Comparing the speed of two methods of approximating the value of π — a computational					
approach					
To what extent can a method of approximation of the value π be computationally more					
To what extent can a method of approximation of the value π be computationally more efficient than another?					
Word count:					

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1 Introduction

The value of π has been researched for many years, although under different names, and the amount of different approaches to reach the value is large. The value has been found through many processes, be it analytically, the most popular, geometrically, or through more obscure or convoluted methods, such as the possibility to approximate the value using physics akin to those from a simple game of billiards. [1]

This paper seeks to examine the extent at which two historical methods of approximation of the value π , namely the approaches suggested by the aforementioned mathematicians Madhava and Viète, differ in terms of computational speed and speed, and explain these differences. This paper does not however, suggest a method to use for computation but rather seeks to only compare the speed of a geometrically derived formula and a analytically derived one.

This research could prove useful in the field of computer science, as there is always a demand for faster and more efficient programs in an ever-changing society. Furthermore, a research based on computational speed of two different kinds approaches to the constant π has not been done to date.

2 Background

2.1 Focus on two methods

In this paper, we focus on two methods for approximating the value of π . The first by French mathematician François Viète, and another discovered by Madhava of Sangamagrama. Two methods with different approaches have been chosen for comparison and the process for original discovery of these methods will be explained. The two in question are one based on the infinite series definition of an inverse trigonometric function discovered by Madhava and one where the value is derived using geometry, by mathematician Viète. These two mathematical methods were chosen as they are both represent a first occurrence in mathematics: Madhava was the first to find the infinite series expansion of the inverse tangent function and Viète was the first mathematician to use an infinite product in calculation.

2.1.1 An analytical method: Madhava's method

Madhava is the first mathematician known to have found the series notation for the inverse tangent function, in the Kerala school of mathematics of Medieval India [2]. The research made at the Kerala school was documented by many mathematicians of their time, namely the astronomer-mathematician Jyesthadeva in his treatise Yukti-Bhasa written in the Malayalam language [3]. Madhava's infinite series expansion of the inverse tangent function can also be found in this treatise. R. C. Gupta, in his translation, describes this expansion as one where the arc θ is equal to the sum of a first term, "the product of the given sine and radius of the desired arc divided by the cosine of the arc" followed by terms that "are obtained by a process of iteration": in which the original term is multiplied by the square of the sine and divided by the square of the cosine. Thereafter, each term is divided by an odd number in order $(1, 3, 5, 7, \ldots)$. It is then said that the arc can be found by "adding and subtracting respectively the terms of odd rank and those of even

rank", definition of an alternating series. [4]

This text explains what can be written in modern mathematical terms as such:

$$r\theta = \frac{r(r\sin\theta)}{1(r\cos\theta)} - \frac{r(r\sin\theta)^3}{3(r\cos\theta)^3} + \frac{r(r\sin\theta)^5}{5(r\cos\theta)^5} - \frac{r(r\sin\theta)^7}{7(r\cos\theta)^7} + \dots$$

And for a circle of radius r = 1, we can cancel all r terms:

$$\theta = \frac{\sin \theta}{\cos \theta} - \frac{\sin^3 \theta}{3\cos^3 \theta} + \frac{\sin^5 \theta}{5\cos^5 \theta} - \frac{\sin^7 \theta}{7\cos^7 \theta} + \dots$$

And because $\frac{\sin \theta}{\cos \theta} = \tan \theta$, the aforementioned expression can be simplified to:

$$\theta = \tan \theta - \frac{\tan^3 \theta}{3} + \frac{\tan^5 \theta}{5} - \frac{\tan^7 \theta}{7} + \dots$$

So then, if we let $\tan \theta = \alpha$, we can find the infinite series expansion of the arctangent function.

$$\arctan \alpha = \alpha - \frac{\alpha^3}{3} + \frac{\alpha^5}{5} - \frac{\alpha^7}{7} + \ldots = \theta$$

Yukti-Bhasa also describes two methods for the calculation of π . Firstly, Madhava's infinite series expansion for π is described, which he obtained through the previous expansion for the arctangent function. And since $\arctan 1 = \frac{\pi}{4}$, it can be said that:

$$\frac{\pi}{4} = \arctan 1 = 1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + \dots + \frac{(-1)^n}{2n+1}$$

