

Topic 3

Differentials and general function
models

Outline

1. Review of continuity and derivative
2. Partial differentiation
3. Comparative-static analysis
4. Differentials
5. Total differentials
6. Total derivatives
7. Homogeneous Functions
8. Derivatives of implicit functions

1. Review of continuity and derivative

- $f(x)$ is continuous at x_0 , denoted

$$\lim_{x \rightarrow x_0} f(x) = f(x_0)$$

- **Example:** a continuous function

$$|x| = \begin{cases} x & \text{if } x \geq 0 \\ -x & \text{if } x < 0 \end{cases}$$

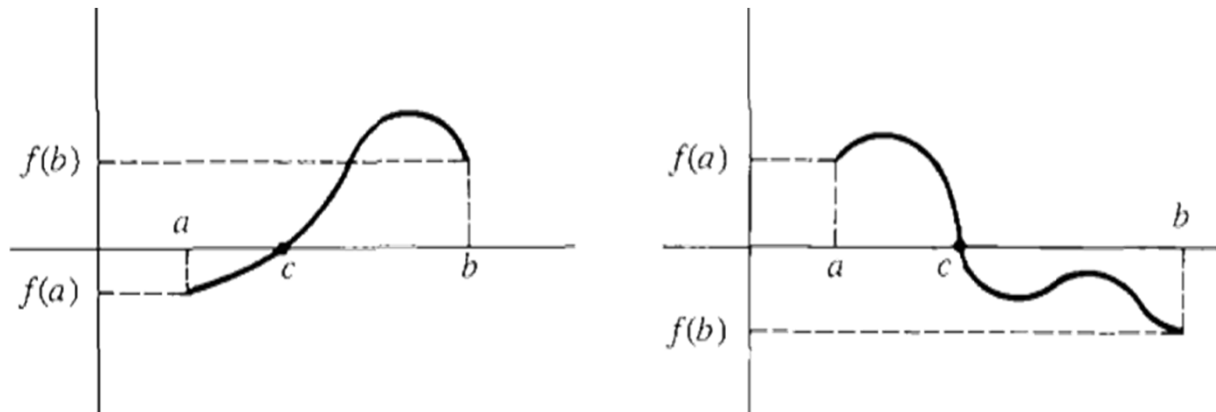
- **Example:** a discontinuous function

$$\text{sgn}(x) = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{if } x = 0 \\ -1 & \text{if } x < 0 \end{cases}$$

$$\text{note that } \begin{cases} \lim_{x \rightarrow +0} \text{sgn}(x) = 1 \\ \lim_{x \rightarrow -0} \text{sgn}(x) = -1 \end{cases}$$

so it is not continuous at 0

- Roughly speaking, a function is continuous if its graph can be drawn in a single stroke, without ever lifting the pen. There should be no "jumps".
- An important property of continuous functions is the **intermediate value theorem**: Suppose that the function $y = f(x)$ is continuous in $[a, b]$ and assume that $f(a)$ and $f(b)$ have different signs, then there is at least one root to the equation $f(x) = 0$ in (a, b) , i.e., a number c with $a < c < b$ such that $f(c) = 0$



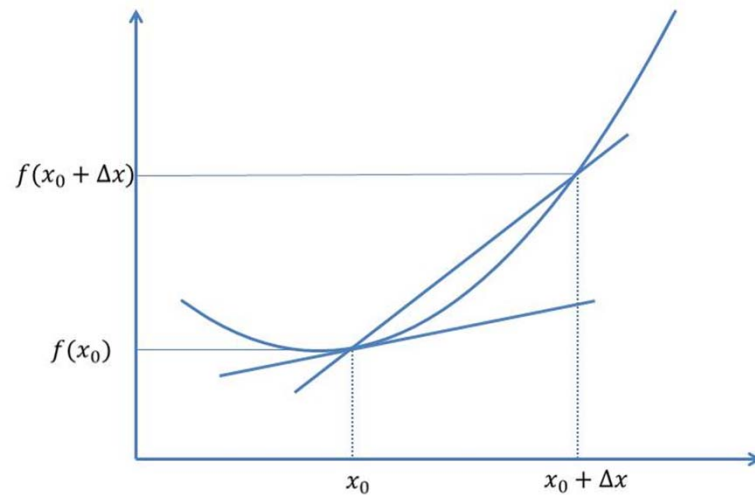
- If f is continuous and $f(a) > 0$, then $f(x) > 0$ for all x close to a .

Review of derivative

- An important topic in economics is the study of **rates of change**
- Consider a function $y = f(x)$ defined on D and $x_0 \in D$, suppose for a small Δx , $x_0 + \Delta x \in D$.
 - The rate of change of $f(x)$ per change of x is

$$\frac{\Delta y}{\Delta x} = \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x}$$

- Geometrically, $\frac{\Delta y}{\Delta x}$ is the slope of the chord passing through the two points $(x_0, f(x_0))$ and $(x_0 + \Delta x, f(x_0 + \Delta x))$
- As Δx becomes smaller and smaller, the slope of the chord approaches the slope of the line tangent to the curve at $(x_0, f(x_0))$, the limit



$$f'(x_0) = \lim_{\Delta x \rightarrow 0} \frac{f(x_0 + \Delta x) - f(x_0)}{\Delta x} \quad \left(\text{or } \left. \frac{df}{dx} \right|_{x=x_0}, \left. \frac{df}{dx} \right|_{x_0} \right)$$

is called the **derivative** of f at point x_0

- The number $f'(x_0)$ gives the slope of the tangent to the curve $y = f(x)$ at the point $(x_0, f(x_0))$

Derivative of monotone functions

- f is increasing function on $(a, b) \Leftrightarrow f'(x) \geq 0$ for $x \in (a, b)$
- f is decreasing function on $(a, b) \Leftrightarrow f'(x) \leq 0$ for $x \in (a, b)$
- $f'(x) = 0$ for all $x \in (a, b) \Leftrightarrow f$ is constant for $x \in (a, b)$
- $f'(x) > 0$ for all $x \in (a, b) \Rightarrow f$ is strictly increasing for $x \in (a, b)$
- $f'(x) < 0$ for all $x \in (a, b) \Rightarrow f$ is strictly decreasing for $x \in (a, b)$

