

6.036/6.862: Introduction to Machine Learning

Lecture: starts Tuesdays 9:35am (Boston time zone)

Course website: introml.odl.mit.edu

Who's talking? Prof. Tamara Broderick

Questions? discourse.odl.mit.edu (“Lecture 11” category)

Materials: Will all be available at course website

Last Time(s)

- I. State machines & Markov decision processes (MDPs)
- II. Choosing “best” actions
- III. Value iteration; Q-learning

Today’s Plan

- I. Back to supervised learning
- II. Sequential data
- III. Recurrent neural networks

Some terminology

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- *Reinforcement learning* (RL): learning (to maximize rewards) by interacting with the world

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 - Contrast with the Q^* function (expected reward of starting at s , making action a , and then making the “best” action ever after)

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 - Contrast with (any horizon) *value iteration*

Text prediction

Text prediction

Final product

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Final product

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Autocomplete

Application that predicts the rest of a word a user is typing.



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travel guide

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news source

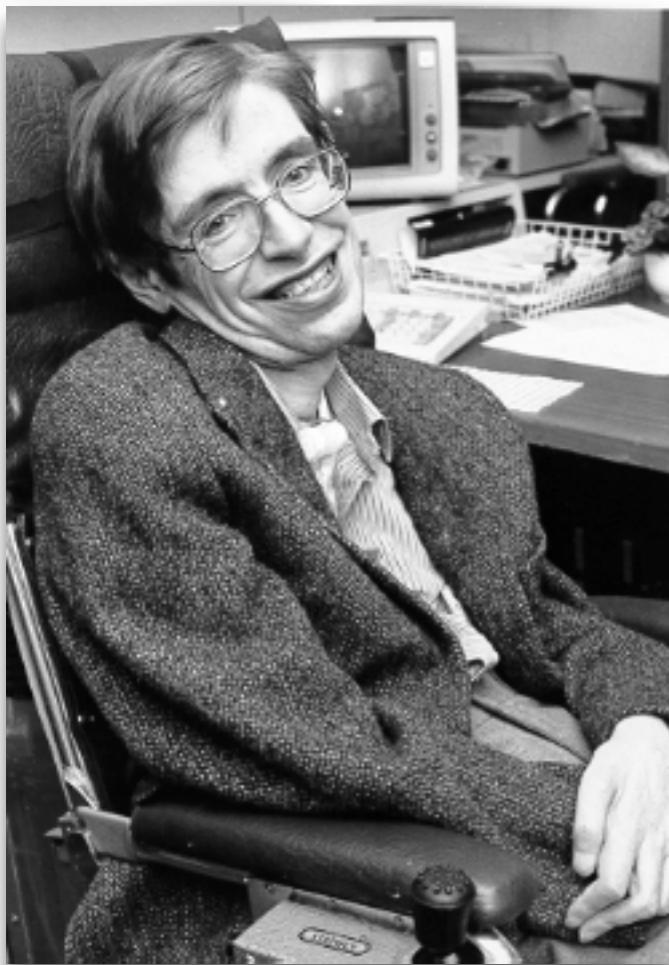
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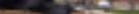
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- Training data: lots of text

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 - “what happens to a dream deferred”

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features	label
w	h

Text prediction: supervised learning

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features	label
w	h
wh	a

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features	label
w	h
wh	a
wha	t

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features	label
w	h
wh	a
wha	t
what	—
what_	h
what_h	a
what_ha	p
what_hap	p
what_happ	e

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- Classification with 27 classes

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- How to featurize?

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- How to featurize?
- Idea: use all previous characters.

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- How to featurize?
- Idea: use all previous characters. But so far we've said $x^{(i)} \in \mathbb{R}^d$; i.e. fixed dimension

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- Idea: just use last character. But lose info
- Idea: use last m characters

Can express as a state machine

“wha”

Can express as a state machine

“wha□”

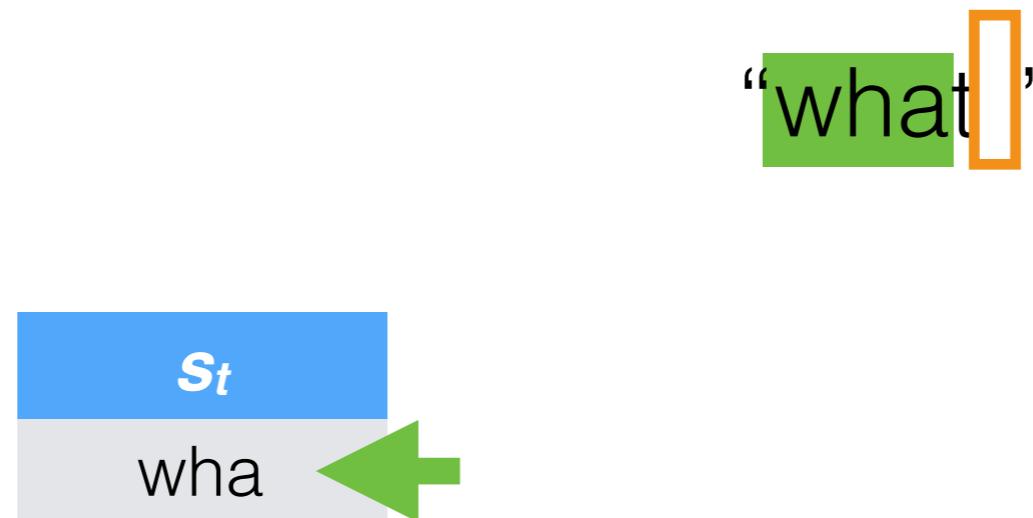
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“wha[]”

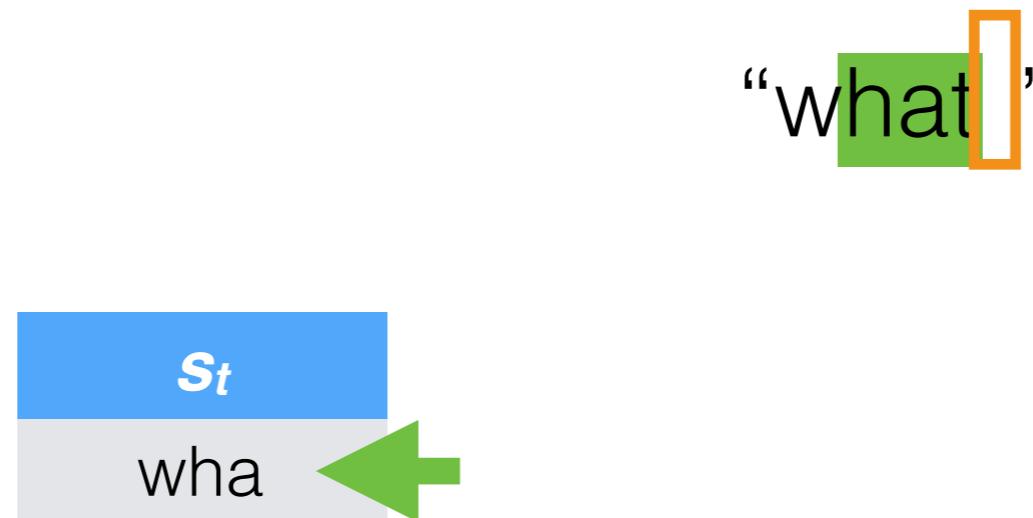
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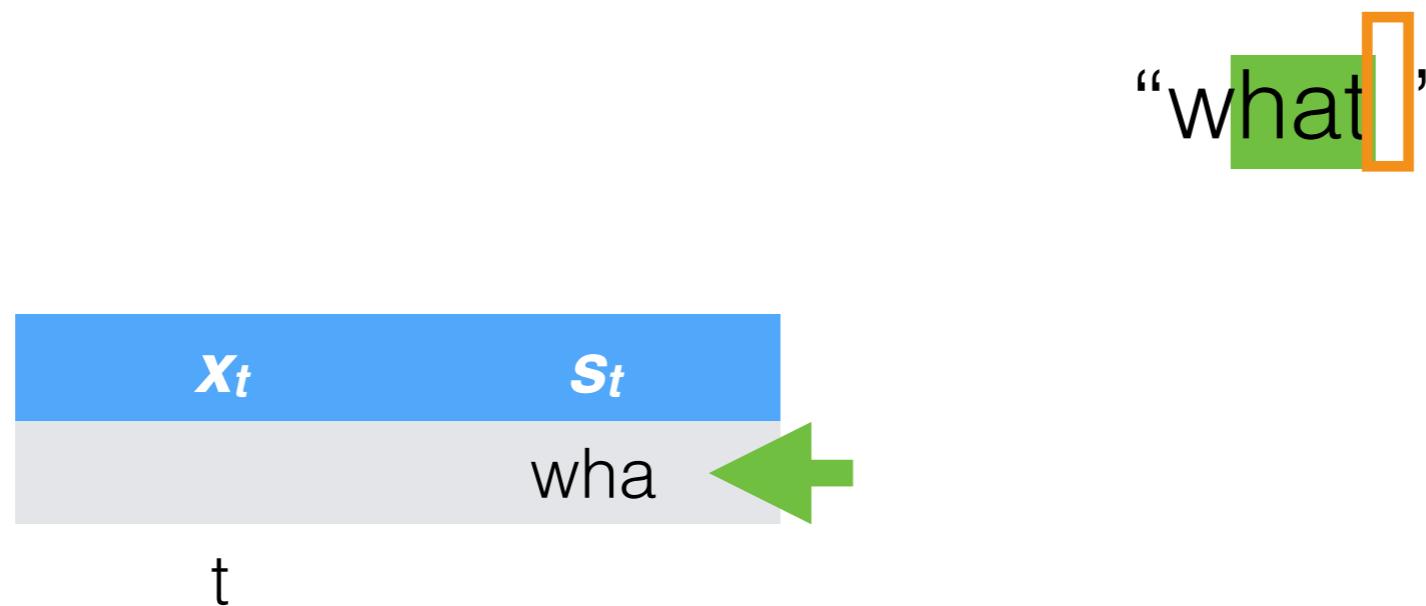
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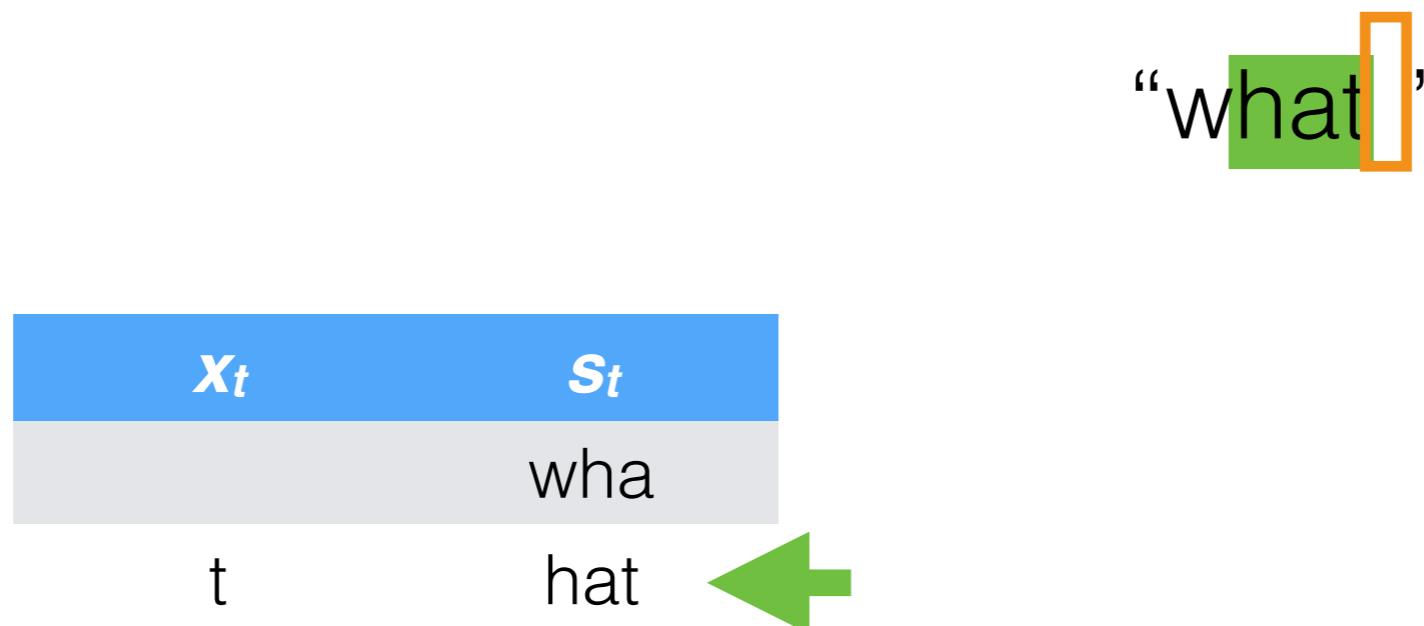
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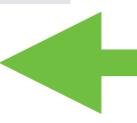
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Can express as a state machine

“what_”

x_t	s_t
	wha
t	hat



Can express as a state machine



Can express as a state machine

“what_”

X_t	S_t
	wha
t	hat
—	at_

Can express as a state machine

“what happens to a
dream deferred”

X_t	S_t
	wha
t	hat
—	at_
h	t_h

Can express as a state machine

- Recall state machines:

“what happens to a
dream deferred”

X_t	S_t
	wha
t	hat
—	at_
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Can express as a state machine

- Recall state machines:
 - Set of possible states S

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- Recall state machines:
 - Set of possible states S
- Example:
 - All ordered m characters

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x_t	s_t
	^ ^ ^
^	^ ^ ^
w	^ ^ w
h	^ w h
a	w h a
t	h a t
_	a t _

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t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ wh
4	a	wha
5	t	hat
6	_	at_

“^what happens to a
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Can express as a state machine

- Recall state machines:
 - Set of possible states S
 - Set of possible inputs \mathcal{X}
 - Initial state
 - Transition function $f(s,x)$
- Example:
 - All ordered m characters
 - All characters
 - m start characters

t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
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 - Transition function $f(s,x)$
- Example:
 - All ordered m characters
 - All characters
 - m start characters
 - Update last m chars

t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
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t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
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 - Transition function $f(s,x)$
 - Set of possible outputs
- Example:
 - All ordered m characters
 - All characters
 - m start characters
 - Update last m chars
 - All vectors of char probs

t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
6	_	a t _

“^what happens to a
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Can express as a state machine

- Recall state machines:
 - Set of possible states S
 - Set of possible inputs \mathcal{X}
 - Initial state
 - Transition function $f(s,x)$
 - Set of possible outputs
 - Output function $g(s)$
- Example:
 - All ordered m characters
 - All characters
 - m start characters
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t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
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- Example:
 - All ordered m characters
 - All characters
 - m start characters
 - Update last m chars
 - All vectors of char probs
 - Multi-class linear classifier

t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
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 - Multi-class linear classifier
- $x^{(1)}$: “^what happens to a dream deferred”

t	x_t	s_t
0		^
1	^	^w
2	w	^w
3	h	^wh
4	a	wha
5	t	hat
6	_	at_

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t	x_t	s_t
0		^ ^ ^
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- Example:
 - All ordered m characters
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- $x^{(1)}$: “^what happens to a dream deferred”
- $x^{(2)}$: “^if you can keep your head when all about you”
- $x^{(3)}$: “^you may write me down in history”

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- | t | $x^{(1)}_t$ | s_t |
|-----|-------------|-------|
| 0 | | ^ |
| 1 | ^ | ^w |
| 2 | w | ^w |
| 3 | h | ^wh |
| 4 | a | wha |
| 5 | t | hat |
| 6 | _ | at_ |

Can express as a state machine

t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
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Can express as a state machine

s_0

t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
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Can express as a state machine

s_0

x_1

t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
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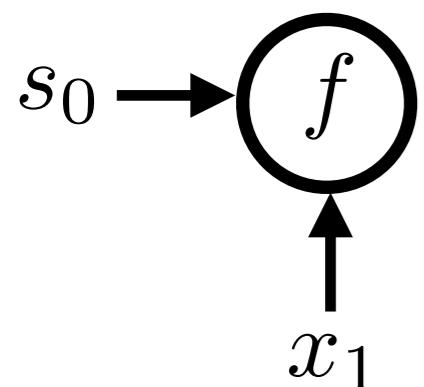
$s_0 \rightarrow$



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ wh
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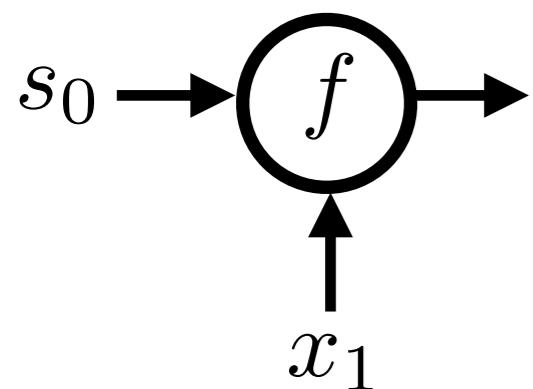
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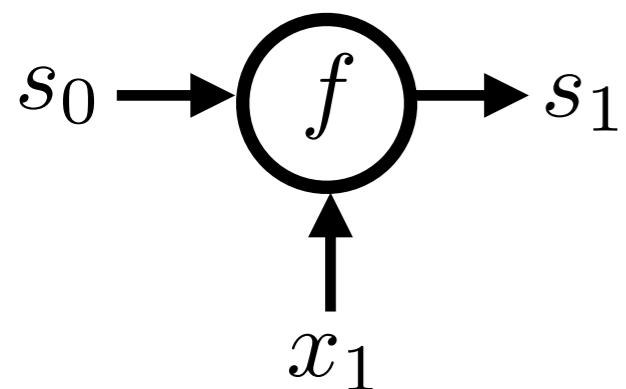
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
6	_	at_

- $x^{(1)}$: “^what happens to a dream deferred”
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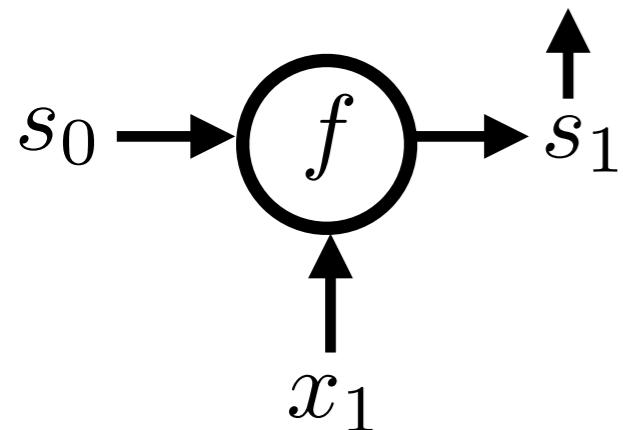
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
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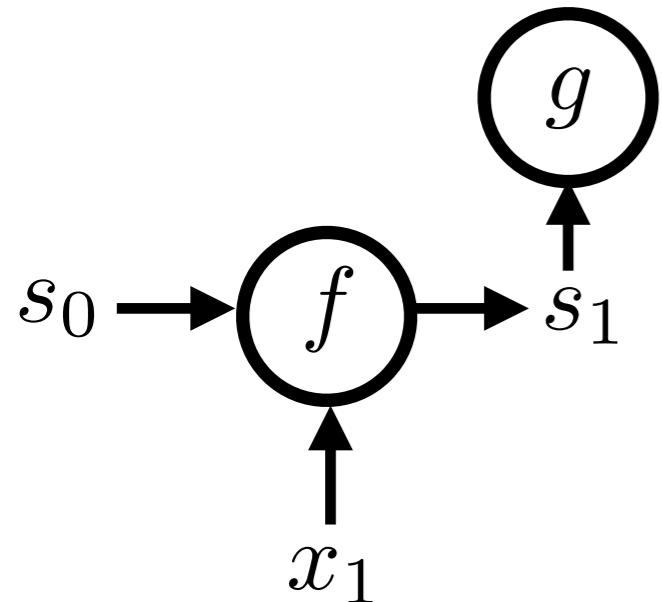
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
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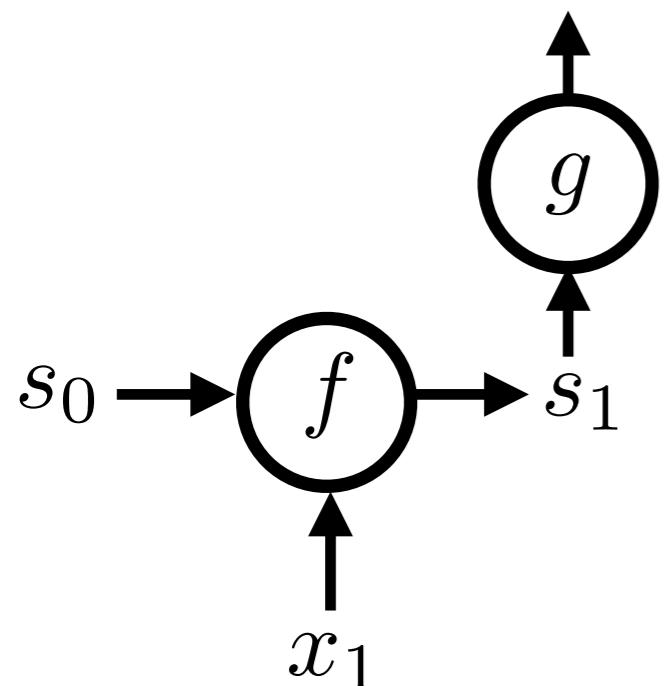
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
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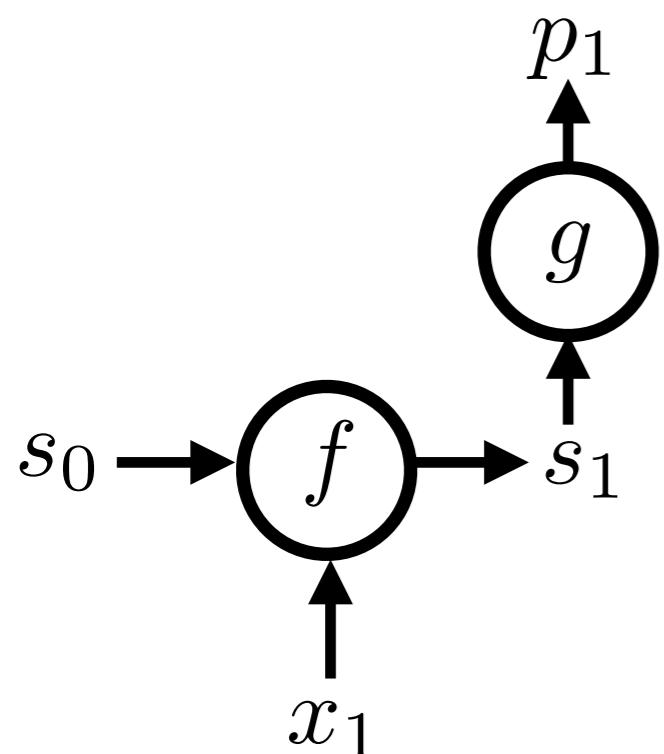
Can express as a state machine



<i>t</i>	<i>X_t</i>	<i>S_t</i>
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
6	_	at_

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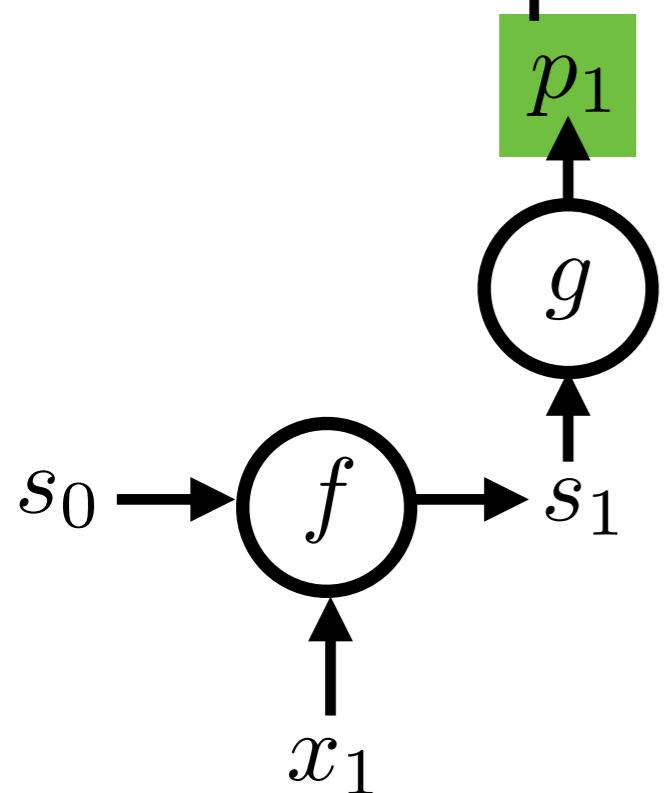
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
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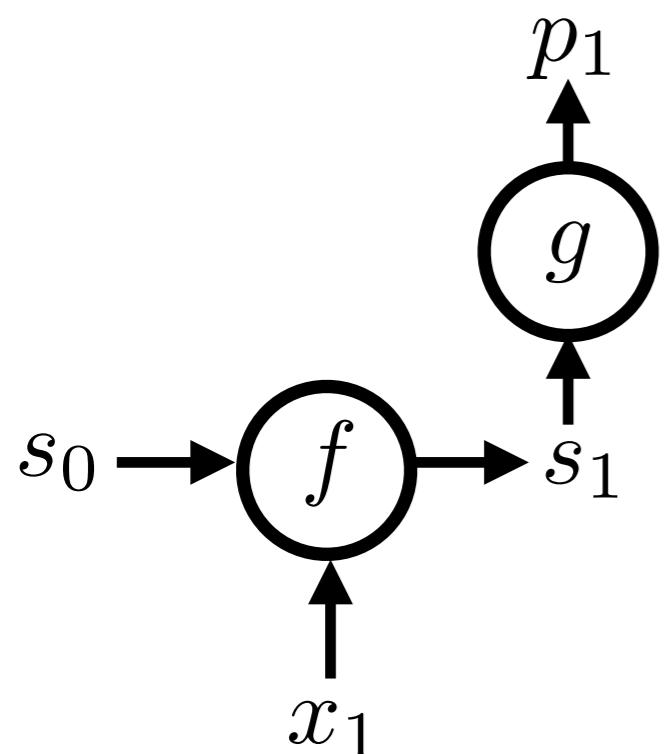
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
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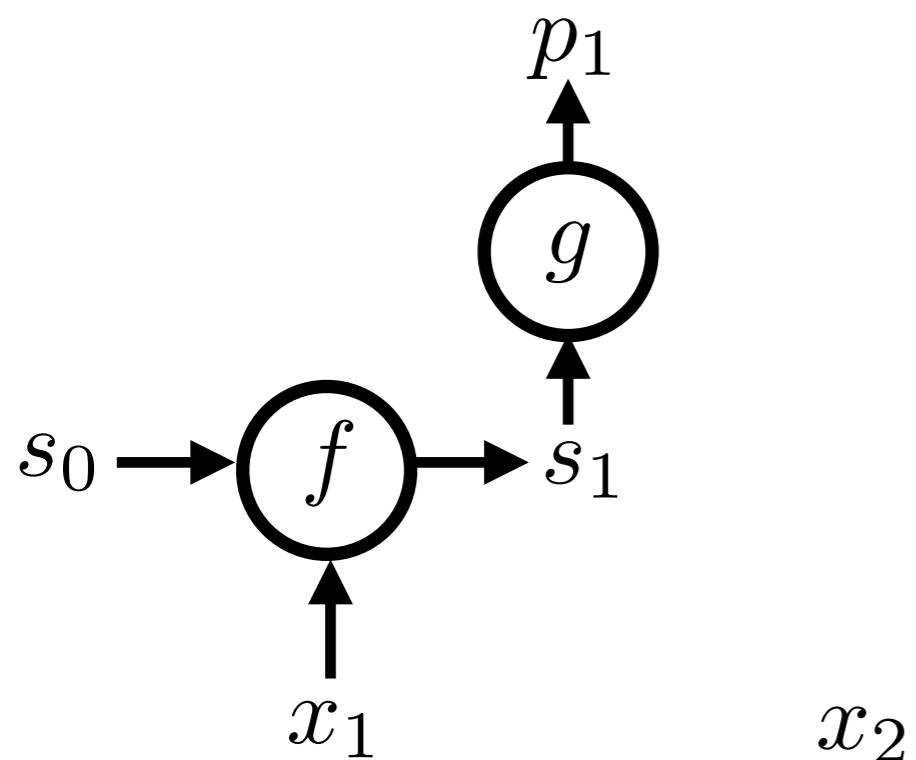
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
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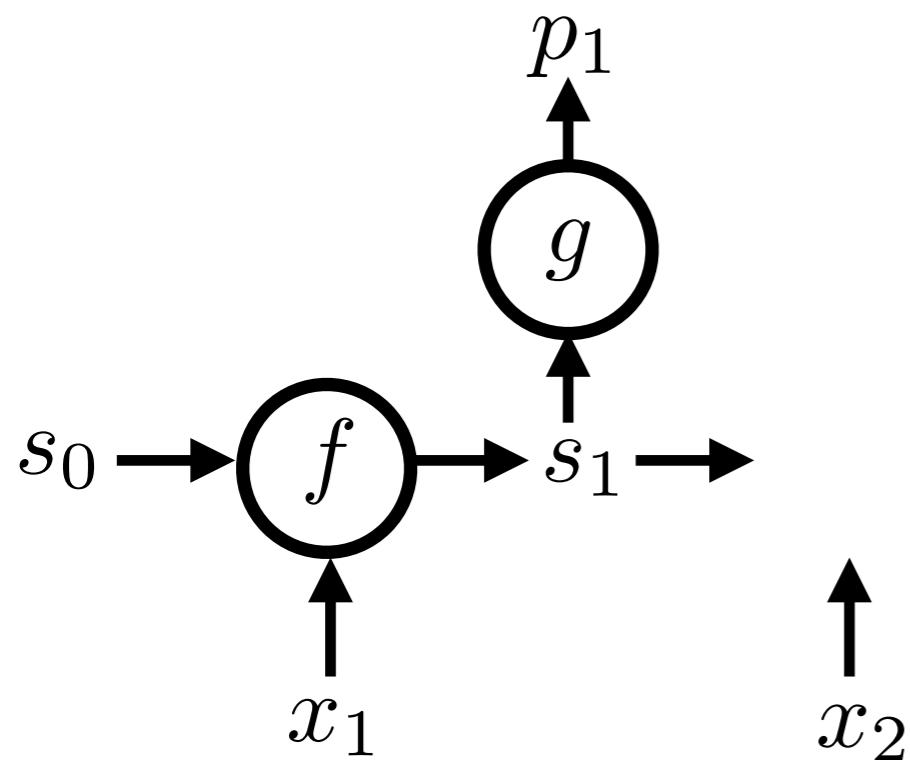
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
6	_	at_

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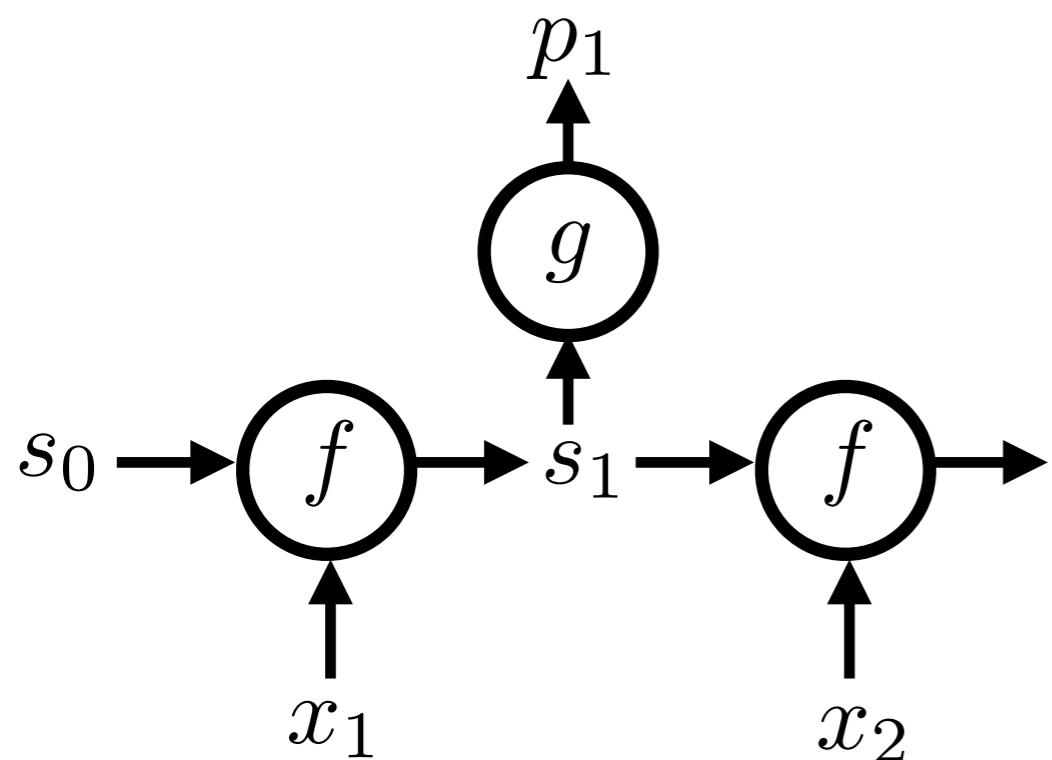
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
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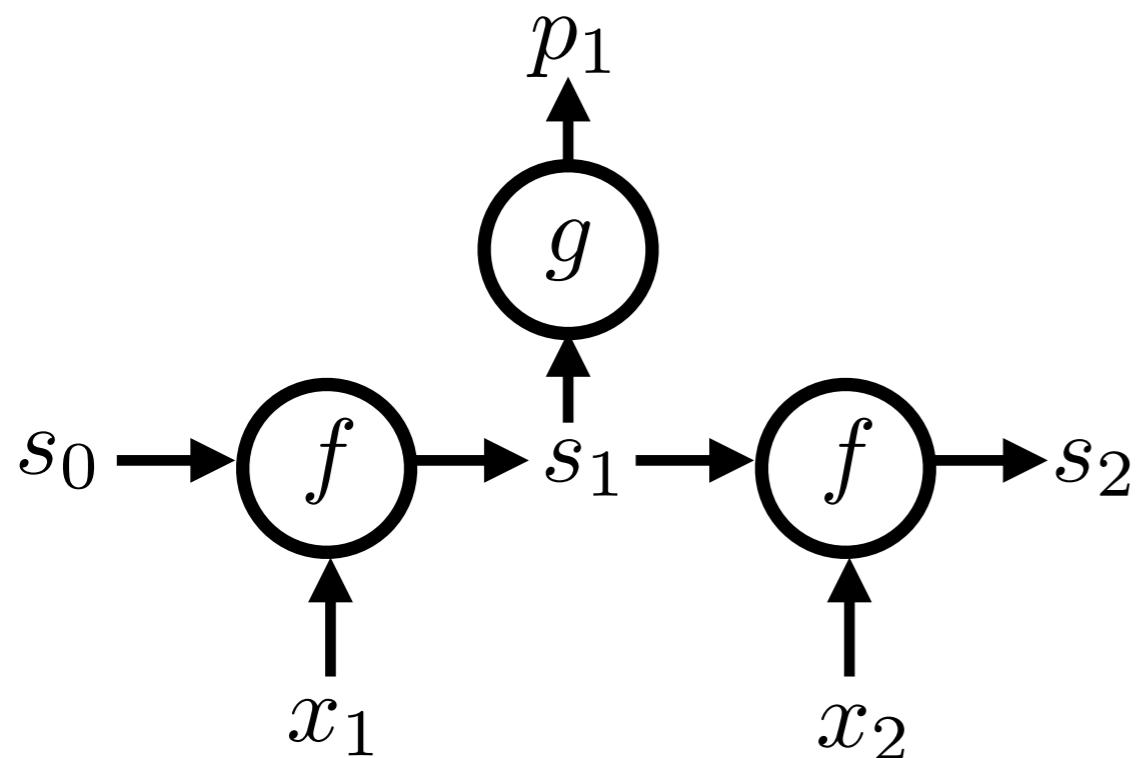
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
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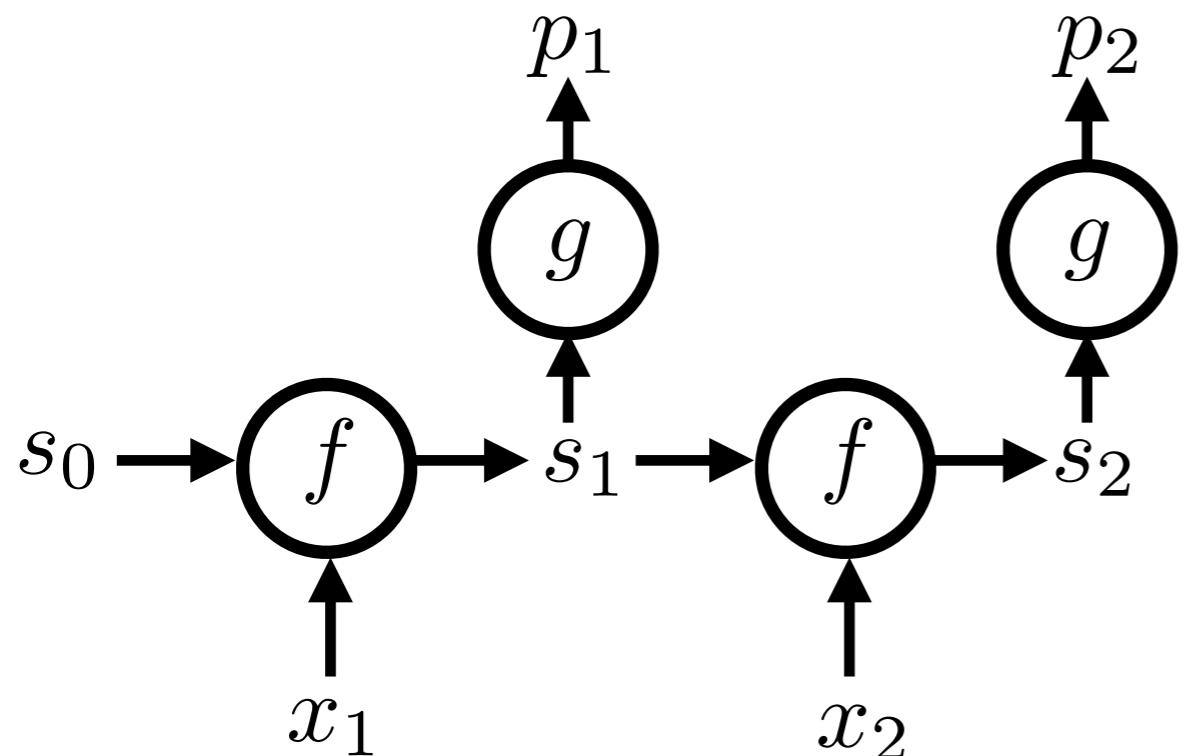
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
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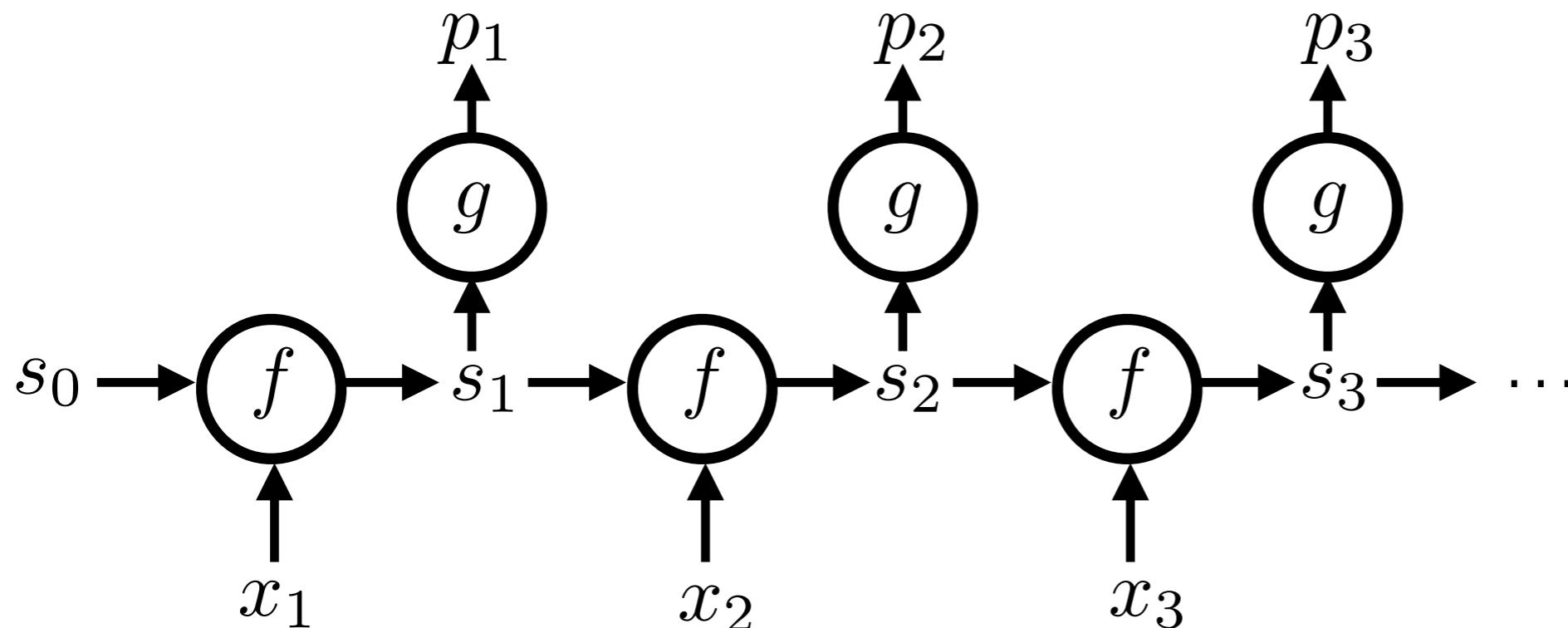
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
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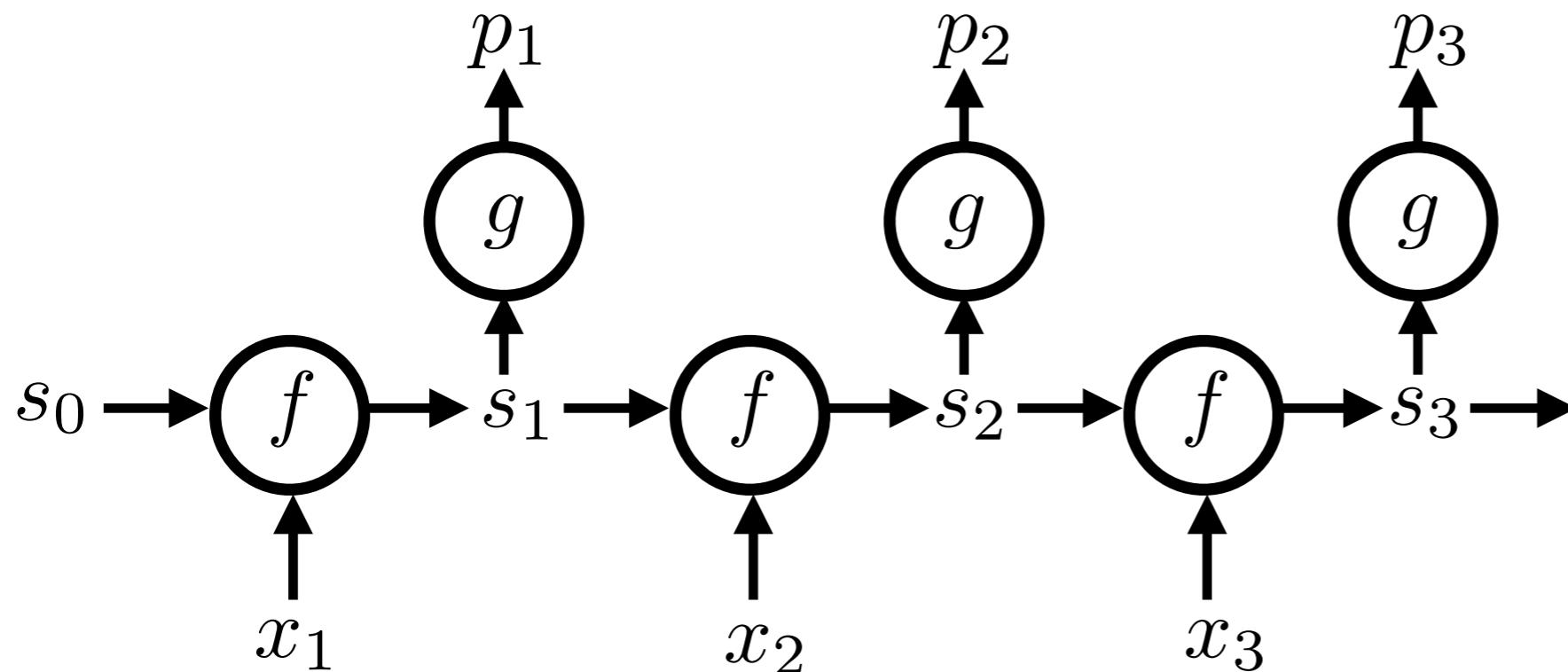
Can express as a state machine



t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
6	_	at _

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Can express as a state machine

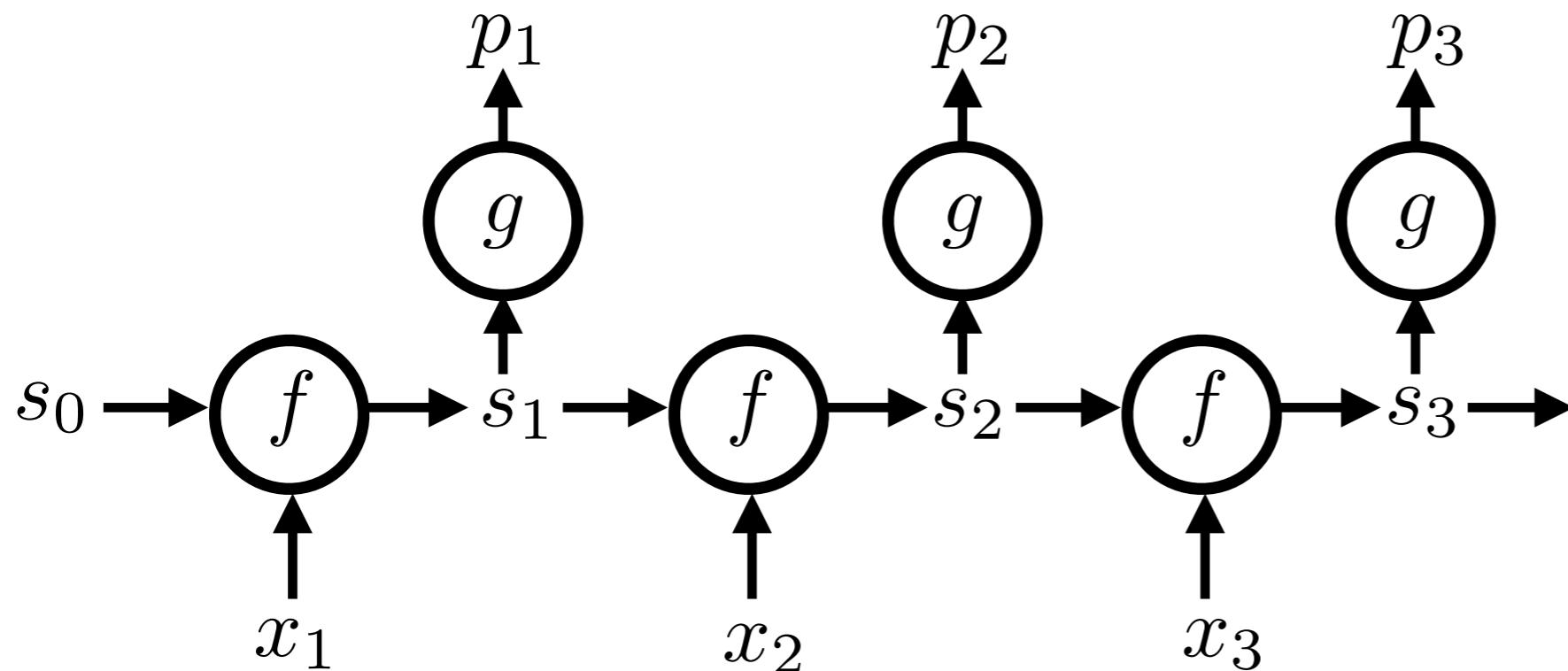


- m : number of characters in the context
- v : number of characters in the alphabet

t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
4	a	w h a
5	t	h a t
6	_	at_

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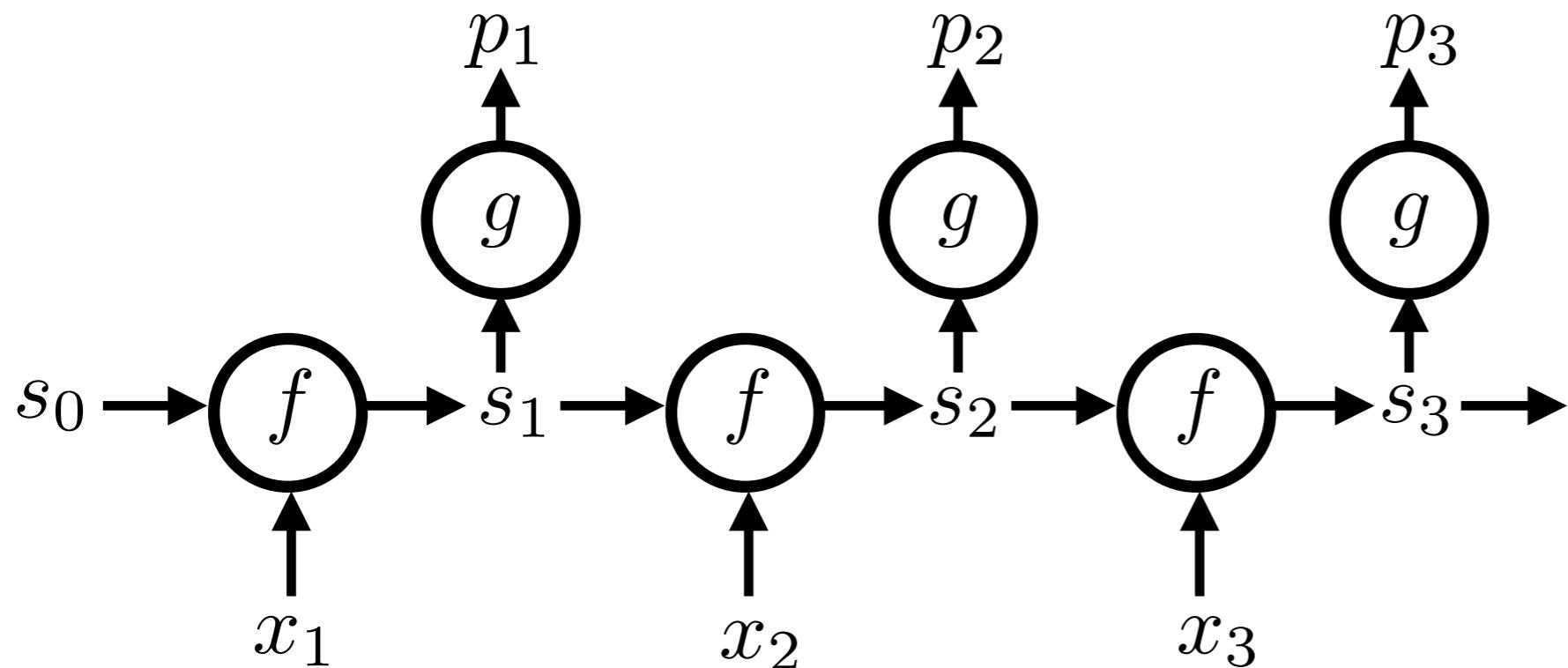


- m : number of characters in the context
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t	x_t	s_t
0		^ ^ ^
1	^	^ ^ ^
2	w	^ ^ w
3	h	^ w h
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6	_	at _

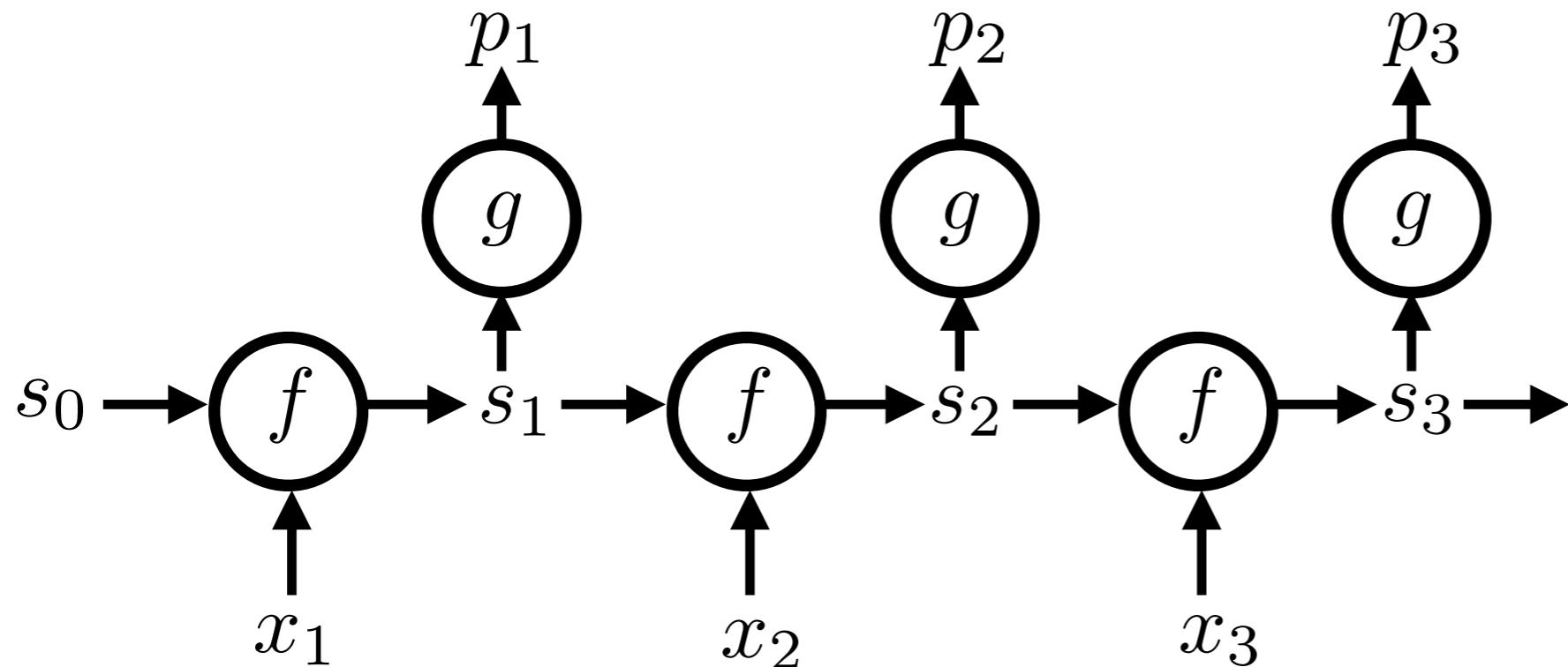
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Can express as a state machine



- m : number of characters in the context
- v : number of characters in the alphabet

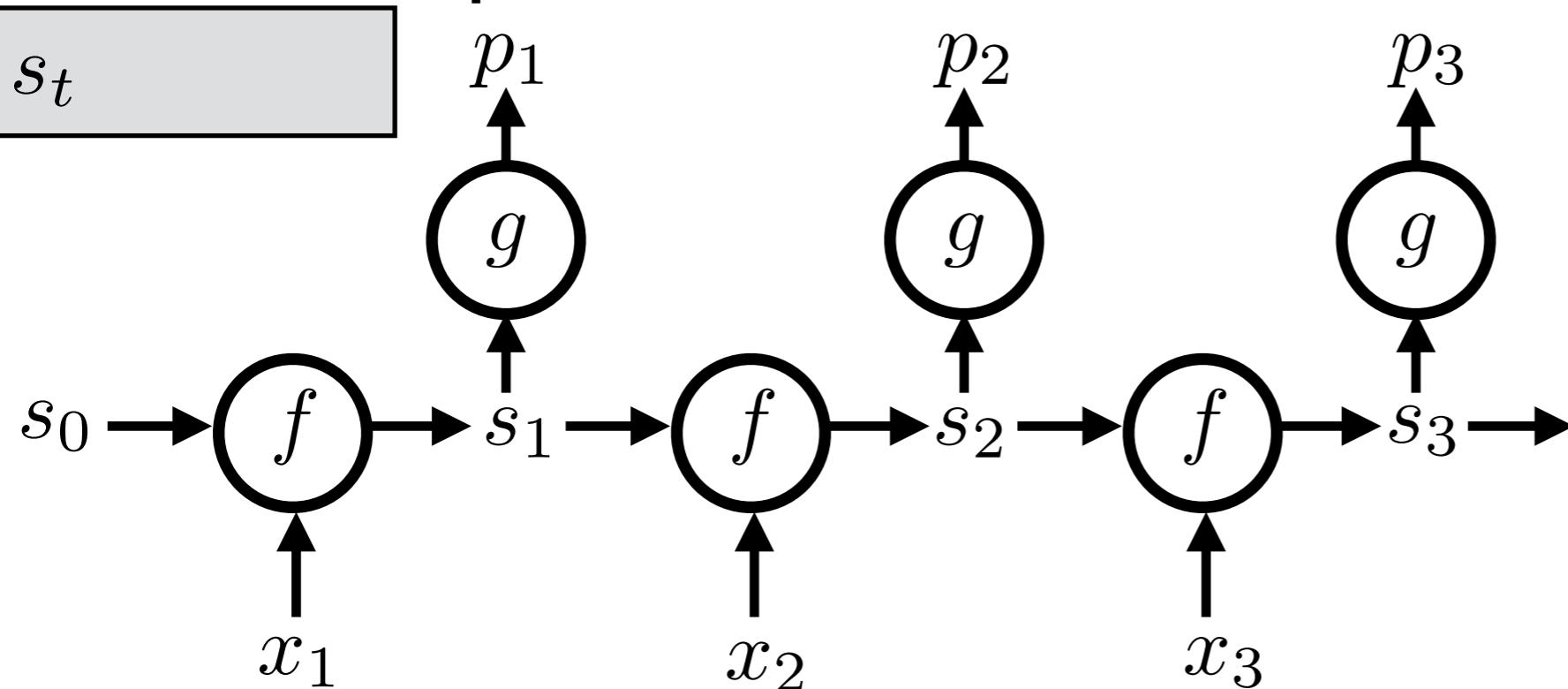
Can express as a state machine



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

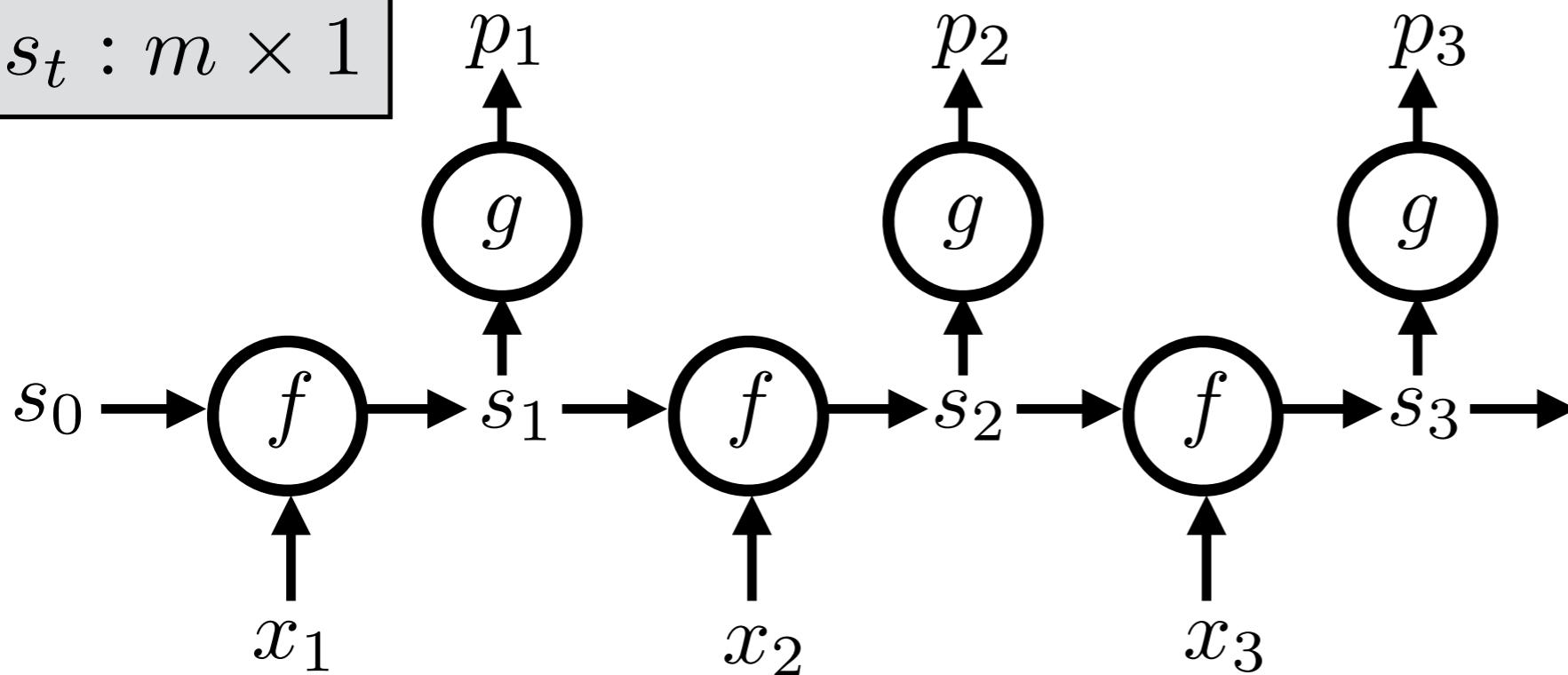


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Can express as a state machine

