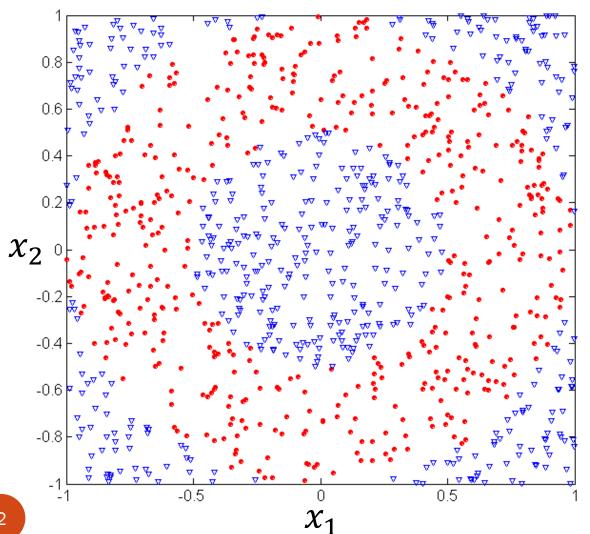
# CZ4041/CE4041: Machine Learning

**Lesson 6a: Generalization** 

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## **Underfitting and Overfitting (Example)**



500 circular and 500 triangular data points.

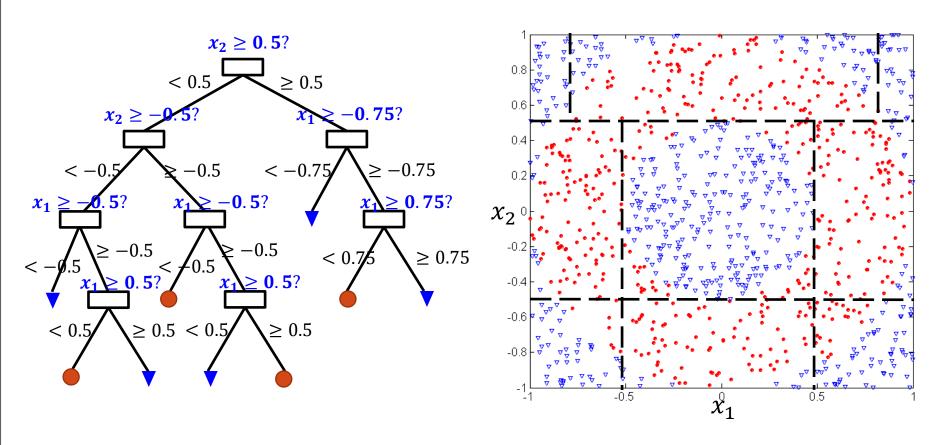
#### Circular points:

$$0.5 \le \sqrt{x_1^2 + x_2^2} \le 1$$

#### Triangular points:

$$\sqrt{x_1^2 + x_2^2} > 1$$
or
$$\sqrt{x_1^2 + x_2^2} < 0.5$$

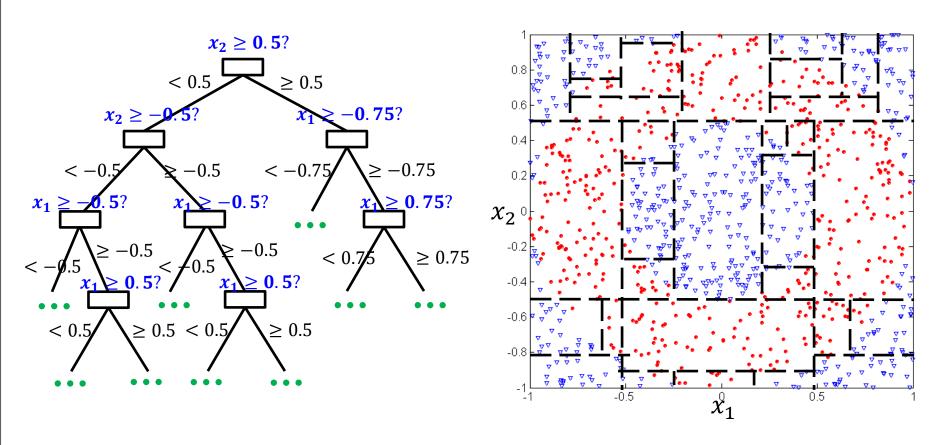
# Overfitting v.s. Model Complexity



Training errors (#misclassified training data) = 100 +

Decision tree with 9 leaf nodes

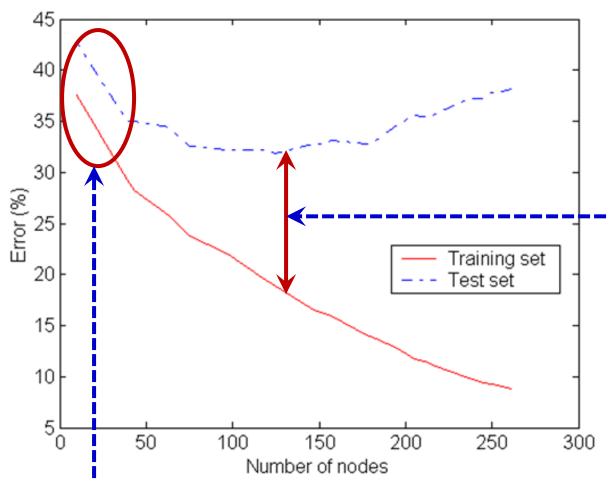
## Overfitting v.s. Model Complexity



Training errors = 20

Decision tree with 30 + leaf nodes

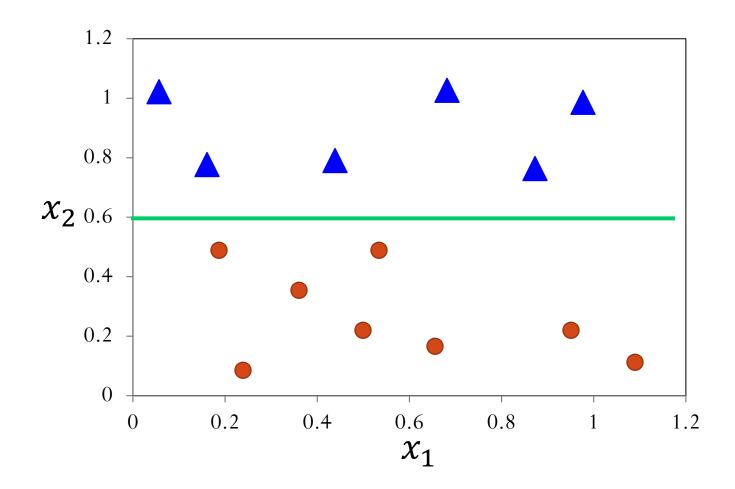
## **Underfitting and Overfitting**



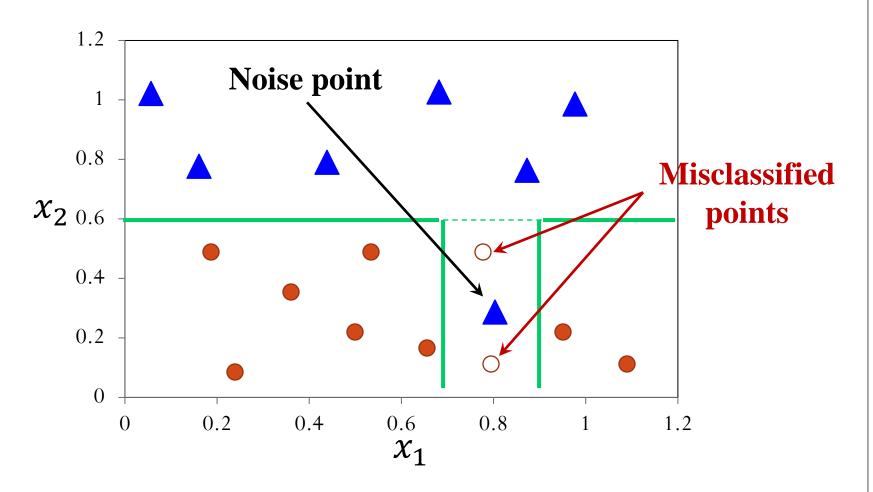
Overfitting: when test error rate begins to increase even though training error rate continues to decrease

<u>Underfitting</u>: when model is too simple, both training and test error rates are large

## Overfitting due to Noise



## Overfitting due to Noise (cont.)



Decision boundary is distorted by noise point

## **Notes on Overfitting**

- Overfitting results in decision trees that are more complex than necessary
- Training error no longer provides a good estimate of how well the tree will perform on previously unseen records
- Need new ways for estimating errors

## Overfitting v.s. Model Complexity (cont.)

- How do we determine the right model complexity?
- A model with ideal complexity is the one that produces the lowest generalization error
- No knowledge of the test data and how well the model will perform on unseen data
- The best it can do is to **estimate** the generalization error of the induced model

#### **Estimation of Generalization Errors**

- Training errors: error on the training set: e(T)
- Generalization errors: error on previously unseen testing set: e'(T)