Which in form of an infinite sum can be expressed as:

$$\frac{\pi}{4} = \sum_{n=0}^{\infty} \frac{(-1)^n}{2n+1}$$

Which has come to be known as the Leibniz formula for π , after the German mathematician who discovered the same formula two decades later. [5] This series converges to π , as seen in (Figure 1) 2.1.2

However, the method with a faster convergence can be found in a further commentary describing the findings of Madhava that states a method for the calculation of the circumference c of a circle of diameter d exists. The passage in question from the commentary Tantrasamgraha-vyakhya of anonymous authorship states that, by following the same argument as stated before, one can find the circumference of a circle through a similar infinite sum. The first term of this sum would be "the square root of the square of

¹Note: the old Indian meaning for the sine of θ is $r \sin \theta$, where r is the radius. The same applies for the cosine.

the diameter multiplied by twelve", followed by the first term "divided by three in each successive case", and when these "are divided in order by the odd numbers, beginning with 1", and after the even terms are subtracted from sum of the odd", one is left with the circumference of the circle (translation from C. K. Raju). [6]

This can be expressed in mathematical terms as such, where we let c be the circumference of a circle of diameter d:

$$c = \sqrt{12d^2} - \frac{\sqrt{12d^2}}{3 \cdot 3} + \frac{\sqrt{12d^2}}{3^2 \cdot 5} - \frac{\sqrt{12d^2}}{3^3 \cdot 7} + \dots$$

And since $c = \pi d$, for a circle of diameter 1, $c = \pi$, all d terms cancel and the expression can be factorized as:

$$c = \pi = \sqrt{12}(1 - \frac{1}{3 \cdot 3} + \frac{1}{3^2 \cdot 5} - \frac{1}{3^3 \cdot 7} + \ldots)$$

Or as an infinite sum:

$$\pi = \sqrt{12} \sum_{n=0}^{\infty} \frac{(-3)^{-n}}{2n+1}$$

2.1.2 A geometric method: Viète's method

François Viète approached the value of π from a geometric standpoint, and found an infinite product. He was able to calculate π to a place of 9 decimal points, in the year 1593 [7], using his method. His method is reminiscent of Archimedes' method, where the length of a side is calculated [8], but differs in that it consists of finding the area of a polygon of n sides in a circle of constant radius, rather than the circumference. As the value of n is increased, the area of the n-gon tends toward the area of a circle. The geometric origin of this formula can be found using simple right-angle trigonometry, by first finding the lengths OH and subsequently BD in (Figure 2) 2.1.2. With the radius of the circle with center R = OB,

$$OH = R\cos\alpha$$

and

$$BD = 2BH = 2R\sin\alpha$$

Since the equation for the area of a polygon is defined as $A = \frac{p \cdot a}{2}$, where p is the perimeter

of the polygon and a is the apothem, in this case $BD \cdot n$ and OH respectively, let A_n equal the area of the polygon with n sides such that:

$$A_n = \frac{OH \cdot BD \cdot n}{2}$$

$$A_n = \frac{R\cos\alpha \cdot 2R\sin\alpha \cdot n}{2} = nR^2\sin\alpha\cos\alpha$$

And if n is multiplied by 2, the angle $\angle \alpha$ is divided by 2, and the new area becomes:

$$A_{2n} = 2nR^2 \sin \frac{\alpha}{2} \cos \frac{\alpha}{2}$$

So it can be written that, by definition, the ratio of the area of an n-gon to one of a 2n-gon is

$$\frac{A_n}{A_{2n}} = \frac{nR^2 \sin \alpha \cos \alpha}{2nR^2 \sin \frac{\alpha}{2} \cos \frac{\alpha}{2}} = \frac{\sin 2\alpha}{2 \sin \alpha}$$

Which through the trigonometric identity $\sin 2\theta = 2 \sin \theta \cos \theta$ can be simplified to:

$$\frac{A_n}{A_{2n}} = \frac{2\sin\alpha\cos\alpha}{2\sin\alpha} = \cos\alpha$$

It can be then written that, through a new variable P,

$$P = \frac{A_n}{A_{2n}} \frac{A_{2n}}{A_{4n}} \frac{A_{4n}}{A_{8n}} \dots \frac{A_{(k-2)n}}{A_{kn}} \frac{A_{kn}}{A}$$

where A is the area of the circle of radius R in 2.1.2.

