



BASICS OF HARDWARE WITH A PYRULER

Brought to you by Kira Hartlage

ENTER



INTRODUCTION



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Hi! I'm Kira Hartlage.

- Mechanical engineering background
- Consumer appliance design
- Self-taught software engineer
- Embedded software development



DESIRED OUTCOMES



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EMBEDDED

Embedded firmware,
software, systems?!

CIRCUITPYTHON

You don't need to learn C!

PYRULER

Let's make something
happen

RESOURCES

You can do it too



EMBEDDED SYSTEMS



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“An embedded system is a computerized system that is purpose-built for its application.”

- Elecia White



HARDWARE

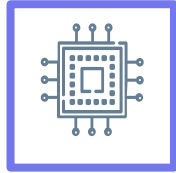


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MICROCONTROLLERS

An integrated circuit with a processor, memory, and various input/output peripherals



PERIPHERALS

Various parts of the microcontroller that interface with the outside world



HARDWARE - MICROCONTROLLERS



01

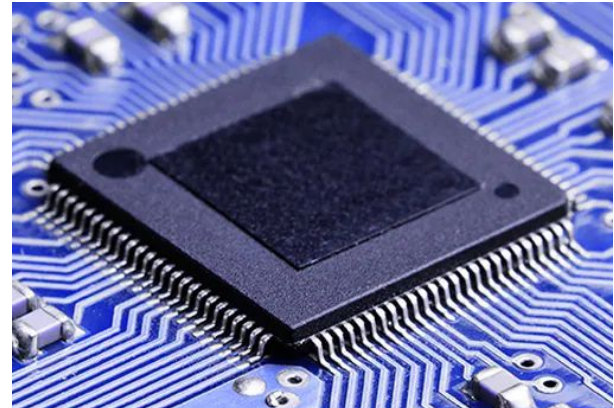
02

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1. Instructions - what the microcontroller is able to do
 - a. Instructions operate on numbers that are stored in registers and memory
2. Registers - fast storage that the micro has that the instructions can use
3. Memory - storage for memory, but slower than registers





HARDWARE - PERIPHERALS



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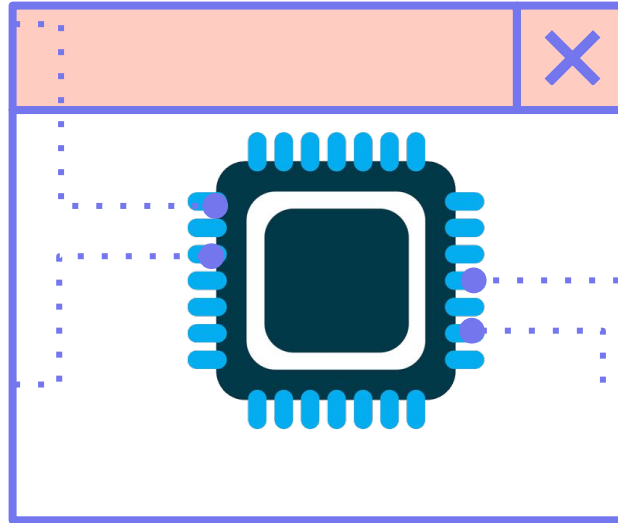