Rules of differentiation

- **Constant function rule:** if $f(x) = k$, then $f'(x) \equiv 0$
- **Power function rule:** If $f(x) = x^a$, where $a \in \mathbb{R}$ is a constant, then
$$f'(x) = ax^{a-1}$$
- **Derivative of Exponential functions and logarithmic functions:**
$$(e^x)' = e^x, \quad (\ln x)' = (1/x)$$
- **Sum-difference rule:** $[f(x) \pm g(x)]' = f'(x) \pm g'(x)$
- **Product rule:** $[f(x)g(x)]' = f'(x)g(x) + f(x)g'(x)$
- **Quotient rule:** $\left[\frac{f(x)}{g(x)}\right]' = \frac{f'(x)g(x) - f(x)g'(x)}{[g(x)]^2}$
- **The chain rule:** The composition of two differentiable functions $y = f(u)$ and $u = g(x)$ is again differentiable and has the derivative

$$\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dx} \text{ or } [f(g(x))]' = f'(g(x)) \cdot g'(x)$$

Higher order derivatives

- The derivative of a function f is often called the **first order derivatives** of function $y = f(x)$
- If f' is differentiable, the derivative of function f' is called the **second order derivative** of f , denoted y'' , $f''(x)$, or $\frac{d^2}{dx^2} f(x)$
- Notation for third order derivative: y''' , $f'''(x)$, $f^{(3)}(x)$, or $\frac{d^3}{dx^3} f(x)$
- n th order derivative: $f^{(n)}(x)$ or $\frac{d^n}{dx^n} f(x)$
- If $f^{(n)}(x)$ exists and is continuous, then we denote $f \in C^n$

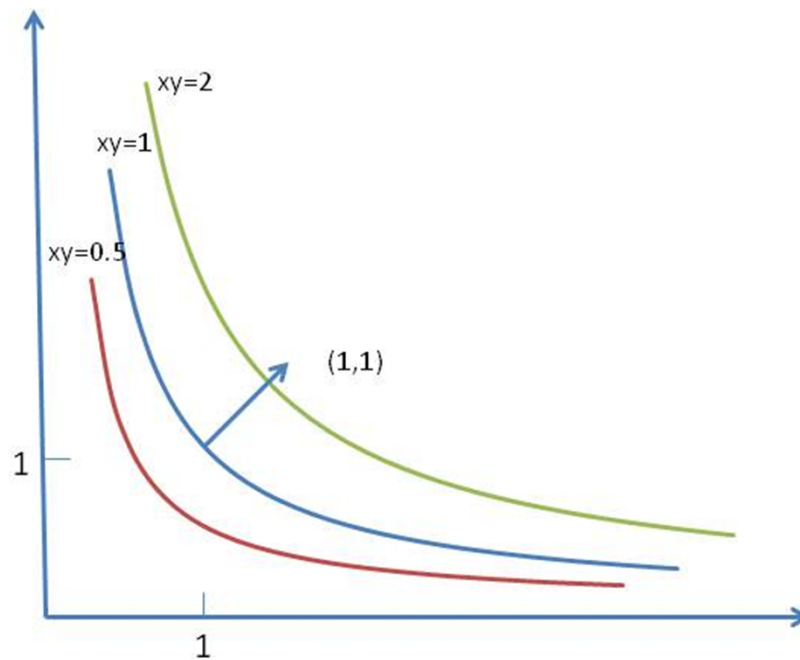
Examples: Higher order derivatives

- Example 1: $f(x) = x^5 + e^{2x}$, then
$$f'(x) = 5x^4 + 2e^{2x}, f''(x) = 20x^3 + 4e^{2x}, f'''(x) = 60x^2 + 8e^{2x}$$
- Example 2: Let $f \in C^2$ and $g(x) = f(x^2)$, then
$$g'(x) = 2xf'(x^2), g''(x) = 2f'(x^2) + (2x)(2x)f''(x^2)$$

2. Partial differentiation

- Consider the function $z = f(x, y) = x^3 + y^2$, suppose y is a constant, i.e., $y = 1$, then z becomes a function of one variable x only, change of z wrt x is $\frac{dz}{dx} = 3x^2$
 - If x is a constant, then, z becomes a function of one variable y only, change of z wrt y is $\frac{dz}{dy} = 2y$
- When we consider functions of two (or more) variables, we use $\frac{\partial z}{\partial x}$ (or $\frac{\partial f}{\partial x}$ or f_1' , f_x' or f_1 , f_x when there is no confusion) instead of $\frac{dz}{dx}$ for the derivative of z with respect to x when y is held fixed, called the **partial derivative** of z wrt x
 - In the same way, we use $\frac{\partial z}{\partial y}$ (or $\frac{\partial f}{\partial y}$ or f_2' , f_y' or f_2 , f_y) instead of $\frac{dz}{dy}$ for the derivative of z with respect to y when x is held fixed, called the **partial derivative** of z wrt y
- The vector of first order partial derivatives $\nabla f = (\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y})'$ is called the gradient vector

- For $f \in C^1$ (meaning ∇f is continuous), at any point (x, y) on the level curve at which $\nabla f \neq 0$, the gradient vector $\nabla f(x, y)$ has the property that it points to the direction in which f increases most rapidly, and it is perpendicular to the tangent line of level curve.
- Example:** The function $f(x, y) = xy$ increase most rapidly in the direction $(1,1)$ at the point $(1,1)$



- **Second order partial derivatives:**

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right), \quad \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial^2 f}{\partial y \partial x}, \quad \frac{\partial^2 f}{\partial y^2} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right)$$

- $f \in C^2$ if the second order partial derivatives are continuous
- For $f(x_1, x_2, \dots, x_n)$ of n variables, Hessian matrix

$$f''(x) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \dots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \dots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \dots & \frac{\partial^2 f}{\partial x_n^2} \end{pmatrix}$$

- **Example:** Let $f(x, y) = x^3 + x^2y^2 + y^4$, then

$$\frac{\partial f}{\partial x} = 3x^2 + 2xy^2,$$

$$\frac{\partial f}{\partial y} = 2x^2y + 4y^3$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial}{\partial x} (3x^2 + 2xy^2) = 6x + 2y^2,$$

$$\frac{\partial^2 f}{\partial y^2} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial y} (2x^2y + 4y^3) = 2x^2 + 12y^2$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial x} (2x^2y + 4y^3) = 4xy,$$

$$\frac{\partial^2 f}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right) = \frac{\partial}{\partial y} (3x^2 + 2xy^2) = 4xy = \frac{\partial^2 f}{\partial x \partial y}$$

