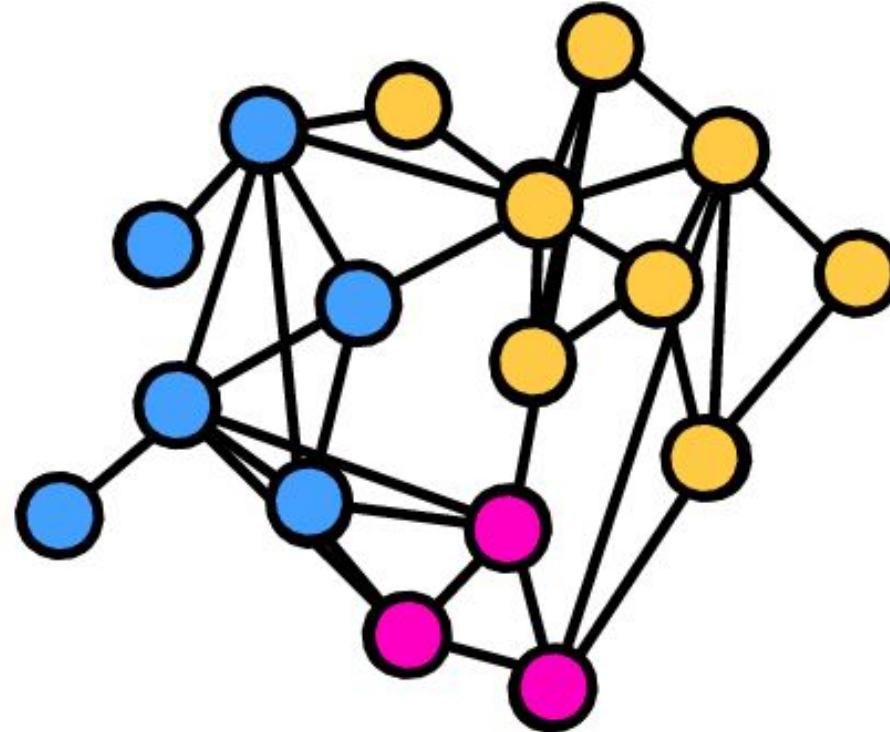
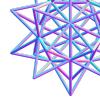


2025

Graphs





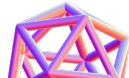
Lecture Flow

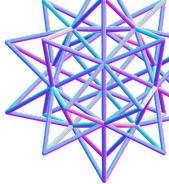
1. Pre-requisites
2. Definition of Graphs
3. Types of Graphs
4. Graph terminologies
5. Checkpoint
- 6) Graph representations
- 7) Graphs & Trees
- 8) Receiving Inputs on Graph Problems
- 9) Practice questions
- 10) Ending quote



Pre-requisites

- Arrays / Linked list
- Matrices
- Dictionaries
- Time and space complexity analysis





What do we mean by Graph?



Definition

- A way to represent **relationships** between objects.
- A collection of **nodes** that have data and are connected to other nodes through edges.



Graph = **Nodes** + **Edges**

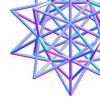


Example: Friendship Graph

- **Nodes or vertices:** The **objects** in graph
 - These people our case
- **Edges:** the **relation** between nodes.
 - The friendship between them (the lines)

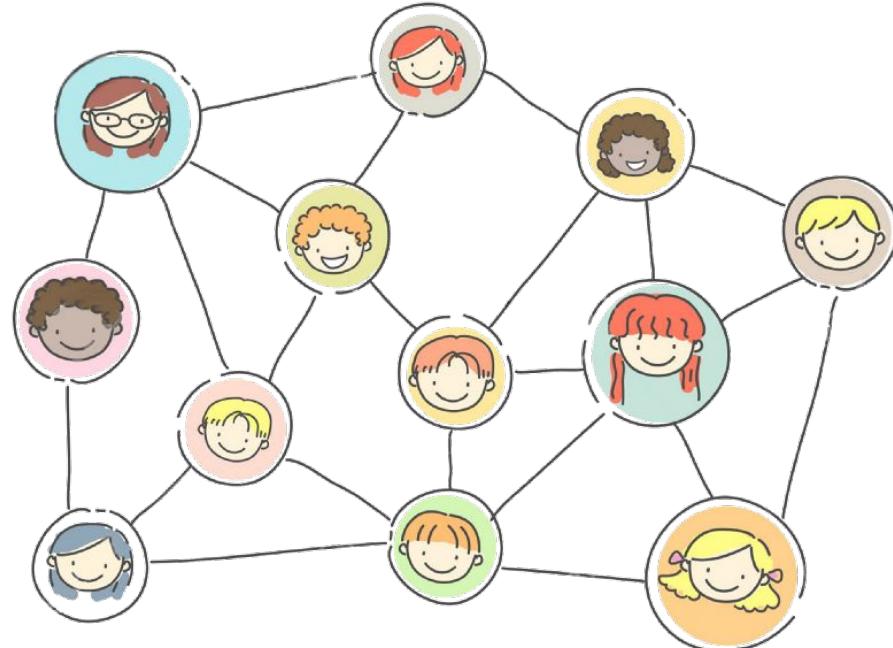


Types of graphs



Undirected Graph

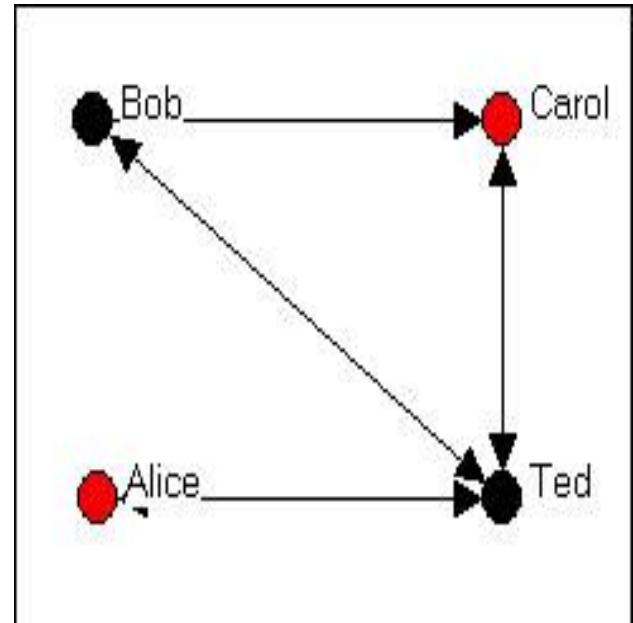
- Facebook friendship
- If Alice is friends with Bob,
Bob is also friends with Alice

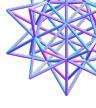




Directed Graph

- Linkedin and instagram "following" relation.
- If Bob follows Carol, that does not mean that Carol follows Bob.

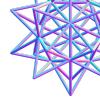




Let's say we want to add a **weight parameter** which represents the strength of the friendship.

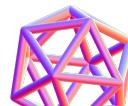
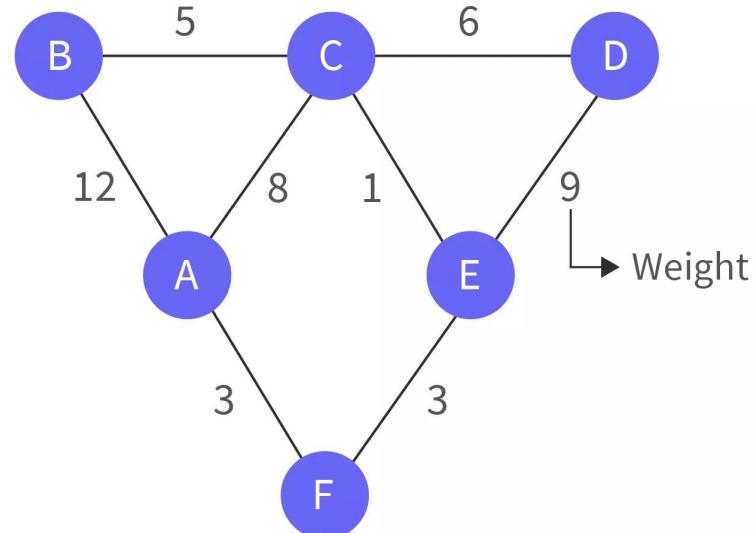


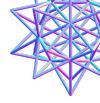
How can we do that?



Weighted Graph

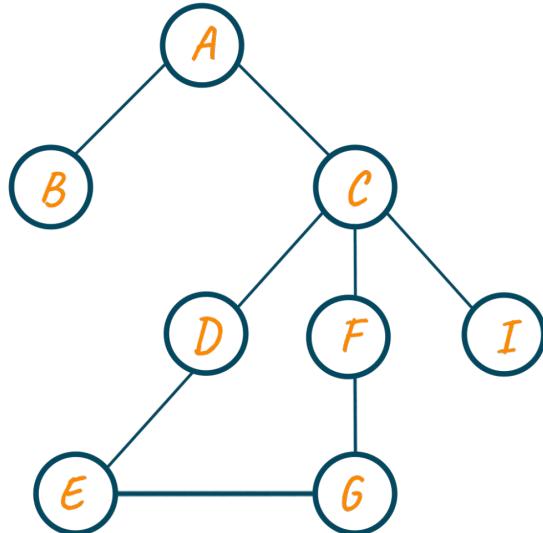
Weighted graphs assign **numerical values** to edges.

