parameter is its distribution before observing data. The *posterior* is the distribution for the parameter after observing data. Beta is the *conjugate* prior of the Binomial because if you have a Beta-distributed prior on p in a Binomial, then the posterior distribution on p given the Binomial data is also Beta-distributed. Consider the following two-level model:

$$X | p \sim \text{Bin}(n, p)$$
$$p \sim \text{Beta}(a, b)$$

Then after observing $X = x$, we get the posterior distribution

$$p | (X = x) \sim \text{Beta}(a + x, b + n - x)$$

Order statistics of the Uniform See *Order Statistics*.

Beta-Gamma relationship If $X \sim \text{Gamma}(a, \lambda)$, $Y \sim \text{Gamma}(b, \lambda)$, with $X \perp\!\!\!\perp Y$ then

- $\frac{X}{X+Y} \sim \text{Beta}(a,b)$
- $X+Y \perp\!\!\!\perp \frac{X}{X+Y}$

This is known as the **bank–post office result**.

χ^2 (Chi-Square) Distribution

Let us say that X is distributed χ^2_n. We know the following:

Story A Chi-Square(n) is the sum of the squares of n independent standard Normal r.v.s.

Properties and Representations

$$X \text{ is distributed as } Z_1^2 + Z_2^2 + \cdots + Z_n^2 \text{ for i.i.d. } Z_i \sim \mathcal{N}(0,1)$$
$$X \sim \text{Gamma}(n/2, 1/2)$$

Discrete Distributions

Distributions for four sampling schemes

	Replace	**No Replace**
Fixed # trials (n)	Binomial (Bern if $n=1$)	HGeom
Draw until r success	NBin (Geom if $r=1$)	NHGeom

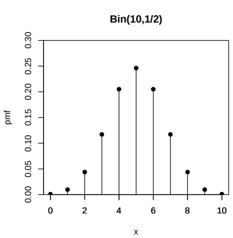
Bernoulli Distribution

The Bernoulli distribution is the simplest case of the Binomial distribution, where we only have one trial ($n=1$). Let us say that X is distributed Bern(p). We know the following:

Story A trial is performed with probability p of "success", and X is the indicator of success: 1 means success, 0 means failure.

Example Let X be the indicator of Heads for a fair coin toss. Then $X \sim \text{Bern}(\frac{1}{2})$. Also, $1-X \sim \text{Bern}(\frac{1}{2})$ is the indicator of Tails.

Binomial Distribution



Let us say that X is distributed Bin(n,p). We know the following:

Story X is the number of "successes" that we will achieve in n independent trials, where each trial is either a success or a failure, each with the same probability p of success. We can also write X as a sum of multiple independent Bern(p) random variables. Let $X \sim \text{Bin}(n,p)$ and $X_j \sim \text{Bern}(p)$, where all of the Bernoullis are independent. Then

$$X = X_1 + X_2 + X_3 + \cdots + X_n$$

Example If Jeremy Lin makes 10 free throws and each one independently has a $\frac{3}{4}$ chance of getting in, then the number of free throws he makes is distributed Bin($10, \frac{3}{4}$).

Properties Let $X \sim \text{Bin}(n,p), Y \sim \text{Bin}(m,p)$ with $X \perp\!\!\!\perp Y$.

- **Redefine success** $n - X \sim \text{Bin}(n, 1-p)$
- **Sum** $X + Y \sim \text{Bin}(n+m, p)$
- **Conditional** $X|(X+Y=r) \sim \text{HGeom}(n,m,r)$
- **Binomial-Poisson Relationship** Bin(n,p) is approximately Po(λ) if p is small.
- **Binomial-Normal Relationship** Bin(n,p) is approximately $\mathcal{N}(np, np(1-p))$ if n is large and p is not near 0 or 1.

Geometric Distribution

Let us say that X is distributed Geom(p). We know the following:

Story X is the number of "failures" that we will achieve before we achieve our first success. Our successes have probability p.

Example If each pokeball we throw has probability $\frac{1}{10}$ to catch Mew, the number of failed pokeballs will be distributed Geom($\frac{1}{10}$).

First Success Distribution

Equivalent to the Geometric distribution, except that it includes the first success in the count. This is 1 more than the number of failures. If $X \sim \text{FS}(p)$ then $E(X) = 1/p$.

