

IoT Project | Automated Guided Vehicle

A robot with manual and auto operation modes which is used to transport packages from the warehouse to production lines



* **Solution 1:** Get the package from operation staff, then transport to the desired production line by defined route on the floor via sticked RFID cards and Bluetooth Low Energy stations

* **Solution 2:** Get the package from operation staff, then transport to the desired production line by integrated camera and black line tapes on the floor

Providing monitoring and controlling user interface via web app, API endpoints for intergrating with other systems

Multiple operating modes



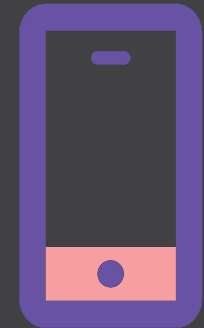
Allowing admin or developer directly control AGV via web app

Manual mode



Via AGV integrated display

Warehouse operator or worker chooses pick up and delivery target location



Via mobile app

Operator or worker chooses delivery package part on MES Mobile app

Automated mode

Navigation and position system | Bluetooth Low Energy

Working principle



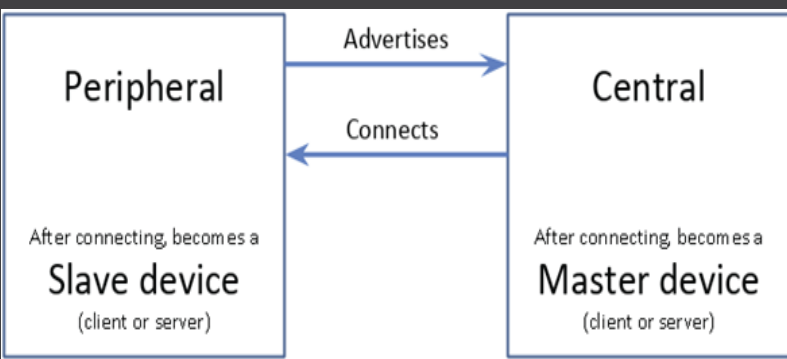
Beacon position data

BLE Profiles

Processing to get corresponding coordinate

BLE Profiles

GAP Profile



GATT Profile



Navigation and position system | RFID

Working principle



Read data on card via card reader

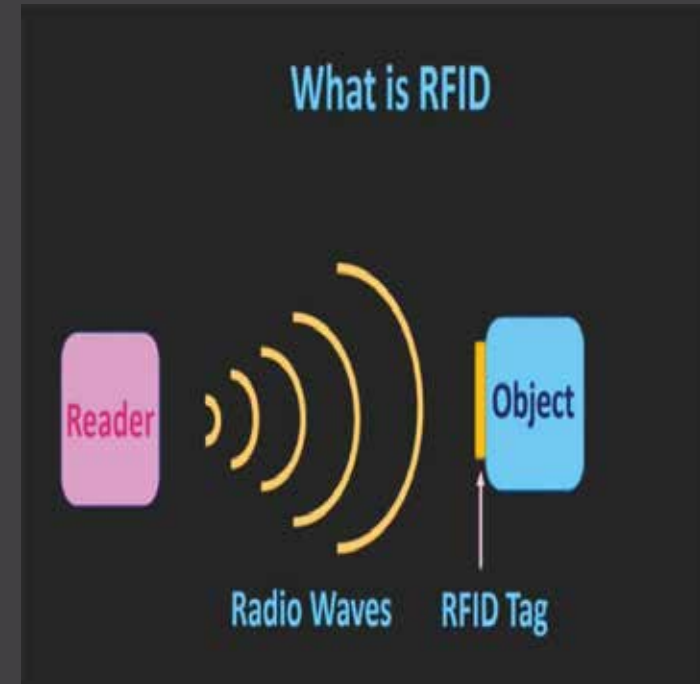


RFID card position data



Processing to get corresponding coordinate

Capability

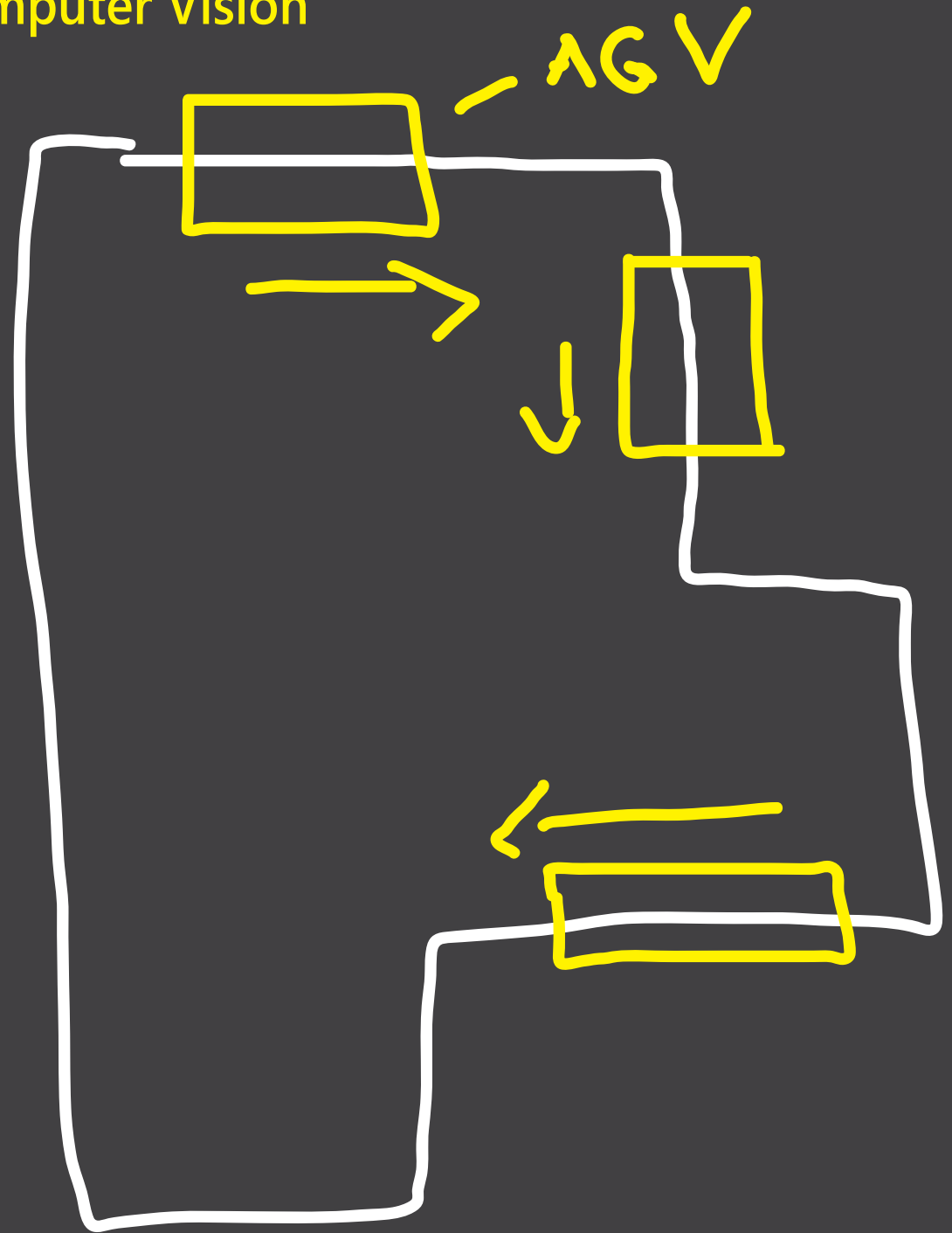
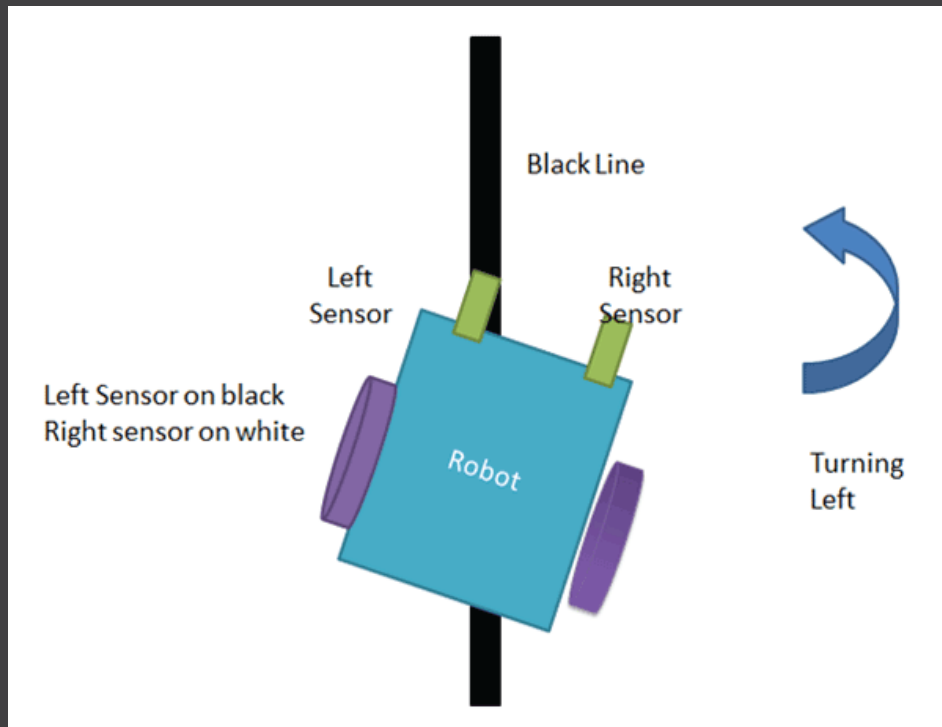
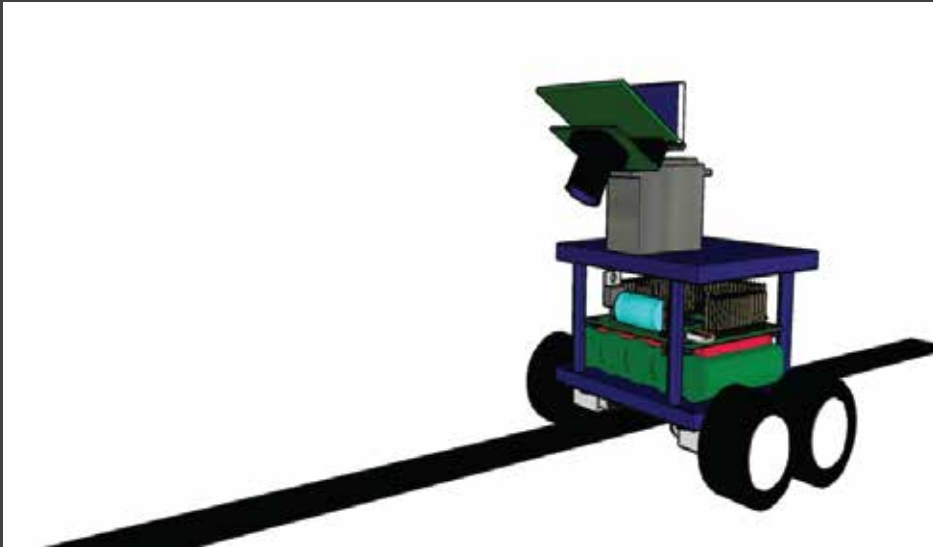


