



Maratona **Cln**

**Seletiva 2020**

# Dijkstra, Floyd-Warshall, DSU, MST

Aula 4

# Dijkstra

# Dijkstra

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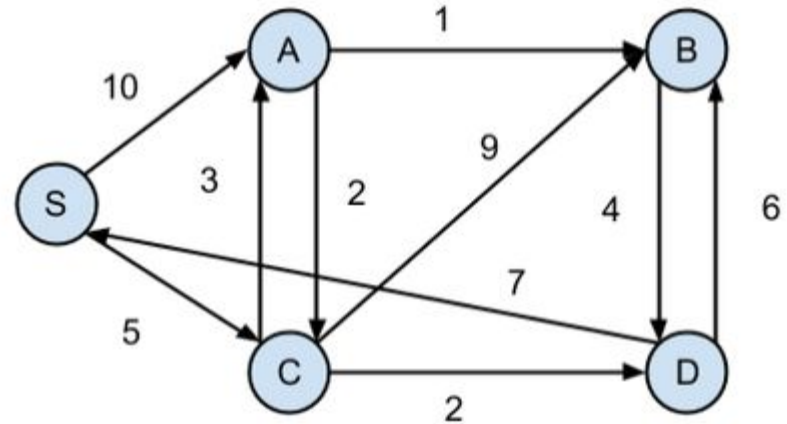


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- Calcula a distância de  $S$  aos demais vértices
- Arestas com pesos
  - Arestas de peso não negativo
- Busca gulosa
- Complexidade:  $O((E+V) \log V)$
- Estruturas usadas:
  - Array com menores distâncias até agora
  - Min Heap com os próximos valores a analisar

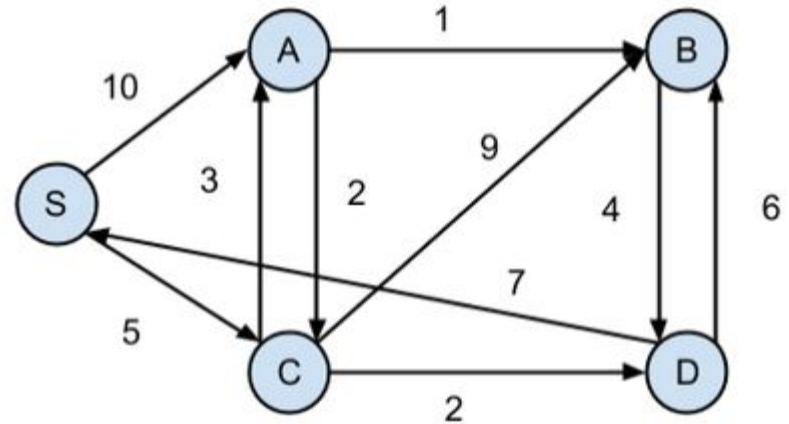
# Dijkstra

Node	$d[v]$	$\Pi[v]$
S	0	NIL
A	$\infty$	NIL
B	$\infty$	NIL
C	$\infty$	NIL
D	$\infty$	NIL



