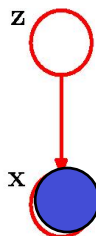


Latent Variable View of EM

Sargur Srihari
srihari@cedar.buffalo.edu

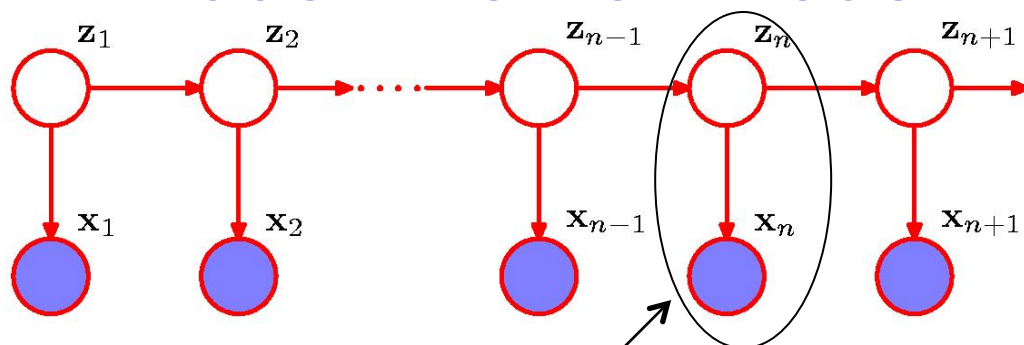
Examples of latent variables

1. Mixture Model



- Joint distribution is $p(x, z)$
- We don't have values for z

2. Hidden Markov Model



- A single time slice is a mixture with components $p(x|z)$
- An extension of mixture model
 - Choice of mixture component depends on choice of mixture component for previous distribution
- Latent variables are multinomial variables z_n
 - That describe component responsible for generating x_n

Another example of latent variables

3. Topic Models (Latent Dirichlet Allocation)

- In NLP unobserved groups explain why some observed data are similar
- Each document is a mixture of various topics (latent variables)
- Topics generate words
 - CAT-related: milk, meow, kitten
 - DOG-related: puppy, bark, bone
- Multinomial distributions over words with Dirichlet priors

Main Idea of EM

- Goal of EM is:
 - find maximum likelihood models for distributions $p(\mathbf{x})$ that have latent (or missing) data
 - E.g., GMMs, HMMs
 - In case of Gaussian mixture models $p(\mathbf{x}) = \sum_{k=1}^K \pi_k N(\mathbf{x} | \mu_k, \Sigma_k)$
 - We have a complex distribution of observed variables \mathbf{x}
 - We wish to estimate its parameters
- Introduce latent variables \mathbf{z} so that $p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z})$
 - joint distribution $p(\mathbf{x}, \mathbf{z})$ is more tractable (since we know forms of components) $p(\mathbf{x} | z_k = 1) = N(\mathbf{x} | \mu_k, \Sigma_k)$
 - Complicated form from simpler components
- The original distribution is obtained by marginalizing the joint distribution

Alternative View of EM

- This view recognizes key role of latent variables

<ul style="list-style-type: none">• Observed data<ul style="list-style-type: none">– matrix	$X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$	<ul style="list-style-type: none">• Latent Variables<ul style="list-style-type: none">– matrix	$Z = \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_n \end{bmatrix}$
---	---	--	---

- where n^{th} row represents $x_n^T = [x_{n1} \ x_{n2} \ \dots \ x_{nD}]$
- with corresponding row $z_n^T = [z_{n1} \ z_{n2} \ \dots \ z_{nK}]$

- Goal of EM algorithm is to find maximum likelihood solution for $p(X)$ given some X
- When we do not have Z

Likelihood Function involving Latent Variables

- Joint likelihood function is $p(X, Z | \theta)$ where θ is the set of all model parameters
 - E.g., means, covariances, responsibilities
- Marginal likelihood function of observed data
 - From sum rule

$$p(X | \theta) = \sum_Z p(X, Z | \theta)$$

- Log likelihood function is

$$\ln p(X | \theta) = \ln \left\{ \sum_Z p(X, Z | \theta) \right\}$$

Latent Variables in EM

- Log likelihood function is

$$\ln p(X | \theta) = \ln \left\{ \sum_Z p(X, Z | \theta) \right\}$$

Summation inside brackets
due to marginalization
Not due to log-likelihood

- Key Observation:

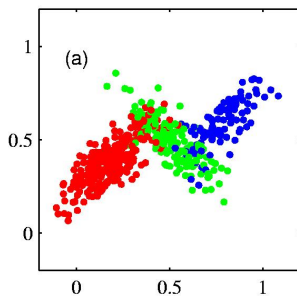
- Summation over latent variables appears inside logarithm

- Even if joint distribution $p(X, Z | \theta)$ belongs to exponential family the marginal distribution $p(X | \theta)$ does not
 - Taking log of Sum of Gaussians does not give simple quadratic
- Results in complicated expressions for maximum likelihood solution, i.e., what value of θ maximizes the likelihood

Complete and Incomplete Data Sets

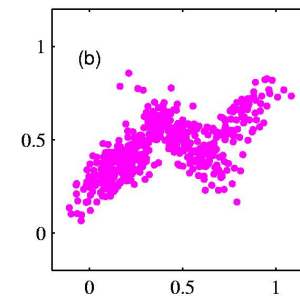
Complete Data $\{X, Z\}$

- For each observation in X we know corresponding value of latent variable Z
- Log-likelihood has the form $p(X, Z | \theta)$
 - maximization over θ is straightforward



Incomplete Data $\{X\}$

- Actual data set
- Log likelihood function is
$$\ln p(X | \theta) = \ln \left\{ \sum_Z p(X, Z | \theta) \right\}$$
- Maximization over θ is difficult
 - summations inside logarithm



Expectation of log-likelihood

- Since we don't have the complete data set $\{X, Z\}$ we evaluate the expected log-likelihood, i.e.,

$$E[\ln p(X, Z | \theta)]$$

- Since we are given X , our state of knowledge of Z is given only by the posterior distribution of the latent variables $p(Z | X, \theta)$
- Thus expected log-likelihood of complete data is

$$E[\ln p(X, Z | \theta)] = \sum_Z p(Z | X, \theta) \underbrace{\ln p(X, Z | \theta)}_{\text{Summation is due to expectation not sum rule!}}$$

Summation is
due to expectation
not sum rule!

We maximize this.

Note that the logarithm acts on the joint-- which is tractable

E and M Steps

- *E Step*: Estimate the missing values
 - Use current parameter value θ^{old} to find the posterior distribution of the latent variables given by

$$p(Z | X, \theta^{old})$$

- *M Step*: Determine revised parameter estimate θ^{new} by maximizing $\theta^{new} = \arg \max_{\theta} Q(\theta, \theta^{old})$

– *where*

$$Q(\theta, \theta^{old}) = \sum_Z p(Z | X, \theta^{old}) p(X, Z | \theta)$$

Summation due to expectation

- is the *expectation* of $p(X, Z | \theta)$ for some general parameter value θ

- Evaluate the log-likelihood $\sum_{i=1}^N \ln p(X_i, Z | \theta)$

General EM Algorithm

- Given joint distribution $p(X, Z | \theta)$ over observed variables X and latent variables Z governed by parameters θ
goal is to maximize likelihood function $p(X | \theta)$

- Step 1:** Choose an initial setting for the parameters θ^{old}
- Step 2:** E Step: Evaluate $p(Z | X, \theta^{old})$
- Step 3:** M Step: Evaluate θ^{new} given by

$$\theta^{new} = \arg \max_{\theta} Q(\theta, \theta^{old})$$

where

$$Q(\theta, \theta^{old}) = \sum_Z p(Z | X, \theta^{old}) \ln p(X, Z | \theta)$$

- Check for convergence
 - of either log-likelihood or parameter values
- If not satisfied then let $\theta^{old} \leftarrow \theta^{new}$
- Return to **Step 2**