GPIO

General
purpose
input/output

PWM

Pulse-width
modulation



ADC

Analog to
digital control

UART

Universal
asynchronous
receiver-transmitter



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CIRCUITPYTHON

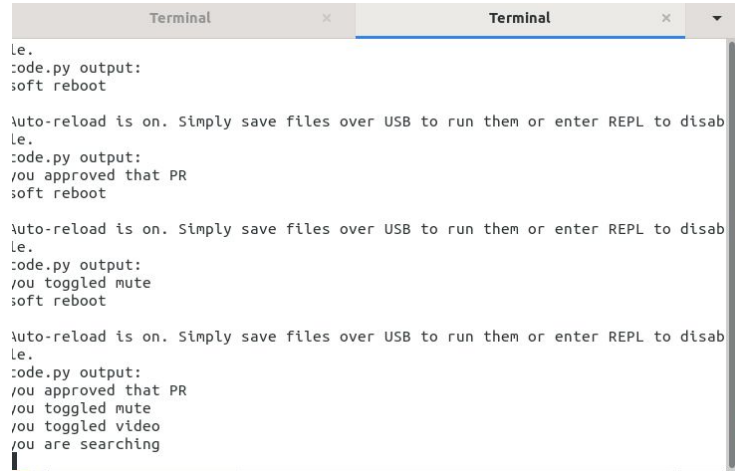
<https://learn.adafruit.com/assets/49441>

FILE STRUCTURE & SERIAL CONSOLE



The screenshot shows the CIRCUITPY file explorer interface. On the left is a sidebar with navigation options: Recent, Starred, Home, and Documents. The main area displays a table of files and folders.

Name	Size	Modified
boot_out.txt	82 bytes	31 Dec 1999
code.py	2.7 kB	23 May
lib	10 items	11 Jan
README.txt	2.9 kB	24 Jul 2019
System Volume Information	2 items	25 Jul 2019



The screenshot shows a terminal window with the REPL interface. The text in the terminal is as follows:

```
le.  
:code.py output:  
soft reboot  
  
\auto-reload is on. Simply save files over USB to run them or enter REPL to disab  
le.  
:code.py output:  
/ou approved that PR  
soft reboot  
  
\auto-reload is on. Simply save files over USB to run them or enter REPL to disab  
le.  
:code.py output:  
/ou toggled mute  
soft reboot  
  
\auto-reload is on. Simply save files over USB to run them or enter REPL to disab  
le.  
:code.py output:  
/ou approved that PR  
/ou toggled mute  
/ou toggled video  
/ou are searching  
|
```

Press any key to enter the REPL. Use CTRL-D to reload.
Adafruit CircuitPython 4.1.0-rc.1 on 2019-07-19; Adafruit PyRuler with samd21e18

```
>>> x = 2  
>>> y = 3  
>>> x + y  
5  
>>> |
```



PYRULER

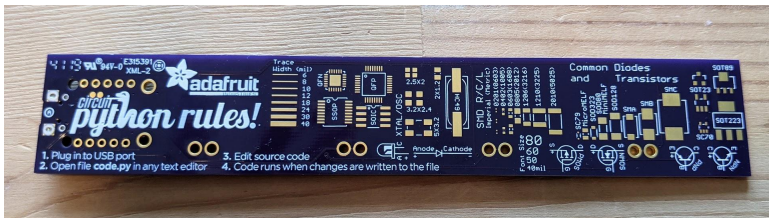
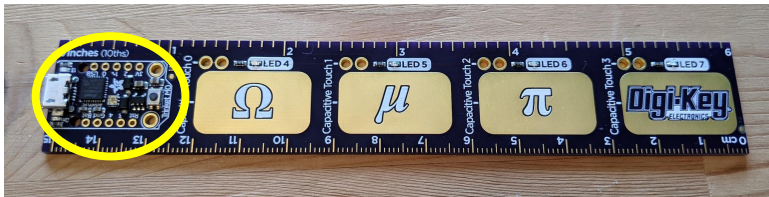


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PyRuler is a reference board with a Trinket M0 (a Cortex M0) microcontroller.



PYRULER PROJECT



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Adapted from an existing
project here:
[https://learn.adafruit.com/
PyRulerVideoPanic/code](https://learn.adafruit.com/PyRulerVideoPanic/code)





