

# Alternative Parameterizations of Markov Networks

Sargur Srihari

[srihari@cedar.buffalo.edu](mailto:srihari@cedar.buffalo.edu)

# Topics

- Three types of parameterization
  1. Gibbs Parameterization shortcomings
  2. Factor Graphs
  3. Log-linear Models with Energy functions
    - Log-linear with Features
    - Ising, Boltzmann
- Overparameterization
  - Canonical Parameterization
  - Eliminating Redundancy

# Gibbs Parameterization

- A distribution  $P_{\Phi}$  is a Gibbs distribution parameterized by a set of factors

$$\Phi = \{\phi_1(D_1), \dots, \phi_K(D_K)\}$$

– If it is defined as follows

$$P_{\Phi}(X_1, \dots, X_n) = \frac{1}{Z} \tilde{P}(X_1, \dots, X_n)$$

where

$$\tilde{P}(X_1, \dots, X_n) = \prod_{i=1}^m \phi_i(D_i)$$

is an unnormalized measure and

$$Z = \sum_{X_1, \dots, X_n} \tilde{P}(X_1, \dots, X_n)$$

$D_i$  are sets of random variables

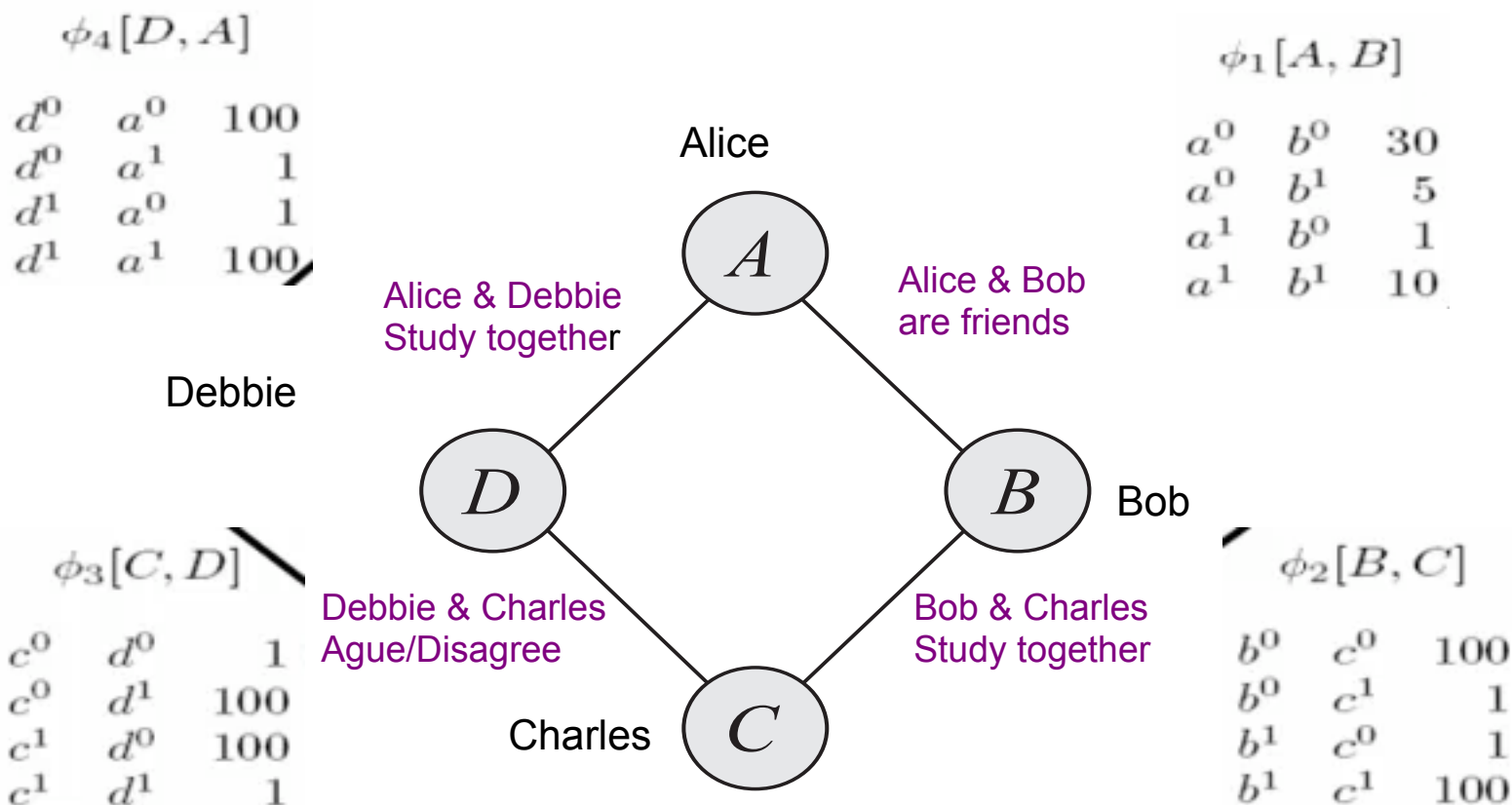
A factor  $\phi$  is a function from  $Val(\mathbf{D})$  to  $R$

where  $Val$  is the set of values that  $\mathbf{D}$  can take

Factor returns a “potential”

The factors do not necessarily represent the marginal distributions  $p(D_i)$  of the variables in their scopes

# Gibbs Parameters with Pairwise Factors



$$P(a, b, c, d) = \frac{1}{Z} \phi_1(a, b) \cdot \phi_2(b, c) \cdot \phi_3(c, d) \cdot \phi_4(d, a)$$

where

$$Z = \sum_{a, b, c, d} \phi_1(a, b) \cdot \phi_2(b, c) \cdot \phi_3(c, d) \cdot \phi_4(d, a)$$

Note that  
Factors are  
Non-negative

# Shortcoming of Gibbs Parameterization

- Network structure doesn't reveal parameterization
- Cannot tell whether the factors are maximal cliques or subsets
- Example next

# Two Gibbs parameterizations, same MN structure

- Gibbs distribution  $P$  over fully connected graph

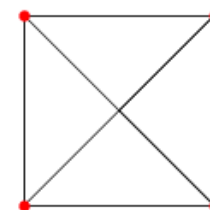
- Clique potential parameterization

- Entire graph is a clique

$$P(a,b,c,d) = \frac{1}{Z} \phi(a,b,c,d) \text{ where } Z = \sum_{a,b,c,d} \phi(a,b,c,d)$$

