

# kintsugi-stack-dsa-cpp: THEORY

"Data Structures and Algorithms (DSA) should be viewed as essential tools, akin to the finely tuned parts of a Formula 1 car. The act of problem-solving with DSA serves as a crucial platform to exhibit both intelligence and creative thinking. The coding challenges themselves are simply various permutations of external factors; like the weather, track, wind, and rain in an F1 race. Ultimately, what dictates success in both domains; coding and Formula 1; is the mastery of planning, strategizing, maintaining flow, and ensuring precise code orchestration." - Siddhant Bali

- Author: [Kintsugi-Programmer](#)

Disclaimer: The content presented here is a curated blend of my personal learning journey, experiences, open-source documentation, and invaluable knowledge gained from diverse sources. I do not claim sole ownership over all the material; this is a community-driven effort to learn, share, and grow together.

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## 0. About

- Introduction and Primary Focus
  - This PreReqs focuses on teaching all the **fundamental data structures and algorithms** that individuals need to know. There is a specific emphasis on preparing for **coding interviews**.
- Target Audience
  - This curriculum is suitable for two main groups:
    - **1. Beginners.**
    - **2. Anyone who just needs a refresher.**
- PreReqs Content and Scope
  - The instruction will cover all the common data structures and algorithms. The discussion will include detailed analysis of four key areas related to these structures and algorithms:
    - **1. Design**
    - **2. Implementation**
    - **3. Tradeoffs**
    - **4. Analysis**
  - Career Impact and Compensation Value
    - Mastering the skills taught in this PreReqs is critical because the ability to perform efficiently can significantly impact compensation. This difference in compensation can amount to **hundreds of thousands of dollars**.
  - The core competencies that yield this high value include:

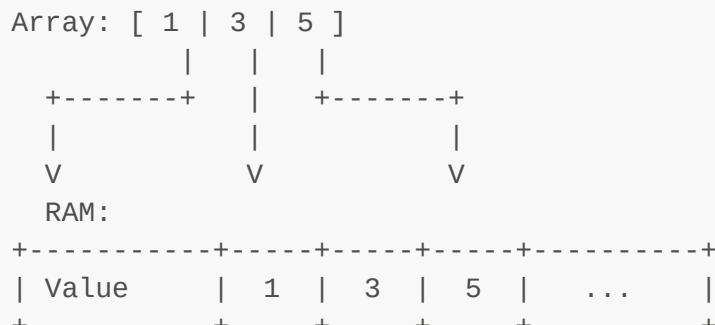
- ▪ Solving these problems **efficiently**.
- ▪ **Analyzing** them.
- ▪ Discussing their **tradeoffs**.
- ▪ **Communicating the idea** to others.
- The goal is that the problem solving skills acquired in this course will serve the participant for their **entire career**.
- Next Steps
  - For participants seeking **more details on what is going to be covered**, they should **scroll down**. Once participants are ready, they are encouraged to **get started**.

## 1. Arrays

### 1.1. RAM(Random-access memory)

- Data Structures and RAM
  - A data structure is a way of structuring data.
  - In computer science, data structures involve structuring data inside of RAM (Random Access Memory).
  - RAM is where all variables are stored.
  - Example: An array containing the numbers 1, 3, and 5 is information stored in RAM.
- RAM Measurement and Composition
  - RAM is measured in bytes.
  - It is common for many computers to have 8 gigabytes of RAM.
  - Giga means about \$10^9\$, or approximately a billion.
  - A byte is eight bits. **1 byte = \_\_\_\_\_ (0 or 1)**
  - eg: **1 Int = 4 Bytes = \_\_\_\_\_**
  - eg: **'1' decimal = 00000000000000000000000000000001 binary**
  - A bit can be thought of as a position that stores a digit.
  - The restriction on the digit stored in a bit is that it can only be a zero or a one.
  - Zeros and ones are the language of computers.
  - Storage Hierarchy: Individual bits form multiple bits, which form bytes, which ultimately form RAM.
  - RAM is used to store advanced data structures.
- Storing Values and Addressing in RAM