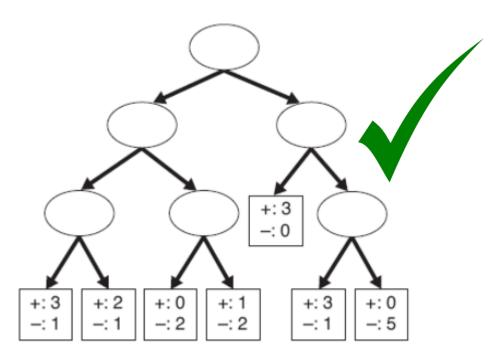
#### **Estimation of Generalization Errors**

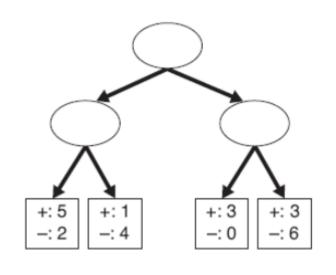
- Approaches to estimating generalization errors:
  - Optimistic Estimate: e'(T) = e(T)
  - Incorporating model complexity
    - Occam's Razor
      - Pessimistic Error Estimate
  - Using Validation Set

## **Optimistic Estimate**

- Assume that the training set is a good representation of the overall data
- The training error can be used to provide an optimistic estimate for the generalization error
  - $\bullet \ e'(T) = e(T)$
- A decision tree induction algorithm selects the model that produces the lowest training error rate

## An Example of Optimistic Estimate





Decision Tree,  $T_L$ 

$$e(T_L) = 4$$

$$e(T_L)$$
 rate =  $\frac{4}{24} = 0.167$ 

Decision Tree,  $T_R$ 

$$e(T_R) = 6$$

$$e(T_L)$$
 rate =  $\frac{6}{24}$  = 0.25

#### **Estimation of Generalization Errors**

- Approaches to estimating generalization errors:
  - Optimistic Estimate: e'(T) = e(T)
  - Incorporating model complexity
    - Occam's Razor
      - Pessimistic Error Estimate
  - Using Validation Set

## Occam's Razor

- Definition: Given two models of similar generalization errors, one should prefer the simpler model over the more complex model
- For complex models, there is a greater chance that it was fitted accidentally by errors in data
- Therefore, one should include model complexity when evaluating a model

"Everything should be made as simple as possible, but no simpler." – Albert Einstein

## **Pessimistic Error Estimate**

 Idea: explicitly computes generalization error as the sum of training error and a penalty term for model complexity

$$e'(T) = e(T) + \Omega(T)$$

• In a decision tree, we can define a penalty term of k > 0 on each leaf node, i.e.,

$$e'(t) = e(t) + \Omega(t) = e(t) + k$$

• Then,

$$e'(T) = e(T) + N \times k$$
Total number of leaf nodes
$$k > 0, \text{e.g.}, k = 0.5$$

## Example

- For a tree with 30 leaf nodes and 10 errors on training (out of 1,000 instances):
  - Training errors = 10
  - Training error rate =  $\frac{10}{1000}$  = 1%
  - Generalization errors =  $10 + 30 \times 0.5 = 25$
  - Generalization error rate  $=\frac{25}{1000}=2.5\%$

#### **Estimation of Generalization Errors**

- Approaches to estimating generalization errors:
  - Optimistic Estimate: e'(T) = e(T)
  - Incorporating model complexity
    - Occam's Razor
      - Pessimistic Error Estimate
  - Using Validation Set

## Using a Validation Set

- Divide the original training data set into two smaller subsets
- One is for training, the other (known as the validation set) is for estimating the generalization error
- The complexity of the best model can be estimated based on the performance of the model on the validation set

## How to Address Overfitting

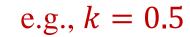
- Pre-Pruning (Early Stopping Rule)
  - Stop the algorithm before it becomes a fullygrown tree
  - Typical stopping conditions for a node:
    - Stop if all instances belong to the same class
    - Stop if all the feature values are the same

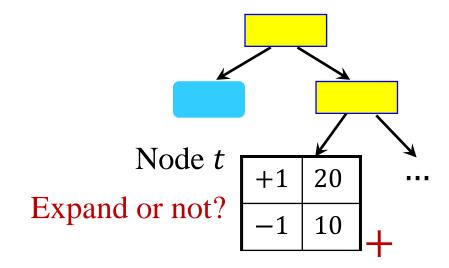
## How to Address Overfitting (cont.)

