# Particle-Based Approximate Inference

Sargur Srihari srihari@cedar.buffalo.edu

## **Topics**

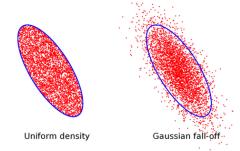
- Approximate Inference Methods
- Terminology of particles (Physics)
- Particle methods and PGMs
- Characterization of Particle Methods
- Task for Particle Methods
- Names of Sampling Methods

## Approximate Inference Methods

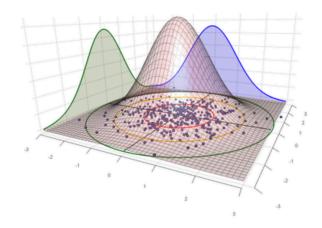
- Variational inference methods
  - Lead to algorithms similar to factor manipulation methods of exact inference
- Particle-based methods
  - Very different class of methods
  - We approximate the joint distribution as a set of instantiations to all or some of the variables
    - Instantiations are often called particles
    - They are designed to provide a good representation of the overall probability distribution

# Particles in Physics

- Charged particle beams in phase space
  - 1. Uniform over ellipse
  - 2. Gaussian (86% lie within ellipse



Particles from symmetric 2D Gaussian



#### Particle-based Methods in PGMs

 Particle-based methods approximate inference by generating multiple samples from the distribution that a graph factorizes

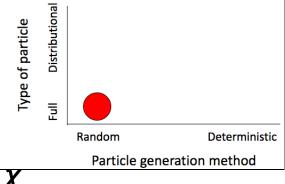
#### Two characterizations of Particle Methods

#### 1. Particle generation method

- Wide variety, two extremes are
  - 1. Particles from a deterministic process
  - 2. Sample particles from some distribution
  - Many variations within each category

### 2. Type of particle

- Full particles
  - Assignment to all network variables \( \chi \)
    - Disadvantage: particle occupies only a small part of space
- Collapsed particle
  - Specifies assignment  $oldsymbol{w}$  to subset of variables  $oldsymbol{W}$ 
    - Associating with it the conditional distribution  $P(\chi \mid W)$  or some summary of it



#### Task for Particle-based Methods

- Given a distribution  $P(\chi)$  we want to estimate the probability of some event Y=y relative to P for some  $Y \in \chi$  and  $y \in Val(Y)$
- More generally we want to estimate the expectation of some function  $f(\xi)$  relative to P

## Methods discussed

### 1. Forward Sampling

- Simplest possible method
- Simply generates samples from original network

### 2. Likelihood weighting and Importance sampling

- Significantly improved method
- Generates samples closer to posterior distribution

#### 3. Markov chain Monte Carlo

- Sampling process that generates, as it converges, samples arbitrarily close to posterior
- Apply mainly to Bayesian Networks, not Markov networks