Negative Binomial Distribution

Let us say that X is distributed NBin(r,p). We know the following:

Story X is the number of "failures" that we will have before we achieve our rth success. Our successes have probability p.

Example Thundershock has 60% accuracy and can faint a wild Raticate in 3 hits. The number of misses before Pikachu faints Raticate with Thundershock is distributed NBin($3, 0.6$).

Hypergeometric Distribution

Let us say that X is distributed HGeom(w,b,n). We know the following:

Story In a population of w desired objects and b undesired objects, X is the number of "successes" we will have in a draw of n objects, without replacement. The draw of n objects is assumed to be a **simple random sample** (all sets of n objects are equally likely).

Examples Here are some HGeom examples.

- Let's say that we have only b Weedles (failure) and w Pikachus (success) in Viridian Forest. We encounter n Pokemon in the forest, and X is the number of Pikachus in our encounters.
- The number of Aces in a 5 card hand.
- You have w white balls and b black balls, and you draw n balls. You will draw X white balls.
- You have w white balls and b black balls, and you draw n balls without replacement. The number of white balls in your sample is HGeom(w,b,n); the number of black balls is HGeom(b,w,n).
- **Capture-recapture** A forest has N elk, you capture n of them, tag them, and release them. Then you recapture a new sample of size m. How many tagged elk are now in the new sample? HGeom($n, N-n, m$)

Poisson Distribution

Let us say that X is distributed Po(λ). We know the following:

Story There are rare events (low probability events) that occur many different ways (high possibilities of occurences) at an average rate of λ occurrences per unit space or time. The number of events that occur in that unit of space or time is X.

Example A certain busy intersection has an average of 2 accidents per month. Since an accident is a low probability event that can happen many different ways, it is reasonable to model the number of accidents in a month at that intersection as Po(2). Then the number of accidents that happen in two months at that intersection is distributed Po(4).

Properties Let $X \sim \text{Po}(\lambda_1)$ and $Y \sim \text{Po}(\lambda_2)$, with $X \perp\!\!\!\perp Y$.

1. **Sum** $X + Y \sim \text{Po}(\lambda_1 + \lambda_2)$
2. **Conditional** $X|(X+Y=n) \sim \text{Bin}\left(n, \frac{\lambda_1}{\lambda_1+\lambda_2}\right)$
3. **Chicken-egg** If there are $Z \sim \text{Po}(\lambda)$ items and we randomly and independently "accept" each item with probability p, then the number of accepted items $Z_1 \sim \text{Po}(\lambda p)$, and the number of rejected items $Z_2 \sim \text{Po}(\lambda(1-p))$, and $Z_1 \perp\!\!\!\perp Z_2$.

Multivariate Distributions

Multinomial Distribution

Let us say that the vector $\vec{X} = (X_1, X_2, X_3, \dots, X_k) \sim \text{Mult}_k(n, \vec{p})$ where $\vec{p} = (p_1, p_2, \dots, p_k)$.

Story We have n items, which can fall into any one of the k buckets independently with the probabilities $\vec{p} = (p_1, p_2, \dots, p_k)$.

Example Let us assume that every year, 100 students in the Harry Potter Universe are randomly and independently sorted into one of four houses with equal probability. The number of people in each of the houses is distributed $\text{Mult}_4(100, \vec{p})$, where $\vec{p} = (0.25, 0.25, 0.25, 0.25)$. Note that $X_1 + X_2 + \cdots + X_4 = 100$, and they are dependent.

Joint PMF For $n = n_1 + n_2 + \cdots + n_k$,

$$P(\vec{X} = \vec{n}) = \frac{n!}{n_1! n_2! \dots n_k!} p_1^{n_1} p_2^{n_2} \dots p_k^{n_k}$$

Marginal PMF, Lumping, and Conditionals Marginally, $X_i \sim \text{Bin}(n, p_i)$ since we can define "success" to mean category i. If you lump together multiple categories in a Multinomial, then it is still Multinomial. For example, $X_i + X_j \sim \text{Bin}(n, p_i + p_j)$ for $i \neq j$ since we can define "success" to mean being in category i or j. Similarly, if $k = 6$ and we lump categories 1-2 and lump categories 3-5, then

$$(X_1 + X_2, X_3 + X_4 + X_5, X_6) \sim \text{Mult}_3(n, (p_1 + p_2, p_3 + p_4 + p_5, p_6))$$