So $P = \frac{A_n}{A}$, since the values A_{kn} cancel, and so it is true that $P = \frac{A_n}{A} \Leftrightarrow A = \frac{A_n}{P}$. The value of R = 1 in this case, and since the area of a circle is defined by $A = \pi R^2$, therefore: $\pi = \frac{A_n}{P}$

By definition, we can say that as the value k approaches infinity, the area of the kn-gon approaches that of a circle, and therefore, the value of π .

$$\frac{A_n}{\cos\alpha\cos\frac{\alpha}{2}\cos\frac{\alpha}{4}...} \to_{k\to\infty} \pi$$

Where the value of A_n is the area of the first polygon, with n=4 sides, and as such $A_n=4\sin 45\cos 45=2$. We can define:

$$U_0 = \cos a = \cos 45 = \frac{1}{\sqrt{2}}$$

$$U_1 = cos \frac{\alpha}{2}$$

Which we can, through the trigonometric identity $\cos^2 \theta = \frac{1}{2} + \frac{1}{2}\cos 2\theta$, simplify as $U_1 = \sqrt{\frac{1}{2} + \frac{1}{2}U_0}$

So it can be said that $U_n = \sqrt{\frac{1}{2} + \frac{1}{2}U_{n-1}}$, which leads to a fully defined expression for the

value of pi, using an infinite product:

$$\pi = \frac{2}{\prod_{k=0}^{\infty} U_k}, U_0 = \frac{1}{\sqrt{2}}, U_n = \sqrt{\frac{1}{2} + \frac{1}{2}U_{n-1}}^2$$

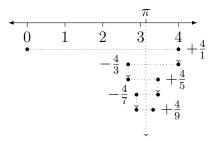


Figure 1: A number line demonstrating the convergence of Madhava's first method for the calculation of π . Adapted from (V. M. Jamkar) [9]

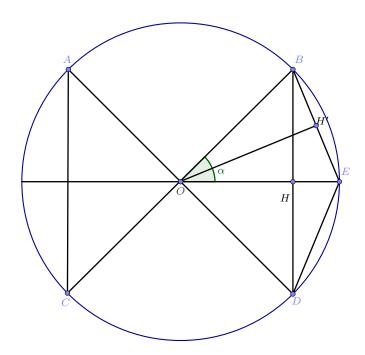


Figure 2: Circle with 1 segment from a n-gon with point H and 2 segments from an 2n-gon, one of which on point H', inscribed in a circle of radius OB, adapted from (Boris Gourévitch) [10]

 $^{^2}$ where \prod signifies a product. Similar expression to \sum

3 Computational approach

3.1 The variables

The dependent variable of this experiment is the time taken t by the program to approximate a given number n of correct decimal value of the constant π .

The value n will be altered in order to avoid possible similar convergence rates at a small amount of decimal places, and multiple trials will be run to decrease margin of error. Other variables of the experiment will be controlled. For example, the experiment will be run on a same isolated system, a virtual machine, with a minimal amount of processes running simultaneously to avoid any possible variance in results.

3.2 Implementing in Python

A Python application was programmed (see appendix) in order to run the two methods aforementioned, and manage the collection of data.

The program assigns the time before the execution of the method to a variable t1 with the time.time() Python function. At each iteration of the method, the number of valid decimal places of the resultant approximation are counted and once a specified threshold is reached, a new t2 time variable is assigned and the time taken, defined by the difference between t2 and t1, is stored. This process is repeated for all specified decimal accuracies and for both methods. The times recorded were stored in a .csv file for further analysis.

The mpmath library was used for the floating point operations required for comparison between approximated values and the constant π that wouldn't have been possible using standard Python libraries. [11]

4 Analysis of the results

4.1 Presentation of the data

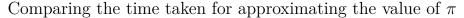
4.1.1 Tabular presentation

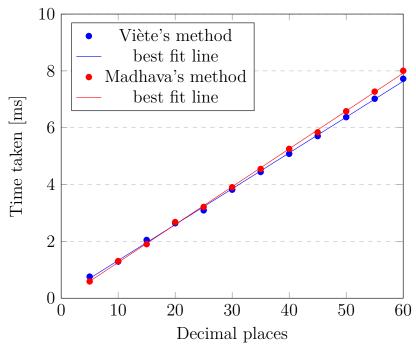
The arithmetic mean of a decimal place was caluclated for 100 trials and the data points in the table shown below were found (rounded to 3 s.f.):

Decimal place	Average time for approximation using Viete's method, in milliseconds (ms)	Average time for approximation using Madhava's method method, in milliseconds (ms)
5	0.760	0.592
10	1.29	1.31
15	2.05	1.9
20	2.64	2.68
25	3.09	3.21
30	3.82	3.9
35	4.44	4.55
40	5.08	5.26
45	5.71	5.84
50	6.37	6.58
55	7.02	7.27
60	7.72	8.00

4.1.2 Graphical presentation

To better show the trend in the data collected, the data has been presented in a scatter chart below. The blue markers and line of best-fit respresent the results received from Viète's method while the red represent those from Madhava's method.





