

DES535

Ubiquitous Computing

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Google Classroom Code : pcwnf5t

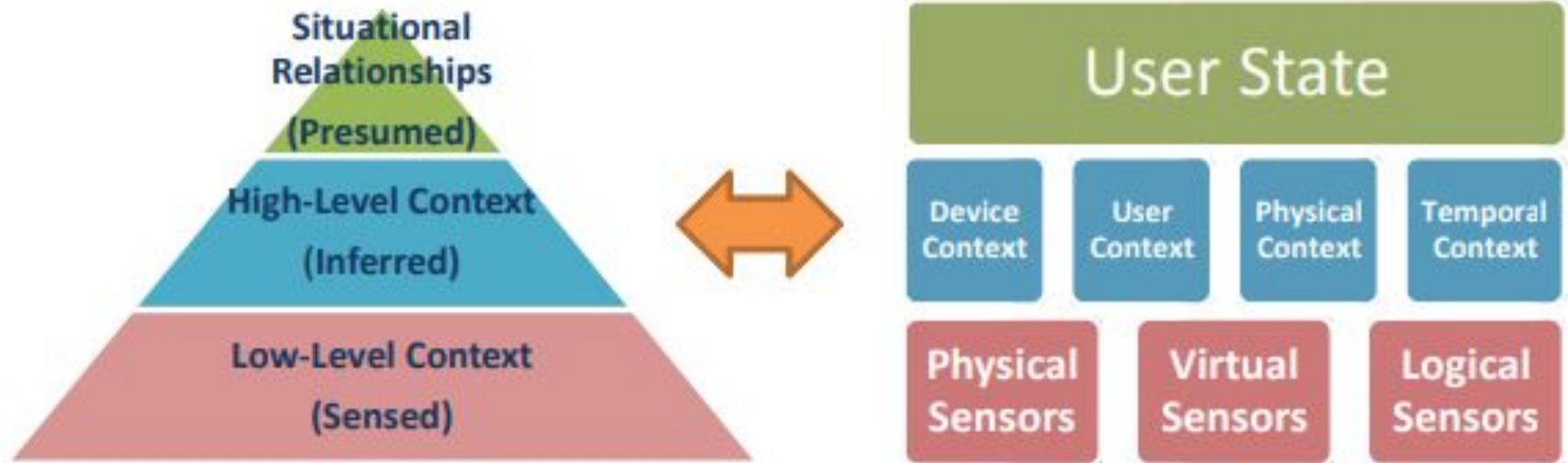
Ambient & Context-Aware Computing

Module III

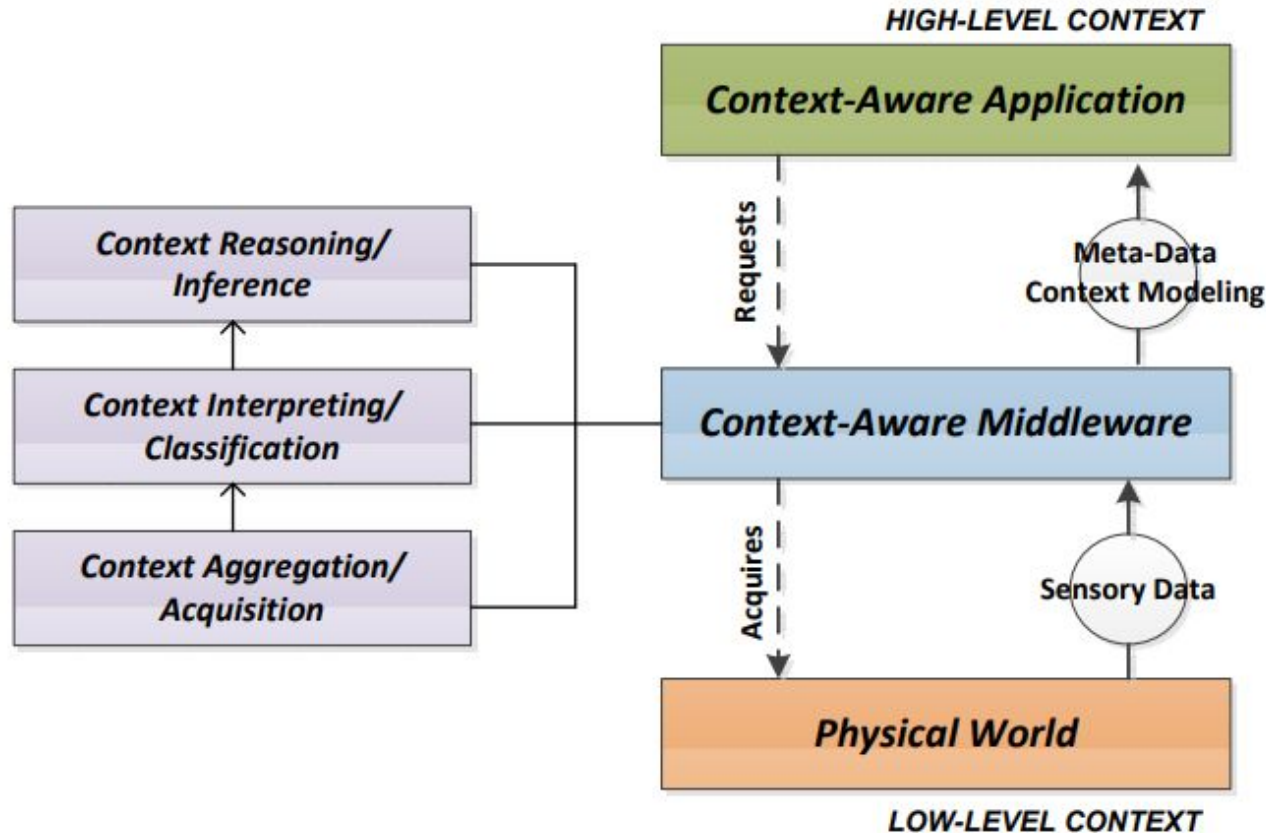
Types of Sensors for Context Sensing

- Physical sensors refer sensors that can capture any physical world belonging data (e.g., GPS: location, accelerometer: activity etc.).
- Virtual sensors imply a source from software applications and/or services, and a semantic data obtained through cognitive inference (e.g., location info by manually entered place pinpoint through social network services or computation power of devices etc.).
- Logical sensors define combination of physical and virtual sensors with additional information obtained through various sources by user interactions (e.g., databases, log files etc.).