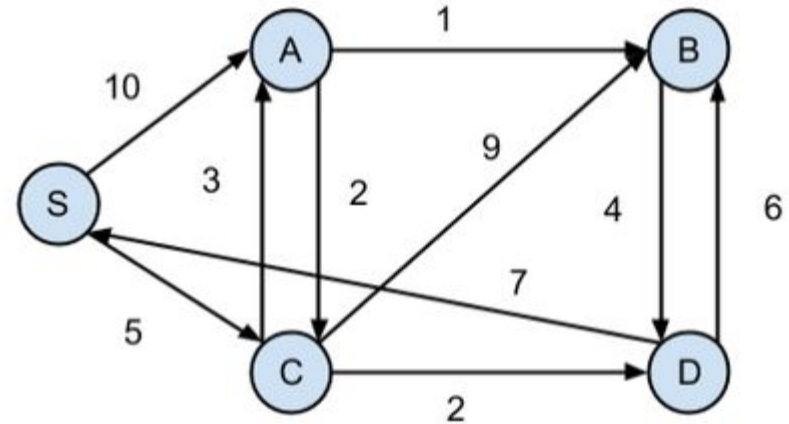
# Dijkstra

Node	$d[v]$	$\Pi[v]$
S	0	NIL
A	10	S
B	$\infty$	NIL
C	5	S
D	$\infty$	NIL



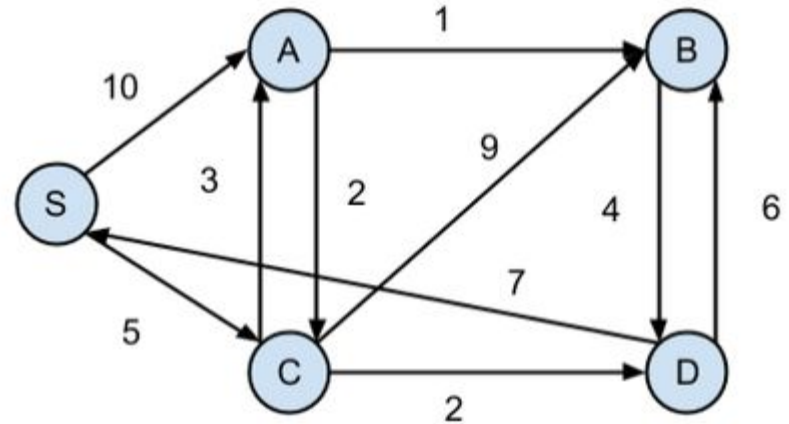
# Dijkstra

Node	$d[v]$	$\Pi[v]$
S	0	NIL
A	8	C
B	14	C
C	5	S
D	7	C



# Dijkstra

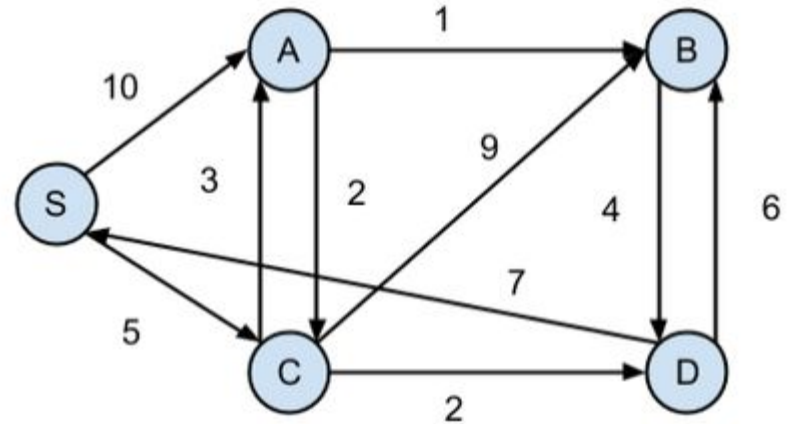
Node	$d[v]$	$\Pi[v]$
S	0	NIL
A	8	C
B	13	D
C	5	S
D	7	C





