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## Computer vision in the task of manipulator control

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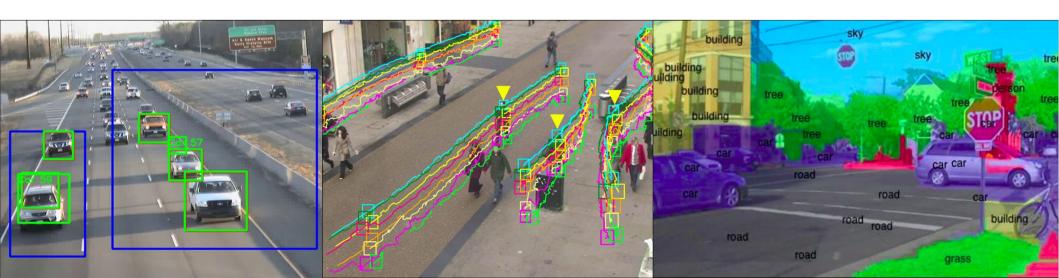
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#### Outline

- What is computer vision (CV)
- Where applicable
- Typical tasks of CV
- Solution for KUKA Youbot Arm
- Conclusions

## What is computer vision

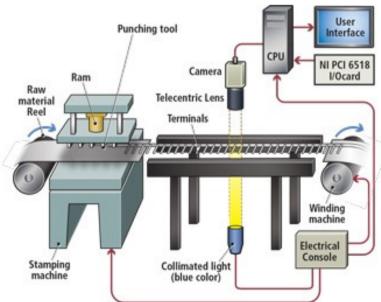
Computer vision is the theory and technology of creating machines that can detect, track and classify objects



## Where applicable

- Automatic inspection
- Assisting humans in identification tasks
- Controlling processes







#### Where applicable

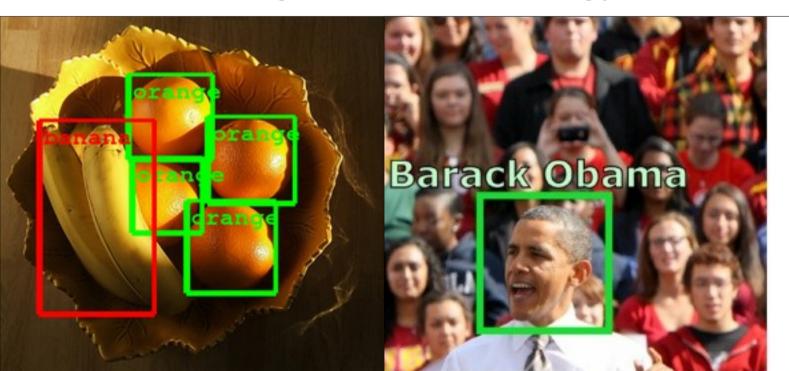
- Detecting events
- Interaction

- Navigation
- Organizing information
- Modeling objects or environments

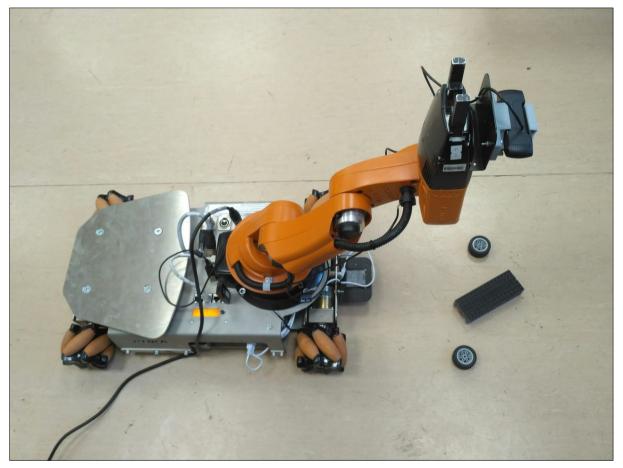


#### Typical tasks in CV

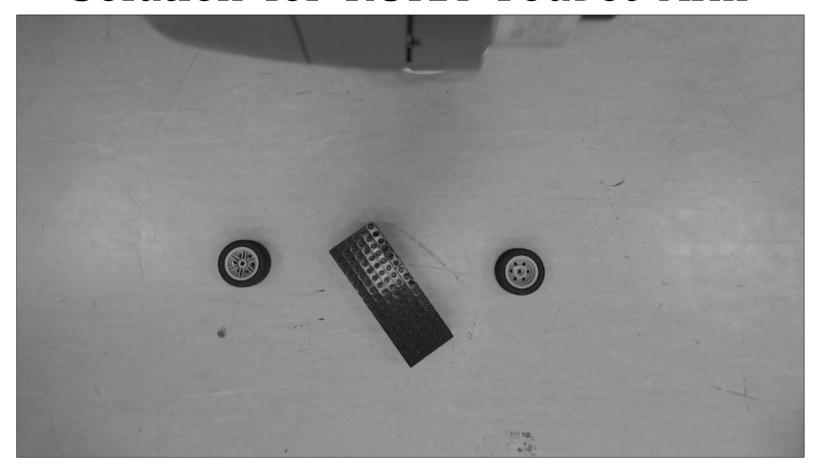
- Content-based image retrieval
- Pose estimation
- Optical character recognition (OCR)
- Facial recognition
- Shape Recognition Technology (SRT)