Hierarchy of Context Representation



Architecture of Context-aware Systems



Case Study 1

CHI 2018 Best Paper Award

Wall++: Room-Scale Interactive and Context-Aware Sensing

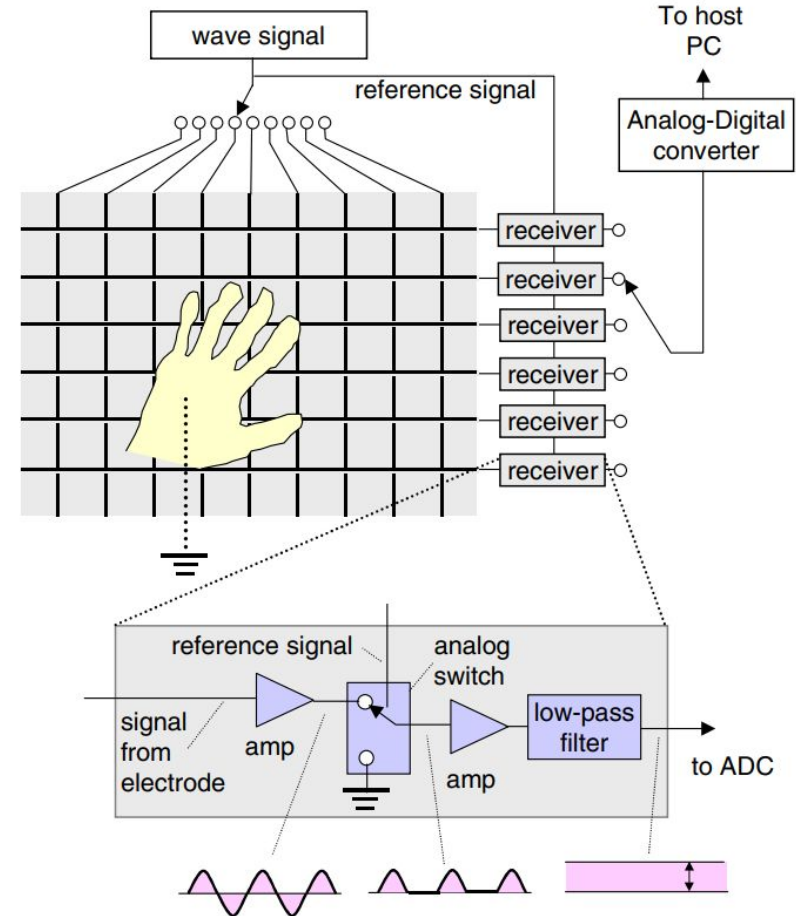
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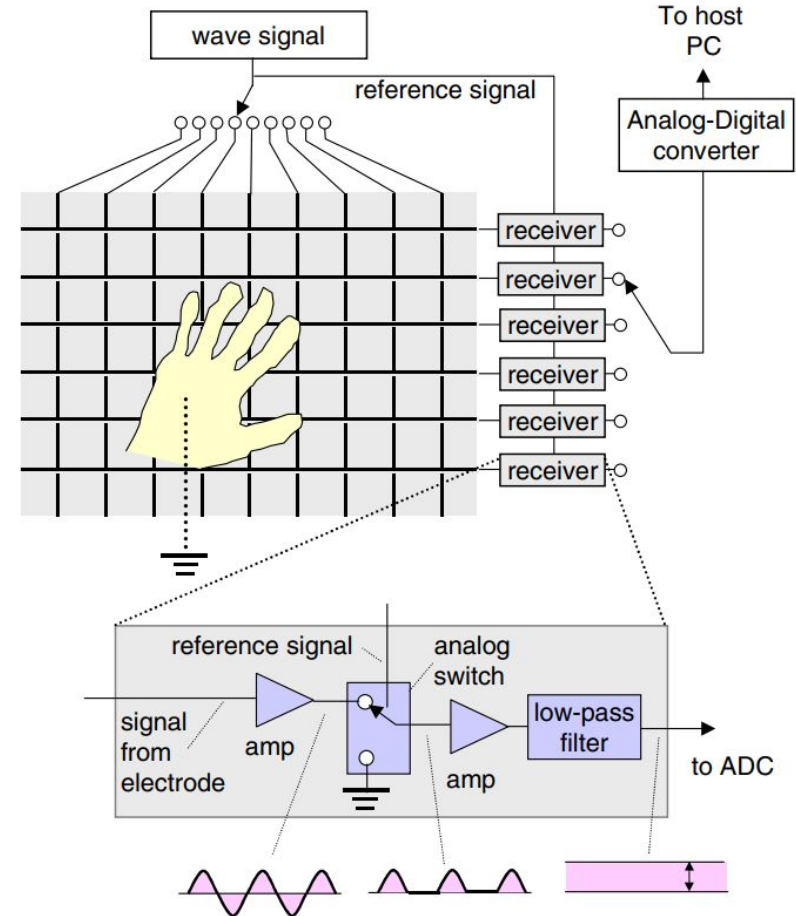
Capacitive Sensing : The pioneers (SmartSkin)

- The sensor consists of grid-shaped transmitter and receiver electrodes (copper wires).
- The vertical wires are transmitter electrodes, and the horizontal wires are receiver electrodes.
- When one of the transmitters is excited by a wave signal (of typically several hundred kilohertz), the receiver receives this wave signal because each crossing point (transmitter/receiver pairs) acts as a (very weak) capacitor.