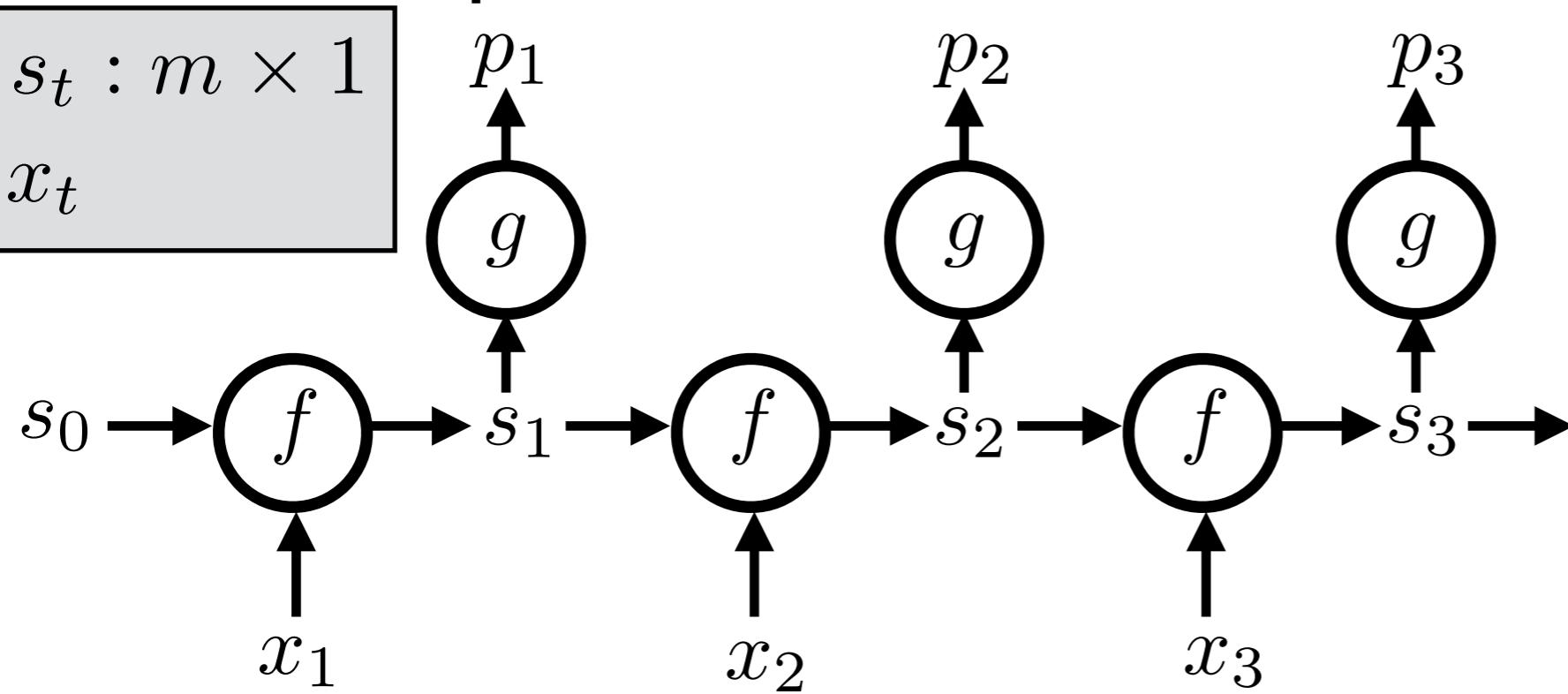
$$s_t : m \times 1$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

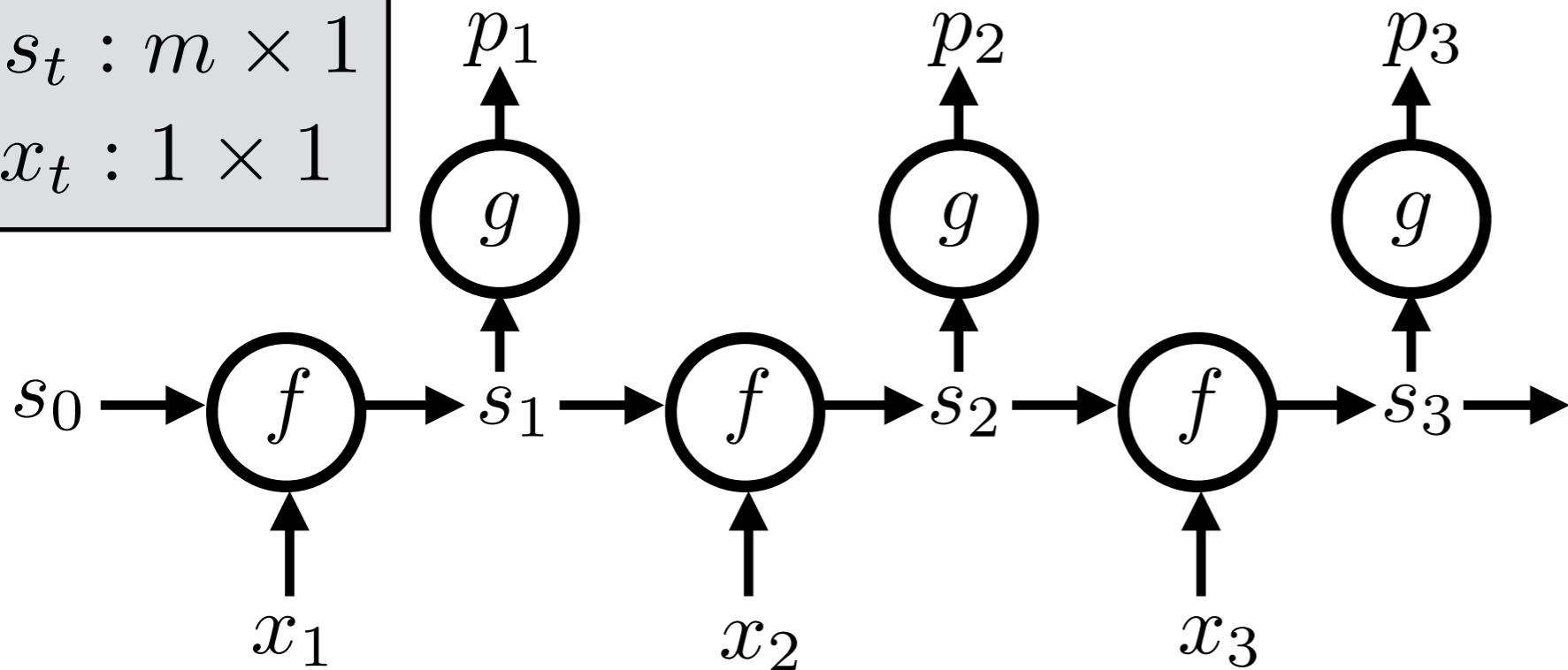


- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1\end{aligned}$$

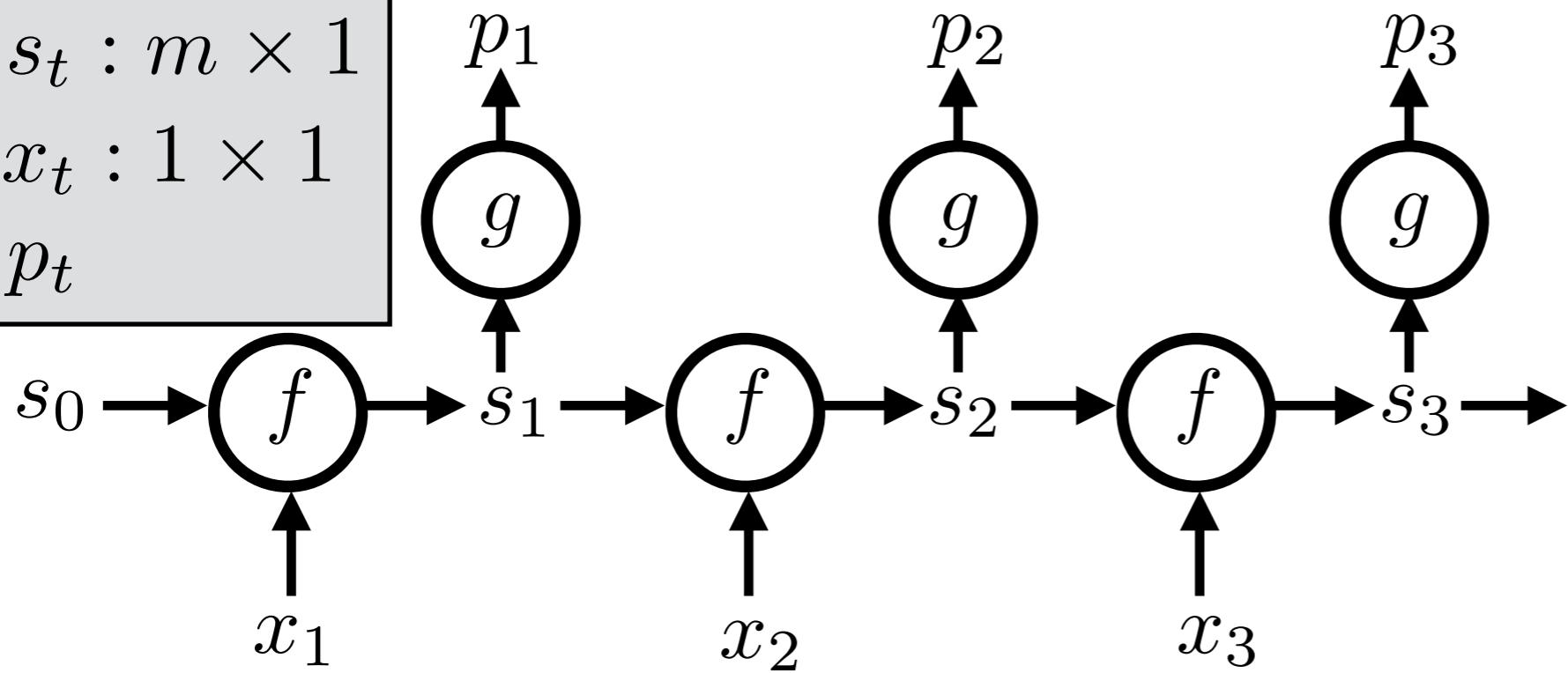


- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$s_t : m \times 1$
 $x_t : 1 \times 1$
 p_t

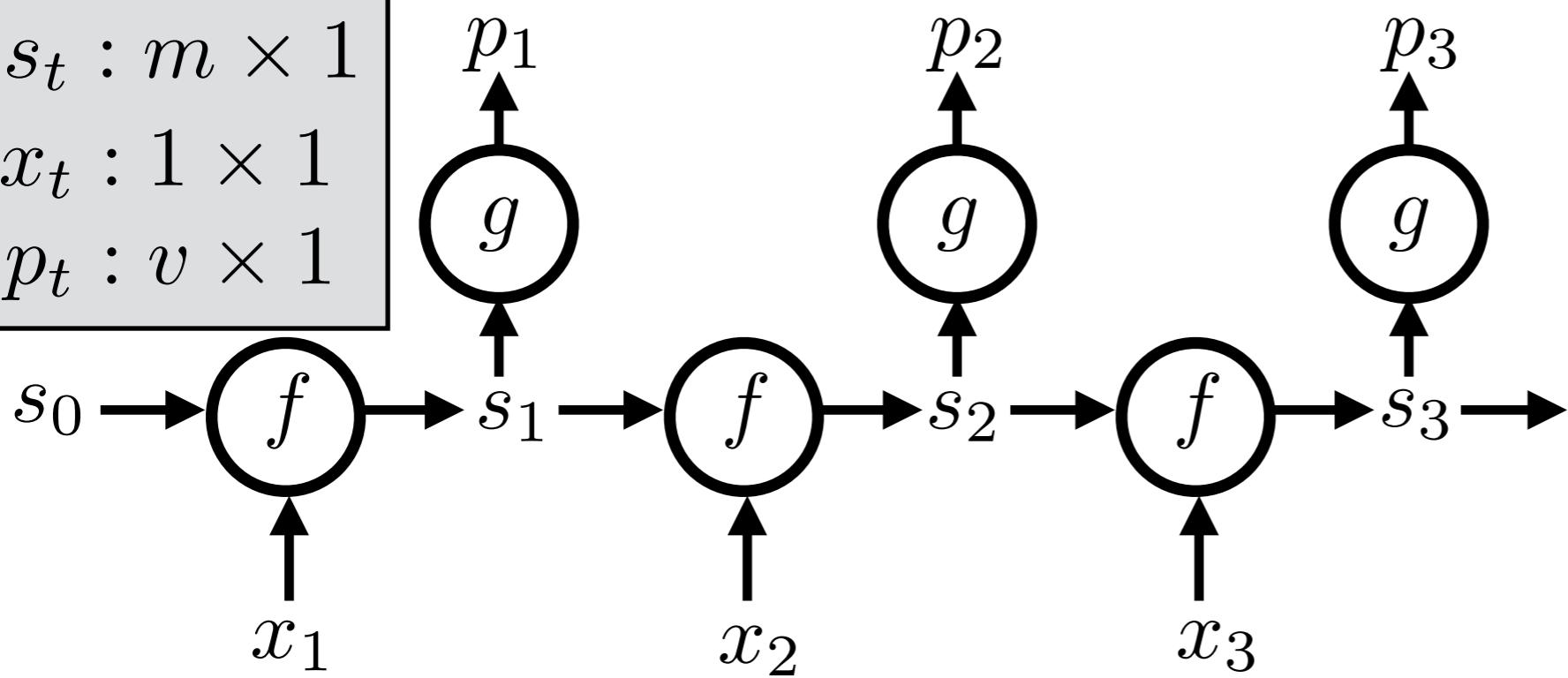


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- m : number of characters in the context
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Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$

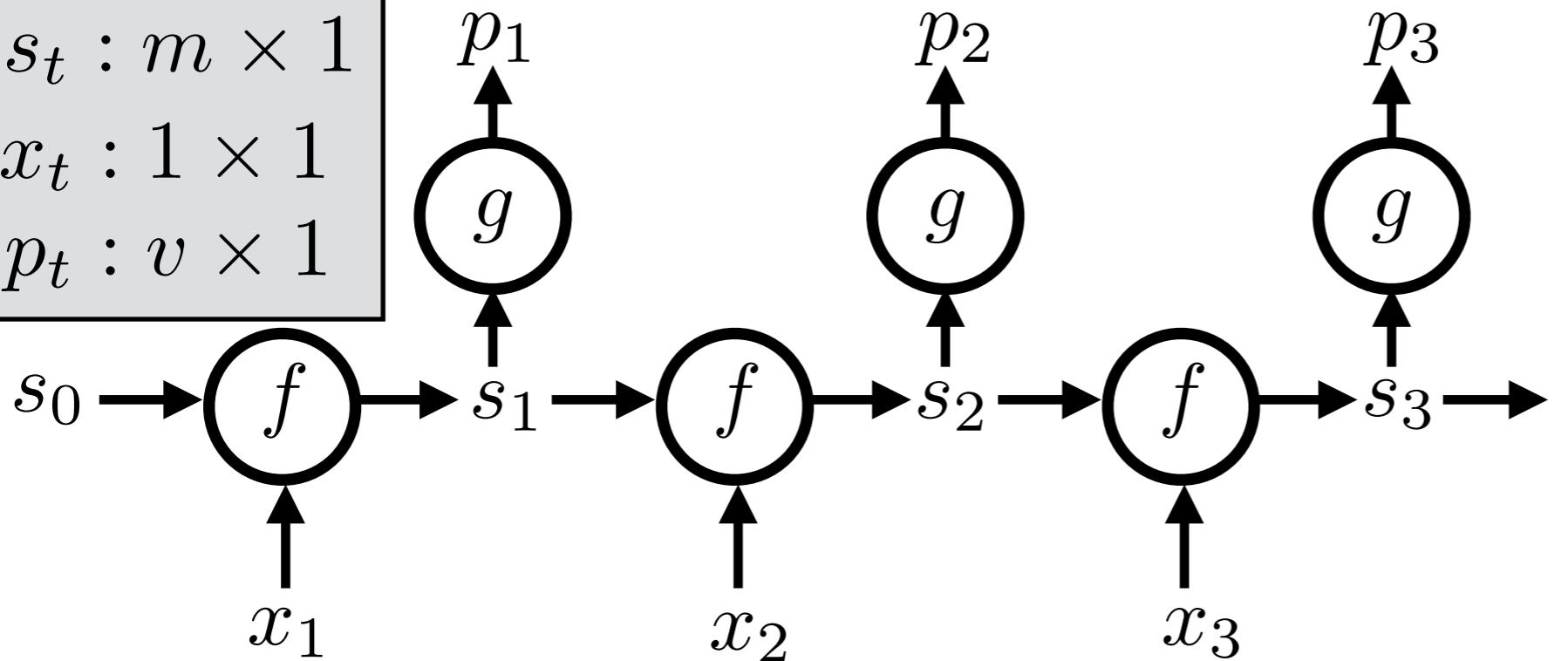


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$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



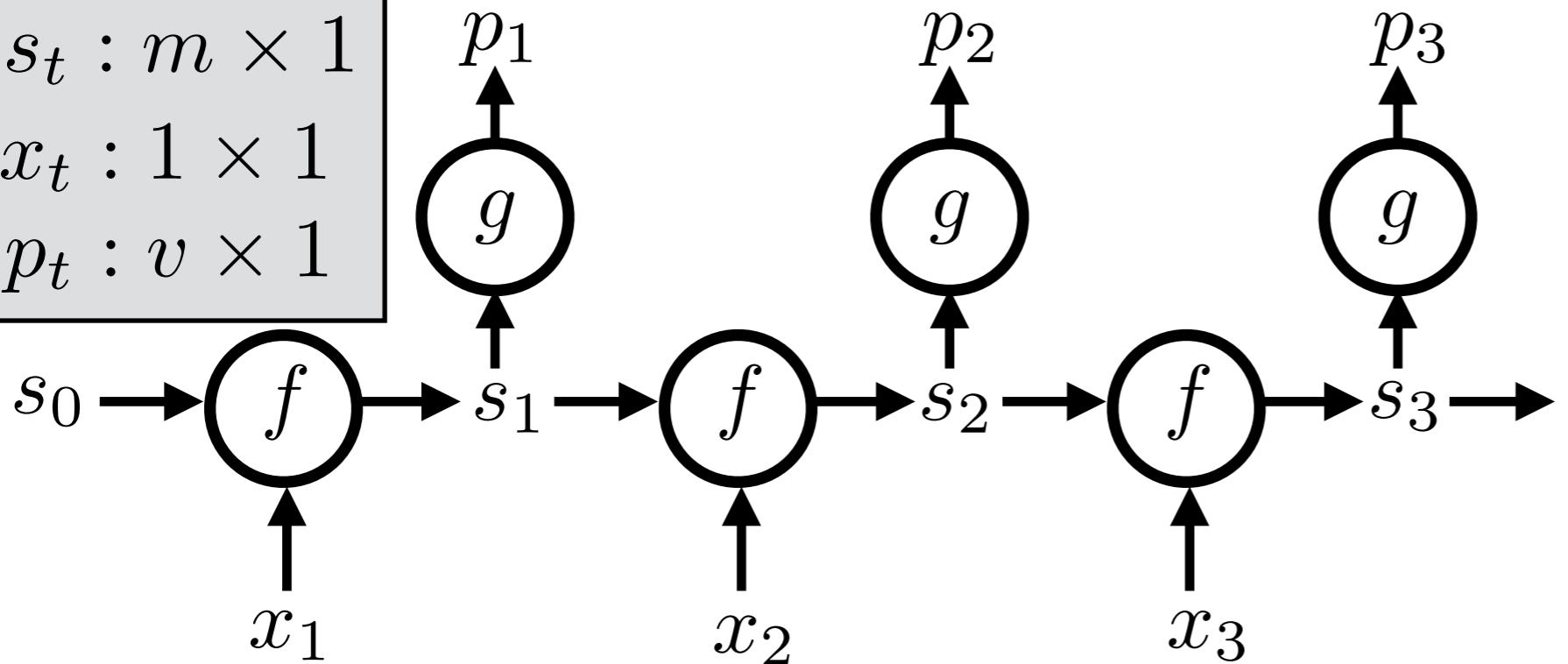
- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) =$$

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



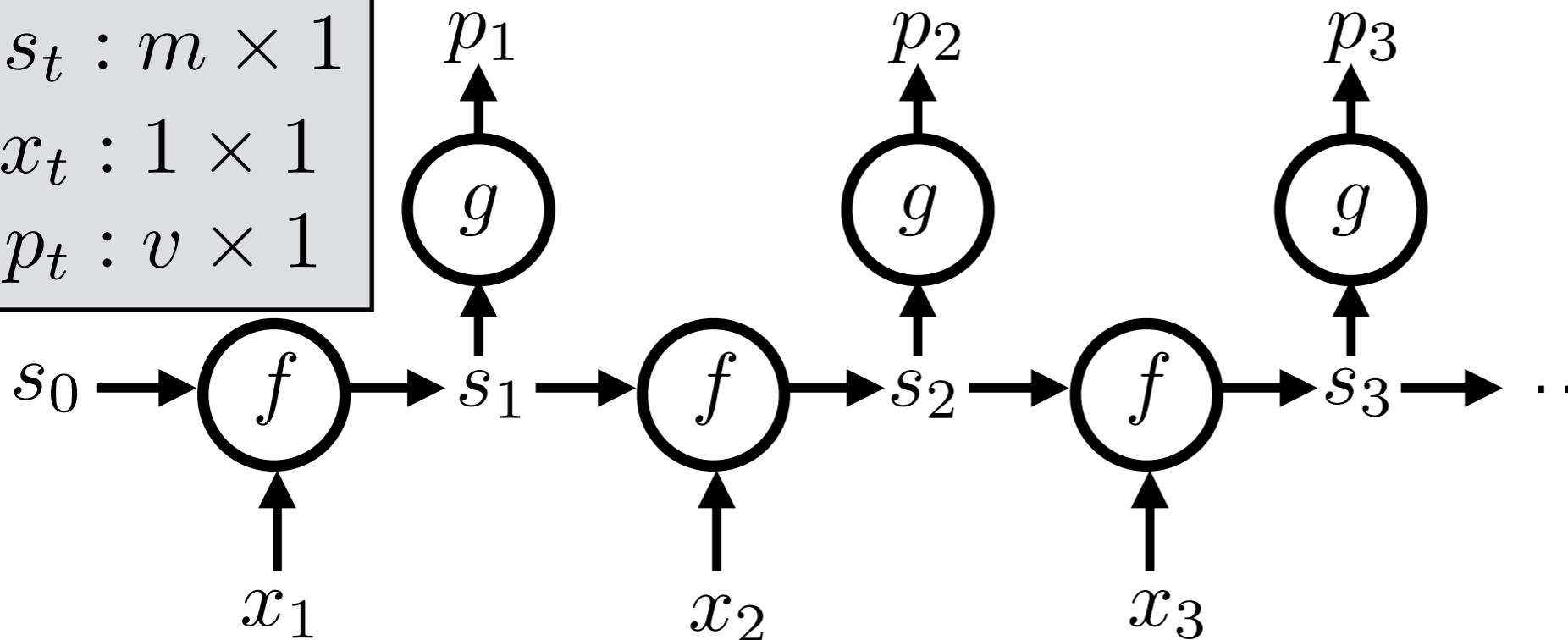
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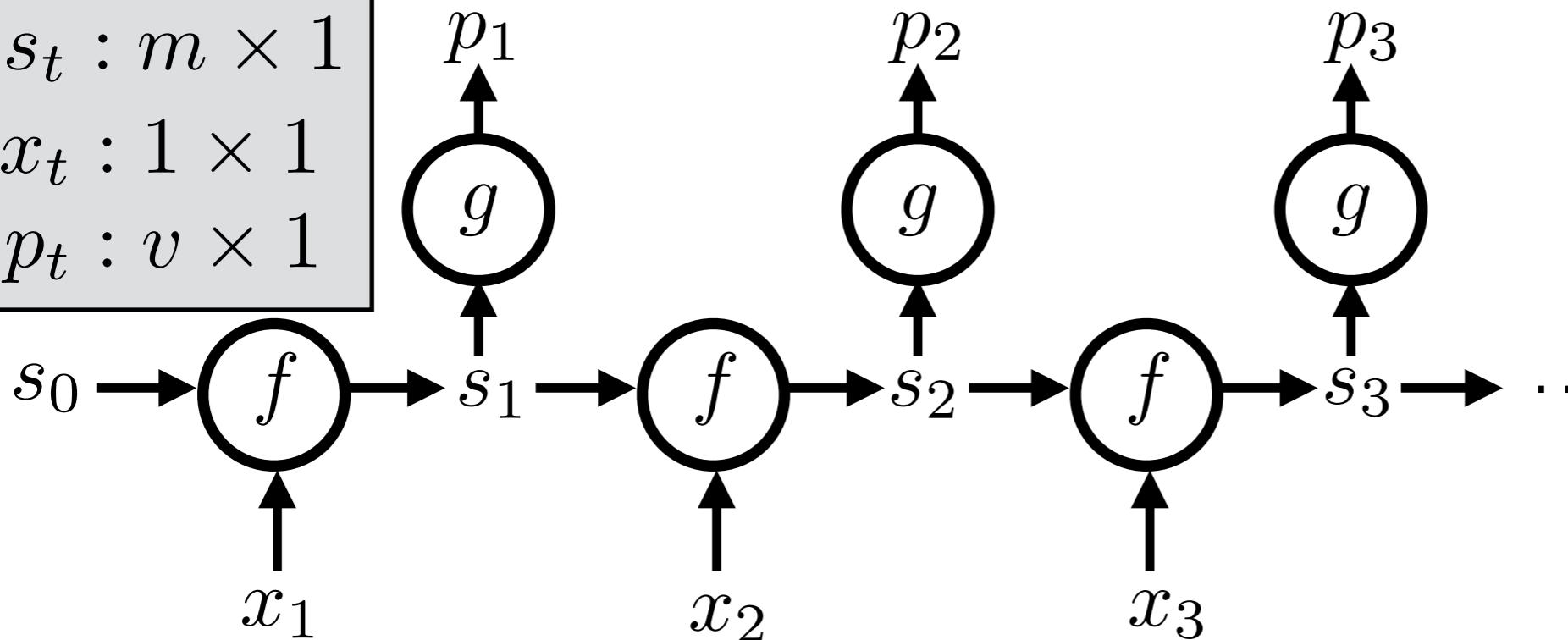
- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \boxed{?} x_t + \boxed{?} s_{t-1}$$

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



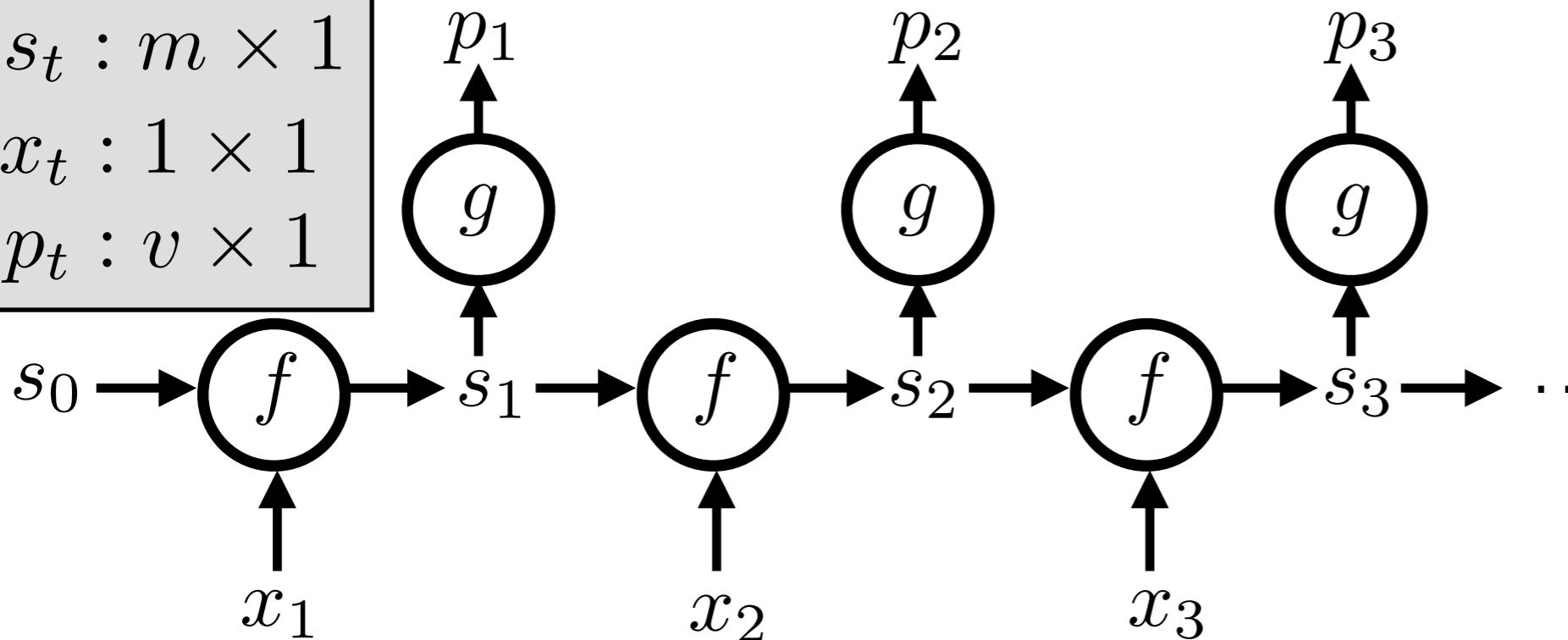
- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{matrix} ? \\ x_t + \end{matrix} s_{t-1}$$

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



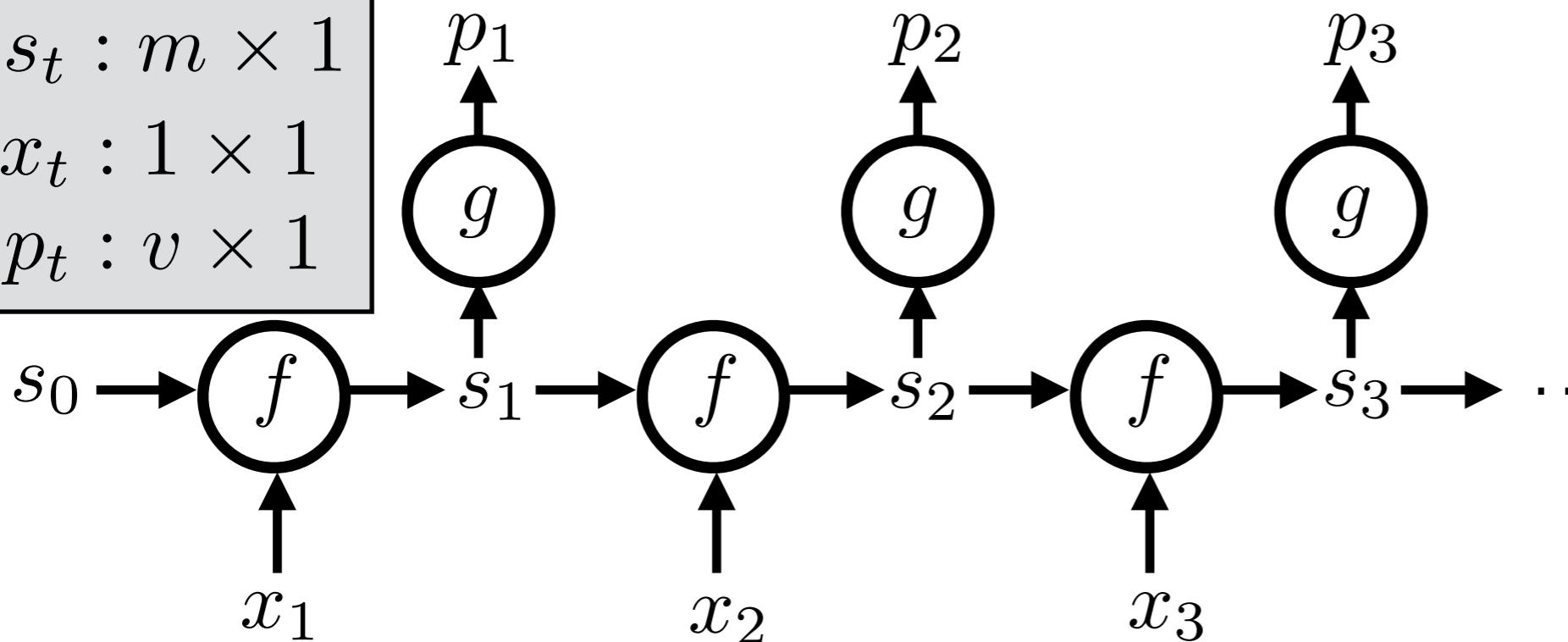
- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{matrix} ? \\ 3 \times 1 \end{matrix} x_t + \begin{matrix} ? \\ 1 \times 1 \end{matrix} s_{t-1}$$

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



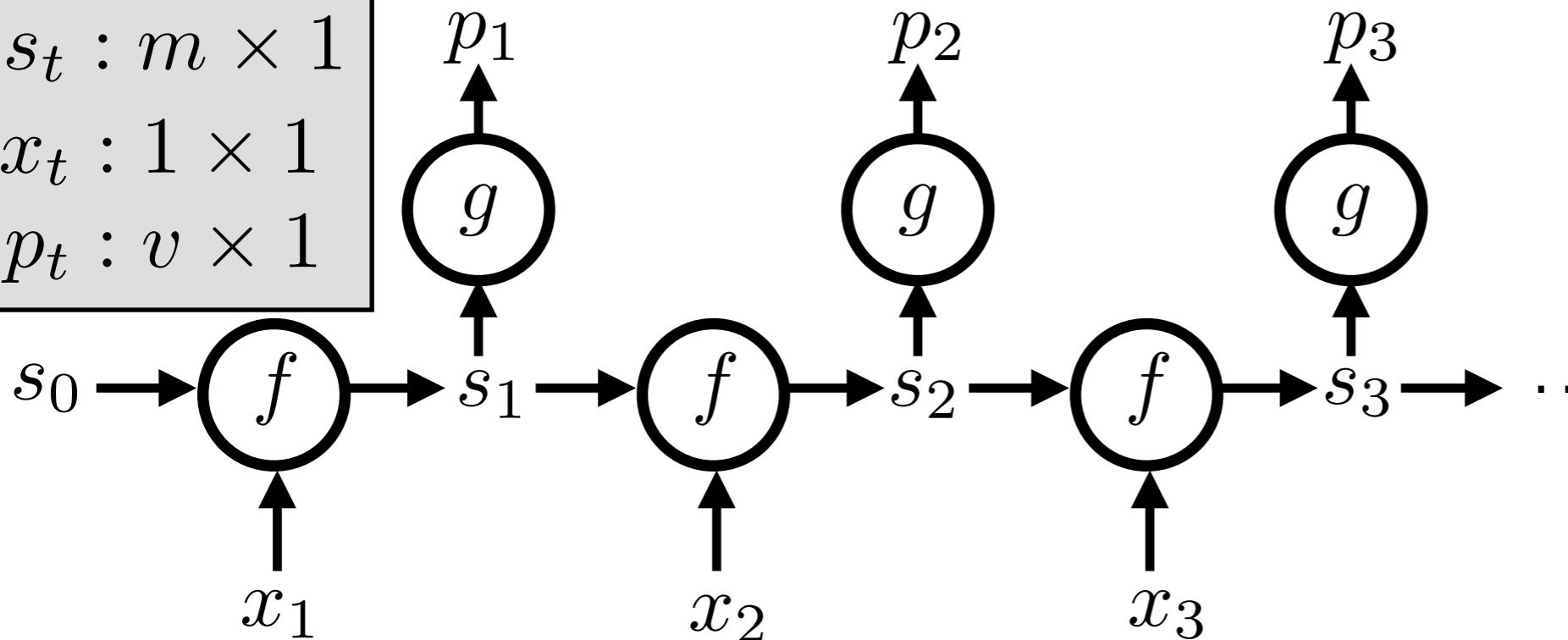
- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{matrix} ? \\ 3 \times 1 \end{matrix} x_t + \begin{matrix} ? \\ 3 \times 1, 1 \times 1 \end{matrix} s_{t-1}$$

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

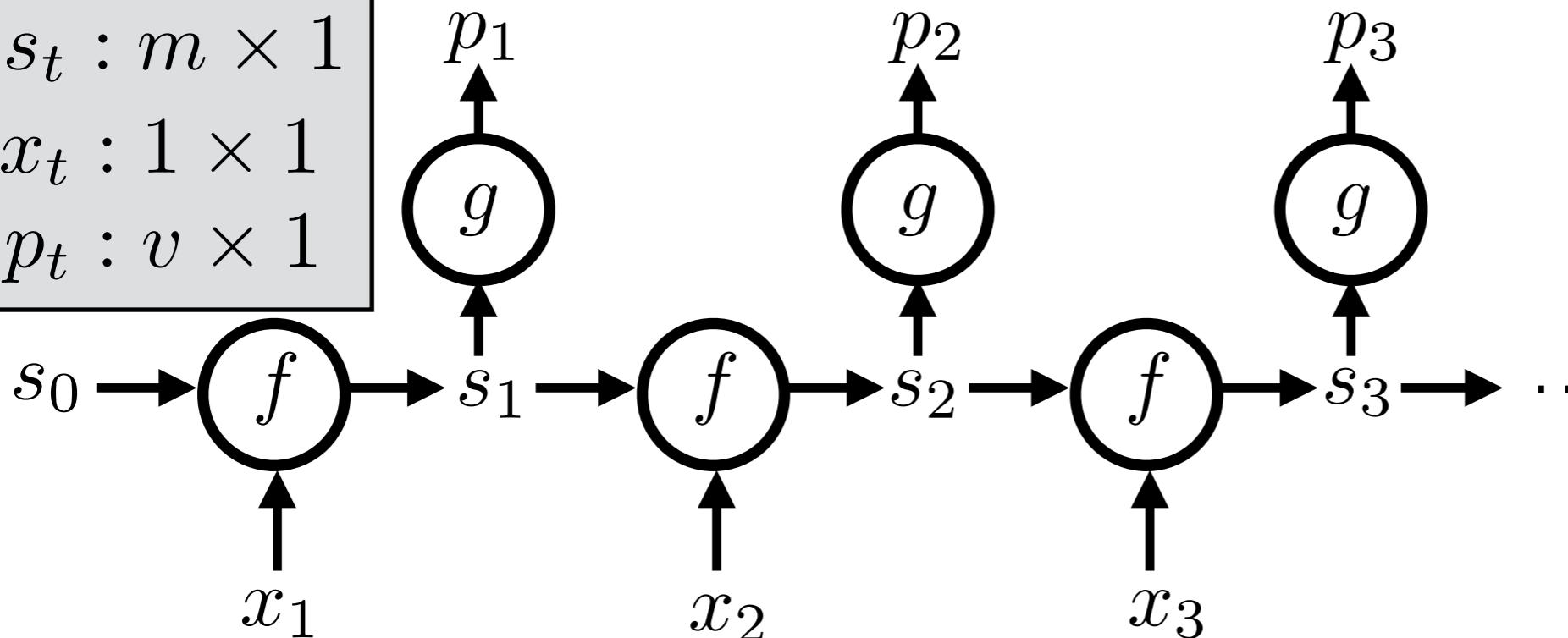
$$s_t = f(s_{t-1}, x_t) = \begin{matrix} ? \\ 3 \times 1 \end{matrix}$$

$$x_t + \begin{matrix} ? \\ 3 \times 1, 1 \times 1 \end{matrix} s_{t-1}$$

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$

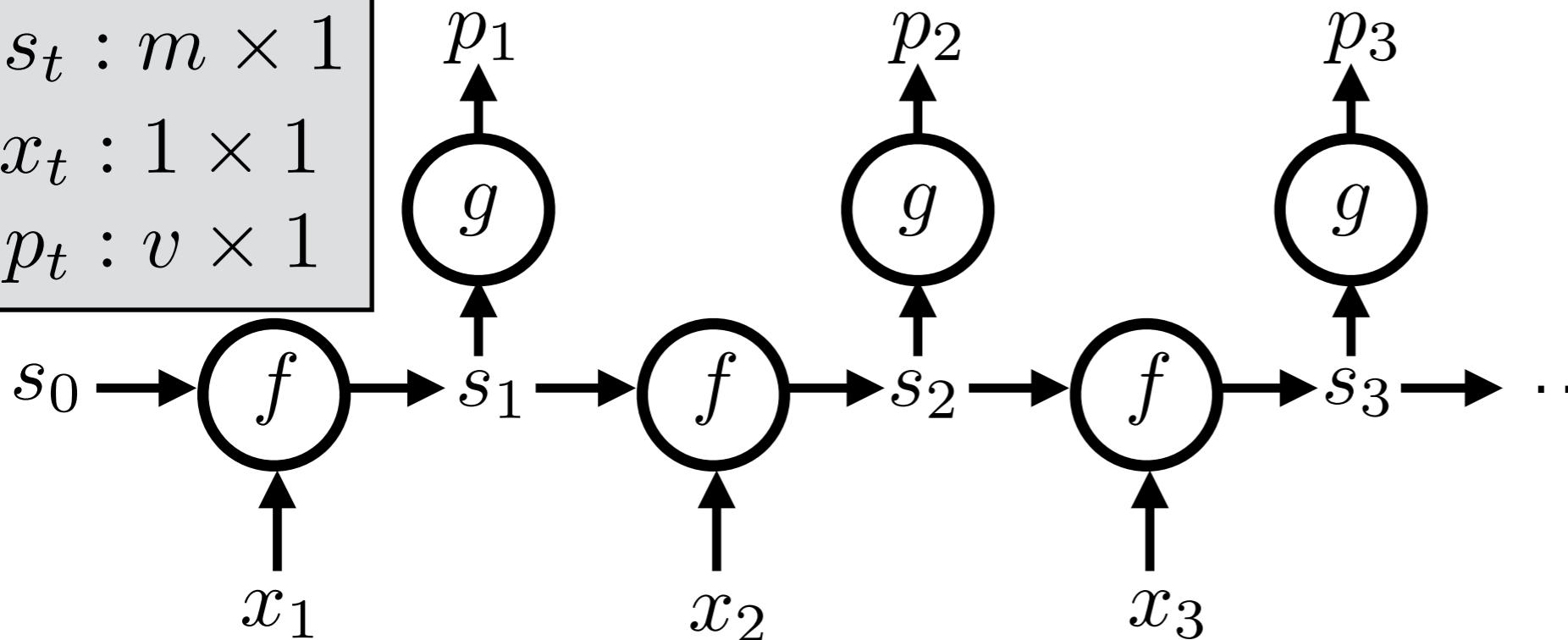


- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \text{? } s_{t-1}$$

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$

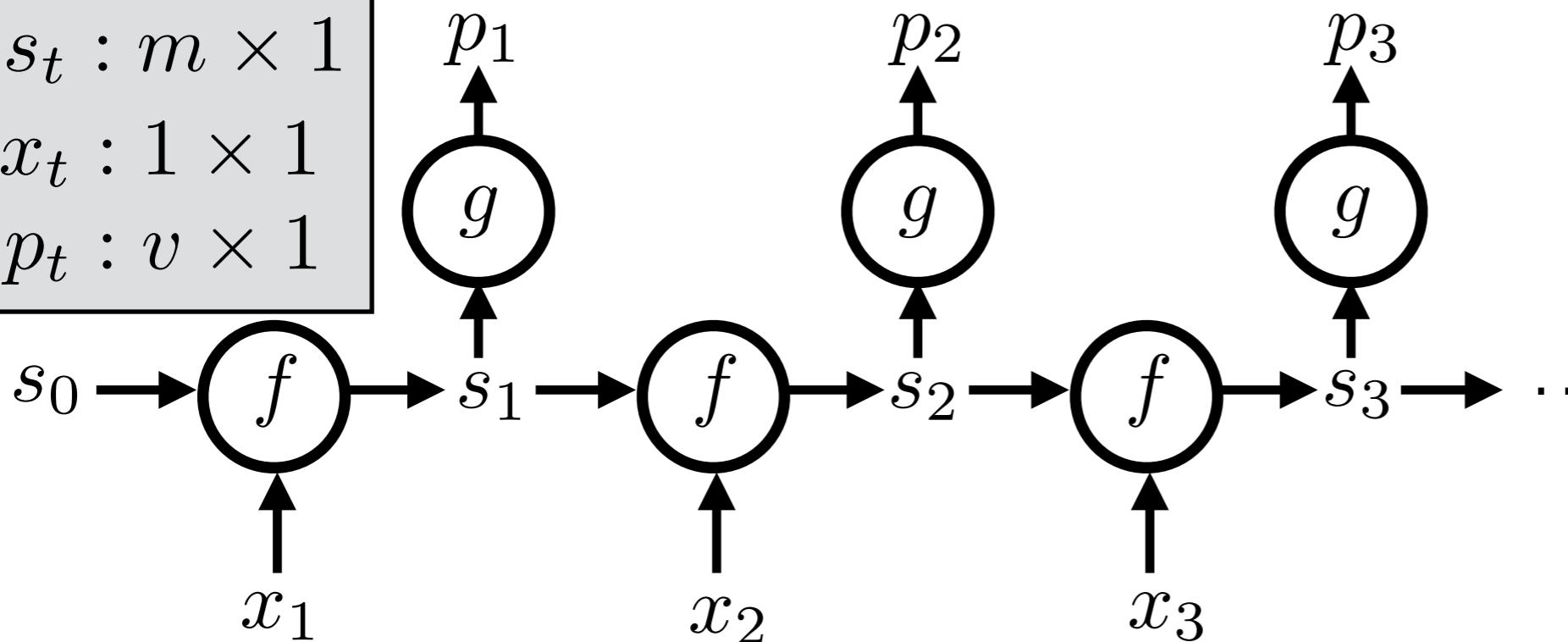


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Can express as a state machine

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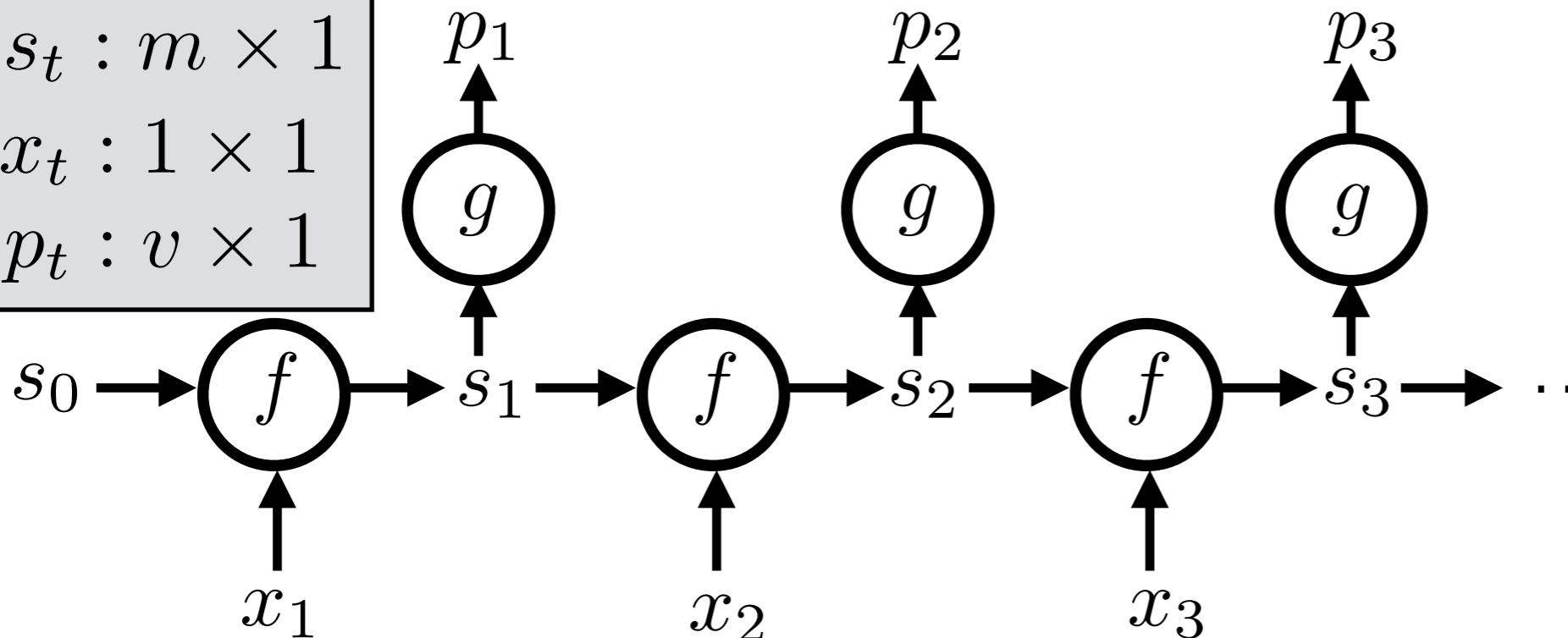
- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



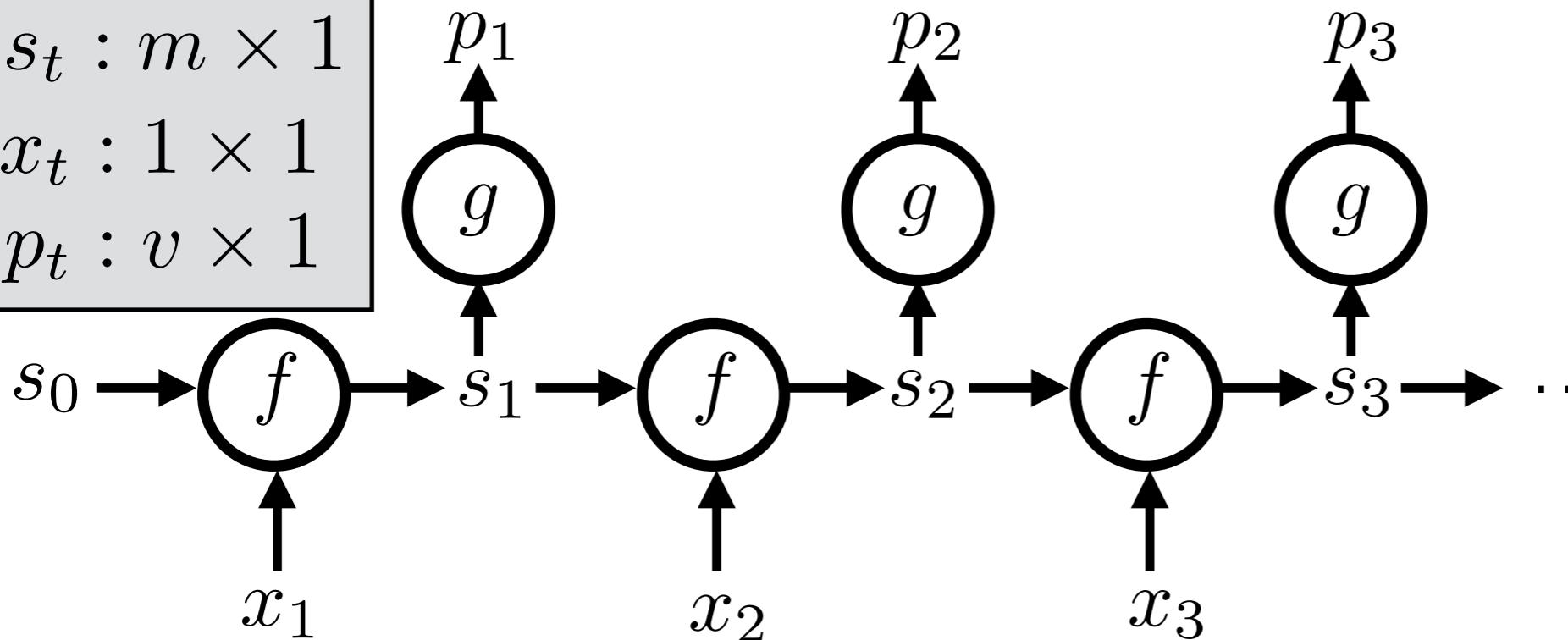
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Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



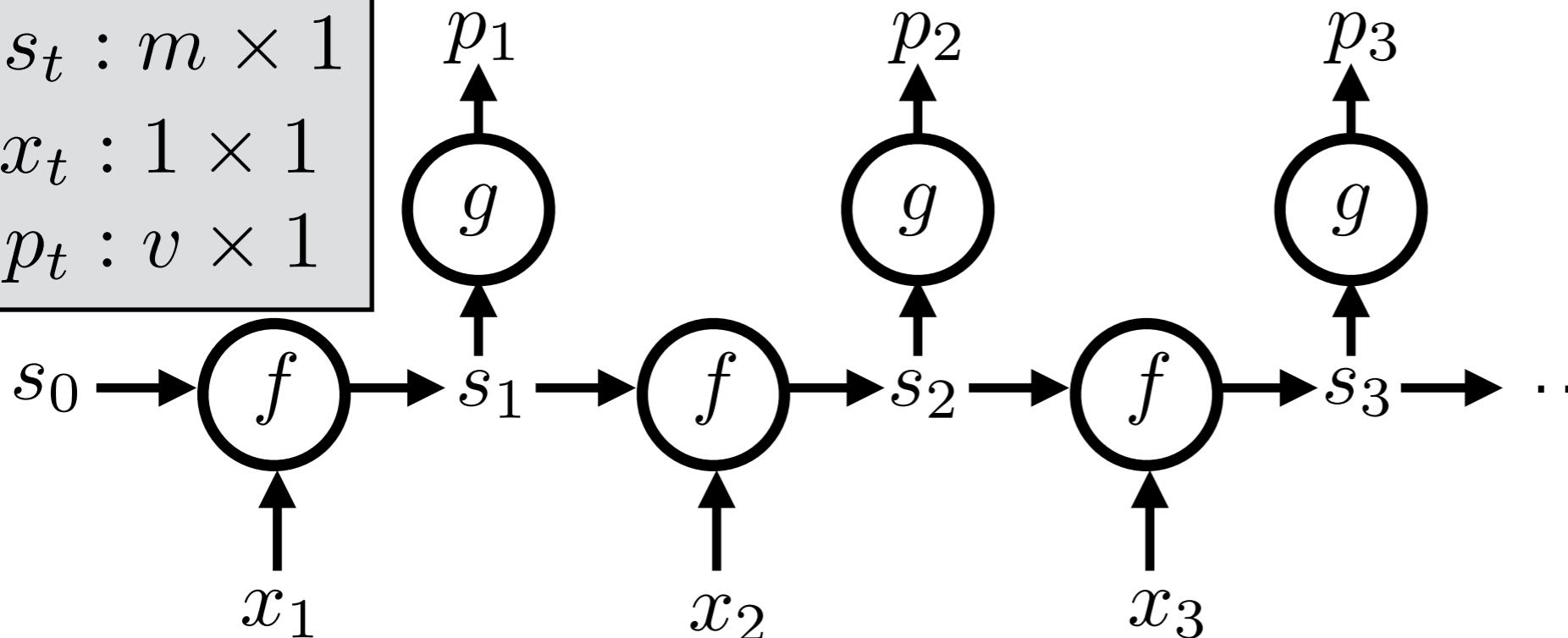
- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

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- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



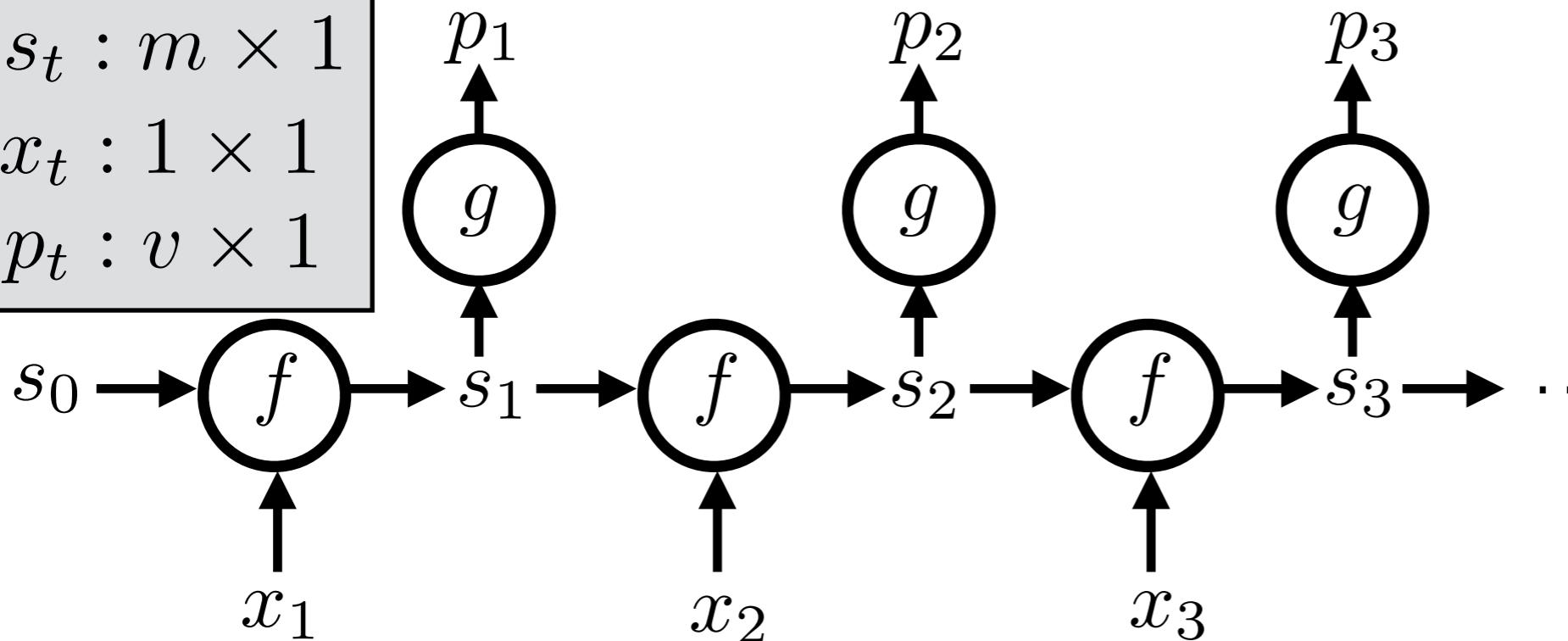
- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