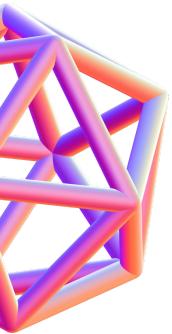
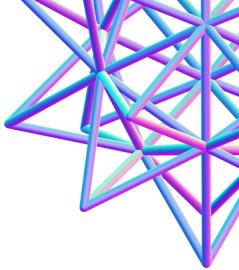




Unweighted Graph

All edges have the **same value**.



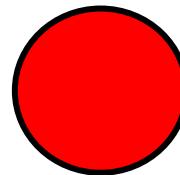
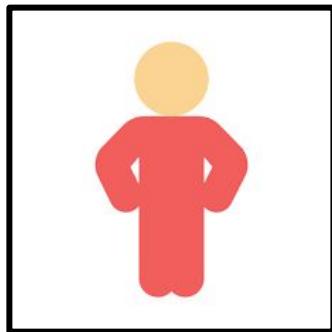


Graph Terminologies



Terminology: Node / Vertex

- Represent entities (e.g., people, devices).
- Connected to other nodes by edges.

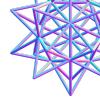




Terminology: Edge

- Connection between two nodes.
- Represented by lines or arrows.
- model relationships in various systems.

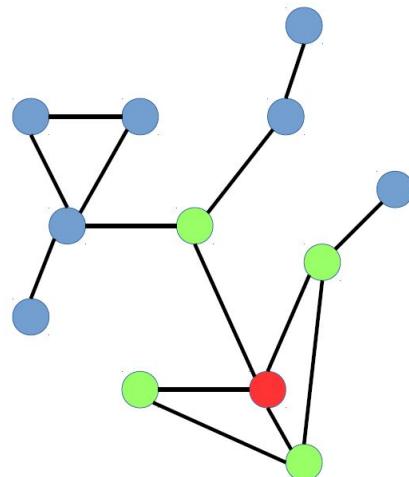


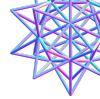


Terminology: Neighbors

- Two nodes are **neighbors** or **adjacent** if there is an edge **between** them

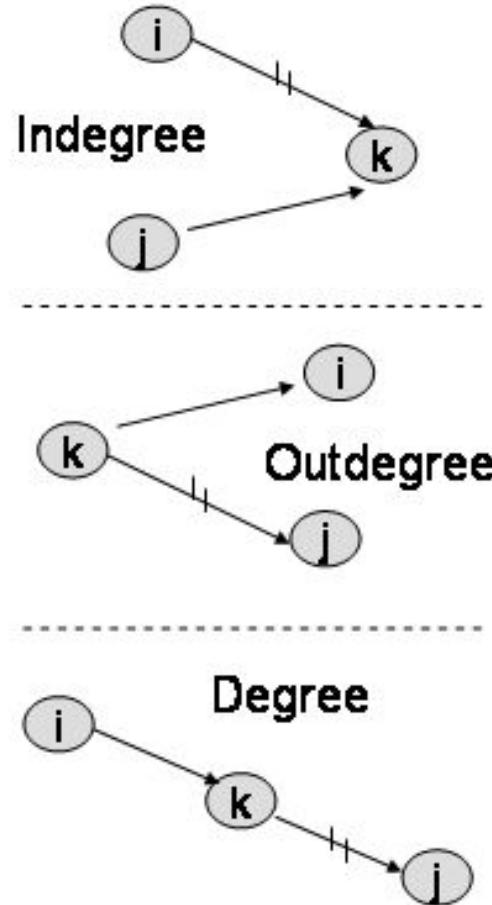
Graph Neighborhood





Terminology: Degree

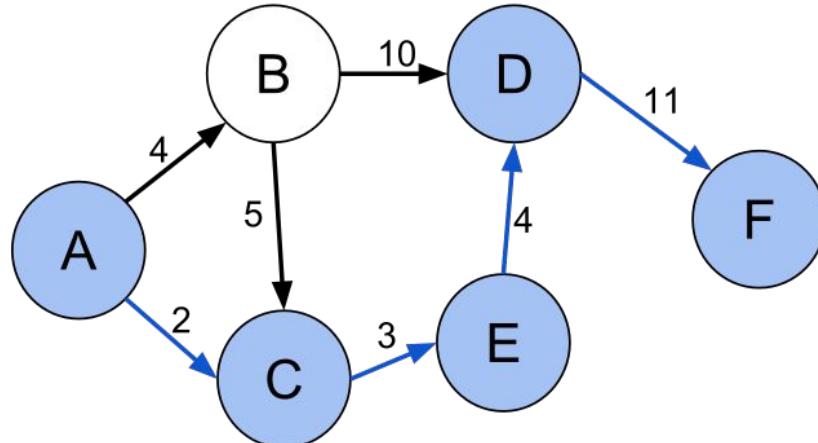
- Node degree = number of neighbors.
- In **directed** graphs, consider node k:
 - **Indegree** of k = edges **ending** at node k.
 - **Outdegree** of k = edges **starting** at node k.

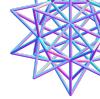




Terminology: Path

- A **path** leads from one node to another.
- The length of a path is the number of edges in it.
- Let's consider the path between node A and node F

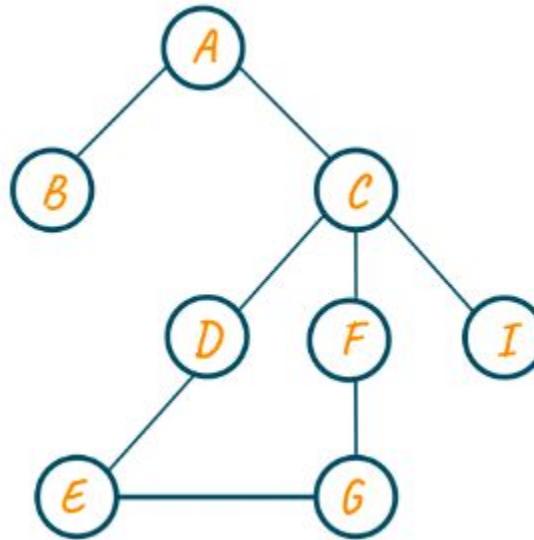




Terminology: Cycle

A path is a **cycle** if the first and the last node of the path is the same.

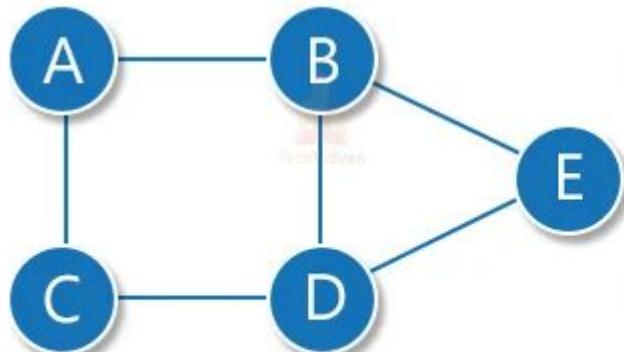
Cycle = C-D-E-G-F-C



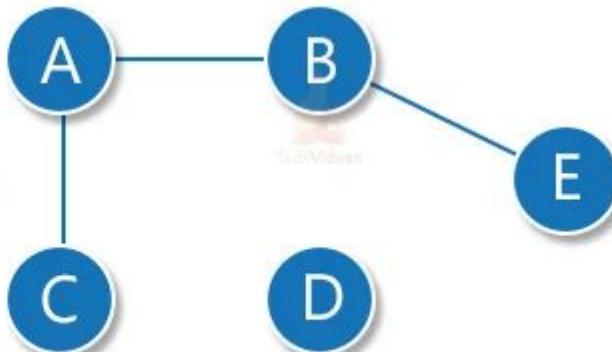


Terminology: Connectivity

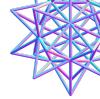
A graph is **connected** if there is a path between any two nodes



Connected graph

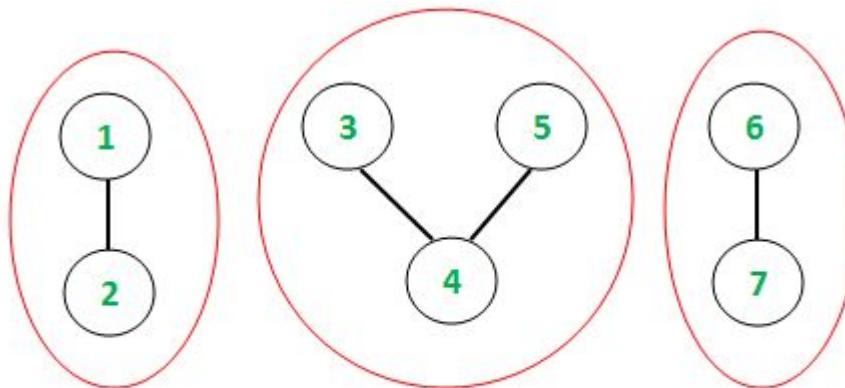


Disconnected graph

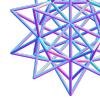


Terminology: Components

The connected parts of a graph are called its **components**.