- No of Parameters

» Exponential in no. of variables:  $2^n - 1$



Completely connected graph with four binary variables

- Pairwise parameterization

- A factor for each pair of variables  $X, Y \in \mathcal{X}$

$$P(a,b,c,d) = \frac{1}{Z} \phi_1(a,b) \cdot \phi_2(b,c) \cdot \phi_3(c,d) \cdot \phi_4(d,a) \cdot \phi_5(a,c) \cdot \phi_6(b,d) \text{ where } Z = \sum_{a,b,c,d} \phi_1(a,b) \cdot \phi_2(b,c) \cdot \phi_3(c,d) \cdot \phi_4(d,a) \cdot \phi_5(a,c) \cdot \phi_6(b,d)$$

- Quadratic no of parameters:  $4 \times {}^nC_2$

- Independencies are same in both

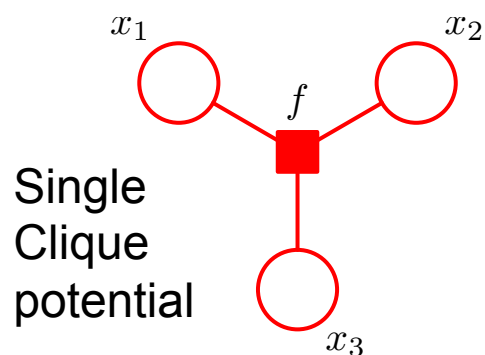
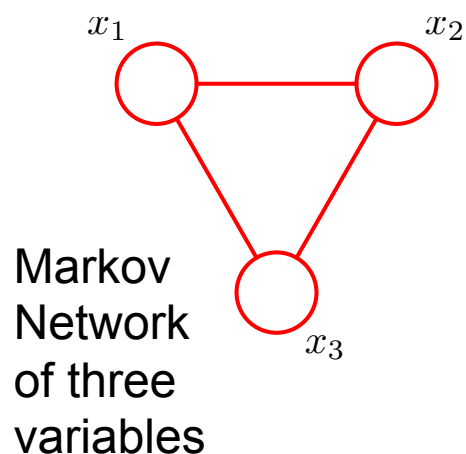
- But significant difference in no of parameters

# Factor Graphs

- Markov network structure does not reveal all structure in a Gibbs parameterization
  - Cannot tell from graph whether factors involve maximal cliques or their subsets
- Factor graph makes parameterization explicit

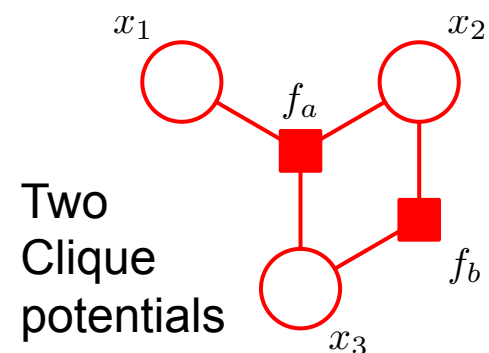
# Factor Graph

- Undirected graph with two types of nodes
  - Variable nodes denoted as ovals
  - Factor nodes denoted as squares
- Contains edges only between variable nodes and factor nodes



$$P(x_1, x_2, x_3) = \frac{1}{Z} f(x_1, x_2, x_3)$$

$$\text{where } Z = \sum_{x_1, x_2, x_3} f(x_1, x_2, x_3)$$



$$P(x_1, x_2, x_3) = \frac{1}{Z} f_a(x_1, x_2, x_3) f_b(x_2, x_3)$$

$$\text{where } Z = \sum_{x_1, x_2, x_3} f_a(x_1, x_2, x_3) f_b(x_2, x_3)$$



# Parameterization of Factor Graphs

- MN parameterized by a set of factors
- Each factor node  $V_\phi$  is associated
  - with only one factor  $\phi$
  - whose scope is the set of variables that are neighbors of  $V_\phi$

A distribution  $P$  factorizes over Factor graph  $\mathcal{F}$  if it can be represented as a set of factors in this form

# Multiple factor graphs for same graph

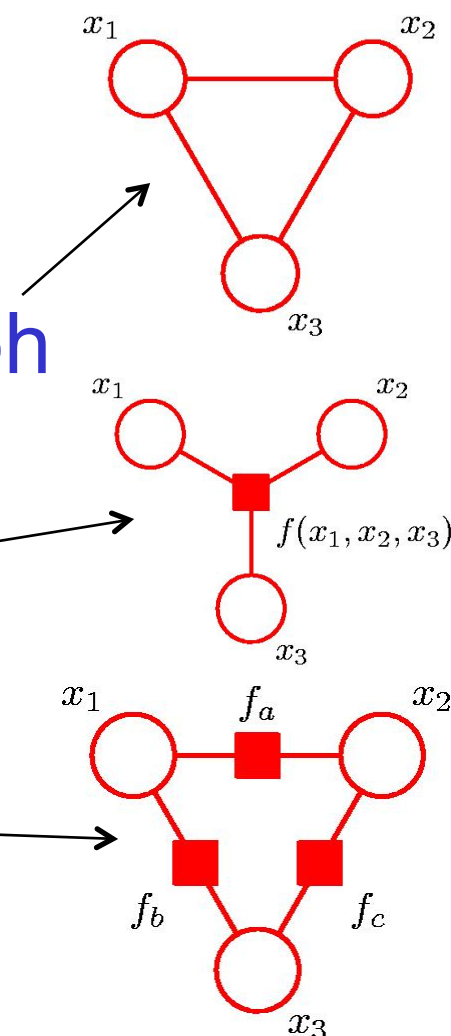
- Factor graphs are specific about factorization
- A fully connected undirected graph
- Joint distribution in two forms

– In general form

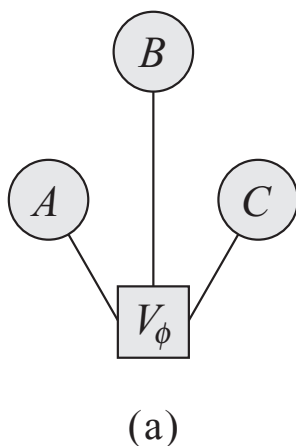
$$p(x) = f(x_1, x_2, x_3)$$

– As a specific factorization

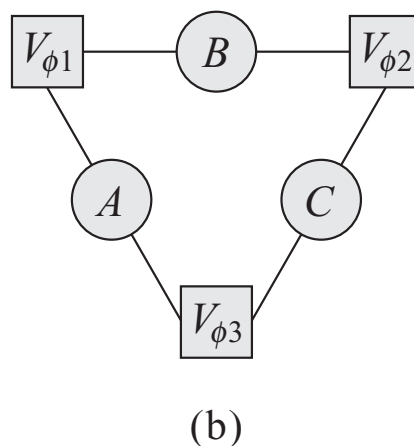
$$p(x) = f_a(x_1, x_2) f_b(x_1, x_3) f_c(x_2, x_3)$$