Conditioning on some X_j also still gives a Multinomial:

$$X_1, \dots, X_{k-1} | X_k = n_k \sim \text{Mult}_{k-1}\left(n - n_k, \left(\frac{p_1}{1-p_k}, \dots, \frac{p_{k-1}}{1-p_k}\right)\right)$$

Variances and Covariances We have $X_i \sim \text{Bin}(n, p_i)$ marginally, so $\text{Var}(X_i) = np_i(1-p_i)$. Also, $\text{Cov}(X_i, X_j) = -np_ip_j$ for $i \neq j$.

Multivariate Uniform Distribution

See the univariate Uniform for stories and examples. For the 2D Uniform on some region, probability is proportional to area. Every point in the support has equal density, of value $\frac{1}{\text{area of region}}$. For the 3D Uniform, probability is proportional to volume.

Multivariate Normal (MVN) Distribution

A vector $\vec{X} = (X_1, X_2, \dots, X_k)$ is Multivariate Normal if every linear combination is Normally distributed, i.e., $t_1X_1 + t_2X_2 + \cdots + t_kX_k$ is Normal for any constants $t_1, t_2, \dots, t_k$. The parameters of the Multivariate Normal are the **mean vector** $\vec{\mu} = (\mu_1, \mu_2, \dots, \mu_k)$ and the **covariance matrix** where the (i,j) entry is $\text{Cov}(X_i, X_j)$.

Properties The Multivariate Normal has the following properties.

- Any subvector is also MVN.
- If any two elements within an MVN are uncorrelated, then they are independent.
- The joint PDF of a Bivariate Normal (X,Y) with $\mathcal{N}(0,1)$ marginal distributions and correlation $\rho \in (-1,1)$ is

$$f_{X,Y}(x,y) = \frac{1}{2\pi\tau} \exp\left(-\frac{1}{2\tau^2}(x^2 + y^2 - 2\rho xy)\right),$$

with $\tau = \sqrt{1-\rho^2}$.

Distribution Properties

Important CDFs

Standard Normal Φ

Exponential(λ) $F(x) = 1 - e^{-\lambda x}$, for $x \in (0, \infty)$

Uniform(0,1) $F(x) = x$, for $x \in (0, 1)$

Convolutions of Random Variables

A convolution of n random variables is simply their sum. For the following results, let X and Y be *independent*.

1. $X \sim \text{Po}(\lambda_1), Y \sim \text{Po}(\lambda_2) \longrightarrow X + Y \sim \text{Po}(\lambda_1 + \lambda_2)$
2. $X \sim \text{Bin}(n_1, p)$, $Y \sim \text{Bin}(n_2, p) \longrightarrow X + Y \sim \text{Bin}(n_1 + n_2, p)$. $\text{Bin}(n, p)$ can be thought of as a sum of i.i.d. $\text{Bern}(p)$ r.v.s.
3. $X \sim \text{Gamma}(a_1, \lambda)$, $Y \sim \text{Gamma}(a_2, \lambda)$ $\longrightarrow X + Y \sim \text{Gamma}(a_1 + a_2, \lambda)$. $\text{Gamma}(n, \lambda)$ with n an integer can be thought of as a sum of i.i.d. $\text{Exp}(\lambda)$ r.v.s.
4. $X \sim \text{NBin}(r_1, p)$, $Y \sim \text{NBin}(r_2, p)$ $\longrightarrow X + Y \sim \text{NBin}(r_1 + r_2, p)$. $\text{NBin}(r, p)$ can be thought of as a sum of i.i.d. $\text{Geom}(p)$ r.v.s.
5. $X \sim \mathcal{N}(\mu_1, \sigma_1^2)$, $Y \sim \mathcal{N}(\mu_2, \sigma_2^2)$ $\longrightarrow X + Y \sim \mathcal{N}(\mu_1 + \mu_2, \sigma_1^2 + \sigma_2^2)$