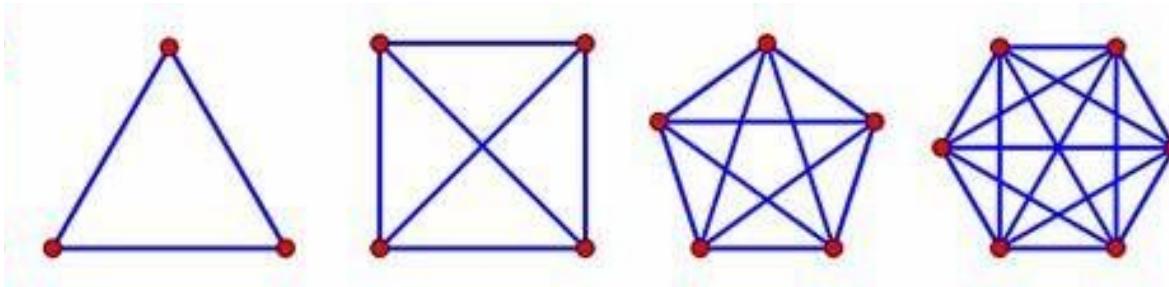


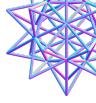
The counts of connected components are - 2, 3 and 2



Terminology: Complete Graph

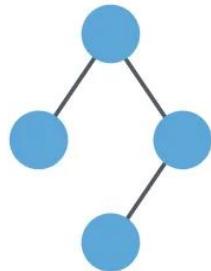
A complete graph is a graph in which **each pair of node** is connected by an edge.



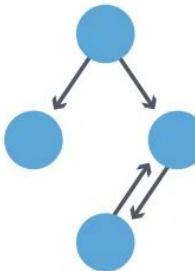


Summary

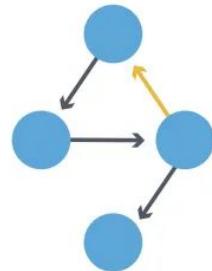
Undirected



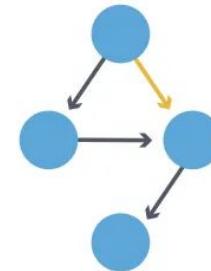
Directed



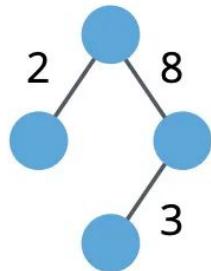
Cyclic



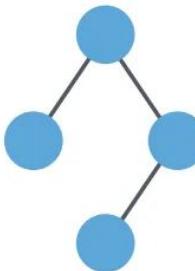
Acyclic



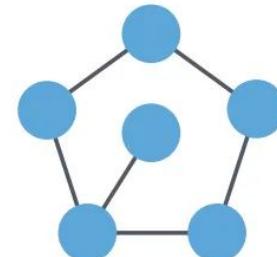
Weighted



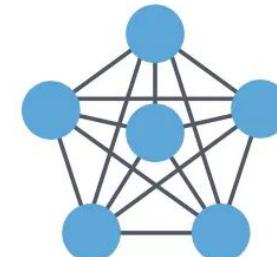
Unweighted



Sparse



Dense





Common Terminologies

Node

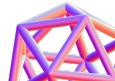
Edge

Path

Cycle

Connectivity

Components





Common Terminologies

Node	Element in a graph.
Edge	Connection between two nodes.
Path	Sequence of edges connecting nodes.
Cycle	Path that starts and ends at the same node.
Connectivity	The ability to reach any node from another.
Components	Independent connected subgraphs.



Common Terminologies

Neighbors

Degree

In-degree

Out-degree

Complete

Traverse





Common Terminologies

Neighbors

Nodes connected by an edge.

Degree

Number of neighbors a node has.

In-degree

Number of edges ending at a node.

Out-degree

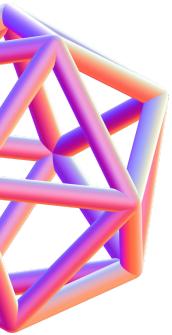
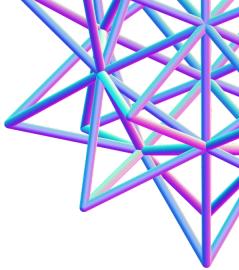
Number of edges starting from a node.

Complete

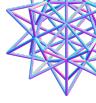
Each node is connected to every other node.

Traverse

Visiting nodes using edges.

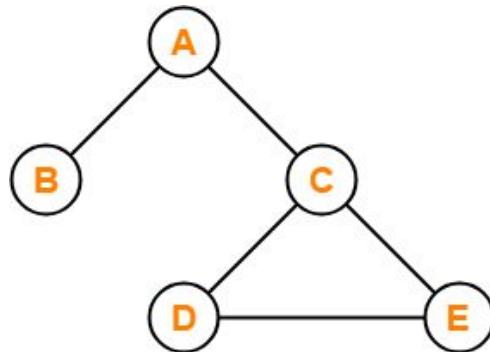


Graph and Tree

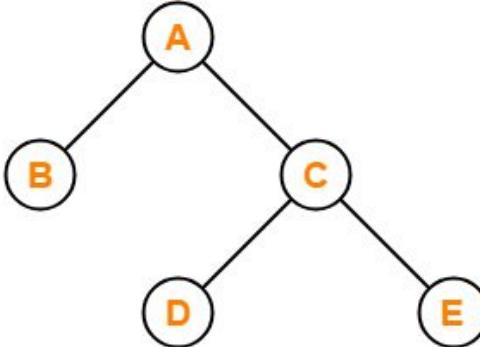


Tree

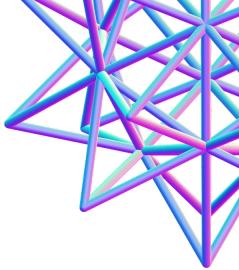
- Tree is special type of graph.
- A tree is a **connected** and **acyclic graph**.
- A tree has a **unique** path between any two vertices.
- How many edges does a tree have?