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- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



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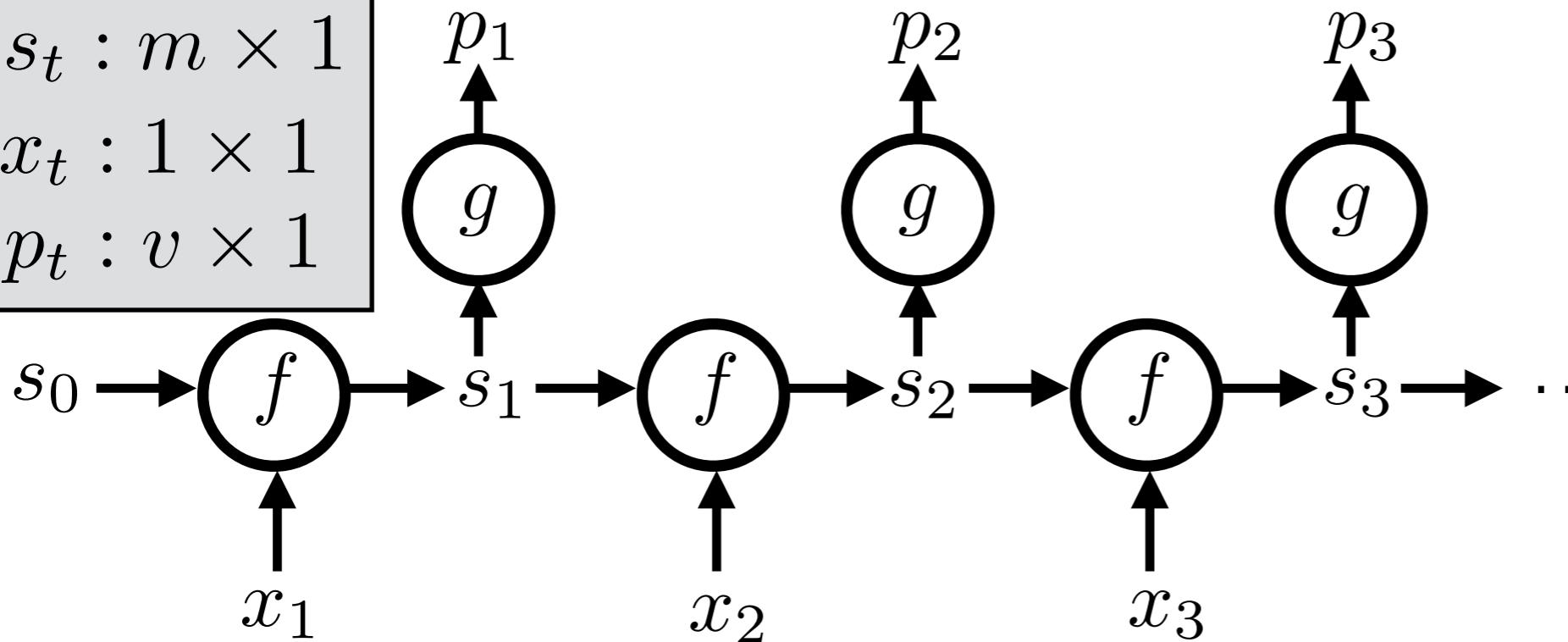
$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

$$p_t = g(s_t)$$
$$=$$

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

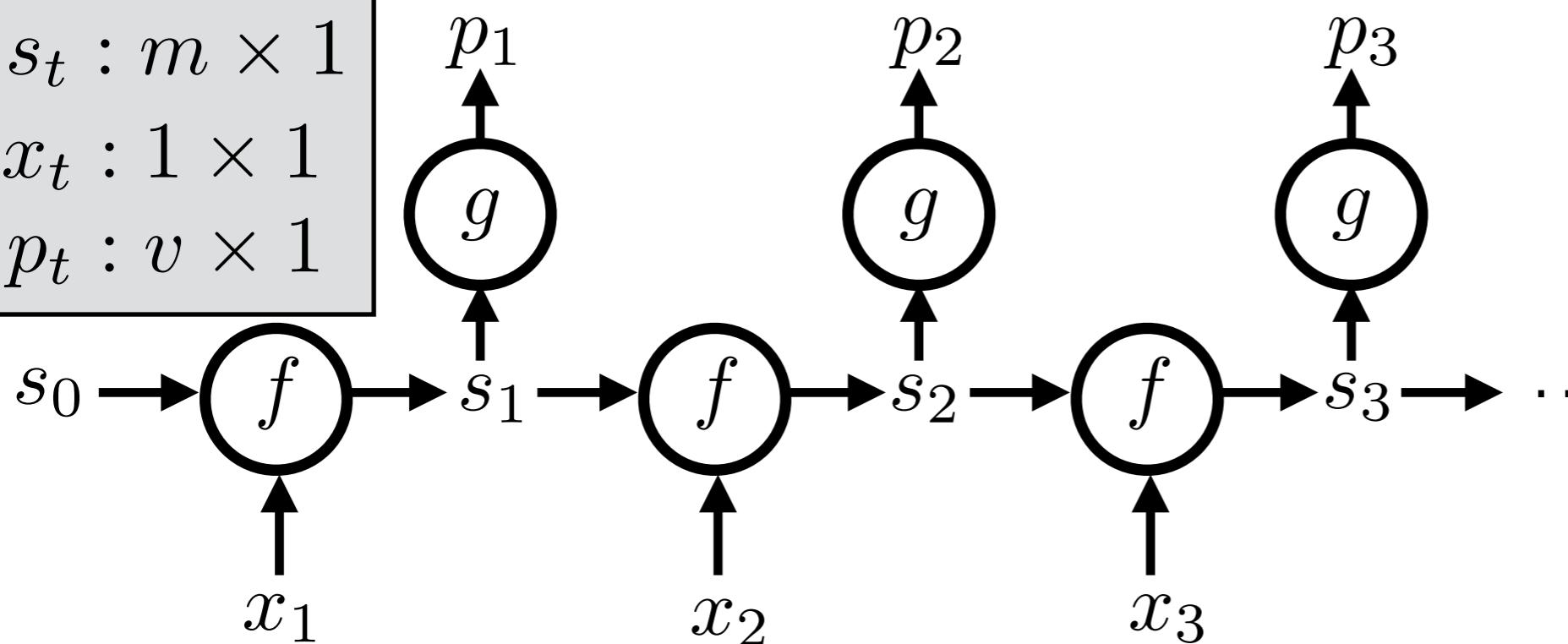
$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

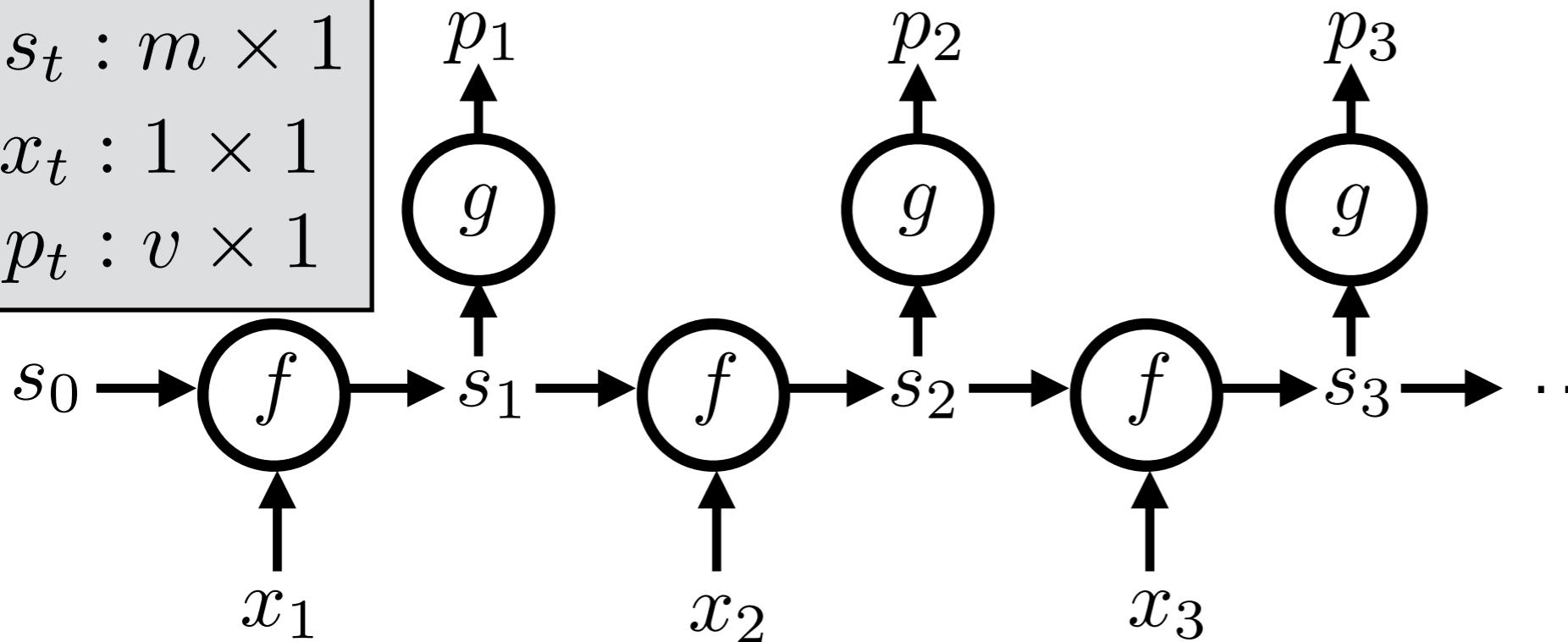
$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

2-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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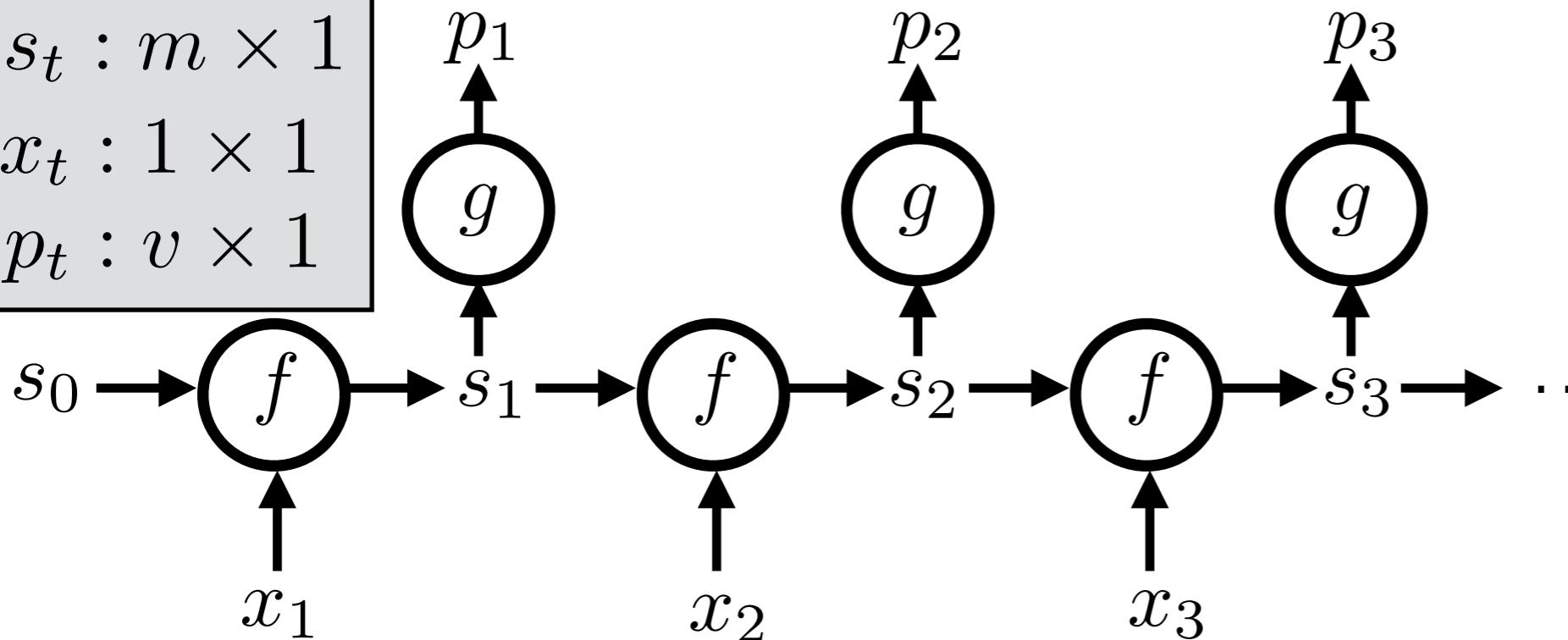
1 × 3

2-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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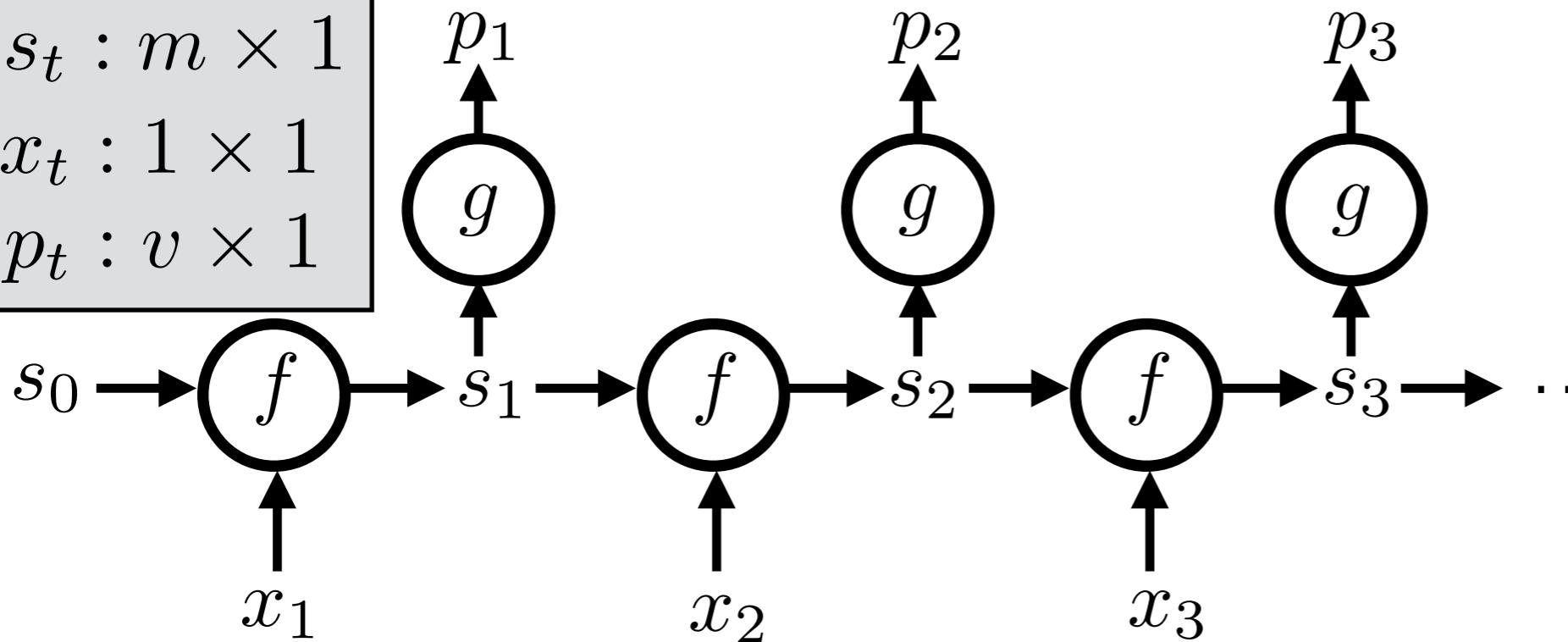
$1 \times 3 \quad 1 \times 1$

2-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

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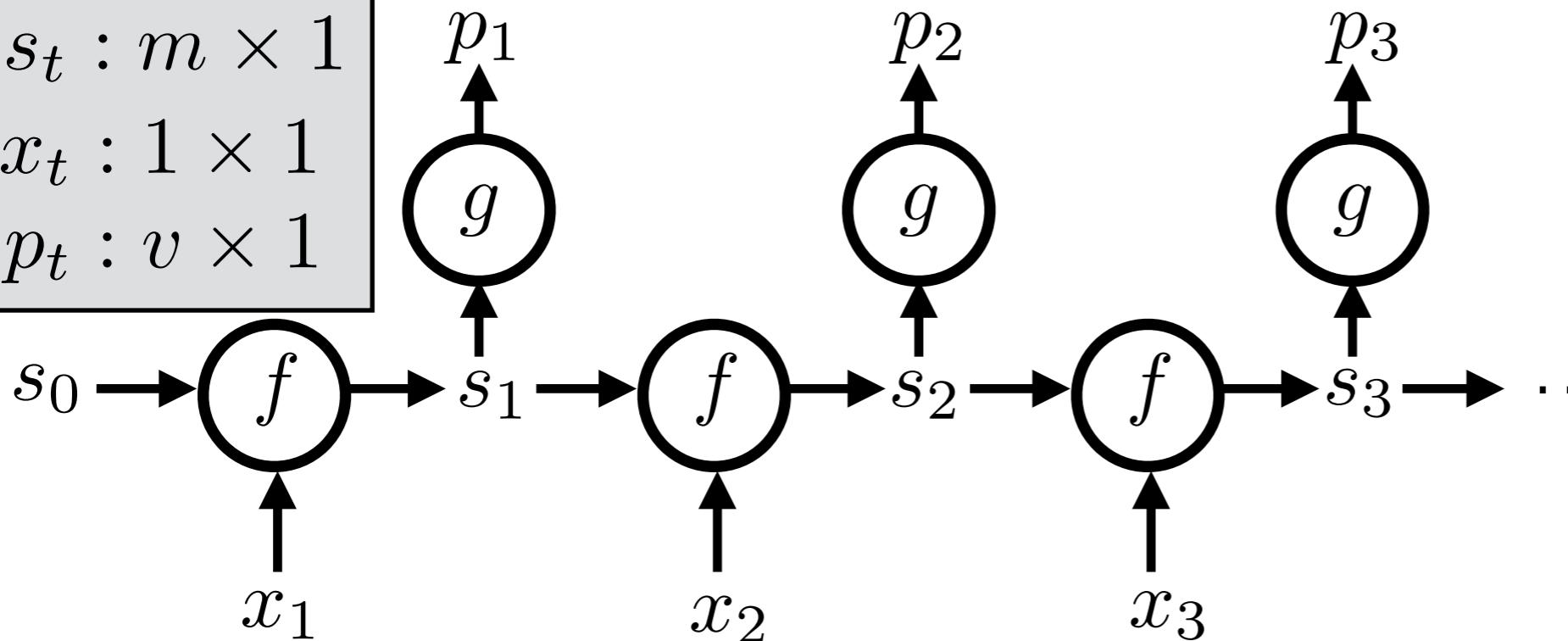
1 x 3 1 x 1

2-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



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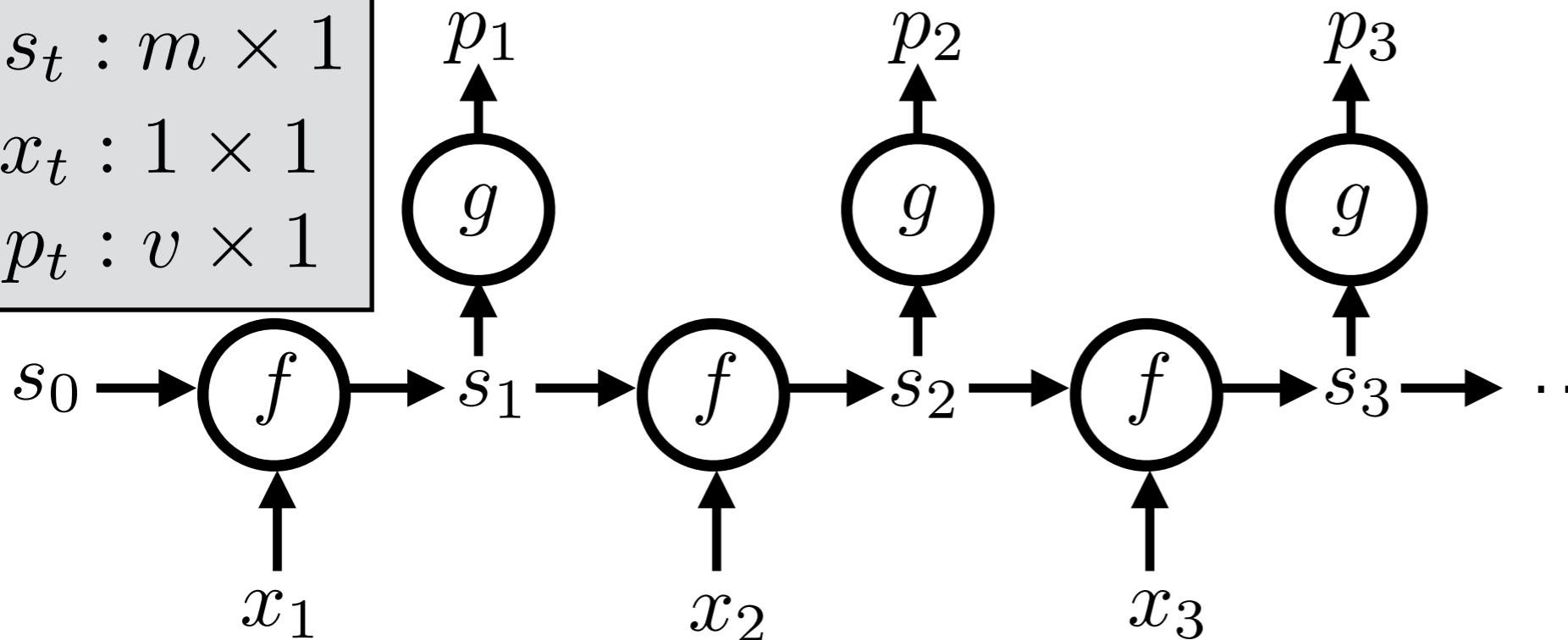
1 x 3 1 x 1

v-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



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1 x 3

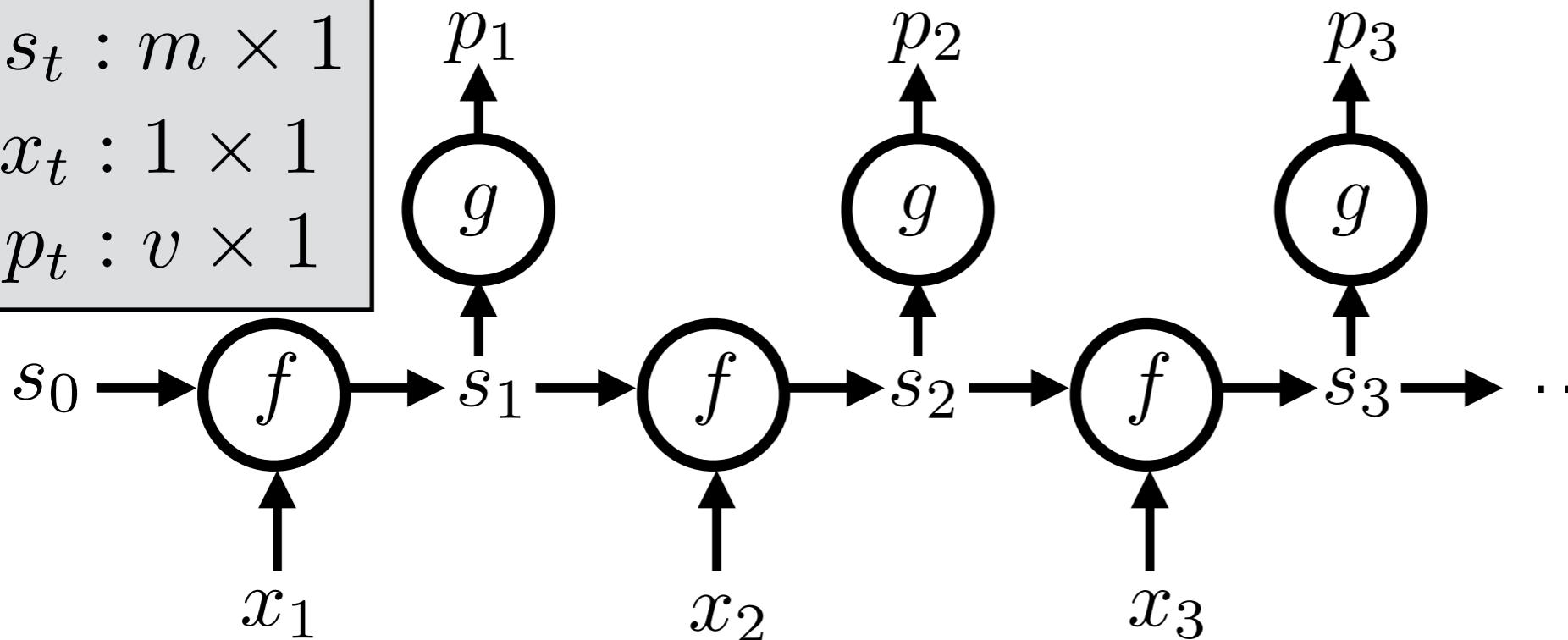
1 x 1

v-class
logistic
regression

- m : number of characters in the context
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Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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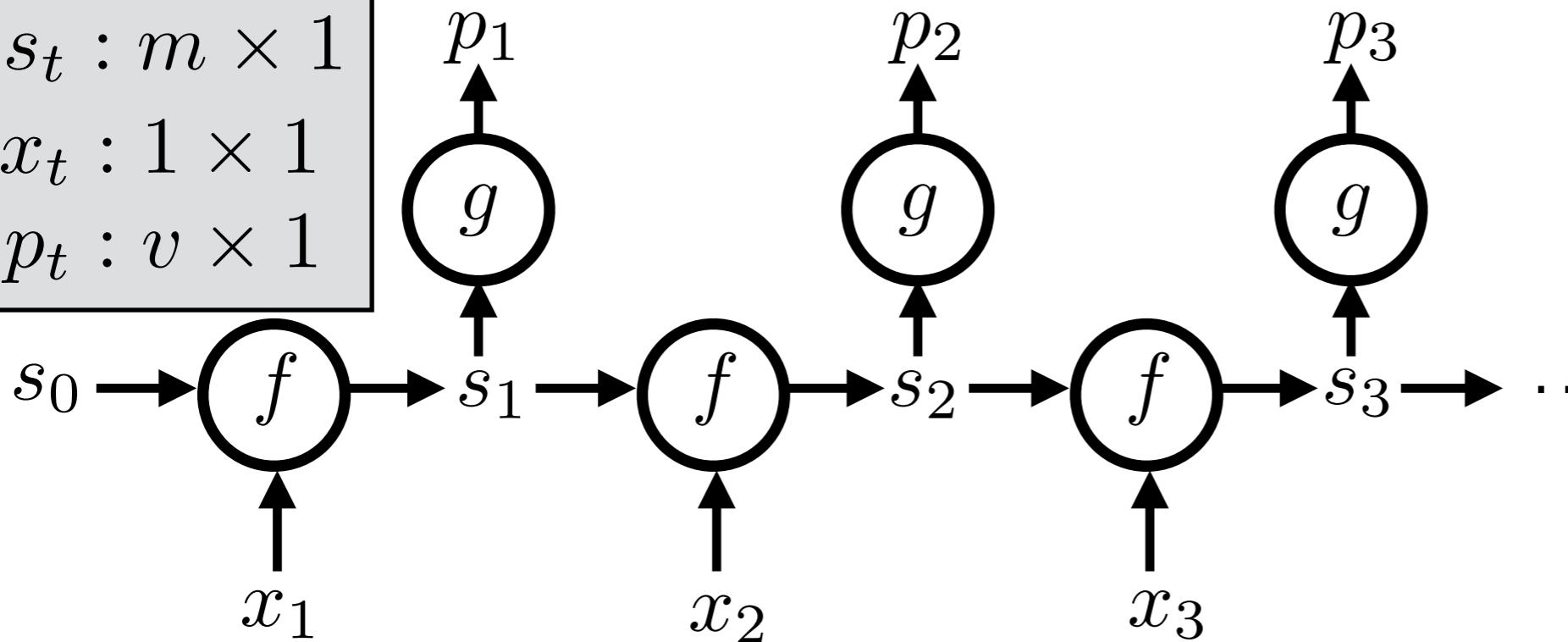
v x 3 v x 1

v-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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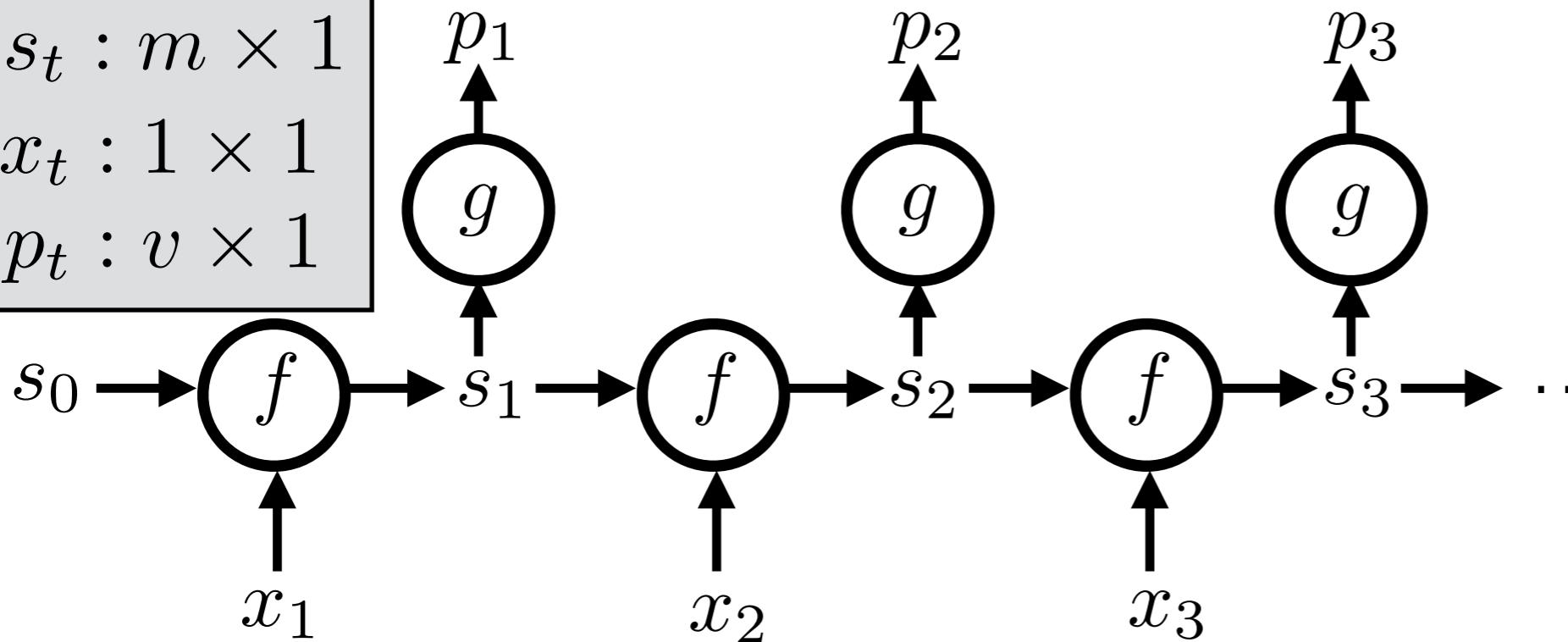
$v \times 3$ $v \times 1$

v-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



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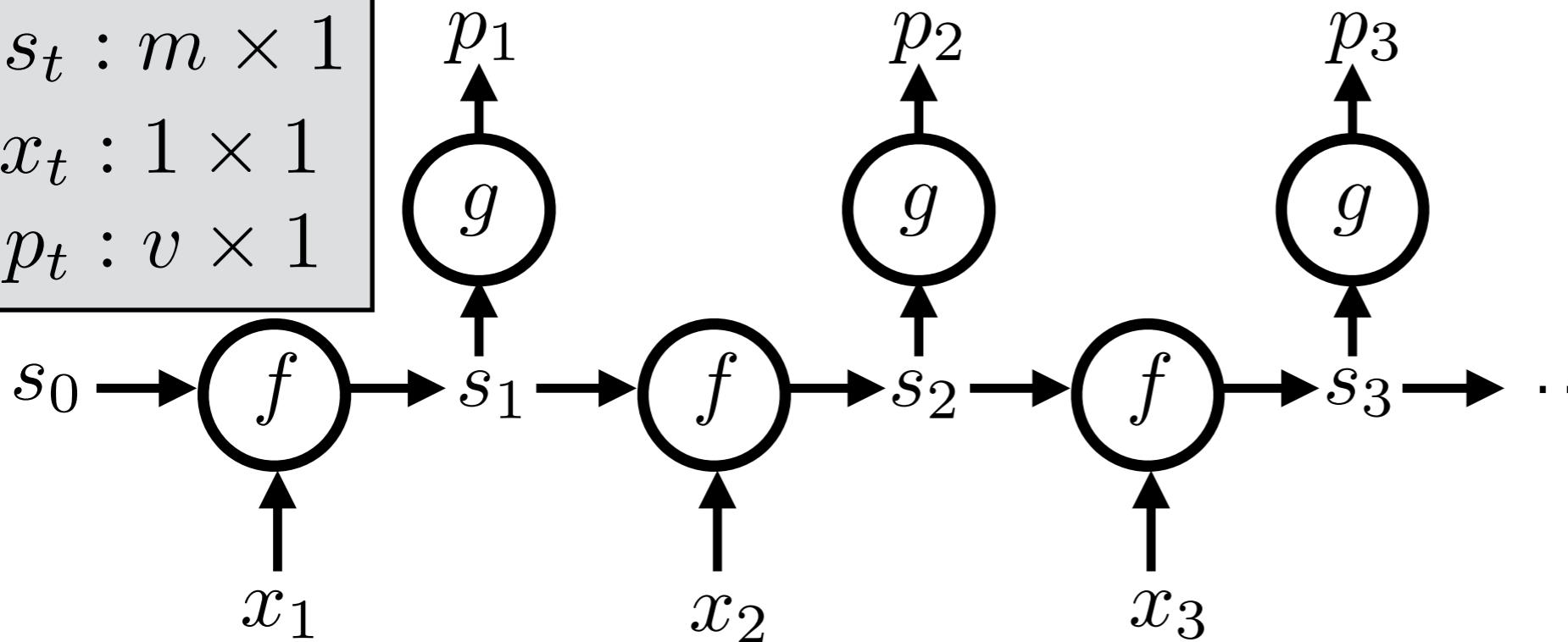
$v \times 3 \quad v \times 1$

v-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



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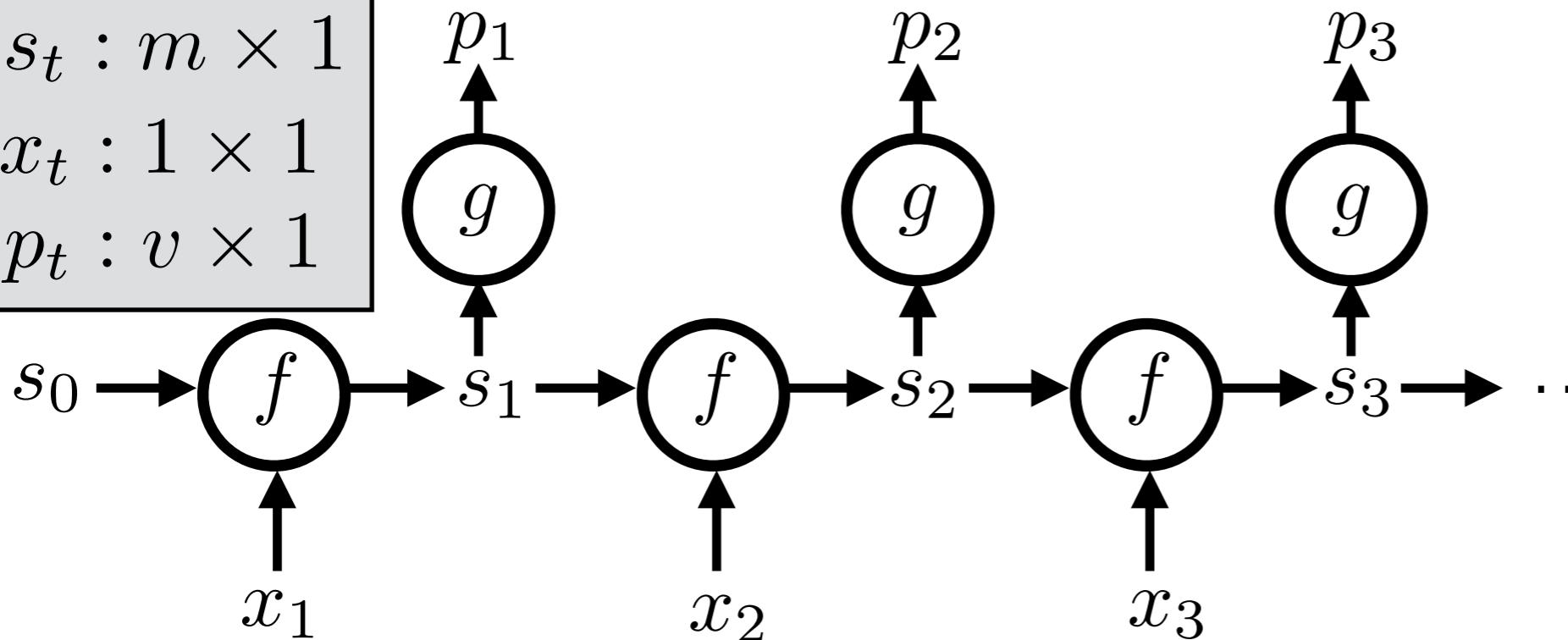
$\text{vx } 3 \quad \text{vx } 1$

v-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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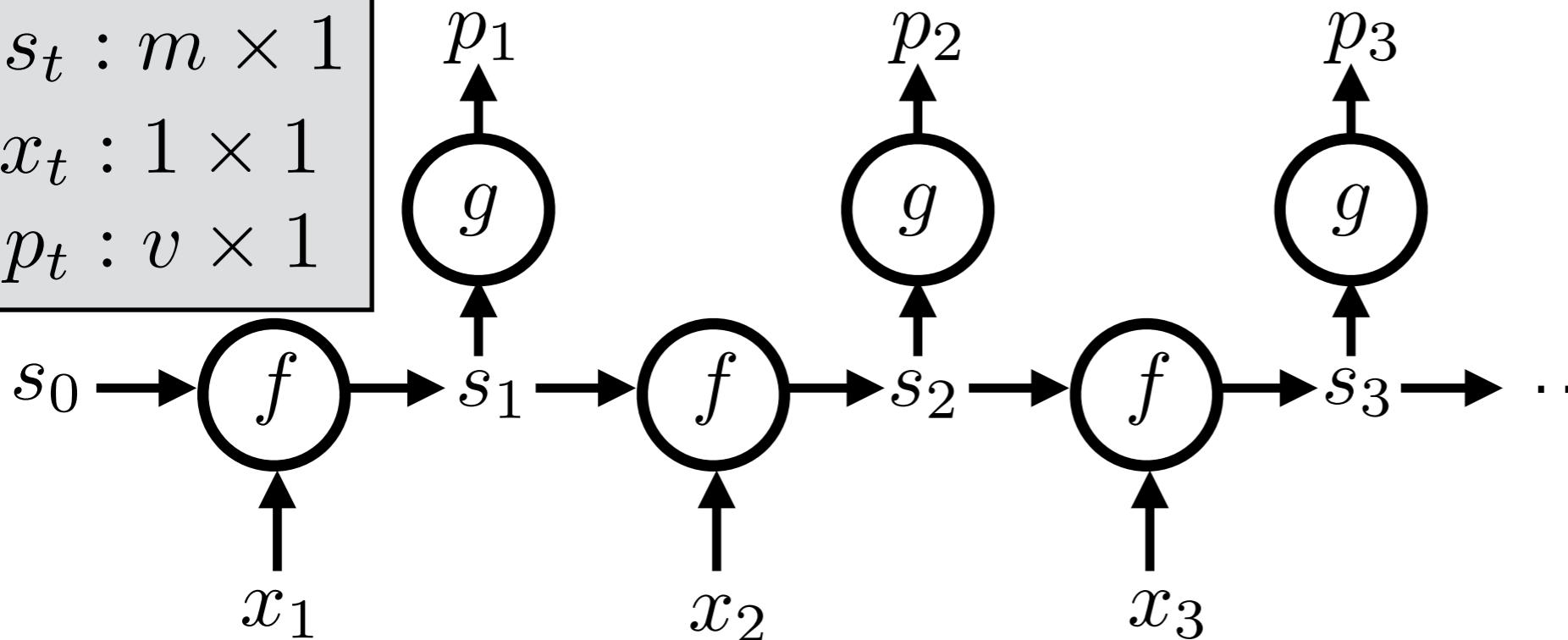
$v \times m$ $v \times 1$

v-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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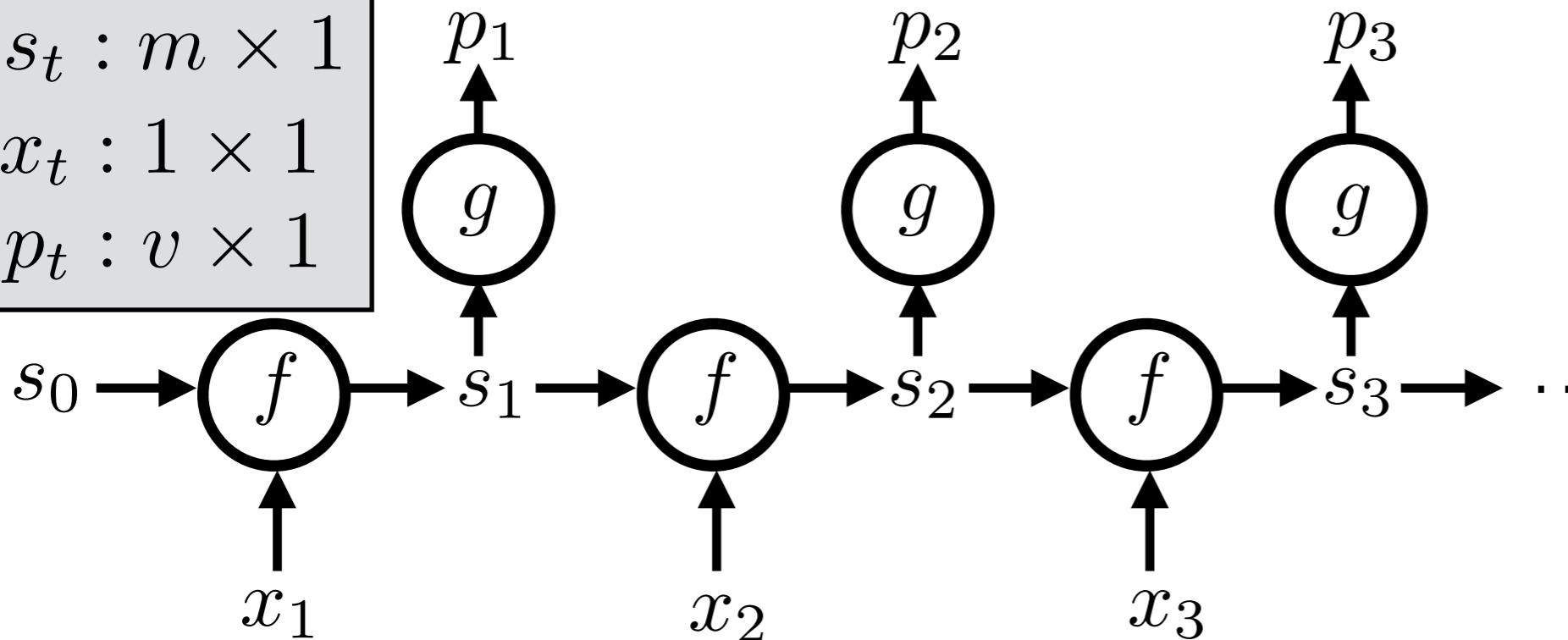
$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}\quad \begin{matrix} v \times m \\ v \times 1 \end{matrix}$$

v-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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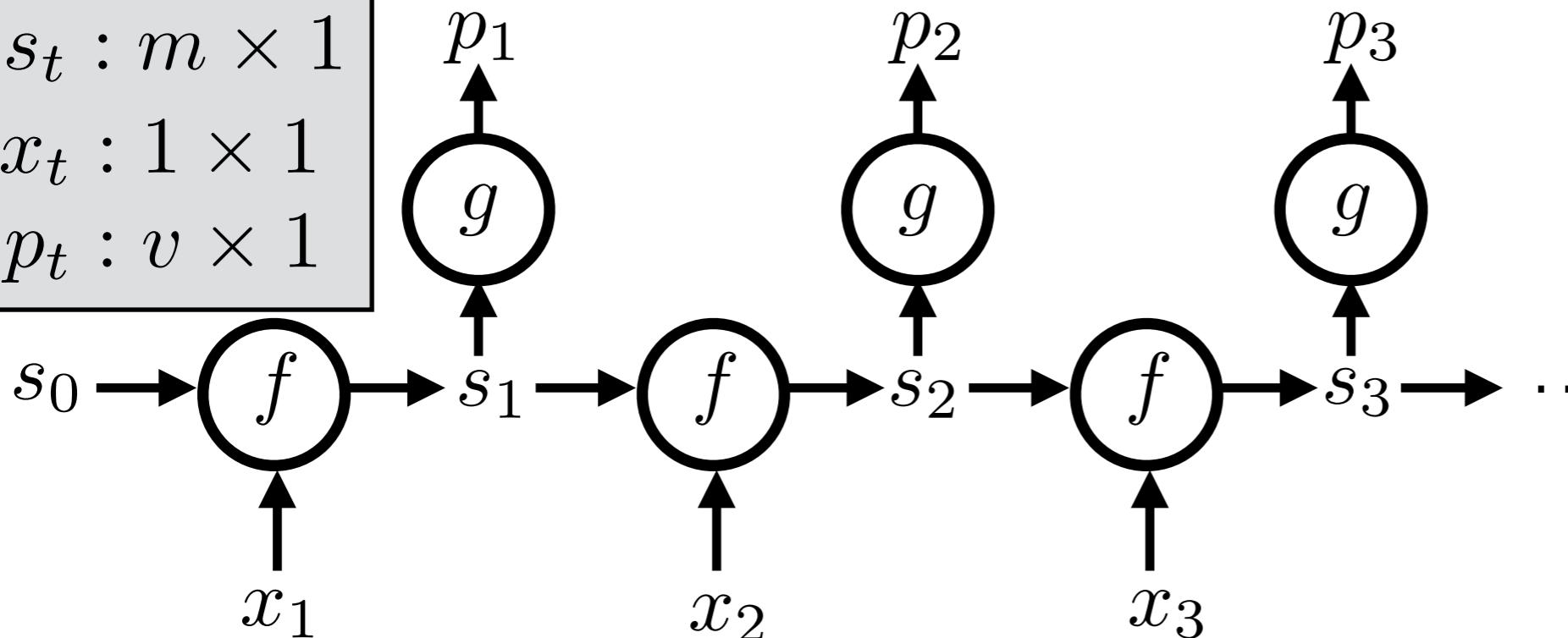
$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}\quad \begin{matrix} v \times m \\ v \times 1 \end{matrix}$$

v-class
logistic
regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = x_t + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} s_{t-1}$$

no transpose

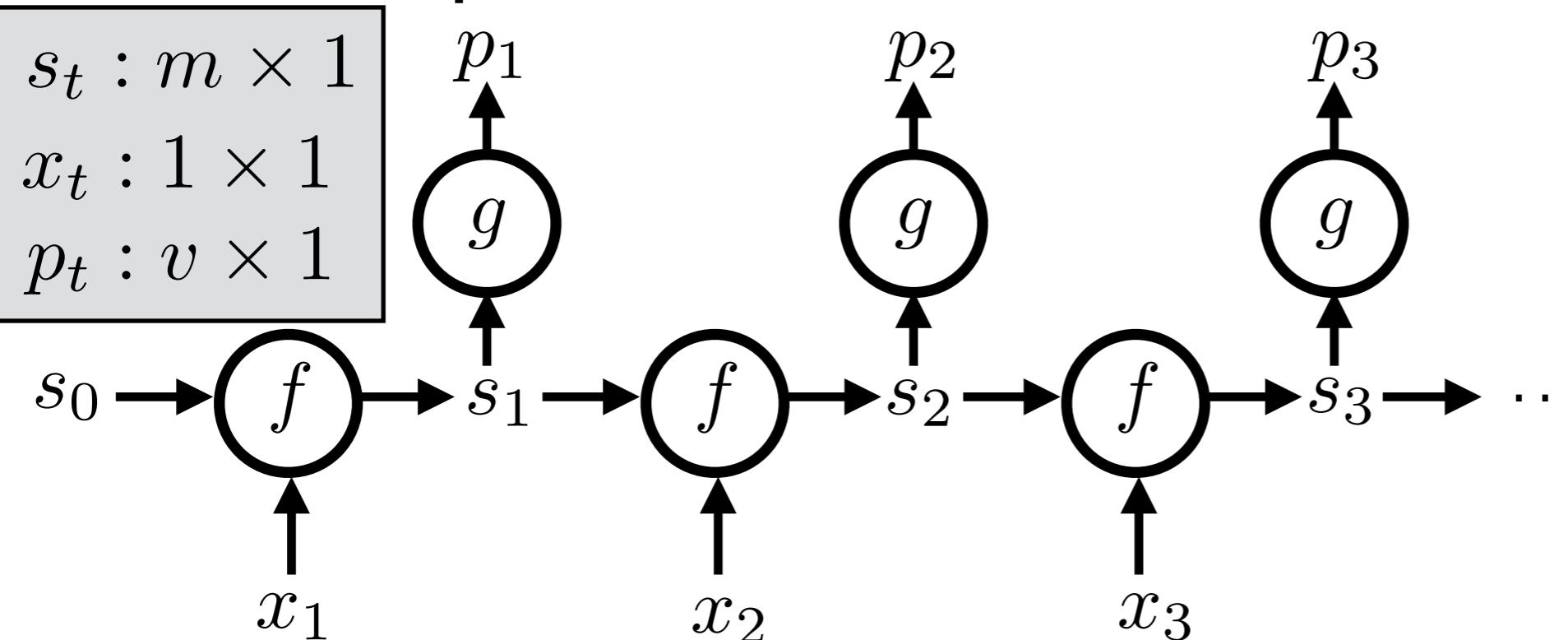
$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

$v \times m \quad v \times 1$

v-class logistic regression

- m : number of characters in the context
- v : number of characters in the alphabet

Can express as a state machine



- Example: Alphabet {0,1};
state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

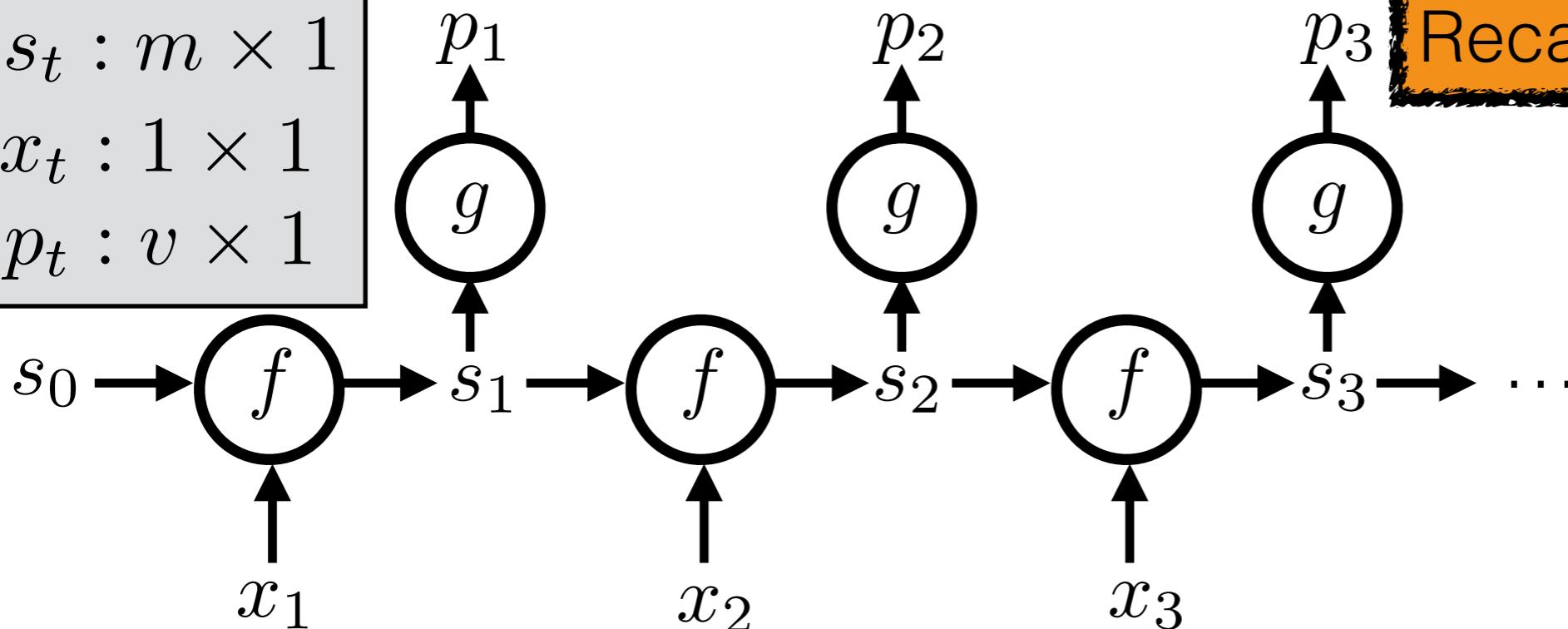
$$\begin{aligned} p_t &= g(s_t) \\ &= f_2(W^o s_t + W_0^o) \end{aligned}$$

$v \times m \quad v \times 1$

v-class
logistic
regression

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$;
state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

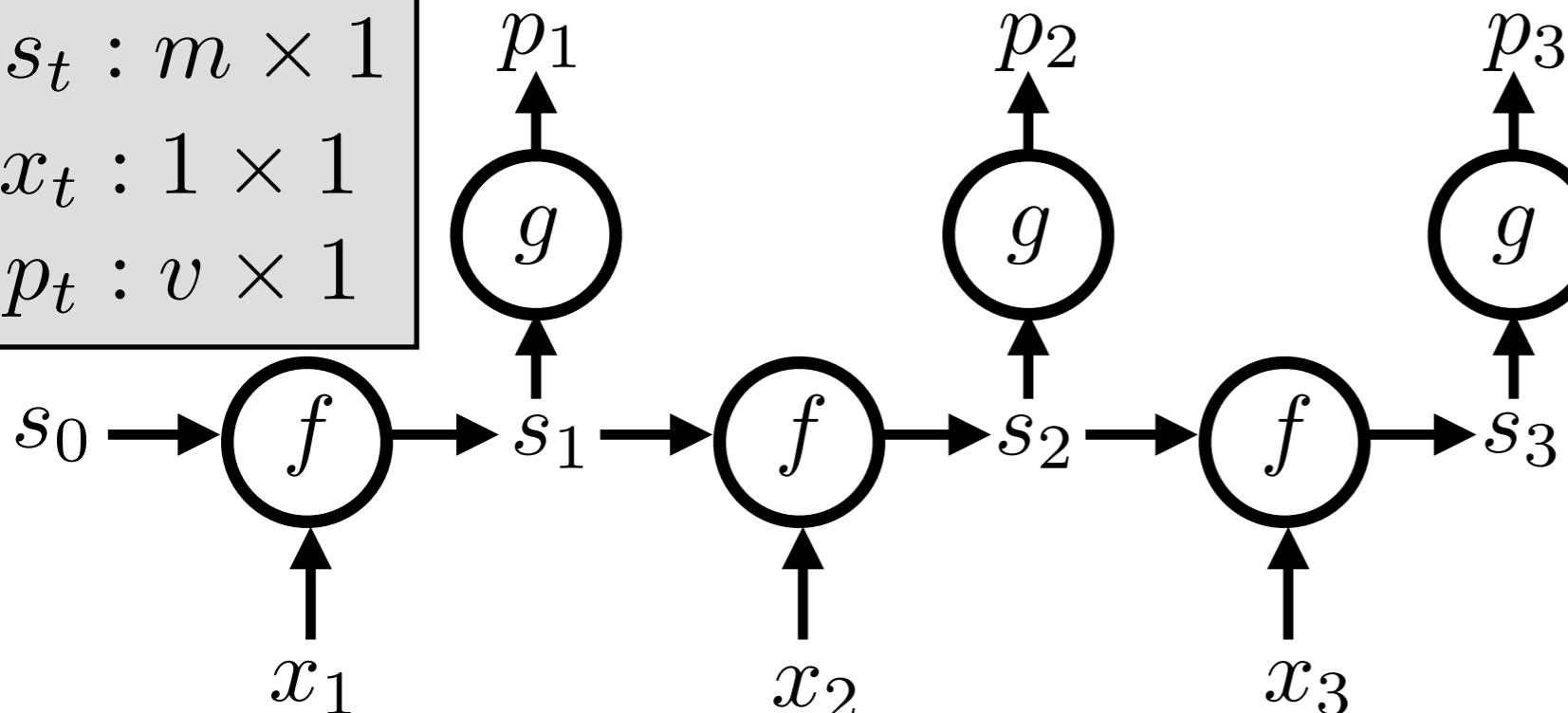
$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}\quad \begin{matrix} v \times m \\ v \times 1 \end{matrix}$$

v-class
logistic
regression

Recall: familiar pattern

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



Recall: familiar pattern
1. Choose how to predict label (given features & parameters)