Missing Variables

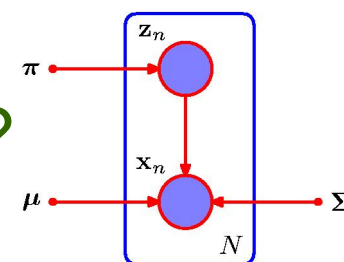
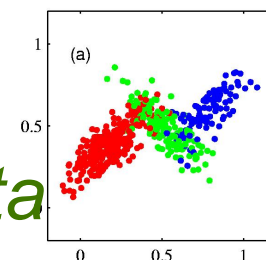
- EM has been described for maximum likelihood function when there are discrete latent variables
- It can also be applied when there are unobserved variables corresponding to missing values in data set
 - Take the joint distribution of all variables and then marginalize over missing ones
 - EM is then used to maximize corresponding likelihood function
- Method is valid when data is missing at random
 - Not if missing value depends on unobserved values
 - E.g., if quantity exceeds some threshold

Gaussian Mixtures Revisited

- Apply EM (latent variable view) to GMM
- In the E-step we compute
 - Expectation of *log-likelihood of complete data* $\{X, Z\}$ wrt posterior of latent Variables Z

$$Q(\theta, \theta^{old}) = \sum_Z p(Z | X, \theta^{old}) \ln p(X, Z | \theta)$$

- What is the form of the two product terms?
- In the M-step we maximize $Q(\theta, \theta^{old})$ wrt θ
 - Will show that this leads to the same m.l estimates for GMM parameters π, μ, Σ as before



Likelihood for Complete Data

- Likelihood function for the complete data set is

$$p(X, Z | \pi, \mu, \Sigma) = \prod_{n=1}^N \prod_{k=1}^K \pi_k^{z_{nk}} N(x_n | \mu_k, \Sigma_k)^{z_{nk}}$$

- Log-likelihood is

$$\ln p(X, Z | \pi, \mu, \Sigma) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \left\{ \ln \pi_k + \ln N(x_n | \mu_k, \Sigma_k) \right\}$$

- Much simpler than log-likelihood for incomplete data:

$$\ln p(X | \pi, \mu, \Sigma) = \sum_{n=1}^N \ln \left\{ \sum_{k=1}^K \pi_k N(x_n | \mu_k, \Sigma_k) \right\}$$

- Maximum likelihood solution for complete data can be obtained in closed form
- Since we don't have values for latent variables, we obtain its expectation wrt the posterior distribution of latent variables

Posterior Distribution of Latent Variables

- From $p(z) = \prod_{k=1}^K \pi_k^{z_k}$ and $p(x | z) = \prod_{k=1}^K N(x | \mu_k, \Sigma_k)^{z_k}$ we have

$$p(Z | X, \mu, \Sigma) \propto \prod_{n=1}^N \prod_{k=1}^K \left(\pi_k N(x_n | \mu_k, \Sigma_k) \right)^{z_{nk}}$$

- From which we can get the expected value for the indicator variable as

$$E[z_{nk}] = \frac{\pi_k N(x_n | \mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j N(x_n | \mu_j, \Sigma_j)} = \gamma(z_{nk})$$

- Substituting into complete log-likelihood:

$$E_Z [\ln p(X, Z | \pi, \mu, \Sigma)] = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \left\{ \ln \pi_k + \ln N(x_n | \mu_k, \Sigma_k) \right\}$$

- Final procedure:** choose initial values for $\pi^{old}, \mu^{old}, \Sigma^{old}$
 - Evaluate the responsibilities (E-step)
 - Keep responsibilities fixed and use closed-form solutions for $\pi^{new}, \mu^{new}, \Sigma^{new}$

$$\mu_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) x_n$$

$$\Sigma_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) (x_n - \mu_k)(x_n - \mu_k)^T$$

$$\pi_k = \frac{N_k}{N}$$

Relation to K-means

- EM for Gaussian mixtures has close similarity to K-means
- K-means performs a hard assignment of data points to clusters
 - Each data point is associated uniquely with one cluster
- EM makes a soft assignment based on posterior probabilities
- K-means does not estimate the covariances of the clusters but only the cluster means