X



✓



Graph Representations



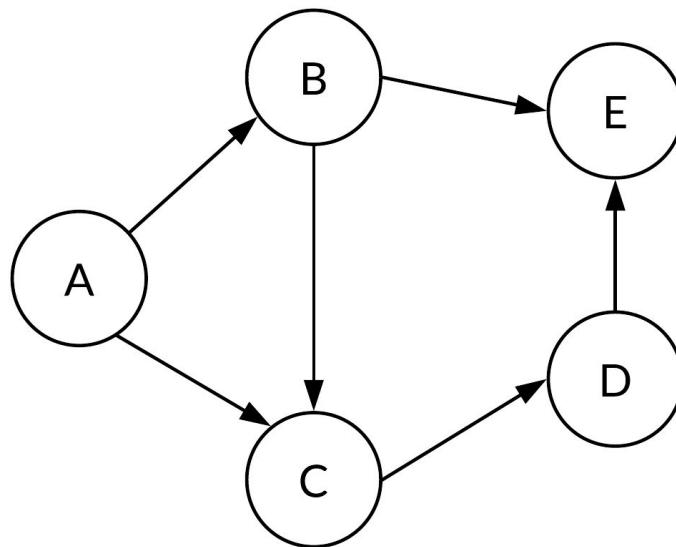
Graph Representations

- Edge List
- Adjacency Matrix
- Adjacency List
- Grids as Graphs



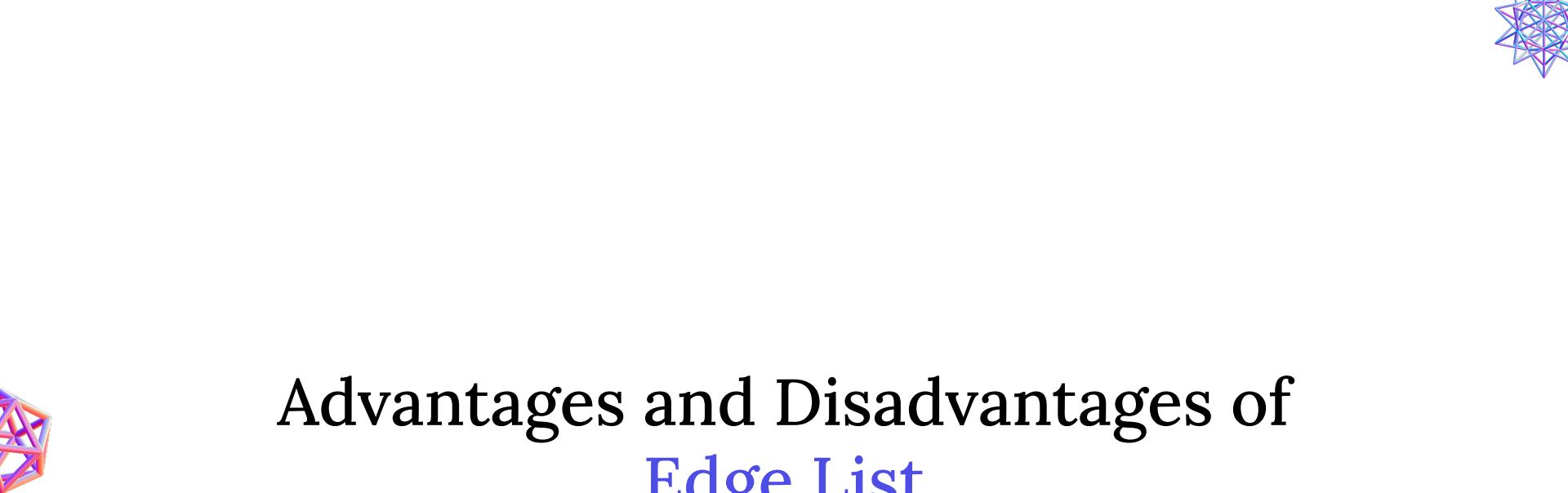


Graph Representation: Edge list

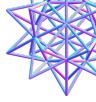


Edge list:

```
graph = [('A', 'B'),  
        ('A', 'C'),  
        ('B', 'C'),  
        ('B', 'E'),  
        ('C', 'D'),  
        ('D', 'E')]
```



Advantages and Disadvantages of Edge List



Graph Representation: Edge list

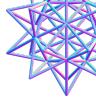
Advantages:

- It uses less memory.
- Easy to represent

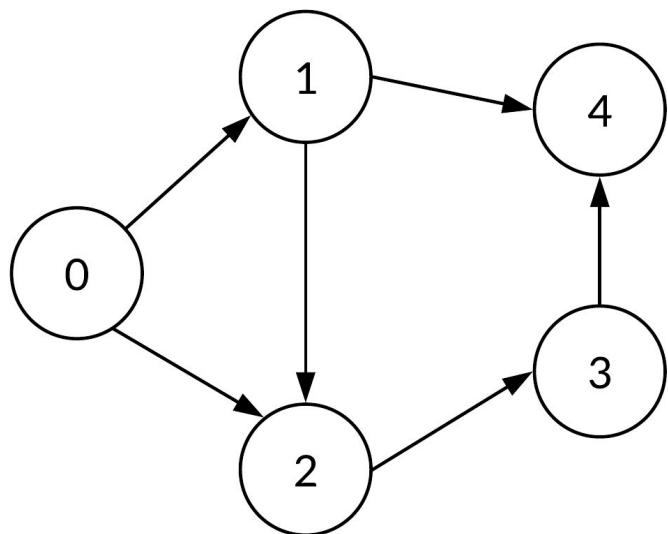
Disadvantages:

- Edge look up is slow
- Hard to traverse





Graph Representation: Adjacency matrix



Adjacency Matrix

	0	1	2	3	4
0	0	1	1	0	0
1	0	0	1	0	1
2	0	0	0	1	0
3	0	0	0	0	1
4	0	0	0	0	0

Graph Representation: Adjacency matrix

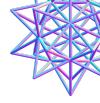
[Leetcode Playground: Convert Edge List to Adjacency Matrix](#)

Implementation

```
def buildAdjacencyMatrix(n, edge_list) -> list[list]:  
  
    # Initialize n x n matrix with zeros  
    matrix = [[0] * n for _ in range(n)]  
    for u, v in edge_list:  
        matrix[u][v] = 1  
        matrix[v][u] = 1  
        # Since the graph is undirected  
  
    return matrix
```



Advantages and disadvantages of Adjacency Matrix



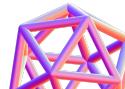
Graph Representation: Adjacency matrix

Advantages:

- To represent **dense** graphs.
- Edge lookup is fast

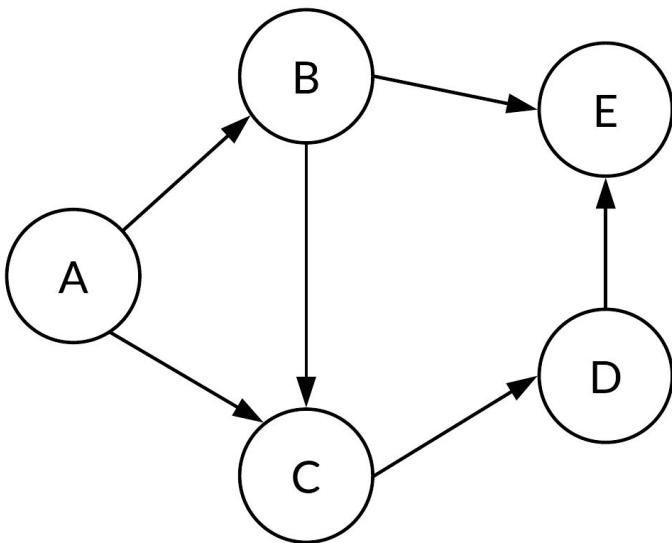
Disadvantages:

- It takes more time to build and consume more memory ($O(N^2)$ for both cases)
- Finding neighbors of a node is costly





Graph Representation: Adjacency List using List



Adjacency list:

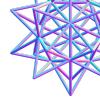
```
graph = {  
    'A': ['B', 'C'],  
    'B': ['C', 'E'],  
    'C': ['D'],  
    'D': ['E'],  
}
```

Graph Representation: Adjacency List

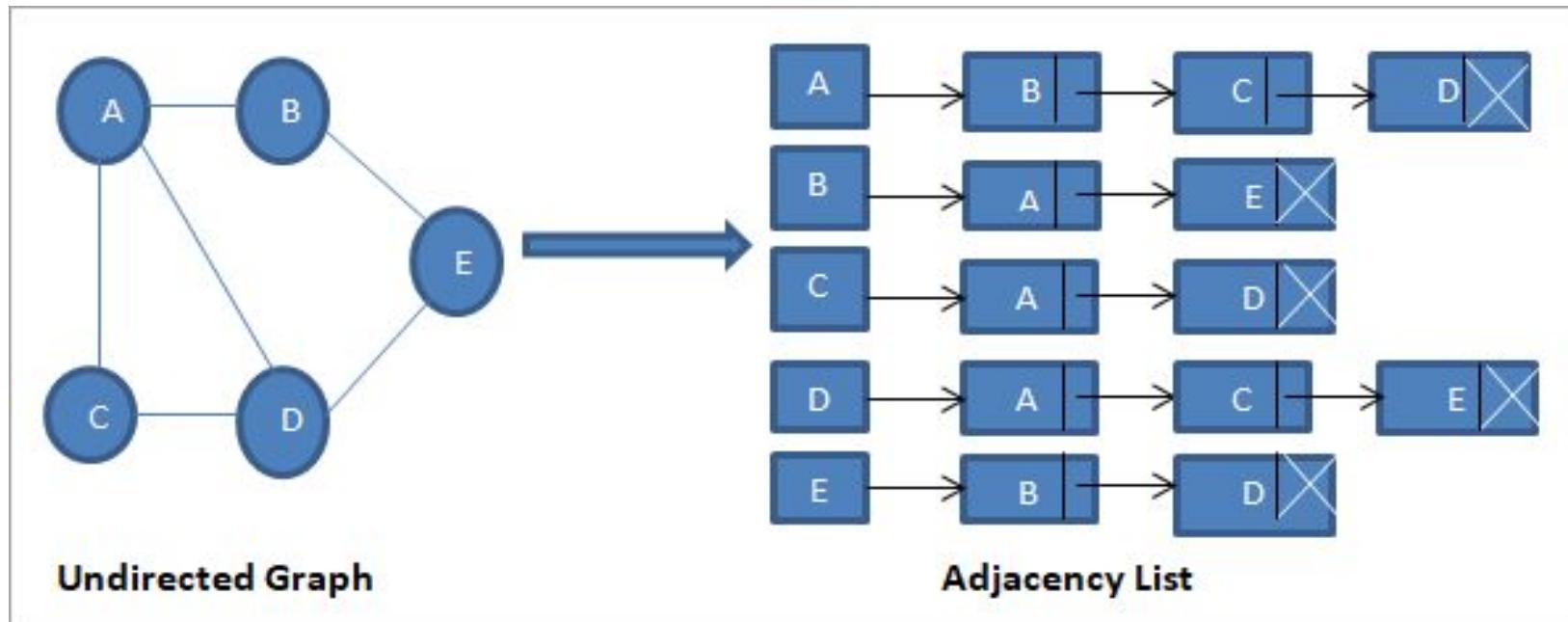
[Leetcode Playground: Convert Edge List to Adjacency List](#)