[ Array storage in RAM ]



Address	\$0	\$4	\$8	\$12 ...	GAP OF 4B
+-----+-----+-----+-----+-----+					
[ 'a', 'b', 'c' ] =					
+-----+-----+-----+-----+-----+					
Value	'a'	'b'	'c'	...	
+-----+-----+-----+-----+-----+					
Address	\$0	\$1	\$2	\$3 ...	GAP OF 1B
+-----+-----+-----+-----+-----+					

- RAM can be conceptually viewed as a contiguous block of data.
  - i.e. Nothing Can be B/w 2 adjacent blocks
- RAM has two components: values and addresses.
- Values are the data being stored.
- Every value is stored at a distinct location called an address.
- In representations, a dollar sign (\$) may be used in front of every address to distinguish it from the stored values.
- Example: The first address might be \$0.
- Representation of Integers in RAM
  - It is common for integers to be represented by four bytes, not a single byte.
  - Four bytes is equivalent to 32 bits.
  - Example of storing the integer '1' using 32 bits:
    - The representation will be 31 zeros, followed by a single one at the end.
  - The process involves taking the value, representing it in terms of bytes, and then placing that representation into RAM.

## 1.2. Static Arrays

- Arrays
  - Arrays are considered the most simple data structure.
  - **Definition/Key Property:** Arrays are always contiguous.
  - Contiguous storage means that nothing is stored in between the values of the array (e.g., nothing between the 3 and the 5).
  - Arrays look exactly the same in memory as they are represented conceptually: a contiguous set of values.
  - When storing an array in RAM, the starting location (address) is not always chosen by the user.
  - Arrays can store different types of values, such as integers or characters.
- Array Storage and Address Incrementing (The Size Rule)
  - Values are stored contiguously regardless of how large or small they are.
  - The address must be incremented by the size of the value being stored.
  - **Example: Storing 32-bit Integers (4 bytes)**

Array: [ 1   3   5 ]

Value	1	3	5	...		
Address	\$0	\$4	\$8	\$12	...	

- Each integer takes four bytes to store.
  - If the address stored the value '1' starting at address \$0.
  - It uses four bytes (\$0, \$1, \$2, \$3).
  - The next value ('3') must be stored starting at address \$4 (incremented by four).
  - The final value ('5') would be stored starting at address \$8.
  - If each value only took one byte, the addresses would increment by one (\$0, \$1, \$2), but 32-bit integers require four bytes.
- **Example: Storing Characters (1 byte)**

Array: [ a   b   c ]						
	a	b	c	...		
Value	a	b	c	...		
Address	\$0	\$1	\$2	\$3	...	