Special Cases of Distributions

1. $\text{Bin}(1, p) \sim \text{Bern}(p)$
2. $\text{Beta}(1, 1) \sim \text{Unif}(0, 1)$
3. $\text{Gamma}(1, \lambda) \sim \text{Exp}(\lambda)$
4. $\chi_n^2 \sim \text{Gamma}\left(\frac{n}{2}, \frac{1}{2}\right)$
5. $\text{NBin}(1, p) \sim \text{Geom}(p)$

Inequalities

1. **Cauchy-Schwarz** $|E(XY)| \leq \sqrt{E(X^2)E(Y^2)}$
2. **Markov** $P(X \geq a) \leq \frac{E|X|}{a}$ for $a > 0$
3. **Chebyshev** $P(|X - \mu| \geq a) \leq \frac{\sigma^2}{a^2}$ for $E(X) = \mu, \text{Var}(X) = \sigma^2$
4. **Jensen** $E(g(X)) \geq g(E(X))$ for g convex; reverse if g is concave

Formulas

Geometric Series

$$1 + r + r^2 + \cdots + r^{n-1} = \sum_{k=0}^{n-1} r^k = \frac{1 - r^n}{1 - r}$$

$$1 + r + r^2 + \cdots = \frac{1}{1 - r} \text{ if } |r| < 1$$

Exponential Function (e^x)

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \cdots = \lim_{n \to \infty} \left(1 + \frac{x}{n}\right)^n$$

Gamma and Beta Integrals

You can sometimes solve complicated-looking integrals by pattern-matching to a gamma or beta integral:

$$\int_0^{\infty} x^{t-1} e^{-x}\, dx = \Gamma(t) \qquad \int_0^1 x^{a-1}(1 - x)^{b-1}\, dx = \frac{\Gamma(a)\Gamma(b)}{\Gamma(a + b)}$$

Also, $\Gamma(a + 1) = a\Gamma(a)$, and $\Gamma(n) = (n - 1)!$ if n is a positive integer.

Miscellaneous Definitions

Medians and Quantiles Let X have CDF F. Then X has median m if $F(m) \geq 0.5$ and $P(X \geq m) \geq 0.5$. For X continuous, m satisfies $F(m) = 1/2$. In general, the ath quantile of X is $\min\{x : F(x) \geq a\}$; the median is the case $a = 1/2$.

log Statisticians generally use log to refer to natural log (i.e., base e).

i.i.d r.v.s Independent, identically-distributed random variables.

Problem-Solving Strategies

Contributions from Jessy Hwang, Yuan Jiang, Yuqi Hou

1. **Getting started.** Start by *defining relevant events and random variables.* ("Let A be the event that I pick the fair coin"; "Let X be the number of successes.") Clear notion is important for clear thinking! Then decide what it is that you're supposed to be finding, in terms of your notation ("I want to find $P(X = 3|A)$"). Think about what type of object your answer should be (a number? A random variable? A PMF? A PDF?) and what it should be in terms of.

   Try simple and extreme cases. To make an abstract experiment more concrete, try *drawing a picture* or making up numbers that could have happened. Pattern recognition: does the structure of the problem resemble something we've seen before?
2. **Calculating probability of an event.** Use counting principles if the naive definition of probability applies. Is the probability of the complement easier to find? Look for symmetries. Look for something to condition on, then apply Bayes' Rule or the Law of Total Probability.
3. **Finding the distribution of a random variable.** First make sure you need the full distribution not just the mean (see next item). Check the *support* of the random variable: what values can it take on? Use this to rule out distributions that don't fit. Is there a *story* for one of the named distributions that fits the problem at hand? Can you write the random variable as a function of an r.v. with a known distribution, say $Y = g(X)$?
4. **Calculating expectation.** If it has a named distribution, check out the table of distributions. If it's a function of an r.v. with a named distribution, try LOTUS. If it's a count of something, try breaking it up into indicator r.v.s. If you can condition on something natural, consider using Adam's law.
5. **Calculating variance.** Consider independence, named distributions, and LOTUS. If it's a count of something, break it up into a sum of indicator r.v.s. If it's a sum, use properties of covariance. If you can condition on something natural, consider using Eve's Law.
6. **Calculating $E(X^2)$.** Do you already know $E(X)$ or $\text{Var}(X)$? Recall that $\text{Var}(X) = E(X^2) - (E(X))^2$. Otherwise try LOTUS.
7. **Calculating covariance.** Use the properties of covariance. If you're trying to find the covariance between two components of a Multinomial distribution, X_i, X_j, then the covariance is $-np_ip_j$ for $i \neq j$.
8. **Determining independence.** There are several equivalent definitions. Think about simple and extreme cases to see if you can find a counterexample.
9. **Do a painful integral.** If your integral looks painful, see if you can write your integral in terms of a known PDF (like Gamma or Beta), and use the fact that PDFs integrate to 1?
10. **Before moving on.** Check some simple and extreme cases, check whether the answer seems plausible, check for cautionary notes below.