- Example: Alphabet {0,1}; state is last $m = 3$ characters

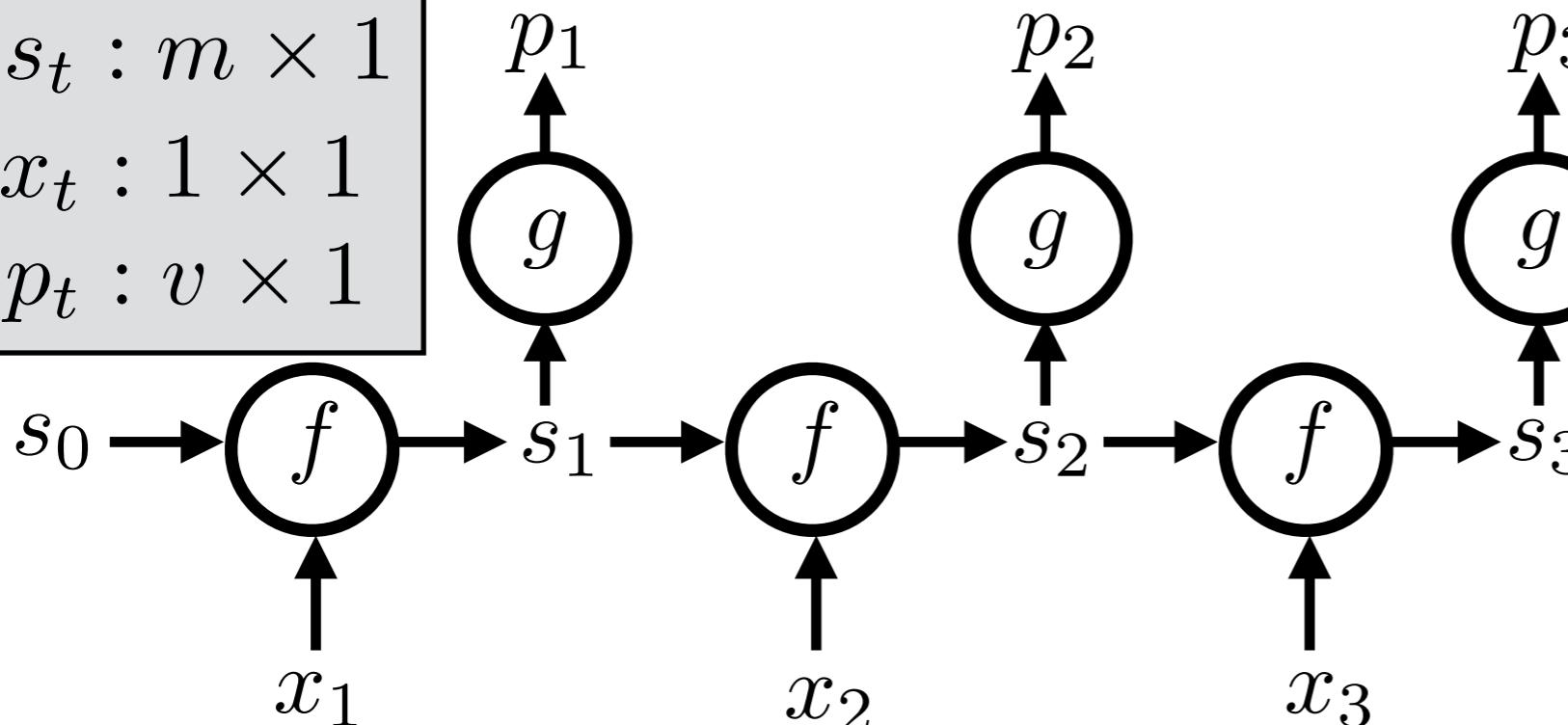
$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}\quad \begin{matrix} v \times m \\ v \times 1 \end{matrix}$$

v-class logistic regression

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Recall: familiar pattern
1. Choose how to predict label (given features & parameters)
 2. Choose a loss (between guess & actual label)

- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

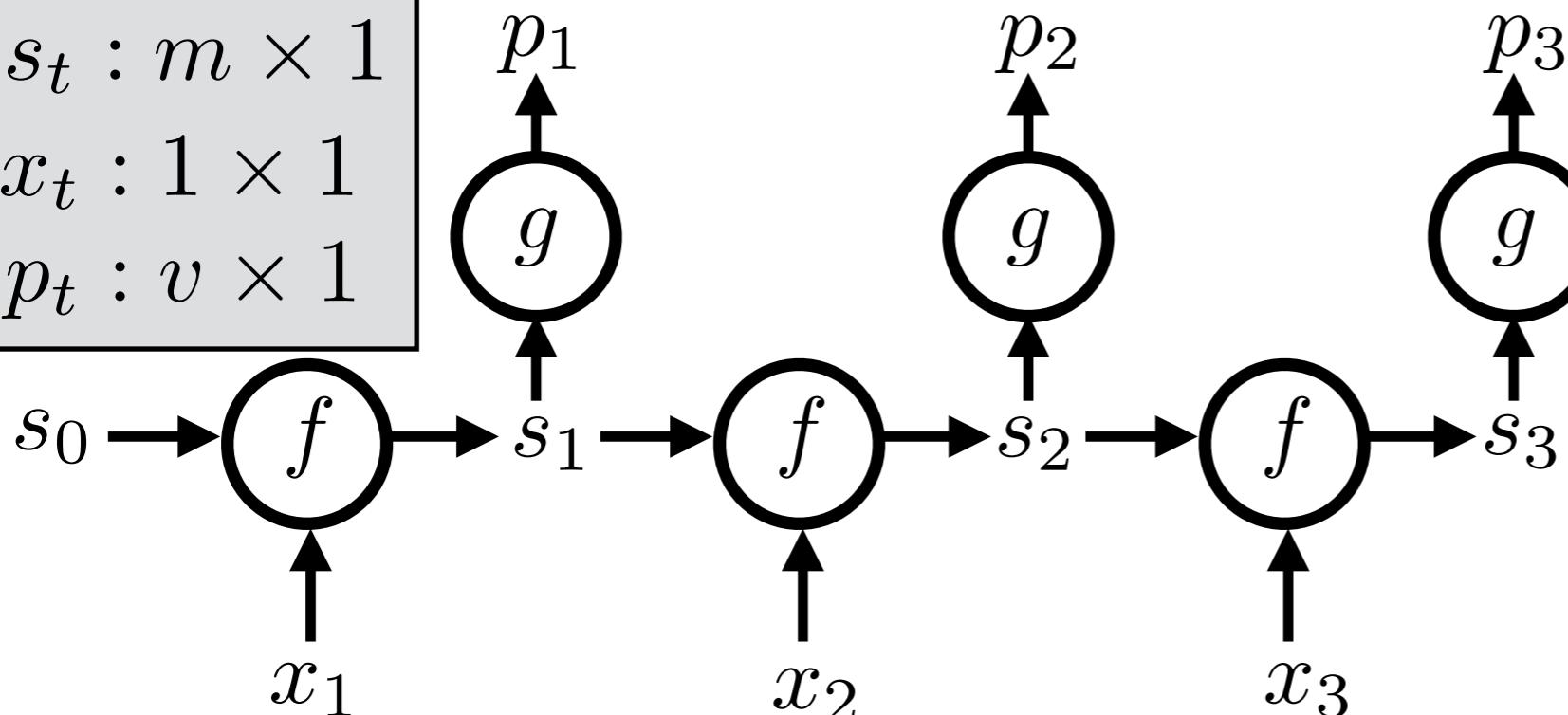
$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

$v \times m$ $v \times 1$

**v-class
logistic
regression**

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

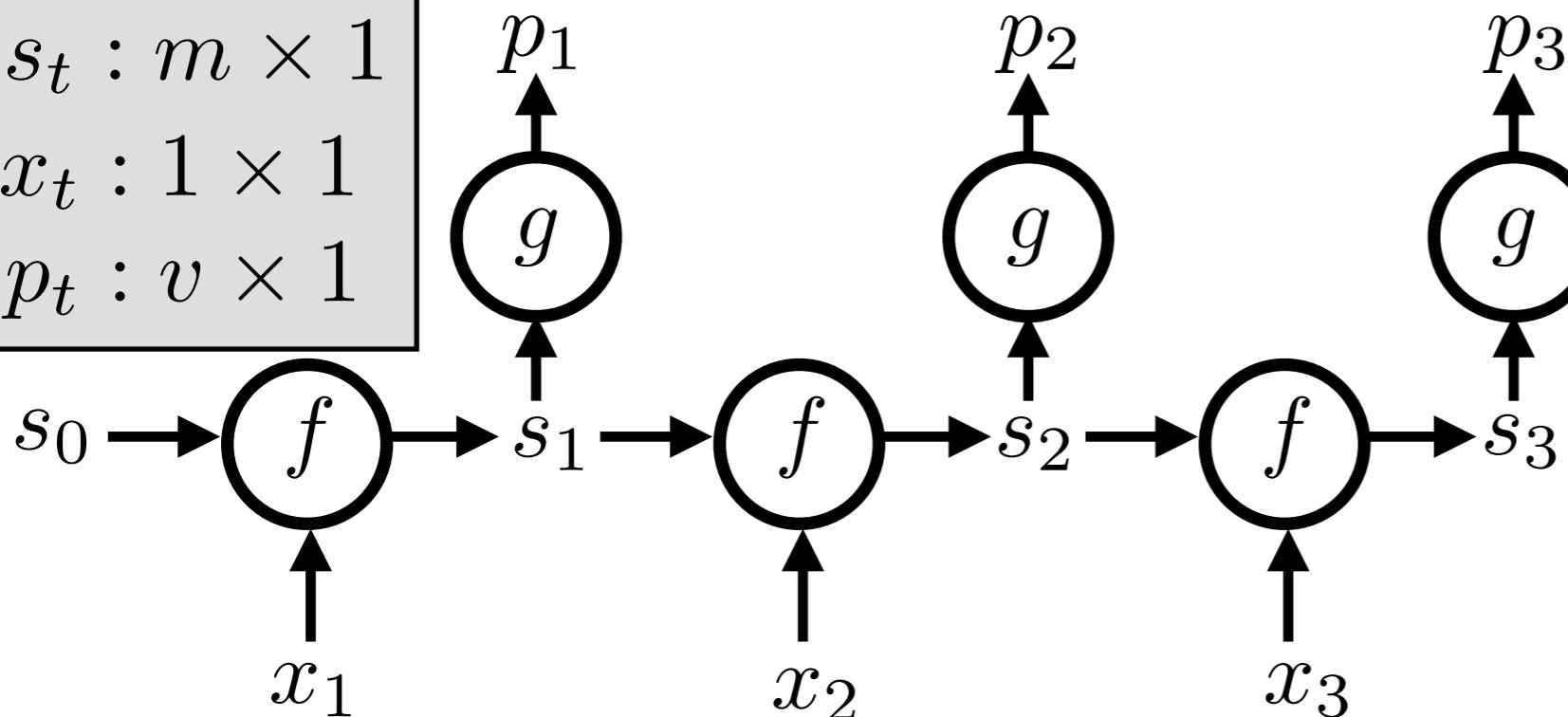
$v \times m$ $v \times 1$

v-class
logistic
regression

- Recall: familiar pattern
1. Choose how to predict label (given features & parameters)
 2. Choose a loss (between guess & actual label)
 3. Choose parameters by trying to minimize the training loss

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet {0,1}; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

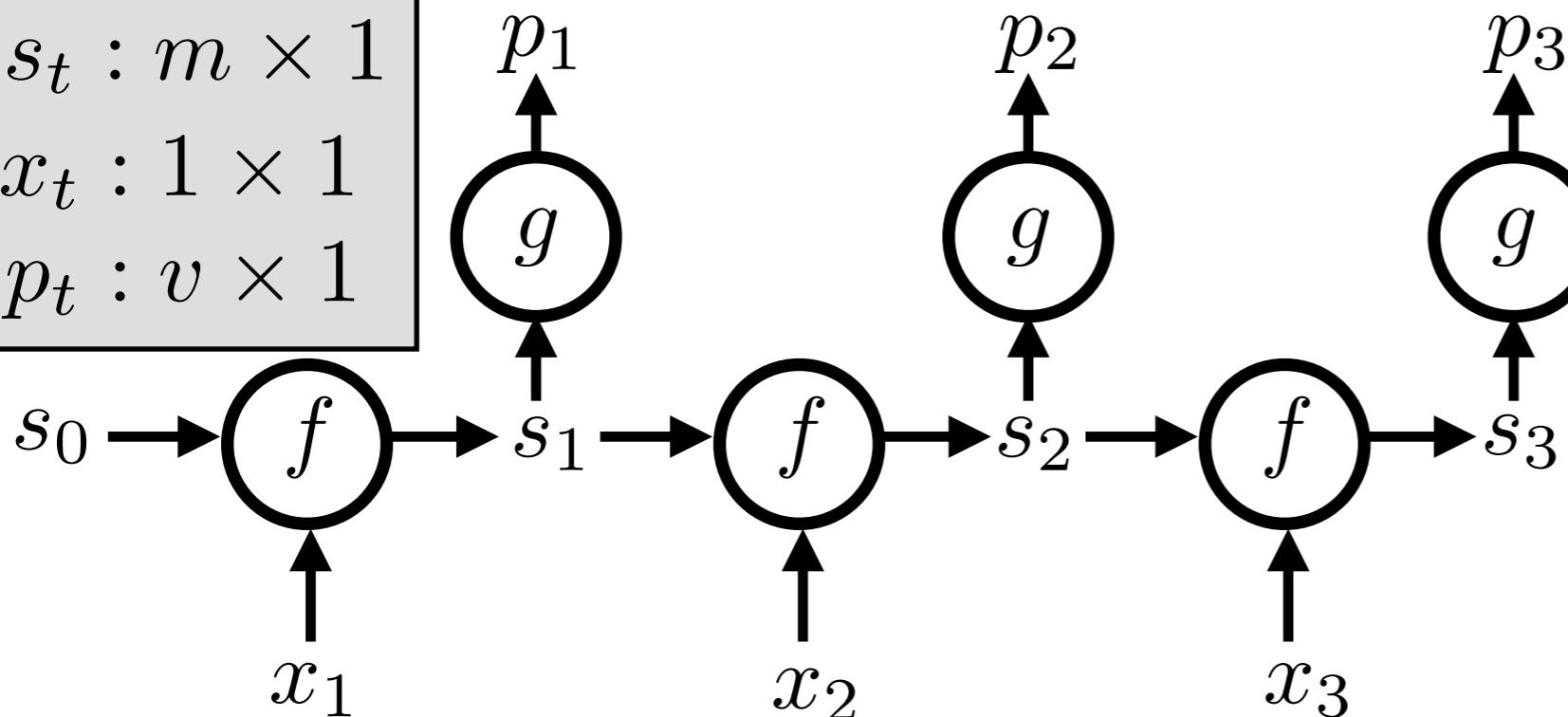
$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

$v \times m \quad v \times 1$

- Recall: familiar pattern
1. Choose how to predict label (given features & parameters)
 2. Choose a loss (between guess & actual label)
 3. Choose parameters by trying to minimize the training loss

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

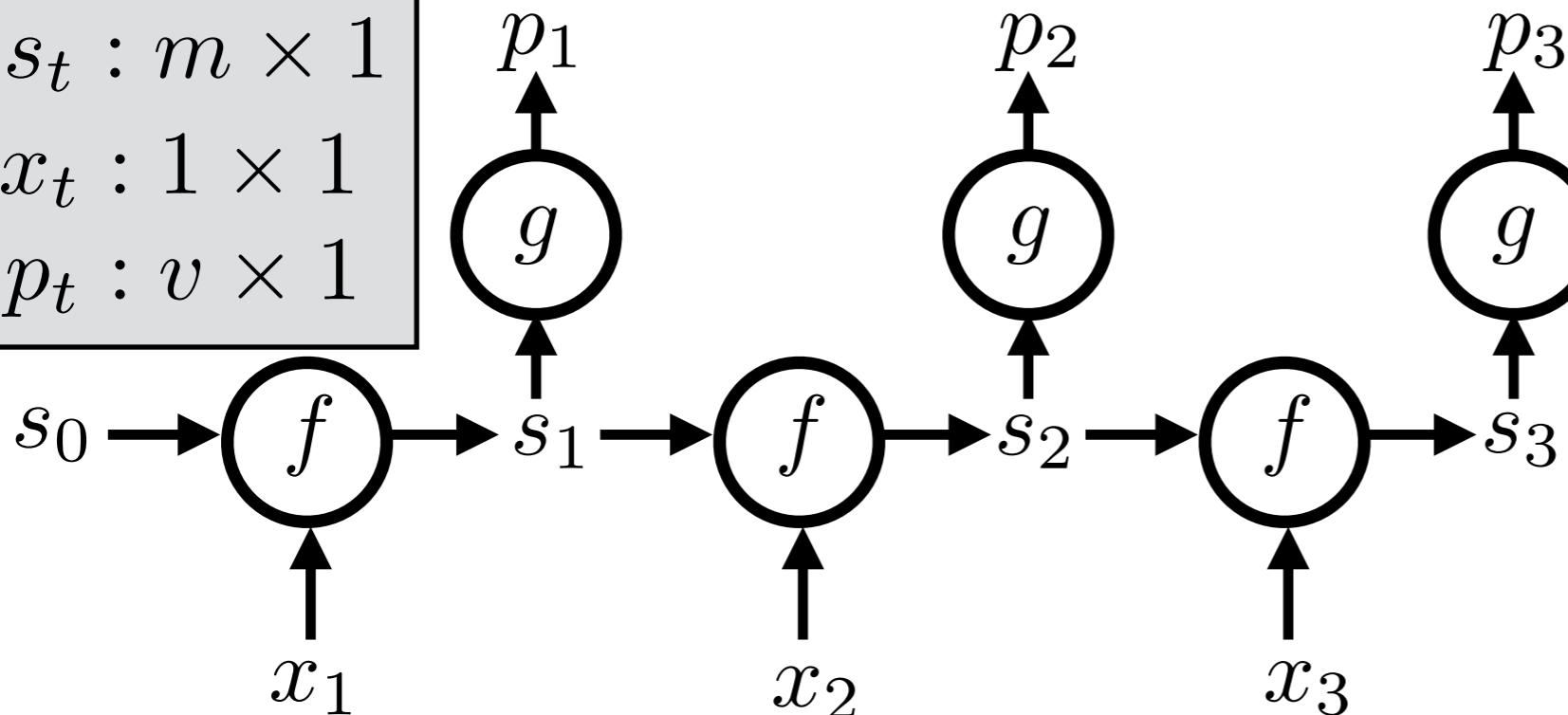
$v \times m \quad v \times 1$

- Recall: familiar pattern
1. Choose how to predict label (given features & parameters)
 2. Choose a loss (between guess & actual label)
 3. Choose parameters by trying to minimize the training loss

$$L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet {0,1}; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

$v \times m \quad v \times 1$

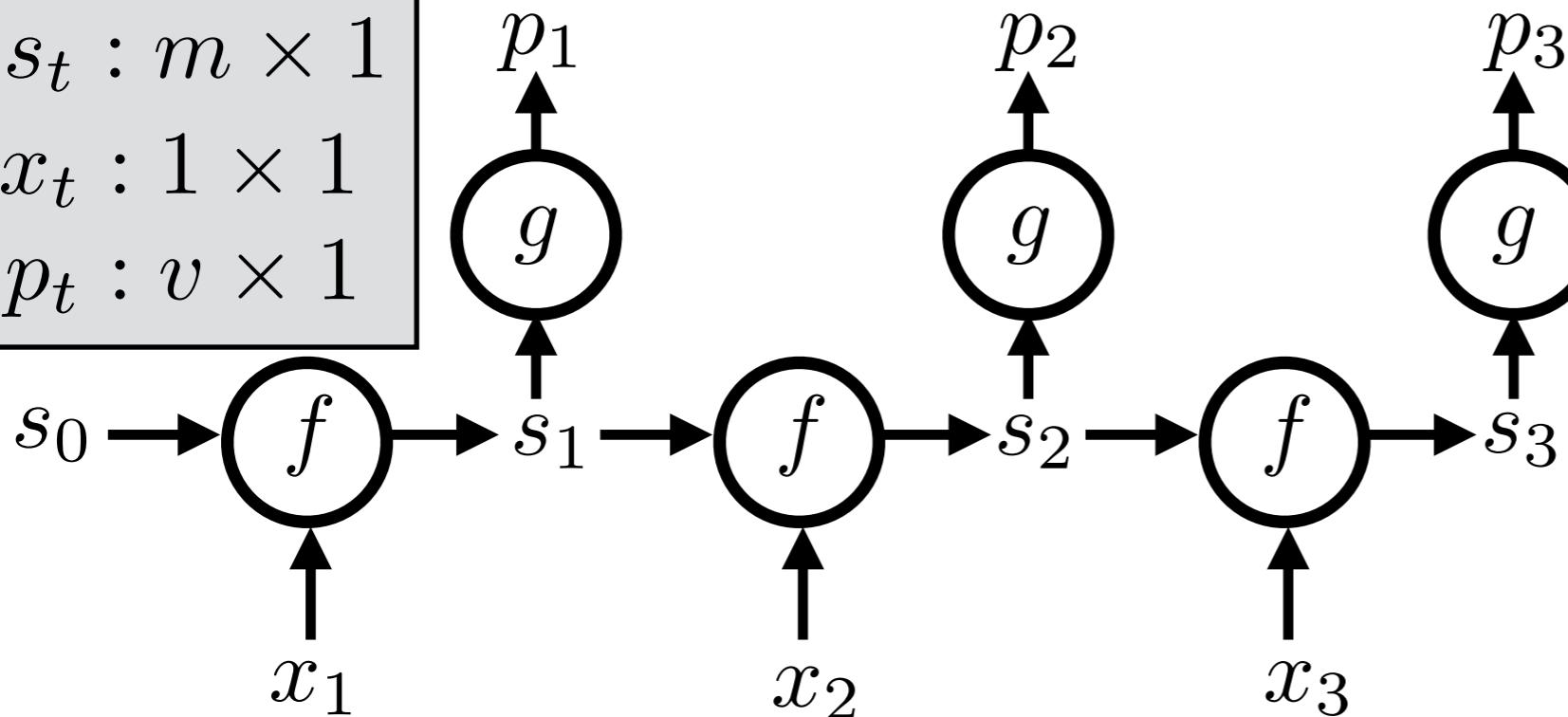
- Recall: familiar pattern
1. Choose how to predict label (given features & parameters)
 2. Choose a loss (between guess & actual label)
 3. Choose parameters by trying to minimize the training loss

$$L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

$$p^{(i)} = R(x^{(i)}; W^o, W_0^o)$$

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

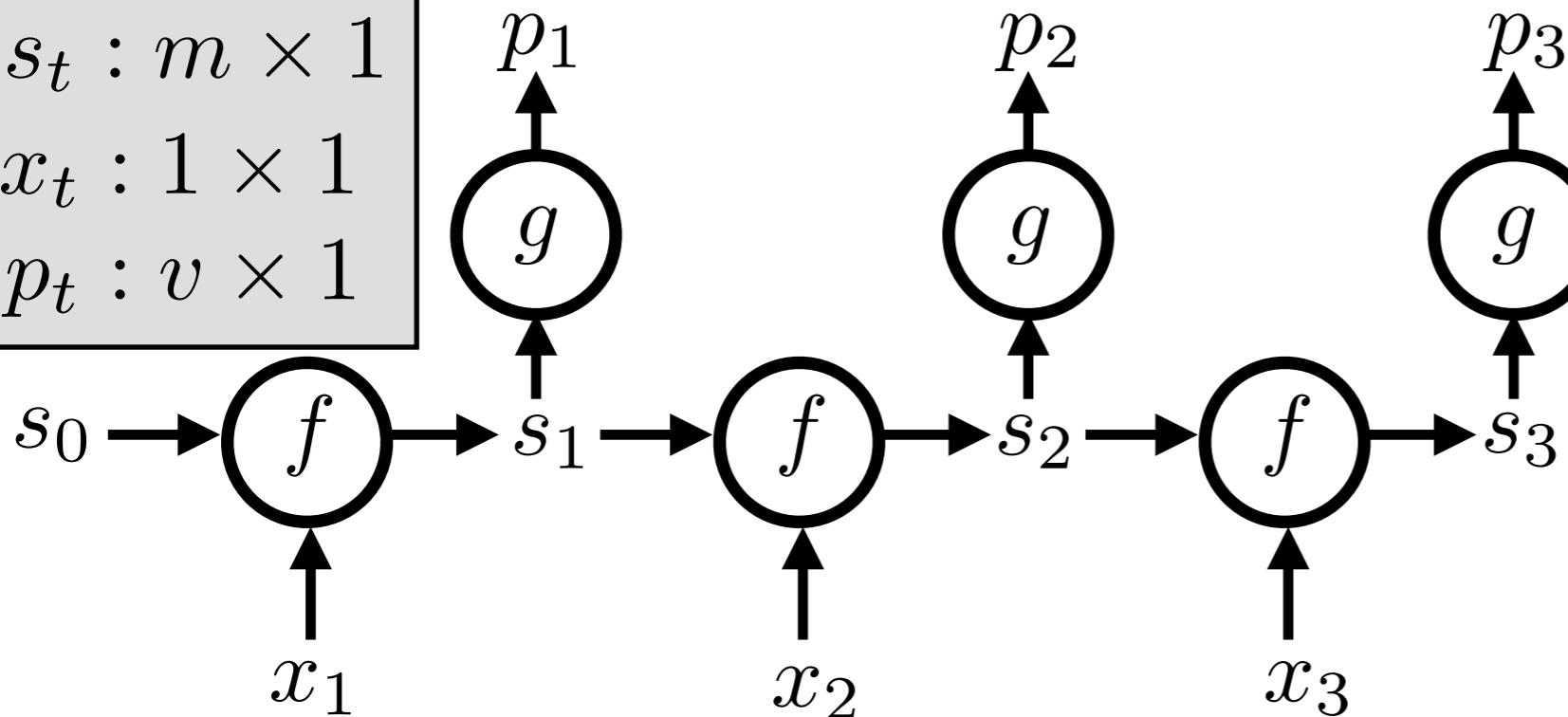
$v \times m \quad v \times 1$

- Recall: familiar pattern
1. Choose how to predict label (given features & parameters)
 2. Choose a loss (between guess & actual label)
 3. Choose parameters by trying to minimize the training loss

$$\begin{aligned}L_{\text{seq}}(p^{(i)}, y^{(i)}) &= \sum_{t=1}^{n^{(i)}} L_{\text{elt}}(p_t^{(i)}, y_t^{(i)}) \\p^{(i)} &= R(x^{(i)}; W^o, W_0^o)\end{aligned}$$

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f(s_{t-1}, x_t) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_t + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} s_{t-1}$$

$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

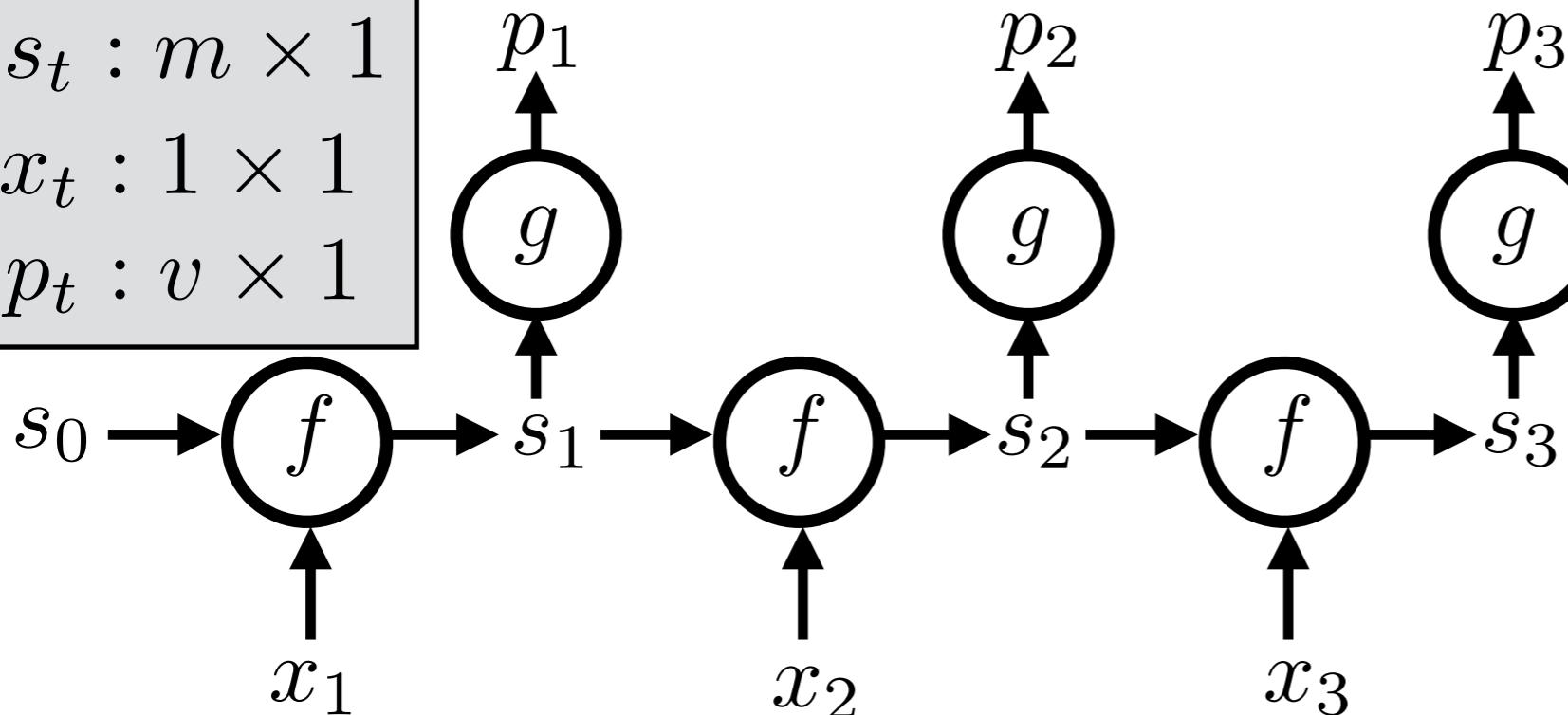
$v \times m \quad v \times 1$

- Recall: familiar pattern
1. Choose how to predict label (given features & parameters)
 2. Choose a loss (between guess & actual label)
 3. Choose parameters by trying to minimize the training loss

$$\begin{aligned}L_{\text{seq}}(p^{(i)}, y^{(i)}) &= \sum_{t=1}^{n^{(i)}} L_{\text{elt}}(p_t^{(i)}, y_t^{(i)}) \\p^{(i)} &= R(x^{(i)}; W^o, W_0^o) \\J(W^o, W_0^o) &= \sum_{i=1}^q L_{\text{seq}}(p^{(i)}, y^{(i)})\end{aligned}$$

Can express as a state machine

$$\begin{aligned}s_t &: m \times 1 \\x_t &: 1 \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

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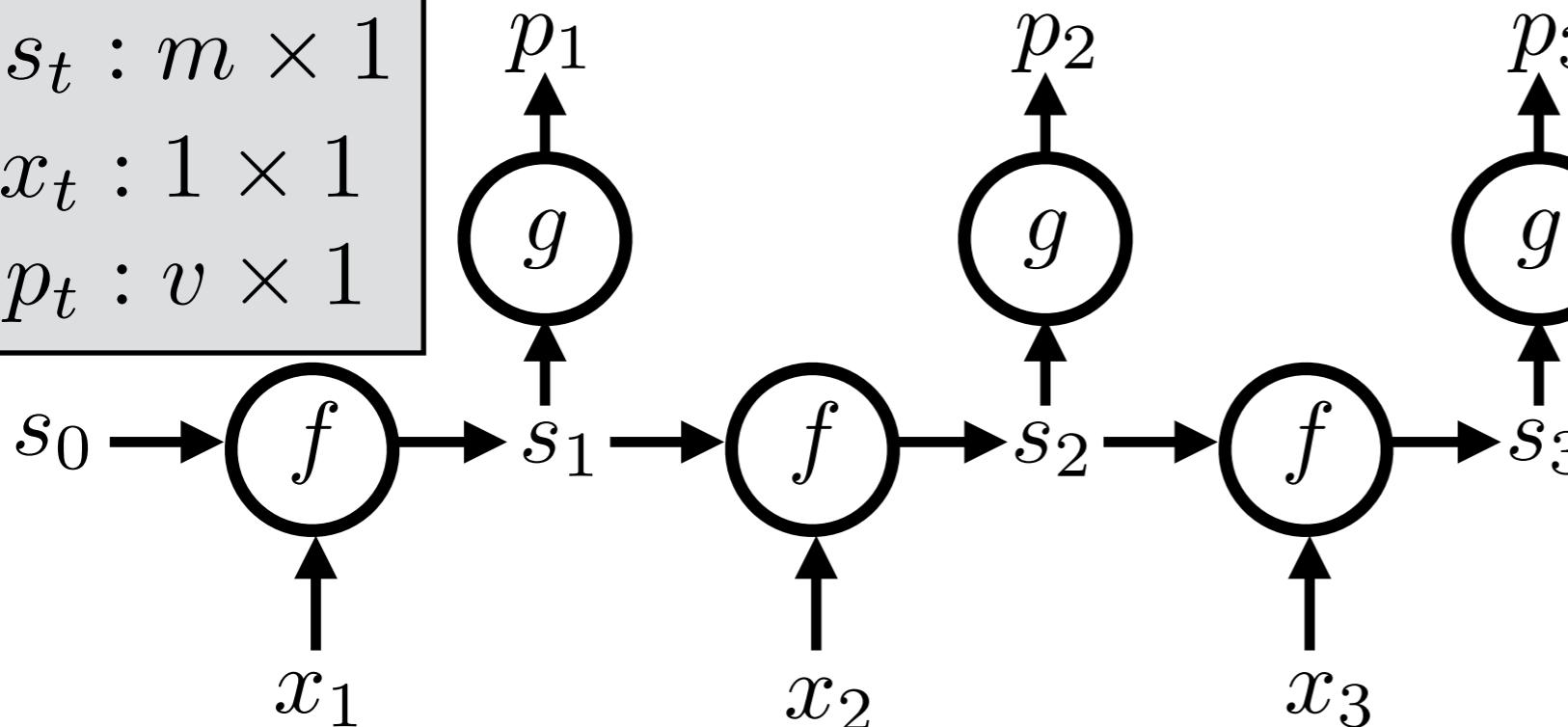
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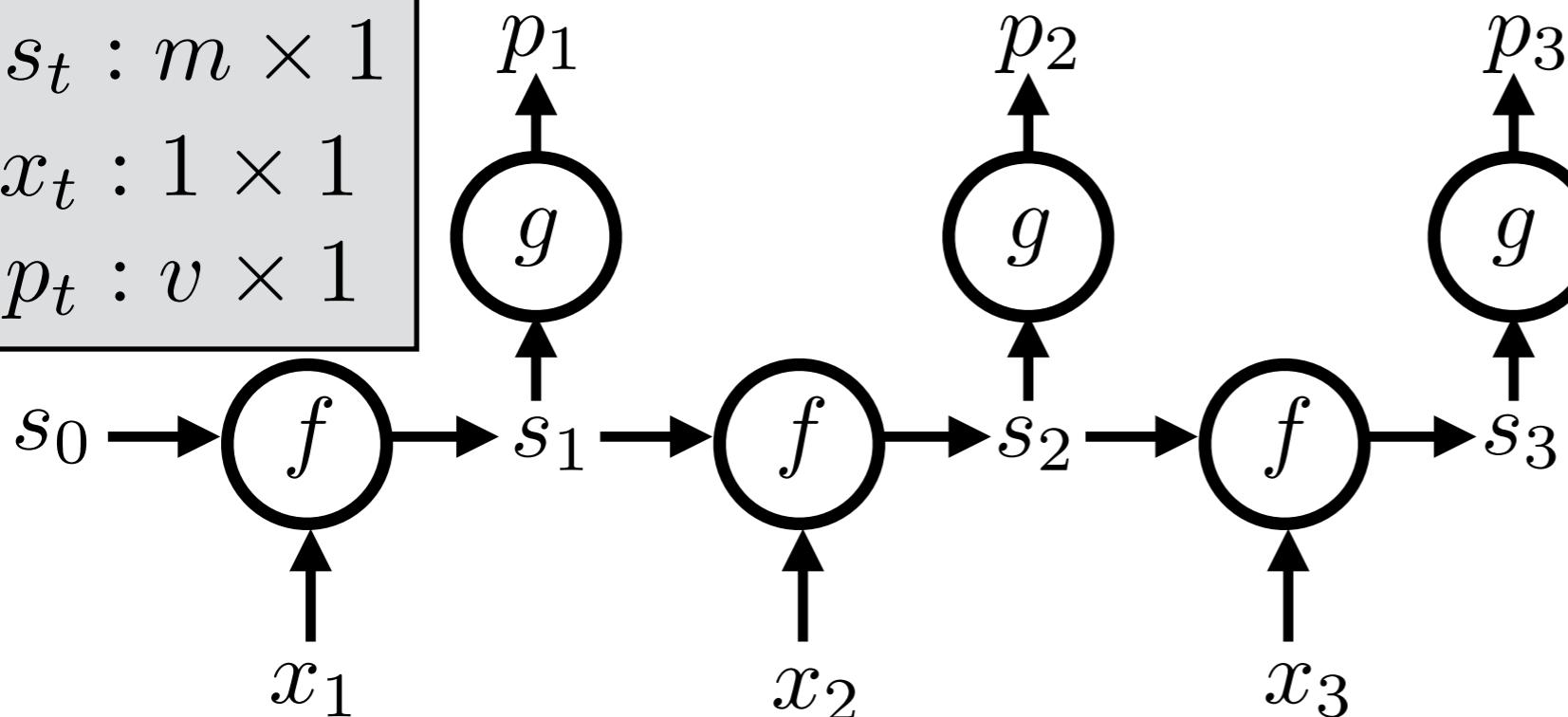
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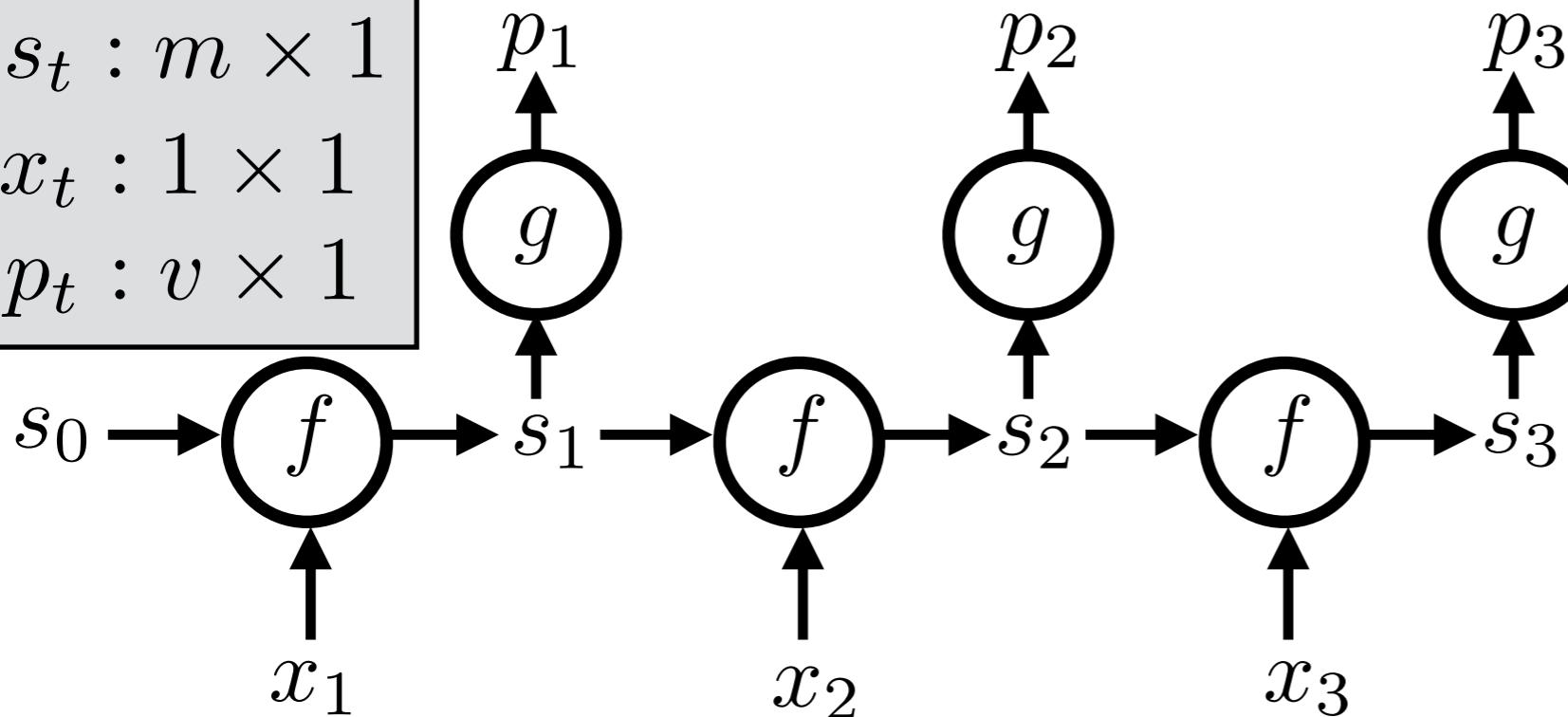
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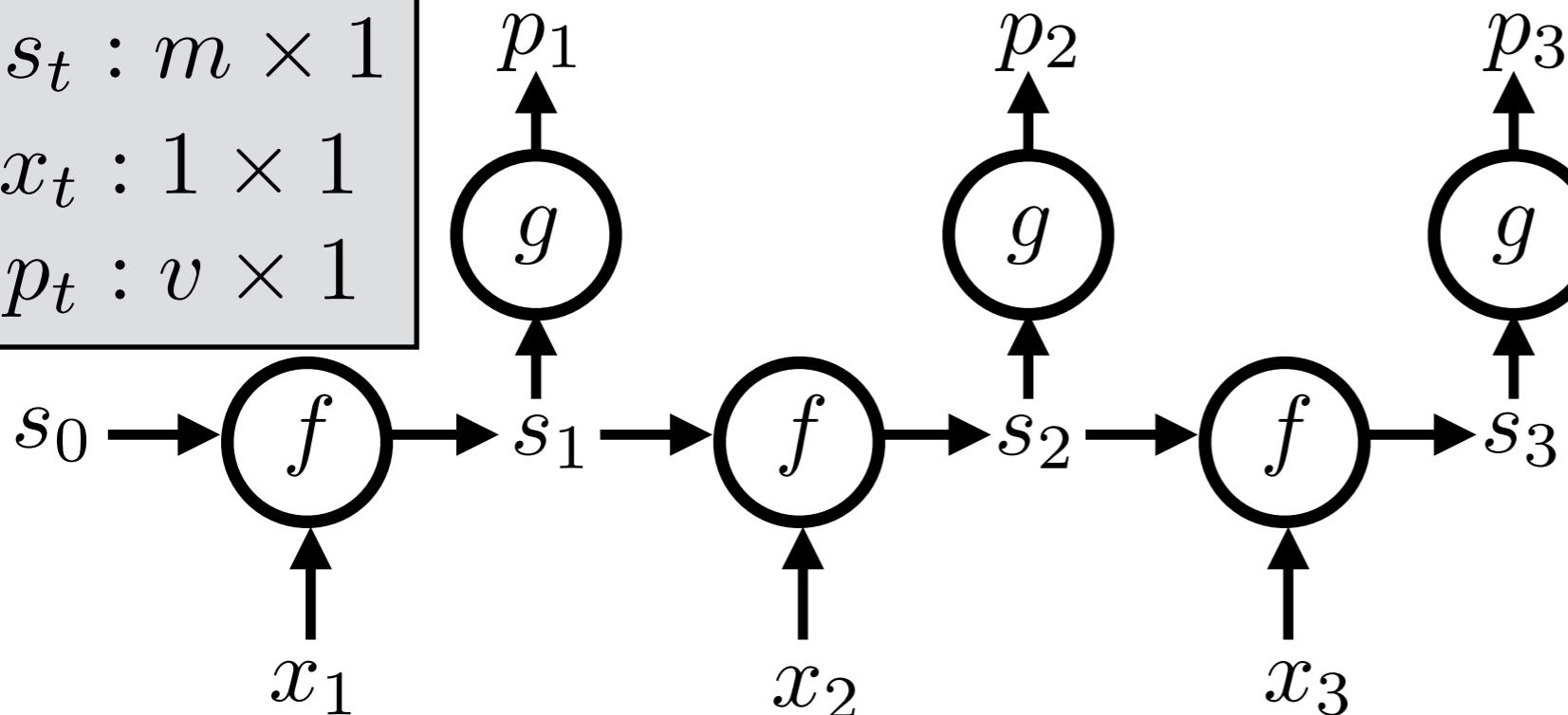
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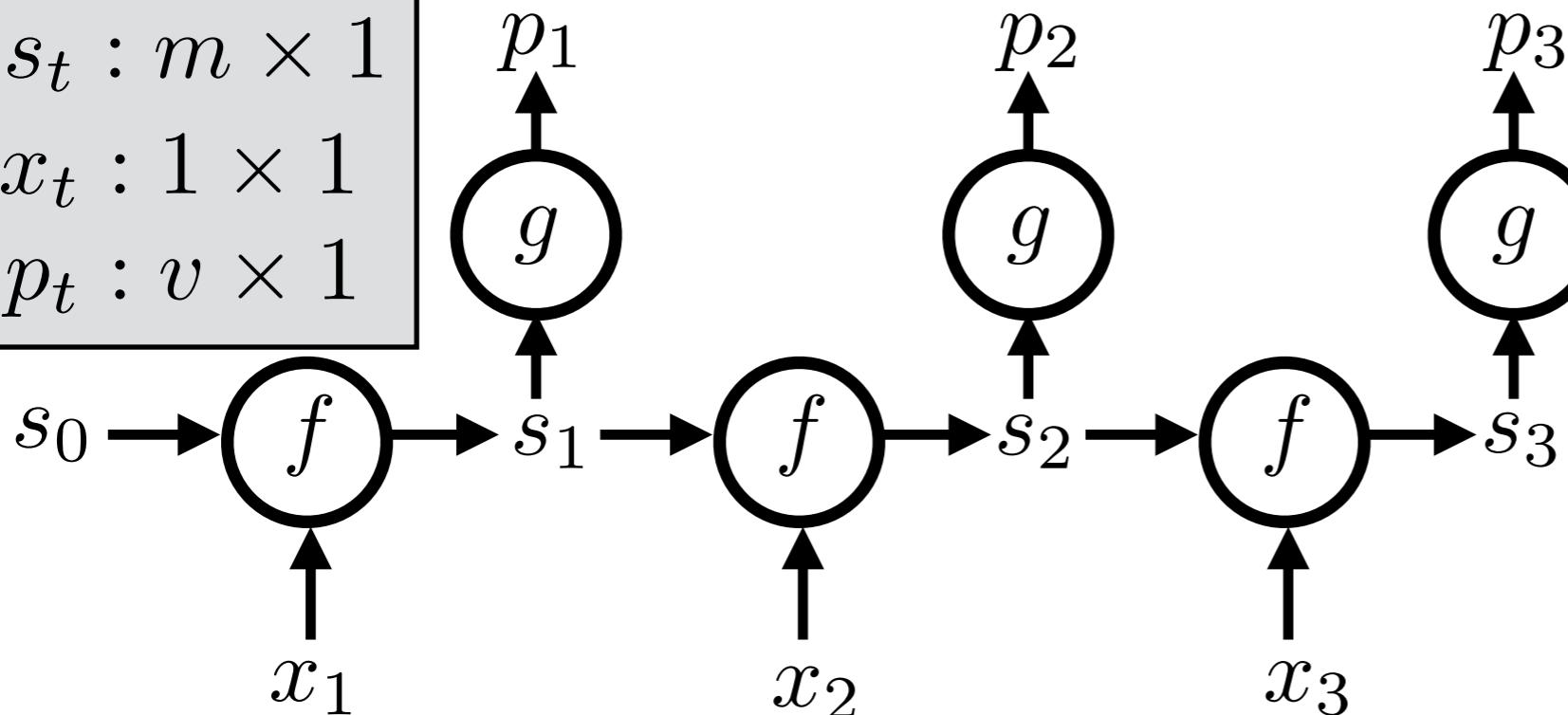
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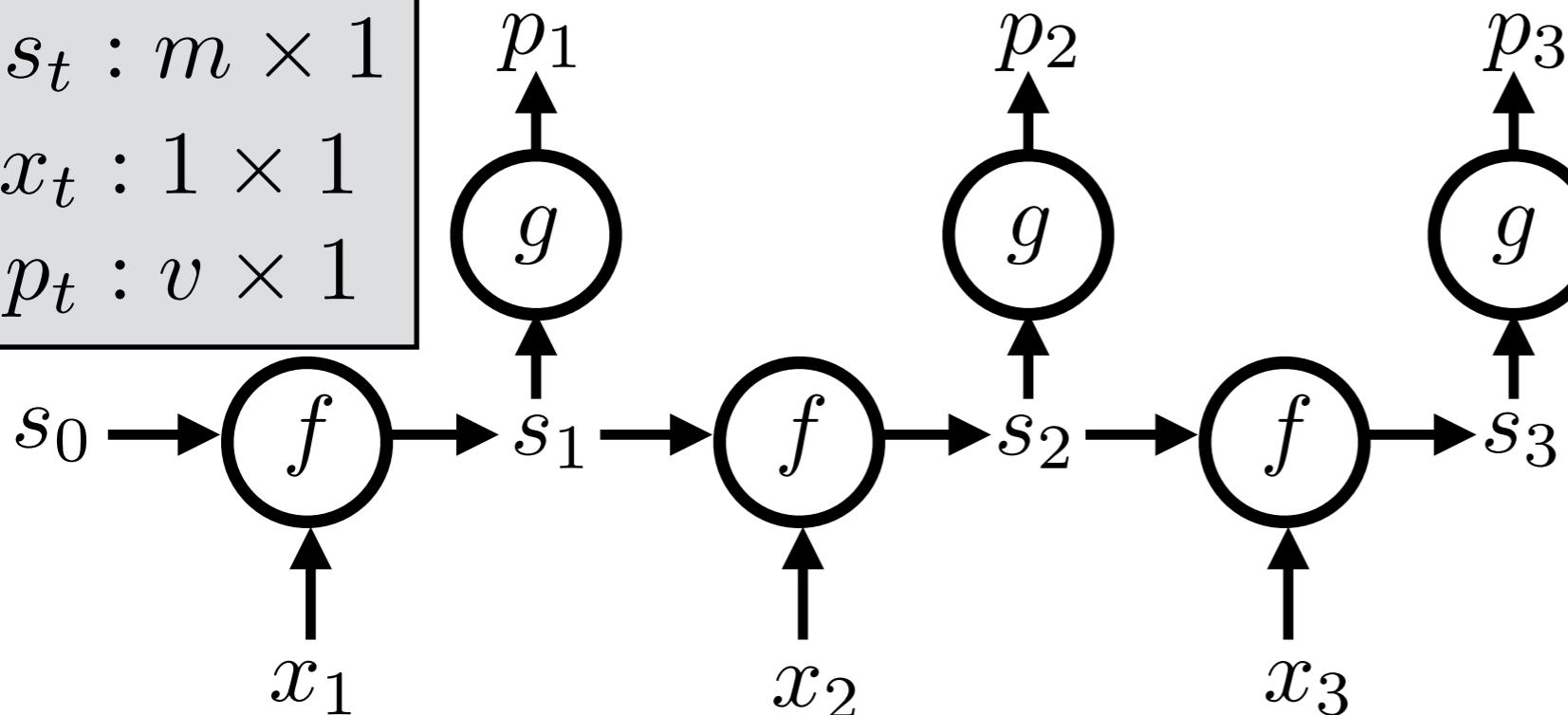
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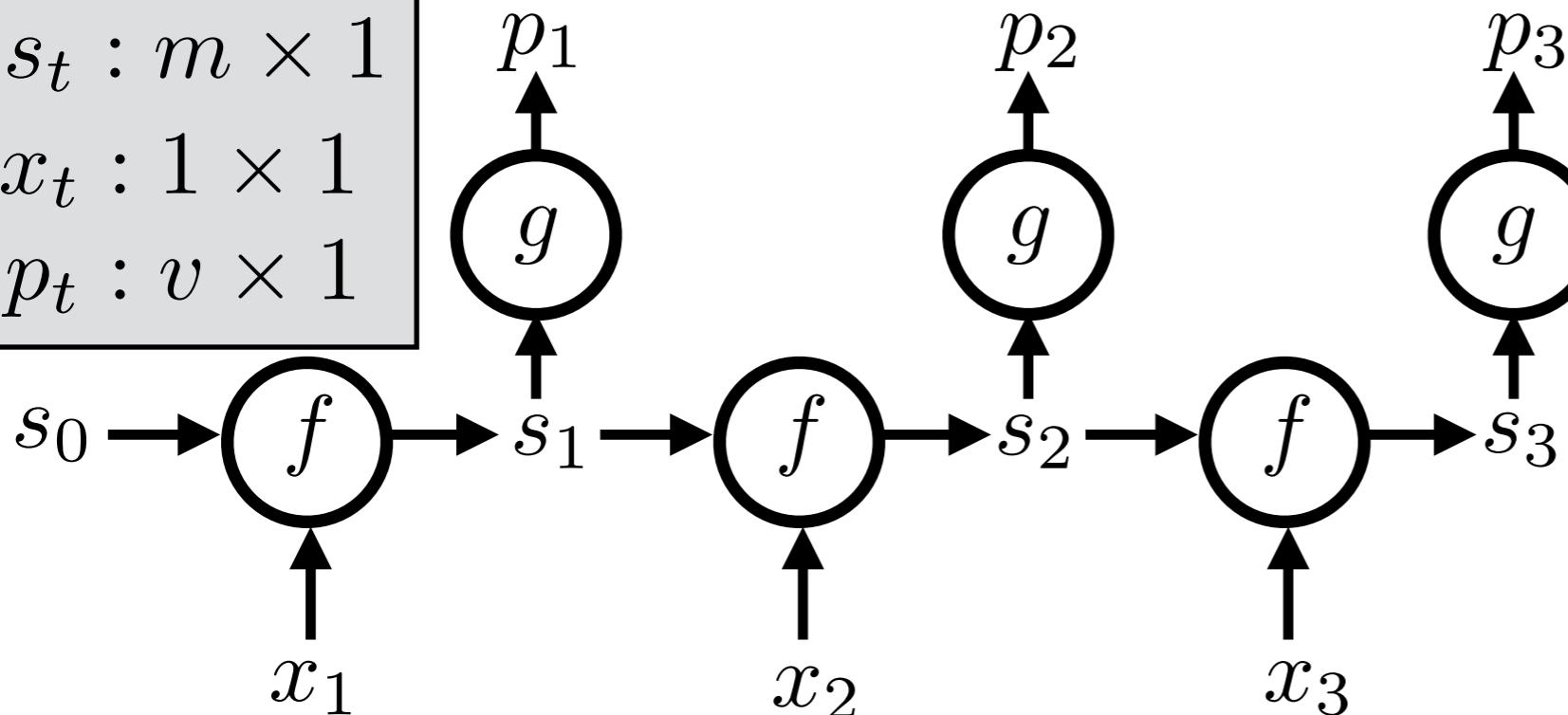
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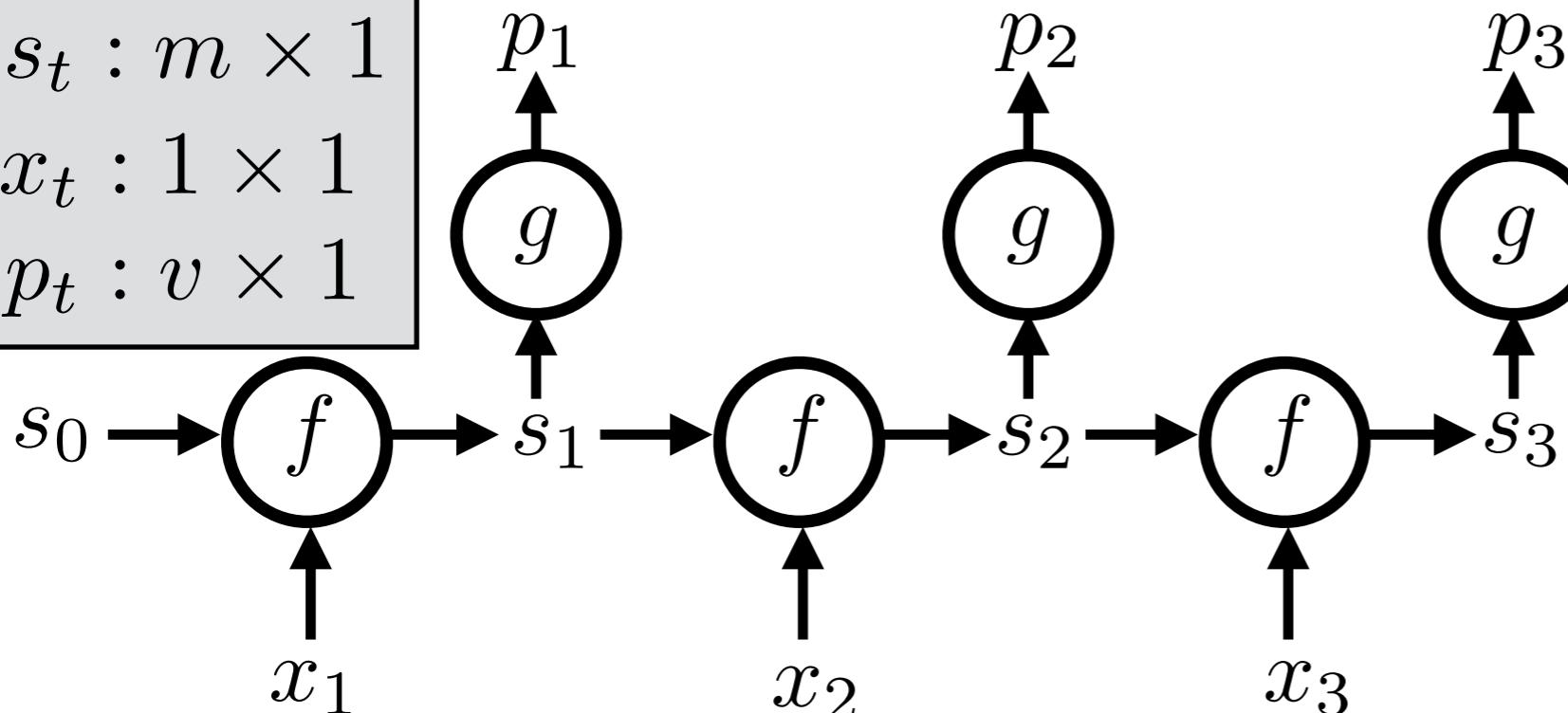
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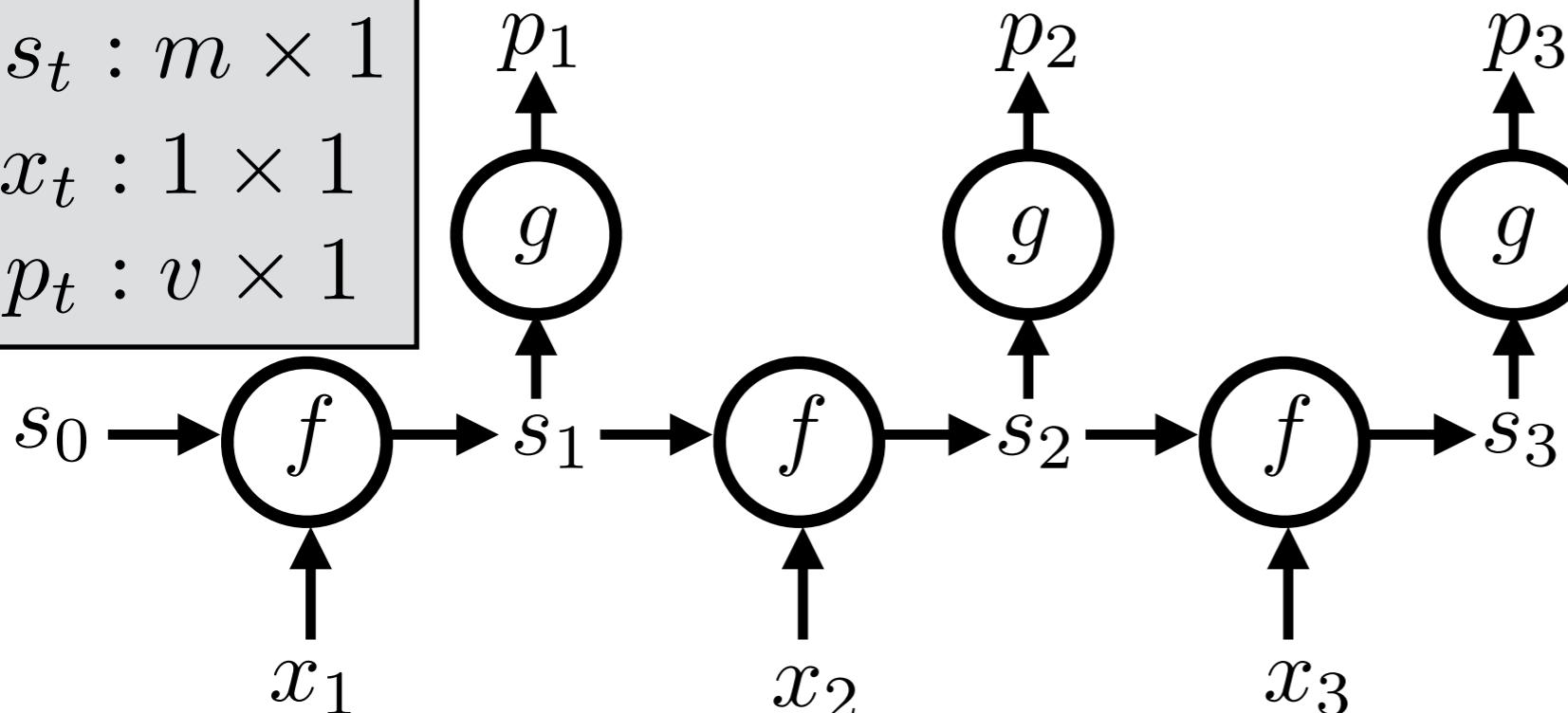
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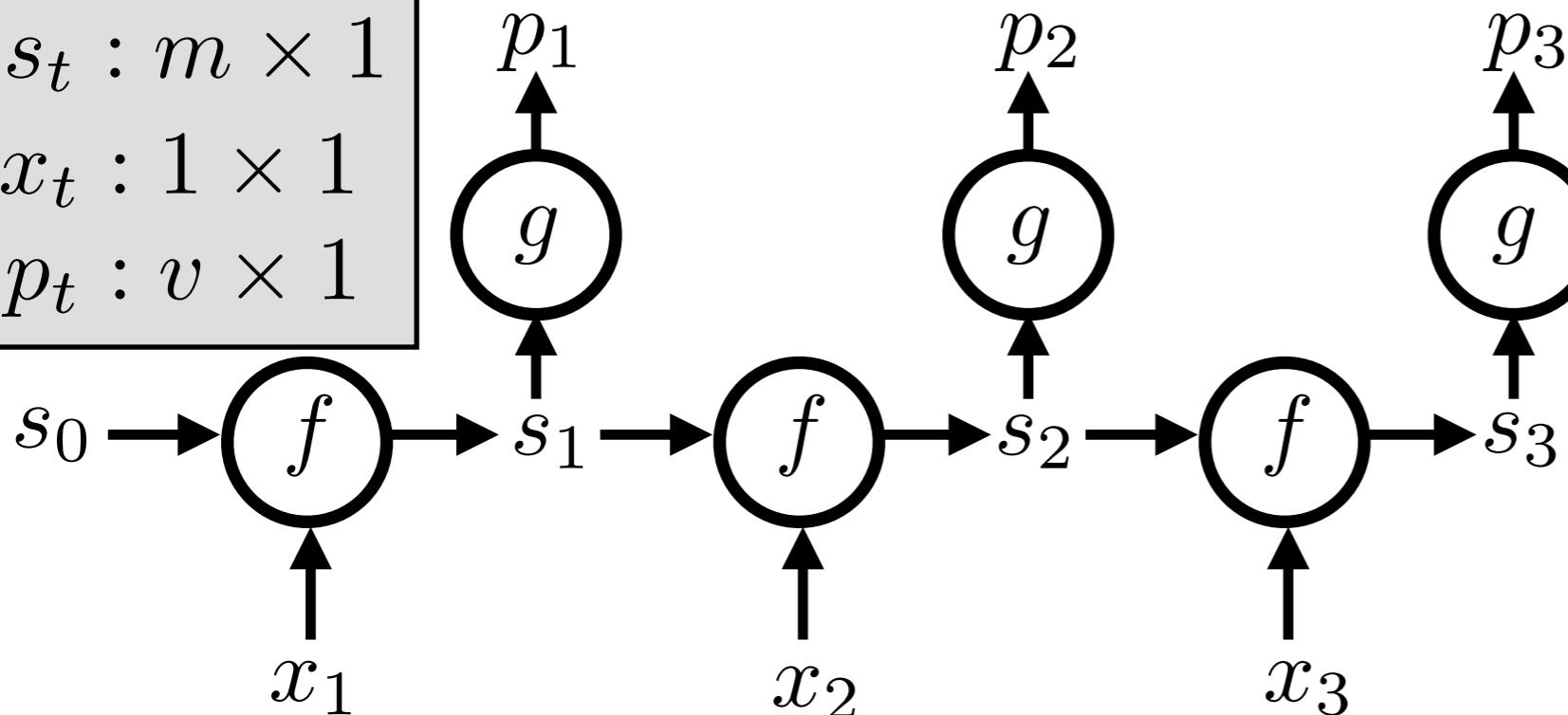
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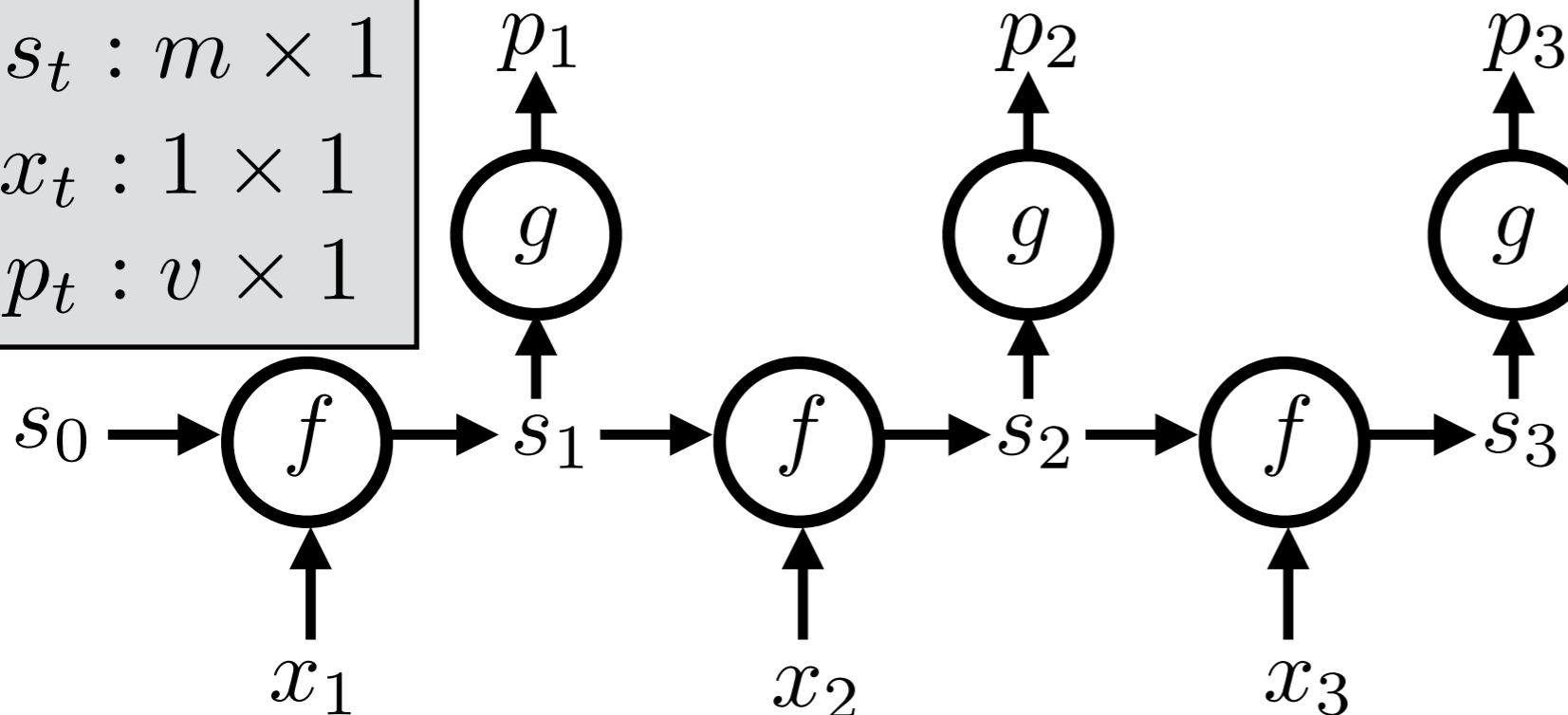
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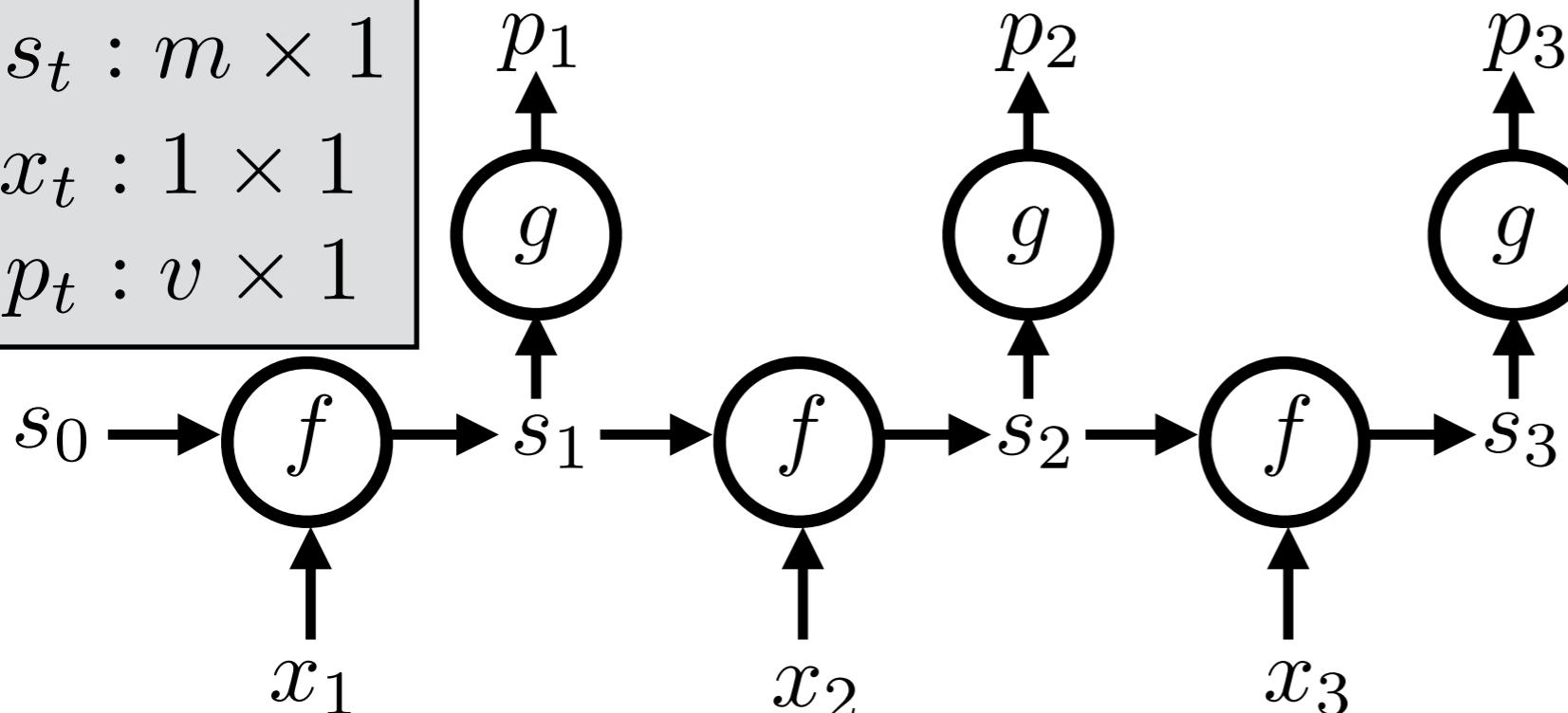
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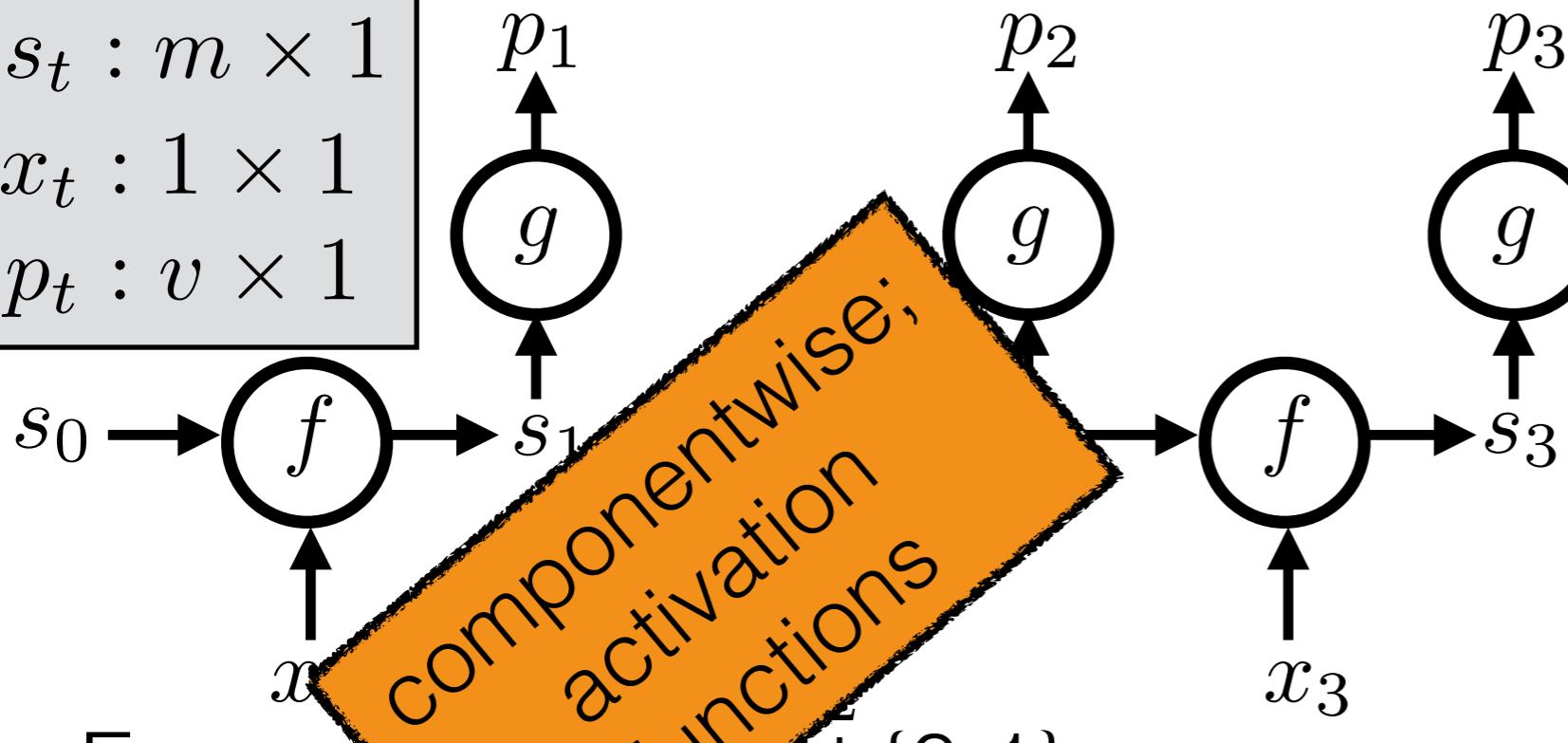
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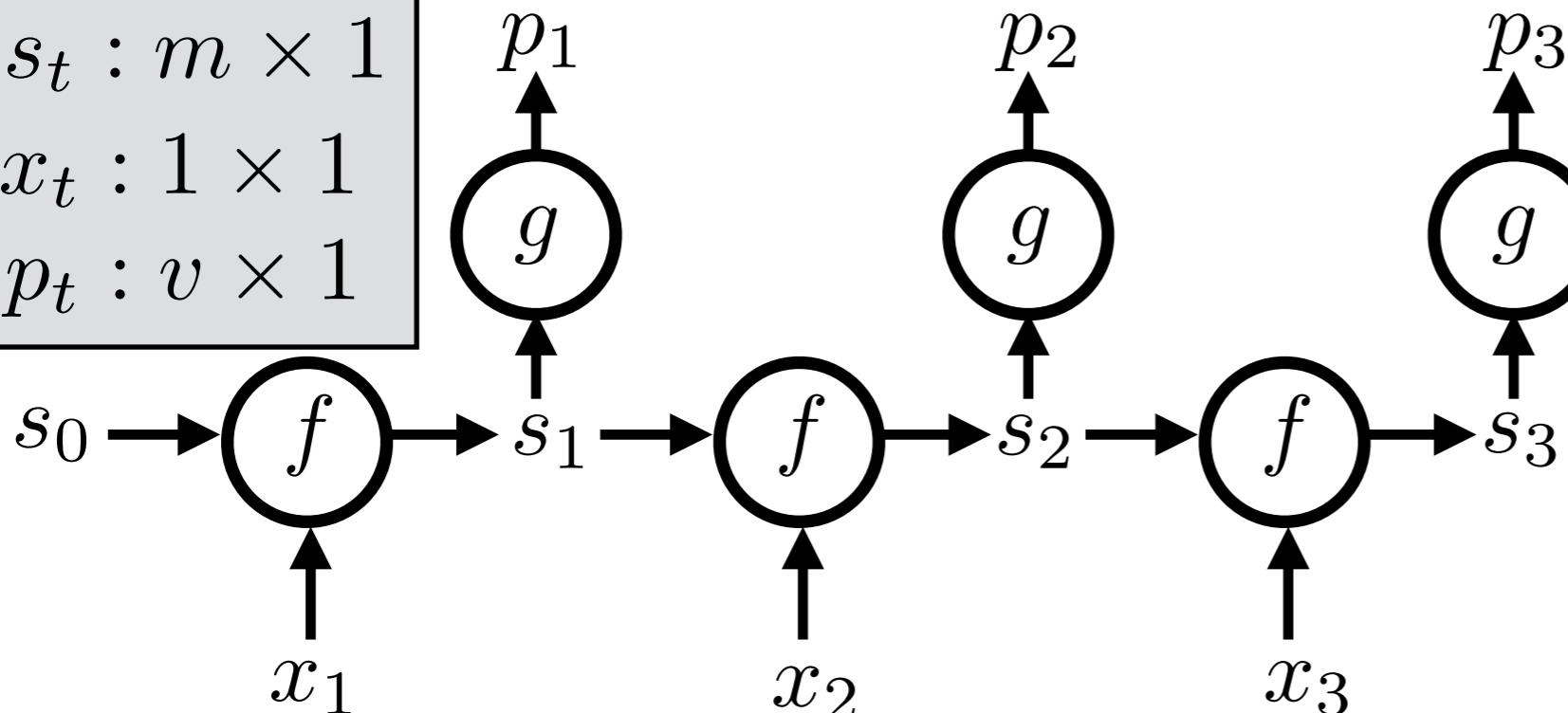
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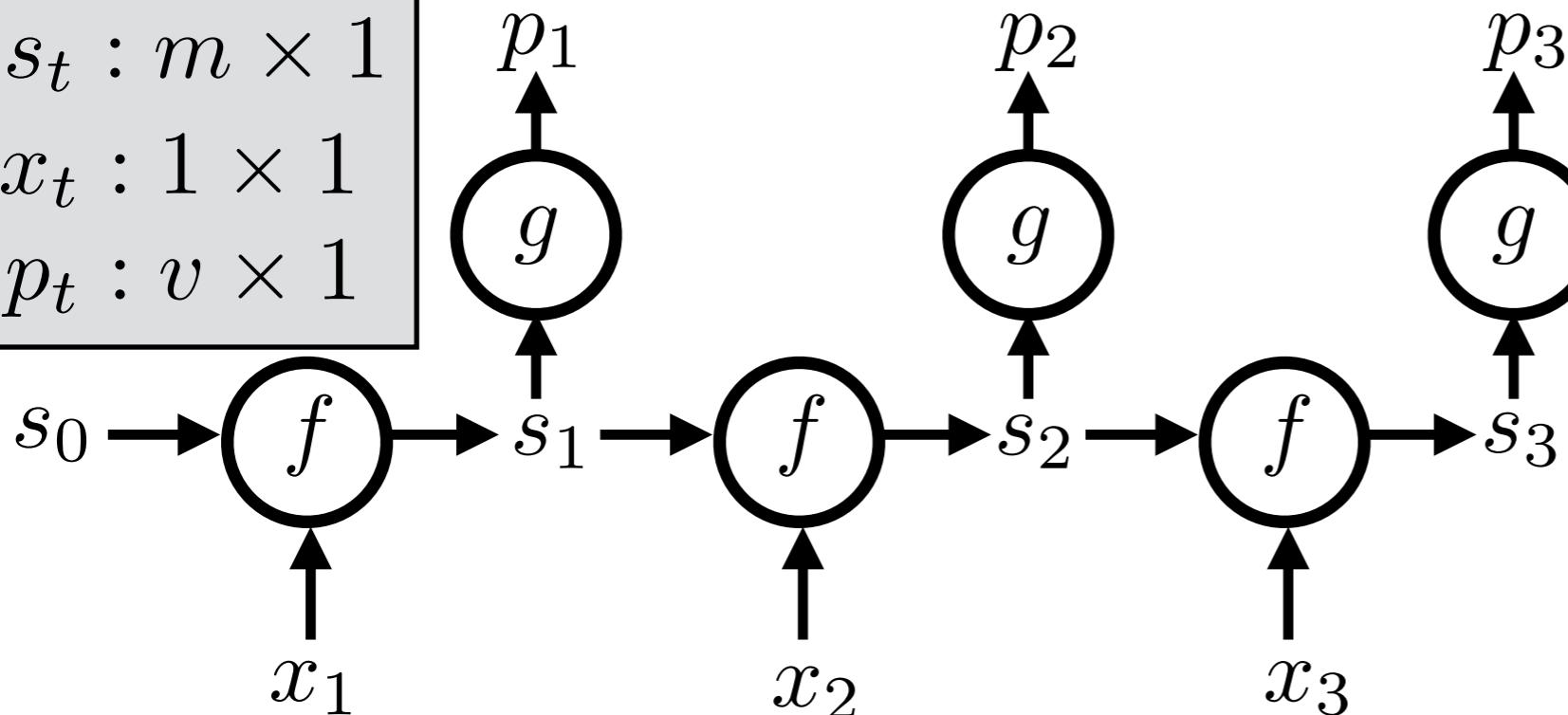
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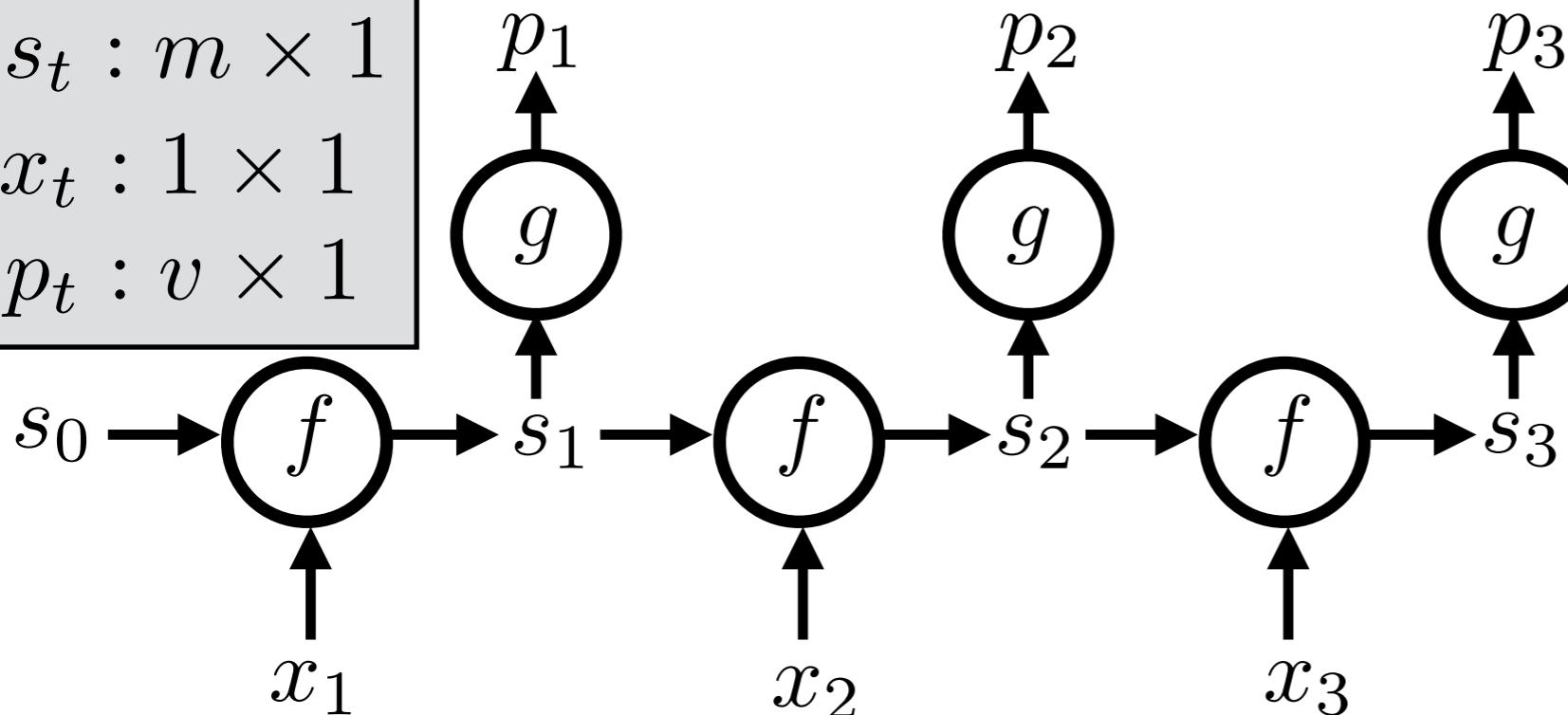
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- Example: Alphabet $\{0,1\}$; state is last $m = 3$ characters