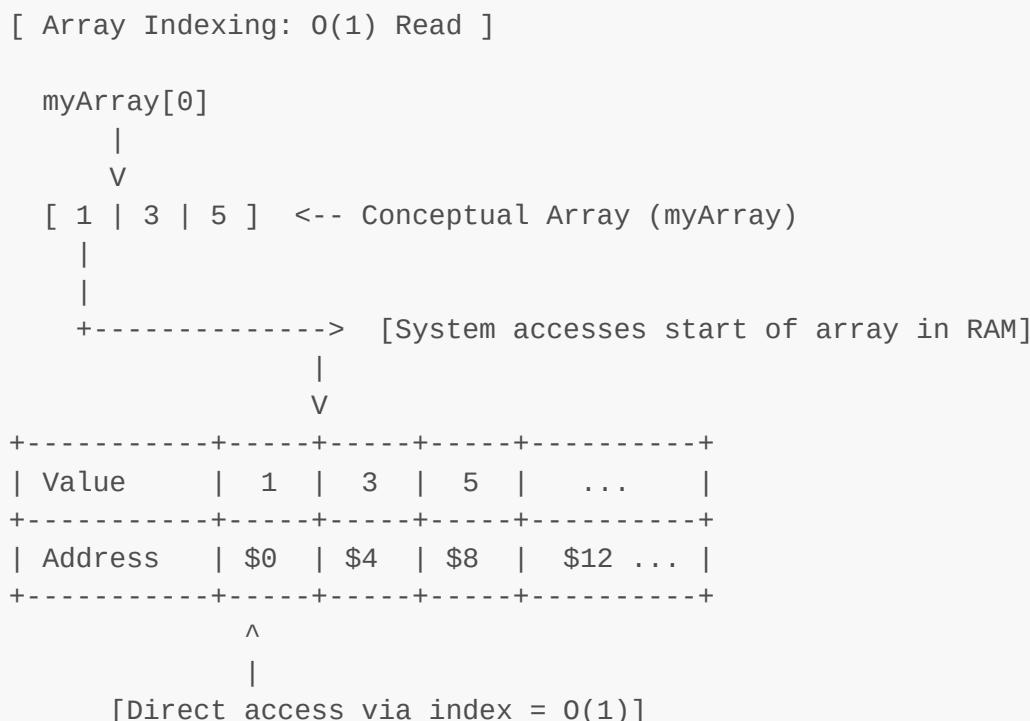
- Characters (like A, B, C) are stored continuously.
- Characters typically take only one byte to store in memory.
- This one-byte size is typical when storing ASKY characters, although knowing the specific encoding (ASKY) is not super important.
- If the first character 'A' starts at address \$0.
- The next address is incremented by one: 'B' is stored at address \$1.
- The next character 'C' is stored at address \$2.

- Course Focus
  - The information presented covers theoretical aspects of memory and how arrays are stored.
  - This course will mostly focus on practical knowledge.
  - Upcoming topics will cover array properties, usage, and tradeoffs.
- ARRAY PROPERTIES AND OPERATIONS (STATIC ARRAYS)

Operation	Big-O Time

r / w i-th element	0(1)
Insert / Remove End	0(1)
Insert Middle	0(n)
Remove Middle	0(n)

- Array Definition and Structure
  - An array is defined as a **contiguous block of data**.
  - Arrays are stored in RAM (Random Access Memory) as a contiguous block of data.
- Common Array Operations
  - The two most common operations for any data structure are reading to the data or writing to the data.
- I. Reading Data from Arrays



- Indexing
  - Programmers use indexes to access values in an array.
  - The first value is **always at index zero**, not index one.
  - Subsequent values are at index one, two, etc..
- Reading Mechanism
  - To read the first element of an array (e.g., **my array**), the intuitive action is to go to the first address in memory and read the value.
  - Under the hood, this is exactly what happens.
  - Programmers do not need to know the exact address of every single value.
  - When reading the value at index zero, the system automatically goes to that location in memory and reads the stored value.
- Efficiency of Reading