- Pre-Pruning (Early Stopping Rule)
  - More restrictive conditions:
    - Stop if number of instances is less than some user-specified threshold
    - Stop if expanding the current node does not improve generalization errors

## **Pre-Pruning Example**

Generalization errors:  $e'(T) = e(T) + \Omega(T) = e(T) + N \times k$ 



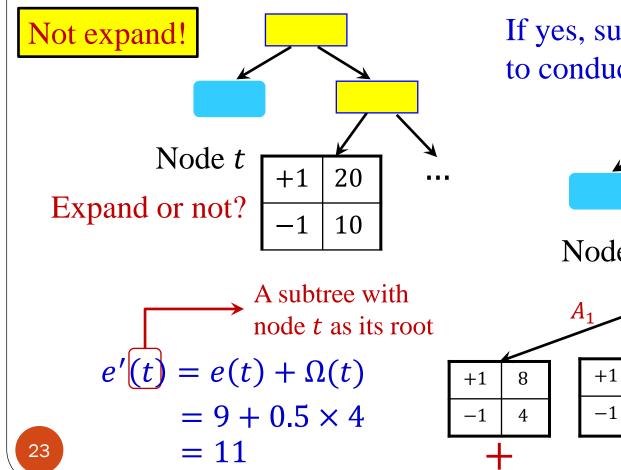


$$e'(t) = e(t) + \Omega(t)$$
A subtree with node t as its root
$$= 10 + 1 \times 0.5$$

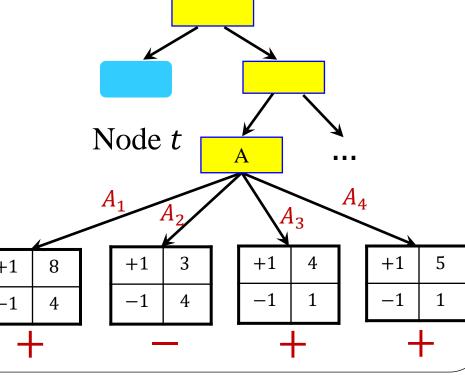
$$= 10.5$$

## **Pre-Pruning Example (cont.)**

Generalization errors:  $e'(T) = e(T) + N \times 0.5$ 

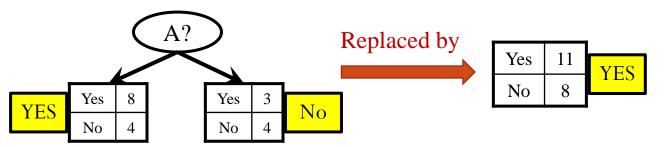


If yes, suppose A is best feature to conduct condition test



## How to Address Overfitting (cont.)

- Post-pruning
  - Grow decision tree to its entirety
  - Trim the nodes of the decision tree in a bottomup fashion
  - If generalization error improves after trimming, replace sub-tree by a new leaf node
  - Class label of leaf node is determined from majority class of instances in the sub-tree



**Example of Post-Pruning** 



$$e'(T) = e(T) + N \times 0.5$$

PRUNE?

Class = Yes	8
Class = No	4

Class = Yes	3
Class = No	4

Class = Yes	4
Class = No	1

*A*?

Class = Yes

Class = No

E	Error	= 10	
	$A_4$		
	114		
Yes	4	Class = Ye	es 5

Class = No

20

10

Training errors (before pruning) = 4 + 3 + 1 + 1 = 9Pessimistic errors (before pruning) =  $9 + 4 \times 0.5 = 11$ 

Training errors (after pruning) = 10Pessimistic errors (after pruning) = 10 + 0.5 = 10.5

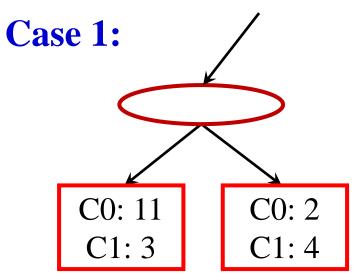
## **Examples of Post-pruning**

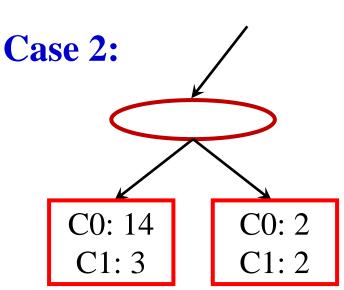
• Pessimistic error?

$$e'(T) = e(T) + N \times 0.5$$

PRUNE?







#### In Practice

#### criterion: {"gini", "entropy"}, default="gini"

The function to measure the quality of a split. Supported criteria are "gini" for the Gini impurity and "entropy" for the information gain.

#### max\_depth: int, default=None

The maximum depth of the tree. If None, then nodes are expanded until all leaves are pure or until all leaves contain less than min\_samples\_split samples.

#### max\_features : int, float or {"auto", "sqrt", "log2"}, default=None

The number of features to consider when looking for the best split:

- If int, then consider max\_features features at each split.
- If float, then max\_features is a fraction and int(max\_features \* n\_features) features are considered at each split.
- If "auto", then max features=sqrt(n features).
- If "sqrt", then max\_features=sqrt(n\_features).
- If "log2", then max\_features=log2(n\_features).
- If None, then max\_features=n\_features.

# Thank you!