4.2 Observations and analysis

The results gathered from this experiment show linear relationship between the amount of decimal places approximated and the time required for this approximation. The two lines of best fit for the two methods show similarities but also differences. It can be firstly noted that Madhava's method is faster than the other until the decimal 20, when the two best fit lines diverge. This can be explained as due to the convergence rates of the two methods, which can be seen in (Figure 3) 3. In the beginning of this curve representing the convergence of Viète's method, it can be seen that it does not follow an alternating method, like the one formulated by Madhava. Madhava's method is what is called an alternating series, in this case one that converges to the value π^3

³Note: not all alternating series converge

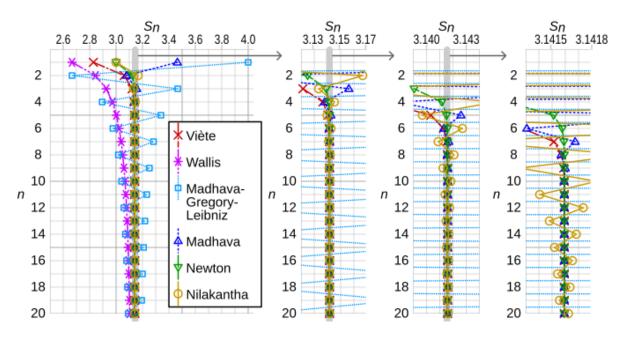


Figure 3: Comparison of historical methods of approximating the value of π . This image demonstrates their convergence rates. The line labelled Madhava in dark blue is the method used in this paper. From (Wikimedia Commons) [12]

5 Further research opportunities

5.1 Investigating newer, more efficient algorithms

As the computation of π moved from paper to machines, as all did from accounting to mathematics, newer and more efficient methods were developed, notably by Ramanujan and the Chudnovsky brothers.

6 Conclusion and Evaluation

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A Appendix

A.1 Python program

This application was run on Python version 3.9.1, on a virtual machine running the Debian operating system under QEMU/KVM on a Intel i5-2500 processor. Used the mpmath library for better floating-point precision [11].

```
import time
from mpmath import *
import csv
import pandas as pd
```

```
mp.dps = 100
PI\_CONST = mp.pi
```

Function that determines if the approximated value of

```
# pi is correct to a specified decimal
def decimal_is_correct(pi, decvalue):
    \#pi\_diff = str(abs(pi))
    zeros = 0
    pistr = str(pi)[2:]
    piconst = str(PI\_CONST)[2:]
    for i in range(len(pistr)):
        if pistr[i] != piconst[i]: break
        else:
            zeros += 1
    if zeros == decvalue:
        return True
    else:
        return False
# Function that approximates pi using Madhava's method
def madhava (decimals):
    piapprox = 0
    i = 0
    t1 = time.time()
    while not decimal_is_correct(piapprox * mp.sqrt(12), decimals):
        # This is a direct mirror of the summation from the formula
        piapprox += mp.power(-3, -i) / (2*i+1)
        i += 1
    piapprox *= mp. sqrt (12)
    t2 = time.time()
```

```
# Function that approximates pi using Viete's method
def viete (decimals):
    piapprox = 1
    numer = 0
    t1 = time.time()
    while not decimal_is_correct((1.0 / piapprox) * 2.0, decimals):
        numer = mp. sqrt (2.0 + numer)
        piapprox *= (numer / 2.0)
    piapprox = (1.0 / piapprox) * 2.0
    t2 = time.time()
    \# Return the time spent (t2-t1) getting d value of decimal places
    return t2-t1
if _{mane} = "_{main}":
    decimals = [i \text{ for } i \text{ in } range(0, 65, 5)]
    trials = 100
    # Exporting data for plotting and analysis
    f = open(r'out.csv', 'w')
    fieldnames = ['decimals', 'viete', 'madhava']
```

Return the time spent (t2-t1) getting d value of decimal places

return t2-t1