Cautionary notes

Contributions from Jessy Hwang

1. **Don't misuse the naive definition of probability.** When answering "What is the probability that in a group of 3 people, no two have the same birth month?", it is *not* correct to treat the people as indistinguishable balls being placed into 12 boxes, since that assumes the list of birth months {January, January, January} is just as likely as the list {January, April, June}, even though the latter is six times more likely.
2. **Don't confuse unconditional, conditional, and joint probabilities.** In applying $P(A|B) = \frac{P(B|A)P(A)}{P(B)}$, it is *not* correct to say "$P(B) = 1$ because we know B happened"; $P(B)$ is the *prior* probability of B. Don't confuse $P(A|B)$ with $P(A, B)$.
3. **Don't assume independence without justification.** In the matching problem, the probability that card 1 is a match and card 2 is a match is not $1/n^2$. Binomial and Hypergeometric are often confused; the trials are independent in the Binomial story and dependent in the Hypergeometric story.
4. **Don't confuse random variables, numbers, and events.** Let X be an r.v. Then $g(X)$ is an r.v. for any function g. In particular, X^2, $|X|$, $F(X)$, and $I_{X>3}$ are r.v.s. $P(X^2 < X|X \geq 0)$, $E(X)$, $\text{Var}(X)$, and $g(E(X))$ are numbers. $X = 2$ and $F(X) \geq -1$ are events. It does not make sense to write $\int_{-\infty}^{\infty} F(X)dx$, because $F(X)$ is a random variable. It does not make sense to write $P(X)$, because X is not an event.
5. **Don't confuse a random variable with its distribution.** To get the PDF of X^2, you can't just square the PDF of X. The right way is to use transformations. To get the PDF of $X + Y$, you can't just add the PDF of X and the PDF of Y. The right way is to compute the convolution.
6. **Don't pull non-linear functions out of expectations.** $E(g(X))$ does not equal $g(E(X))$ in general. The St. Petersburg paradox is an extreme example. See also Jensen's inequality. The right way to find $E(g(X))$ is with LOTUS.

Distributions in R

Command	What it does
`help(distributions)`	shows documentation on distributions
`dbinom(k,n,p)`	PMF $P(X = k)$ for $X \sim \text{Bin}(n, p)$
`pbinom(x,n,p)`	CDF $P(X \leq x)$ for $X \sim \text{Bin}(n, p)$
`qbinom(a,n,p)`	ath quantile for $X \sim \text{Bin}(n, p)$
`rbinom(r,n,p)`	vector of r i.i.d. $\text{Bin}(n, p)$ r.v.s
`dgeom(k,p)`	PMF $P(X = k)$ for $X \sim \text{Geom}(p)$
`dhyper(k,w,b,n)`	PMF $P(X = k)$ for $X \sim \text{HGeom}(w, b, n)$
`dnbinom(k,r,p)`	PMF $P(X = k)$ for $X \sim \text{NBin}(r, p)$ PMF P
`dpois(k,r)`	$(X = k)$ for $X \sim \text{Po}(r)$
`dbeta(x,a,b)`	PDF $f(x)$ for $X \sim \text{Beta}(a, b)$
`dchisq(x,n)`	PDF $f(x)$ for $X \sim \chi^2_n$
`dexp(x,b)`	PDF $f(x)$ for $X \sim \text{Exp}(b)$
`dgamma(x,a,r)`	PDF $f(x)$ for $X \sim \text{Gamma}(a, r)$
`dlnorm(x,m,s)`	PDF $f(x)$ for $X \sim \mathcal{LN}(m, s^2)$
`dnorm(x,m,s)`	PDF $f(x)$ for $X \sim \mathcal{N}(m, s^2)$ PDF
`dt(x,n)`	$f(x)$ for $X \sim t_n$
`dunif(x,a,b)`	PDF $f(x)$ for $X \sim \text{Unif}(a, b)$

The table above gives R commands for working with various named distributions. Commands analogous to `pbinom`, `qbinom`, and `rbinom` work for the other distributions in the table. For example, `pnorm`, `qnorm`, and `rnorm` can be used to get the CDF, quantiles, and random generation for the Normal.