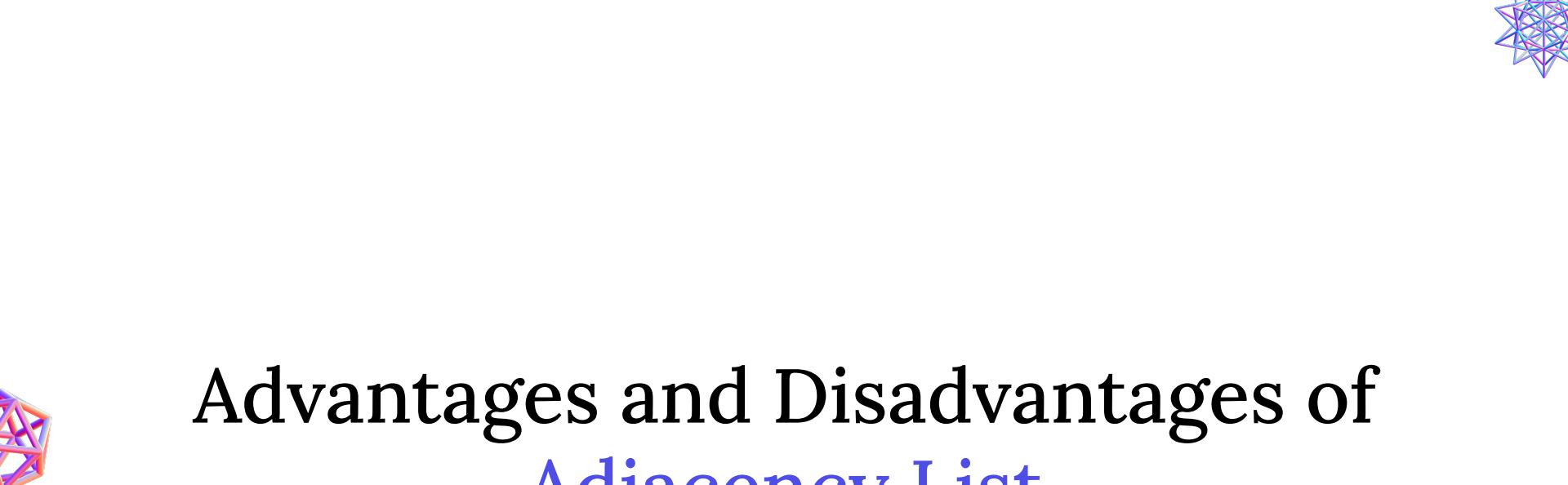
Implementation

```
def buildAdjacencyList(n, edge_list) -> list[list]:  
    graph = [[] for i in range(n)]  
  
    for u, v in edge_list:  
        graph[u].append(v)  
        graph[v].append(u)  
  
    return graph
```



Graph Representation: Adjacency List using Linked List





Advantages and Disadvantages of Adjacency List



Graph Representation: **Adjacency list**

Advantages:

- It uses less memory
- Neighbours of a node can be found pretty fast
- Best for sparse graphs

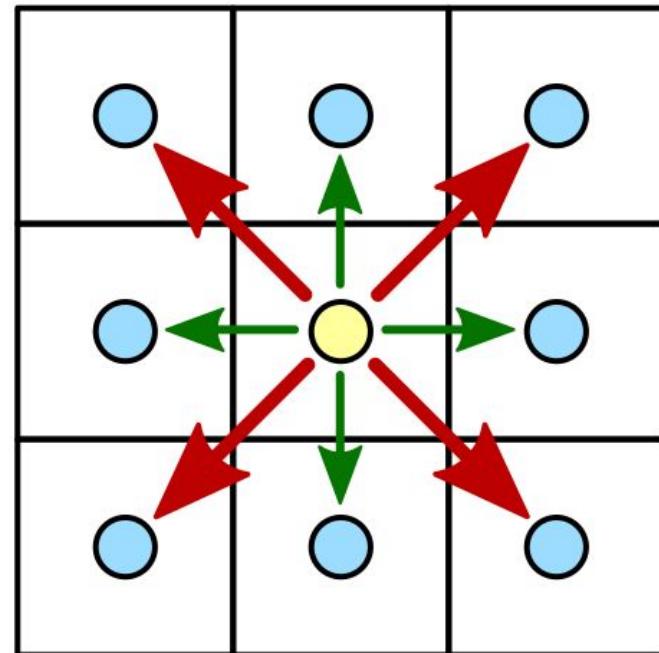
Disadvantages:

- Edge look up is slow



Graph Representation: Grids as Graph

- Matrix cells = **nodes**
- **Edges** between adjacent cells:
 - 4 perpendicular
 - 2 diagonal
 - 2 antidiagonal.





Grids – Direction vectors

The standard square neighborhood

(-1,-1)	(-1, 0)	(-1,+1)
(0, -1)		(0, +1)
(+1,-1)	(+1, 0)	(+1,+1)

Only vertical and horizontal neighbors

	(-1, 0)	
(0, -1)		(0, +1)
	(+1, 0)	

The chess knight neighborhood

	(-2,-1)		(-2,+1)	
(-1,-2)				(-1,+2)
(+1,-2)				(+1,+2)

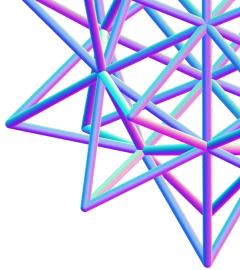


Generic template — 4 Directional Traversal

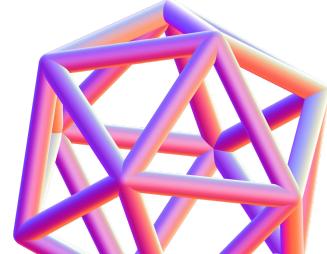
```
# Direction vectors for moving up, down, left, and right
directions = [(-1, 0), (1, 0), (0, -1), (0, 1)]

def is_inbound(x, y, rows, cols):
    """Checks if the given (x, y) position is inside the grid"""
    return 0 <= x < rows and 0 <= y < cols

def traverse_grid(grid):
    rows, cols = len(grid), len(grid[0])
    for i in range(rows):
        for j in range(cols):
            # Explore all 4 directions
            for dx, dy in directions:
                new_x, new_y = i + dx, j + dy
                if is_inbound(new_x, new_y, rows, cols):
                    # Do Something
                    pass
```



Receiving Inputs on Graph Problems





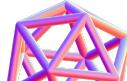
Adjacency List Inputs

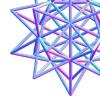


Receiving Inputs: Directed Unweighted Graphs - AL

Input:

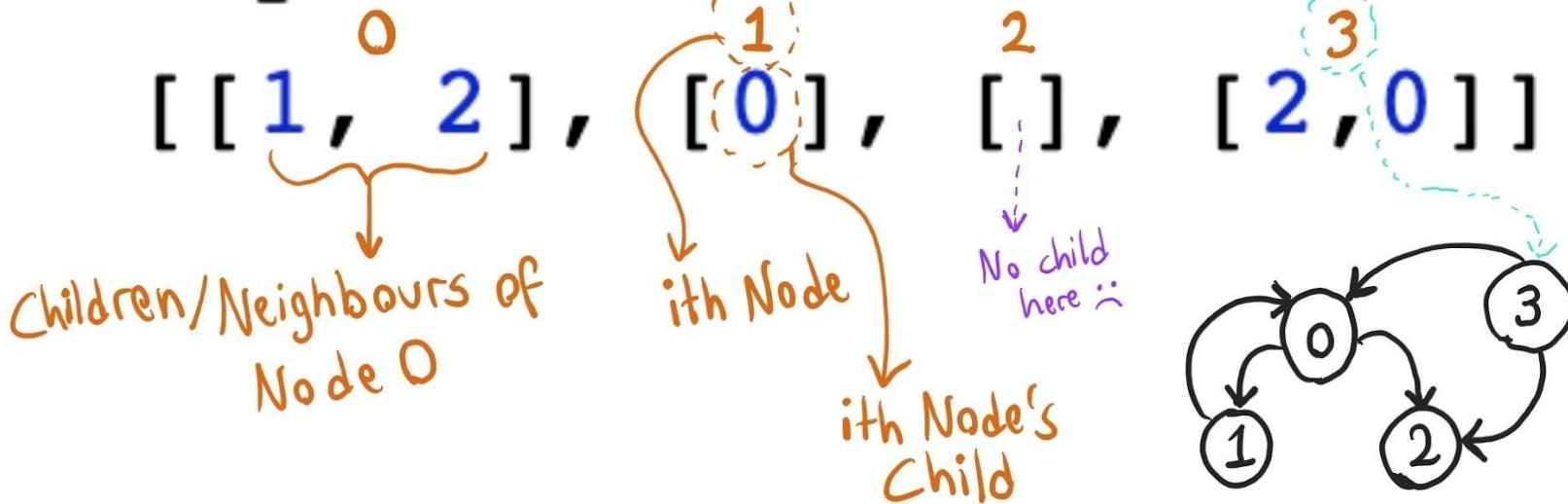
```
[[1, 2], [0], [], [2, 0]]
```





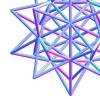
Receiving Inputs: Directed Unweighted Graphs - AL

Input:





Think of ways to implement this



Receiving Inputs: Directed Weighted Graphs - AL

Input:

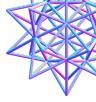
4

3 2,3 1,2 0,5

1 2,5

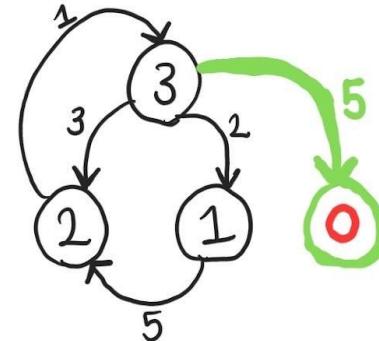
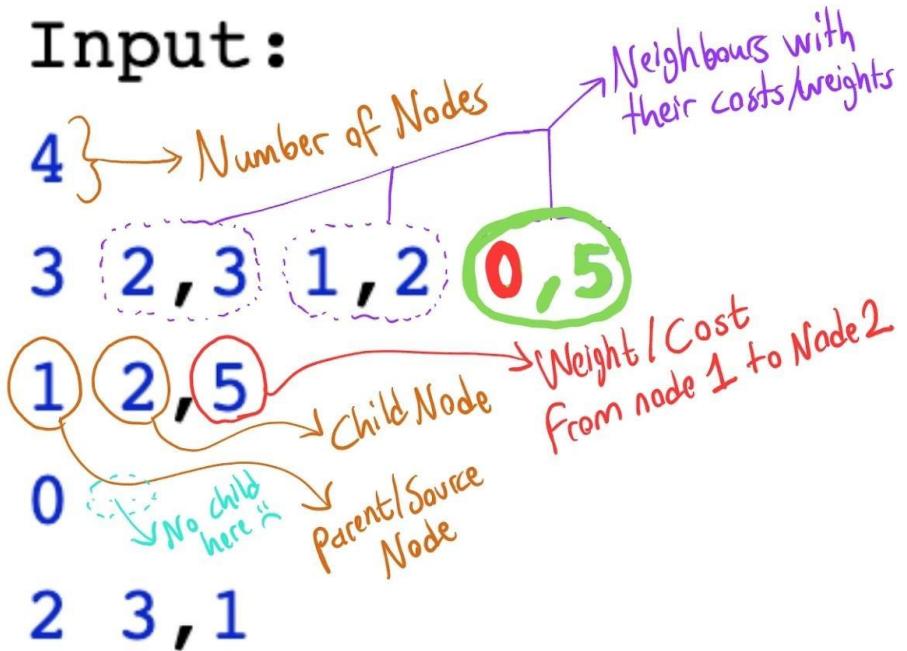
0

2 3,1



Receiving Inputs: Directed Weighted Graphs - AL

Input:



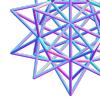


Receiving Inputs: DWG - AL - Implementation

```
from collections import defaultdict

n = int(input())
graph = defaultdict(list)

for i in range(n):
    line = input().split()
    node = int(line[0])
    for neighbor in range(1, len(line)):
        adj_node, weight = map(int, line[neighbor].split(","))
        graph[node].append((adj_node, weight))
```



Receiving Inputs: DWG Complexity Analysis - AL

Time Complexity: $O(n + E)$

Space Complexity: $O(E)$

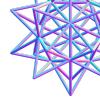
n = number of nodes

E = number of edges





Adjacency Matrix Inputs



Receiving Inputs: Directed Weighted Graphs - AM

Input:

3

0 1 2

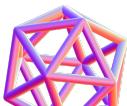
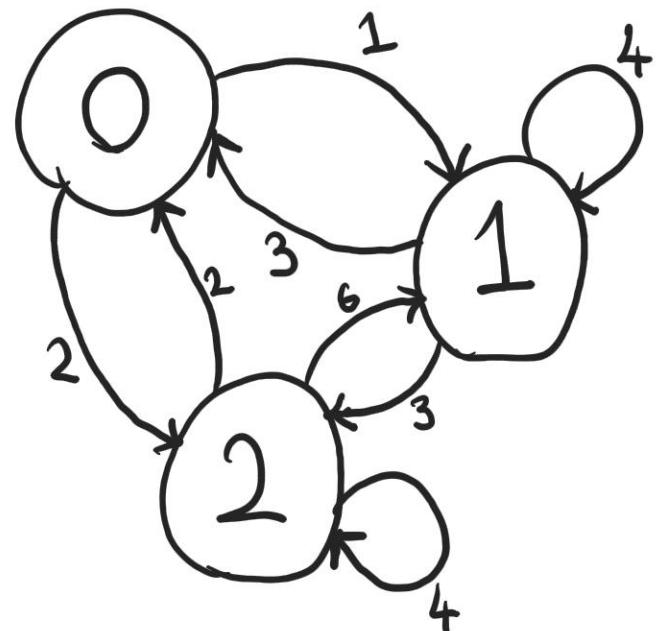
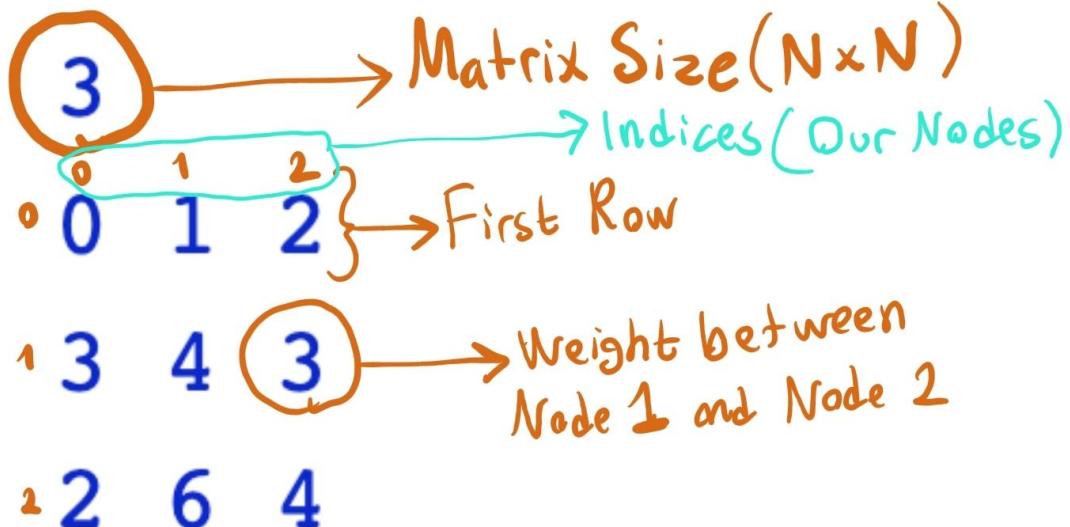
3 4 3

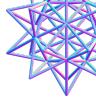
2 6 4



Receiving Inputs: DWG Illustration - AM

Input:





Receiving Inputs: DWG - Implementation - AM

```
from collections import defaultdict

n = int(input())
graph = defaultdict(list)

for i in range(n):
    row = list(map(int, input().split()))

    for j in range(len(row)):
        graph[i].append((j, row[j]))
```

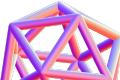


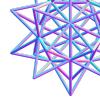


Receiving Inputs: DWG Complexity Analysis - AM

- Time Complexity: $O(n^2)$
- Space Complexity: $O(n^2)$

n = number of **nodes**(matrix length)





Receiving Inputs: Undirected Weighted Graphs - AM

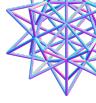
Input:

3

0 1 2

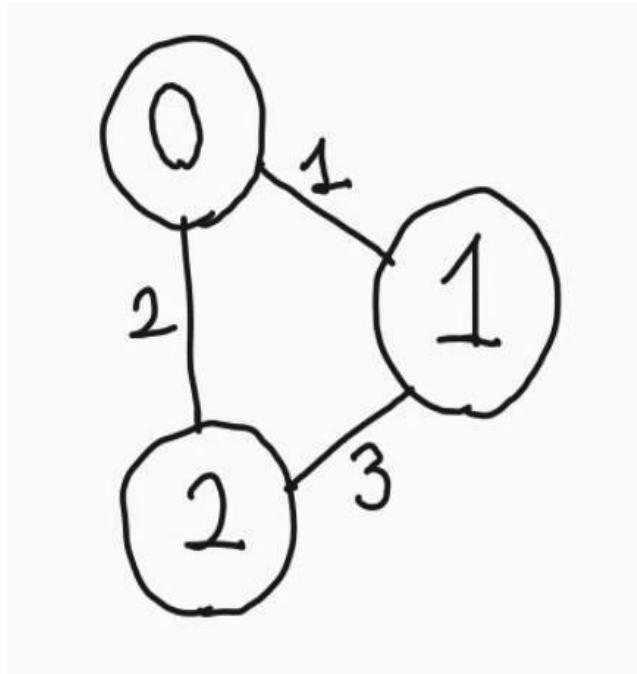
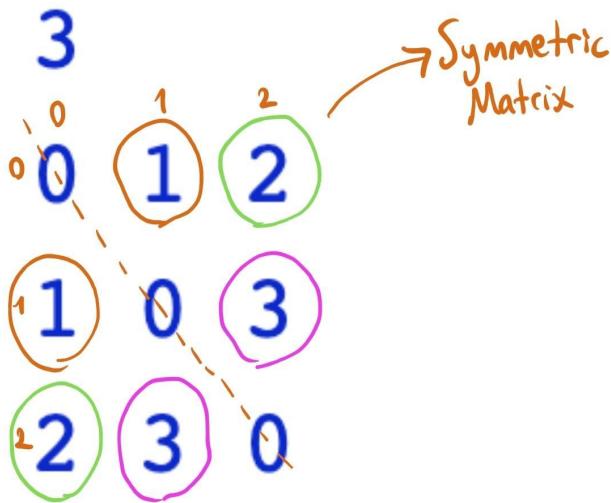
1 0 3