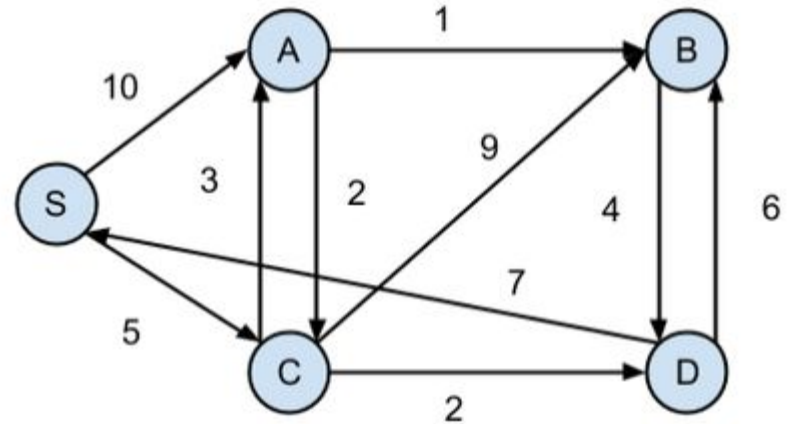
# Dijkstra

Node	$d[v]$	$\Pi[v]$
S	0	NIL
A	8	C
B	9	A
C	5	S
D	7	C



# Dijkstra

Node	$d[v]$	$\Pi[v]$
S	0	NIL
A	8	C
B	9	A
C	5	S
D	7	C



# Dijkstra



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Código:

```
typedef pair<int, int> ii; const int inf = 0x3f3f3f3f;
#define inf 0x3f3f3f3f
const int N = 1e5+5;
int dist[N]; vector<ii> adjList[N];

void dijkstra(int source){
    for(int i = 0; i < n; i++) dist[i] = inf;
    dist[source] = 0;
    priority_queue<ii, vector<ii>, greater<ii>> pq;
    pq.emplace(0, source);

    while (!pq.empty()){
        int d = pq.top().first, u = pq.top().second;
        pq.pop();
        if (d > dist[u]) continue;

        for(auto e : adjList[u]){
            int v = e.first, w = e.second;
            if (dist[u] + w < dist[v]) {
                dist[v] = dist[u] + w;
                pq.emplace(dist[v], v);
            }
        }
    }
}
```

# Floyd Warshall

# Floyd Warshall

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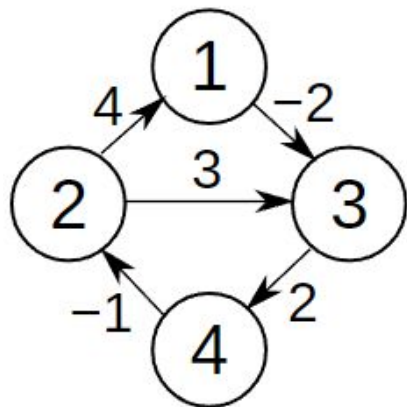
- Calcula o caminho mais curto entre todos os pares de vértices
- Programação dinâmica
- Recalcula as distâncias a partir de vértices intermediários
- Complexidade:  $O(V^3)$

# Floyd Warshall

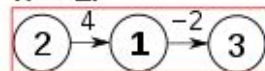


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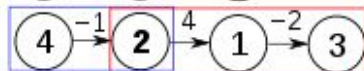
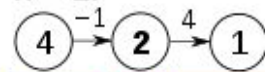
Exemplo:



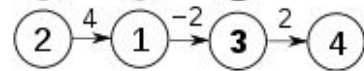
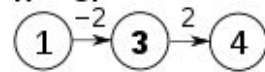
$k = 1$ :



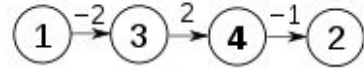
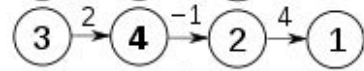
$k = 2$ :



$k = 3$ :



$k = 4$ :



$k=0$		$j$				
		1	2	3	4	
$i$	1	0	$\infty$	-2	$\infty$	
	2	4	0	3	$\infty$	
	3	$\infty$	$\infty$	0	2	
	4	$\infty$	-1	$\infty$	0	

$k=1$		$j$				
		1	2	3	4	
$i$	1	0	$\infty$	-2	$\infty$	
	2	4	0	2	$\infty$	
	3	$\infty$	$\infty$	0	2	
	4	$\infty$	-1	$\infty$	0	

$k=2$		$j$				
		1	2	3	4	
$i$	1	0	$\infty$	-2	$\infty$	
	2	4	0	2	$\infty$	
	3	$\infty$	$\infty$	0	2	
	4	3	-1	1	0	

$k=3$		$j$				
		1	2	3	4	
$i$	1	0	$\infty$	-2	0	
	2	4	0	2	4	
	3	$\infty$	$\infty$	0	2	
	4	3	-1	1	0	

$k=4$		$j$				
		1	2	3	4	
$i$	1	0	-1	-2	0	
	2	4	0	2	4	
	3	5	1	0	2	
	4	3	-1	1	0	

# Floyd Warshall



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Código:

```
const int inf = 0x3f3f3f3f;
int dist[N][N];

void floyd(){
    for(int i = 0; i < n; i++) for(int j = 0; j < n; j++) {
        if(i == j) dist[i][j] = 0;
        else dist[i][j] = inf;
    }
    for(int i = 0; i < m; i++) {
        int u, v, w; cin >> u >> v >> w;
        dist[u][v] = min(dist[u][v], w);
    }
    for(int k = 0; k < n; k++) {
        for(int i = 0; i < n; i++) {
            for(int j = 0; j < n; j++) {
                dist[i][j] = min(dist[i][j], dist[i][k] + dist[k][j]);
            }
        }
    }
}
```