- **Note:** $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$

- **Hessian matrix:** $f''(x) = \begin{pmatrix} 6x + 2y^2 & 4xy \\ 4xy & 2x^2 + 12y^2 \end{pmatrix}$ is a symmetric matrix

- **Example:** Let $f \in C^2$ and $g(x, y) = f(xy)$, then

$$\frac{\partial g}{\partial x} = yf'(xy), \quad \frac{\partial g}{\partial y} = xf'(xy)$$

$$\frac{\partial^2 g}{\partial^2 x} = y^2 f''(xy), \quad \frac{\partial^2 g}{\partial x \partial y} = f'(xy) + xyf''(xy), \quad \frac{\partial^2 g}{\partial^2 y} = x^2 f''(xy)$$

- **Example:** A function of two variables appearing in many economic models is

$$q = f(K, L) = AK^\alpha L^\beta, \quad A, 0 < \alpha < 1, 0 < \beta < 1 \text{ are constants}$$

where K =capital, L =labor, and q =number of units produced.

- f is generally called a **Cobb-Douglas function**, it is most often used to describe certain production processes
- The two partial derivatives $\frac{\partial q}{\partial K} = A\alpha K^{\alpha-1}L^\beta$ and $\frac{\partial q}{\partial L} = A\beta K^\alpha L^{\beta-1}$ are called the marginal product of capital and labor respectively
- Differentiating a second time we obtain: $\frac{\partial^2 q}{\partial L^2} = A\beta(\beta - 1)K^\alpha L^{\beta-2} < 0$, or the marginal product of labor is decreasing (diminishing productivity of labor).
- Verify similarly that there is diminishing productivity of capital.

3. Comparative-static analysis

- Comparative-static analysis deals with how the equilibrium value of an endogenous variables (variables solved from the model) change when there is a change of the exogenous variables (variables determined by forces external to the model) or parameters.
- **Example 1:** Single-good equilibrium model

$$\begin{cases} Q = a - bP & a, b > 0 \quad [\text{demand}] \\ Q = -c + dP & c, d > 0 \quad [\text{supply}] \end{cases}$$

with solution (P^*, Q^*) , where

$$P^* = \frac{a + c}{b + d}, \quad Q^* = \frac{ad - bc}{b + d}$$

- How will P^* and Q^* change when there is a change of the parameters?

$$\frac{\partial P^*}{\partial a} = \frac{1}{b + d} > 0, \quad \frac{\partial P^*}{\partial b} = -\frac{a + c}{(b + d)^2} < 0$$
$$\frac{\partial P^*}{\partial c} = \frac{1}{b + d} > 0, \quad \frac{\partial P^*}{\partial d} = -\frac{a + c}{(b + d)^2} < 0,$$

- **Example 2:** National income model with taxes:

$$\begin{cases} Y = C + I_0 + G_0 \\ C = \alpha + \beta Y^d & (\alpha > 0, 0 < \beta < 1) \\ T = \gamma + \delta Y & (\gamma > 0, 0 < \delta < 1) \end{cases}$$

Here $Y^d = Y - T$ is disposable income, β is marginal propensity to consume, δ is income tax rate.

- The equilibrium income is $Y^* = \frac{\alpha - \beta\gamma + I_0 + G_0}{1 - \beta + \beta\delta}$, thus $\frac{\partial Y^*}{\partial G_0} = \frac{1}{1 - \beta + \beta\delta} > 1$

The term $\frac{1}{1 - \beta + \beta\delta}$ is called the government-expenditure multiplier: \$1 million increase in government-expenditure will lead to more than \$1 million increase in national income.

For example, if $\beta = 0.9, \delta = 0.3$, then $\frac{1}{1 - \beta + \beta\delta} = 2.7$.

- In addition

$$\frac{\partial Y^*}{\partial \delta} = -\beta \frac{\alpha - \beta\gamma + I_0 + G_0}{(1 - \beta + \beta\delta)^2} = -\frac{\beta Y^*}{1 - \beta + \beta\delta} < 0$$

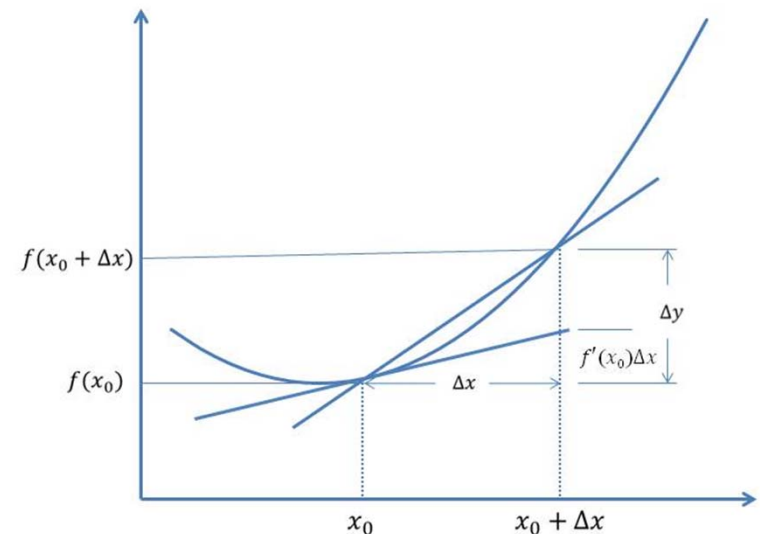
or, an increase in the income tax rate δ will lower the equilibrium income Y^* .