Write new data to RFID card

Change/Update data to RFID card

Navigation and position system | Computer Vision

Working principle



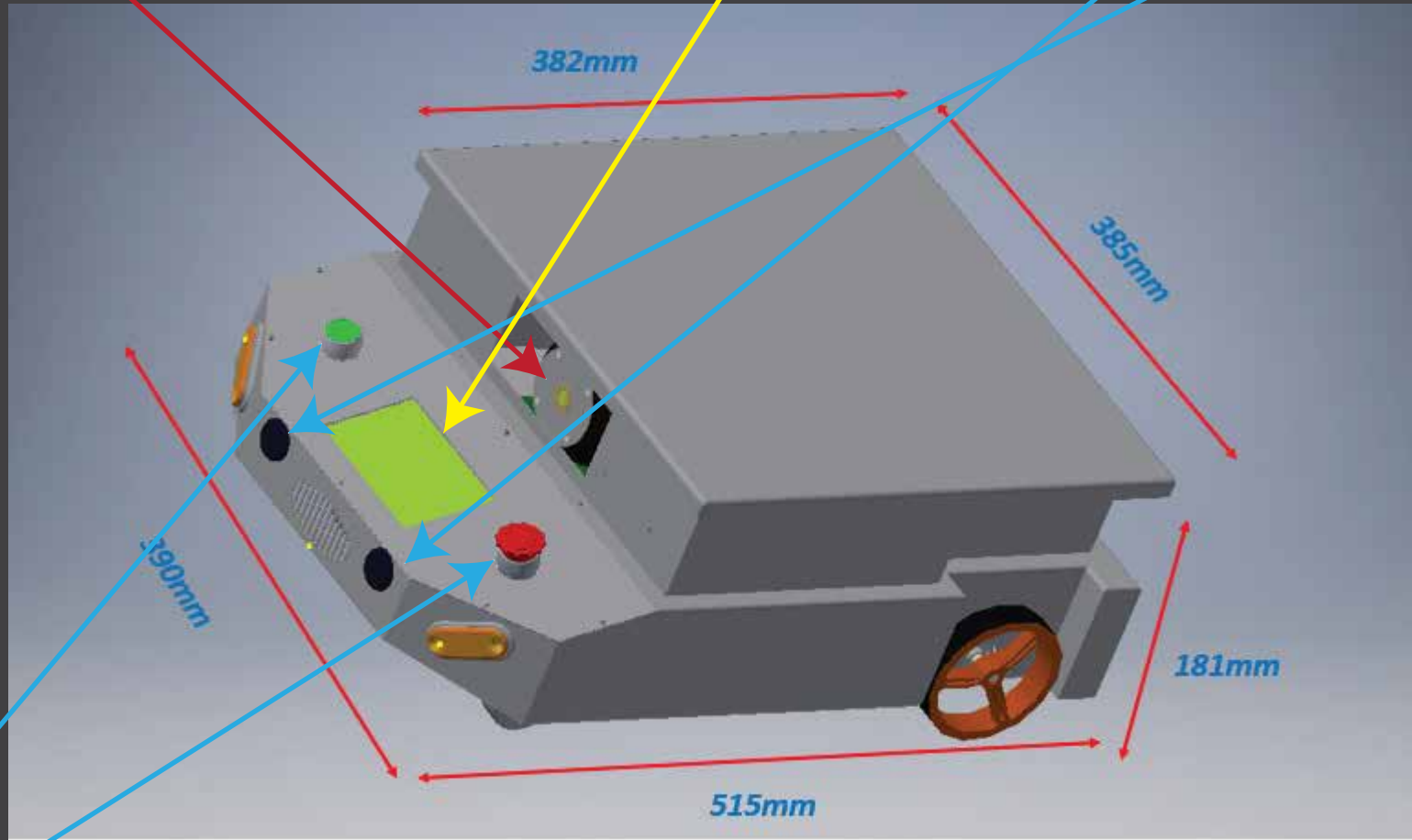
General description | Hardware design

Hardware

Camera for monitoring easier

Touchscreen for manual configuration and display operating data

Sensors for avoiding obstacles



Start/Emergency Stop button