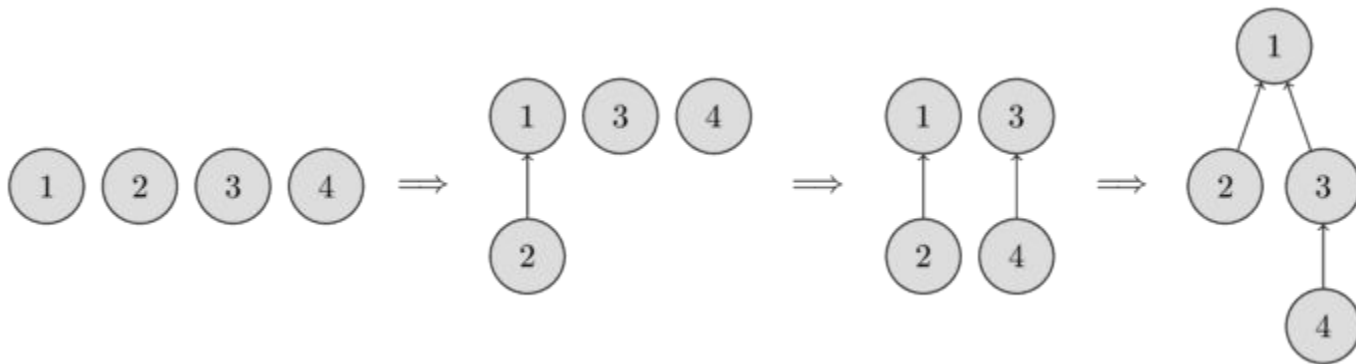
# Disjoint Set Union(Union Find)



# Disjoint-set Union

Estrutura de dados capaz de rapidamente informar em qual conjunto determinado elemento está, se dois elementos estão em um mesmo conjunto e para unir dois conjuntos.

Visualização: <https://s3.amazonaws.com/learneroo/visual-algorithms/DisjointSets.html>



# Código



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```
void dsBuild() {
    for(int i = 0; i < n; i++) {
        ds[i] = i;
        sz[i] = 1;
    }
}

int dsFind(int i) {
    if(ds[i] != i) ds[i] = dsFind(ds[i]);
    return ds[i];
}

