Modeling Sequences Conditioned on Context with RNNs

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Topics in Sequence Modeling

- Overview
- 1. Unfolding Computational Graphs
- 2. Recurrent Neural Networks
- 3. Bidirectional RNNs
- 4. Encoder-Decoder Sequence-to-Sequence Architectures
- 5. Deep Recurrent Networks
- 6. Recursive Neural Networks
- 7. The Challenge of Long-Term Dependencies
- 8. Echo-State Networks
- 9. Leaky Units and Other Strategies for Multiple Time Scales

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- 10. LSTM and Other Gated RNNs
- 11. Optimization for Long-Term Dependencies
- 12. Explicit Memory

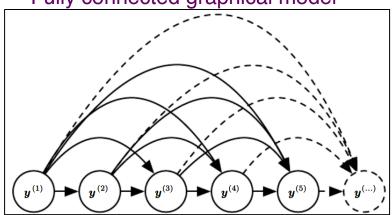
Topics in Recurrent Neural Networks

- O. Overview
- 1. Teacher forcing for output-to-hidden RNNs
- 2. Computing the gradient in a RNN
- 3. RNNs as Directed Graphical Models
- 4. Modeling Sequences Conditioned on Context with RNNs

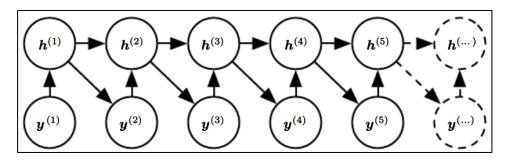
Graphical models of RNNs without inputs

- Directed graphical models of RNNs without inputs
 - having a set of random variables $y^{(t)}$:

Fully connected graphical model



Efficient parameterization based on $h^{(t)} = f(h^{(t-1)}, x^{(t)}; \theta)$



• RNN graphical models can be extended to the conditional distribution of y given the inputs $\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, ... \mathbf{x}^{(\tau)}$

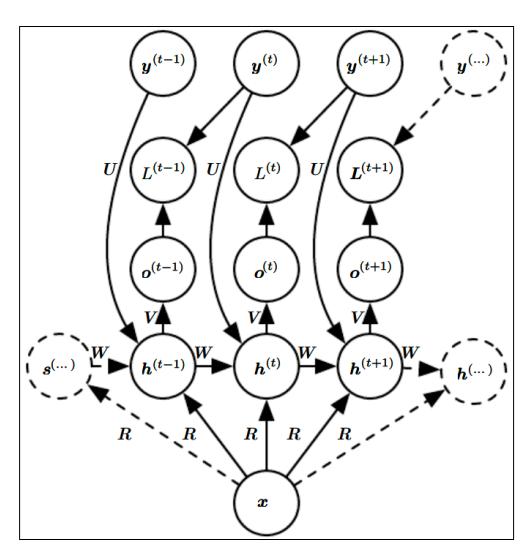
Extending RNNs to represent conditional P(y|x)

- A model representing a variable $P(y|\theta)$ can be reinterpreted as a model representing a conditional distribution $P(y|\omega)$ with $\omega=\theta$
- We can extend such a model to represent a distribution P(y|x) by using the same $P(y|\omega)$ as before but making ω a function of x
- In the case of RNNs this can be achieved in several ways
 - Most common choices are described next

Taking a single vector x as an extra input

- Instead of taking a sequence $x^{(t)}$, $t=1,...,\tau$ as input we can take a single vector x as input
- When x is a fixed-size vector we can simply make it an extra input of the RNN that generates the y sequence
- Common ways of providing an extra input to RNN are
 - An extra input at each time step, or
 - As the initial state $h^{(0)}$, or
 - Both
- The first and common approach is illustrated next
 - The interaction between the input x and each hidden unit vector $h^{(t)}$ is parameterized by a newly introduced weight matrix R that was absent from the model with only y values

RNN to map a fixed length vector x over sequences Y



Appropriate for tasks such as image captioning where a single image is input which produces a sequence of words describing the image.

Each element of the observed output $y^{(t)}$ of the observed output sequence serves both as input (for the current time step) and during training as target

RNN to receive a sequence of vectors $\boldsymbol{x}^{(t)}$ as input

- RNN described by $a^{(t)}=b + Wh^{(t-1)}+Ux^{(t)}$ corresponds to a conditional distribution $P(y^{(1)},...,y^{(\tau)}|x^{(1)},...,x^{(\tau)})$
- It makes a conditional independence assumption that this distribution factorizes as

$$\prod P(\boldsymbol{y}^{(t)} | \boldsymbol{x}^{(1)}, ..., \boldsymbol{x}^{(t)})$$

- To remove the conditional independence assumption, we can add connections from the output at time t to the hidden unit at time t+1 (see next slide)
 - The model can then represent arbitrary probability distributions over the y sequence

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- Limitation: both sequences must be of same length
 - Removing this restriction is discussed in Section 10.4

Removing conditional independence assumption

Connections from previous output to current state allow RNN to model arbitrary distribution over sequences of \boldsymbol{y} given sequences of the same length

Compare to model that is only able to represent distributions in which the y values are conditionally independent from each other given x values