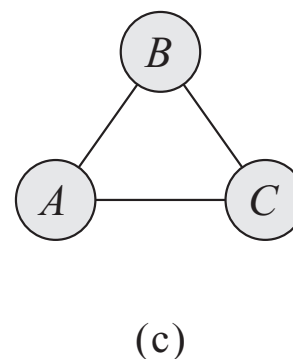
# Factor graphs for same network



Single factor  
over all variables



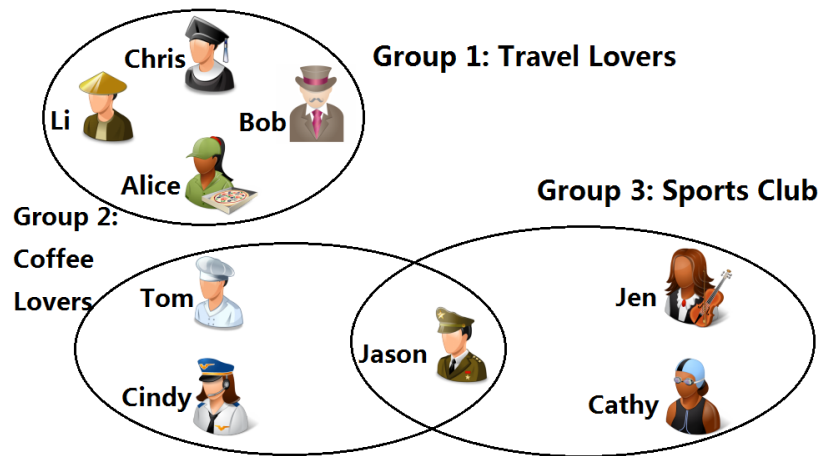
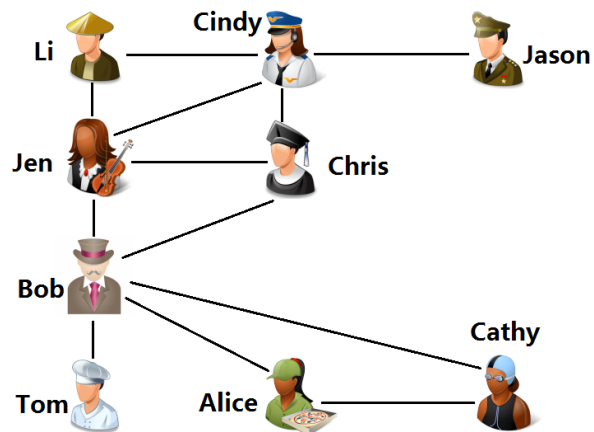
Three pairwise  
factors



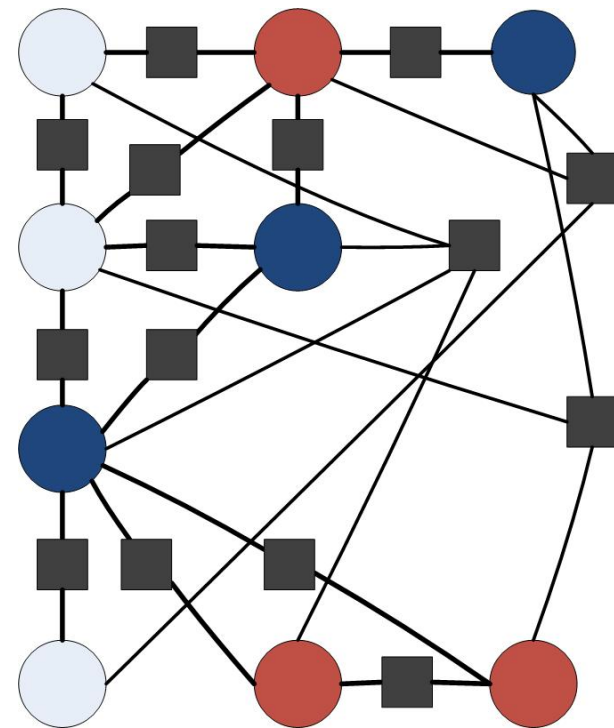
Induced Markov network  
for both is a clique over  $A, B, C$

- Factor graphs (a) and (b) imply the same Markov network (c)
- Factor graphs make explicit the difference in factorization

# Social Network Example

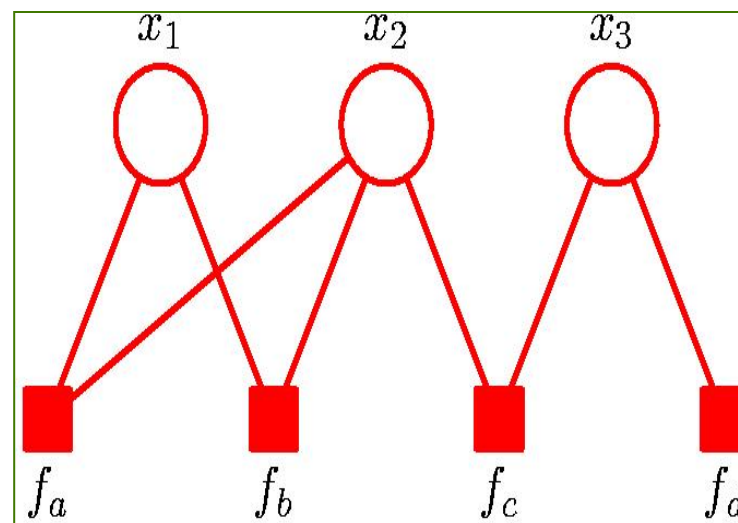


Factor graph with pairwise and Higher-order factors



# Factor graphs properties

- They are bipartite since
  1. Two types of nodes
  2. All links go between nodes of opposite type
- Representable as two rows of nodes
  - Variables on top
  - Factor nodes at bottom
- Other intuitive representations used
  - When derived from directed/undirected graphs