4. Differentials

- Recall $f'(x_0) = \lim_{\Delta x \rightarrow 0} \frac{\Delta y}{\Delta x}$, when Δx is very small, $f'(x_0) \approx \frac{\Delta y}{\Delta x}$, or equivalently, $\Delta y \approx f'(x_0)\Delta x$
- Example: for $y = f(x) = x^2$ at $x_0 = 1$, $f'(x_0) = 2x_0 = 2$

Δx	Δy	$f'(x_0)\Delta x$	Difference
0.1	0.21	0.2	0.01
0.01	0.0201	0.02	0.0001

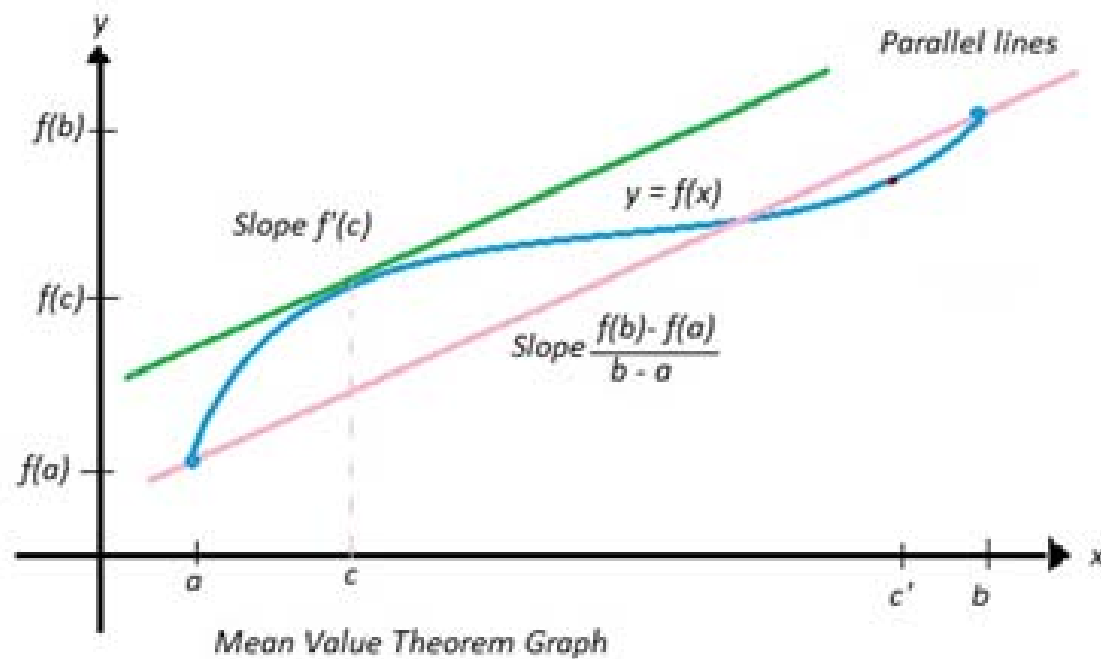
when Δx is small, Δy is very close to $f'(x_0)\Delta x$



- Another way to understand the approximation is through the **Mean Value Theorem**.

- **Mean Value Theorem:** If $f \in C^1$, then there is at least one c between a and b such that

$$f'(c) = \frac{f(b) - f(a)}{b - a}$$



- **Differential** for one-variable function $y = f(x)$ at $x = x_0$:

$$dy(\text{or } df) = f'(x_0)dx,$$

here dx stands for a very small change in x

- The definition of differential coincides with the notation $\frac{dy}{dx} = f'(x)$
- Note: it is not meaningful to write $dy = f'(x)$
- Using the notation of differential, if $y = f(g(x))$, then by the chain rule $y' = f'(g(x))g'(x)$, thus $dy = f'(g(x))g'(x)dx = f'(u)du$ ($u = g(x)$)
- Example: $y = f(x^2)$, let $u = x^2$, $du = 2xdx$
thus $dy = f'(u)du = f'(x^2)2xdx$, $\frac{dy}{dx} = 2xf'(x^2)$

Price (point) Elasticity of demand

- By what percentage the quantity demanded changes when the price increases by 1%? This number is independent of the units in which both quantities and prices are measured.
- Let $x = x(p)$ be the quantity demanded at price p , the elasticity of $x(p)$ with respect to p is

$$\varepsilon_{xp} = \frac{dx / x}{dp / p} = \frac{p}{x} \cdot \frac{dx}{dp} = \frac{d \ln x}{d \ln p}$$

- **Example:** Assume $x(p) = a - bp$, where $a, b > 0$ are constants,

$$\frac{dx}{dp} = -b, \quad \varepsilon_{xp} = \frac{p}{x} \cdot \frac{dx}{dp} = -\frac{bp}{x} = -\frac{bp}{a - bp}$$

- **Example:** Assume $x(p) = Ap^b$ where $A > 0$ and b are constants.

$$\frac{dx}{dp} = Abp^{b-1}, \quad \varepsilon_{xp} = \frac{p}{x} \cdot \frac{dx}{dp} = \frac{p}{x} Abp^{b-1} = b$$

Alternatively,

$$\ln x = \ln(A) + b \ln p, \quad \text{thus } \varepsilon_{xp} = \frac{d \ln x}{d \ln p} = b$$

5. Total differentials

- The concept of differential can be easily generalized to a function of two or more variables.
- Let $z = f(x, y)$ be a function of two variables.
 - When there is a small change (Δx) in x while holding y as constant, the change in z is
 $\Delta z \approx f'_x \Delta x$, in differential format: $dz = f'_x dx$
 - likewise, when there is small change in y while x is held constant,
 $\Delta z \approx f'_y \Delta y$, thus $dz = f'_y dy$
 - When there is a small change in both x and y , the change in z is
 $\Delta z \approx f'_x \Delta x + f'_y \Delta y$
 - **Total differential** for two-variable function $z = f(x, y)$:
 $dz(\text{or } df) = f'_x dx + f'_y dy$

- **Example:** Consider the Cobb-Douglas production function $Q = 4K^{\frac{1}{2}}L^{\frac{1}{2}}$
when $K = K_0 = 100$ and $L = L_0 = 25$, output is $Q = 4(100)^{\frac{1}{2}}(25)^{\frac{1}{2}} = 200$
- Compute the partial derivatives

$$\frac{\partial Q}{\partial K} = 2K^{-\frac{1}{2}}L^{\frac{1}{2}}, \quad \frac{\partial Q}{\partial L} = 2K^{\frac{1}{2}}L^{-\frac{1}{2}}$$

- Thus, $\frac{\partial Q}{\partial K}(100, 25) = 1, \quad \frac{\partial Q}{\partial L}(100, 25) = 4$

- if there is small change in K or L

$$\Delta Q \approx \frac{\partial Q}{\partial K}(100, 25) \cdot \Delta K + \frac{\partial Q}{\partial L}(100, 25) \cdot \Delta L = 1 \cdot \Delta K + 4 \cdot \Delta L$$