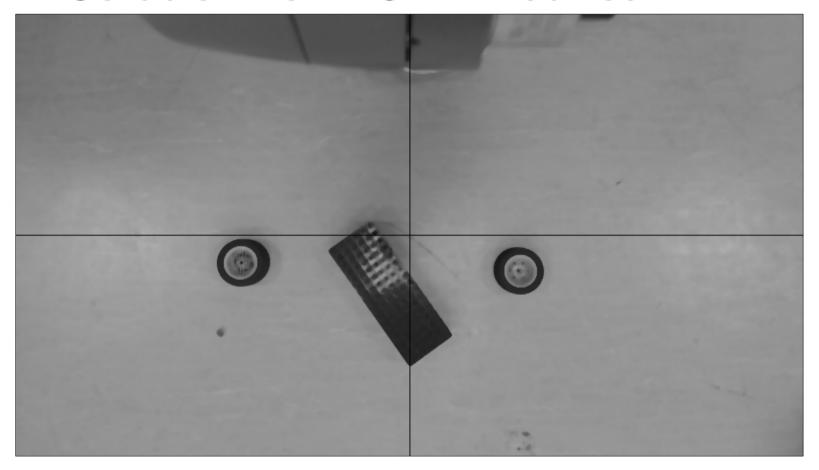




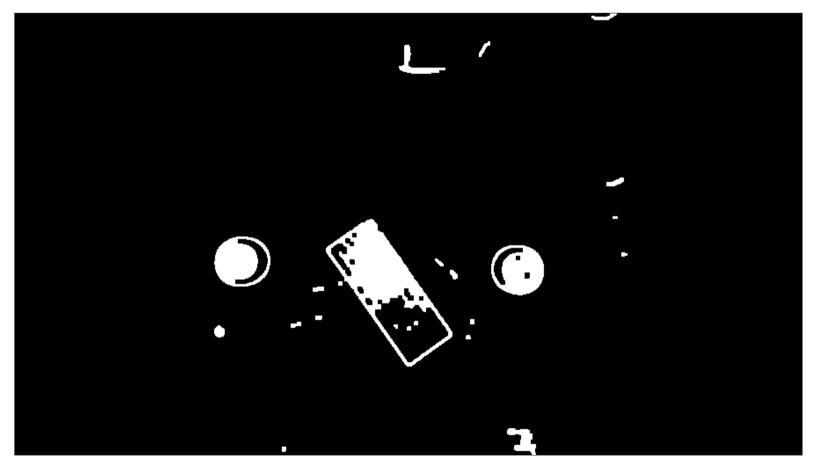
KUKA Youbot Arm with camera



Step 1: getting gray image from camera



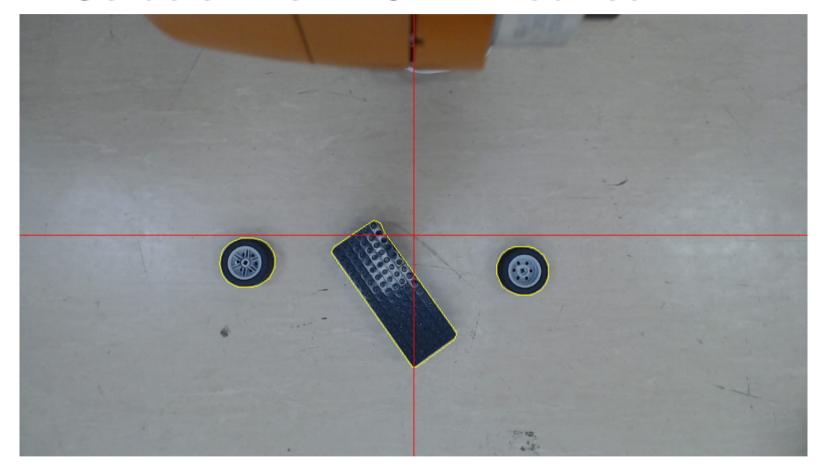
Step 2: blur the image



Step 3: apply Canny filter



Step 4: finding all contours



Step 5: comparing each contour with templates, find useful

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# Thank you for your attention!

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