# Deriving factor graphs from Graphical Models

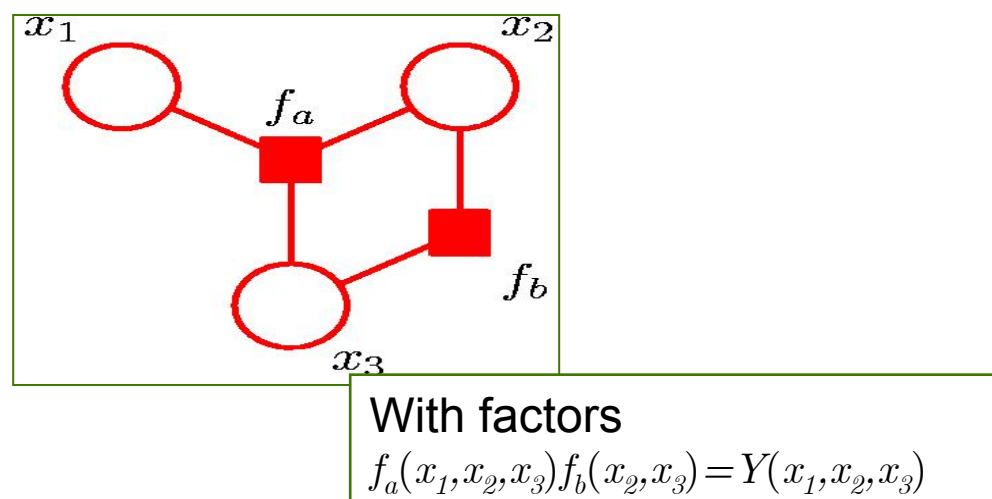
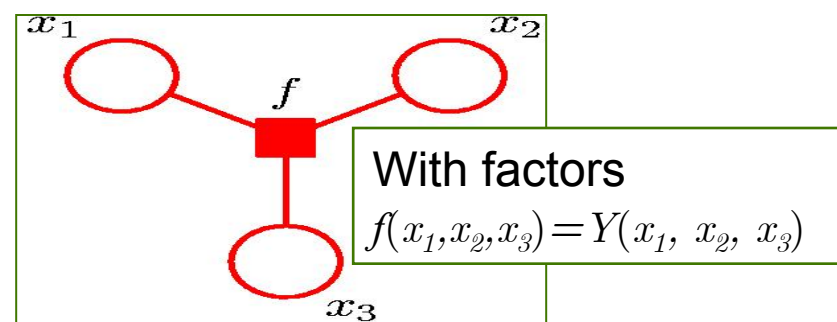
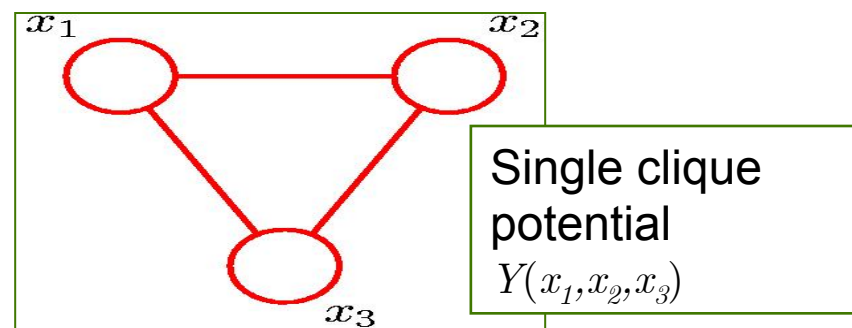
- Undirected Graph (MN)
- Directed Graph (BN)

# Conversion of MN to Factor Graph

- Steps in converting distribution expressed as undirected graph:

1. Create variable nodes corresponding to nodes in original
2. Create factor nodes for maximal cliques  $x_s$
3. Factors  $f_s(x_s)$  set equal to clique potentials

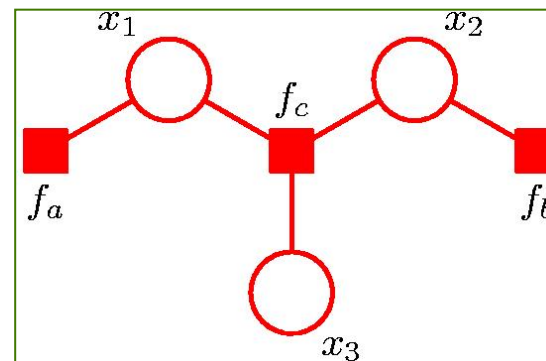
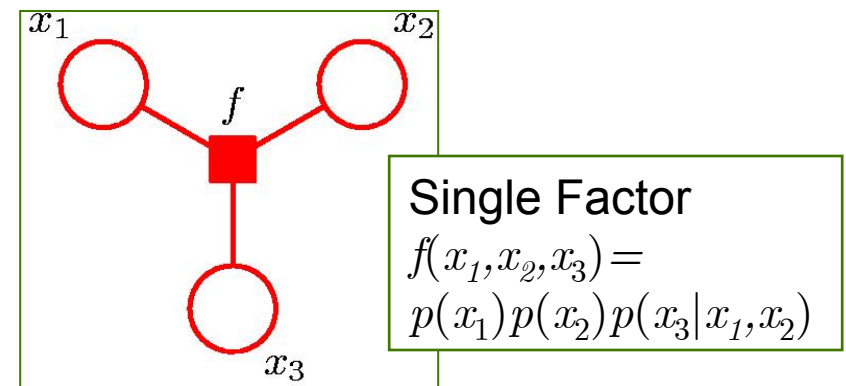
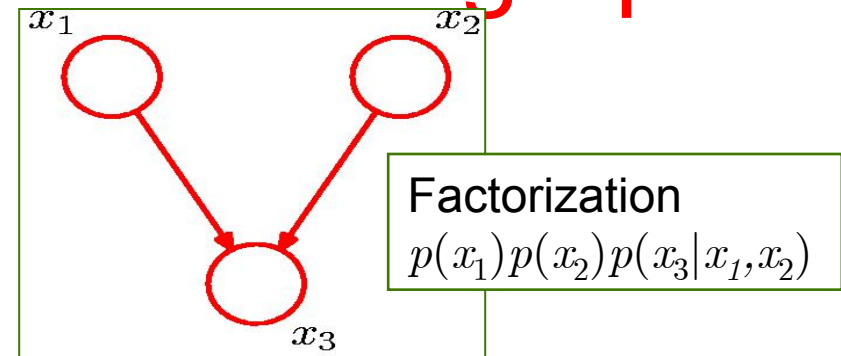
- Several different factor graphs possible from same distribution



# Conversion of BN to factor graph

- Steps

1. Variable nodes correspond to nodes in factor graph
2. Create factor nodes corresponding to conditional distributions
  - Multiple factor graphs possible from same graph