CIRCUIT PLAYGROUND EXPRESS / BLUEFRUIT



01

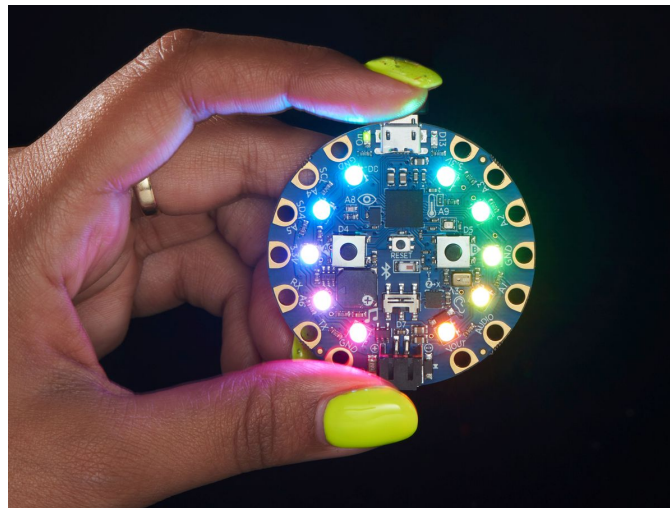
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- nRF52840 microcontroller
- Bluetooth Low Energy support for wireless connectivity
- 10 x mini NeoPixels, each one can display any color
- 1 x Motion sensor
- 1 x Temperature sensor (thermistor)
- 1 x Light sensor (phototransistor)
- 1 x Sound sensor (MEMS microphone)
- 1 x Mini speaker with class D amplifier
- 2 x Push buttons
- 1 x Slide switch
- And more!



<https://learn.adafruit.com/assets/80528>



CIRCUIT PLAYGROUND EXPRESS / BLUEFRUIT



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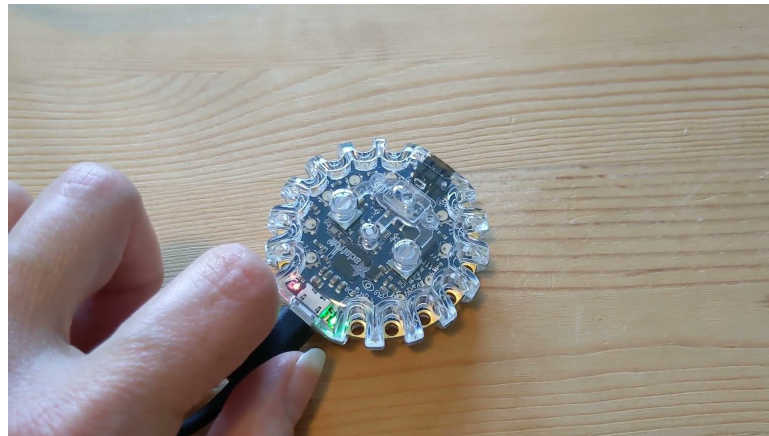
04



```
from adafruit_circuitplayground import cp
import time

cp.pixels.brightness = 0.1

while True:
    if cp.button_a:
        cp.play_mp3("radio-tune.mp3")
    if cp.button_b:
        cp.play_mp3("punch.mp3")
    if cp.loud_sound(sound_threshold = 250):
        cp.pixels.fill((50, 0, 50))
        time.sleep(0.2)
    else:
        cp.pixels.fill((0, 0, 0))
    cp.red_led = cp.switch
```





CIRCUIT PLAYGROUND EXPRESS / BLUEFRUIT PROJECT



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Multi-tasking and scheduling can be difficult when you have one main loop.

One solution is using a software timer and handling events asynchronously.



RESOURCES



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GITHUB REPO - with code and list of more links!

- <https://github.com/kirakirakira/python-hardware-pyruler>

ADAFRUIT

- <https://learn.adafruit.com/>



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THANKS!