Capacitive Sensing : The pioneers (SmartSkin)

- When a conductive and grounded object (finger) approaches a crossing point, it capacitively couples to the electrodes, and drains the wave signal.
- As a result, the received signal amplitude becomes weak.



Capacitive Sensing : Smartscreens

Typical diamond pattern of a mutual-capacitance touch sensor. Approaching fingers couple to the lines and cause a drop in capacitance between them.

Watch this video :

<https://www.youtube.com/watch?v=IdWXT391FJE>

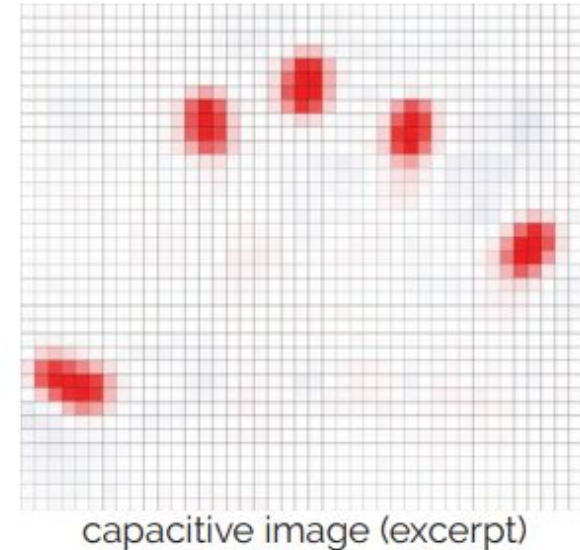
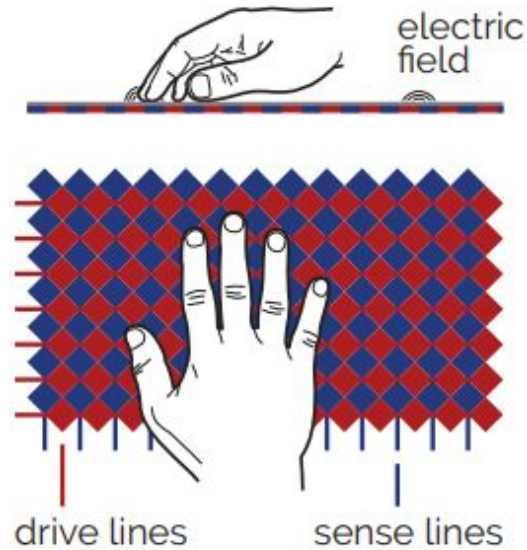


Image Source: <https://siplab.org/projects/TouchPose>

HOW DO TOUCHSCREENS ACTUALLY WORK?