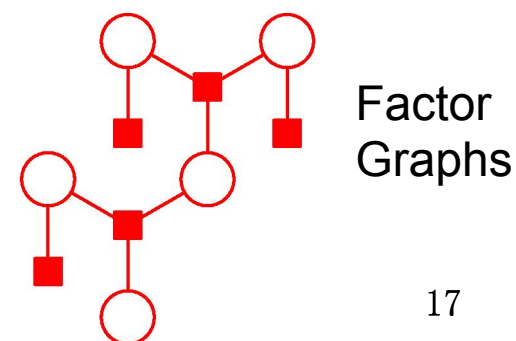
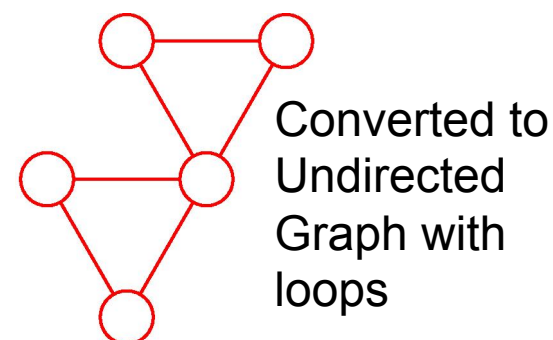
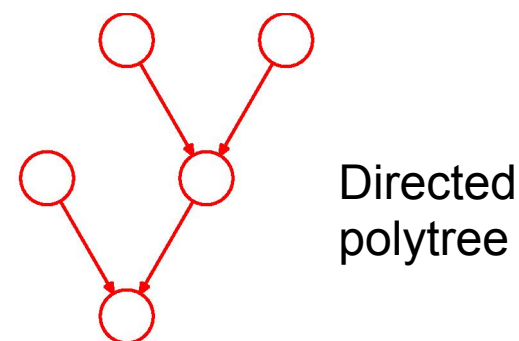
With three Factors

$$\begin{aligned} f_a(x_1) &= p(x_1) \\ f_b(x_2) &= p(x_2) \\ f_c(x_1, x_2, x_3) &= p(x_3|x_1, x_2) \end{aligned}$$



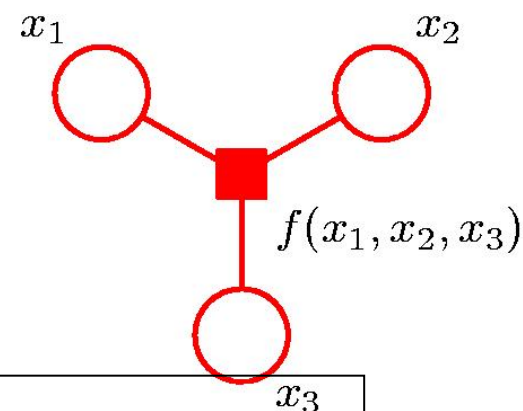
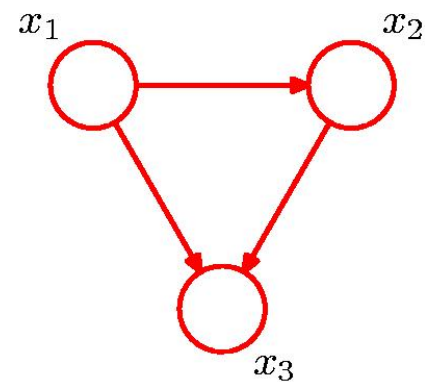
# Tree to Factor Graph

- Conversion of directed or undirected tree to factor graph is a tree
  - No loops
  - Only one path between 2 nodes
- In the case of a directed polytree
  - Conversion to undirected graph has loops due to moralization
  - Conversion again to factor graph results in a tree



# Removal of local cycles

- Local cycles in a directed graph having links connecting parents
- Can be removed on conversion to factor graph
  - By defining a factor function



Factor Graph with tree structure

$$f(x_1, x_2, x_3) = p(x_1) p(x_2 | x_1) p(x_3 | x_1, x_2)$$

# Log-linear Models

- As in Gibbs parameterization,
  - Factor graphs still encode factors as tables over its scope

$$P(x_1, x_2, x_3) = \frac{1}{Z} f_a(x_1, x_2, x_3) f_b(x_2, x_3)$$

where  $Z = \sum_{x_1, x_2, x_3} f_a(x_1, x_2, x_3) f_b(x_2, x_3)$

- Factors can also exhibit Context-specific structure (as in BNs)
- Patterns more readily seen in log-space

# Conversion to log-space

- A factor  $\phi(D)$  is a function from  $Val(D)$  to  $R$ 
  - where  $Val$  is the set of values that  $D$  can take

- Rewrite factor  $\phi(D)$  as

$$\phi(D) = \exp(-\varepsilon(D))$$

- Where  $\varepsilon(D)$  is the *energy* function defined as

$$\varepsilon(D) = -\ln \phi(D)$$

- Note that if  $\ln a = -b$  then  $a = \exp(-b)$
    - If we have  $a = \phi(D) = \exp(-\varepsilon(D))$  then  $b = -\ln a = \varepsilon(D)$
- Thus factor value  $\phi(D)$ , a probability, is negative exponential of energy value  $\varepsilon(D)$

# Energy: Terminology of Physics

- Higher energy states have lower probability
- $D$  is a set of atoms with their values being states and  $\varepsilon(D)$  is its energy, a scalar
- Probability  $\phi(D)$  of a physical state depends inversely on its energy

$$\phi(D) = \exp(-\varepsilon(D)) = \frac{1}{\exp(\varepsilon(D))}$$

- “Log linear” is term used in field of statistics for logarithms of cell frequencies

$$\varepsilon(D) = -\ln \phi(D)$$

# Probability in logarithmic representation

$$P_{\Phi}(X_1, \dots, X_n) = \frac{1}{Z} \tilde{P}(X_1, \dots, X_n)$$

where

$$\tilde{P}(X_1, \dots, X_n) = \prod_{i=1}^m \phi_i(D_i)$$

is an unnormalized measure and

$$Z = \sum_{X_1, \dots, X_n} \tilde{P}(X_1, \dots, X_n)$$

$$P(X_1, \dots, X_n) \propto \exp \left[ - \sum_{i=1}^m \varepsilon_i(D_i) \right]$$

Since

$$\phi_i(D_i) = \exp(-\varepsilon_i(D_i))$$

$$\text{where } \varepsilon_i(D_i) = -\ln(\phi_i(D_i))$$

- Taking logarithm requires that  $\phi(D)$  be positive  
Note that probability is positive
- Log-linear parameters  $\varepsilon(D)$  can be any value along the real line  
Not just non-negative as with factors
- Any Markov network parameterized using positive factors can be converted into a log-linear representation