$$s_t = f_1 (W^{sx} x_t + W^{ss} s_{t-1} + W_0^{ss})$$

$$\begin{aligned}p_t &= g(s_t) \\&= f_2(W^o s_t + W_0^o)\end{aligned}$$

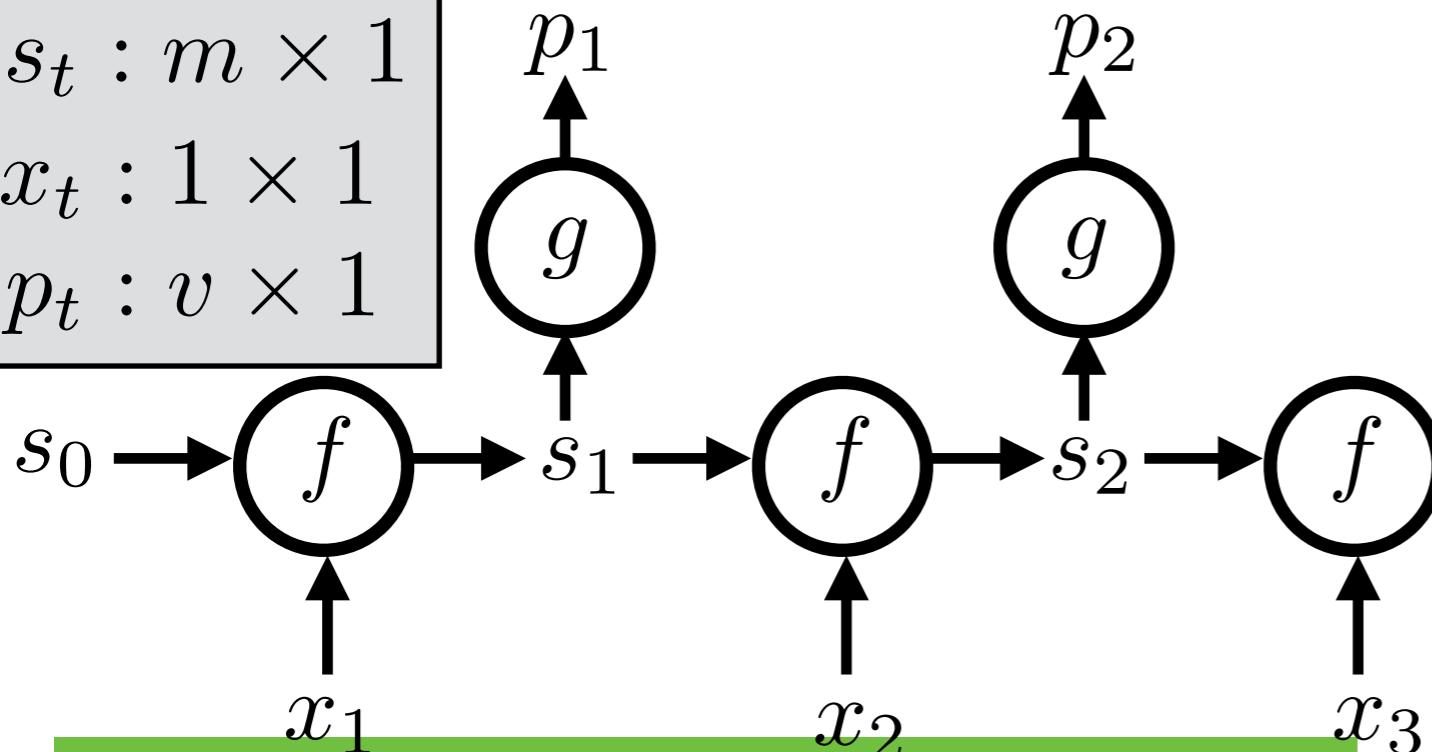
$v \times m \quad v \times 1$

- Recall: familiar pattern
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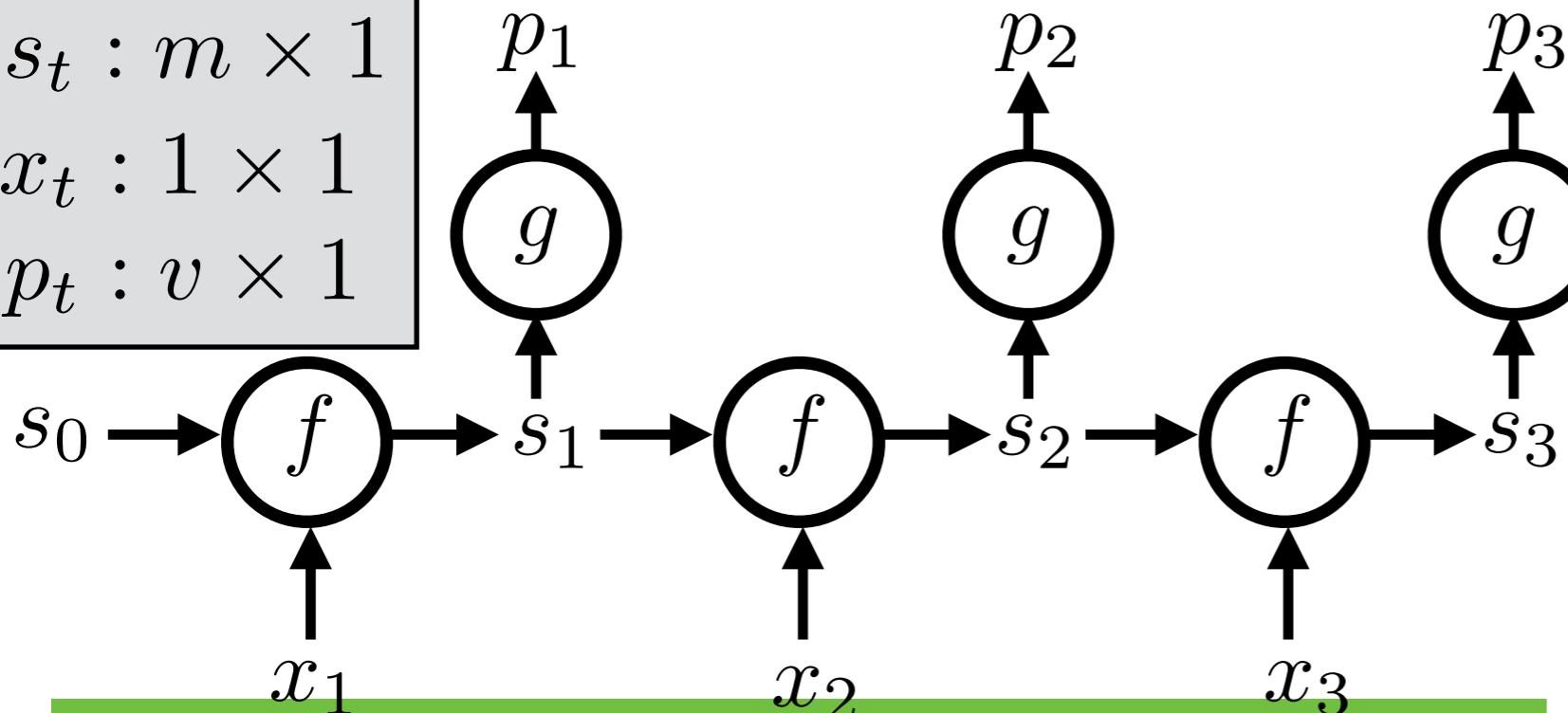
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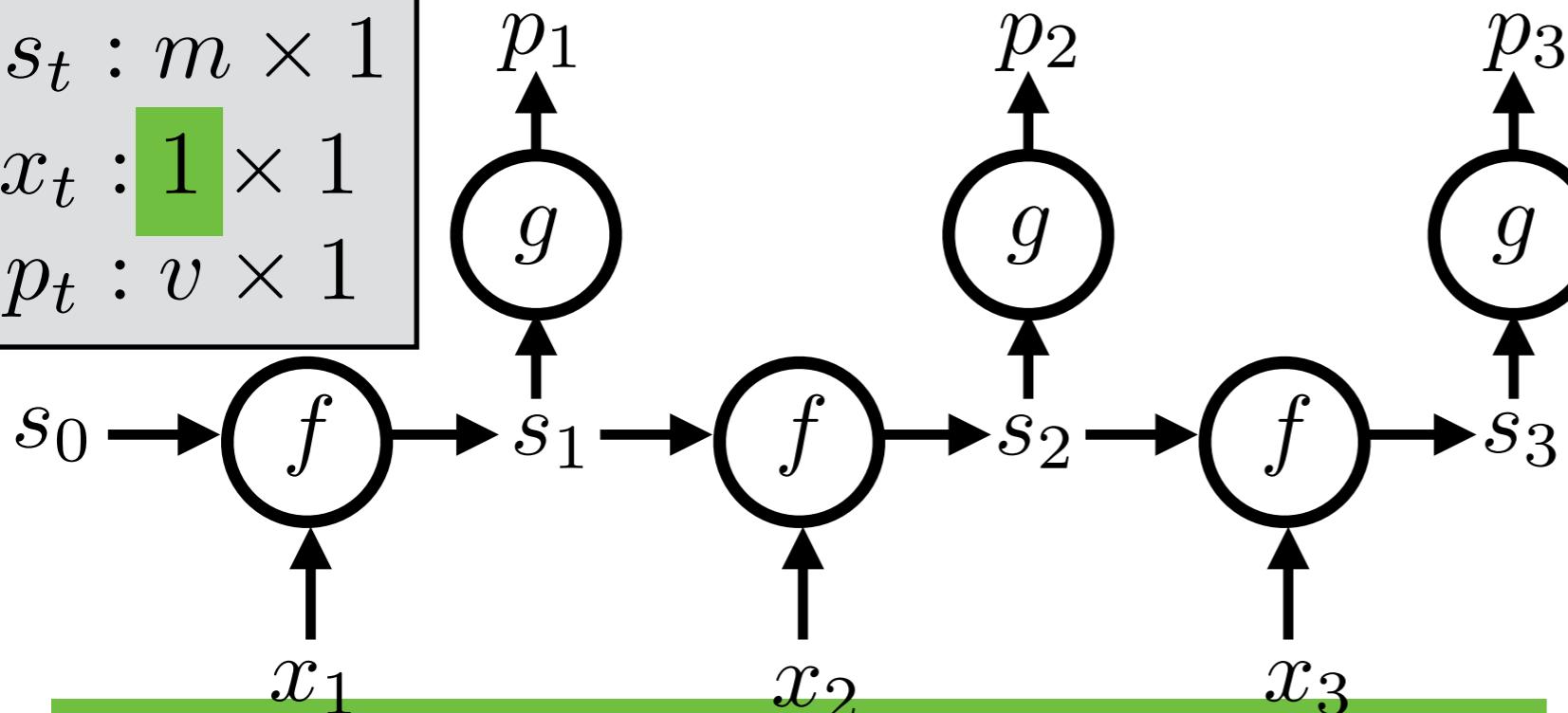
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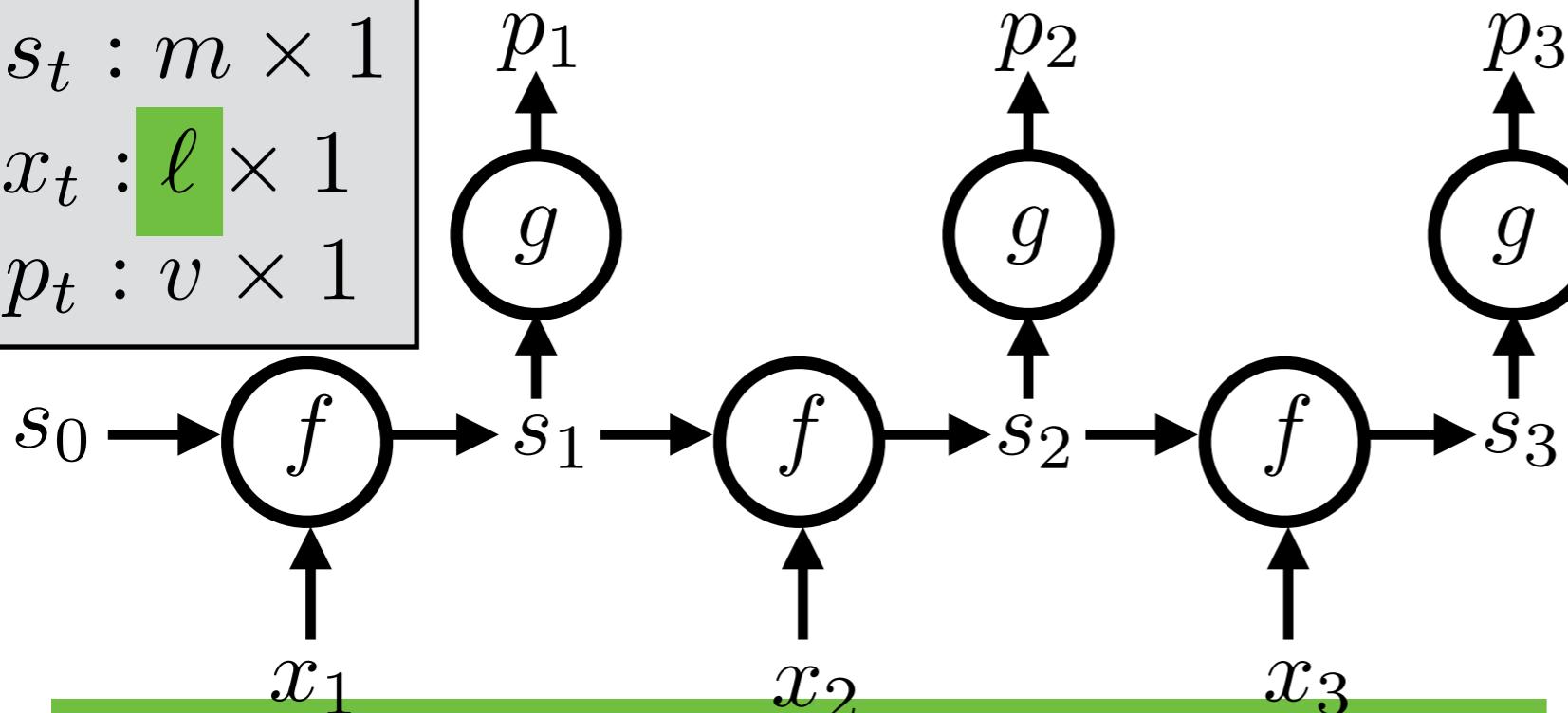
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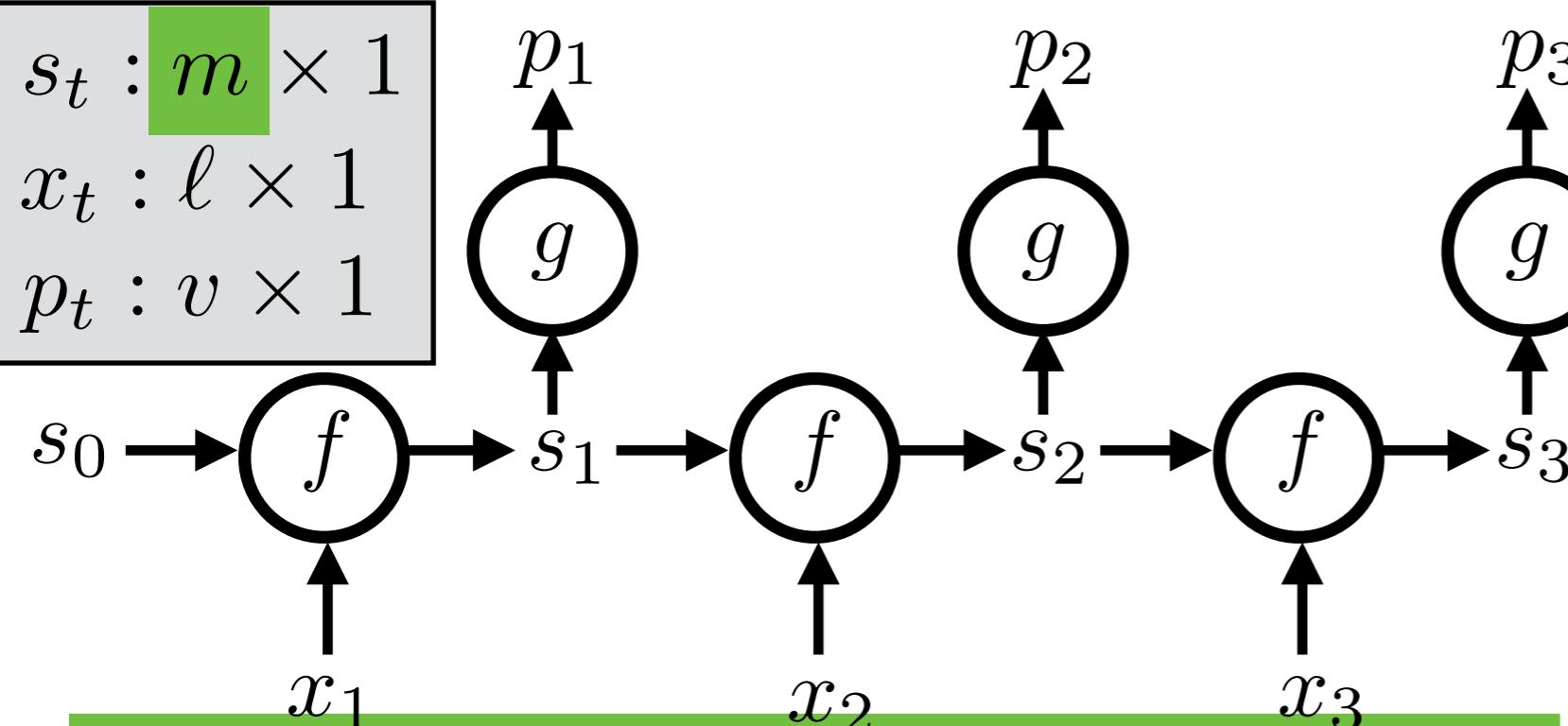
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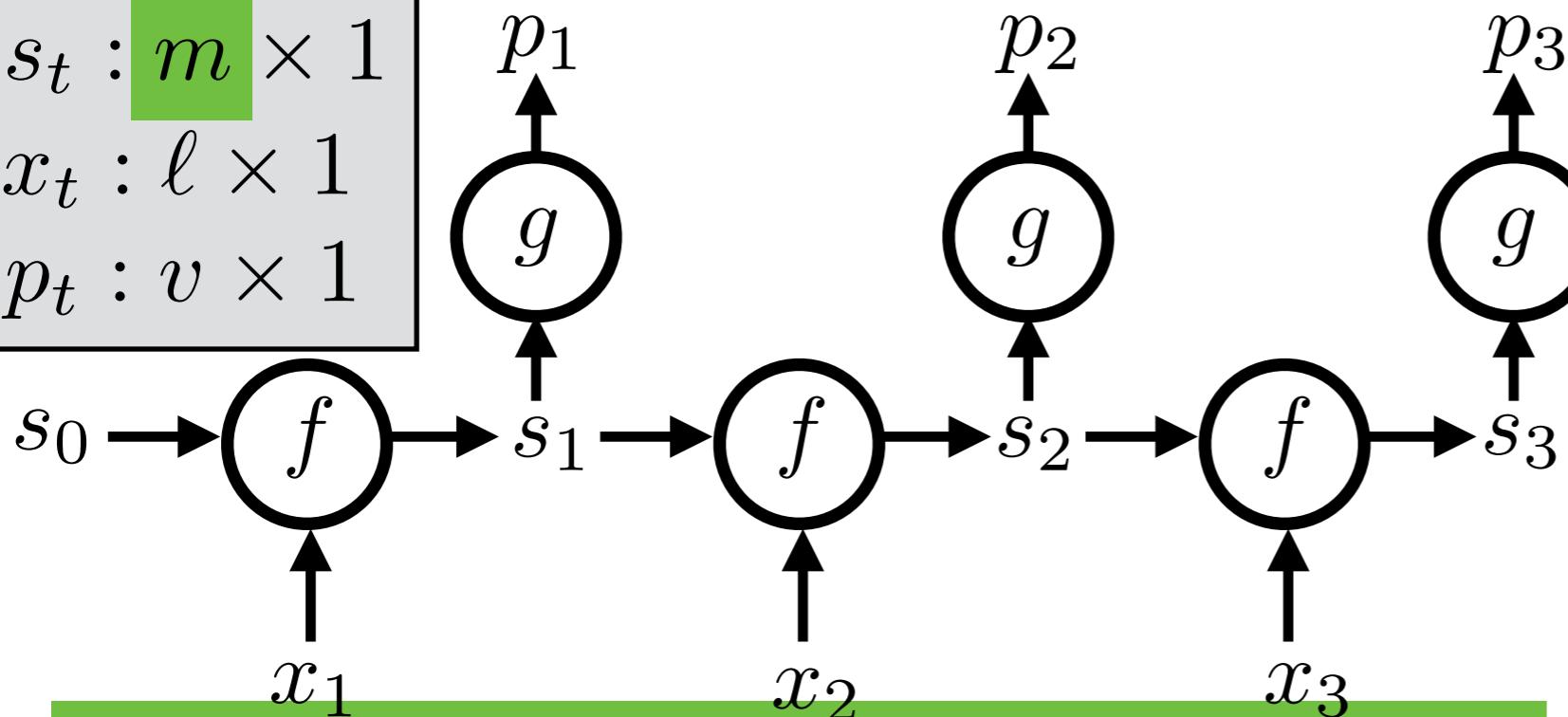
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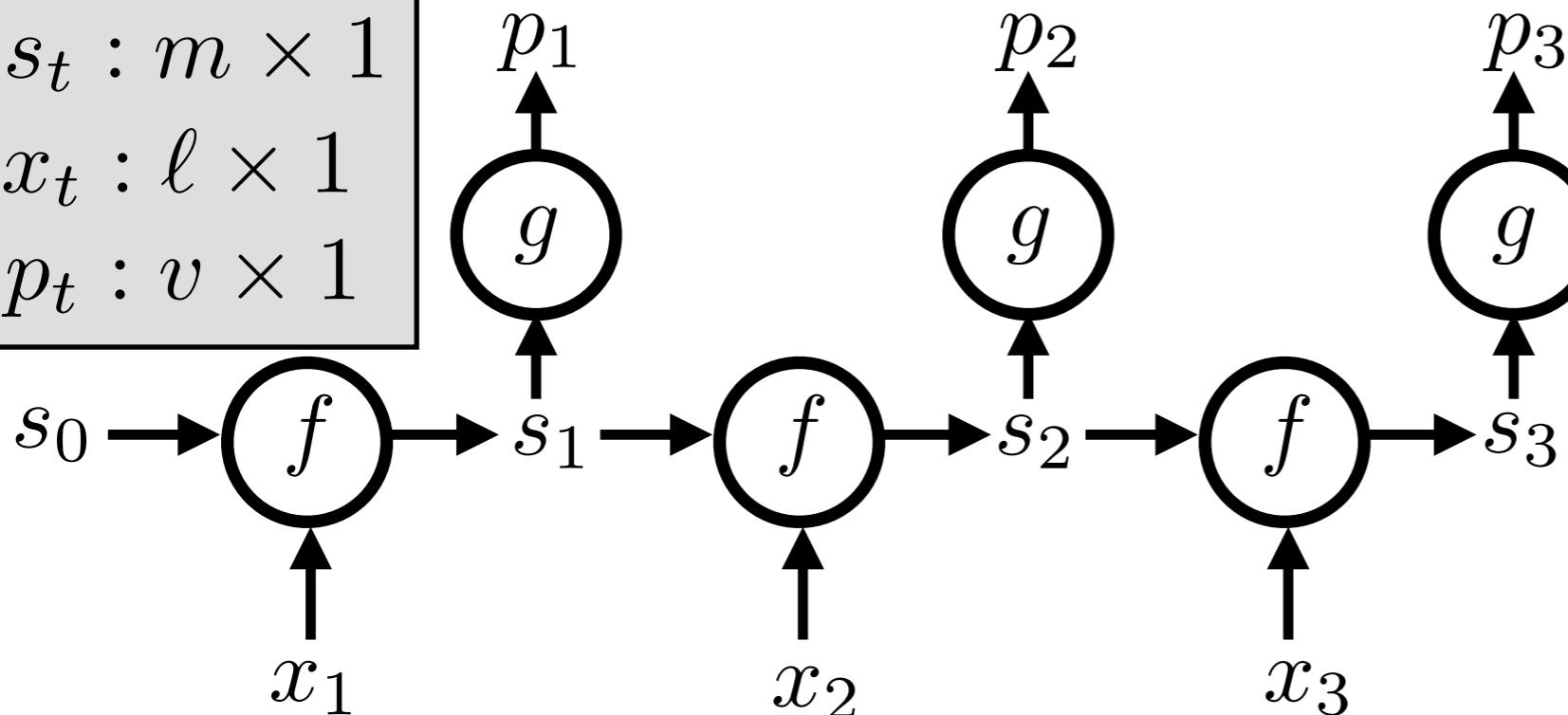
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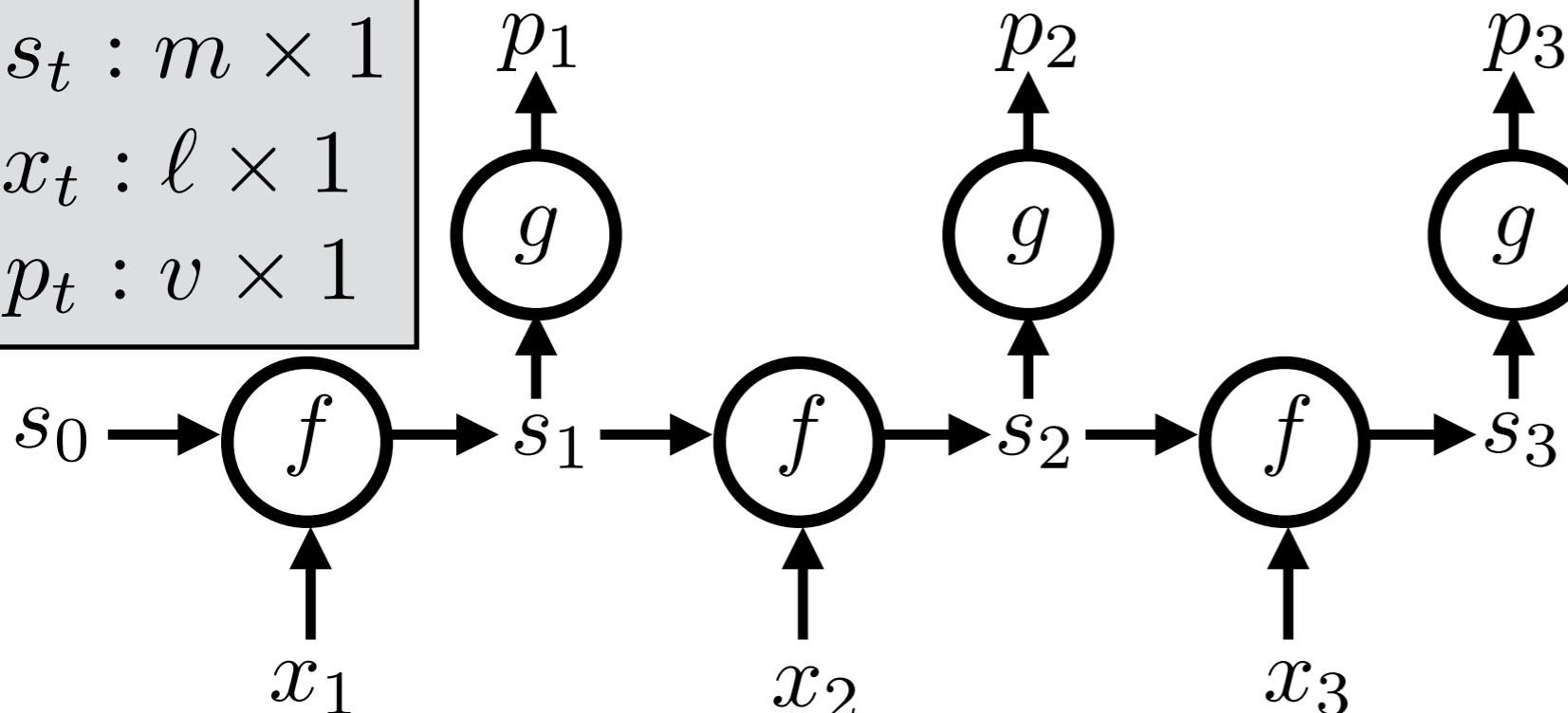
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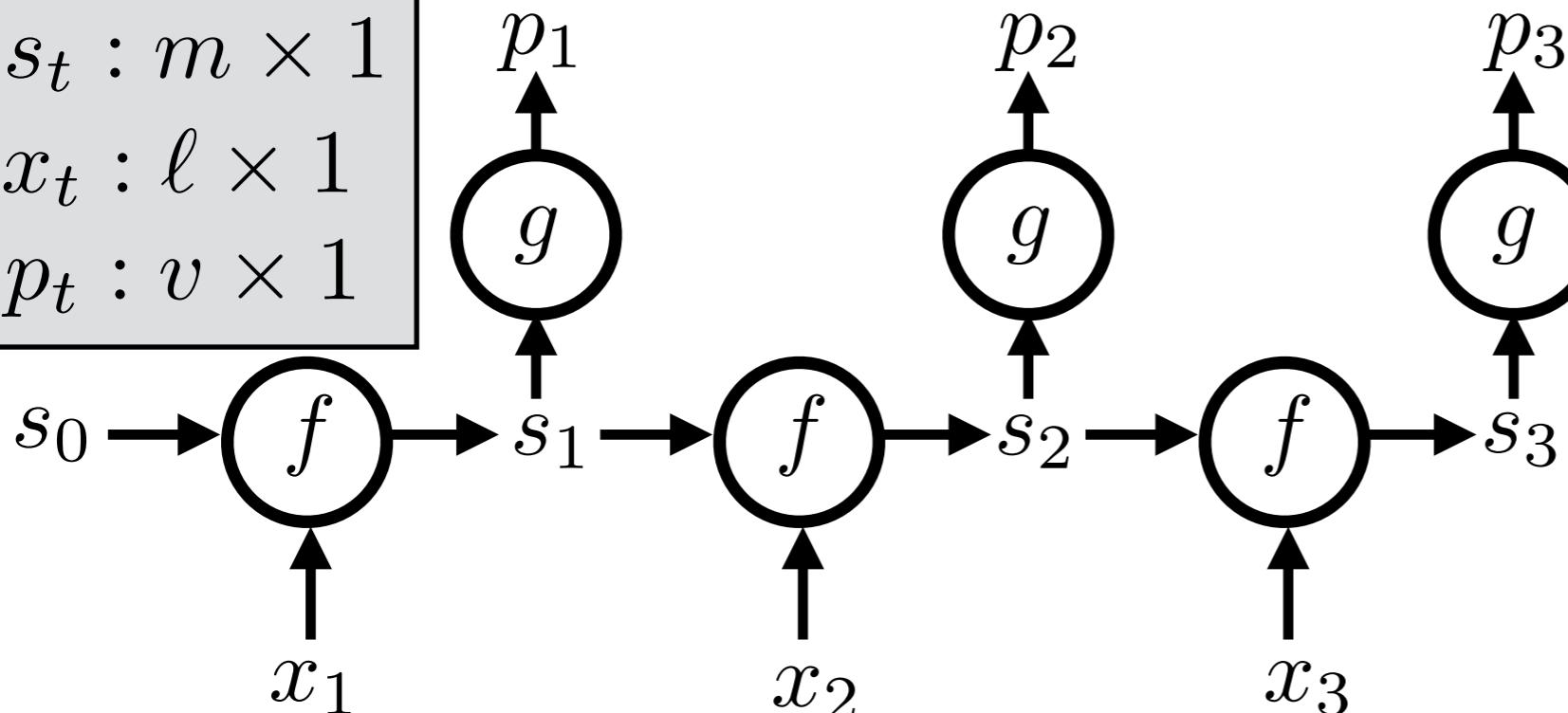
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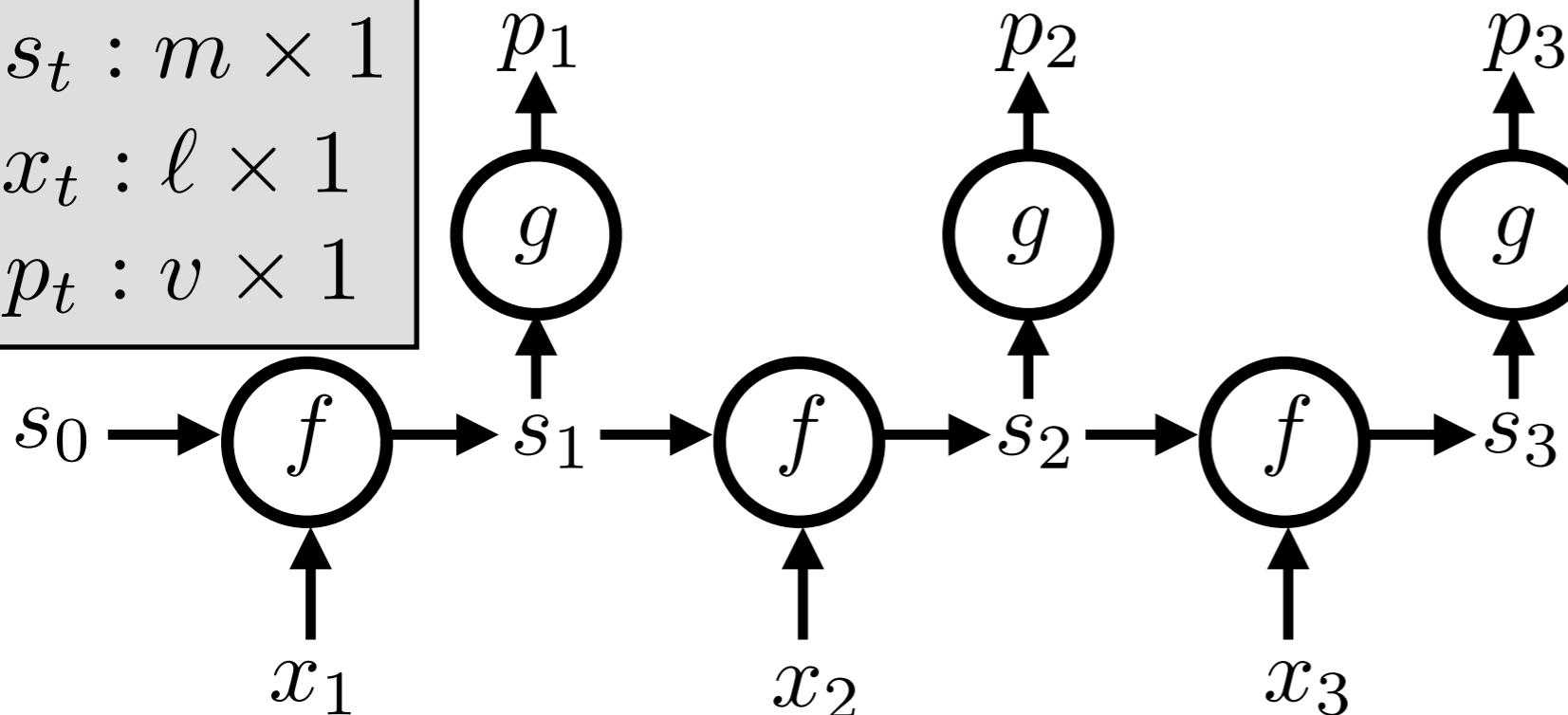
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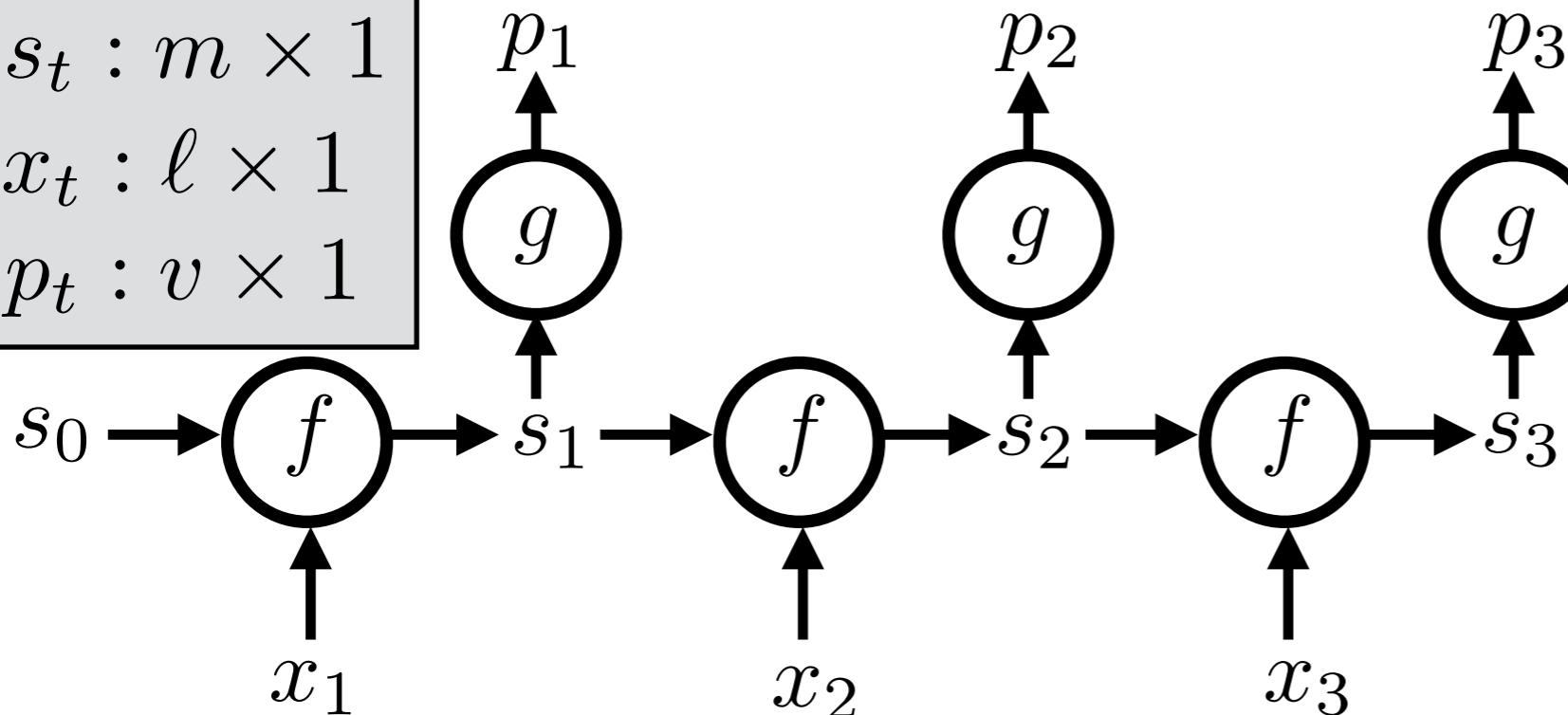
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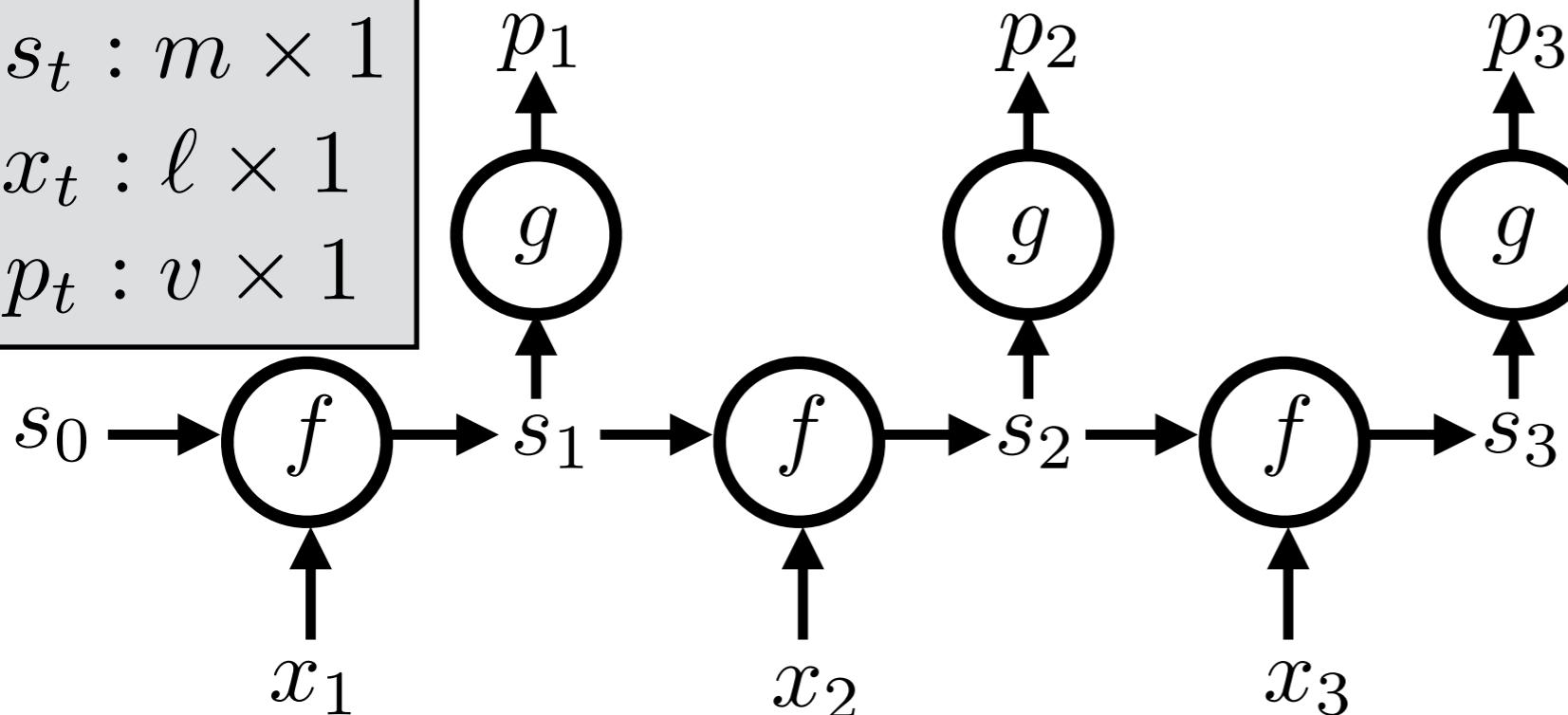
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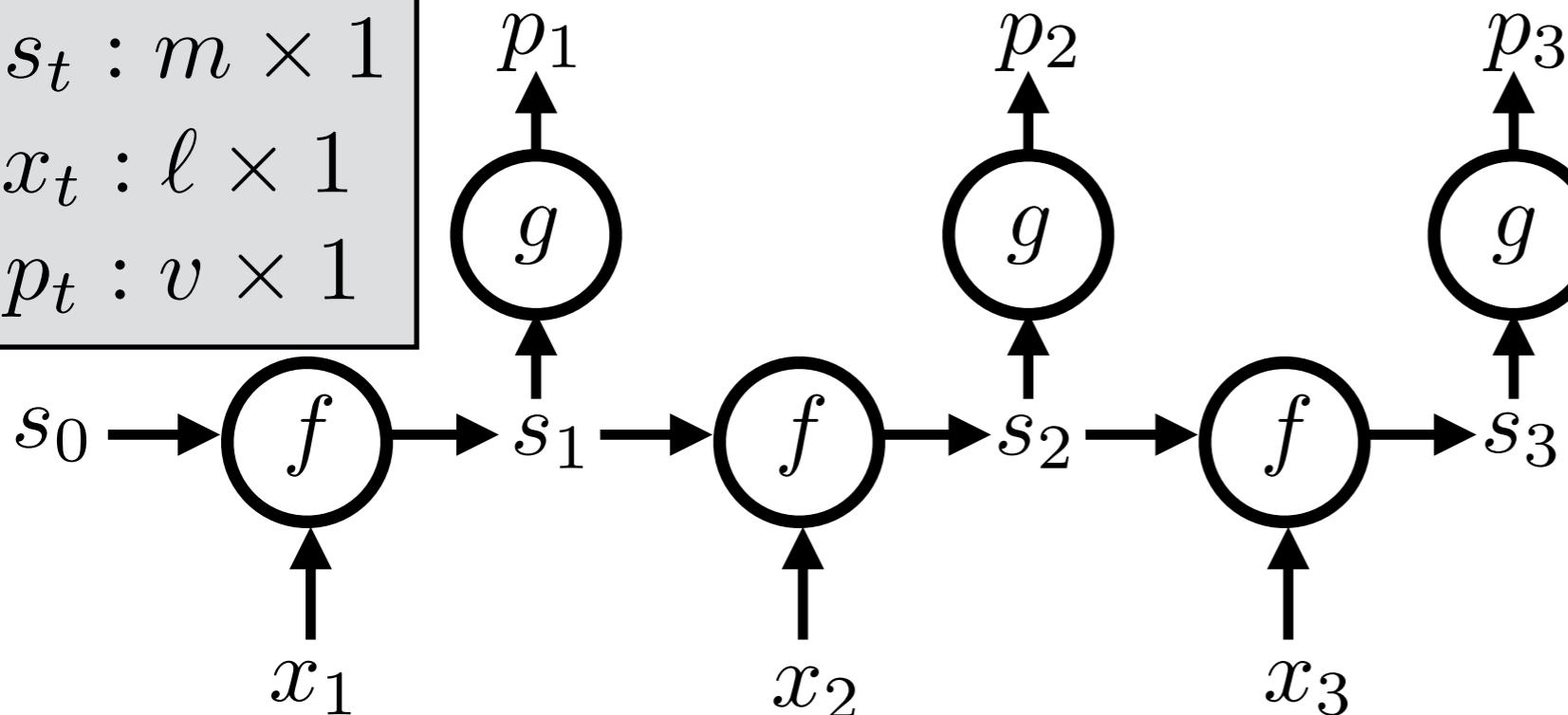
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Recurrent neural network