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PYRULER PROJECT



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```
# Modified from https://learn.adafruit.com/PyRulerVideoPanic/code
# Keyboard shortcuts work in Microsoft Teams

import os
import board
from digitalio import DigitalInOut, Direction
import time
import touchio
import adafruit_dotstar

leddot = adafruit_dotstar.DotStar(board.APA102_SCK, board.APA102_MOSI, 1)
leddot[0] = (128, 0, 128)
leddot.brightness = 0.3

# Set this to True to turn the touchpads into a keyboard
ENABLE_KEYBOARD = True

# Used if we do HID output, see below
if ENABLE_KEYBOARD:
    from adafruit_hid.keyboard import Keyboard
    from adafruit_hid.keycode import Keycode
    from adafruit_hid.keyboard_layout_us import KeyboardLayoutUS
    kbd = Keyboard()
    layout = KeyboardLayoutUS(kbd)
```

Import helpful libraries

Set up LED

Enable keyboard input



PYRULER PROJECT



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```
led = DigitalInOut(board.D13)
led.direction = Direction.OUTPUT
```



Set up D13 LED as output

```
touches = [DigitalInOut(board.CAP0)]
for p in (board.CAP1, board.CAP2, board.CAP3):
    touches.append(touchio.TouchIn(p))
```



Record touches

```
leds = []
for p in (board.LED4, board.LED5, board.LED6, board.LED7):
    led = DigitalInOut(p)
    led.direction = Direction.OUTPUT
    led.value = True
    time.sleep(0.25)
    leds.append(led)
for led in leds:
    led.value = False
```



Turn on all LEDs then turn them off



PYRULER PROJECT



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```
cap_touches = [False, False, False, False]

def read_caps():
    t0_count = 0
    t0 = touches[0]
    t0.direction = Direction.OUTPUT
    t0.value = True
    t0.direction = Direction.INPUT
    # funky idea but we can 'diy' the one non-hardware captouch device by hand
    # by reading the drooping voltage on a tri-state pin.
    t0_count = t0.value + t0.value + t0.value + t0.value + t0.value + \
        t0.value + t0.value + t0.value + t0.value + t0.value + \
        t0.value + t0.value + t0.value + t0.value + t0.value
    cap_touches[0] = t0_count > 2
    cap_touches[1] = touches[1].raw_value > 3000
    cap_touches[2] = touches[2].raw_value > 3000
    cap_touches[3] = touches[3].raw_value > 3000
    return cap_touches
```

Read cap touch inputs



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```
def type_alt_code(code):  
    kbd.press(Keycode.CONTROL, Keycode.SHIFT)  
    kbd.press(Keycode.U)  
    kbd.release_all()  
    kbd.send(Keycode.TWO)  
    kbd.send(Keycode.ONE)  
    kbd.send(Keycode.TWO)  
    kbd.send(Keycode.SIX)  
    kbd.send(Keycode.ENTER)
```

Send/type keyboard input for an ALT code

```
def toggle_mute():  
    kbd.press(Keycode.CONTROL, Keycode.SHIFT)  
    kbd.press(Keycode.M)  
    kbd.release_all()
```

Toggle mute in Teams

```
def toggle_video():  
    kbd.press(Keycode.CONTROL, Keycode.SHIFT)  
    kbd.press(Keycode.O)  
    kbd.release_all()
```

Toggle video camera in Teams

```
def go_to_search():  
    kbd.press(Keycode.CONTROL)  
    kbd.press(Keycode.E)  
    kbd.release_all()
```

Go to search in Teams



PYRULER PROJECT



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```
while True:
    caps = read_caps()
    # light up the matching LED
    for i, c in enumerate(caps):
        leds[i].value = c
    if caps[0]:
        if ENABLE_KEYBOARD:
            go_to_search()
    if caps[1]:
        if ENABLE_KEYBOARD:
            toggle_video()
    if caps[2]:
        if ENABLE_KEYBOARD:
            toggle_mute()
    if caps[3]:
        if ENABLE_KEYBOARD:
            print("you approved that PR")
            layout.write('LGTM :+1:')
    time.sleep(0.1)
```

This is the main loop. It loops indefinitely and services the functions that are within it.

1. It reads the cap touch buttons.
2. Lights up the matching LED if the button is touched.
3. If cap 0 is touched, it will go to search in Teams.
4. If cap 1 is touched, it will toggle the video camera in Teams.
5. If cap 2 is touched, it will mute the video.
6. If cap 3 is touched, it will print "LGTM 👍" to wherever the keyboard input is placed if active.