- Since any index in the array can be automatically mapped to a location in memory, any value can be read **instantly** if the index is available.
- This efficient operation is represented by **big O of one ( $O(1)$ )**.
- $O(1)$  means that in the worst case, reading a value (assuming the index is known, e.g., index 2) is an **instant operation**.
- Reading happens in **constant time**, regardless of how large the array becomes.
- Role of RAM
  - The ability to go to any arbitrary address in RAM and read the value is a property of RAM.
  - **RAM stands for Random Access Memory.**
  - Random access means memory can be accessed randomly in constant time.
  - We do not have to start from the beginning of RAM and keep looking for a value; we can access it automatically.
  - This is important because if there is a lot of RAM, we avoid going through the entire RAM every time.
  - If accessing the third value, we do not have to go through the first and second values.
- Looping Through Arrays (Reading All Values)
  - After reading the first value, we read the second, third, and continue until the end of the array.
  - In code, reading a value at index *i* is typically represented by `my_array at index i`.
  - The index *i* is incremented (to one, then two, etc.).
  - The loop stops when *i* equals the length of the array.
  - This process loops through the entire input array.
  - In most languages, this can be done using a `for loop` or a `while loop`.
- II. Writing Data and Limitations of Static Arrays
  - **ARRAY IS NOT DYNAMIC, YOU CAN'T APPEND SPACE TO ADD MORE ELEMENTS**
  - Fixed Size Property
    - Arrays possess the property of **fixed size**.
    - Example: If an array was declared to hold three values, it is fixed size.
  - The Contiguity Constraint for Adding Values
    - If we want to add a fourth value (e.g., a seven) to an array of size three, the new value must be added to maintain contiguity.
    - Example: If the existing data ends just before address 12, the seven would need to be added precisely at address 12 to maintain a contiguous array of size four.
    - Limitations in RAM allocation prevent simple expansion.
      - We do not always get to decide exactly where RAM is allocated or where values are stored.
      - The required spot in RAM might already be used by another array or the operating system.
      - If a value is put anywhere else in memory, the array loses its contiguous property, resulting in two separate arrays, which is not the intended outcome.
    - Loss of Contiguity Breaks Operations
      - If contiguity is lost, looping through the array breaks.

- Example: If a loop is at index two and increments to index three, it will attempt to access the expected contiguous spot; if the value is stored elsewhere, the operation will fail.
- Static Arrays Defined
  - This fixed-size constraint is the biggest limitation of **static arrays**.
  - Static arrays are defined as **fixed size arrays**.
  - **Recommendation is to first define upperbound static arrays with initialisation with zeros or use vector array**
- Static vs. Dynamic Arrays
  - Programming languages like Python or JavaScript often use **dynamic arrays** by default, which means programmers rarely encounter the fixed-size limitation or worry about running out of space.
- Initialization
  - When a static array (e.g., size three) is allocated, there must be something stored in memory.
  - Default initialization varies:
    - Languages usually initialize values to all zero.
    - Sometimes they do not initialize them at all, resulting in random arbitrary values.
- III. Overwriting and Efficient Operations ( $O(1)$ )
  - Writing/Adding at the End
    - Adding a new value to the end of the array (at the next empty spot being tracked) is an **instant operation**.
    - We know the index (e.g., index 2) and thus instantly know the position in RAM.
    - **Writing to any position** is a **big O of one ( $O(1)$ ) operation**; it is constant time.
    - Inserting a value at the end of the array is also a **big O of one ( $O(1)$ )** time operation, assuming an empty space is available.
  - Removing/Overwriting
    - When "removing" a value in a static array, we cannot actually delete or deallocate it from memory.
    - Removal means **overwriting** the value (e.g., replacing it with a zero).
    - We effectively declare that the original value is "no longer relevant," even though it remains in memory.
    - **Removing a value** is also efficient: **big O of one ( $O(1)$ )**.
    - It is a constant time operation because it involves going to that memory position and overwriting it (e.g., replacing it with a zero or negative 1).
    - Removing the value at the end of the array is a **big O of one ( $O(1)$ )** time operation, assuming at least one element exists to remove.
  - Summary of Efficient Operations
    - Reading or overwriting the arbitrary element **E** (meaning any index) is done in **big O of one ( $O(1)$ )** time, or constant time.
- IV. Arbitrary Insertion and Removal (Inefficient Operations:  $O(N)$ )
  - Ordered Values
    - In arrays, including static arrays, the **order of the values matters**.
    - Values are ordered because of the way indexes work (e.g., five comes before six).
  - Inserting into the Middle or Beginning