# Partition Function in Physics

$$P(X_1, \dots, X_n) = \frac{1}{Z} \exp \left[ - \sum_{i=1}^m \varepsilon_i(D_i) \right]$$

where

$$Z = \sum_{X_1, \dots, X_n} \exp \left[ - \sum_{i=1}^m \varepsilon_i(D_i) \right]$$

- $Z$  describes the statistical properties of a system in thermodynamic equilibrium
  - They are functions of thermodynamic state variables such as temperature and volume
  - it encodes how probabilities are partitioned among different microstates, based on their individual energies
  - $Z$  for *Zustandssumme*, "sum over states"

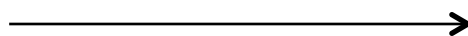
# Log-linear Parameterization

- To convert factors in Gibbs parameterization to log-linear form:
  - Take negative natural logarithm of each potential
    - Requires potential to be positive (to take logarithm)

$$\phi_1[A, B]$$

$a^0$	$b^0$	30
$a^0$	$b^1$	5
$a^1$	$b^0$	1
$a^1$	$b^1$	10

$$-\ln 30 = -3.4$$



$$\epsilon(D) = -\ln \phi(D)$$

Thus

$$\phi(D) = \exp(-\epsilon(D))$$

$$\epsilon_1(A, B)$$

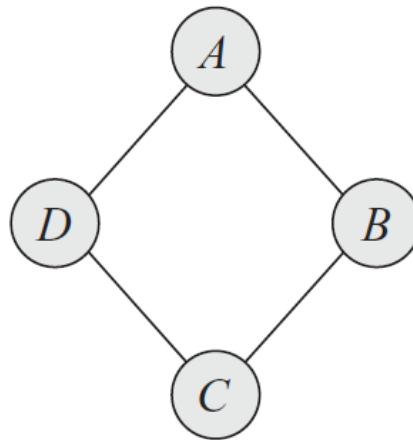
$a^0$	$b^0$	-3.4
$a^0$	$b^1$	-1.61
$a^1$	$b^0$	0
$a^1$	$b^1$	-2.3

Energy is  
Negative log probability



# Example

$$P(X_1, \dots, X_n) \propto \exp \left[ - \sum_{i=1}^m \varepsilon_i(D_i) \right]$$



$$P(A, B, C, D) \propto \exp \left[ -\varepsilon_1(A, B) - \varepsilon_2(B, C) - \varepsilon_3(C, D) - \varepsilon_4(D, A) \right]$$

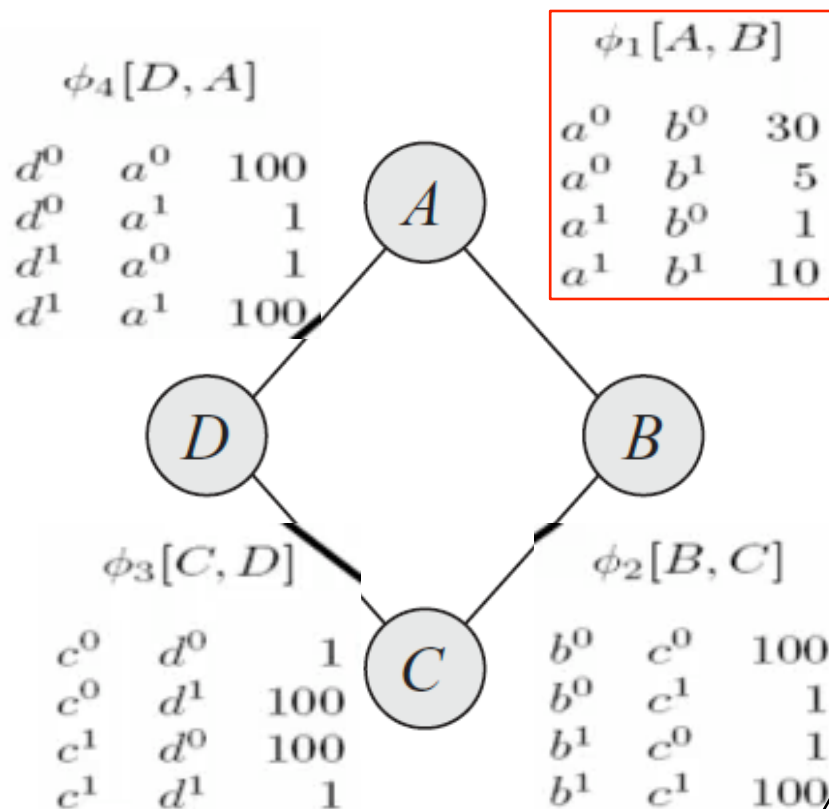
Partition function  $Z$  is sum of RHS over all values of  $A, B, C, D$

Product of Factors becomes sum of exponentials , e.g.,

$$\phi(A, B) = \exp(-\varepsilon(A, B))$$

# From Potentials to Energy Functions

Factors:  
Edge  
Potentials



$a^0$  = has misconception

$a^1$  = no misconception

$b^0$  = has misconception

$b^1$  = no misconception

Take negative natural  
logarithm

$$P(A, B, C, D) \propto \prod_{i=1,2,3,4} \exp(-\epsilon_i(D_i))$$

Factors:  
Energy  
Functions

$\epsilon_1(A, B)$	$\epsilon_2(B, C)$	$\epsilon_3(C, D)$	$\epsilon_4(D, A)$
$a^0 \quad b^0 \quad -3.4$	$b^0 \quad c^0 \quad -4.61$	$c^0 \quad d^0 \quad 0$	$d^0 \quad a^0 \quad -4.61$
$a^0 \quad b^1 \quad -1.61$	$b^0 \quad c^1 \quad 0$	$c^0 \quad d^1 \quad -4.61$	$d^0 \quad a^1 \quad 0$
$a^1 \quad b^0 \quad 0$	$b^1 \quad c^0 \quad 0$	$c^1 \quad d^0 \quad -4.61$	$d^1 \quad a^0 \quad 0$
$a^1 \quad b^1 \quad -2.3$	$b^1 \quad c^1 \quad -4.61$	$c^1 \quad d^1 \quad 0$	$d^1 \quad a^1 \quad -4.61$