void dsUnion(int a, int b) {
    a = dsFind(a); b = dsFind(b);
    if(sz[a] < sz[b]) swap(a, b);
    if(a != b) sz[a] += sz[b];
    ds[b] = a;
}
```

# MST(Minimum spanning tree)

# Minimum spanning tree

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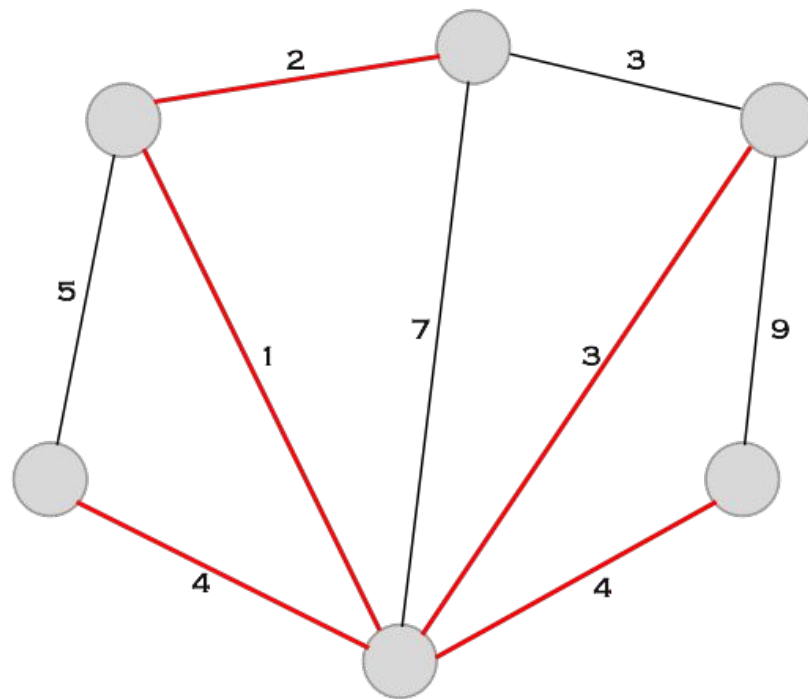
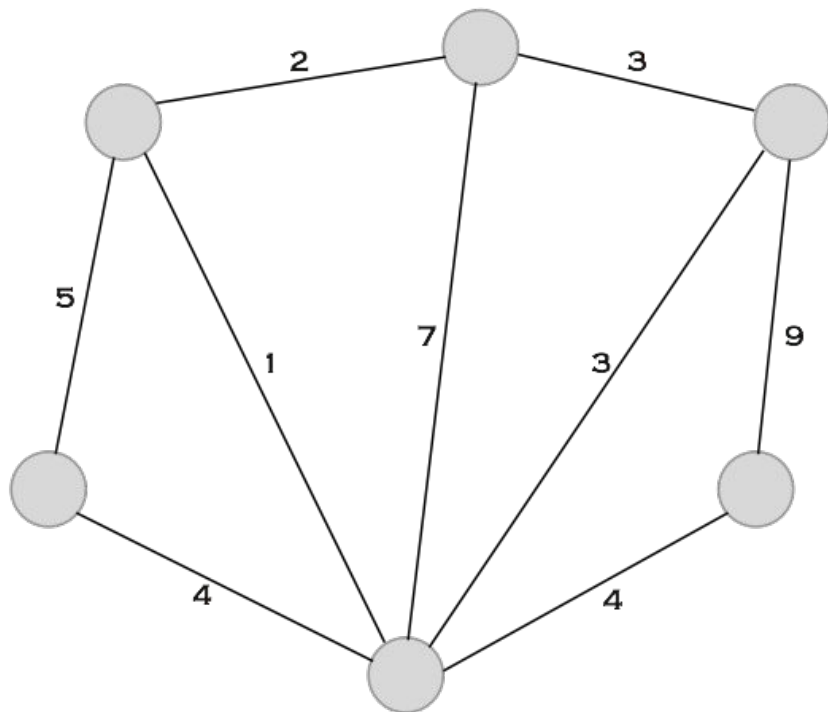


Uma MST é um conjunto de arestas de um grafo conectado, que conecta todos os vértices, sem formar ciclos e que a soma do peso dessas arestas seja o menor possível.

# Exemplo



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# Kruskal

# Kruskal



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Algoritmo:

- 1 - Ordene as arestas de acordo com o peso.
- 2 - Se os vértices da aresta estiverem na mesma componente, ignore e continue o algoritmo.
- 3 - Senão, inserir a aresta na MST

# Kruskal



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Código:

```
struct Edge{
    int u, v, cost;
    bool operator < (Edge b) {
        return cost < b.cost;
    }
};