- If L is held constant, and K is increased by $\Delta K = 1$, Q will increase by approximately $1 \cdot \Delta K = 1$, thus $Q(101, 25) \approx 200 + 1 = 201$ which is a good approximation to $Q(101, 25) = 200.9975$
- If K is held constant and $\Delta L = -1$, $\Delta Q \approx 4 \cdot \Delta L = -4$, thus $Q(100, 24) \approx 200 - 4 = 196$, a good approximation to $Q(100, 24) = 195.9592$
- If there are small changes to both variables, $\Delta K = 1, \Delta L = -1$, then

$$Q \approx 200 + \left(\frac{\partial Q}{\partial K}\right)(100, 25) \cdot \Delta K + \left(\frac{\partial Q}{\partial L}\right)(100, 25) \cdot \Delta L = 197$$

which is good approximation to the exact value of $Q(101, 24) = 196.9365$

- **Example:** Find the total differential of $f(x, y) = x^3 + x^2y^2 + y^4$,

$$\frac{\partial f}{\partial x} = 3x^2 + 2xy^2, \quad \frac{\partial f}{\partial y} = 2x^2y + 4y^3$$

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy = (3x^2 + 2xy^2)dx + (2x^2y + 4y^3)dy$$

- **Example:** Find the total differential of $f(x, y) = \frac{x+y}{2x^2}$

$$\frac{\partial f}{\partial x} = \frac{1}{2} \frac{(1)(x^2) - (x+y)(2x)}{(x^2)^2} = -\frac{x+2y}{2x^3}, \quad \frac{\partial f}{\partial y} = \frac{1}{2x^2}$$

$$df = -\frac{x+2y}{2x^3}dx + \frac{1}{2x^2}dy$$

Rules of differentials

1. Constant-function rule: $dk = 0$
2. Power-function rule $d(cu^n) = cnu^{n-1}du$
3. sum-difference rule $d(u \pm v) = du \pm dv$
4. product rule $d(uv) = vdu + u dv$
5. quotient rule $d\left(\frac{u}{v}\right) = \frac{1}{v^2}(vdu - u dv)$

- **Example (revisit):** Find the total differential of $f(x, y) = x^3 + x^2y^2 + y^4$,

$$\begin{aligned}
 df &= d(x^3) + d(x^2y^2) + d(y^4) \quad [\text{by Rule 3}] \\
 &= d(x^3) + y^2d(x^2) + x^2dy^2 + d(y^4) \quad [\text{by Rule 4}] \\
 &= 3x^2dx + 2xy^2dx + 2x^2ydy + 4y^3dy \quad [\text{by Rule 2}] \\
 &= (3x^2 + 2xy^2)dx + (2x^2y + 4y^3)dy
 \end{aligned}$$

- **Example (revisit):** Find the total differential of $f(x, y) = \frac{x+y}{2x^2}$

$$\begin{aligned}
 df &= \frac{1}{(2x^2)^2} (2x^2d(x+y) - (x+y)d(2x^2)) \quad [\text{by Rule 5}] \\
 &= \frac{1}{(2x^2)^2} (2x^2(dx+dy) - 4x(x+y)dx) \quad [\text{by Rules 2 and 3}] \\
 &= \frac{1}{4x^4} ((-2x^2 - 4xy)dx + 2x^2dy) \\
 &= -\frac{x+2y}{2x^3}dx + \frac{1}{2x^2}dy
 \end{aligned}$$

6. Total derivatives

- *Case 1:* Consider function $y = f(x, w)$, where $x = g(w)$, this can be combined into a composite function $y = f(g(w), w)$
 - Then $dy = f'_x dx + f'_w dw = f'_x g' dw + f'_w dw$
 - the **total derivative** is $\frac{dy}{dw} = f'_x g' + f'_w$
- **Example:** $y = f(x, w) = 3x - w^2$, where $x = g(w) = e^{2w}$
 - $f'_x = 3, f'_w = -2w, g' = 2e^{2w}$
 - the total derivative is $\frac{dy}{dw} = f'_x g' + f'_w = (3)(2e^{2w}) - 2w = 6e^{2w} - 2w$
 - Check $y = 3e^{2w} - w^2$, $\frac{dy}{dw}$ can then be easily found

- **Case 2:** $y = f(x_1, x_2, w)$, where $x_1 = g(w)$, $x_2 = h(w)$

- Then

$$dy = f_1' dx_1 + f_2' dx_2 + f_w' dw$$

$$= f_1' g' dw + f_2' h' dw + f_w' dw$$

$$\frac{dy}{dw} = f_1' g' + f_2' h' + f_w'$$

- **Example:** Suppose $z = f(x, y, t) = xy + 2t$, where

$$x = g(t) = t^3, y = h(t) = t^2 - t$$

- $f_1' = y = t^2 - t, g' = 3t^2, f_2' = x = t^3, h' = 2t - 1, f_t' = 2,$

- the total derivative is $\frac{dz}{dt} = f_1' g' + f_2' h' + f_t'$

$$= (t^2 - t)(3t^2) + t^3(2t - 1) + 2$$

- Alternatively, we can get the same result by differentiating $z = t^3(t^2 - t) + 2t$

$$\frac{dz}{dt} = (3t^2)(t^2 - t) + t^3(2t - 1) + 2$$

- *Case 3:* $z = f(x, y)$, where $x = g(s, t)$, $y = h(s, t)$

- The total differentials of z, x, y :

$$dz = f'_x dx + f'_y dy$$

$$dx = g'_s ds + g'_t dt, \quad dy = h'_s ds + h'_t dt$$

- Therefore

$$\begin{aligned} dz &= f'_x (g'_s ds + g'_t dt) + f'_y (h'_s ds + h'_t dt) \\ &= (f'_x g'_s + f'_y h'_s) ds + (f'_x g'_t + f'_y h'_t) dt \end{aligned}$$

- and

$$\frac{\partial z}{\partial s} = f'_x g'_s + f'_y h'_s$$

$$\frac{\partial z}{\partial t} = f'_x g'_t + f'_y h'_t$$

- *General version:* suppose $y = f(x_1, \dots, x_n)$ and $x_i = g_i(t_1, \dots, t_m)$ for $i = 1, \dots, n$, then y is a function of t_1, \dots, t_m and

$$\frac{\partial y}{\partial t_i} = f_1 \cdot \frac{\partial x_1}{\partial t_i} + f_2 \cdot \frac{\partial x_2}{\partial t_i} + \dots + f_n \cdot \frac{\partial x_n}{\partial t_i} \text{ for } i = 1, 2, \dots, m$$