2 3 0



Receiving Inputs: UDWG Illustration - AM

Input:





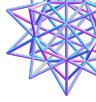
Receiving Inputs: UDWG - Implementation - AM

```
from collections import defaultdict

n = int(input())
graph = defaultdict(list)

for i in range(n):
    row = list(map(int, input().split()))

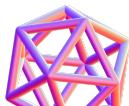
    for j in range(i + 1, len(row)):
        graph[i].append((j, row[j]))
        graph[j].append((i, row[i]))
```

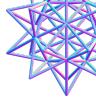


Receiving Inputs: UDWG Complexity Analysis - AM

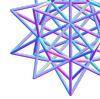
- Time Complexity: $O(n^2)$
- Space Complexity: $O(n^2)$

n = number of **nodes** (matrix length)





Edge List Inputs



Receiving Inputs: Directed Weighted Graphs - EL

Input:

3

1 2 2

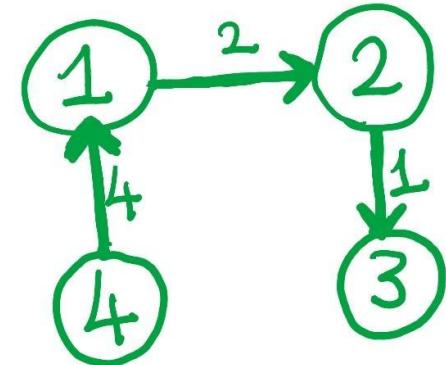
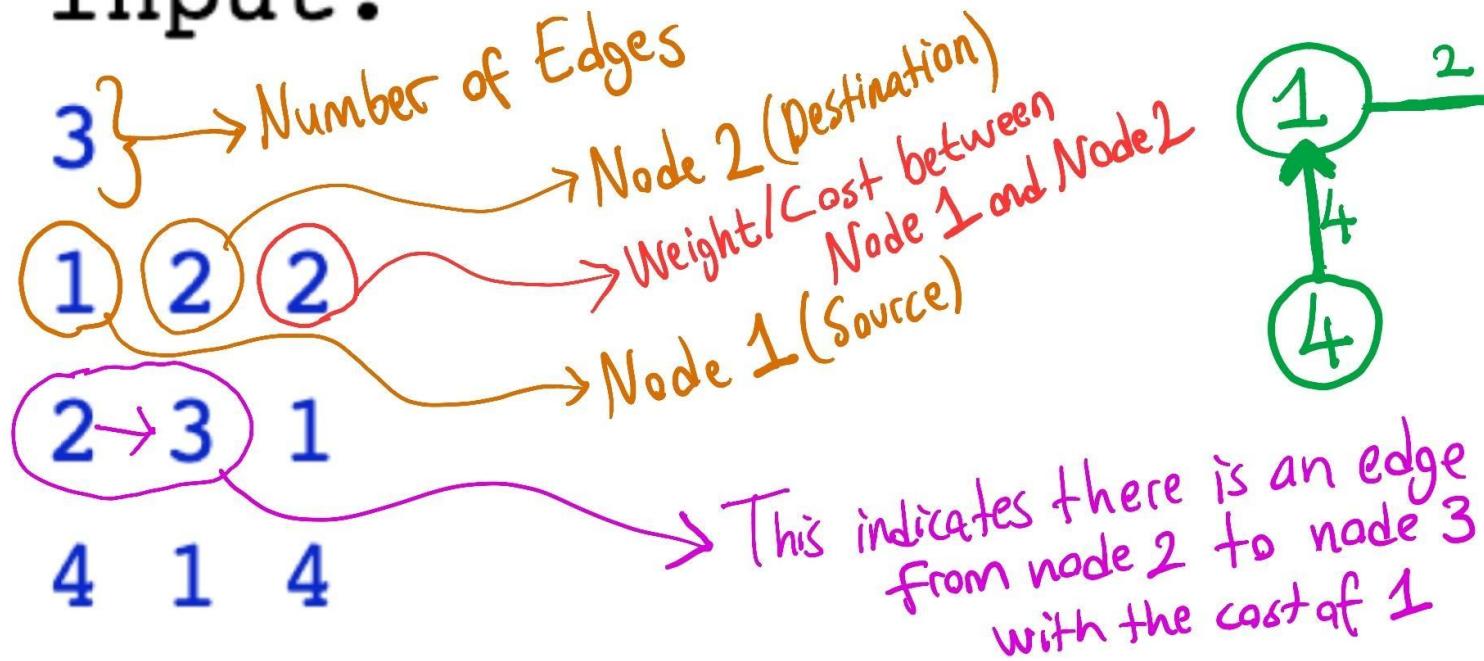
2 3 1

4 1 4



Receiving Inputs: DWG Illustration - EL

Input:





Receiving Inputs: DWG - Implementation - EL

```
from collections import defaultdict

n = int(input())
graph = defaultdict(list)

for i in range(n):
    src, dest, w = list(map(int, input().split()))
    graph[src].append((dest, w))
```



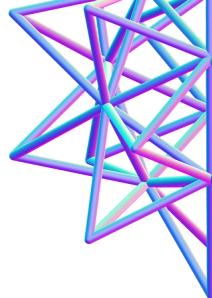


Receiving Inputs: DWG Complexity Analysis - EL

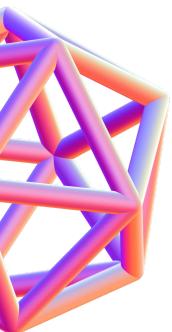
- Time Complexity: $O(E)$
- Space Complexity: $O(E)$

E = number of edges





For Multiple Graph Problems (Generic Templates)





Generic template - I

```
t = int(input()) # number of test cases

for _ in range(t):
    # number of nodes and edges
    n, m = map(int, input().split())
    graph = [[] for _ in range(n)]
    for j in range(m):
        u, v = map(int, input().split())
        graph[u - 1].append(v - 1)
        graph[v - 1].append(u - 1)

    # do something with the graph
```

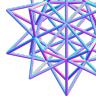


Which kind of input is
the graph?





OR



Generic template - II

```
from collections import defaultdict

t = int(input()) # number of test cases
for _ in range(t):
    # number of nodes and edges
    n, m = map(int, input().split())
    graph = defaultdict(list)
    for j in range(m):
        u, v = map(int, input().split())
        graph[u].append(v)
        graph[v].append(u)
```

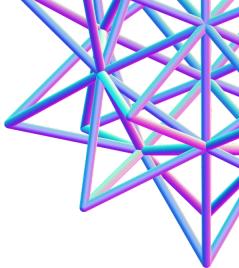


Tip - To make your inputs faster...

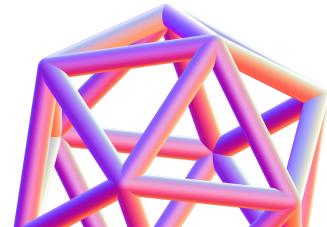
```
import sys  
  
input = sys.stdin.readline().strip()
```

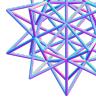
- This replaces the input() function with sys.stdin.readline() which is faster.





Common Pitfalls





Common Pitfalls

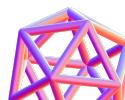
- Not considering cycles in the graph.
- Not checking whether the graph is directed or undirected
- Not understanding input format well
- Falling in to infinite loop (because of cycles)





Types of Graph Questions

- Graph questions can be classified into different categories based on the problem requirements.
- Some common types of graph questions include:
 - Shortest path: find the shortest path between two vertices.
 - Connectivity: determine if there is a path between two vertices.
 - Cycle detection: detect cycles in the graph.
 - Topological sorting: order the vertices in a directed acyclic graph.



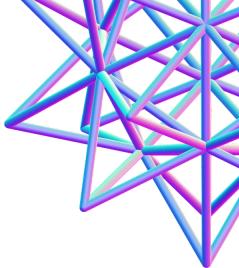


Approaches to Solving Graph Problems

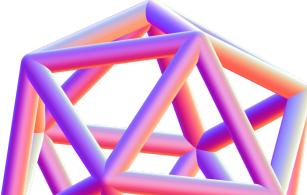
There are several approaches to solving graph problems, including:

- Breadth-first search (BFS)
- Depth-first search (DFS)
- Dijkstra's algorithm
- Bellman-Ford algorithm
- Kruskal's algorithm
- Floyd-Warshall algorithm

The choice of algorithm depends on the **problem's requirements**.