void Kruskal() {
    vector<Edge> edge(m);
    for (int i = 0; i < m; i++) {
        cin >> edge[i].u >> edge[i].v >> edge[i].cost;
    }
    sort(edge.begin(), edge.end());
    long long total = 0;
    for (int i = 0; i < m; i++) {
        if (find(edge[i].u) != find(edge[i].v)) {
            merge(edge[i].u, edge[i].v);
            mst.push_back(edge[i]);
            total += edge[i].cost;
        }
    }
}
```

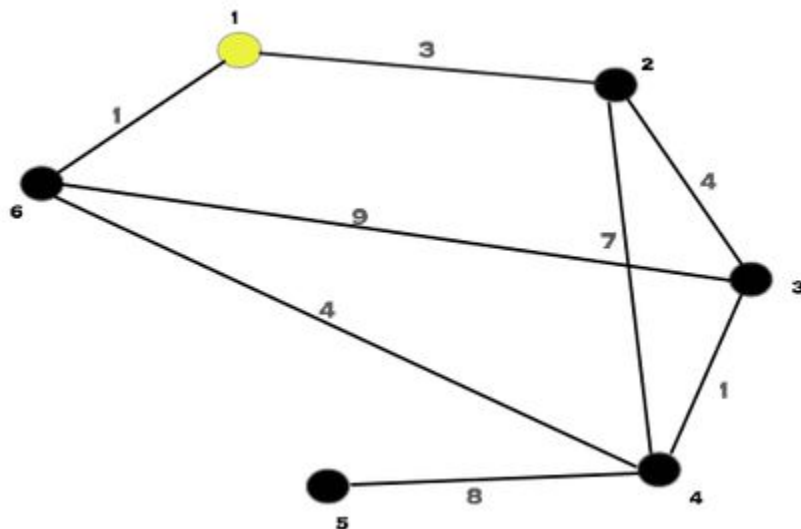


# Prim

# Prim



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Nó Distância

1 0

2 3

3  $\infty$

4  $\infty$

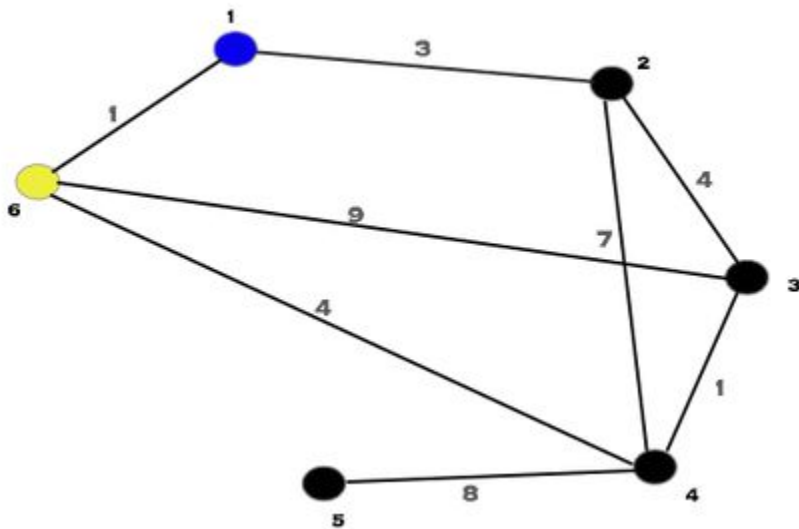
5  $\infty$

6 1

# Prim



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Nó Distância

1 0

2 3

3 9

4 4

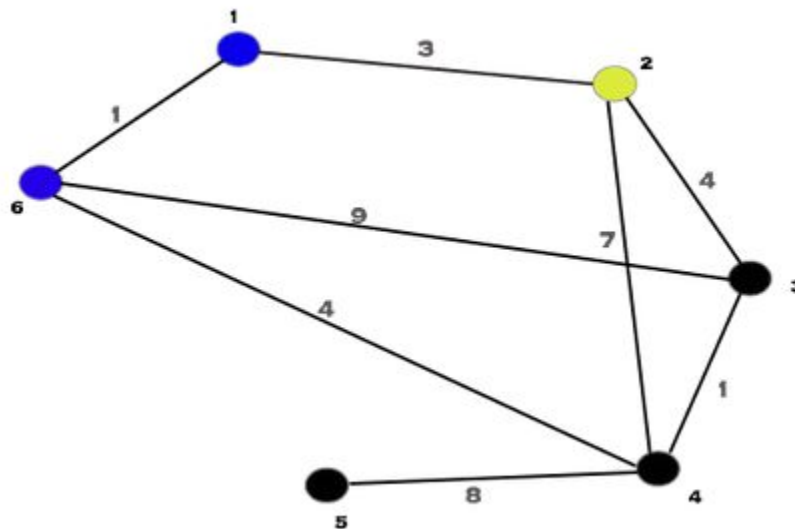
5  $\infty$

6 1

# Prim



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Nó Distância

1 0

2 3

3 4

4 4

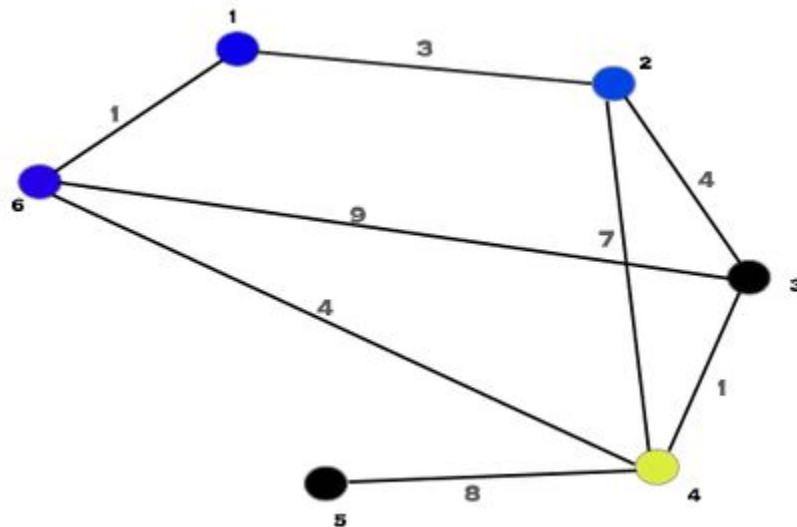
5  $\infty$

6 1

# Prim



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NóDistância

