SYMMETRIES, FIELDS, AND PARTICLES

IAN LIM MICHAELMAS 2018

These notes were taken for the *Symmetries, Fields, and Particles* course taught by Nick Dorey at the University of Cambridge as part of the Mathematical Tripos Part III in Michaelmas Term 2018. I live-TEXed them using Overleaf, and as such there may be typos; please send questions, comments, complaints, and corrections to itel2@cam.ac.uk. Many thanks to Arun Debray for the LATEX template for these lecture notes: as of the time of writing, you can find him at https://web.ma.utexas.edu/users/a.debray/.

Contents

1. Thursday, October 4, 2018

1

Lecture 1.

Thursday, October 4, 2018

Today we'll outline the content of this course and motivate it with a few examples. To begin with, symmetry as a principle has led physicists all the way to our current model of physics. This course's content will be almost exclusively mathematical, yet more pragmatic about introducing the necessary tools to apply symmetries to the physical systems we're interested in.

Resources

- Notes (online)
 - Nick Manton's notes (concise, more on geometry of Lie groups)
 - Osborn (comprehensive, don't cover Cartan classification)
 - Gutowski (classification of Lie algebras)
- o Books: "Symmetries, Lie Algebras and Representations", Fuchs & Schweigert Ch. 1-7.

Introduction

Definition 1.1. We define a *symmetry* as a transformation of dynamical variables that leaves the form of physical laws invariant.

Example 1.2. A rotation is a transformation, e.g. on $\mathbf{x} \in \mathbb{R}^3$ such that $\mathbf{x}' = M \cdot \mathbf{x} \in \mathbb{R}^3$. There are *orthogonal* matrices which satisfy $MM^T = 1_3$ and also *special* matrices which satisfy det M = 1.

It's also useful for us to define the notion of a group (likely familiar from an intro course on abstract algebra or mathematical methods).

Definition 1.3. A group G is a set equipped with a multiplication law (binary operation) obeying

- Closure $(\forall g_1, g_2 \in G, g_1g_2 \in G)$
- ∘ Identity ($\exists e \in G$ s.t. $\forall g \in G, eg = ge = g$)
- Existence of inverses $(\forall g \in G, \exists g^{-1} \in G \text{ s.t. } g^{-1}g = gg^{-1} = e)$
- ∘ Associativity $(\forall g_1, g_2, g_3 \in G, (g_1g_2)g_3) = g_1(g_2g_3)$.

Exercise 1.4. For rotations G = SO(3), the group of 3-dimensional special orthogonal matrices, check that the group axioms apply (SO(3) forms a group).

1

We also remark that the set may be finite or infinite¹. A group G is called *abelian* if the multiplication law is commutative ($\forall g_1, g_2 \in G, g_1g_2 = g_2g_1$). Otherwise, it is called non-abelian.

We notice that a rotation in \mathbb{R}^3 depends continuously on 3 parameters: $\hat{n} \in S^2$, $\theta \in [0, \pi]$ (with \hat{n} the axis of rotation, θ the angle of rotation). This leads us to introduce the idea of a Lie group.

Definition 1.5. A *Lie group G* is a group which is also a smooth manifold. It's key that the group and manifold structures must be compatible, and so G is (almost) completely determined by the behavior "near" e, i.e. by infinitesimal transformations in a small neighborhood of the identity element e. These correspond to the *tangent vectors* to G at e.

The tangent vectors are local objects which span the tangent space to the manifold at some given point. It turns out that $\forall v_1, v_2 \in T_e(G)$ the tangent space of G, we can define a binary operation $[,]: T_e(G) \times T_e(G) \to T_e(G)$ such that [,] is bilinear, antisymmetric, and obeys the Jacobi identity.

Definition 1.6. The tangent space at the identity equipped with the Lie bracket defines a *Lie algebra* $\mathcal{L}(G)$.

It's a remarkable fact that *all* finite-dimensional semi-simple Lie algebras (over \mathbb{C}) can be classified into four infinite families A_n , B_n , C_n , D_n with $n \in \mathbb{N}$, plus five *exceptional cases* E_6 , E_7 , E_8 , G_2 , F_4 .² We call this the *Cartan classification*.

Symmetries in physics In classical physics, (continuous) symmetries give rise to conserved quantities. This is the conclusion of Noether's theorem.

Example 1.7. Rotations in \mathbb{R}^3 correspond to conservation of angular momentum, $\mathbf{L} = (L_1, L_2, L_3)$.

In quantum mechanics, we have

- \circ states: vectors in Hilbert space $|\psi\rangle \in \mathcal{H}$
- o observables: linear operators $\hat{O}: \mathcal{H} \to \mathcal{H}$ with (generally) non-commutative multiplication.

We recall from previous courses in QM that operators which commute with the Hamiltonian (e.g. $[\hat{H}, \hat{L}_i] = 0, i = 1, 2, 3$) give rise to "quantum conserved quantities."

In fact, we recall that the angular momentum operators are associated to a Lie bracket: $[\hat{L}_i, \hat{L}_j] = i\epsilon_{ijk}\hat{L}_k$. But this is exactly the $\mathcal{L}(SO(3))$ Lie algebra.

Our angular momentum operators often act on finite-dimensional vector spaces, e.g. electron spin.

$$|\!\!\uparrow\rangle \equiv \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$
 , $|\!\!\downarrow\rangle \equiv \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

This corresponds to a two-dimensional *representation* of $\mathcal{L}(SO(3))$, i.e. a set of 2 × 2 matrices Σ_i , i = 1, 2, 3 satisfying the same Lie algebra,

$$[\Sigma_i, \Sigma_I] = i\varepsilon_{ijk}\Sigma_k,$$

which is provided by setting $\Sigma_i = \frac{1}{2}\sigma_i$, our old friends the Pauli matrices.

More generally, we should think of a representation as a map e from a Lie group to some space of transformations on a vector space which preserves the Lie bracket, $e([v_1, v_2]) = [e(v_1), e(v_2)]$.

Now suppose we have a rotational symmetry in a quantum system,

$$[\hat{H}, \hat{L}_i] = 0, i = 1, 2, 3.$$

Then the spin states obey $\hat{H} |\uparrow\rangle = E |\uparrow\rangle$, $\hat{H} |\downarrow\rangle = E' |\downarrow\rangle$, with E = E'. More generally, degeneracies in the energy spectrum of quantum systems correspond to irreducible representations of symmetries.

Example 1.8. We have an approximate SU(3) symmetry for the strong force, with

$$G = SU(3) \equiv \{3 \times 3 \text{ complex matrices } M \text{ with } MM^{\dagger} = I_3 \text{ and } \det M = 1.\}$$

The spectrum of mesons and baryons are thus defined by the representation of the Lie algebra $\mathcal{L}(SU(3))$. See also the "eightfold way," due to Murray Gell-Mann, who showed that plotting the various mesons and baryons with respect to certain quantum numbers (isospin and hypercharge) gives rise to a very nice picture corresponding to the 8-dimensional representation of the Lie algebra $\mathcal{L}(SU(3))$.

¹For example, cyclic groups \mathbb{Z}_n (i.e. addition in modular arithmetic) vs. most matrix groups like GL_n .

²The exceptional groups have not yet come up in physical phenomena, but they seem to have a mysterious connection to the absence of anomalies in string theory.