# Log-linear makes potentials apparent

$\epsilon_1(A, B)$			$\epsilon_2(B, C)$			$\epsilon_3(C, D)$			$\epsilon_4(D, A)$		
$a^0$	$b^0$	-3.4	$b^0$	$c^0$	-4.61	$c^0$	$d^0$	0	$d^0$	$a^0$	-4.61
$a^0$	$b^1$	-1.61	$b^0$	$c^1$	0	$c^0$	$d^1$	-4.61	$d^0$	$a^1$	0
$a^1$	$b^0$	0	$b^1$	$c^0$	0	$c^1$	$d^0$	-4.61	$d^1$	$a^0$	0
$a^1$	$b^1$	-2.3	$b^1$	$c^1$	-4.61	$c^1$	$d^1$	0	$d^1$	$a^1$	-4.61

$\epsilon_2(B, C)$  and  $\epsilon_4(D, A)$  take on values that are constant (-4.61) multiples of 1 and 0 for agree/disagree

- Such structure is captured by general framework of features
  - Defined next

# Features in a Markov Network

- If  $\mathbf{D}$  is a subset of variables, feature  $f(\mathbf{D})$  is a function from  $\mathbf{D}$  to  $R$  (a real value)
- Feature is a factor *without* a non-negativity requirement

- Given a set of  $k$  features  $\{f_1(D_1), \dots, f_k(D_k)\}$

$$P(X_1, \dots, X_n) = \frac{1}{Z} \exp \left[ - \sum_{i=1}^k w_i f_i(D_i) \right]$$

- where  $w_i f_i(D_i)$  is entry in energy function table, since

$$P(X_1, \dots, X_n) = \frac{1}{Z} \exp \left[ - \sum_{i=1}^m \varepsilon_i(D_i) \right]$$

- Can have several functions over same scope,  $k.ne.m$ 
  - So can represent a standard set of table potentials

# Example of Feature

- Pairwise Markov Network  $A \text{---} B \text{---} C$ 
  - Variables are binary
  - Three clusters:  $C_1 = \{A, B\}$ ,  $C_2 = \{B, C\}$ ,  $C_3 = \{C, A\}$
  - Log-linear model with features
    - $f_{00}(x, y) = 1$  if  $x=0, y=0$  ; 0 otherwise for  $x, y$  instance of  $C_i$
    - $f_{11}(x, y) = 1$  if  $x=1, y=1$  and 0 otherwise
  - Three data instances  $(A, B, C)$ :  $(0, 0, 0), (0, 1, 0), (1, 0, 0)$ 
    - Unnormalized Feature counts are

$$E_{\hat{P}}[f_{00}] = (3 + 1 + 1) / 3 = 5 / 3$$

$$E_{\hat{P}}[f_{11}] = (0 + 0 + 0) / 3 = 0$$

## Definition of Log-linear model with features

- A distribution  $P$  is a log-linear model over  $\mathbf{H}$  if
  - A set of  $k$  features  $F = \{f_1(D_1), \dots, f_k(D_k)\}$  where each  $D_i$  is a complete subgraph and a set of weights  $w_i$
- Such that

$$P(X_1, \dots, X_n) = \frac{1}{Z} \exp \left[ - \sum_{i=1}^k w_i f_i(D_i) \right]$$

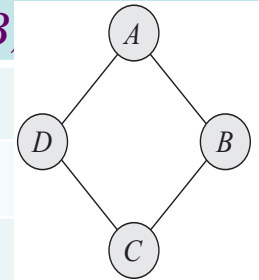
- Note that  $k$  is the no of features, not no of subgraphs

# Example of binary features

$$P(X_1, \dots, X_n; \theta) = \frac{1}{Z(\theta)} \exp \left\{ \sum_{i=1}^k \theta_i f_i(D_i) \right\}$$

- Diamond Network
- With all four variables binary-valued
- Features corresponding to this network are sixteen indicator functions

A	B	$\phi_1(A, B)$
$a^0$	$b^0$	$\phi^{a^0 b^0}$
$a^0$	$b^1$	$\phi^{a^0, b^1}$
$a^1$	$b^0$	$\phi^{a^1 b^0}$
$a^1$	$b^1$	$\phi^{a^1, b^1}$



$Val(A) = \{a^0, a^1\}$   $Val(B) = \{b^0, b^1\}$

$\phi_1(A, B)$  is defined for four features  $f_{a^0, b^0}$ ,  $f_{a^0, b^1}$ ,  $f_{a^1, b^0}$ , and  $f_{a^1, b^1}$

$f_{a^0, b^0} = 1$  if  $a = a^0, b = b^0$   
0 otherwise, etc.

- Four for each assignment of variables to four pairwise clusters

$$f_{a^0 b^0}(a, b) = I\{a = a^0\} I\{b = b^0\}$$

- With this representation

$$\theta_{a^0 b^0} = \ln \phi_1(a^0, b^0)$$

# Compaction using Features

- Consider  $D = \{A_1, A_2\}$  each have  $l$  values  $a^1, \dots, a^l$ 
  - As a full factor, clique potential would need  $l^2$  values

$\phi$	Potential
$a^0, b^0$	
$a^l, b^l$	

- If we prefer situations in which  $A_1 = A_2$  but no preference for others, energy function is

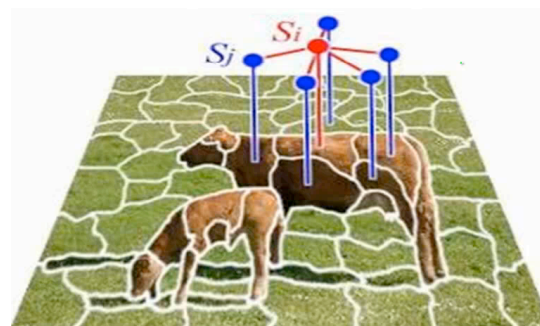
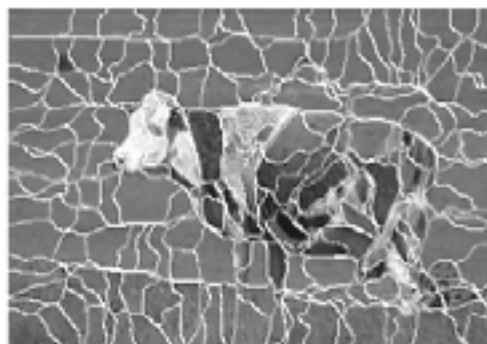
$$\begin{aligned} \varepsilon(A_1, A_2) &= 3 \text{ if } A_1 = A_2 \\ &= 0 \text{ otherwise} \end{aligned}$$

- We can encode it as a feature  $f(A_1, A_2)$  is an *indicator function* for the event  $A_1 = A_2$ 
  - Energy  $\varepsilon$  is 3 times this feature