- **Example:** assume the following:

$$z = x^2 + xy^3, \quad x = uv^2 + w^3, \quad y = u + ve^w$$

- Then (let $f(x, y) = x^2 + xy^3$)

$$\frac{\partial z}{\partial u} = f_x \cdot \frac{\partial x}{\partial u} + f_y \cdot \frac{\partial y}{\partial u} = (2x + y^3)(v^2) + (3xy^2)(1)$$

$$\frac{\partial z}{\partial v} = f_x \cdot \frac{\partial x}{\partial v} + f_y \cdot \frac{\partial y}{\partial v} = (2x + y^3)(2uv) + (3xy^2)(e^w)$$

$$\frac{\partial z}{\partial w} = f_x \cdot \frac{\partial x}{\partial w} + f_y \cdot \frac{\partial y}{\partial w} = (2x + y^3)(3w^2) + (3xy^2)(ve^w)$$

Example: assume the following: $y = f(tx_1, tx_2, \dots, tx_n)$

- Write $y = f(w_1, \dots, w_n)$, where $w_i = tx_i$ for $i = 1, \dots, n$, then
$$\begin{aligned} dy &= f'_1 dw_1 + \dots + f'_n dw_n \\ &= f'_1 (tdx_1 + x_1 dt) + \dots + f'_n (tdx_n + x_n dt) \\ &= tf'_1 dx_1 + \dots + tf'_n dx_n + (x_1 f'_1 + \dots + x_n f'_n) dt \end{aligned}$$
- Thus $\frac{\partial y}{\partial x_1} = tf'_1, \dots, \frac{\partial y}{\partial x_n} = tf'_n$, and $\frac{\partial y}{\partial t} = x_1 f'_1 + \dots + x_n f'_n$

7. Homogeneous Functions

- Homogeneous functions arise naturally throughout economics.
- A function $f: R_+^n \rightarrow R$ is **homogeneous of degree k** (Chiang 2005, P383) if
$$f(\lambda x_1, \lambda x_2, \dots, \lambda x_n) = \lambda^k f(x_1, x_2, \dots, x_n),$$
for all $(x_1, x_2, \dots, x_n) \in R^n$
- When $k = 1$, f is linearly homogeneous.
- When $k = 0$, f is zero homogeneous.
- **Examples:**
 - $x_1^2 x_2 + 3x_1 x_2^2 + x_2^3$ is homogeneous of degree 3
 - The Cobb-Douglas production function $f(K, L) = AK^\alpha L^\beta$ is homogeneous of degrees $k = \alpha + \beta$
 - The CES function $f(x, y) = (\alpha x^\rho + \beta y^\rho)^{1/\rho}$ is linearly homogeneous

- Production function $f(K, L) = AK^\alpha L^\beta$ is linearly homogeneous,
$$f(\lambda K, \lambda L) = \lambda f(K, L) \quad (3.1)$$

when $\alpha + \beta = 1$.

- taking $\lambda=2$, equation (3.1) says that if the firm doubles all its inputs (K and L), it doubles its output too. For $\lambda = 3$, if the firm triples each input, it triples its corresponding output. Such a firm is said to exhibit **constant returns to scale**.
- Suppose, on the other hand, $k = \alpha + \beta > 1$, if such a firm double the amount of each input, its output would rise by a factor of $2^k > 2$, its output would more than double. Such a firm is said to exhibit **increasing returns to scale**.
- If $k = \alpha + \beta < 1$, such a firm is said to exhibit **decreasing returns to scale**.

- **(Euler's Theorem)** If f is linearly homogeneous, then

$$\sum_{i=1}^n x_i f_i(x_1, \dots, x_n) = f(x_1, \dots, x_n)$$

- **Example:** For the Cobb-Douglas production function

$$f(K, L) = AK^\alpha L^{1-\alpha}$$

we have $f_K(K, L) = A\alpha K^{\alpha-1} L^{1-\alpha}$, $f_L(K, L) = A(1-\alpha)K^\alpha L^{-\alpha}$

- thus
$$Kf_K(K, L) + Lf_L(K, L) = A\alpha K^\alpha L^{1-\alpha} + A(1-\alpha)K^\alpha L^{1-\alpha} \\ = AK^\alpha L^{1-\alpha} = f(K, L)$$

- If $f(x_1, \dots, x_n)$ is homogeneous of degree k , then $f_i(x_1, \dots, x_n)$ is homogeneous of degree $k - 1$
- **Example:** $f(x_1, x_2) = x_1^2 x_2 + 3x_1 x_2^2 + x_2^3$ is homogeneous of degrees 3, $f_1(x_1, x_2) = 2x_1 x_2 + 3x_2^2$ and $f_2(x_1, x_2) = x_1^2 + 6x_1 x_2 + 3x_2^2$ are both homogeneous of degrees 2.

8. Derivatives of implicit functions

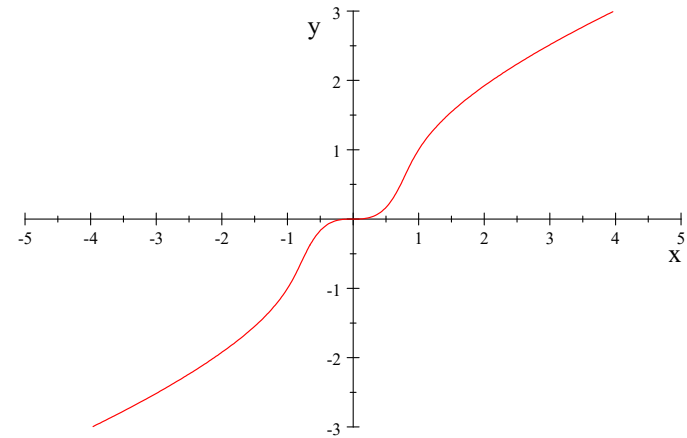
- **Example:** Consider the following relationship

$$y^5 + 3y = 4x^3$$

- obviously, y is an increasing function of x , and it passes through $(1,1)$
- How to find the slope of the tangent at $(1,1)$?
- It is not easy to solve for y in this case, use implicit differentiation, you get

$$5y^4 y' + 3y' = 12x^2, \Rightarrow y' = \frac{12x^2}{5y^4 + 3}$$

- At $(1,1)$, $y' = \frac{12}{5+3} = \frac{3}{2}$



- An implicit function can be written in the form of $F(x, y) = 0$
- Previous example: $F(x, y) = y^5 + 3y - 4x^3$, $F(x, y) = 0$ defines y as a function of x .
- An implicit function does not automatically defines y as a function of x .