1 0

2 3

3 1

4 4

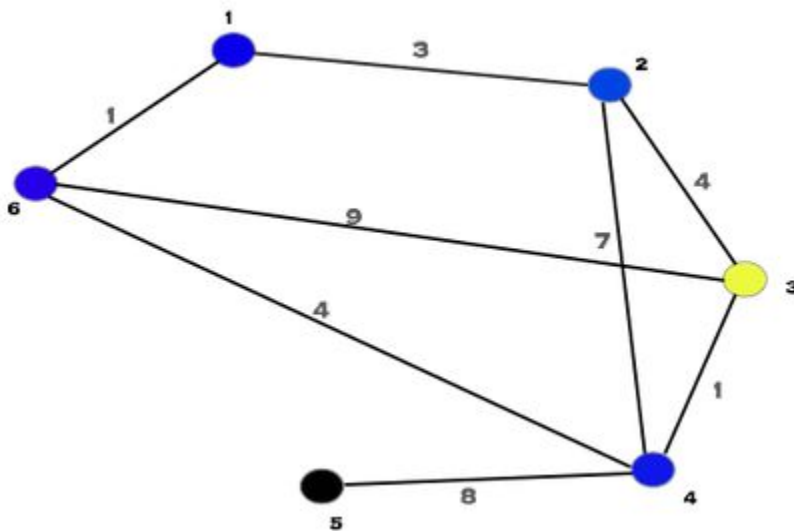
5 8

6 1

# Prim



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NóDistância

1 0

2 3

3 1

4 4

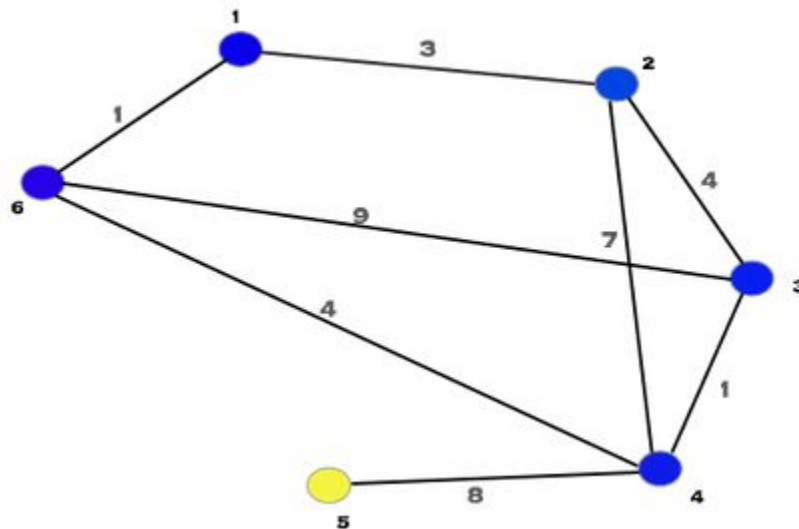
5 8

6 1

# Prim



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Nó Distância

1 0

2 3

3 1

4 4

5 8

6 1

# Prim



Maratona**CIn**

Código:

```
long long Prim(int source = 0){
    for(int i = 0; i < n; i++) dist[i] = inf;
    dist[source] = 0;
    priority_queue<ii, vector<ii>, greater<ii>> pq;
    pq.emplace(0, source);
    while (!pq.empty()){
        int d = pq.top().first, u = pq.top().second;
        pq.pop();
        if (inMST[u]) continue;
        inMST[u] = true;

        for(auto e : adjList[u]){
            int v = e.first, w = e.second;
            if (!inMST[v] && w < dist[v]) {
                // parent[v] = u;
                dist[v] = w;
                pq.emplace(dist[v], v);
            }
        }
    }
}
```