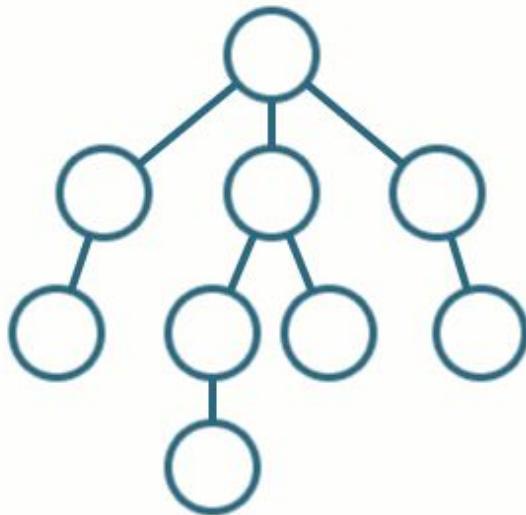
What is next?



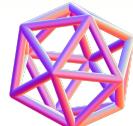
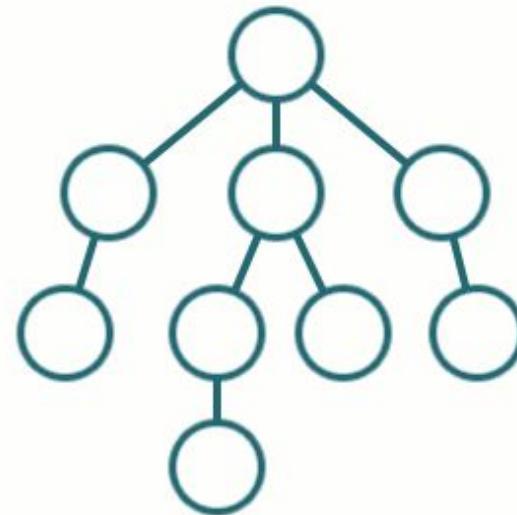


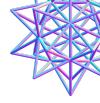
Graph Traversal: DFS and BFS

DFS

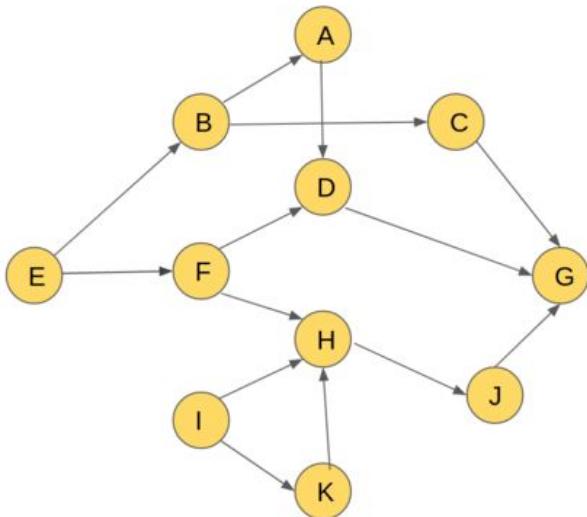


BFS





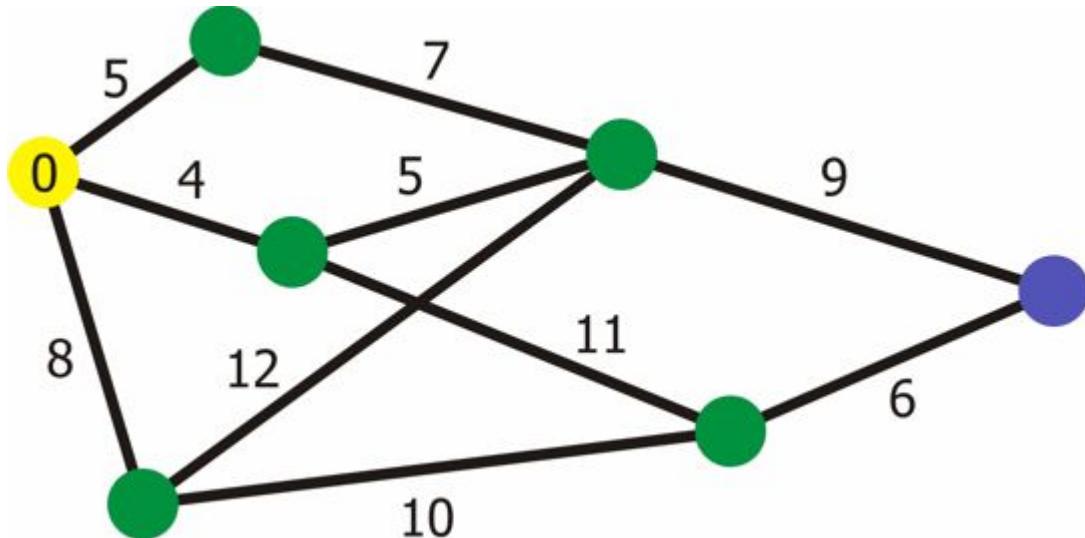
Topological Sort

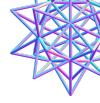


RESULT :

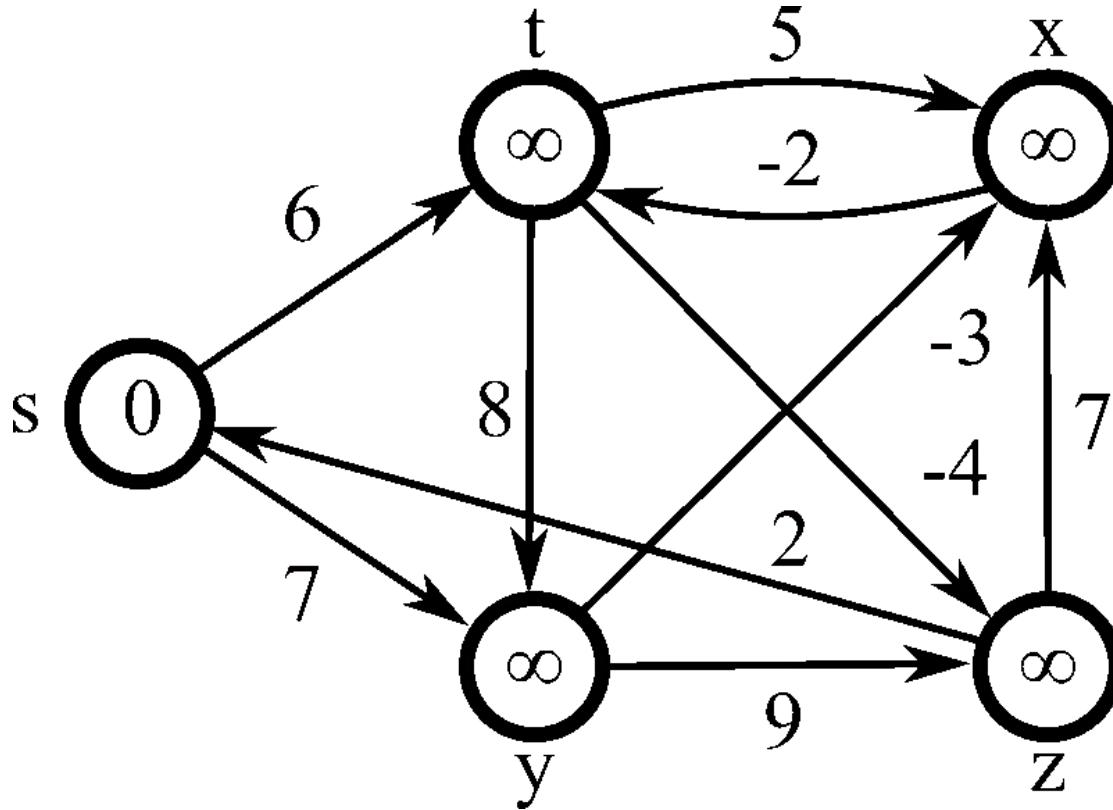


Shortest path: Dijkstra





Shortest path: Bellman Ford



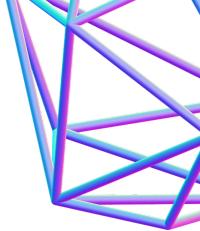


Exercise problems...

1. [Operations on graph](#)
2. [Cities and roads](#)
3. [From adjacency matrix to adjacency list](#)
4. [From adjacency list to adjacency matrix](#)
5. [Regular graph](#)
6. [Sources and sinks](#)

For more graph representation Problems: [Link](#)

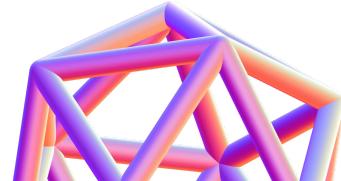




Ending Quote

*"You can always recognize truth
by its **beauty** and **simplicity**."*

- Richard P. Feynman



Slide Assets

Colors:

- Color 1
- Color 2
- Color 3

Fonts:

- Headings Font (Lora)
- Body Font (Inter)

Graphic Elements