Example: Consider the implicit function $F(x, y) = 0$ where

$$F(x, y) = x^2 + y^2 - 25 \quad (3.2)$$

- when $|x| > 5$, there is no y which satisfy (3.2)
- We start with a specific solution (x_0, y_0) of the implicit equation $F(x, y) = 0$ and ask if we vary x a little from x_0 , can we find a y near y_0 that satisfies the equation
- For example, $(x_0, y_0) = (3, 4)$ satisfies $F(x, y) = 0$, and vary x a little, we can find a unique $y = \sqrt{25 - x^2}$ near $y = 4$ that corresponds to the new x
- $(x_0, y_0) = (3, -4)$ also satisfies $F(x, y) = 0$, and vary x a little, we can find a unique $y = -\sqrt{25 - x^2}$ near $y = -4$ that corresponds to the new x
- However, for $(x_0, y_0) = (5, 0)$, if we increase x a little, e.g, $x = 5.001$, there is no corresponding y so that $(5.001, y)$ solves $F(x, y) = 0$; if we decrease x a little to $x_1 = 4.999$, there are two y 's near $y = 0$ which satisfy $F(x_1, y) = 0$, namely $y = \sqrt{25 - 4.999^2}$ and $y = -\sqrt{25 - 4.999^2}$

- For a given implicit function $F(x, y) = 0$ and a specified solution point (x_0, y_0) , we want to know the answers to the following two questions:
 1. Does $F(x, y) = 0$ determine y as a continuous function of x for x near x_0 and y near y_0 ?
 2. If so, how do changes in x affect the corresponding y 's? in other words, what is dy/dx ?

- **Implicit function Theorem:** If the function $F(x, y) \in C^1$, suppose that $F(x_0, y_0) = 0$ and $F_y'(x_0, y_0) \neq 0$, then equation $F(x, y) = 0$ defines y as a continuously differentiable function of x : $y = f(x)$ for (x, y) close to (x_0, y_0) .
 - For $F(x, y) = y^5 + 3y - 4x^3$, $\frac{\partial F(x, y)}{\partial y} = 5y^4 + 3 > 0$ for all (x, y) , $F(x, y) = 0$ defines y as a differentiable function of x for all $x \in \mathbb{R}$.
 - For $F(x, y) = x^2 + y^2 - 25$ and $(x_0, y_0) = (3, 4)$, $F_y'(x_0, y_0) = 2y_0 = 8 \neq 0$, $F(x, y) = 0$ defines y as a differentiable function of x for x close to x_0 .
However, when $y_0 = 0$, ($x_0 = 5$ or -5), you can not find $y = f(x)$ for x close to x_0 .
- When $F(x, y) = 0$ defines y as a differentiable function of x , differentiate the equation gives

$$F_x'(x, y) + F_y'(x, y)y' = 0$$

- or
$$y' = \frac{dy}{dx} = -\frac{F_x'(x, y)}{F_y'(x, y)}$$

- **Example:** $F(x, y) = y^3 + 3x^2y - 13$,

- Let (x_0, y_0) be a point on $F(x, y) = 0$,

- $F_y(x_0, y_0) = 3y_0^2 + 3x_0^2 \neq 0$

- By the implicit function theorem,

$F(x, y) = 0$ defines y as a differentiable function of x .

Take the derivative wrt x :

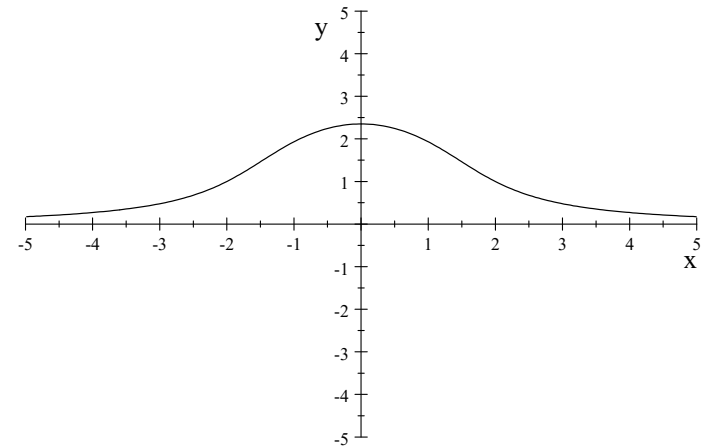
$$3y^2y' + 3(2xy + x^2y') = 0,$$

$$y' = -\frac{2xy}{x^2 + y^2}$$

- $F(x, y) = 0$ passes through the points $(2, 1)$ and $(-2, 1)$

using above formula for y' , we get:

at $(2, 1)$, $y' = -(4/5)$, and at $(-2, 1)$, $y' = (4/5)$



- **Example** (Linear supply and demand model) Suppose that a tax of t per unit is imposed on consumers, then

$$\begin{cases} Q^d = a - b(P + t) \\ Q^s = -c + dP \end{cases}$$

Here a, b, c and d are positive parameters

- The equilibrium price (P^*) is determined by equating the supply and demand

$$a - b(P^* + t) = -c + dP^* \Rightarrow P^* = \frac{a + c - bt}{b + d}$$

- Differentiate wrt t :

$$\frac{dP^*}{dt} = -\frac{b}{b + d} < 0$$

i.e., the price received by the producer will go down if the tax rate t increases

- On the other hand

$$\begin{aligned} \frac{d(P^* + t)}{dt} &= \frac{dP^*}{dt} + 1 = \frac{d}{b + d} \\ \Rightarrow 0 &< \frac{d(P^* + t)}{dt} < 1 \end{aligned}$$

i.e., the consumer price increases, but by less than the increase in the tax

- **Example** (non-linear supply and demand model): Assume that

$$Q^d = f(P + t), Q^s = g(P)$$

where f and g are differentiable functions with $f' < 0$ and $g' > 0$

- The equilibrium price (P^*) now satisfies

$$f(P^* + t) = g(P^*), \text{ or } F(P^*, t) = 0, \quad (3.3)$$

where $F(P, t) = f(P + t) - g(P)$

- Since $\frac{\partial F}{\partial P} = f'(P + t) - g'(P) < 0$, so $F(P^*, t) = 0$ defines P^* implicitly as a differentiable function of t
- Differentiate the equilibrium condition (3.3) with respect to t gives

$$f'(P^* + t) \left(\left(\frac{dP^*}{dt} \right) + 1 \right) = g'(P^*) \left(\frac{dP^*}{dt} \right)$$

$$\frac{dP^*}{dt} = \frac{f'(P^* + t)}{g'(P^*) - f'(P^* + t)} < 0$$

- Moreover $\frac{d(P^* + t)}{dt} = \frac{g'(P^*)}{g'(P^*) - f'(P^* + t)}$
- Thus, $0 < \frac{d(P^* + t)}{dt} < 1$