Table of Distributions

Distribution	PMF/PDF and Support	Expected Value	Variance	MGF
Bernoulli Bern(p)	$P(X=1)=p$ $P(X=0)=q=1-p$	p	pq	$q+pe^t$
Binomial Bin(n,p)	$P(X=k)=\binom{n}{k}p^k q^{n-k}$ $k \in \{0,1,2,\dots n\}$	np	npq	$(q+pe^t)^n$
Geometric Geom(p)	$P(X=k)=q^k p$ $k \in \{0,\,1,\,2,\,\dots\}$	q/p	q/p^2	$\frac{p}{1-qe^t},\, qe^t<1$
Negative Binomial NB(r,p)	$P(X=n)=\binom{r+n-1}{r-1}p^r q^n$ $n \in \{0,\,1,\,2,\,\dots\}$	rq/p	rq/p^2	$(\frac{p}{1-qe^t})^r,\, qe^t<1$
Hypergeometric HGeom(w,b,n)	$P(X=k)=\binom{w}{k}\binom{b}{n-k}/\binom{w+b}{n}$ $k \in \{0,1,2,\dots,n\}$	$\mu=\frac{nw}{b+w}$	$\left(\frac{w+b-n}{w+b-1}\right)n\frac{\mu}{n}(1-\frac{\mu}{n})$	messy
Poisson Po(λ)	$P(X=k)=\frac{e^{-\lambda}\lambda^k}{k!}$ $k \in \{0,\,1,\,2,\,\dots\}$	λ	λ	$e^{\lambda(e^t-1)}$
Uniform Unif(a,b)	$f(x)=\frac{1}{b-a}$ $x \in (a,b)$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$	$\frac{e^{tb}-e^{ta}}{t(b-a)}$
Normal $\mathcal{N}(\mu,\sigma^2)$	$f(x)=\frac{1}{\sigma\sqrt{2\pi}}e^{-(x\,-\,\mu)^2/(2\sigma^2)}$ $x \in (-\infty,\infty)$	μ	σ^2	$e^{t\mu+\frac{\sigma^2 t^2}{2}}$
Exponential Exp(λ)	$f(x)=\lambda e^{-\lambda x}$ $x \in (0,\infty)$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$	$\frac{\lambda}{\lambda-t},\, t<\lambda$
Gamma Gamma(a,λ)	$f(x)=\frac{1}{\Gamma(a)}(\lambda x)^a e^{-\lambda x}\frac{1}{x}$ $x \in (0,\infty)$	$\frac{a}{\lambda}$	$\frac{a}{\lambda^2}$	$\left(\frac{\lambda}{\lambda-t}\right)^a,\, t<\lambda$
Beta Beta(a,b)	$f(x)=\frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)}x^{a-1}(1-x)^{b-1}$ $x \in (0,1)$	$\mu=\frac{a}{a+b}$	$\frac{\mu(1-\mu)}{(a+b+1)}$	messy
Log-Normal $\mathcal{LN}(\mu,\sigma^2)$	$\frac{1}{x\sigma\sqrt{2\pi}}e^{-(\log x-\mu)^2/(2\sigma^2)}$ $x \in (0,\infty)$	$\theta=e^{\mu+\sigma^2/2}$	$\theta^2(e^{\sigma^2}-1)$	doesn't exist
Chi-Square χ^2_n	$\frac{1}{2^{n/2}\Gamma(n/2)}x^{n/2-1}e^{-x/2}$ $x \in (0,\infty)$	n	$2n$	$(1-2t)^{-n/2},\, t<1/2$
Student-t t_n	$\frac{\Gamma((n+1)/2)}{\sqrt{n\pi}\Gamma(n/2)}(1+x^2/n)^{-(n+1)/2}$ $x \in (-\infty,\infty)$	0 if $n>1$	$\frac{n}{n-2}$ if $n>2$	doesn't exist