TEDEd



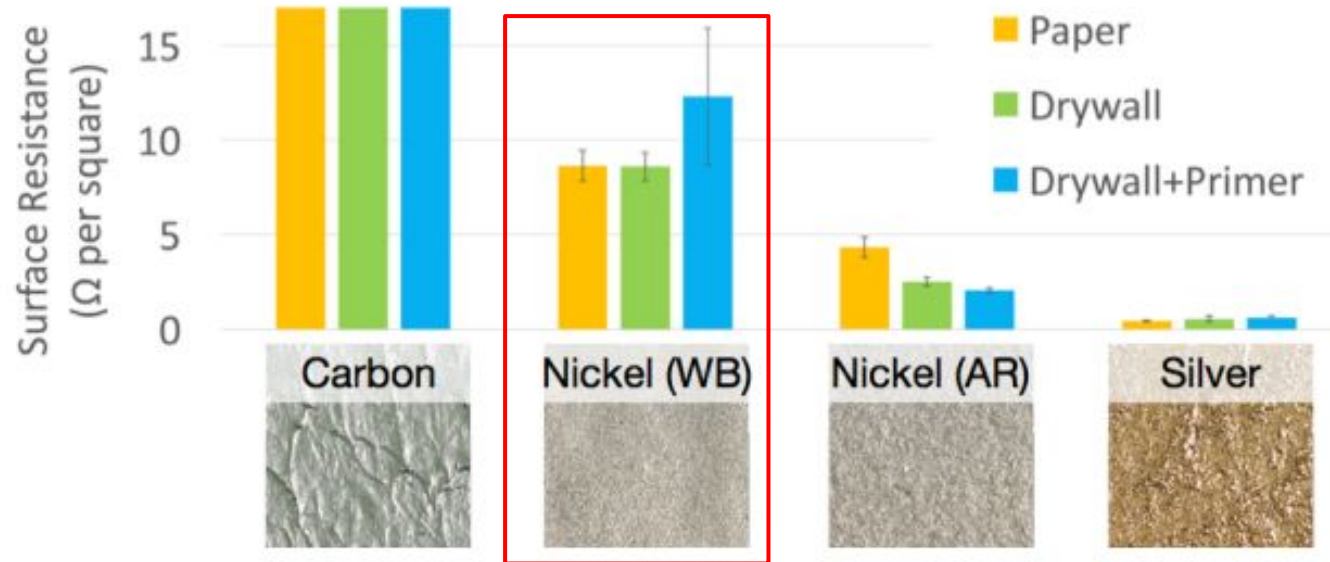
Capacitive Sensing : Other Applications



Phases of Wall ++

Phase 1: Paint and Backing Materials

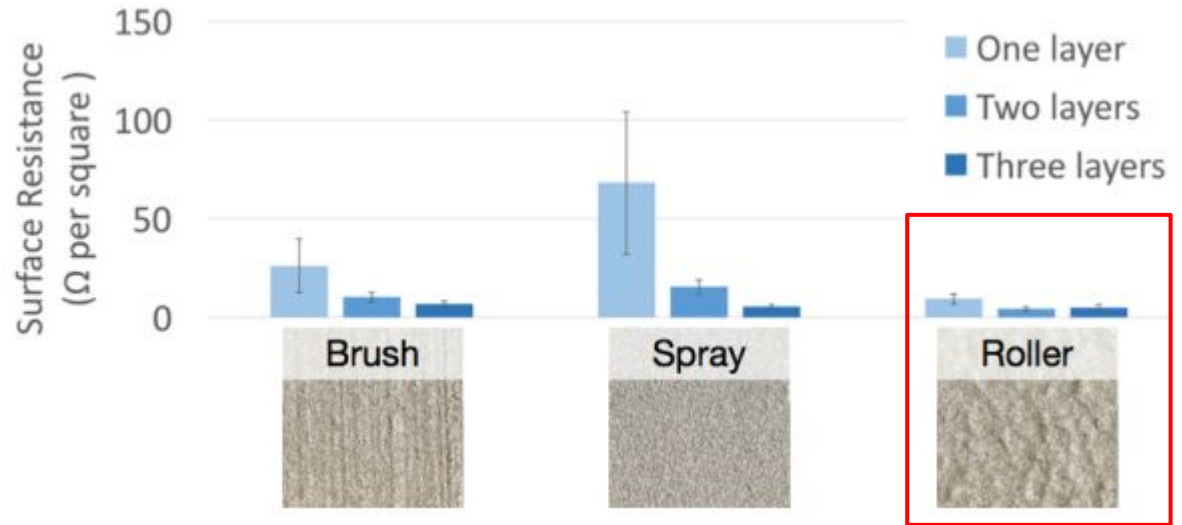
- carbon
- water-based nickel
- acrylic-based nickel
- silver