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- Example: Alphabet of ℓ chars; state is last c chars ($m = cl$)

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Recurrent neural network

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$$s_t = f_1(W^{sx}x_t + W^{ss}s_{t-1} + W_0^{ss})$$

$$p_t = f_2(W^o s_t + W_0^o) \quad p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$s_t : m \times 1$$

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$$x_1$$

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$$s_0 \rightarrow$$

$$\xrightarrow{x_1}$$

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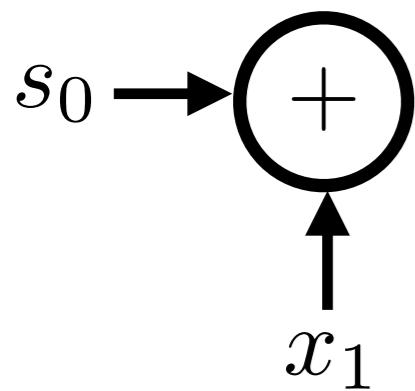
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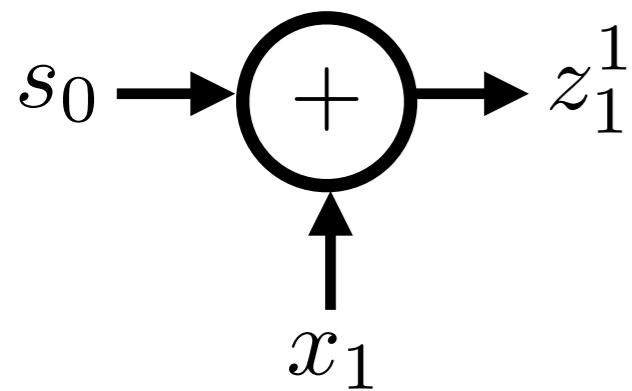
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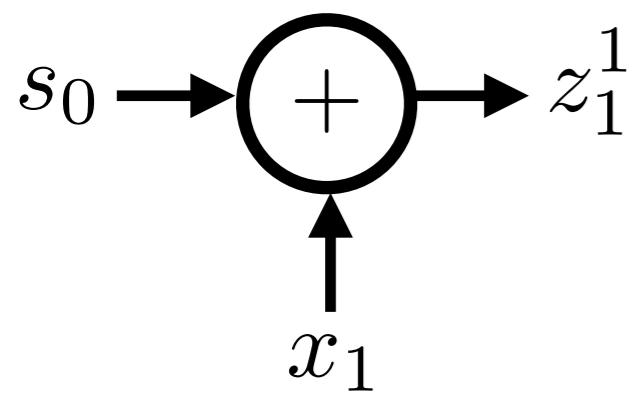
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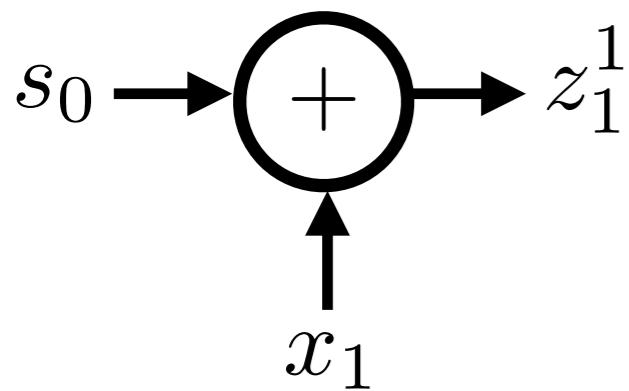
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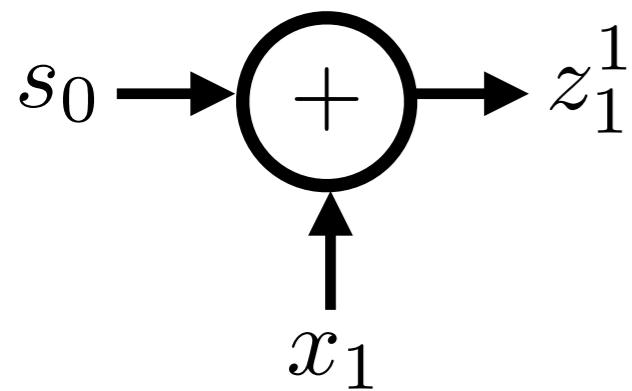
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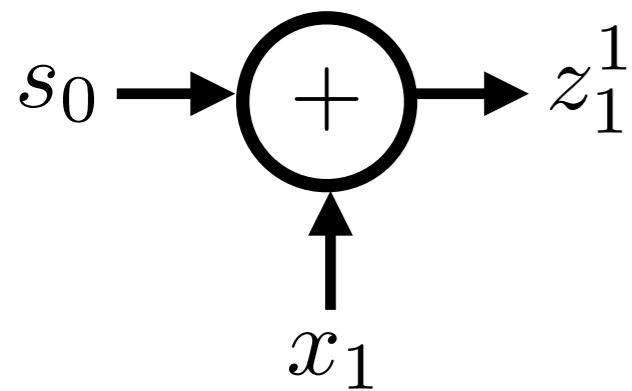
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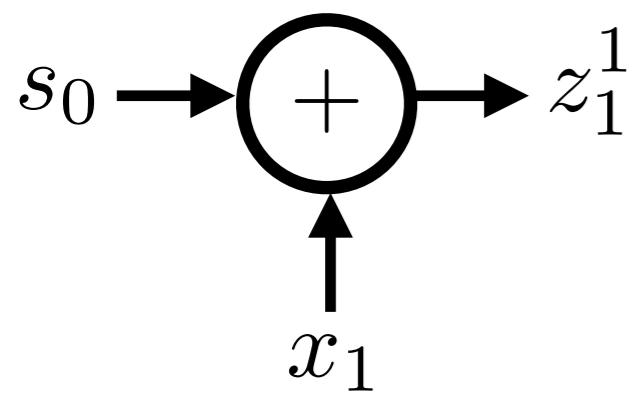
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$$p_t = f_2 \left(\underbrace{W^o s_t}_{p_t} + W_0^o \right) \rightarrow z_t^1 \rightarrow z_t^2$$

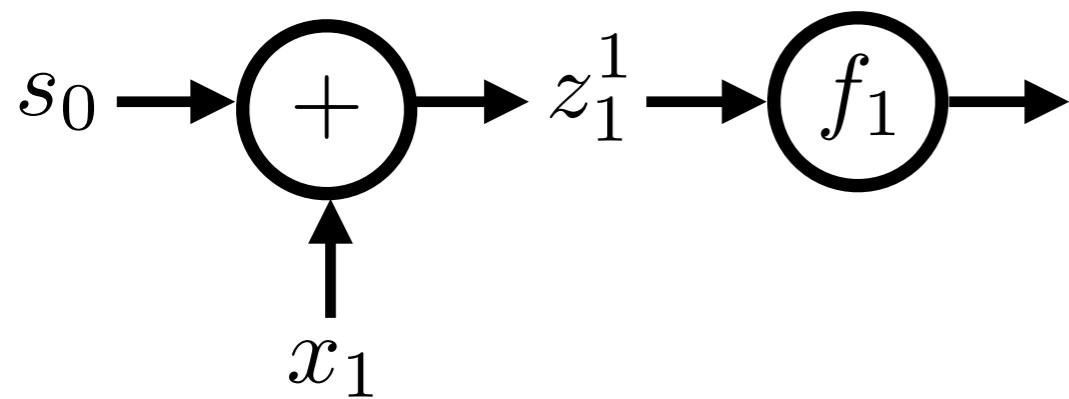
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$$s_t : m \times 1$$

$$x_t : \ell \times 1$$

$$p_t : v \times 1$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

$$s_t = f_1 \left(\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{\text{Input and previous state}} + \underbrace{W_0^{ss}}_{\text{Initial state}} \right)$$

$$p_t = f_2 \left(\underbrace{W^o s_t}_{\text{Output of hidden state}} + \underbrace{W_0^o}_{\text{Initial output}} \right)$$

$\xrightarrow{\hspace{1cm}} z_t^1$
 $\xrightarrow{\hspace{1cm}} z_t^2$

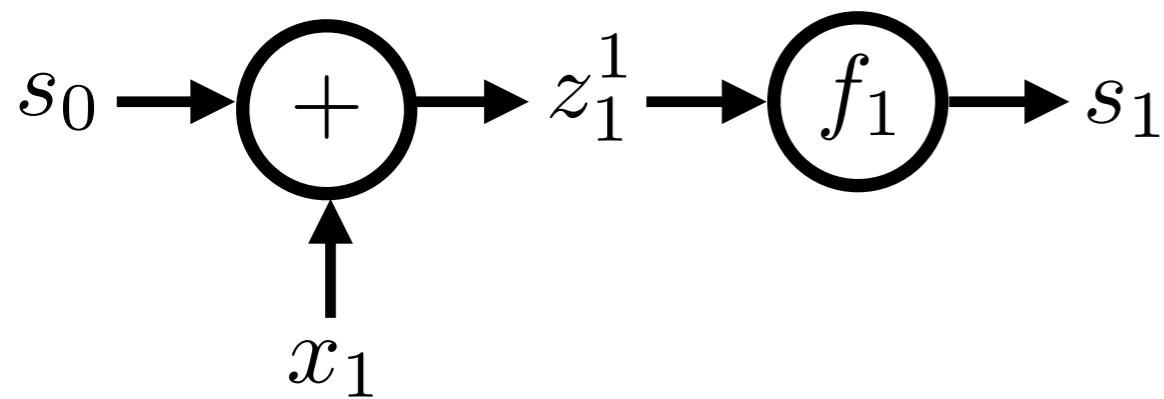
$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$s_t : m \times 1$$

$$x_t : \ell \times 1$$

$$p_t : v \times 1$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

$$s_t = f_1(W^{sx}x_t + W^{ss}s_{t-1} + W_0^{ss})$$

$$p_t = f_2(W^o s_t + W_0^o)$$

$\xrightarrow{z_t^1}$ $\xrightarrow{z_t^2}$

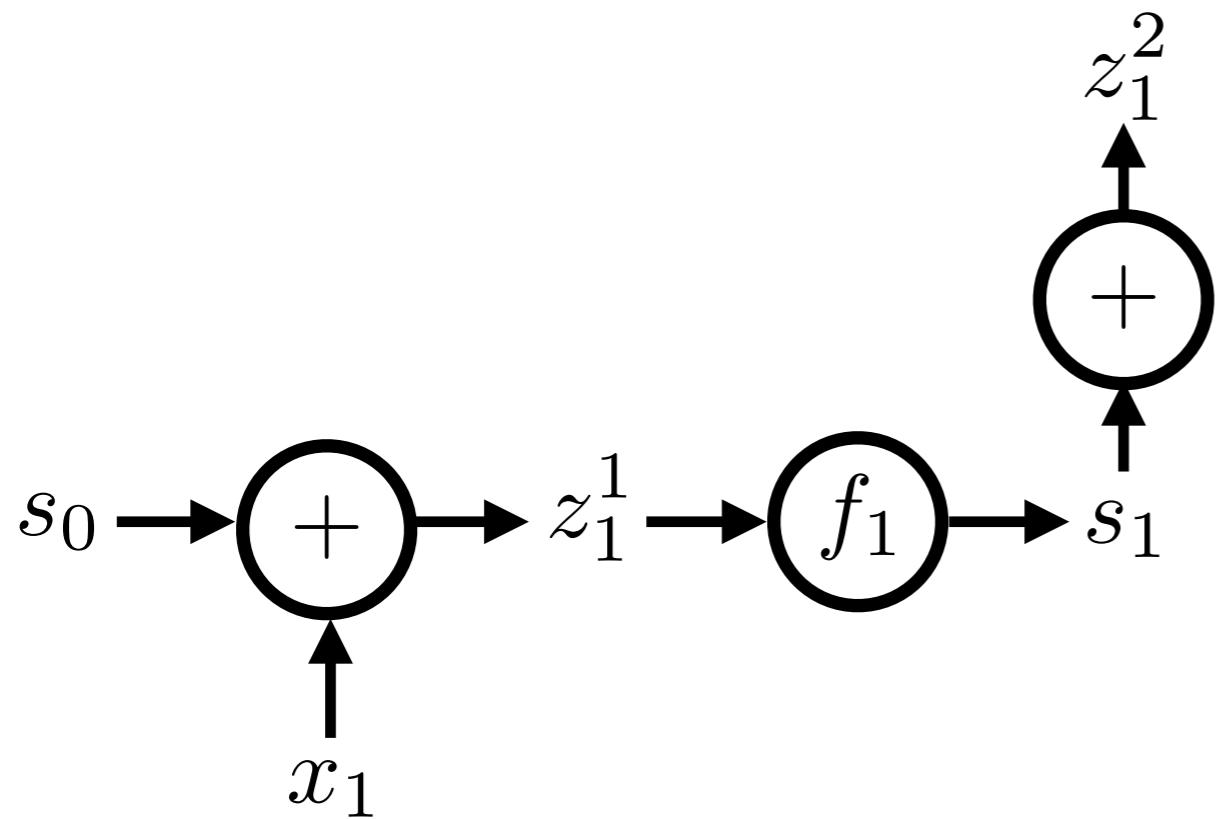
$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$s_t : m \times 1$$

$$x_t : \ell \times 1$$

$$p_t : v \times 1$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

$$s_t = f_1 \left(\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{\text{Input and previous state}} + \underbrace{W_0^{ss}}_{\text{Initial state}} \right)$$

$$p_t = f_2 \left(\underbrace{W^o s_t}_{\text{Output of hidden state}} + \underbrace{W_0^o}_{\text{Initial output}} \right)$$

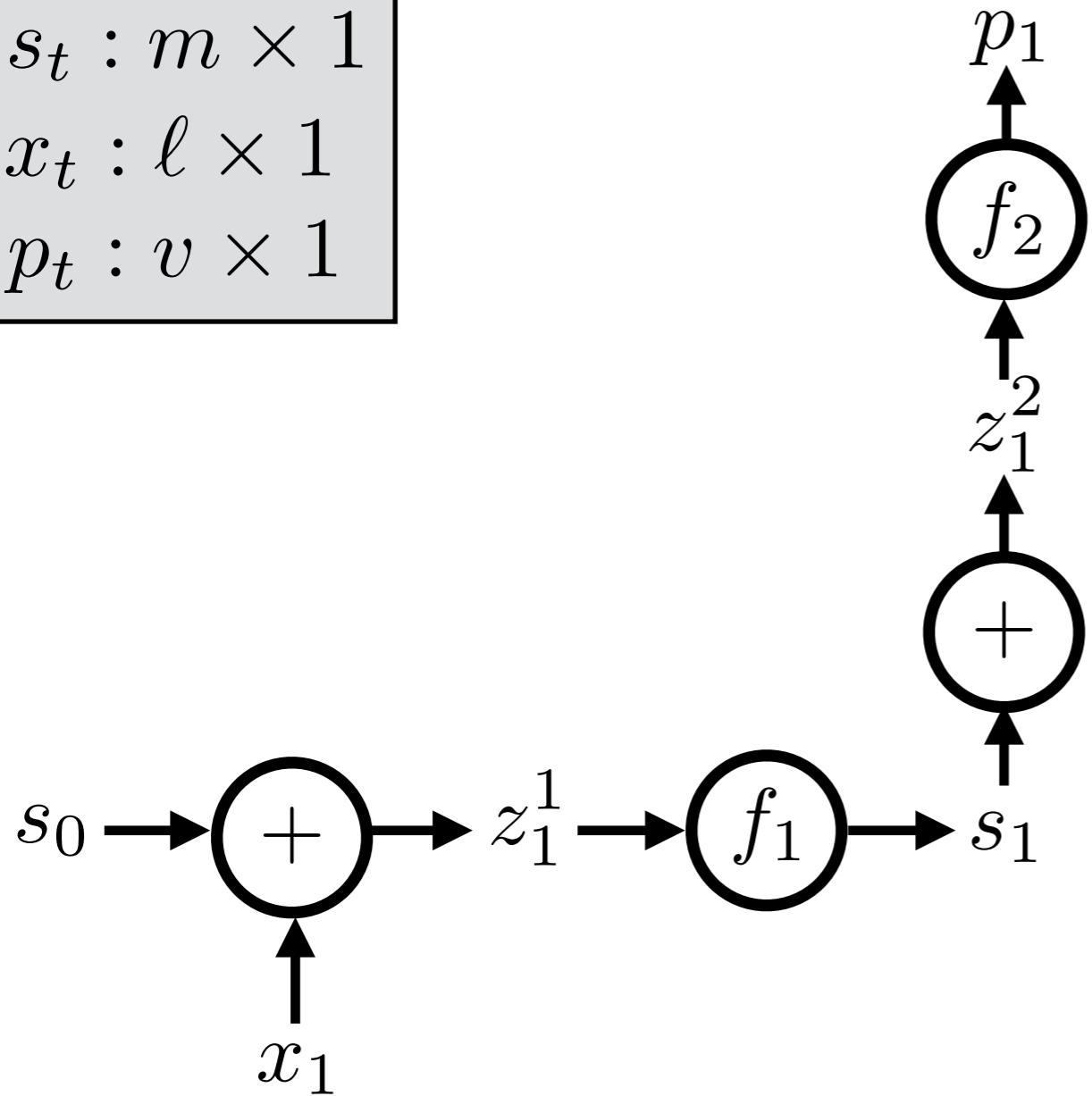
$\xrightarrow{\quad}$

$$\begin{matrix} z_t^1 \\ z_t^2 \end{matrix}$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

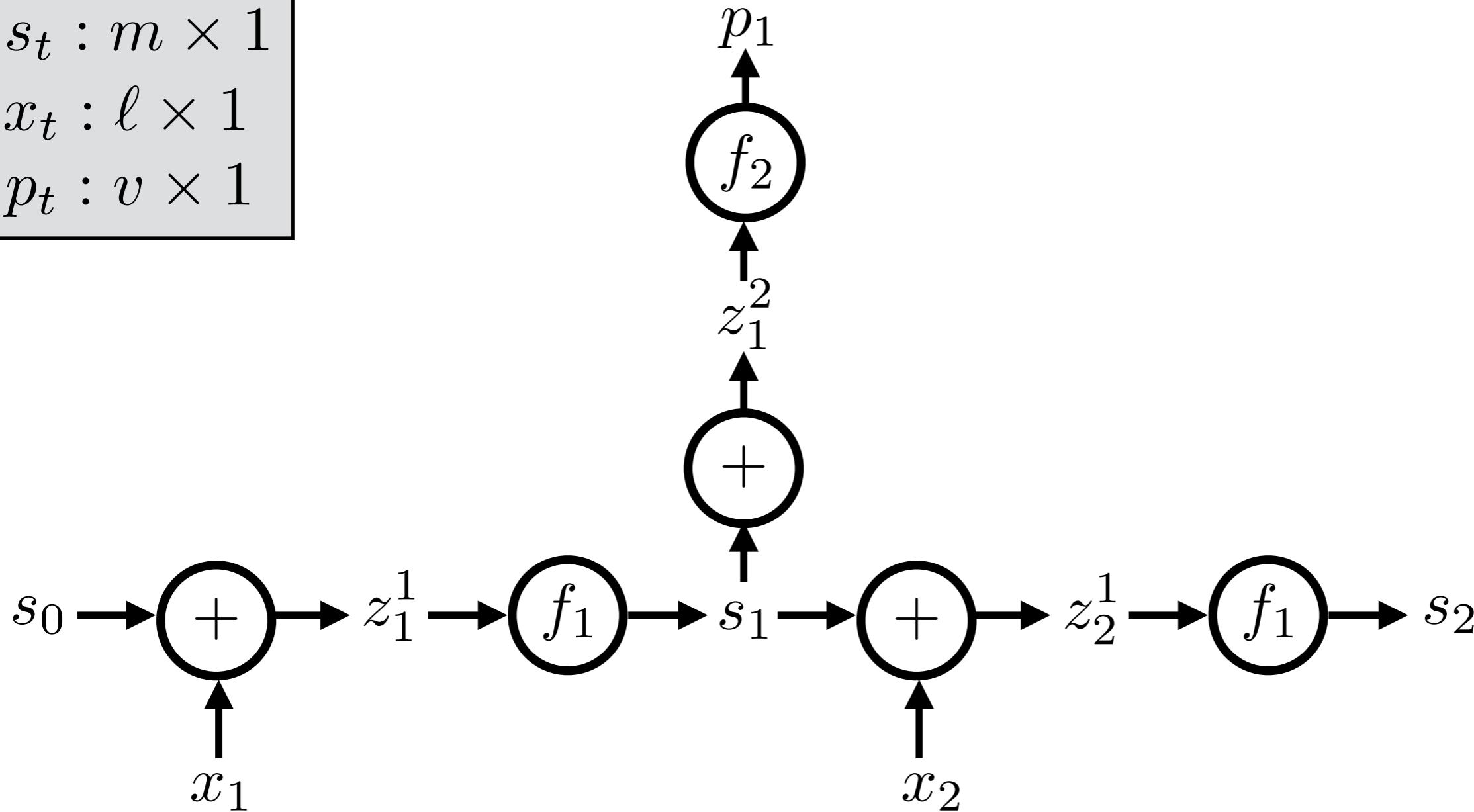
$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{\text{Input and previous state}} + \underbrace{W_0^{ss}}_{\text{Initial state}})$$

$$p_t = f_2 (\underbrace{W^o s_t}_{\text{Hidden state}} + \underbrace{W_0^o}_{\text{Initial output}}) \rightarrow z_t^1 \rightarrow z_t^2$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

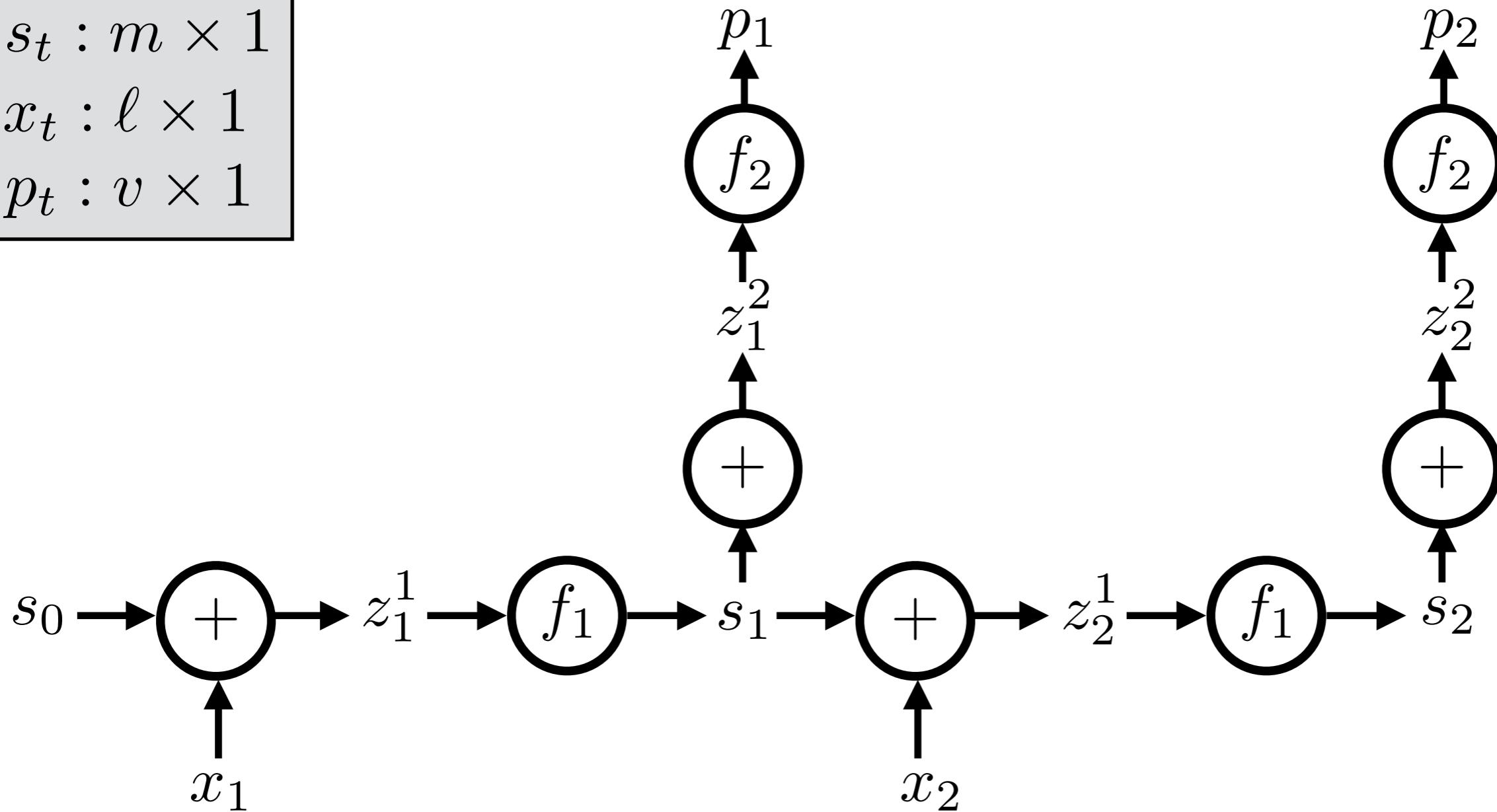
$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{W_0^{ss}} + \underbrace{W_0^{ss}}_{W_0})$$

$$p_t = f_2 (\underbrace{W^o s_t}_{W_0^o} + \underbrace{W_0^o}_{W_0}) \rightarrow \begin{matrix} z_t^1 \\ z_t^2 \end{matrix}$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

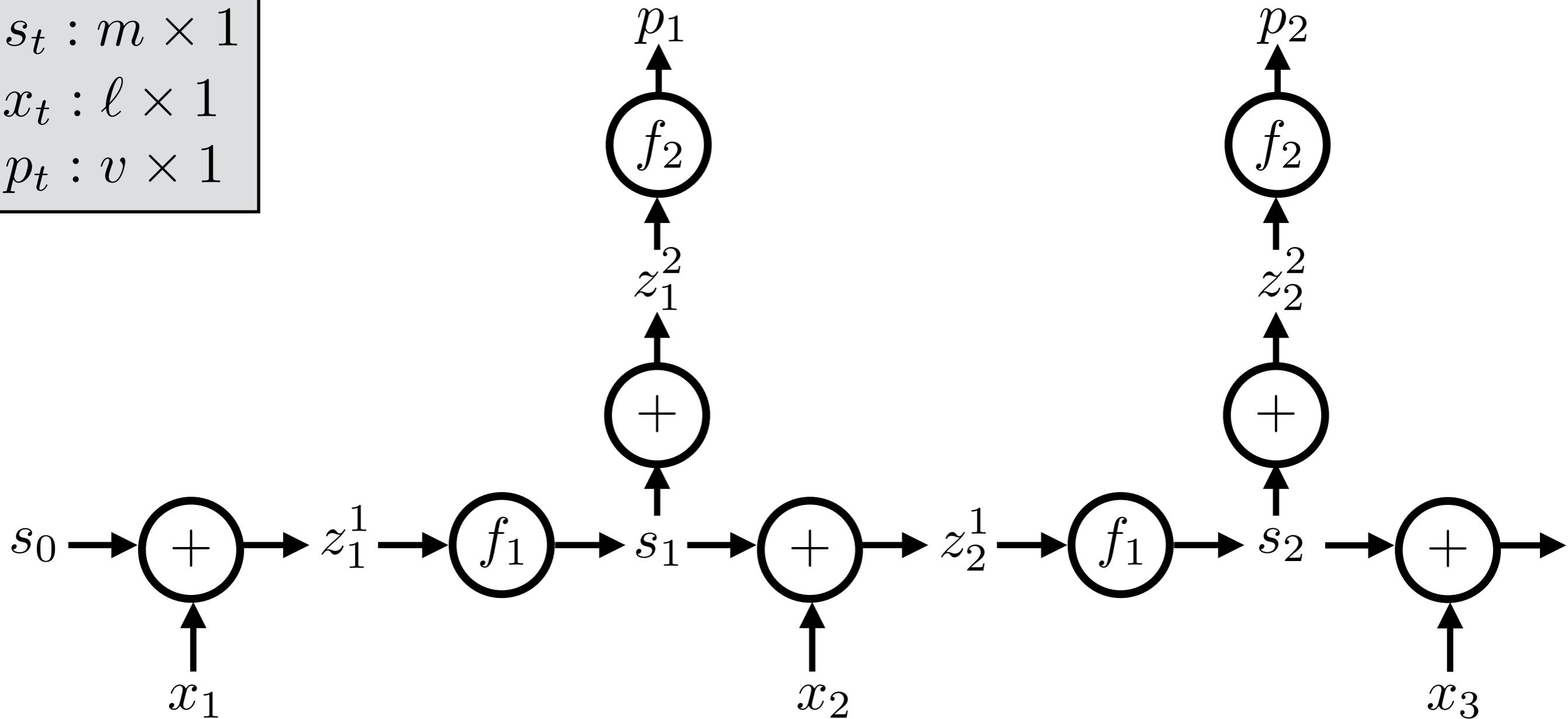
$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{\text{Input and Previous State}} + \underbrace{W_0^{ss}}_{\text{Initial State}})$$

$$p_t = f_2 (\underbrace{W^o s_t}_{\text{Current State}} + \underbrace{W_0^o}_{\text{Initial Output}}) \rightarrow \begin{cases} z_t^1 \\ z_t^2 \end{cases}$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

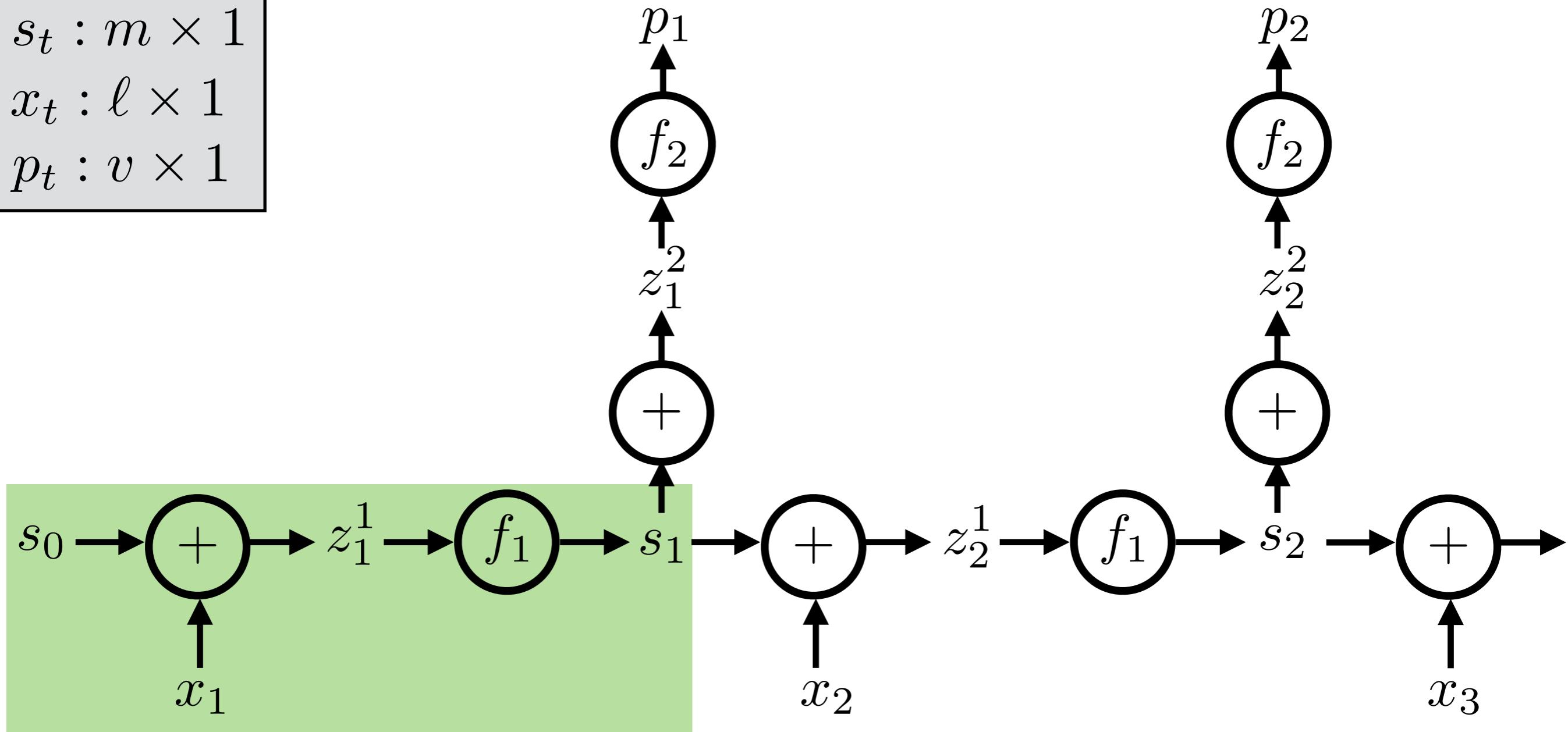
$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{\text{Input and previous state}} + \underbrace{W_0^{ss}}_{\text{Initial state}})$$

$$p_t = f_2 (\underbrace{W^o s_t}_{\text{Output of hidden state}} + \underbrace{W_0^o}_{\text{Initial output}})$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

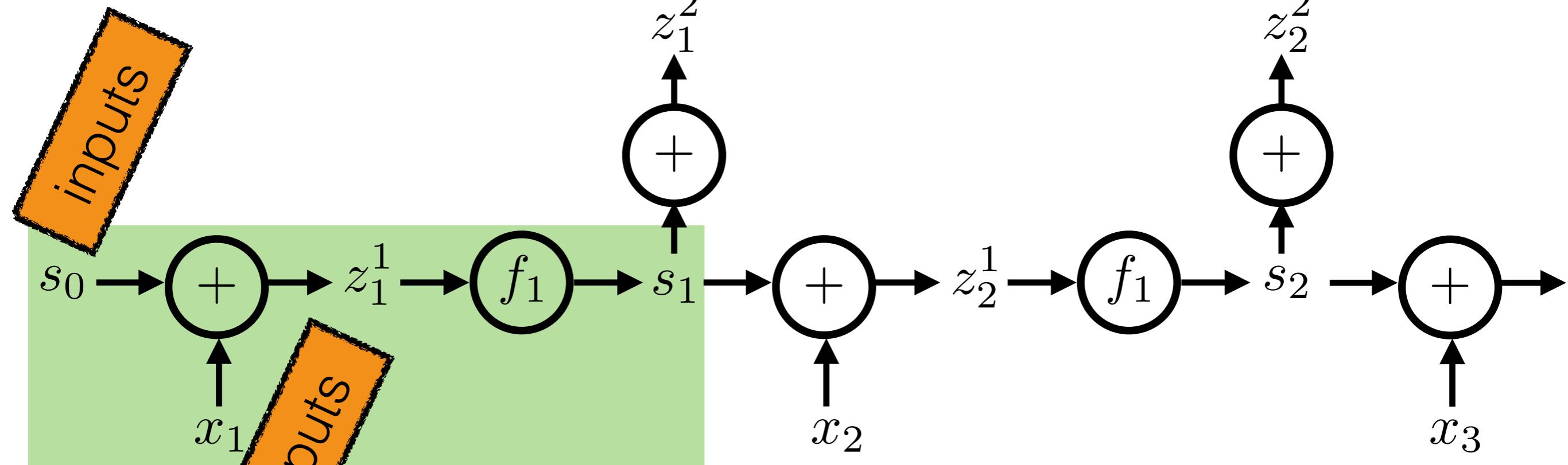
$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{W_0} + \underbrace{W_0^{ss}}_{z_t^1})$$

$$p_t = f_2 (\underbrace{W^o s_t}_{W_0^o} + \underbrace{W_0^o}_{z_t^2})$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

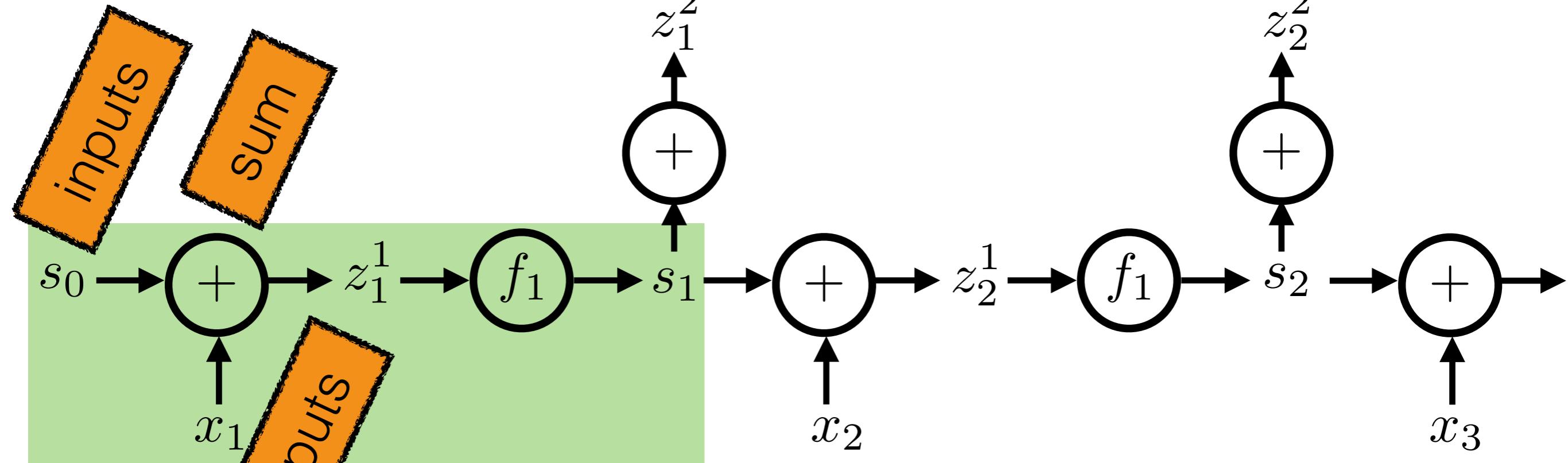
$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{\text{Input and previous state}} + \underbrace{W_0^{ss}}_{\text{Initial state}})$$

$$p_t = f_2 (\underbrace{W^o s_t}_{\text{Transformation of hidden state}} + \underbrace{W_0^o}_{\text{Initial output}})$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = cl$)

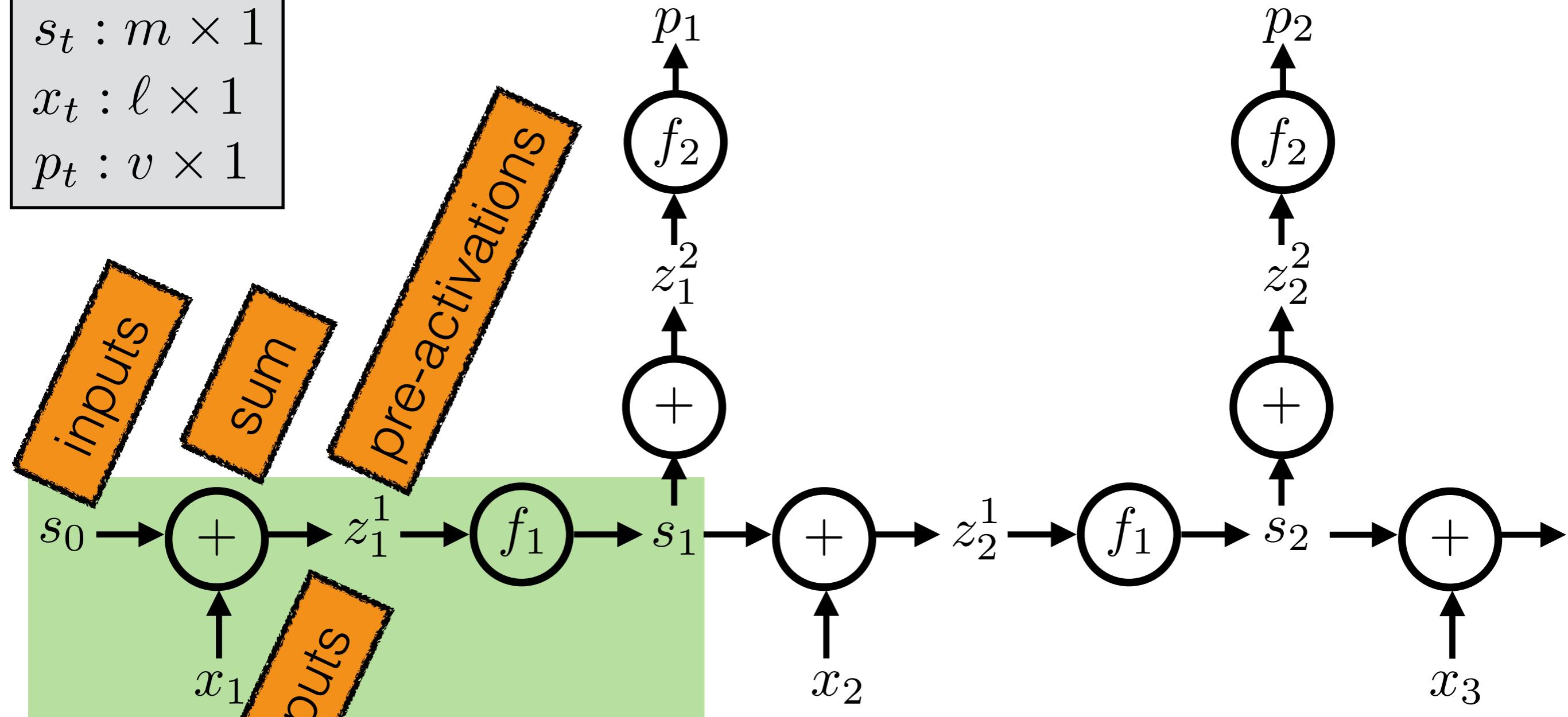
$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{\text{Input and previous state}} + \underbrace{W_0^{ss}}_{\text{Initial state}})$$

$$p_t = f_2 (\underbrace{W^o s_t}_{\text{Output of hidden state}} + \underbrace{W_0^o}_{\text{Initial output}})$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

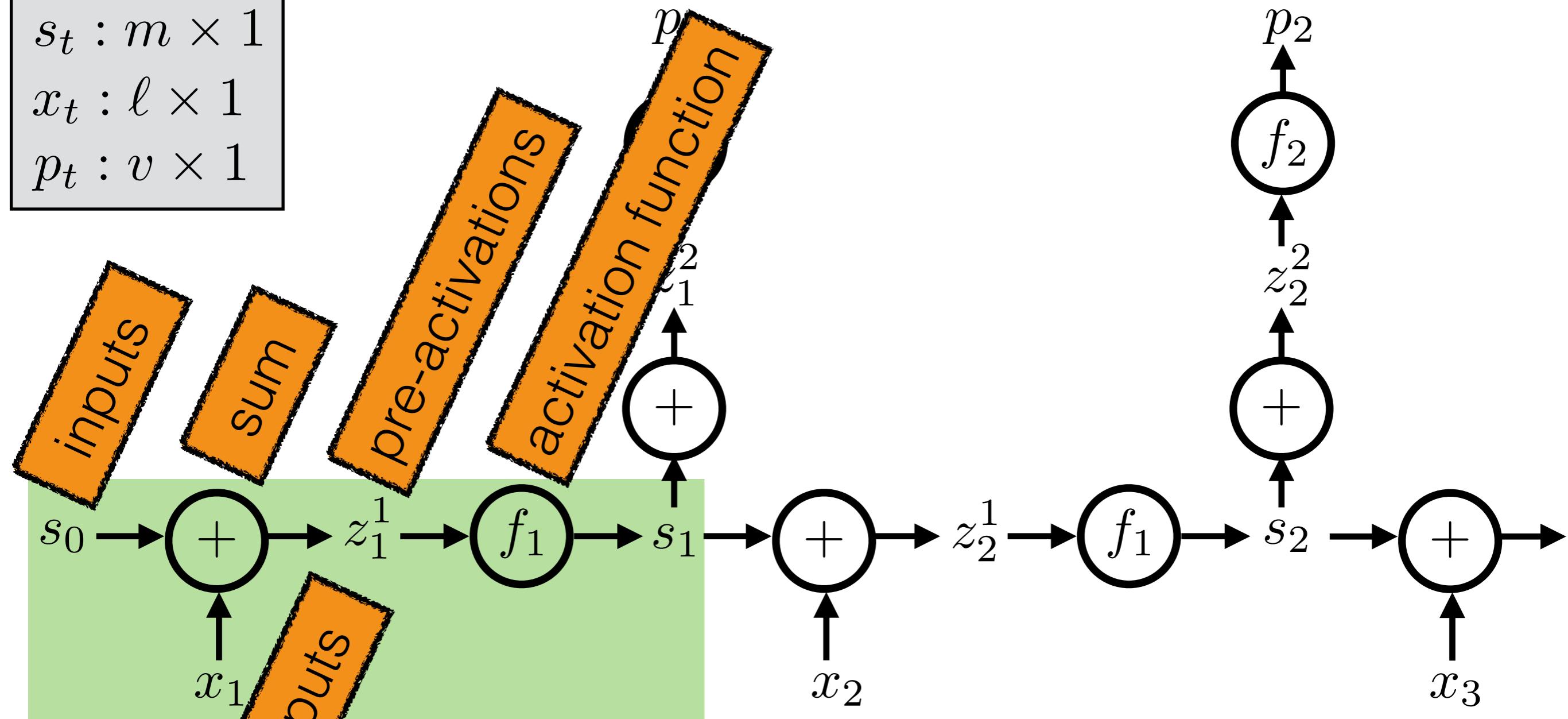
$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{\text{pre-activations}} + \underbrace{W_0^{ss}}_{\text{bias}})$$

$$p_t = f_2 (\underbrace{W^o s_t}_{\text{pre-activations}} + \underbrace{W_0^o}_{\text{bias}})$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = cl$)