- Inserting at an arbitrary position (middle or beginning) is **not efficient**.
- If we simply overwrite an existing value to insert a new one, the desired order is lost (e.g., replacing five with four results in four, six, not four, five, six).
- The Shifting Mechanism for Insertion
  - To insert a value (e.g., four) while maintaining order (e.g., four, five, six), the existing elements must be **shifted to the right**.
  - **Step 1: Shift existing values.** We must shift the elements starting from the end towards the right.
    - Example: Before shifting the five, the six must be shifted to prevent loss of data.
    - Six (at index 1) moves to index 1 + 1 (index 2).
    - Five (at index 0) moves to index 0 + 1 (index 1).
  - **Step 2: Insert the new value.** Only after shifting is completed can the new value (four) be placed in the now-available position (index 0).
  - **Downside:** This requires moving every existing value in the array.
- Insertion Time Complexity (Worst Case)
  - Shifting many elements is **not very efficient**.
  - This operation is called **big O of N (O(N))**.
  - **N** refers to the **number of elements** in the array (the length), not the size of the array.
  - **Big O** notation refers to the **worst case** scenario.
  - **Worst Case for Insertion:** If inserting a value at the beginning of a filled array, we must shift every value in the array ( $N$  values) over to the right by one.
  - **Worst Case Time Complexity:** Inserting into the middle of an array is **big O of N**.
    - Note: While inserting into an empty array would be  $O(1)$ , the worst case determines the Big O notation.
  - Example of a better case: If inserting between five and six to achieve five, four, six, only the six would need to be shifted (one value), not every value. However, the generalized worst case is still  $O(N)$ .
- Arbitrary Removal Time Complexity
  - Removing a value at an arbitrary index requires similar shifting.
  - Arbitrary removal means we want to act as if the value no longer exists, not just replace it with a zero.
- The Shifting Mechanism for Removal
  - Removal requires shifting values to the **left**.
  - Example: If removing the value at index 0 from (5, 6, 7), the goal is to shift the 6 and 7 forward.
    - Six (at index 1) moves to index 1 - 1 (index 0).
    - Seven (at index 2) moves to index 2 - 1 (index 1).
  - Memory Note: The memory allocated for the element that was removed still exists and is reflected in RAM, even if the resulting array (6, 7) appears smaller.
  - **Worst Case Time Complexity:** Removing in the middle of an array is **big O of N ( $O(N)$ )**, as we might have to shift every value.

- ARRAY PROPERTIES AND OPERATIONS (STATIC ARRAYS) CODE

```
#include <iostream>

using std::cout;
using std::endl;

// Insert n into arr at the next open position.
// Length is the number of 'real' values in arr, and capacity
// is the size (aka memory allocated for the fixed size array).
void insertEnd(int arr[], int n, int length, int capacity) {
    if (length < capacity) {
        arr[length] = n;
    }
}

// Remove from the last position in the array if the array
// is not empty (i.e. length is non-zero).
void removeEnd(int arr[], int length) {
    if (length > 0) {
        arr[length - 1] = 0;
    }
}

// Insert n into index i after shifting elements to the right.
// Assuming i is a valid index and arr is not full.
void insertMiddle(int arr[], int i, int n, int length) {
    for (int index = length - 1; index >= i; index--) {
        arr[index + 1] = arr[index];
    }
    arr[i] = n;
}

// Remove value at index i before shifting elements to the left.
// Assuming i is a valid index.
void removeMiddle(int arr[], int i, int length) {
    for (int index = i + 1; index < length; index++) {
        arr[index - 1] = arr[index];
    }
}

void printArr(int arr[], int capacity) {
    for (int i = 0; i < capacity; i++) {
        cout << arr[i] << ' ';
    }
    cout << endl;
}
```

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End-of-File

The [kintsugi-stack](#) repository, authored by Kintsugi-Programmer, is less a comprehensive resource and more an Artifact of Continuous Research and Deep Inquiry into Computer Science and Software Engineering. It

serves as a transparent ledger of the author's relentless pursuit of mastery, from the foundational algorithms to modern full-stack implementation.

Made with ❤️ Kintsugi-Programmer