Phases of Wall ++

Phase 2: Application Method and Number of Coats

- brush
- spray
- roller

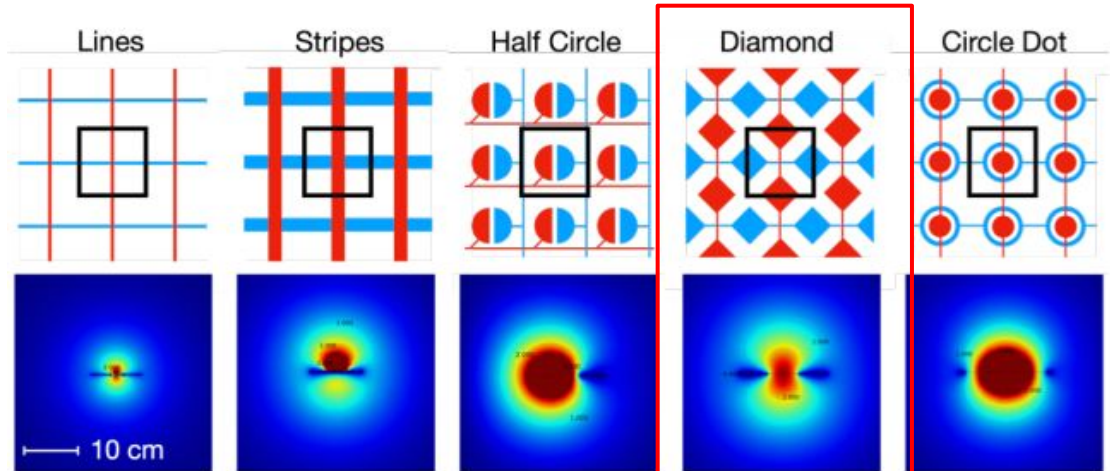


Phases of Wall ++

Phase 3 & 4: Topcoat, Traces & Insulation : Latex overcoat, copper traces with vinyl stickers

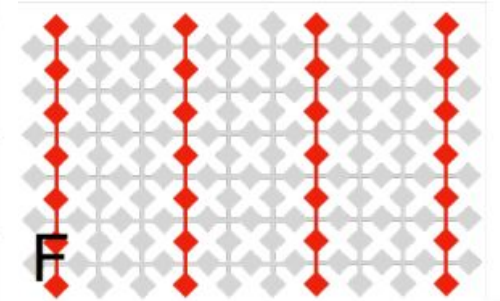
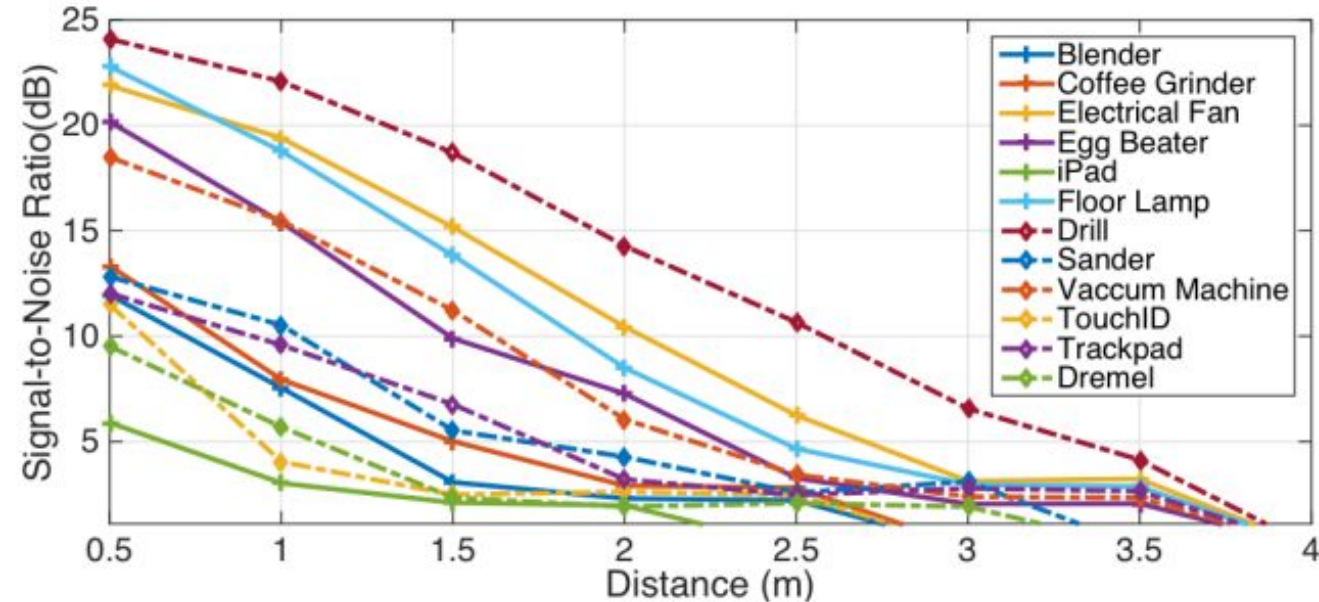
Phase 5 & 6: Electrode pattern and optimization