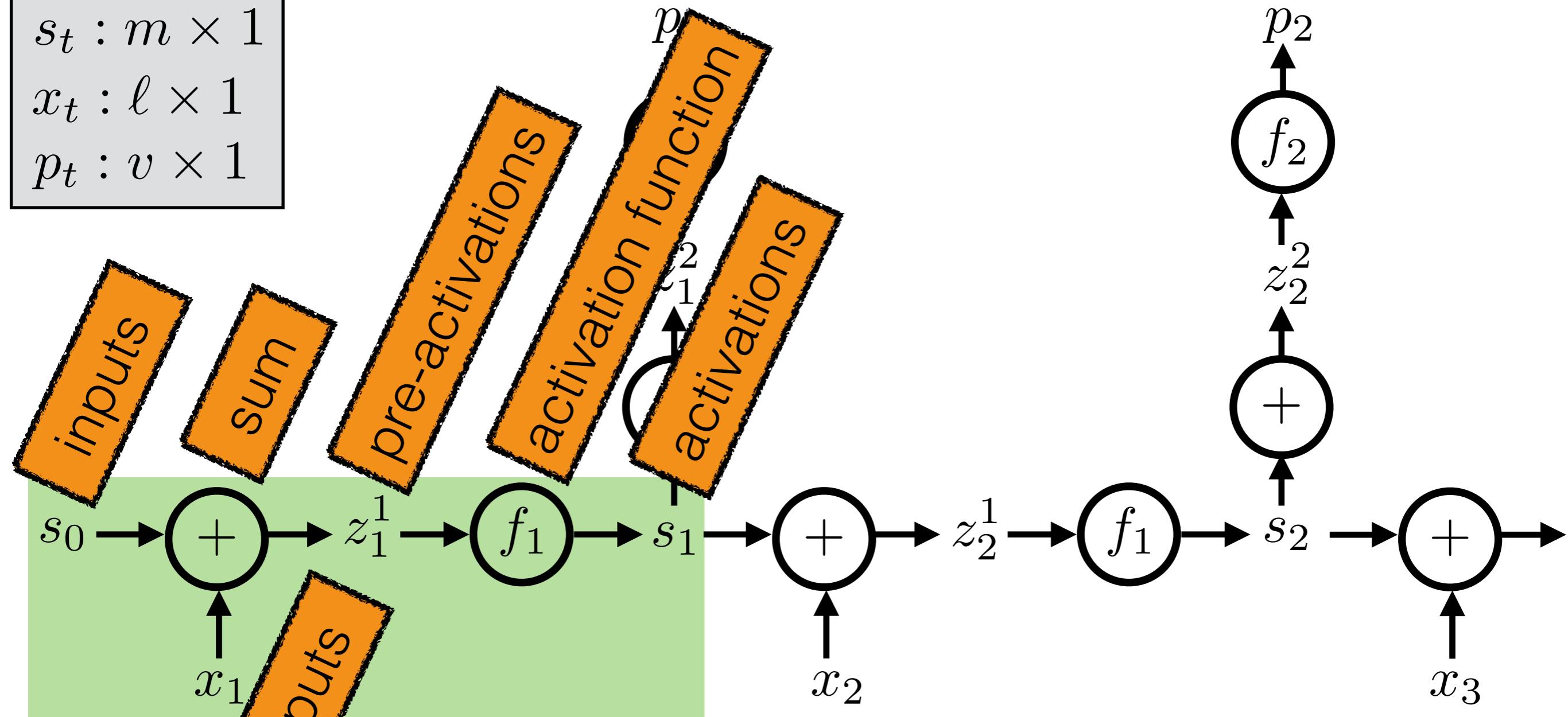
$$s_t = f_1 \underbrace{(W^{sx}x_t + W^{ss}s_{t-1} + W_0^{ss})}_{z_t^1}$$

$$p_t = f_2 \underbrace{(W^o s_t + W_0^o)}_{z_t^2}$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = cl$)

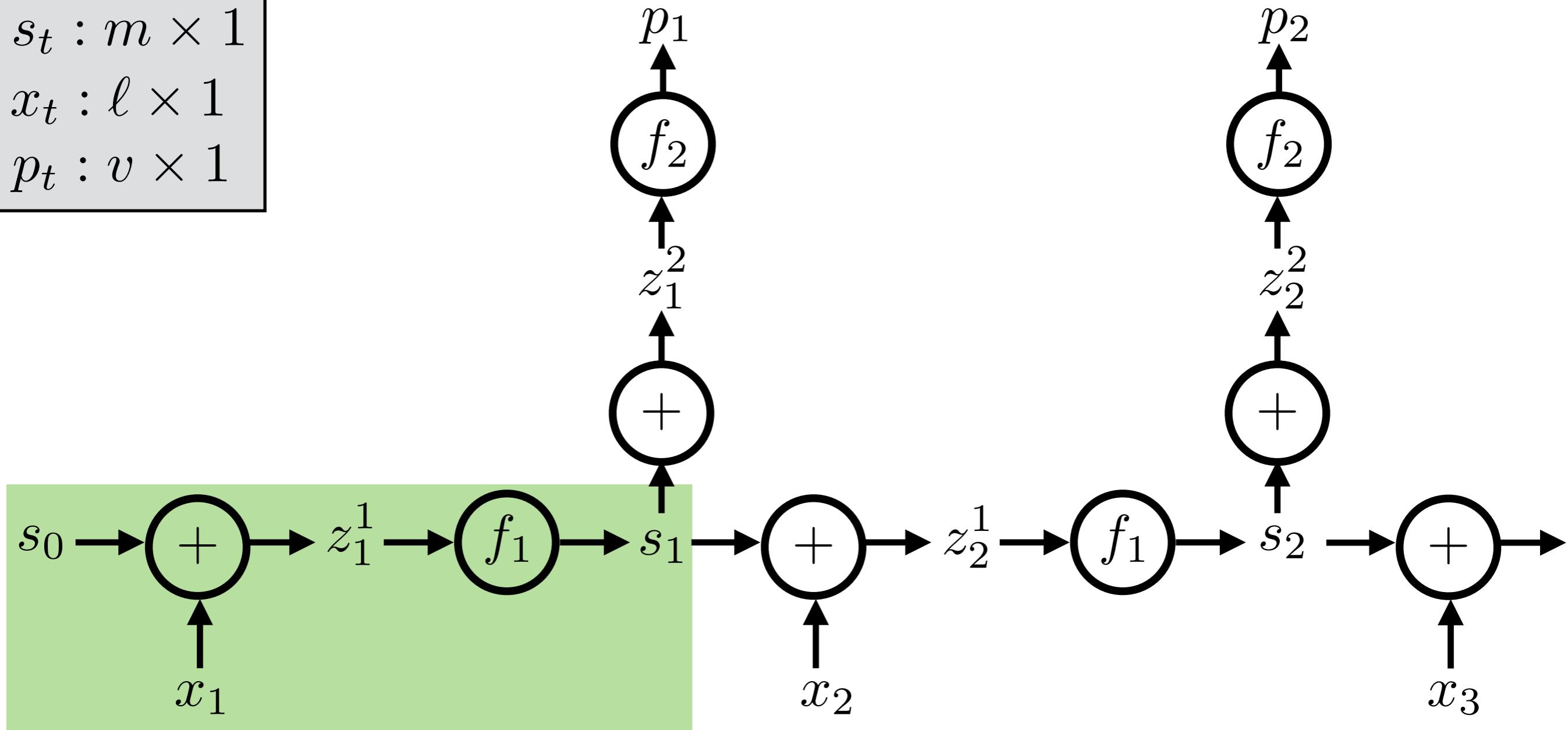
$$s_t = f_1 \left(\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{z_t^1} + W_0^{ss} \right)$$

$$p_t = f_2 \left(\underbrace{W^o s_t}_{z_t^2} + W_0^o \right)$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

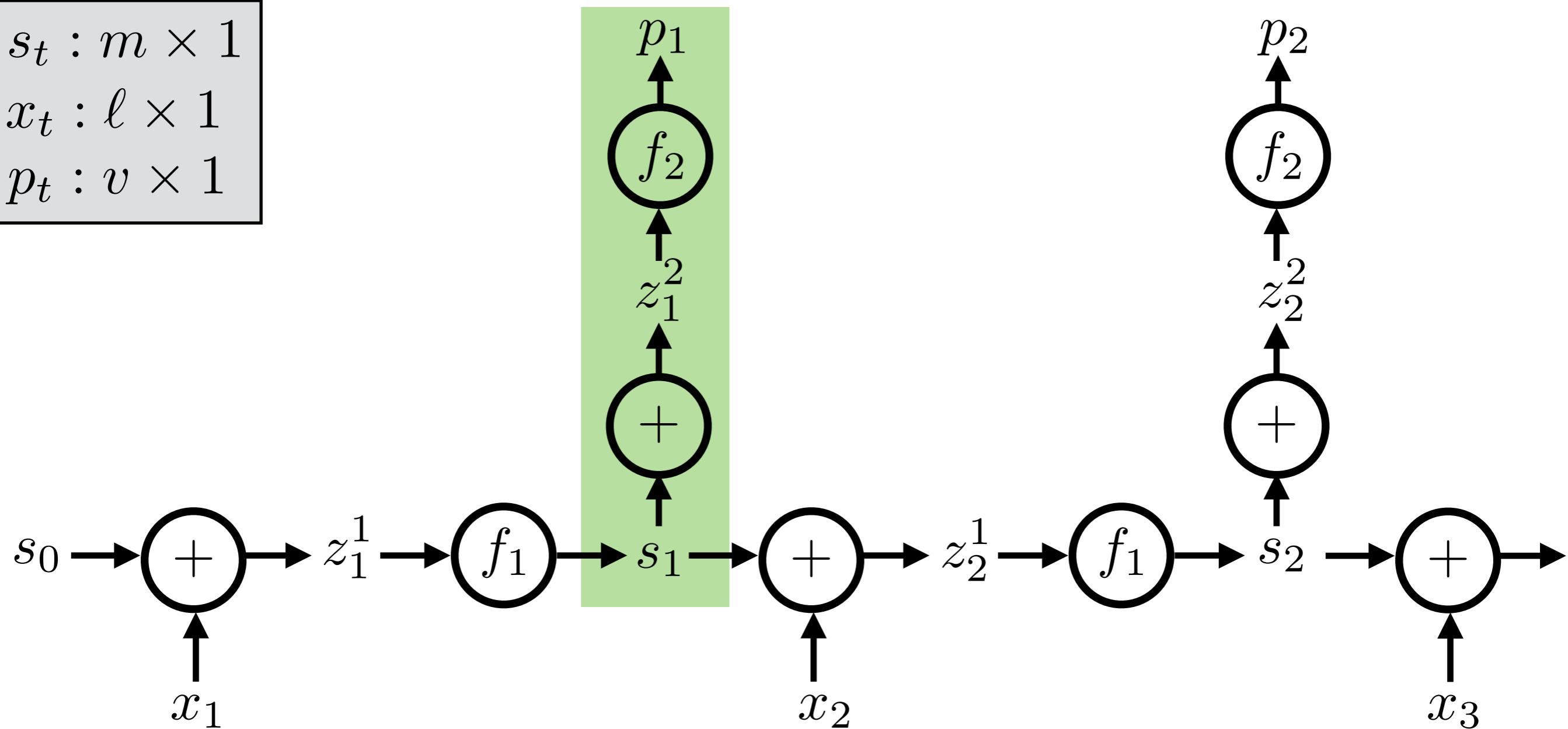
$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{W_0} + \underbrace{W_0}_{ss})$$

$$p_t = f_2 (\underbrace{W^o s_t}_{W_0} + \underbrace{W_0^o}_{s_t})$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

Recurrent neural network

$$\begin{aligned}s_t &: m \times 1 \\x_t &: \ell \times 1 \\p_t &: v \times 1\end{aligned}$$



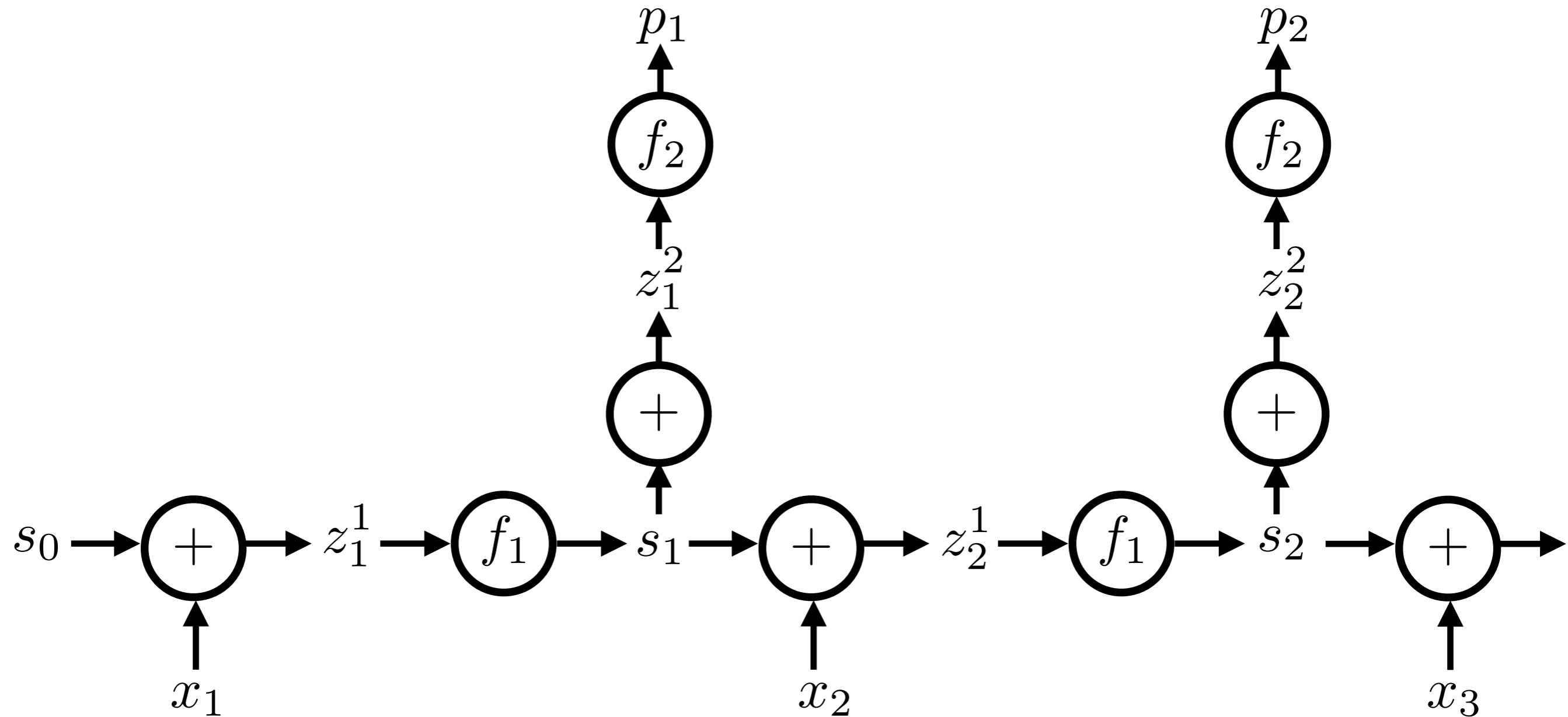
- Example: Alphabet of ℓ chars; state is last c chars ($m = c\ell$)

$$s_t = f_1 (\underbrace{W^{sx} x_t + W^{ss} s_{t-1}}_{\text{Input and previous state}} + \underbrace{W_0^{ss}}_{\text{Initial state}})$$

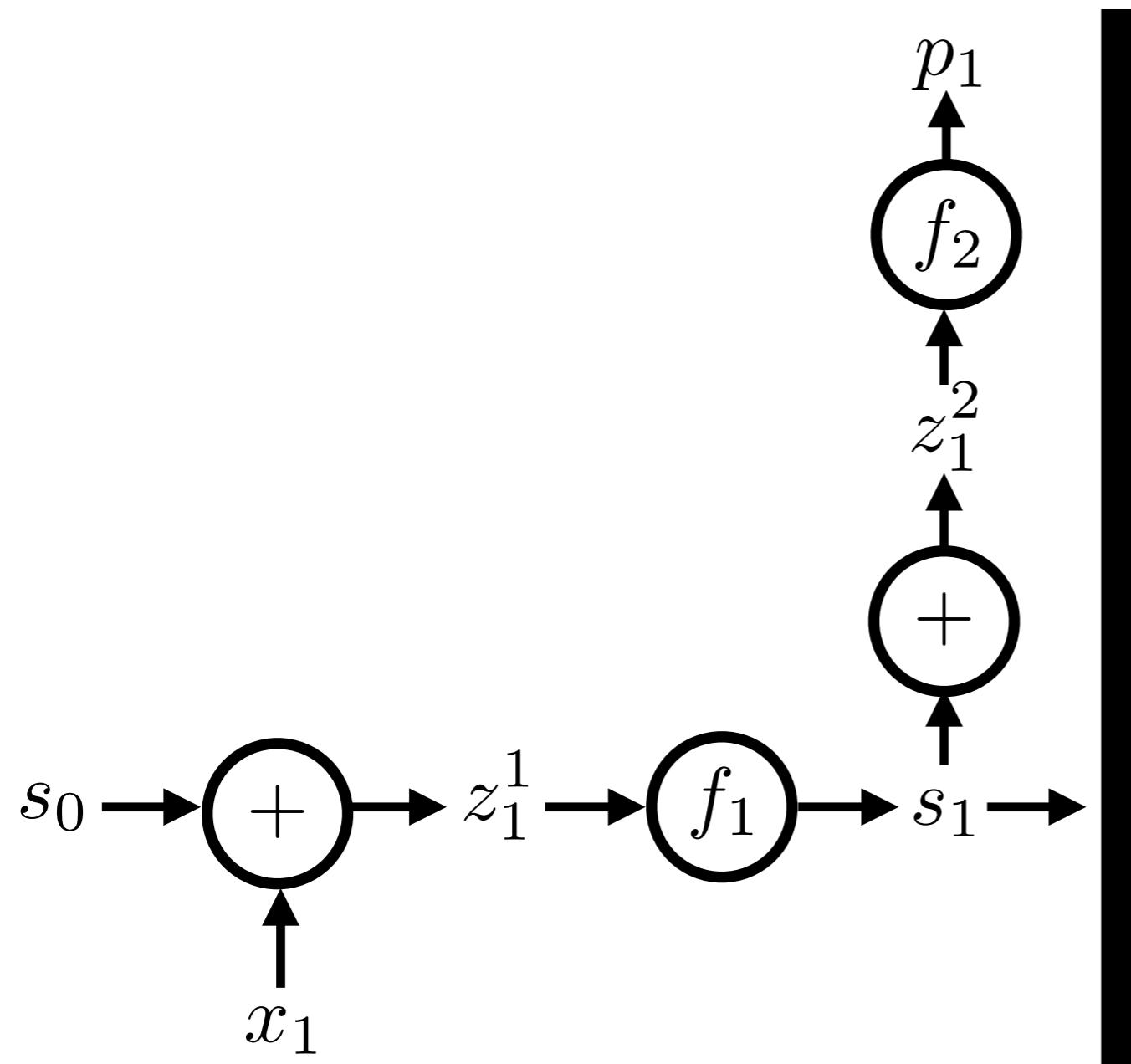
$$p_t = f_2 (\underbrace{W^o s_t}_{\text{Output of hidden state}} + \underbrace{W_0^o}_{\text{Initial output}})$$

$$p^{(i)} = \text{RNN}(x^{(i)}; W, W_0)$$

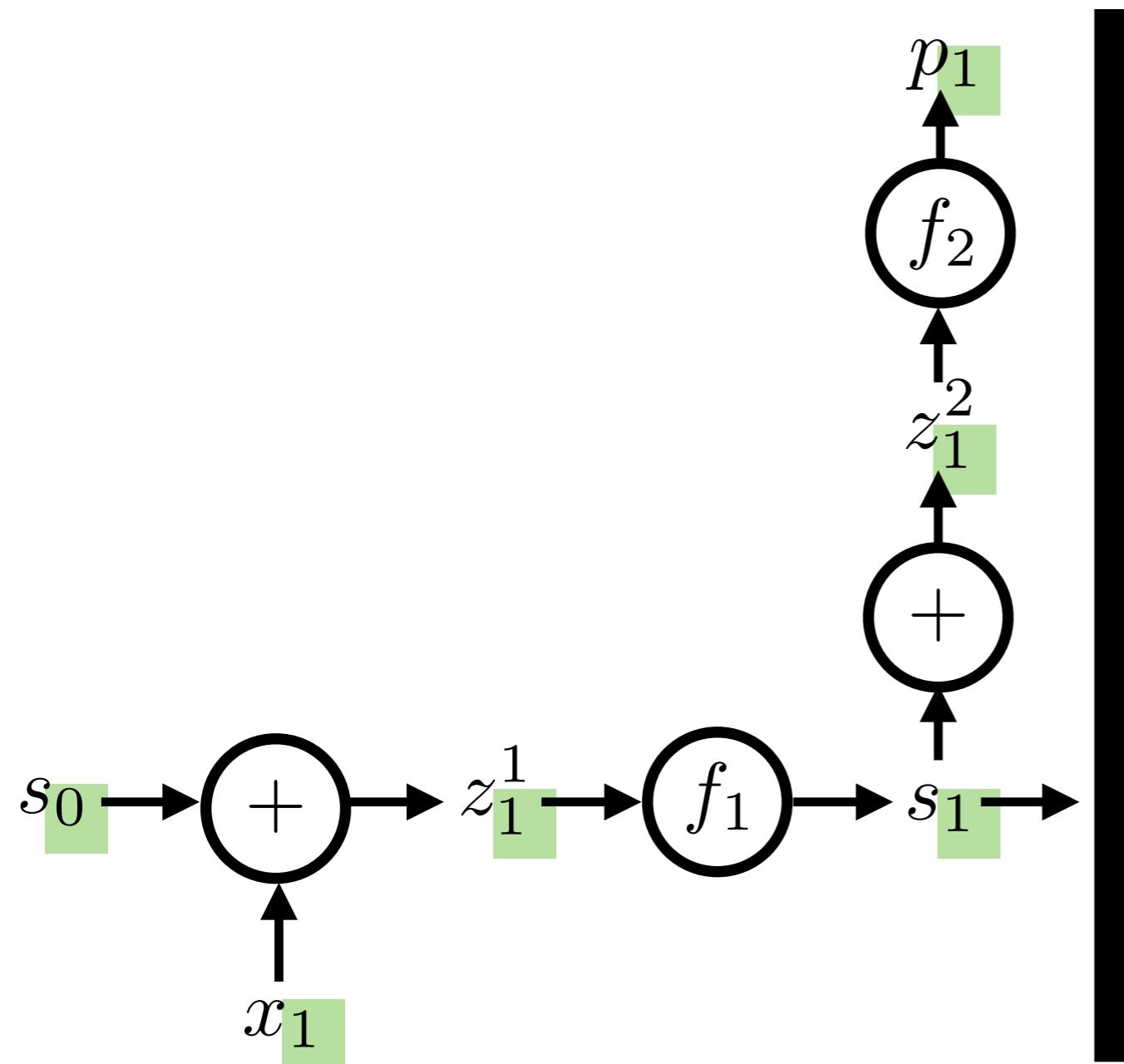
Recurrent neural network



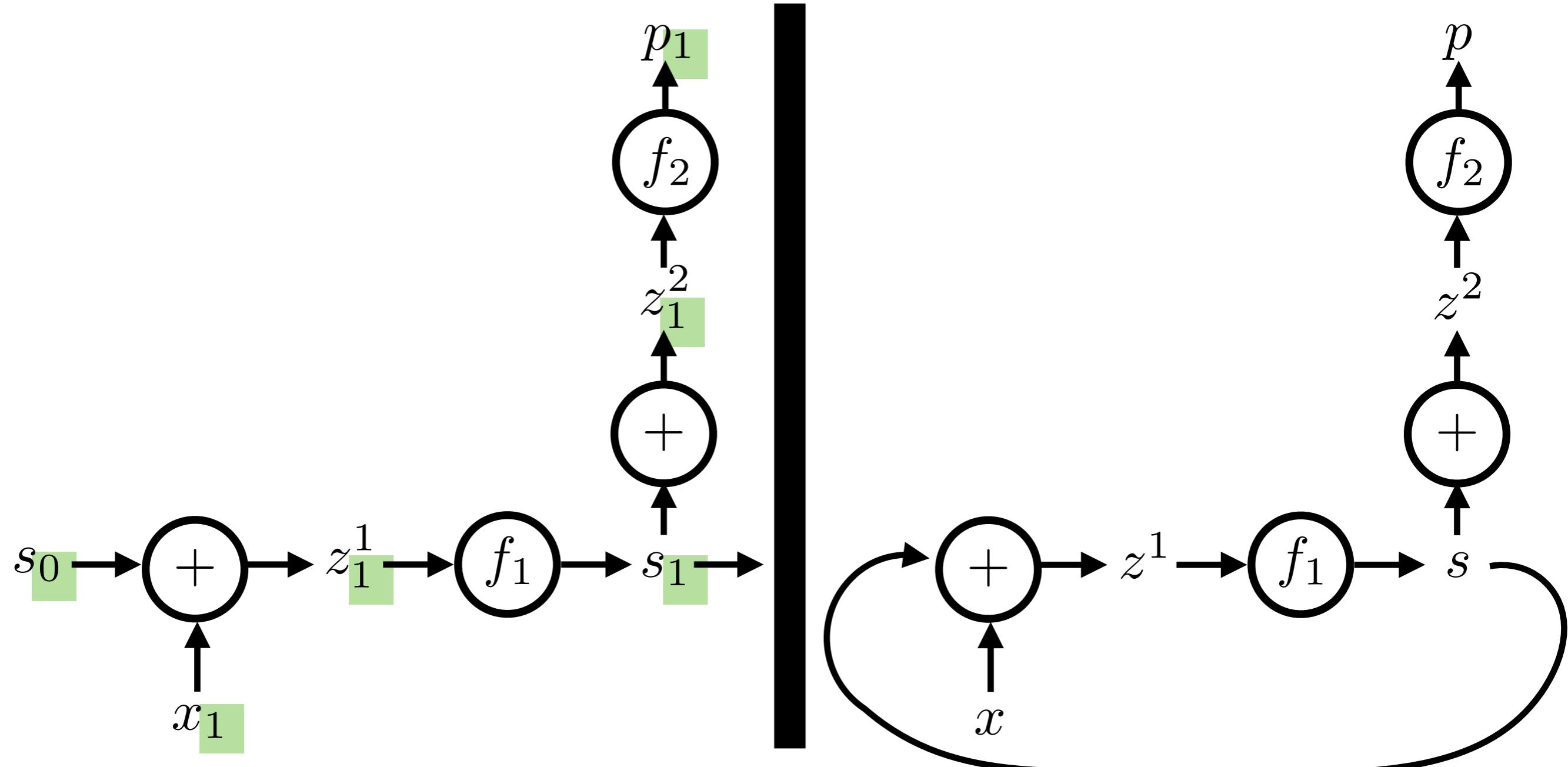
Recurrent neural network



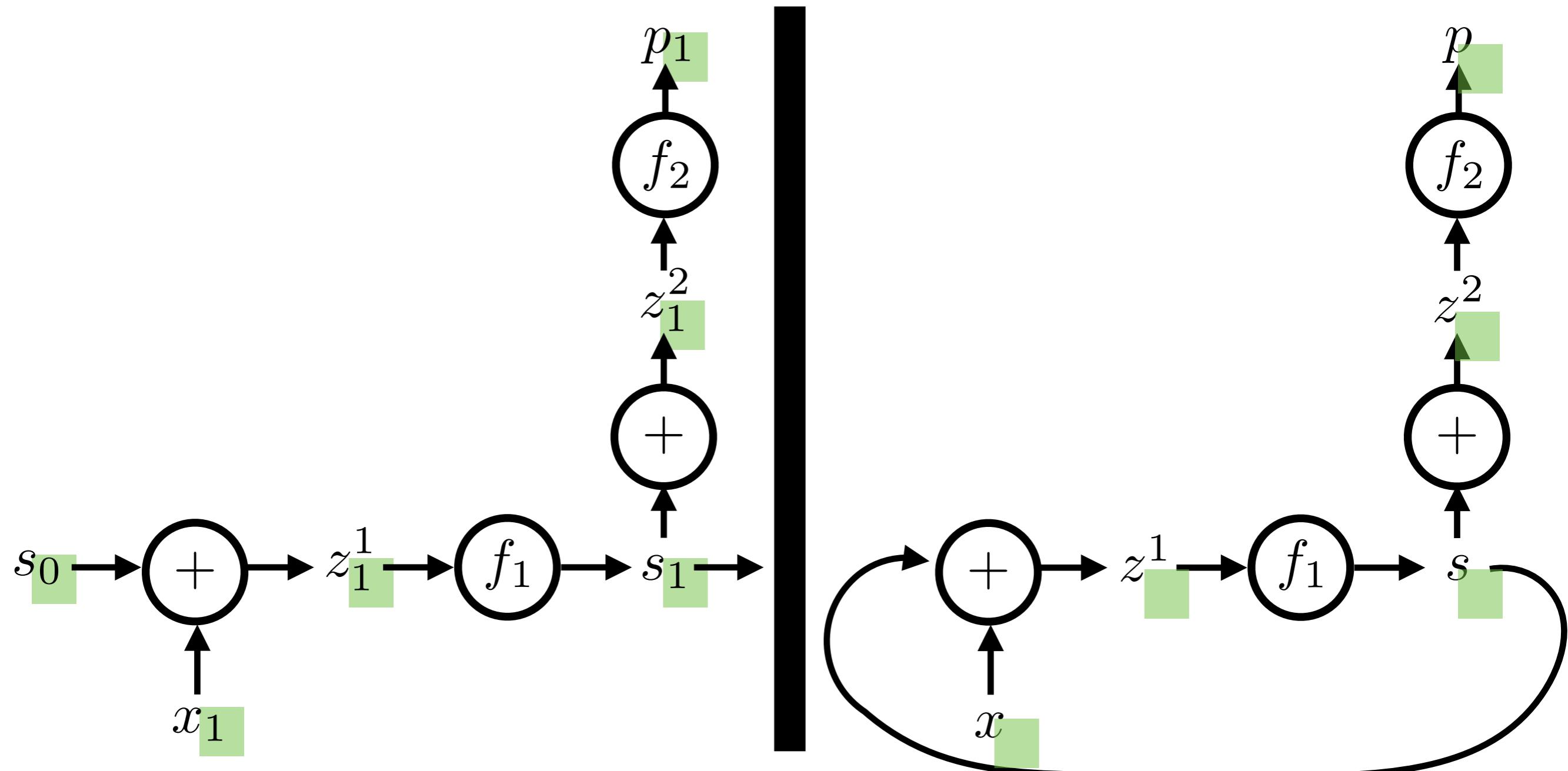
Recurrent neural network



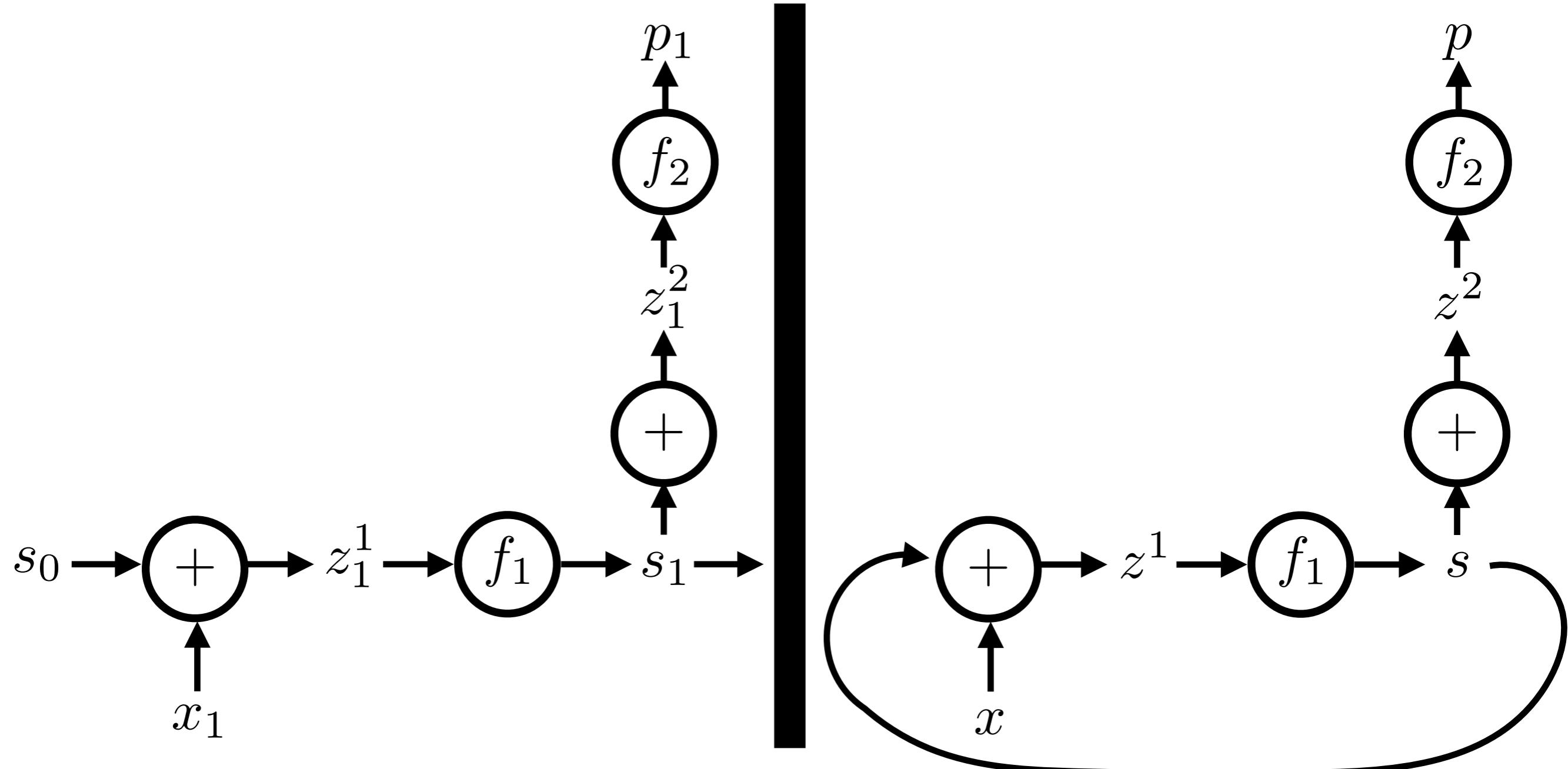
Recurrent neural network



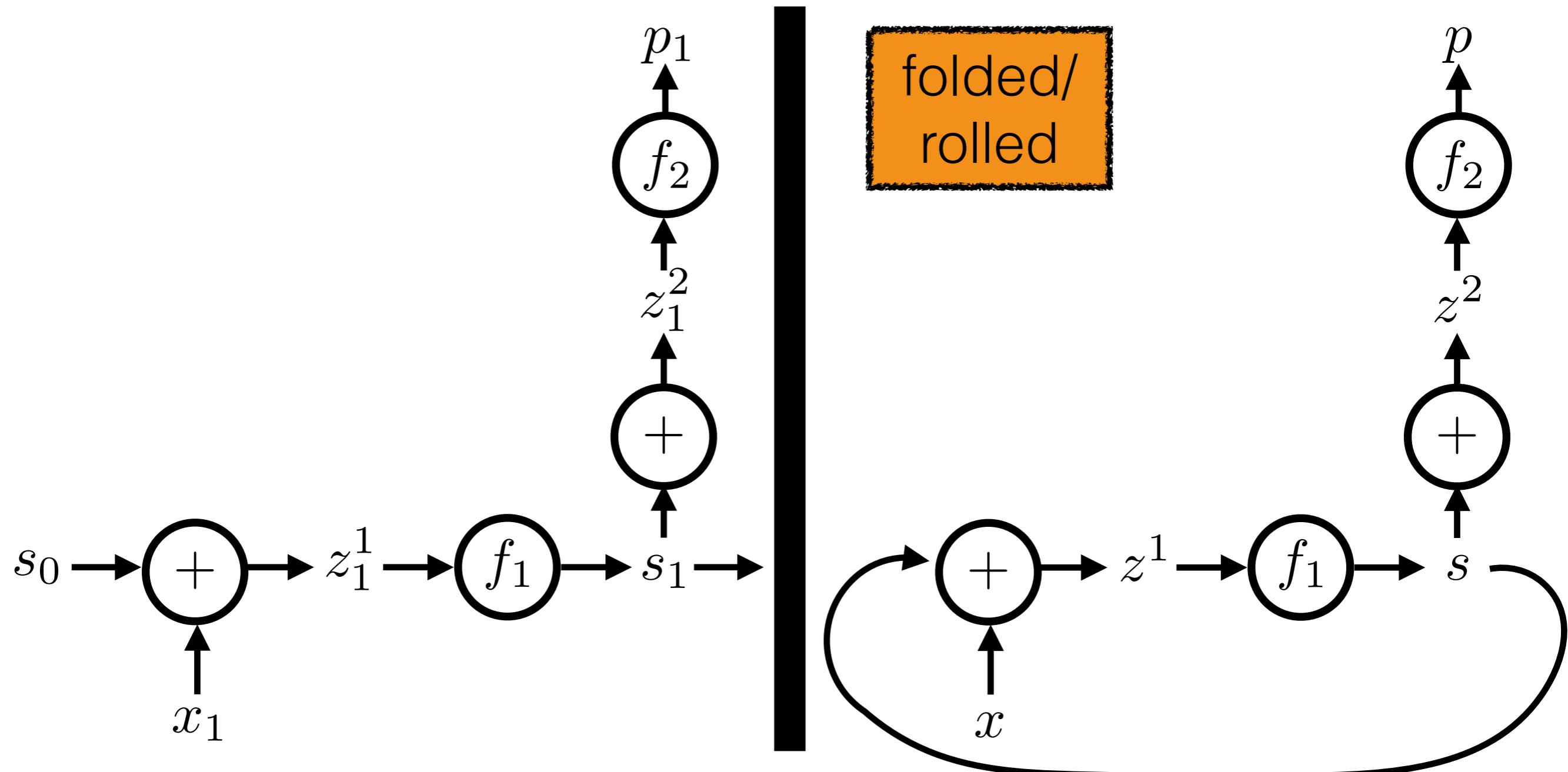
Recurrent neural network



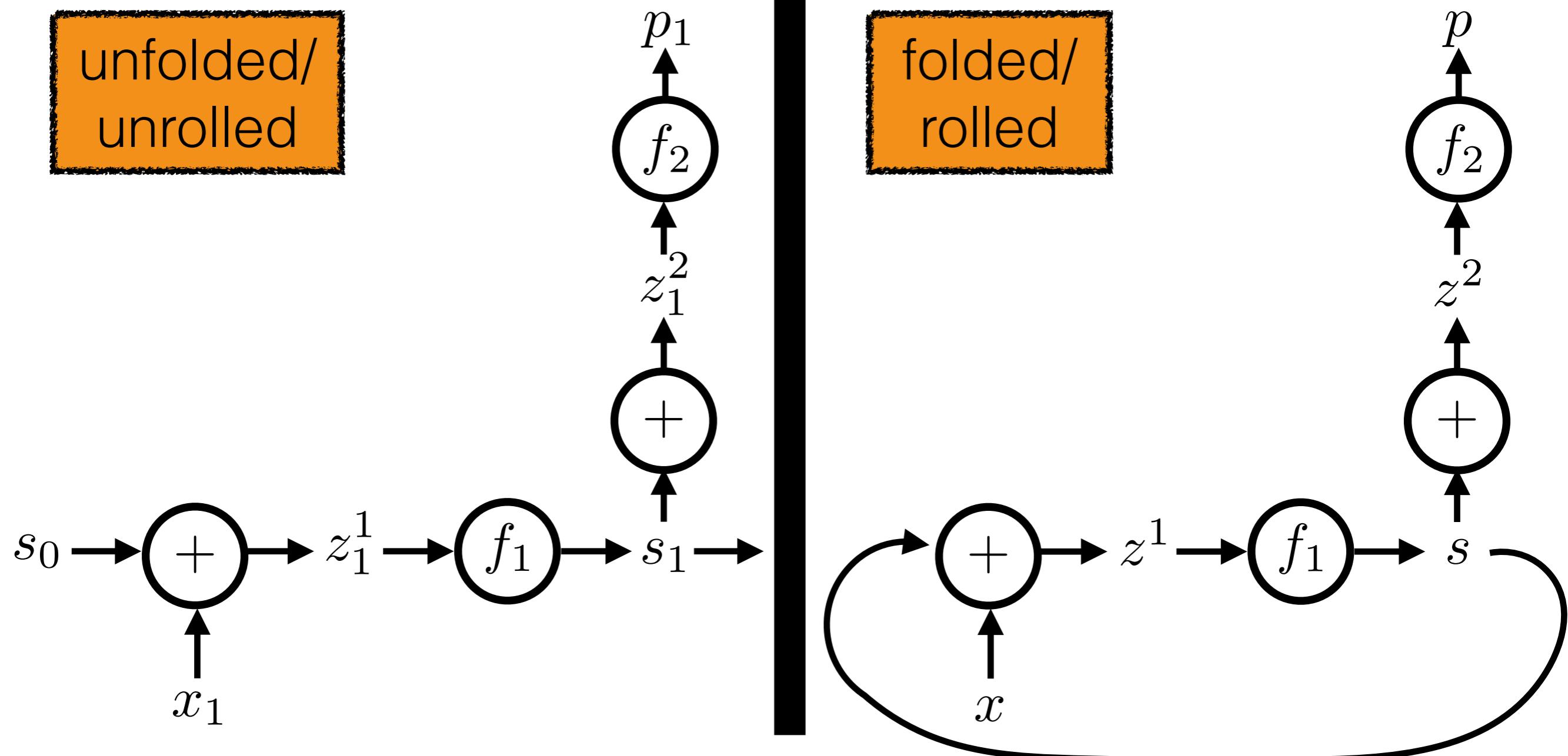
Recurrent neural network



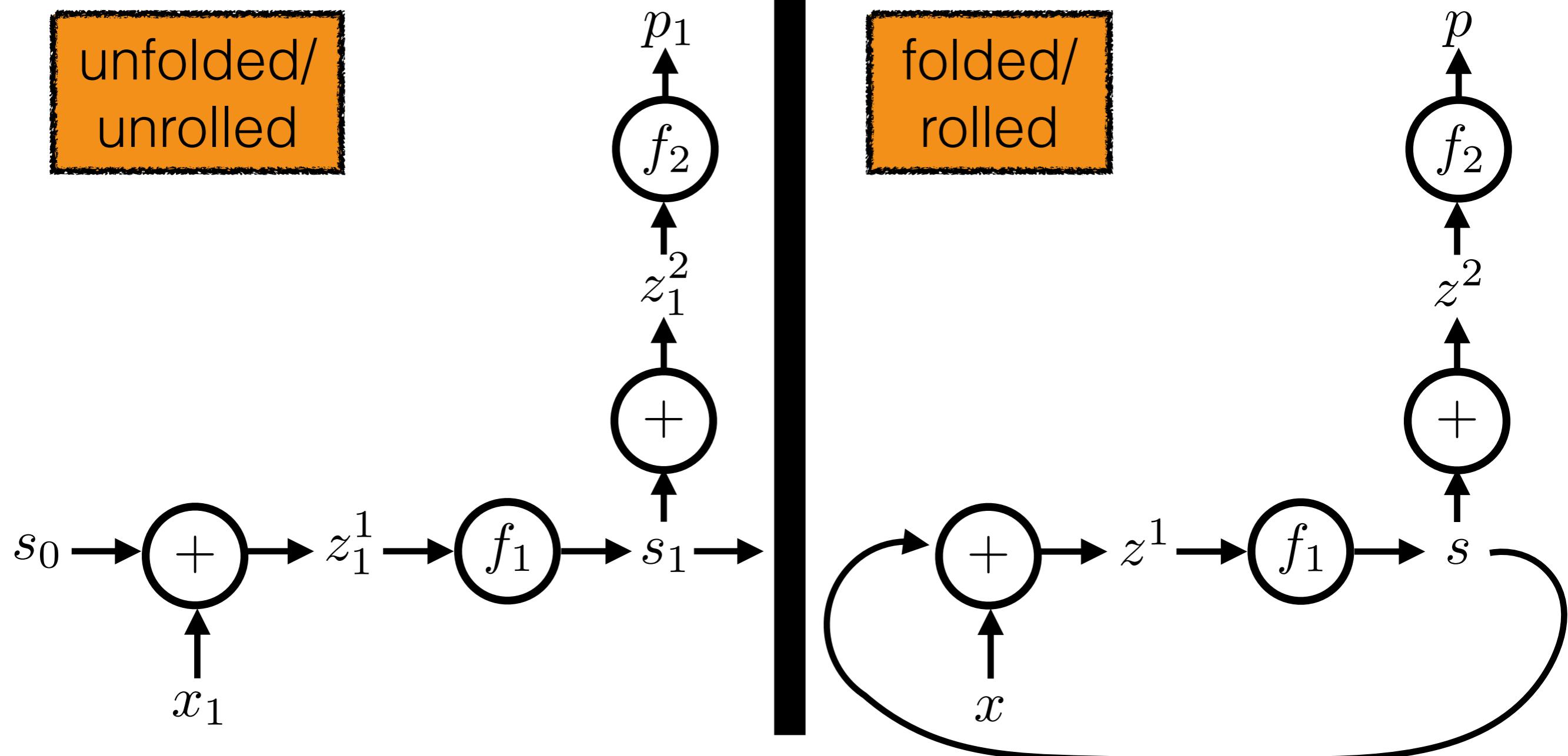
Recurrent neural network



Recurrent neural network

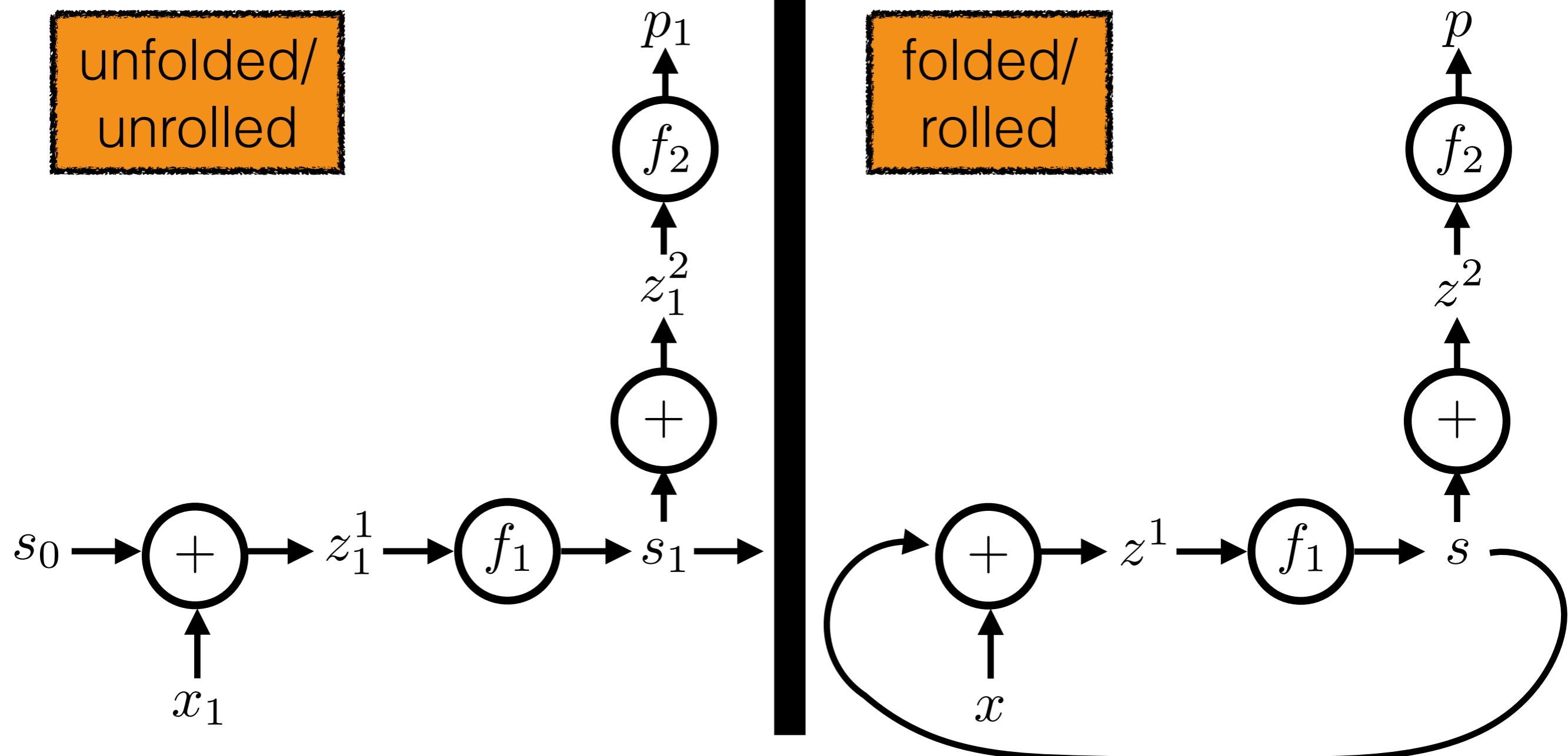


Recurrent neural network



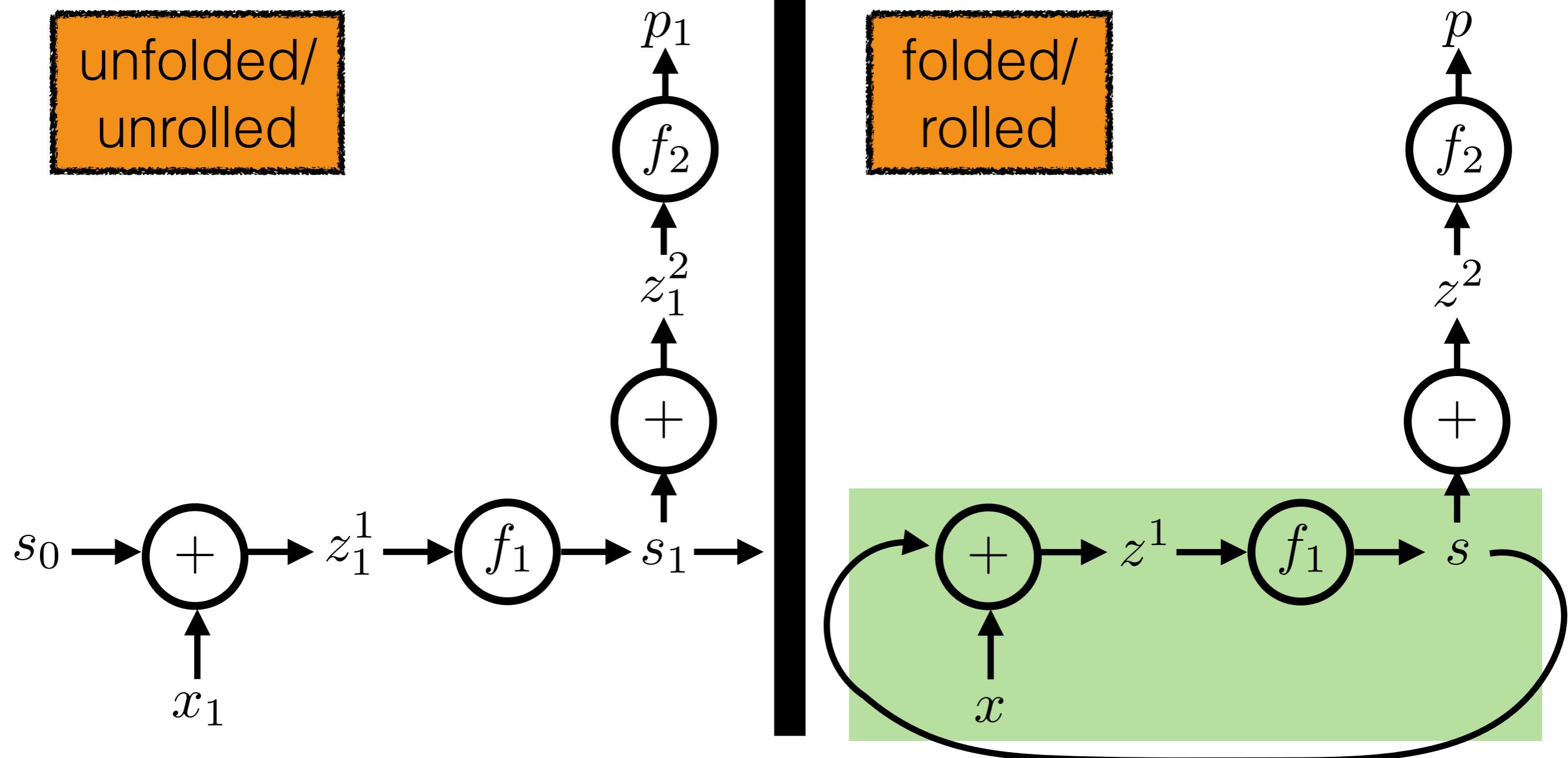
- Compare to:

Recurrent neural network



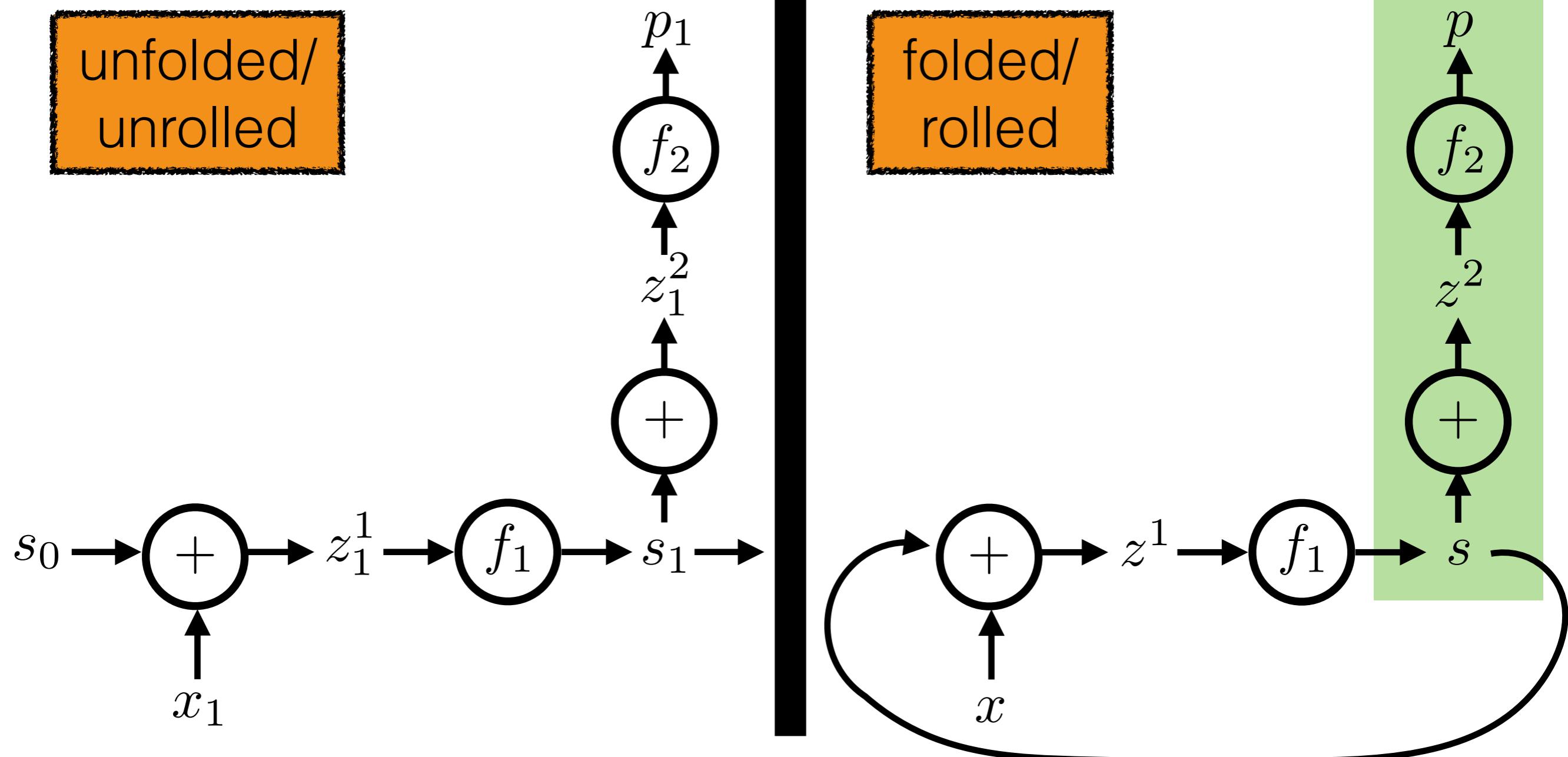
- Compare to:
 - Feedforward neural networks

Recurrent neural network



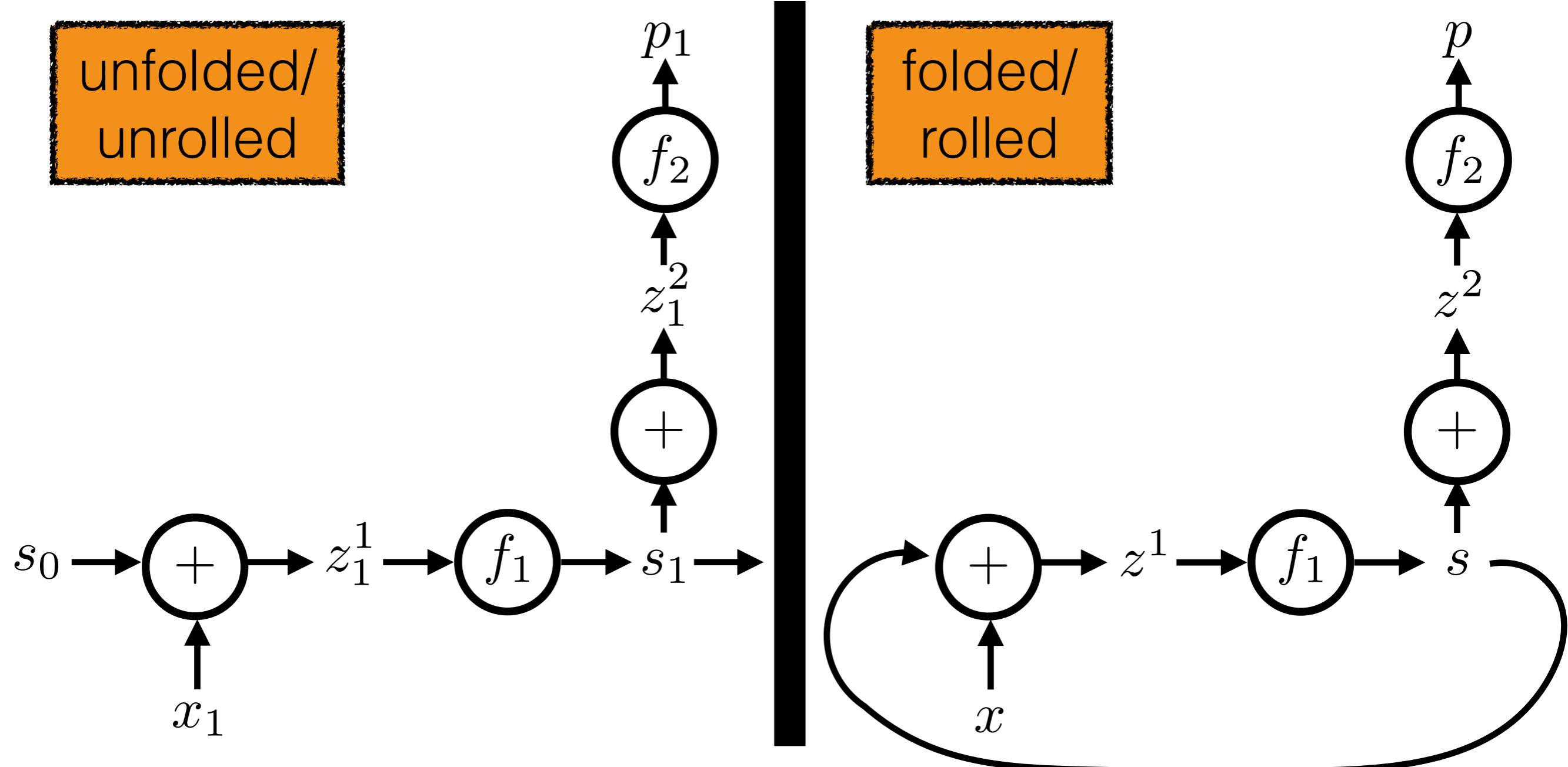
- Compare to:
 - Feedforward neural networks