- **Generalization of the implicit function theorem to multi-variable:** If the function $F(x_1, x_2, \dots, x_m, y)$ is continuously differentiable. Suppose further that $F(x_1^0, x_2^0, \dots, x_m^0, y^0) = 0, F_y'(x_1^0, x_2^0, \dots, x_m^0, y^0) \neq 0$, then equation $F(x_1, x_2, \dots, x_m, y) = 0$ defines y as a continuously differentiable function of x_1, x_2, \dots, x_m : $y = f(x_1, x_2, \dots, x_m)$ for $(x_1, x_2, \dots, x_m, y)$ close to $(x_1^0, x_2^0, \dots, x_m^0, y^0)$.
- Since $F(x_1, x_2, \dots, x_m, y) = 0$, take partial derivative wrt x_i ,
- $$F_{x_i} + F_y \frac{\partial y}{\partial x_i} = 0$$

therefore

$$f_{x_i} = \frac{\partial y}{\partial x_i} = -F_{x_i} / F_y \quad \text{for } i = 1, 2, \dots, m$$

- **Example:** Let $F(x, y, z) = x^2 + y^2 + z^2 - 1 = 0$. F has continuous partial derivatives and $\frac{\partial F}{\partial z} = F'_z = 2z \neq 0$ when $z \neq 0$
- From the implicit function Theorem, the equation $F(x, y, z) = 0$ defines z as a continuous function of (x, y) : $z = f(x, y)$.
- Take partial derivatives wrt x and y respectively

$$\begin{cases} 2x + 2z \frac{\partial z}{\partial x} = 0 \\ 2y + 2z \frac{\partial z}{\partial y} = 0 \end{cases}$$

- therefore

$$\frac{\partial z}{\partial x} = -\frac{x}{z}, \frac{\partial z}{\partial y} = -\frac{y}{z}$$

- Generalization of the implicit function theorem to multi-variable, multi-function:

If the functions $F^1(x_1, \dots, x_m, y_1, \dots, y_n), \dots, F^n(x_1, \dots, x_m, y_1, \dots, y_n)$ are continuously differentiable. Suppose further that

$$\begin{cases} F^1(x_1^0, \dots, x_m^0, y_1^0, \dots, y_n^0) = 0 \\ F^2(x_1^0, \dots, x_m^0, y_1^0, \dots, y_n^0) = 0 \\ \vdots \\ F^n(x_1^0, \dots, x_m^0, y_1^0, \dots, y_n^0) = 0 \end{cases} \quad \text{and} \quad |J| = \left| \frac{\partial(F^1, \dots, F^n)}{\partial(y_1, \dots, y_n)} \right| = \begin{vmatrix} \frac{\partial F^1}{\partial y_1} & \frac{\partial F^1}{\partial y_2} & \dots & \frac{\partial F^1}{\partial y_n} \\ \frac{\partial F^2}{\partial y_1} & \frac{\partial F^2}{\partial y_2} & \dots & \frac{\partial F^2}{\partial y_n} \\ \vdots & \vdots & & \vdots \\ \frac{\partial F^n}{\partial y_1} & \frac{\partial F^n}{\partial y_2} & \dots & \frac{\partial F^n}{\partial y_n} \end{vmatrix} \neq 0$$

at $(x_1^0, \dots, x_m^0, y_1^0, \dots, y_n^0)$, then equation

$$F^1(x_1, \dots, x_m, y_1, \dots, y_n) = 0, \dots, F^n(x_1, \dots, x_m, y_1, \dots, y_n) = 0$$

defines (y_1, \dots, y_n) as a continuously differentiable functions of (x_1, x_2, \dots, x_m) :

$$\begin{cases} y_1 = f_1(x_1, \dots, x_m) \\ \vdots \\ y_n = f_n(x_1, \dots, x_m) \end{cases}$$

for $(x_1, \dots, x_m, y_1, \dots, y_n)$ close to $(x_1^0, \dots, x_m^0, y_1^0, \dots, y_n^0)$.

- **Example:** Consider the system of non-linear equations

$$\begin{cases} u^2 + v = xy \\ uv = -x^2 + y^2 \end{cases} \quad (3.4)$$

when does the equations define u, v as differential functions of x and y ? Find the partial derivative of u, v wrt x and y .

- Let
$$\begin{cases} F^1(x, y, u, v) = u^2 + v - xy \\ F^2(x, y, u, v) = uv + x^2 - y^2 \end{cases}$$

then the determinant of Jacobian matrix is $|J| = \left| \frac{\partial(F^1, F^2)}{\partial(u, v)} \right| = \begin{vmatrix} 2u & 1 \\ v & u \end{vmatrix} = 2u^2 - v$

- From the implicit function theorem, when $2u^2 - v \neq 0$, the two equations define u, v as differential functions of x and y
- To find the partial derivatives $\partial u / \partial x$ and $\partial v / \partial x$, take partial derivatives wrt x in (3.4)

$$\begin{cases} 2u \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} = y \\ v \frac{\partial u}{\partial x} + u \frac{\partial v}{\partial x} = -2x \end{cases} \quad \text{or} \quad \begin{pmatrix} 2u & 1 \\ v & u \end{pmatrix} \begin{pmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial v}{\partial x} \end{pmatrix} = \begin{pmatrix} y \\ -2x \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial v}{\partial x} \end{pmatrix} = \begin{pmatrix} 2u & 1 \\ v & u \end{pmatrix}^{-1} \begin{pmatrix} y \\ -2x \end{pmatrix} = \frac{1}{|J|} \begin{pmatrix} u & -1 \\ -v & 2u \end{pmatrix} \begin{pmatrix} y \\ -2x \end{pmatrix} = \frac{1}{|J|} \begin{pmatrix} yu + 2x \\ -yv - 4xu \end{pmatrix}$$