

Workshop: Introduction to Scilab  
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(The sequence of spoken tutorials to be listened/followed is same as that of exercise sets below.)

### 1. Getting Started

Solve the following examples on the Scilab Console as soon as the relevant topic is explained in the tutorial.

- (a) Perform the following calculations on the scilab command line:

$$\text{phi} = \frac{\sqrt{5} + 1}{2} \quad \text{psi} = \frac{\sqrt{5} - 1}{2}$$

Find  $1/\text{phi}$  and  $1/\text{psi}$ .

- (b)  $\tan(45)$   
(c)  $\tan^{-1}(1)$   
(d) Verify Euler's identity: Is  $e^{\pi i} + 1$  close to zero?  
(e)  $\sqrt[4]{256}$   
(f)  $256^{0.25}$   
(g)  $e^{i\pi}$

### 2. Matrix Operations

- (a) 03:15: In Scilab, enter the following Matrices:

$$A = \begin{bmatrix} 1 & 1/2 \\ 1/3 & 1/4 \\ 1/5 & 1/6 \end{bmatrix}$$

$$B = \begin{bmatrix} 5 & -2 \end{bmatrix}, \quad C = \begin{bmatrix} 4 & 5/4 & 9/4 \\ 1 & 2 & 3 \end{bmatrix}$$

Using Scilab commands, compute each of the following, if possible.

- i.  $A * C$   
ii.  $A * B$   
iii.  $A + C'$   
iv.  $B * A - C' * A$   
v.  $(2 * C - 6 * A') * B'$   
vi.  $A * C - C * A$   
vii.  $A * A' + C' * C$

Explain the errors, if any.

- (b) 04:15: From the video:

- i. Find  $E(:, :)$   
ii. Extract the second column of  $E$   
iii. Display just the first and last columns<sup>1</sup> of  $E$ .

(c) 05:46: If  $A = \begin{bmatrix} 1 & -1 & 0 \\ 2 & 3 & 1 \\ 4 & 1 & 5 \end{bmatrix}$

Use a suitable sequence of row operations on  $A$  to bring  $A$  to upper triangular form.<sup>2</sup>

- (d) 07:28: Represent the following linear system as a matrix equation. Solve the system using the inverse method:

$$\begin{aligned} x + y + 2z - w &= 3 \\ 2x + 5y - z - 9w &= -3 \\ 2x + y - z + 3w &= -11 \\ x - 3y + 2z + 7w &= -5 \end{aligned}$$

- (e) 08:01: Try solving the above system using the backslash method.  
(f) 08:38: Verify the solution from the previous question.  
(g) 09:38: Try  $\det(A)$ ,  $A^2$ ,  $A^3$  and Eigenvalues of  $A$  (from the previous question).

Also multiply  $A$  by an identity matrix of the same size.

### 3. Scripts and Functions

- (a) 02:48:

- i. Create a scilab script file to display time on console window. (hint: `clock()`)  
ii. Create a scilab script file to display product of a matrix  $A$  and inverse of  $A$ .  $A = [1, 1; 1, -1]$

- (b) 05:04:

- i. Create a function file to calculate sum and difference of any two numbers. The output should be the sum and the difference of numbers.

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<sup>1</sup>Tip: from a given matrix  $E$ , desired columns can be specified by defining a vector  $v$  consisting of just the desired column indices and using  $E(:, v)$ . Similarly for rows also.

<sup>2</sup>Upper triangular matrix: all elements below the North-West to South-East diagonal of the matrix are zero.

- ii. Create a function file to calculate the rowwise and columnwise mean and standard deviation of a user defined matrix. Display the matrix, its mean and standard deviation in output. (hint: mean(), stdev() )
- (c) 09:05:
  - i. Create an inline function to sort the elements of a random vector in descending order. (hint: gsort())
  - ii. Create an inline function to round off the elements of a vector [1.9, 2.3, -1.1, 50.5] to the nearest integer. (hint: round())
- (d) 10:30: Create a function file to calculate LU factorization of a matrix. (hint: lu()).

#### 4. Plotting

- (a) 01:12: Create a linearly spaced vector from 0 to 1 with 10 points
- (b) 01:12: Also create a linearly spaced vector from 0 to 1 with 11 points
- (c) 01:35: plot sin(x) versus x.
- (d) 02:50: Use plot2d and try changing the color to red. Also try style = -1
- (e) 03:53: Put a title: "Sine", and labels, 'x axis' and 'y axis'
- (f) 05:50: Plot sin(x) and cos(x) on the same window.
- (g) 06:08: Create a legend for the above plots.
- (h) 09:25: Now plot sin(x) and cos(x) as subplots within the same window.
- (i) 10:10: Save your plot as a file.

#### 5. Conditional Branching

Note the importance of 'end' at the end of the 'if-then-else-end' construct.

- (a) Write a code to check if a given number  $n$  is less than or equal to 10, if yes, display its square.(for  $n = 4, 13$  and 10)
- (b) Write a code to check if a number is less than 10, if yes, then display '> 10', if it is greater than 10, then display '> 10', else display the number. (for  $n = 4, 13$  and 10)

#### 6. Iteration

- (a) Write a for loop to display all the even numbers between 1 to 50
- (b) Find summation of vector  $x = [1 \ 2 \ 6 \ 4 \ 2]$ , using iterative procedure. Hint: Check length(), add each number using 'for' loop.
- (c) Write a code using while loop to display odd numbers in the range 1 to 25.

#### 7. Polynomials

- (a) Construct a polynomial with 3 repeated roots at 4 and 2 repeated roots at 0. Check the roots of the derivative of this polynomial. (Use derivat)
- (b) Write a function that takes a polynomial and gives out only real roots as output. (hint isreal )
- (c) Write a function that takes a polynomial and gives the INVERSE polynomial, i.e. all roots are inverses of each other. (Hint: Coefficients are to just be reversed.) (Check that no root was at zero: check this within the function, and display error, and exit.)
- (d) Write a function that takes a polynomial and gives all the maxima/minima candidates. (Hint: find all real roots of the derivative).

#### 8. Ordinary Differential Equations

Solve the following differential equations using Scilab and plot the dependent variable vs independent variable

- (a)  $dy/dx + y/x = -x^3; (x > 0)$
- (b)  $\cos(x)dy/dx + \sin(x)y = x^2; y(0) = 4$
- (c)  $dy/dx = (-x^3 - y)/x; (y(1) = 0)$
- (d)  $dy/dx + y = 2x + 5; (y(1) = 1)$
- (e)  $dy/dx + y = x^4; (y(0) = 0)$
- (f)  $dy/dt + (t - 1)y = 0; (y(4) = 5)$
- (g)  $dy/dt + 2ty = t; (y(2) = 4)$
- (h)  $dy/dx + 2xy = 10xe^{-x^2}; (y(0) = 1)$
- (i)  $2x^2dy/dx - yx = 3; (y(1) = 0)$

#### 9. Control Systems

- (a) Find the step response of the system described by the transfer function:

$$\frac{1}{s^2 + 2s + 9}$$

- (b) Define a system whose open loop

transfer function has roots at -1, -2 and -3. From the root locus of this system, find the value of gain K for which the system becomes unstable in the closed loop.