Recurrent neural network



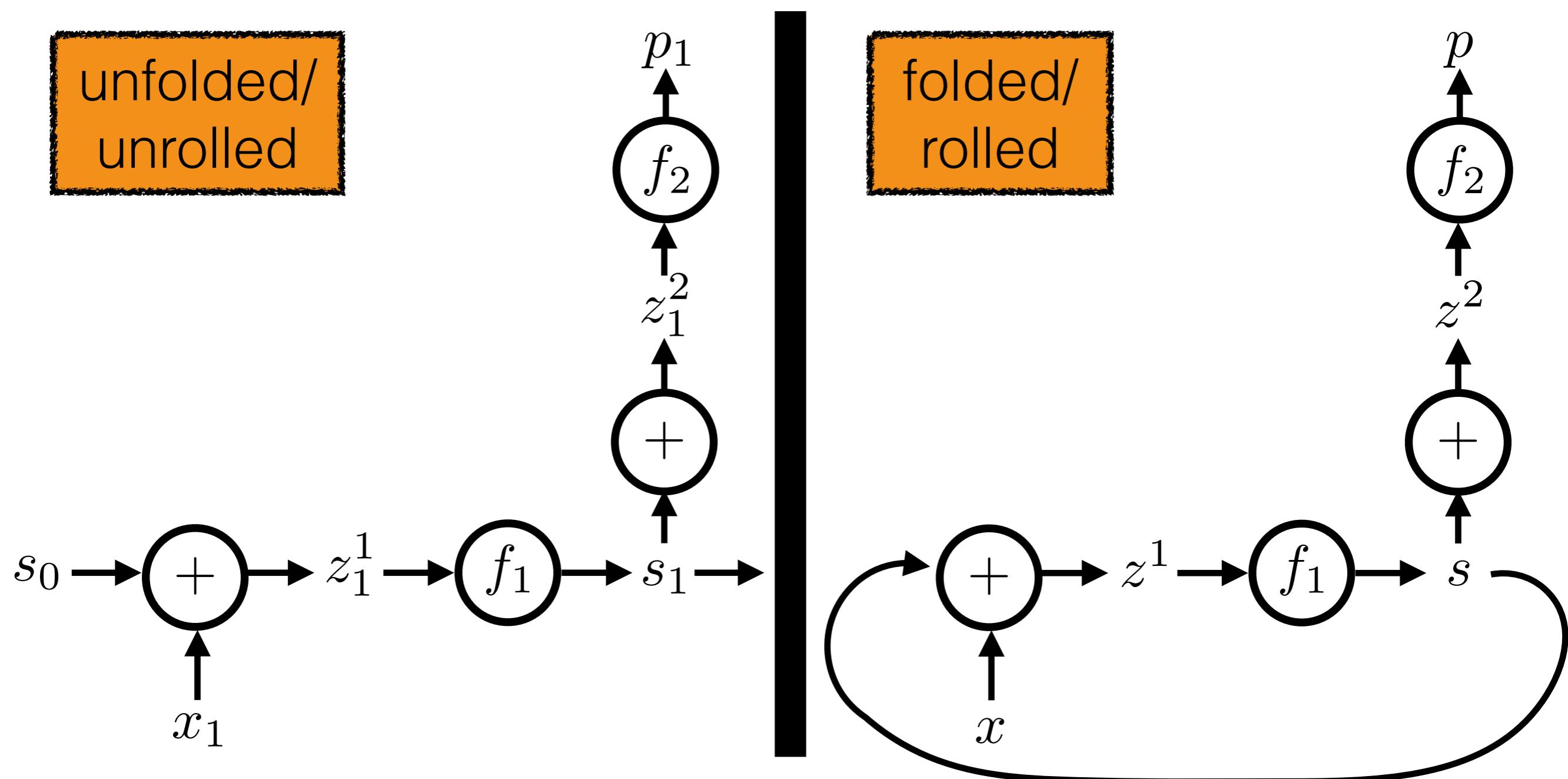
- Compare to:
 - Feedforward neural networks

Recurrent neural network

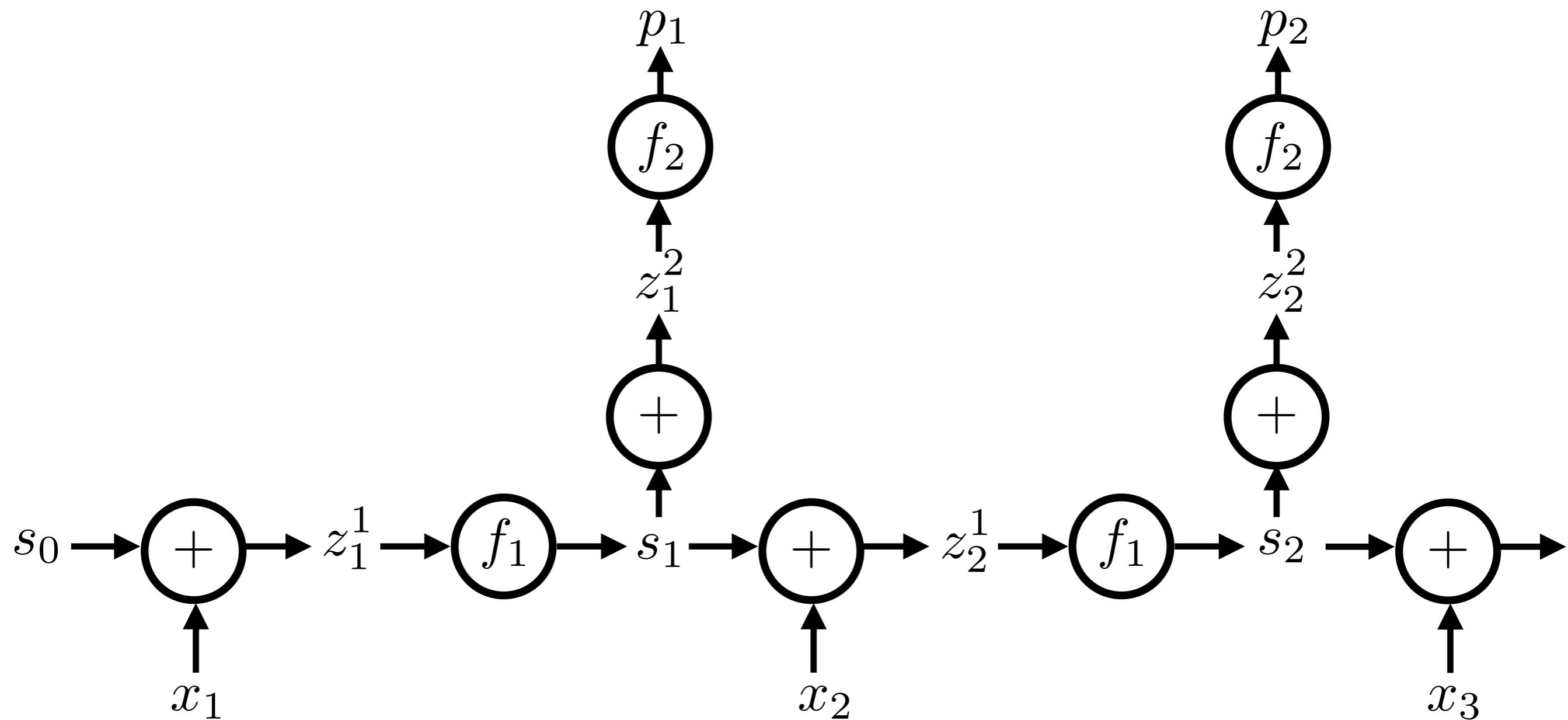


- Compare to:
 - Feedforward neural networks
 - Convolutional neural networks

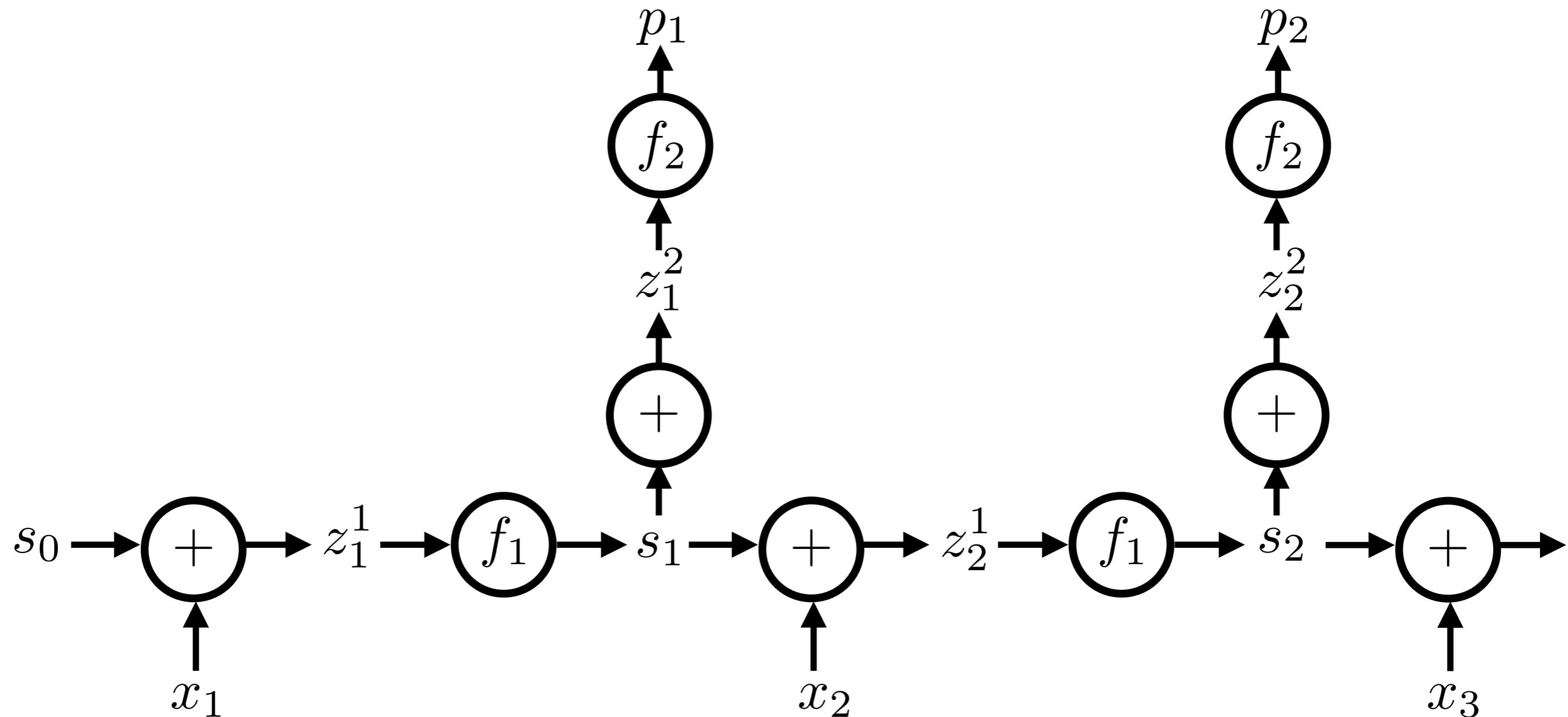
Recurrent neural network



- Compare to:
 - Feedforward neural networks
 - Convolutional neural networks
 - Reinforcement learning

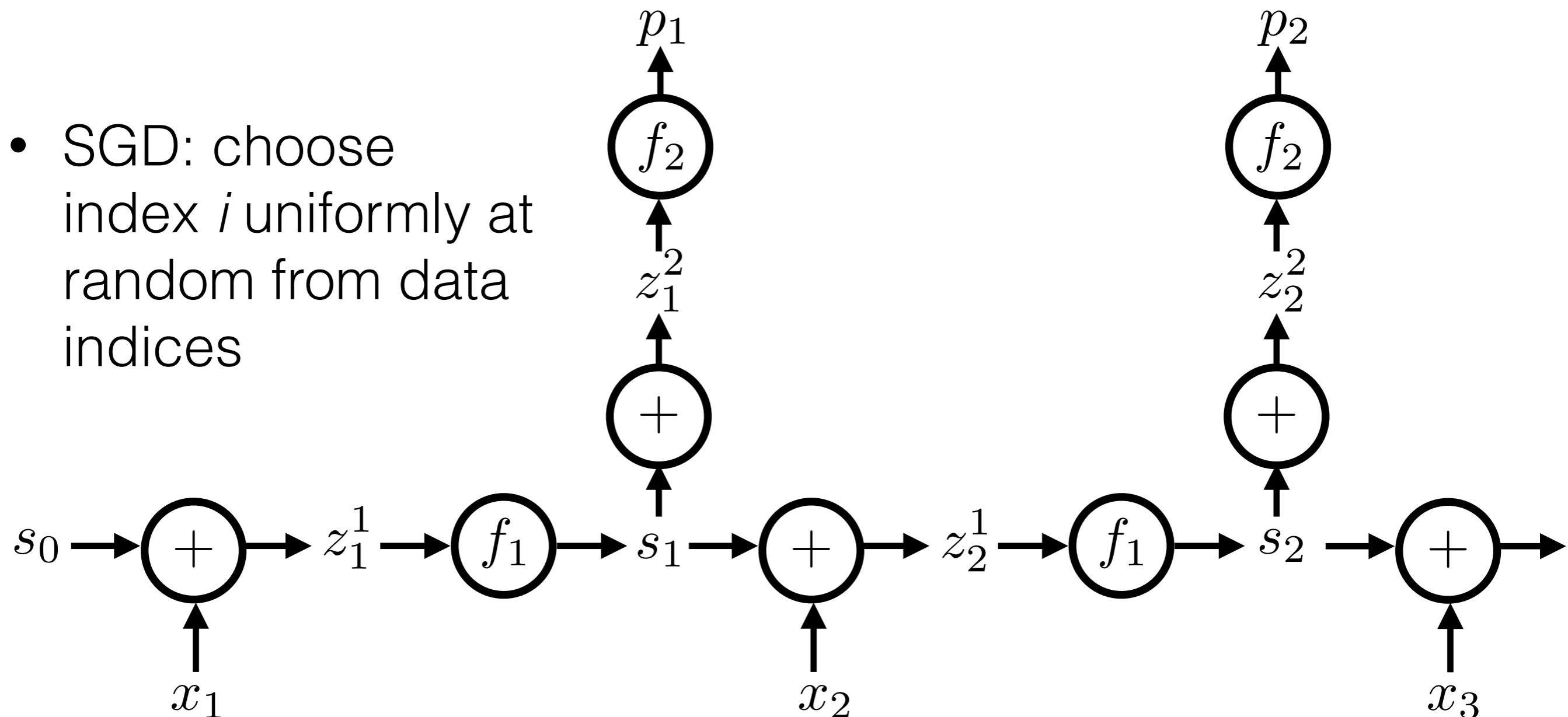


RNNs: a taste of backpropagation



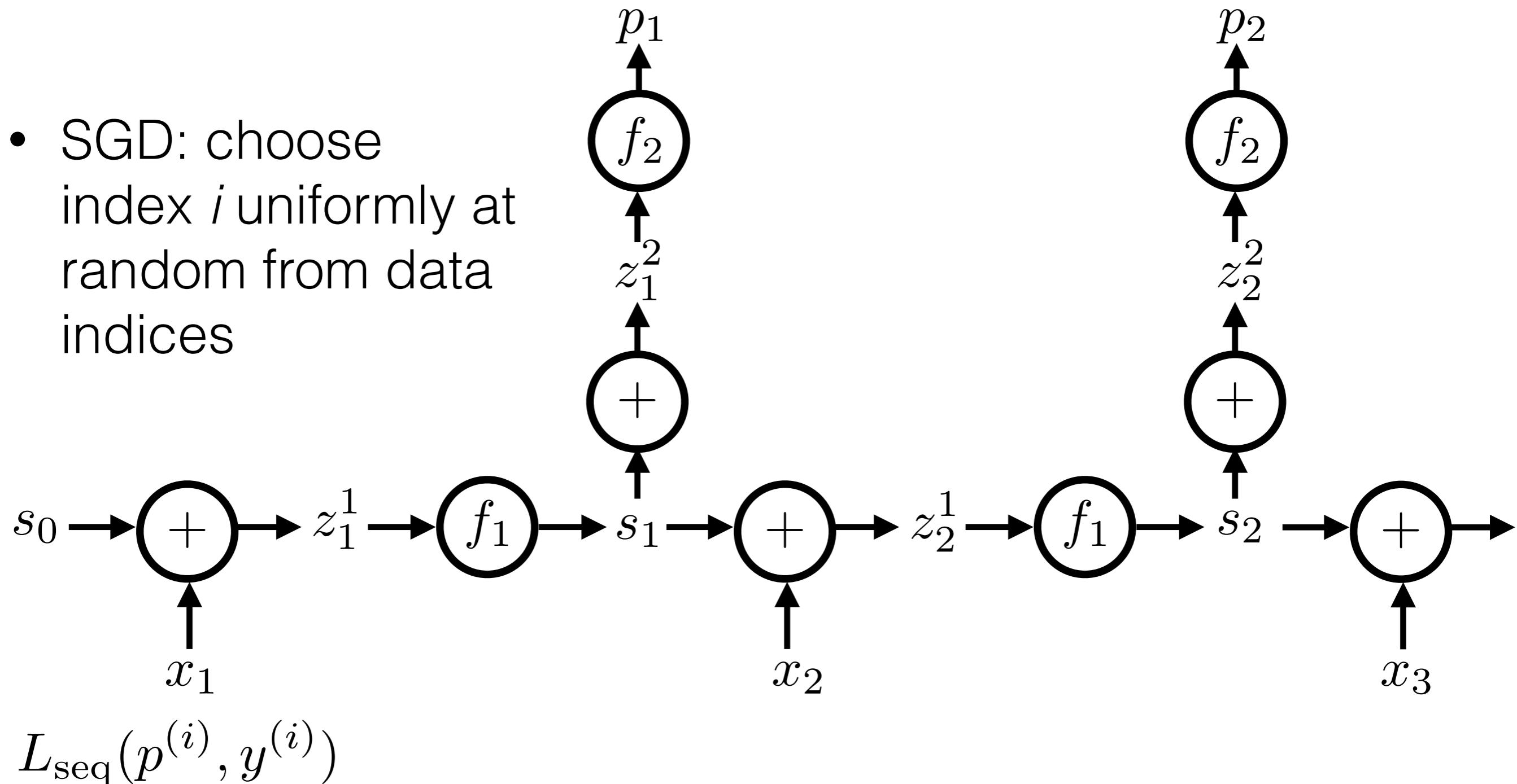
RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices



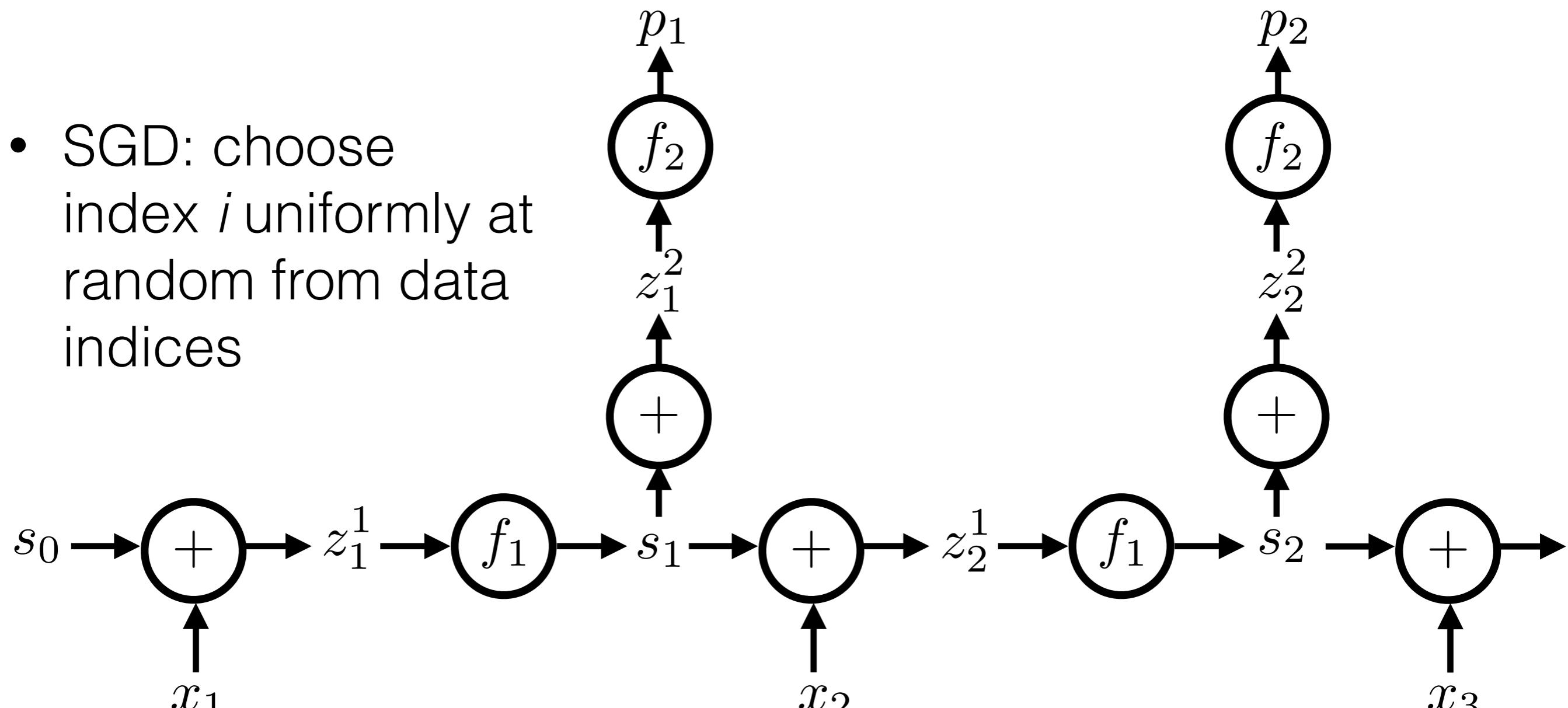
RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices



RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices

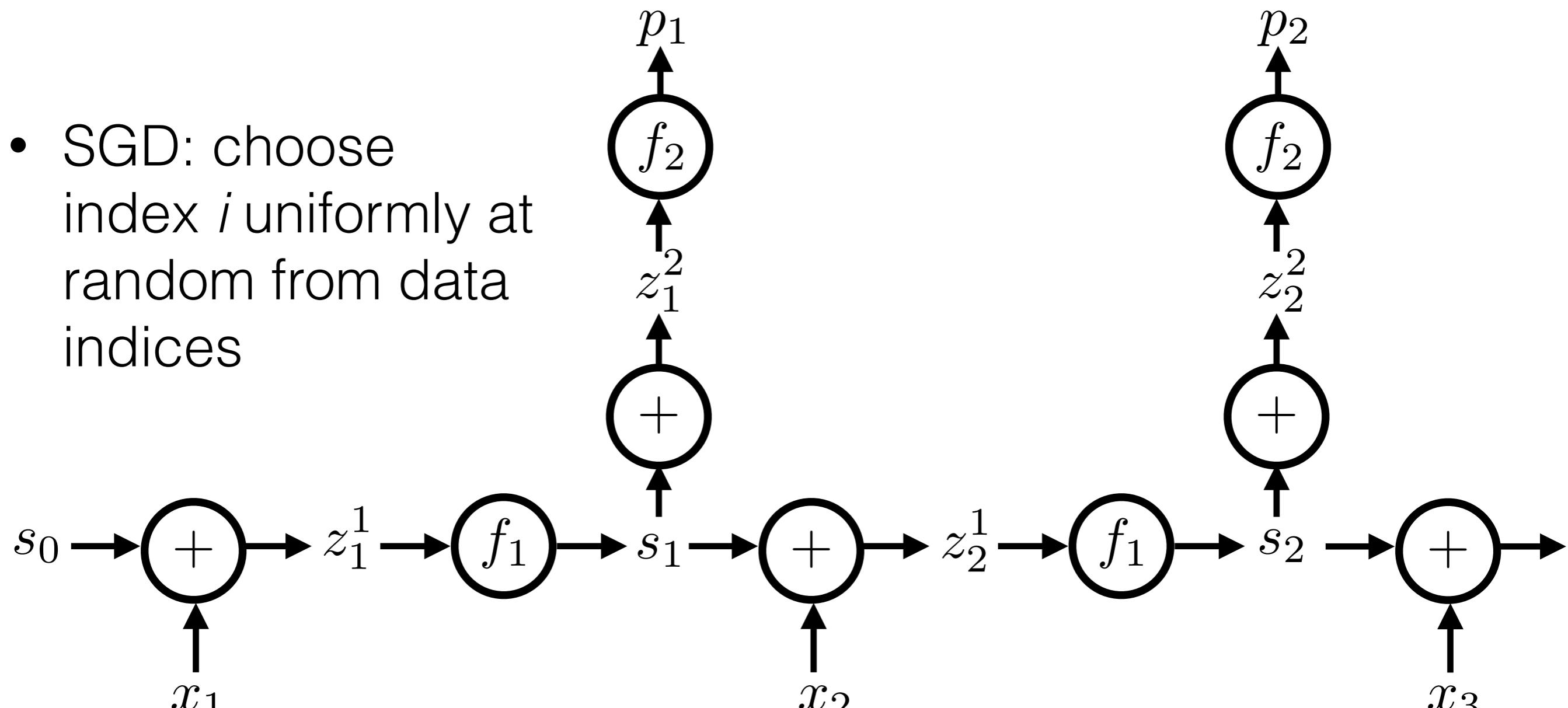


$$L_{\text{seq}}(p^{(i)}, y^{(i)})$$

$$\frac{dL_{\text{seq}}(p^{(i)}, y^{(i)})}{dW^{sx}}$$

RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices

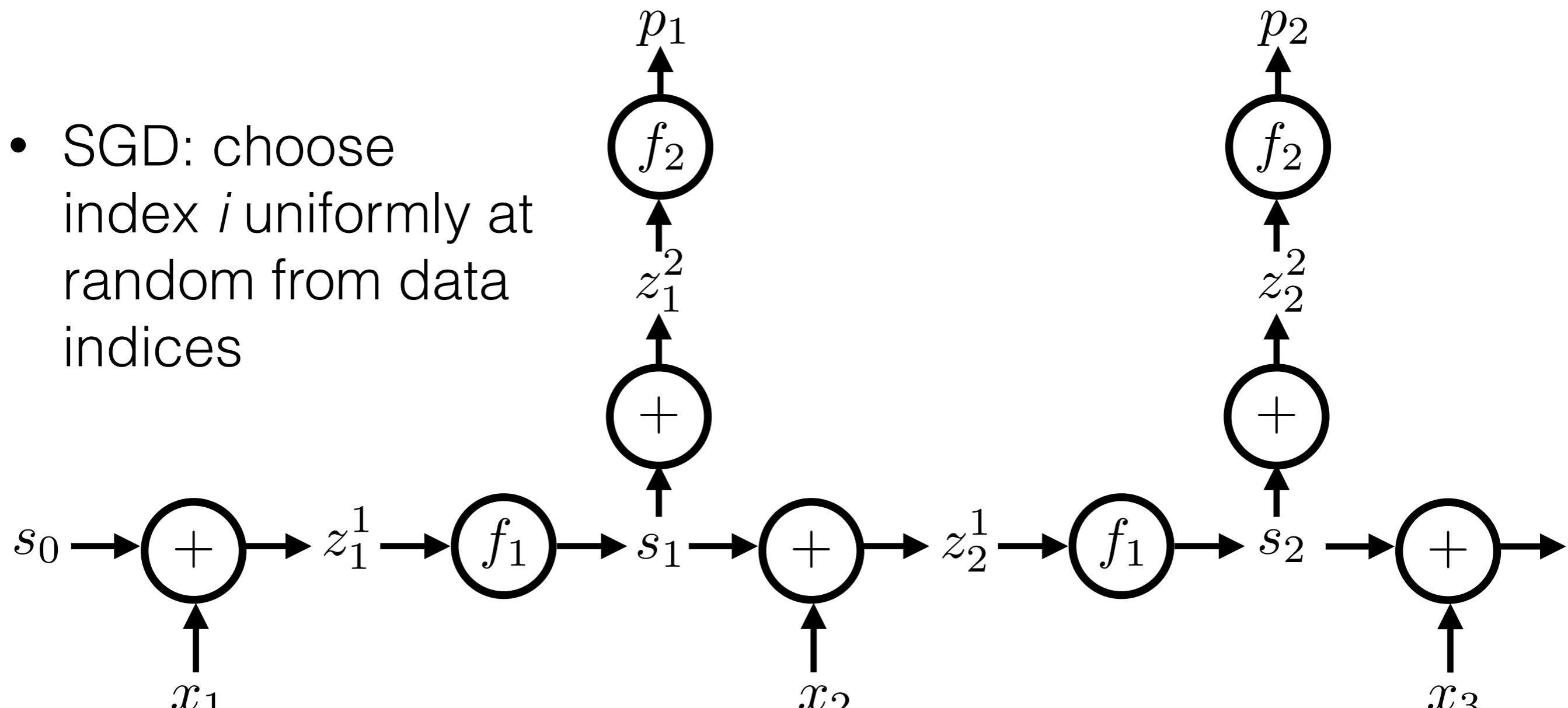


$$L_{\text{seq}}(p^{(i)}, y^{(i)})$$

$$\frac{dL_{\text{seq}}(p^{(i)}, y^{(i)})}{dW^{sx}}$$

RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices

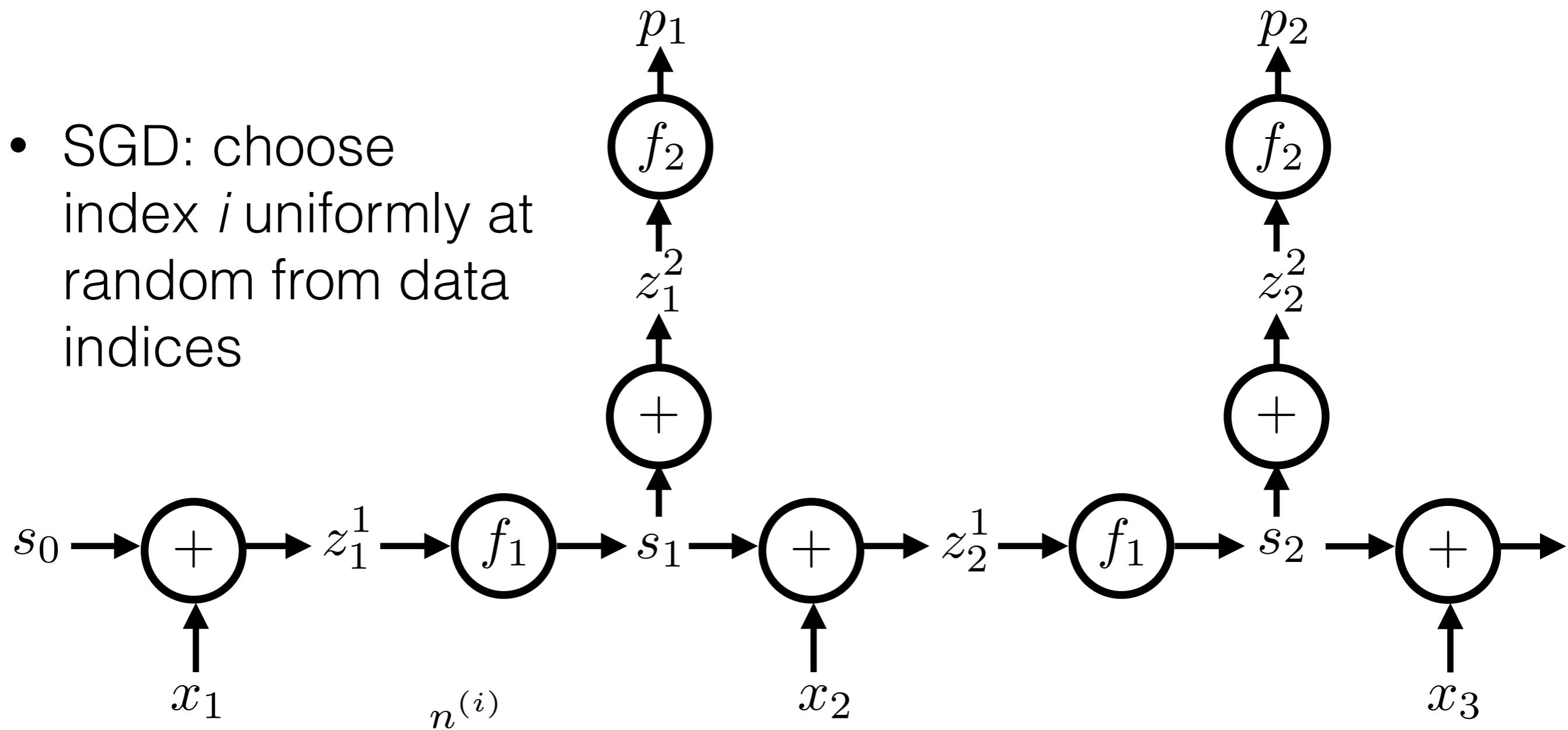


$$L_{\text{seq}}(p^{(i)}, y^{(i)})$$

$$\frac{dL_{\text{seq}}(p^{(i)}, y^{(i)})}{dW^{sx}}$$

RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices

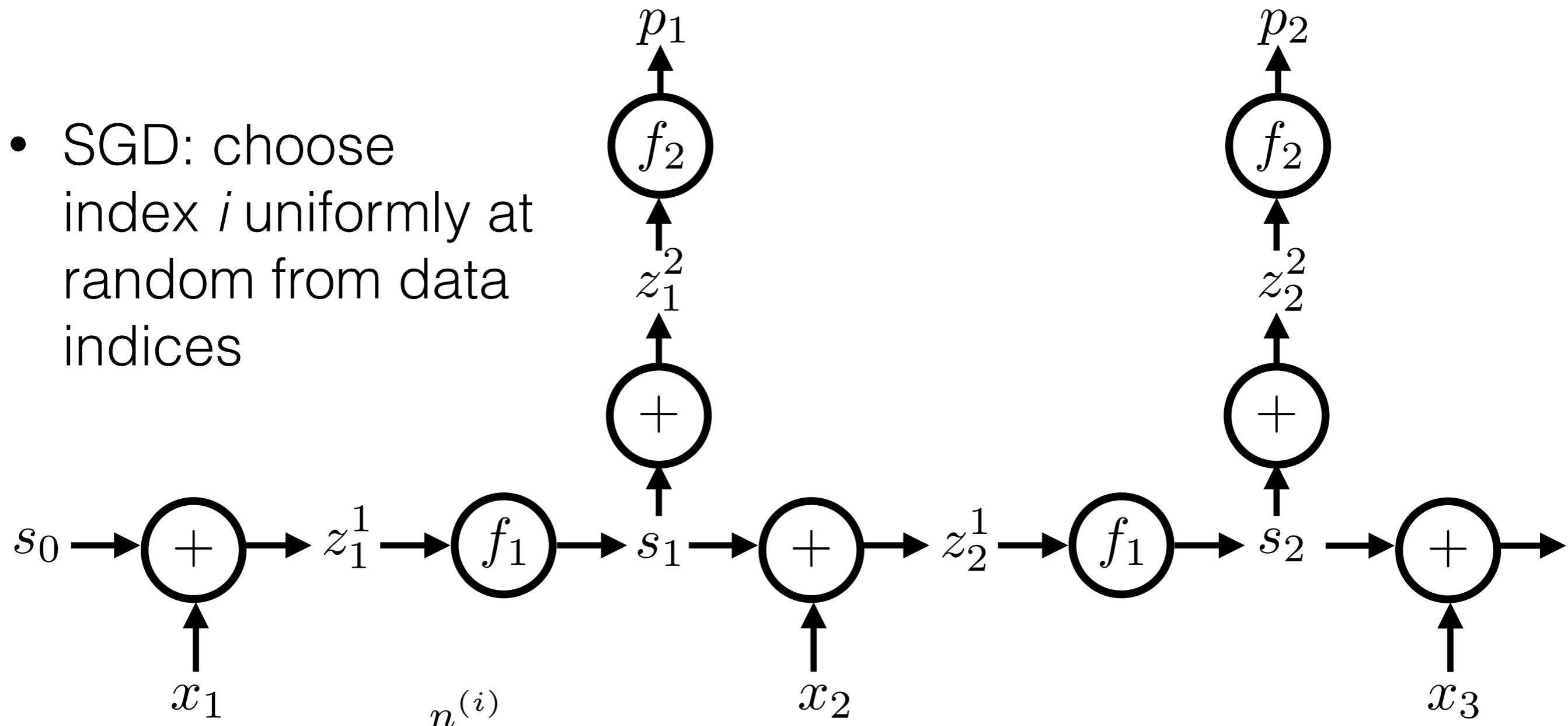


$$L_{\text{seq}}(p^{(i)}, y^{(i)}) = \sum_{t=1}^{n^{(i)}} L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

$$\frac{dL_{\text{seq}}(p^{(i)}, y^{(i)})}{dW^{sx}}$$

RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices

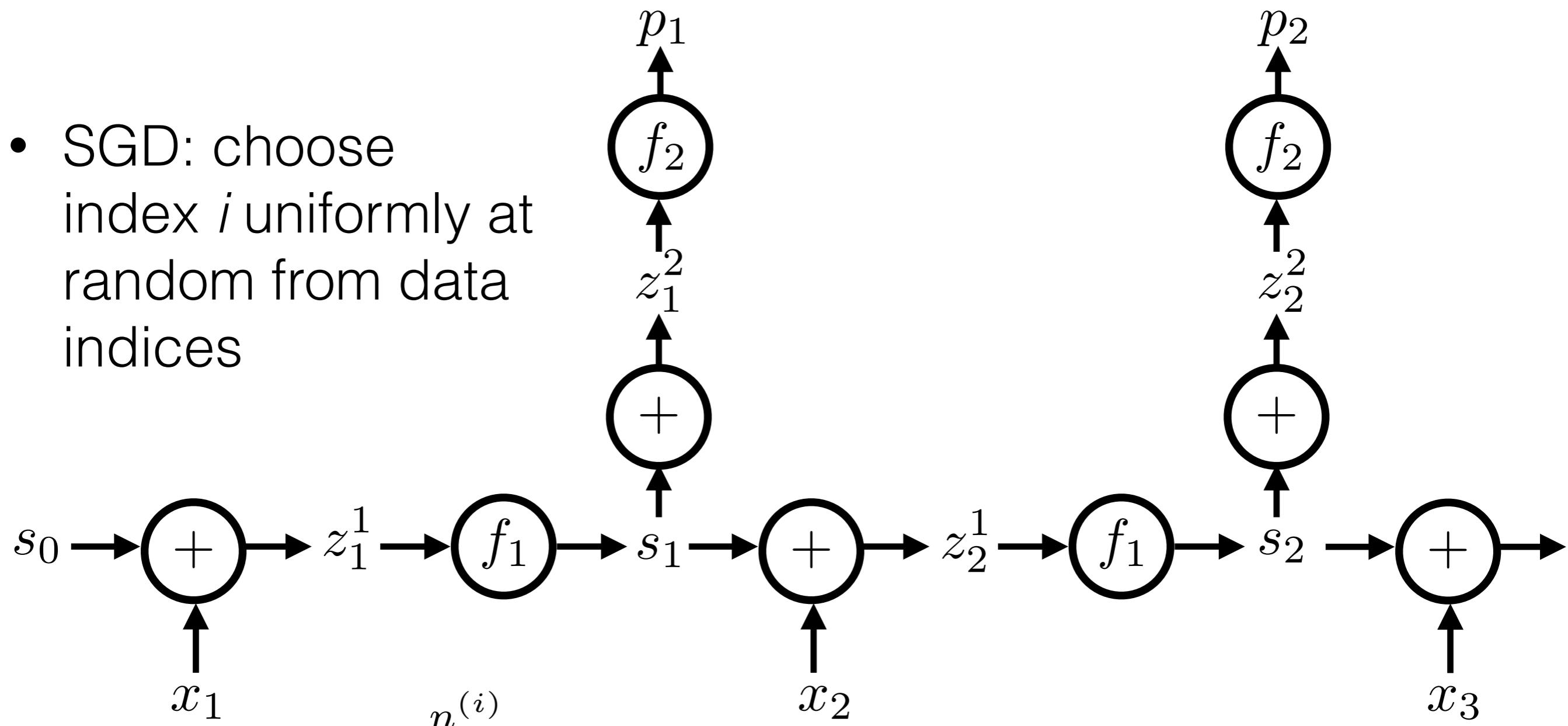


$$L_{\text{seq}}(p^{(i)}, y^{(i)}) = \sum_{t=1}^{n^{(i)}} L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

$$\frac{dL_{\text{seq}}(p^{(i)}, y^{(i)})}{dW^{sx}} = \sum_{t=1}^{n^{(i)}} \frac{dL_{\text{elt}}(p_t^{(i)}, y_t^{(i)})}{dW^{sx}}$$

RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices



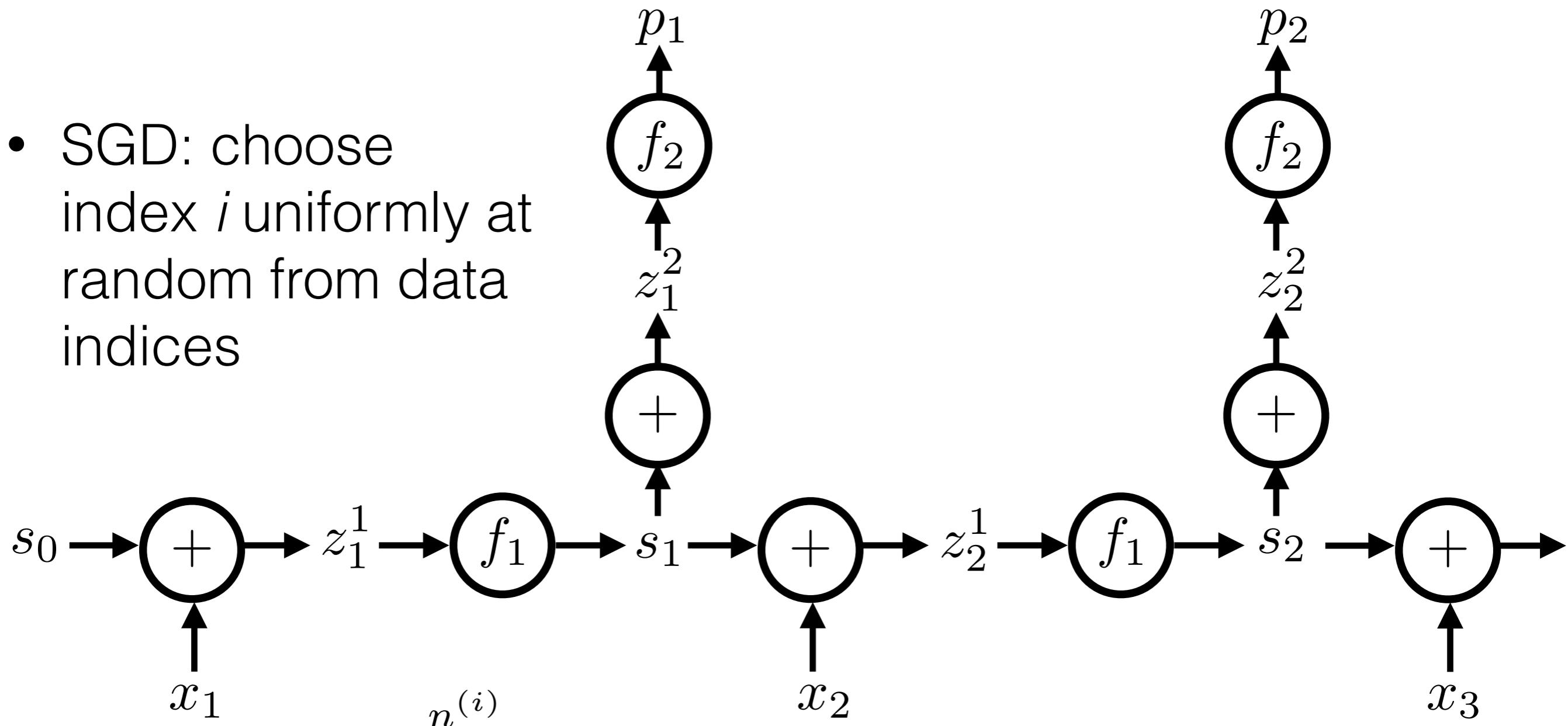
$$L_{\text{seq}}(p^{(i)}, y^{(i)}) = \sum_{t=1}^{n^{(i)}} L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

$$L_t := L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

$$\frac{dL_{\text{seq}}(p^{(i)}, y^{(i)})}{dW^{sx}} = \sum_{t=1}^{n^{(i)}} \frac{dL_{\text{elt}}(p_t^{(i)}, y_t^{(i)})}{dW^{sx}}$$

RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices



$$L_{\text{seq}}(p^{(i)}, y^{(i)}) = \sum_{t=1}^{n^{(i)}} L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

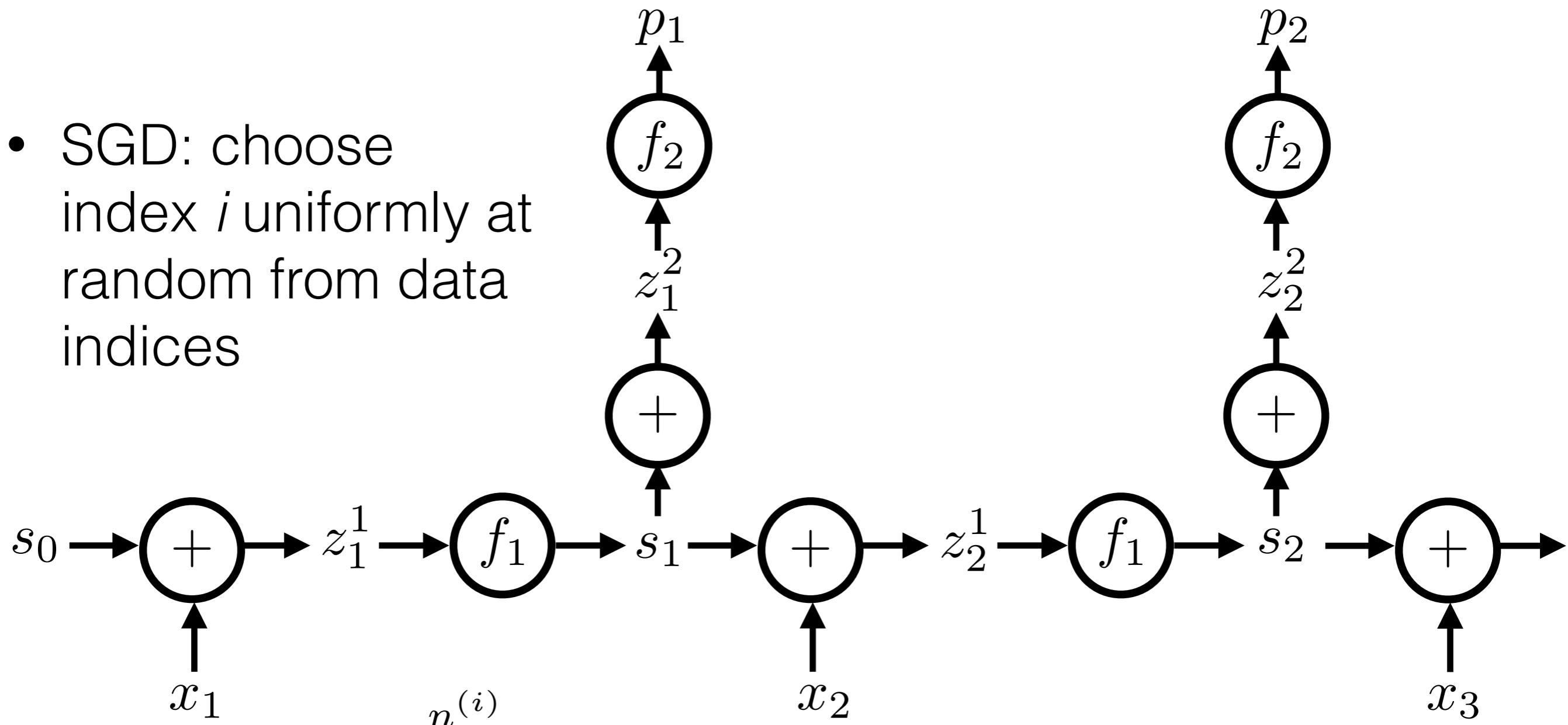
$$\frac{dL_{\text{seq}}(p^{(i)}, y^{(i)})}{dW^{sx}} = \sum_{t=1}^{n^{(i)}} \frac{dL_{\text{elt}}(p_t^{(i)}, y_t^{(i)})}{dW^{sx}}$$

$$L_t := L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

- Need: $\frac{dL_t}{dW^{sx}}$

RNNs: a taste of backpropagation

- SGD: choose index i uniformly at random from data indices



$$L_{\text{seq}}(p^{(i)}, y^{(i)}) = \sum_{t=1}^{n^{(i)}} L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

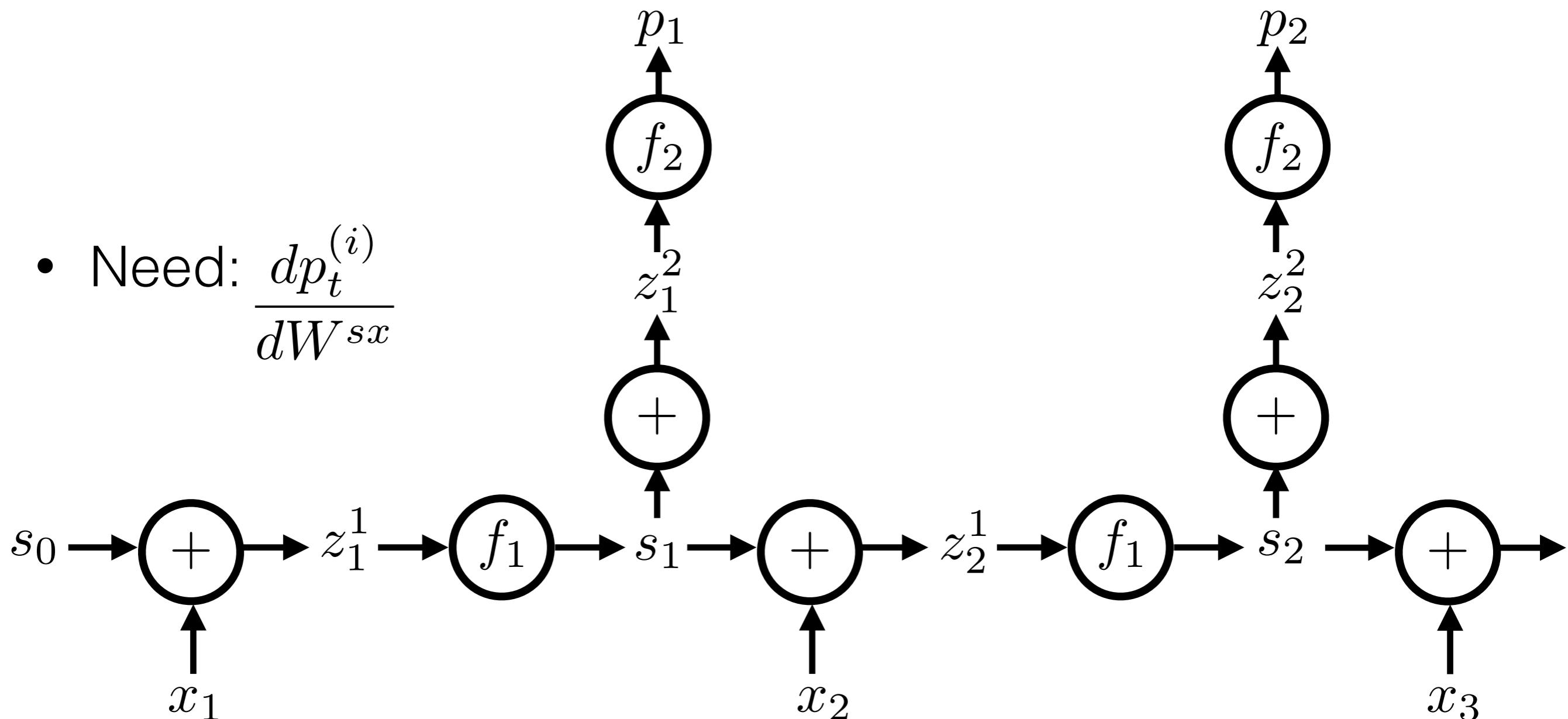
$$\frac{dL_{\text{seq}}(p^{(i)}, y^{(i)})}{dW^{sx}} = \sum_{t=1}^{n^{(i)}} \frac{dL_{\text{elt}}(p_t^{(i)}, y_t^{(i)})}{dW^{sx}}$$

$$L_t := L_{\text{elt}}(p_t^{(i)}, y_t^{(i)})$$

- Need: $\frac{dp_t^{(i)}}{dW^{sx}}$

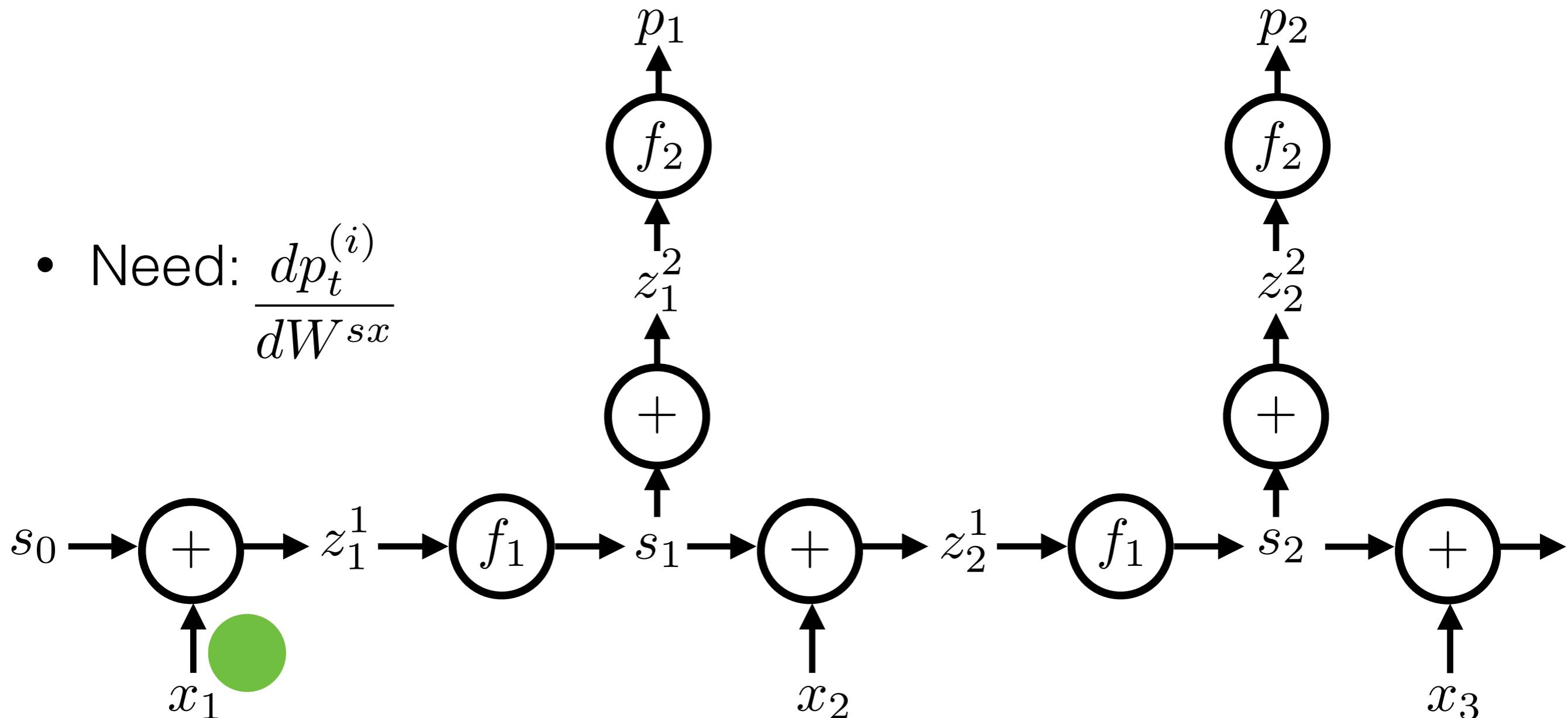
RNNs: a taste of backpropagation

- Need: $\frac{dp_t^{(i)}}{dW^{sx}}$



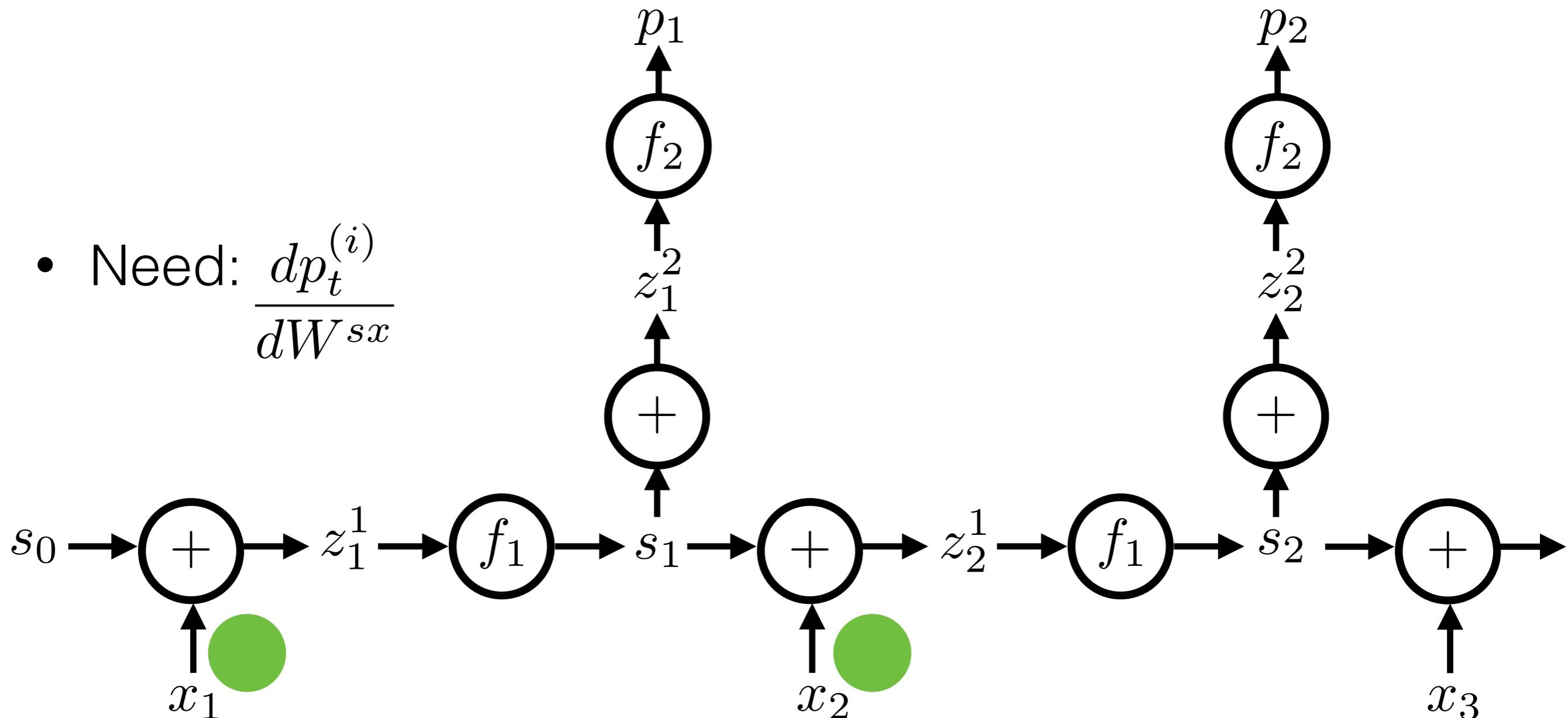
RNNs: a taste of backpropagation

- Need: $\frac{dp_t^{(i)}}{dW^{sx}}$



RNNs: a taste of backpropagation

- Need: $\frac{dp_t^{(i)}}{dW^{sx}}$



RNNs: a taste of backpropagation

- Need: $\frac{dp_t^{(i)}}{dW^{sx}}$