- 1) projected an electric field as far as possible, so as to provide the largest interactive volume, while also
- 2) offering sufficient resolution to enable fine-grained interactions

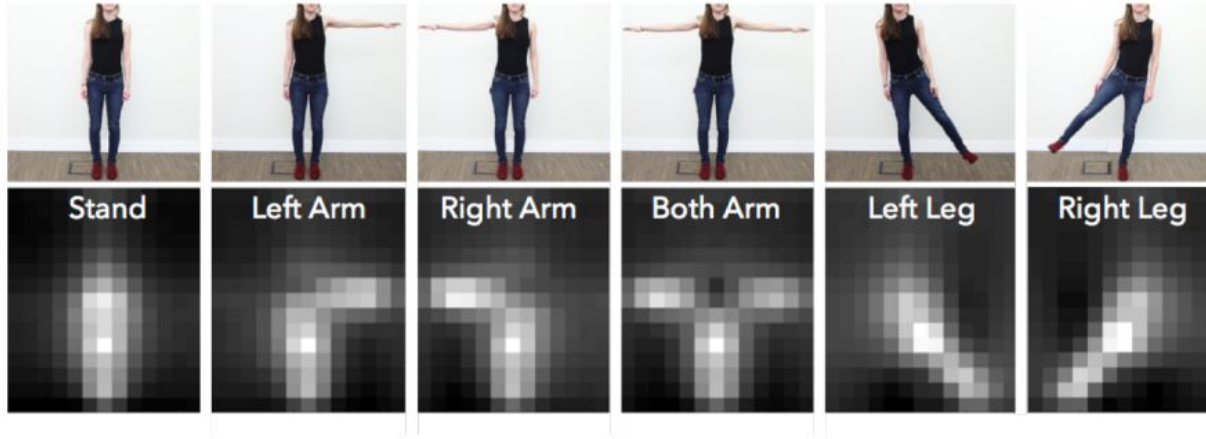


Phases of Wall ++

Phase 7: Antenna for Electromagnetic Signals (Environment Sensing)



Results of Wall ++ : Pose Estimation



Actual Class (%)	Stand	99.6	0.3	0.1	0.0	0.0	0.0
	Left Arm	1.9	98.0	0.0	0.1	0.0	0.0
	Right Arm	2.0	0.0	97.0	1.0	0.0	0.0
	Both Arm	0.6	3.9	4.1	91.4	0.0	0.0
	Left Leg	15.3	0.0	0.7	0.0	84.0	0.0
	Right Leg	15.2	3.0	0.0	0.0	0.0	81.8
		Stand	Left Arm	Right Arm	Both Arm	Left Leg	Right Leg
		Predicted Class (%)					

Results of Wall ++ : Tracking distance error at three test locations



Wall++

Interactive & Context Sensing Walls



Derived Idea

Can we build Smart Papers with Capacitive sensing capabilities? If so, can you develop a conceptual model ?

Activity 2 : Time bound activity on Capacitive Sensing

Develop a simple mobile application that displays your touch points on its screen.

Hint: Use canvas element in MIT App Inventor