# Indicator Feature

- A type of feature of particular interest
- Takes on value 1 for some values  $y \in Val(\mathbf{D})$  and 0 for others
- Example:
  - $\mathbf{D} = \{A_1, A_2\}$  : each variable has  $l$  values  $a^1, \dots, a^l$
  - Function  $\phi(A_1, A_2)$  is an indicator function for the event  $A_1 = A_2$ 
    - E.g., two super-pixels have the same greyscale



# Neural network and Markov Network

Classification Problem: Features  $\mathbf{x} = \{x_1, \dots, x_d\}$  and two-class label  $y$

Neuron(Logistic Regression) is same as a Conditional MN with a single query variable:

feature parameters  $w_i$

## Conditional Probability:

Unnormalized

$$\tilde{P}(y=1|\mathbf{x}) = \exp\left\{w_0 + \sum_{i=1}^d w_i x_i\right\} \quad \tilde{P}(y=0|\mathbf{x}) = \exp\{0\} = 1$$

Normalized

$$P(y=1|\mathbf{x}) = \text{sigmoid}\left\{w_0 + \sum_{i=1}^d w_i x_i\right\} \quad \text{where } \text{sigmoid}(z) = \frac{e^z}{1+e^z} = \frac{1}{1+e^{-z}}$$

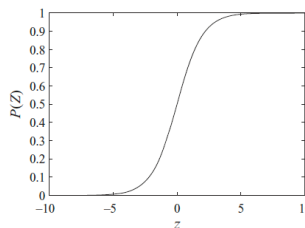
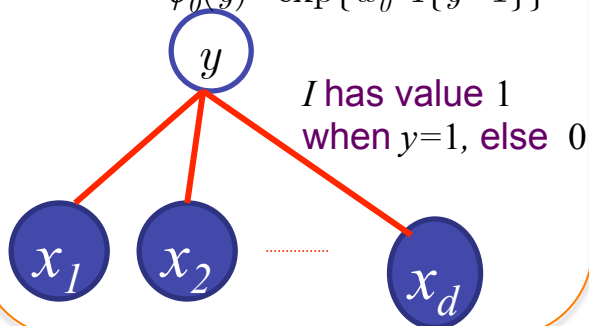
$Z$  has term 1 because  $P^-(y=0|\mathbf{x})=1$

## Factors (log-linear w. features):

$$D_i = \{x_i, y\} \quad f_i(D_i) = x_i I(y)$$

$$\phi_i(x_i, y) = \exp\{w_i x_i I\{y=1\}\},$$

$$\phi_0(y) = \exp\{w_0 I\{y=1\}\}$$



sigmoid

## Learning: Jointly optimize $d$ parameters $w_i$

High dimensional estimation

but correlations accounted for

Can use much richer features:

Edges, image patches sharing same pixels

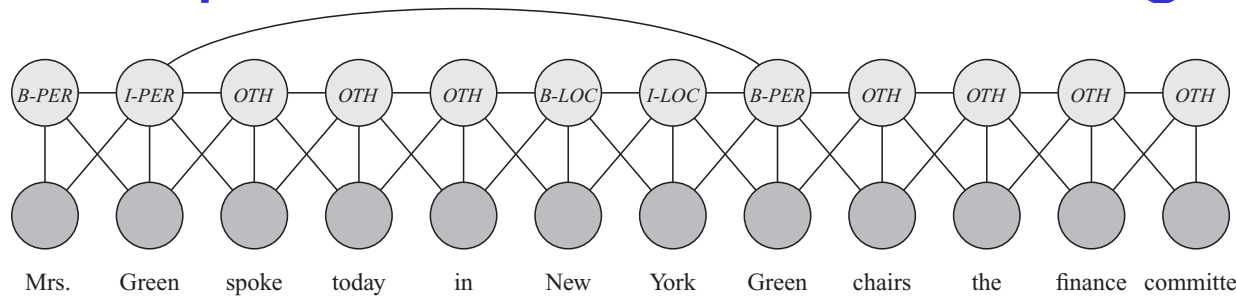
## C-class

$$p(y_c|\mathbf{x}) = \frac{\exp(w_c^T \mathbf{x})}{\sum_j^C \exp(w_j^T \mathbf{x})}$$

$C \times d$  parameters

# Use of Features in Text Analysis

- Compact for variables with large domains



$Y$  = target variables

$X$  = known variables

–  $X$  are words of text,  $Y$  are named entities

- $B-PER$ =Begin Person,  $I-PER$ =within person,  $OTH$ =Not entity

- Factors for word  $t$ :  $\Phi_t^1(Y_t, Y_{t+1})$ ,  $\Phi_t^2(Y_t, X_1, \dots, X_T)$
- Features (hundreds of thousands):
  - Word itself (capitalised, in list of common names)
  - Aggregate features of sequence ( $>2$  words related)
  - $Y_t$  dependent on several words in a window of  $t$
  - Skip chain CRF: connections between adjacent words & multiple occurrences of same word

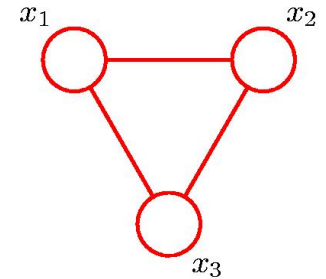
# Examples of Feature Parameterization of MNs

- Text Analysis
- Ising Model
- Boltzmann Model
- Metric MRFs

# Summary of three MN parameterizations (each finer than previous)

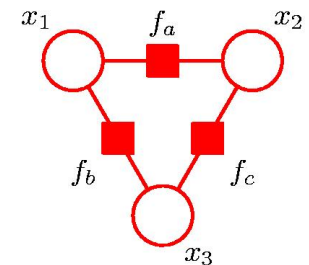
## 1. Markov network

- Product of potentials on cliques
- Good for discussing independence queries



## 2. Factor Graphs

- Product of factors describes Gibbs distribution
- Useful for inference



$$P_{\Phi}(X_1, \dots, X_n) = \frac{1}{Z} \tilde{P}(X_1, \dots, X_n) \text{ where } \tilde{P}(X_1, \dots, X_n) = \prod_{i=1}^m \phi_i(D_i)$$

is an unnormalized measure and  $Z = \sum_{X_1, \dots, X_n} \tilde{P}(X_1, \dots, X_n)$

## 3. Features

- Product of features
- Can describe all entries in each factor
- For both hand-coded models and for learning

$$P(X_1, \dots, X_n) = \frac{1}{Z} \exp \left[ - \sum_{i=1}^k w_i f_i(D_i) \right]$$